Experiment No. 01

Aim: Introduction to MATLAB

S**oftware used:** MATLAB.

MATLAB® is a programming language and numerical computing environment. The name MATLAB® is an acronym for "Matrix Laboratory". As it names suggests it allows easy manipulation of matrix and vectors. Plotting functions and data is made easy with MATLAB®. It has a good Graphic User Interface and conversion of MATLAB files to C/C++ is possible. It has several toolboxes that possess specific functions for specific applications. For example, Image Processing, Neural Networks, CDMA toolboxes are name a few. An additional package, Simulink, adds graphical multidomain simulation and Model-Based Design for dynamic and embedded systems. Simulink contains Block sets that is analogous to Toolboxes. It was created by MathWorks Incorporation, USA. Writing MATLAB programs for modulation applications require knowledge on very few functions and operators. The operators mostly used are arithmetic operators and matrix operators. To know more type in the command prompt „help ops". MATLAB will give a list in that to know on specific operator say addition type in the command prompt „help plus". MATLAB will give how to use and other relevant information.

Commonly used graphical functions are plot, figure, subplot, title, and mathematical functions are sin and cos only. The mathematical functions sin and cos are self-explanatory. The graphical function figure will create a new window and then subsequent graphical commands can be applied. The plot function usually takes two vectors and plot data points according to given vector data. Subplot function is used when two or more plots are drawn on the same figure. As title function suggests it helps to write title of the graph in the figure. For further details type „help plot" or „help subplot" in the command prompt and learn the syntax.

MATLAB CODE:

```
>> A=9;
>> B=7;
>> B+A

ans =

    16

>> A-B

ans =

     2

>> A*B

ans =

    63

>> A/B

ans =

    1.2857

>> A|B

ans =

  logical

   1
```

```
>> A\B

ans =

    0.7778

>> A<B

ans =

  logical

   0

>> A>B

ans =

  logical

   1

>> A==B

ans =

  logical

   0

>> sqrt(B)

ans =

    2.6458
```

```
>> complex(A,B)

ans =

   9.0000 + 7.0000i

>> abs(A)

ans =

     9

>> I=-9

I =

    -9

>> abs(I)

ans =

     9

>> conj(complex(A,B))

ans =

   9.0000 - 7.0000i

>> log(10)

ans =

    2.3026
```

```
>> complex(A,B)

ans =

   9.0000 + 7.0000i

>> abs(A)

ans =

     9

>> I=-9

I =

    -9

>> abs(I)

ans =

     9

>> conj(complex(A,B))

ans =

   9.0000 - 7.0000i

>> log(10)

ans =

    2.3026
```

```
>> log10(10)

ans =

     1

>> B = [1 -1 3];
>> sort(B)

ans =

    -1     1     3

>> sort(B,'descend');
>> B

B =

     1    -1     3

>> zeros(3,3)

ans =

     0     0     0
     0     0     0
     0     0     0

>> ones(3,3)

ans =

     1     1     1
     1     1     1
     1     1     1
```

```
>> log10(10)

ans =

     1

>> B = [1 -1 3];
>> sort(B)

ans =

    -1     1     3

>> sort(B,'descend');
>> B

B =

     1    -1     3

>> zeros(3,3)

ans =

     0     0     0
     0     0     0
     0     0     0

>> ones(3,3)

ans =

     1     1     1
     1     1     1
     1     1     1
```

```
>> A = [1 2 3;4 5 6;7 8 9];
>> A

A =

     1     2     3
     4     5     6
     7     8     9

>> A[3]
 A[3]
  ↑
Invalid expression. When ca
for mismatched delimiters.

>> A(3)

ans =

     7

>> B = [9 8 7;6 5 4;3 2 1];
>> A+B

ans =

    10    10    10
    10    10    10
    10    10    10

>> A-B

ans =

    -8    -6    -4
    -2     0     2
     4     6     8
```

```
>> A*B

ans =

    30    24    18
    84    69    54
   138   114    90

>> A.*B

ans =

     9    16    21
    24    25    24
    21    16     9

>> A/B
Warning: Matrix is singular to

ans =

   NaN   NaN   NaN
   NaN   NaN   NaN
   NaN   NaN   NaN

>> A./B

ans =

    0.1111    0.2500    0.4286
    0.6667    1.0000    1.5000
    2.3333    4.0000    9.0000
```

```
>> trace(A)

ans =

    15

>> diag(A)

ans =

     1
     5
     9

>> size(A)

ans =

     3     3

>> det(A)

ans =

   6.6613e-16

>> sum(A)

ans =

    12    15    18
```

```
>> flip(A)

ans =

     7     8     9
     4     5     6
     1     2     3

>> prod(A)

ans =

    28    80   162

>> fliplr(A)

ans =

     3     2     1
     6     5     4
     9     8     7
```

RESULTS: Successfully Implemented Basic Operations in Matlab.

Experiment No. 02

Aim: Generation of various signals and sequences (Periodic and Aperiodic)

S**oftware used:** MATLAB.

MATLAB® is a programming language and numerical computing environment. The name MATLAB® is an acronym for "Matrix Laboratory". As it names suggests it allows easy manipulation of matrix and vectors. Plotting functions and data is made easy with MATLAB®. It has a good Graphic User Interface and conversion of MATLAB files to C/C++ is possible. It has several toolboxes that possess specific functions for specific applications. For example, Image Processing, Neural Networks, CDMA toolboxes are name a few. An additional package, Simulink, adds graphical multidomain simulation and Model-Based Design for dynamic and embedded systems. Simulink contains Block sets that is analogous to Toolboxes. It was created by MathWorks Incorporation, USA. Writing MATLAB programs for modulation applications require knowledge on very few functions and operators. The operators mostly used are arithmetic operators and matrix operators. To know more type in the command prompt „help ops". MATLAB will give a list in that to know on specific operator say addition type in the command prompt „help plus". MATLAB will give how to use and other relevant information.

Commonly used graphical functions are plot, figure, subplot, title, and mathematical functions are sin and cos only. The mathematical functions sin and cos are self-explanatory. The graphical function figure will create a new window and then subsequent graphical commands can be applied. The plot function usually takes two vectors and plot data points according to given vector data. Subplot function is used when two or more plots are drawn on the same figure. As title function suggests it helps to write title of the graph in the figure. For further details type „help plot" or „help subplot" in the command prompt and learn the syntax.

THEORY:

1. **Unit Impulse: for t=0, impulse is 1 otherwise 0.**
2. **Unit Step: for t>=0, step is 1 otherwise 0.**
3. **Unit Ramp: for t>=0, ramp is function of t otherwise 0.**
4. **Parabola: for t>=0, parabola is a function of t, $x(t) = t^2/2$, otherwise 0**
5. **Rectangle: for |t|>=1/2, rectangle is 1 otherwise 0.**
6. **Triangular: for |t|<=2, triangular is a function of t, x(t) = 1-|t|/2 otherwise 0.**
7. **Signun: for t>=0, signun is 1, otherwise 0.**
8. **Sinc, Sawtooth, Sine, Cosine,Exponential functions are inbuilt.**

MATLAB CODE:

Continuous Time Signal [CTS]:

```
close all;
clear all;

%time range
t=-5:0.1:5;

%Unit Impulse Signal
impulse=1.*(t==0)+0.*(t~=0);
subplot(4,3,1);
plot(t,impulse)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Impulse");
axis([min(t),max(t), min(impulse)-0.5,max(impulse)+0.5]);

%Unit Step Signal
step=1.*(t>=0)+0.*(t<0);
subplot(4,3,2);
plot(t,step)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Step");
axis([min(t),max(t), min(step)-0.5,max(step)+0.5]);

%Unit Ramp Signal
ramp=t.*(t>=0)+0.*(t<0);
subplot(4,3,3);
plot(t,ramp)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Ramp");
axis([min(t),max(t), min(ramp)-0.5,max(ramp)+0.5]);

%Unit Parabolic Signal
parabolic=t.^2/2.*(t>=0)+0.*(t<0);
subplot(4,3,4);
plot(t,parabolic)
xlabel("Iime");
ylabel("amplitude");
title("Unit Parabolic");
axis([min(t),max(t), min(parabolic)-0.5,max(parabolic)+0.5]);


%Unit Rectangular Signal
rectangle=1.*(abs(t)<=0.5)+0.*(abs(t)>0.5);
subplot(4,3,5);
plot(t,rectangle)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Rectangle");
axis([min(t),max(t), min(rectangle)-0.5,max(rectangle)+0.5]);

%Unit Triangular Signal
triangular=(1-(abs(t)/2)).*(abs(t)<=2)+0.*(abs(t)>2);
subplot(4,3,6);
plot(t,triangular)
xlabel("Iime");
ylabel("Amplitude");
```

```
title("Unit Triangular");
axis([min(t),max(t), min(triangular)-0.5,max(triangular)+0.5]);

%Unit Signum Signal
signum=1.*(t>=0)-1.*(t<0);
subplot(4,3,7);
plot(t,signum)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Signum");
axis([min(t),max(t), min(signum)-0.5,max(signum)+0.5]);

%Unit Sinc Signal
u_sinc=sinc(t);
subplot(4,3,8);
plot(t,u_sinc)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Sinc");
axis([min(t),max(t), min(u_sinc)-0.5,max(u_sinc)+0.5]);


%Unit Real Exponential Signal
real_exponential=exp(5.*t).*(t>=0)+0.*(t<0);
subplot(4,3,9);
plot(t,real_exponential)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Real Exponential");
axis([min(t),max(t), min(real_exponential)-0.5,max(real_exponential)+0.5]);

%time interval for sin and cos Signals
t1=0:pi/12:2*pi;

%Unit Sin Signal
u_sin=sin(t1);
subplot(4,3,10);
plot(t1,u_sin)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Sinusoidal");
axis([min(t1),max(t1), min(u_sin)-0.5,max(u_sin)+0.5]);

%Unit Cosine Signal
u_cos=cos(t1);
subplot(4,3,11);
plot(t1,u_cos)
xlabel("Iime");
ylabel("Amplitude");
title("Unit  Cosinusoidal"); axis([min(t1),max(t1),
min(u_cos)-0.5,max(u_cos)+0.5]);

%time interval for saw tooth Signal
F=input('enter the frequency:');
T=1/F;
t=0:5*T/100:5*T;

%Umit Sawtooth Signal
u_saw_tooth=sawtooth(2*pi*F*t,1/2);
subplot(4,3,12);
```

```
plot(t,u_saw_tooth)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Saw Tooth");
axis([min(t),max(t), min(u_saw_tooth)-0.5,max(u_saw_tooth)+0.5]);
```

Discrete Time Signal [DTS]:

```
close all;
clear all;

%time range
t=-5:1:5;

%Unit Impulse Signal
impulse=1.*(t==0)+0.*(t~=0);
subplot(4,3,1);
stem(t,impulse)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Impulse");
axis([min(t),max(t), min(impulse)-0.5,max(impulse)+0.5]);

%Unit Step Signal
step=1.*(t>=0)+0.*(t<0);
subplot(4,3,2);
stem(t,step)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Step");
axis([min(t),max(t), min(step)-0.5,max(step)+0.5]);

%Unit Ramp Signal
ramp=t.*(t>=0)+0.*(t<0);
subplot(4,3,3);
stem(t,ramp)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Ramp");
axis([min(t),max(t), min(ramp)-0.5,max(ramp)+0.5]);

%Unit Parabolic Signal
parabolic=t.^2/2.*(t>=0)+0.*(t<0);
subplot(4,3,4);
stem(t,parabolic)
xlabel("Iime");
ylabel("amplitude");
title("Unit Parabolic");
axis([min(t),max(t), min(parabolic)-0.5,max(parabolic)+0.5]);


%Unit Square Signal
square=1.*(abs(t)<=0.5)+0.*(abs(t)>0.5);
subplot(4,3,5);
stem(t,square)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Square");
axis([min(t),max(t), min(square)-0.5,max(square)+0.5]);

%Unit Triangular Signal
```

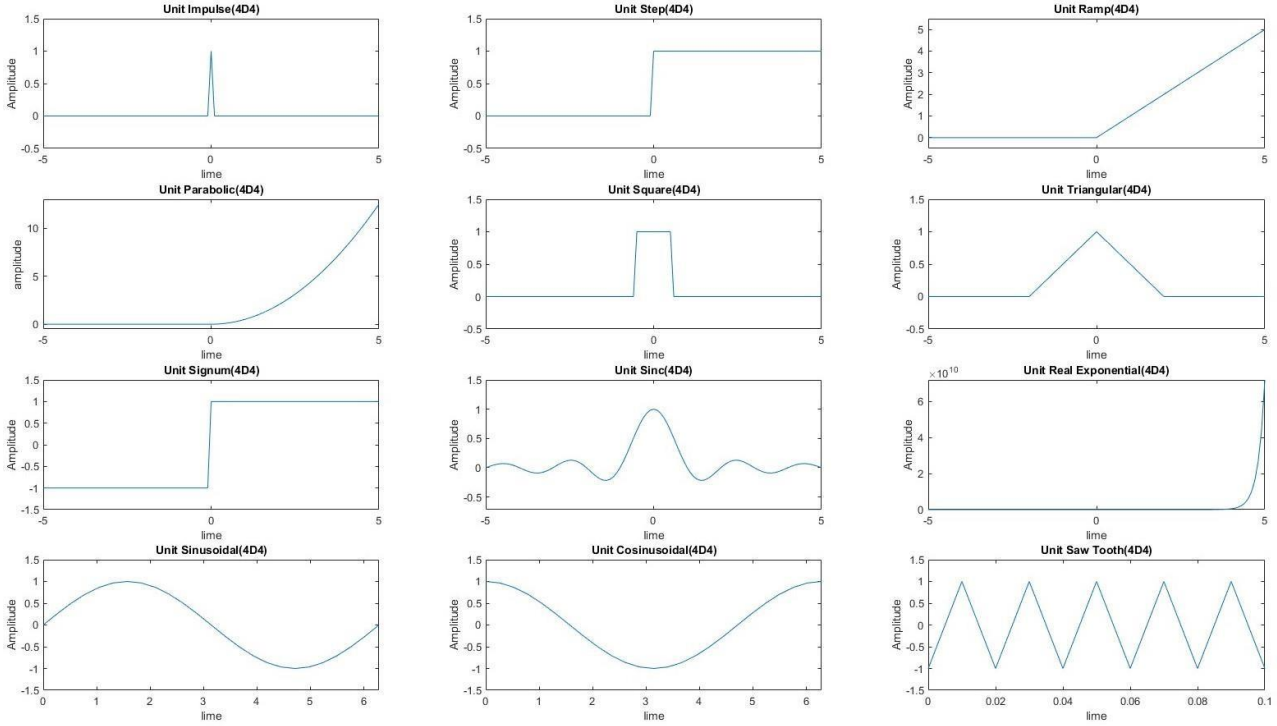
```
triangular=(1-(abs(t)/2)).*(abs(t)<=2)+0.*(abs(t)>2);
subplot(4,3,6);
stem(t,triangular)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Triangular");
axis([min(t),max(t), min(triangular)-0.5,max(triangular)+0.5]);

%Unit Signum Signal
signum=1.*(t>=0)-1.*(t<0);
subplot(4,3,7);
stem(t,signum)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Signum");
axis([min(t),max(t), min(signum)-0.5,max(signum)+0.5]);

%Unit Sinc Signal
u_sinc=sinc(t);
subplot(4,3,8);
stem(t,u_sinc)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Sinc");
axis([min(t),max(t), min(u_sinc)-0.5,max(u_sinc)+0.5]);


%Unit Real Exponential Signal
real_exponential=exp(5.*t).*(t>=0)+0.*(t<0);
subplot(4,3,9);
stem(t,real_exponential)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Real Exponential");
axis([min(t),max(t), min(real_exponential)-0.5,max(real_exponential)+0.5]);

%time interval for sin and cos Signals
t1=0:pi/12:2*pi;

%Unit Sin Signal
u_sin=sin(t1);
subplot(4,3,10);
stem(t1,u_sin)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Sinusoidal");
axis([min(t1),max(t1), min(u_sin)-0.5,max(u_sin)+0.5]);

%Unit Cosine Signal
u_cos=cos(t1);
subplot(4,3,11);
stem(t1,u_cos)
xlabel("Iime");
ylabel("Amplitude");
title("Unit  Cosinusoidal"); axis([min(t1),max(t1),
min(u_cos)-0.5,max(u_cos)+0.5]);

%time interval for saw tooth Signal
F=input('enter the frequency:');
T=1/F;
```

```
t=0:5*T/100:5*T;

%Umit Sawtooth Signal
u_saw_tooth=sawtooth(2*pi*F*t,1/2);
subplot(4,3,12);
stem(t,u_saw_tooth)
xlabel("Iime");
ylabel("Amplitude");
title("Unit Saw Tooth");
axis([min(t),max(t), min(u_saw_tooth)-0.5,max(u_saw_tooth)+0.5]);
```

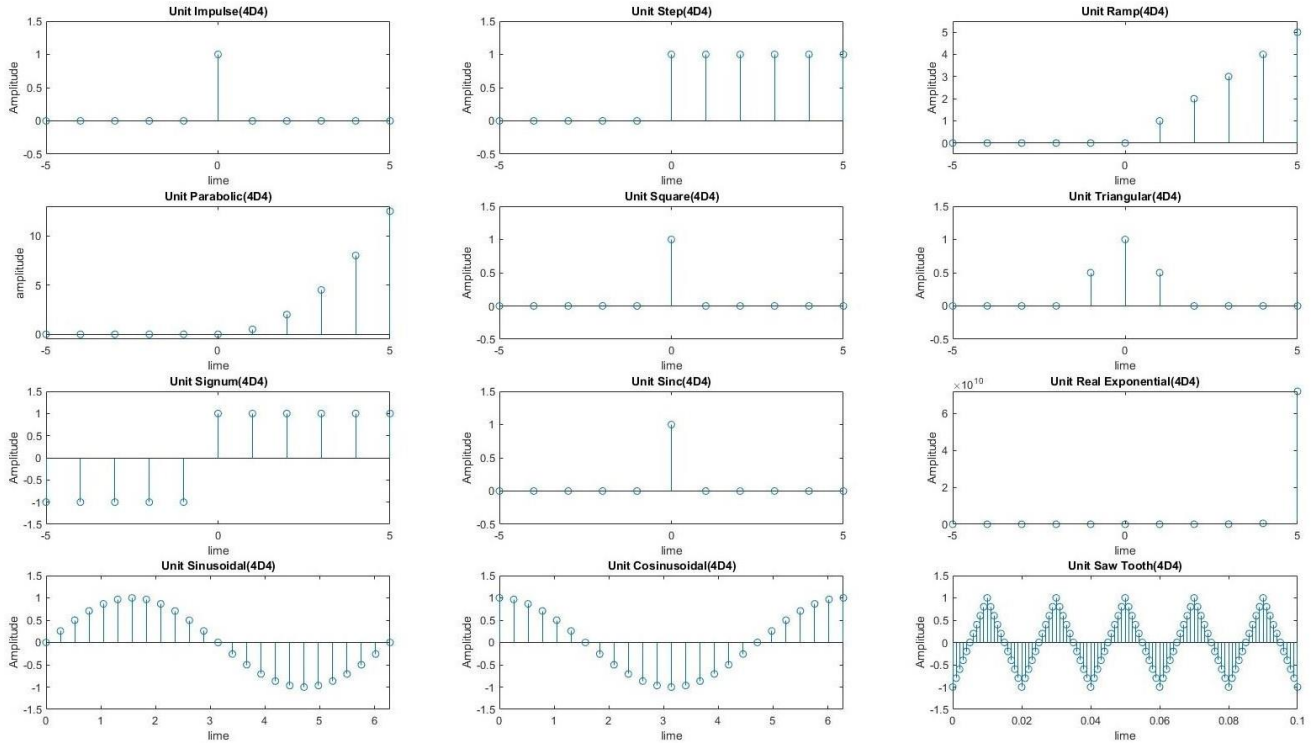
LAB PROCEDURE:

1. Open the MATLAB® software by double clicking its icon.
2. MATLAB®logo will appear and after few moments Command Prompt will appear.
3. Go to the File Menu and select a New M-file. (File →New →M-file) or in the left-hand corner a blank white paper icon will be there. Click it once.
4. A blank M-file will appear with a title „untitled"
5. Now start typing your program. After completing, save the M-file with appropriate name. To execute the program Press F5 or go to Debug Menu and select Run.
6. After execution output will appear in the Command window. If there is an error then with an alarm, type of error will appear in red color.
7. Rectify the error if any and go to Debug Menu and select Run.

OUTPUT WAVEFORMS /GRAPHS:



Continuous Time Signal



Discrete Time Signal

RESULTS:
Successfully Implemented Generation of various signals and sequences (Periodic and Aperiodic).

Experiment No. 03

Aim: Operations on signals and sequences such as Addition, Multiplication, Scaling, Shifting, Folding, Computation of Energy and Average Power.

S**oftware used:** MATLAB.

THEORY:

1. **Input Signal 1[$x_1(t)$]**
   t+2, -2<=t<=-1
   1, -1<t<=0
   2, 0<t<=1
   2-t, 1<t<=2

2. **Input Signal 2[$x_2(t)$]**
   1, -2<=t<=-1
   2, -1<t<=1
   1, 1<t<=2
   3-t, 2<t<=3

MATLAB CODE:

Continuous Time Signal [CTS]:

Arithmetic Operations

```
close all;
clear all;

%time range
t=-5:0.01:+5;

%Signal 1
Signal_1 = (t+2).*(t>=-2 & t<=-1) + (1).*(t>-1 & t<=0)+ (2).*(t>0 & t<=1)+ (2-t).*(t>1 &
t<=2);

subplot(3,3,1);
plot(t,Signal_1);
xlabel("Time");
ylabel("Amplitude");
title("Signal 1");
axis([min(t),max(t),min(Signal_1)-0.5,max(Signal_1)+0.5]);

%Signal 2
Signal_2 = (1).*(t>=-2 & t<=-1)+ (2).*(t>-1 & t<=1) + (1).*(t>1 & t<=2) + (3-t).*(t>2 &
t<=3);

subplot(3,3,2);
plot(t,Signal_2);
xlabel("Time");
ylabel("Amplitude");
title("Signal 2");
axis([min(t),max(t),min(Signal_2)-0.5,max(Signal_2)+0.5]);

%Signal Addition
Signal_Addition = Signal_1 + Signal_2;

subplot(3,3,3);
```

```
plot(t,Signal_Addition);
xlabel("Time");
ylabel("Amplitude");
title("Signal Addition");
axis([min(t),max(t),min(Signal_Addition)-0.5,max(Signal_Addition)+0.5]);

%Signal Multiplication
Signal_Multiplication = Signal_1 .* Signal_2;

subplot(3,3,4);
plot(t,Signal_Multiplication);
xlabel("Time");
ylabel("Amplitude");
title("Signal Multiplication");
axis([min(t),max(t),min(Signal_Multiplication)-0.5,max(Signal_Multiplication)+0.5]);

%Signal Subtraction
Signal_Subtraction = Signal_1 - Signal_2;

subplot(3,3,5);
plot(t,Signal_Subtraction);
xlabel("Time");
ylabel("Amplitude");
title("Signal Subtraction");
axis([min(t),max(t),min(Signal_Subtraction)-0.5,max(Signal_Subtraction)+0.5]);

%Signal Division
Signal_Division = Signal_1 ./ Signal_2;

subplot(3,3,6);
plot(t,Signal_Division);
xlabel("Time");
ylabel("Amplitude");
title("Signal Division");
axis([min(t),max(t),min(Signal_Division)-0.5,max(Signal_Division)+0.5]);

%Signal Exponential
Signal_Exponential = Signal_1 .^ Signal_2;

subplot(3,3,7);
plot(t,Signal_Exponential);
xlabel("Time");
ylabel("Amplitude");
title("Signal Exponential");
axis([min(t),max(t),min(Signal_Exponential)-0.5,max(Signal_Exponential)+0.5]);
```

Other Functions on Signals

```
%Time Range
t=-5:0.01:+5;

%Signal 1
Signal_1=Signal(t);
subplot(4,2,1);
plot(t,Signal_1);
xlabel("Time");
ylabel("Amplitude");
title("Signal 1");
axis([min(t),max(t),min(Signal_1)-0.5,max(Signal_1)+0.5]);

%Signal Left Shifting
```

```
Signal_Left_Shifting=Signal(t+3);
subplot(4,2,2);
plot(t,Signal_Left_Shifting);
xlabel("Time");
ylabel("Amplitude");
title("Signal Left Shifting");
axis([min(t),max(t),min(Signal_Left_Shifting)-0.5,max(Signal_Left_Shifting)+0.5]);

%Signal Right Shifting
Signal_Right_Shifting=Signal(t-3);
subplot(4,2,3);
plot(t,Signal_Right_Shifting);
xlabel("Time");
ylabel("Amplitude");
title("Signal Right Shifting");
axis([min(t),max(t),min(Signal_Right_Shifting)-0.5,max(Signal_Right_Shifting)+0.5]);

%Signal Amplitude Expansion
Signal_Amplitude_Expansion=2.*Signal(t);
subplot(4,2,4);
plot(t,Signal_Amplitude_Expansion);
xlabel("Time");
ylabel("Amplitude");
title("Signal Amplitude Expansion Scaling");
axis([min(t),max(t),min(Signal_Amplitude_Expansion)-
0.5,max(Signal_Amplitude_Expansion)+0.5]);

%Signal Amplitude Compression
Signal_Amplitude_Compression=0.5.*Signal(t);
subplot(4,2,5);
plot(t,Signal_Amplitude_Compression);
xlabel("Time");
ylabel("Amplitude");
title("Signal Amplitude Compression Scaling");
axis([min(t),max(t),min(Signal_Amplitude_Compression)-
0.5,max(Signal_Amplitude_Compression)+0.5]);

%Signal Time Compression
Signal_Time_Compression=Signal(2.*t);
subplot(4,2,6);
plot(t,Signal_Time_Compression);
xlabel("Time");
ylabel("Amplitude");
title("Signal Time Compression Scaling");
axis([min(t),max(t),min(Signal_Time_Compression)-0.5,max(Signal_Time_Compression)+0.5]);

%Signal Time Expansion
Signal_Time_Expansion=Signal(0.5.*t);
subplot(4,2,7);
plot(t,Signal_Time_Expansion);
xlabel("Time");
ylabel("Amplitude");
title("Signal Time Expansion Scaling");
axis([min(t),max(t),min(Signal_Time_Expansion)-0.5,max(Signal_Time_Expansion)+0.5]);

%Signal Folding
Signal_Reverse=Signal(-t);
subplot(4,2,8);
plot(t,Signal_Reverse);

xlabel("Time");
```

```
ylabel("Amplitude");
title("Signal Folding");
axis([min(t),max(t),min(Signal_Reverse)-0.5,max(Signal_Reverse)+0.5]);
```

Discrete Time Signal [DTS]:

Arithmetic Operations

```
close all;
clear all;

%time range
t=-5:1:+5;

%Signal 1
Signal_1 = (t+2).*(t>=-2 & t<=-1) + (1).*(t>-1 & t<=0)+ (2).*(t>0 & t<=1)+ (2-t).*(t>1 &
t<=2);

subplot(3,3,1);
stem(t,Signal_1);
xlabel("Time");
ylabel("Amplitude");
title("Signal 1");
axis([min(t),max(t),min(Signal_1)-0.5,max(Signal_1)+0.5]);

%Signal 1
Signal_2 = (1).*(t>=-2 & t<=-1)+ (2).*(t>-1 & t<=1) + (1).*(t>1 & t<=2) + (3-t).*(t>2 &
t<=3);

subplot(3,3,2);
stem(t,Signal_2);
xlabel("Time");
ylabel("Amplitude");
title("Signal 2");
axis([min(t),max(t),min(Signal_2)-0.5,max(Signal_2)+0.5]);

%Signal Addition
Signal_Addition = Signal_1 + Signal_2;

subplot(3,3,3);
stem(t,Signal_Addition);
xlabel("Time");
ylabel("Amplitude");
title("Signal Addition");
axis([min(t),max(t),min(Signal_Addition)-0.5,max(Signal_Addition)+0.5]);

%Signal Multiplication
Signal_Multiplication = Signal_1 .* Signal_2;

subplot(3,3,4);
stem(t,Signal_Multiplication);
xlabel("Time");
ylabel("Amplitude");
title("Signal Multiplication");
axis([min(t),max(t),min(Signal_Multiplication)-0.5,max(Signal_Multiplication)+0.5]);

%Signal Subtraction
Signal_Subtraction = Signal_1 - Signal_2;

subplot(3,3,5);
stem(t,Signal_Subtraction);
xlabel("Time");
```

```
ylabel("Amplitude");
title("Signal Subtraction");
axis([min(t),max(t),min(Signal_Subtraction)-0.5,max(Signal_Subtraction)+0.5]);

%Signal Division
Signal_Division = Signal_1 ./ Signal_2;

subplot(3,3,6);
stem(t,Signal_Division);
xlabel("Time");
ylabel("Amplitude");
title("Signal Division");
axis([min(t),max(t),min(Signal_Division)-0.5,max(Signal_Division)+0.5]);

%Signal Exponential
Signal_Exponential = Signal_1 .^ Signal_2;

subplot(3,3,7);
stem(t,Signal_Exponential);
xlabel("Time");
ylabel("Amplitude");
title("Signal Exponential");
axis([min(t),max(t),min(Signal_Exponential)-0.5,max(Signal_Exponential)+0.5]);
```

Other Functions on Signals

```
%Time Range
t=-5:1:+5;

%Signal 1
Signal_1=Signal(t);
subplot(4,2,1);
stem(t,Signal_1);
xlabel("Time");
ylabel("Amplitude");
title("Signal 1");
axis([min(t),max(t),min(Signal_1)-0.5,max(Signal_1)+0.5]);

%Signal Left Shifting
Signal_Left_Shifting=Signal(t+3);
subplot(4,2,2);
stem(t,Signal_Left_Shifting);
xlabel("Time");
ylabel("Amplitude");
title("Signal Left Shifting");
axis([min(t),max(t),min(Signal_Left_Shifting)-0.5,max(Signal_Left_Shifting)+0.5]);

%Signal Right Shifting
Signal_Right_Shifting=Signal(t-3);
subplot(4,2,3);
stem(t,Signal_Right_Shifting);
xlabel("Time");
ylabel("Amplitude");
title("Signal Right Shifting");
axis([min(t),max(t),min(Signal_Right_Shifting)-0.5,max(Signal_Right_Shifting)+0.5]);

%Signal Amplitude Expansion
Signal_Amplitude_Expansion=2.*Signal(t);
subplot(4,2,4);
stem(t,Signal_Amplitude_Expansion);
xlabel("Time");
```

```
ylabel("Amplitude");
title("Signal Amplitude Expansion Scaling");
axis([min(t),max(t),min(Signal_Amplitude_Expansion)-
0.5,max(Signal_Amplitude_Expansion)+0.5]);

%Signal Amplitude Compression
Signal_Amplitude_Compression=0.5.*Signal(t);
subplot(4,2,5);
stem(t,Signal_Amplitude_Compression);
xlabel("Time");
ylabel("Amplitude");
title("Signal Amplitude Compression Scaling");
axis([min(t),max(t),min(Signal_Amplitude_Compression)-
0.5,max(Signal_Amplitude_Compression)+0.5]);

%Signal Time Compression
Signal_Time_Compression=Signal(2.*t);
subplot(4,2,6);
stem(t,Signal_Time_Compression);
xlabel("Time");
ylabel("Amplitude");
title("Signal Time Compression Scaling");
axis([min(t),max(t),min(Signal_Time_Compression)-0.5,max(Signal_Time_Compression)+0.5]);

%Signal Time Expansion
Signal_Time_Expansion=Signal(0.5.*t);
subplot(4,2,7);
stem(t,Signal_Time_Expansion);
xlabel("Time");
ylabel("Amplitude");
title("Signal Time Expansion Scaling");
axis([min(t),max(t),min(Signal_Time_Expansion)-0.5,max(Signal_Time_Expansion)+0.5]);

%Signal Folding
Signal_Reverse=Signal(-t);
subplot(4,2,8);
stem(t,Signal_Reverse);
xlabel("Time");
ylabel("Amplitude");
title("Signal Folding");
axis([min(t),max(t),min(Signal_Reverse)-0.5,max(Signal_Reverse)+0.5]);
```

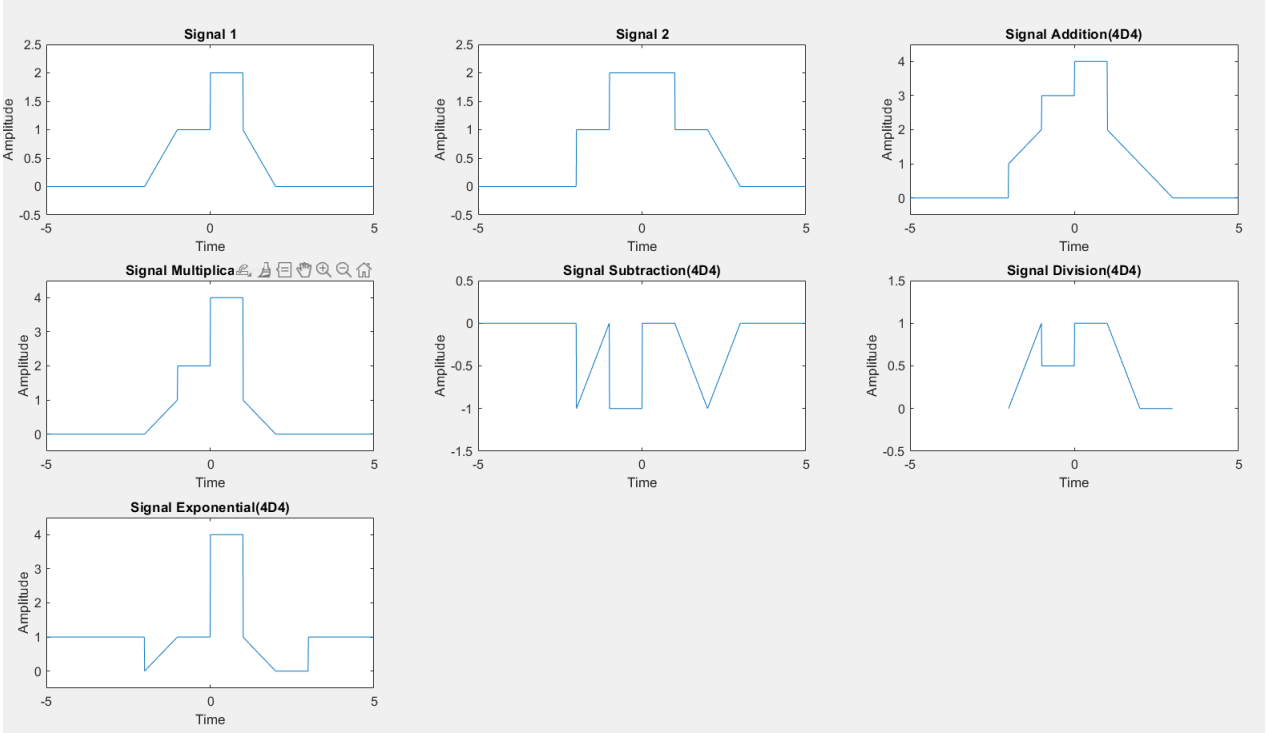
Energy and Average Power Computation

```
%TimeStamp
T = 10;

%Time Range
t=-T:0.01:T;

Signal_1=T.*sin(2*pi.*t);
Signal_2 = Signal_1.^2;

Energy = trapz(t,Signal_2);
Power = Energy/(2*T);

disp(['Energy:',num2str(Energy),'Joule']);
disp(['Power:',num2str(Power),'Watts']);
```

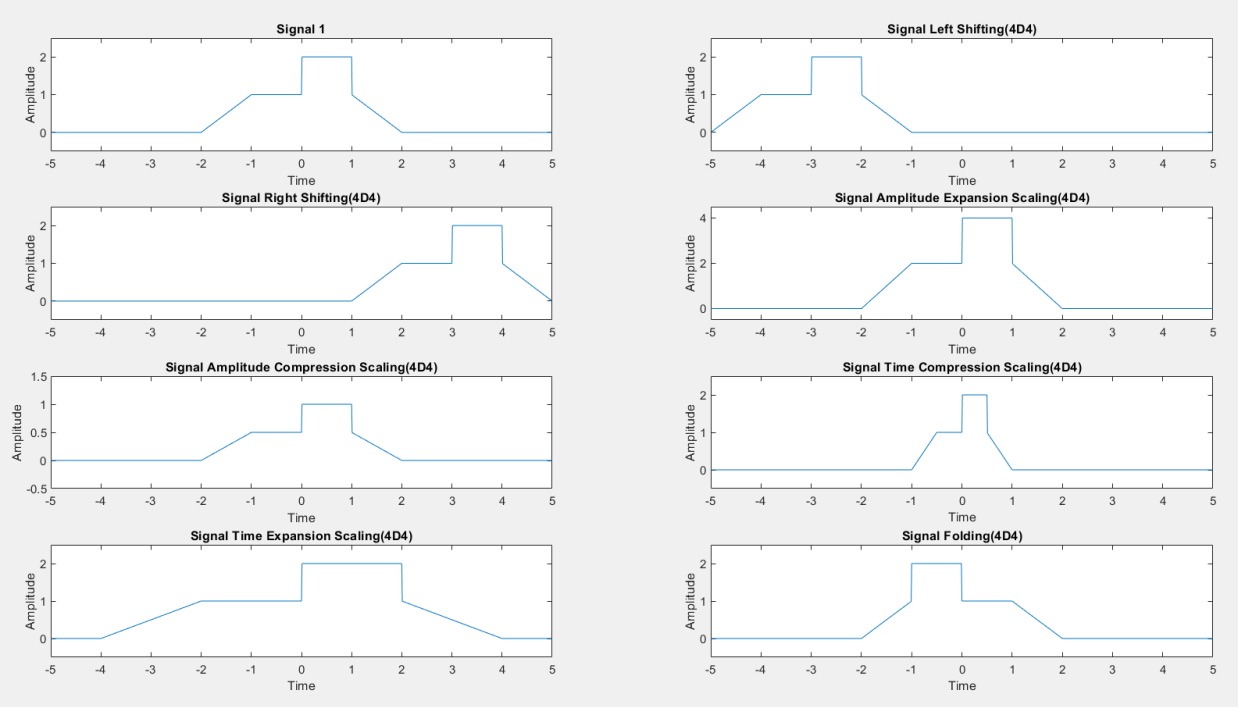
LAB PROCEDURE:

1. Open the MATLAB® software by double clicking its icon.
2. MATLAB®logo will appear and after few moments Command Prompt will appear.
3. Go to the File Menu and select a New M-file. (File →New →M-file) or in the left-hand corner a blank white paper icon will be there. Click it once.
4. A blank M-file will appear with a title „untitled"
5. Now start typing your program. After completing, save the M-file with appropriate name. To execute the program Press F5 or go to Debug Menu and select Run.
6. After execution output will appear in the Command window. If there is an error then with an alarm, type of error will appear in red color.
7. Rectify the error if any and go to Debug Menu and select Run.

OUTPUT WAVEFORMS /GRAPHS:

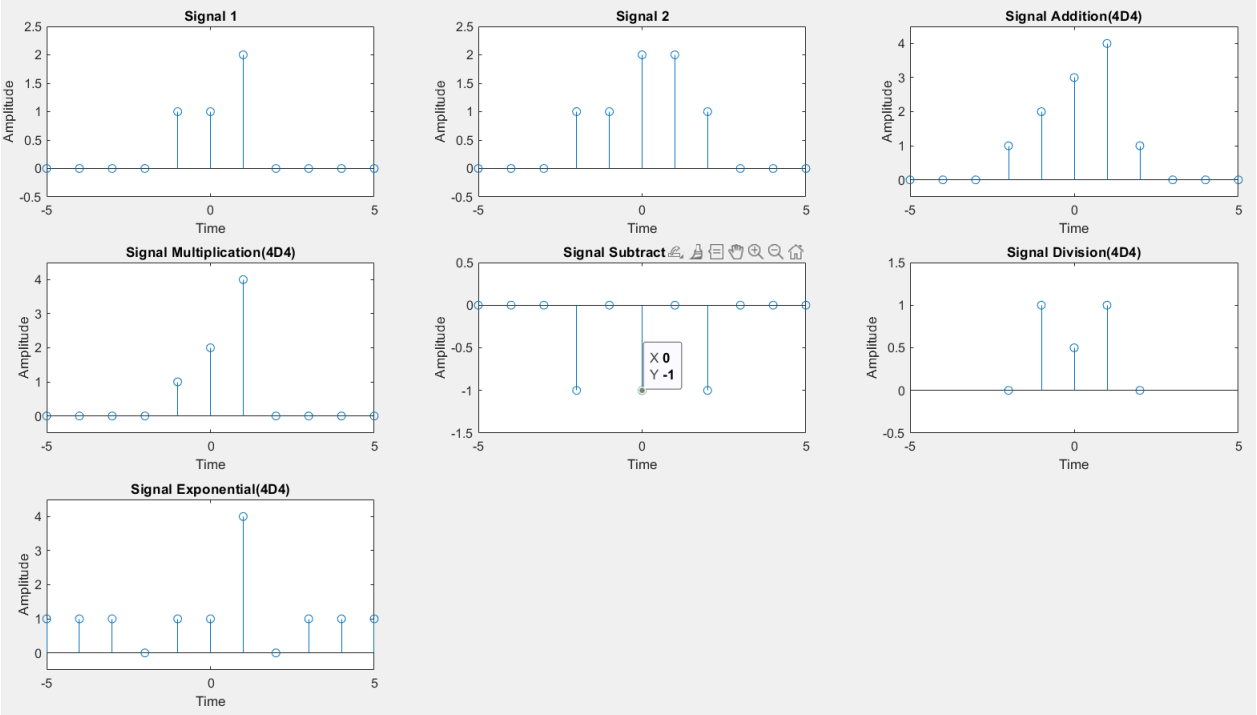


Arithmetic Operations on Signals

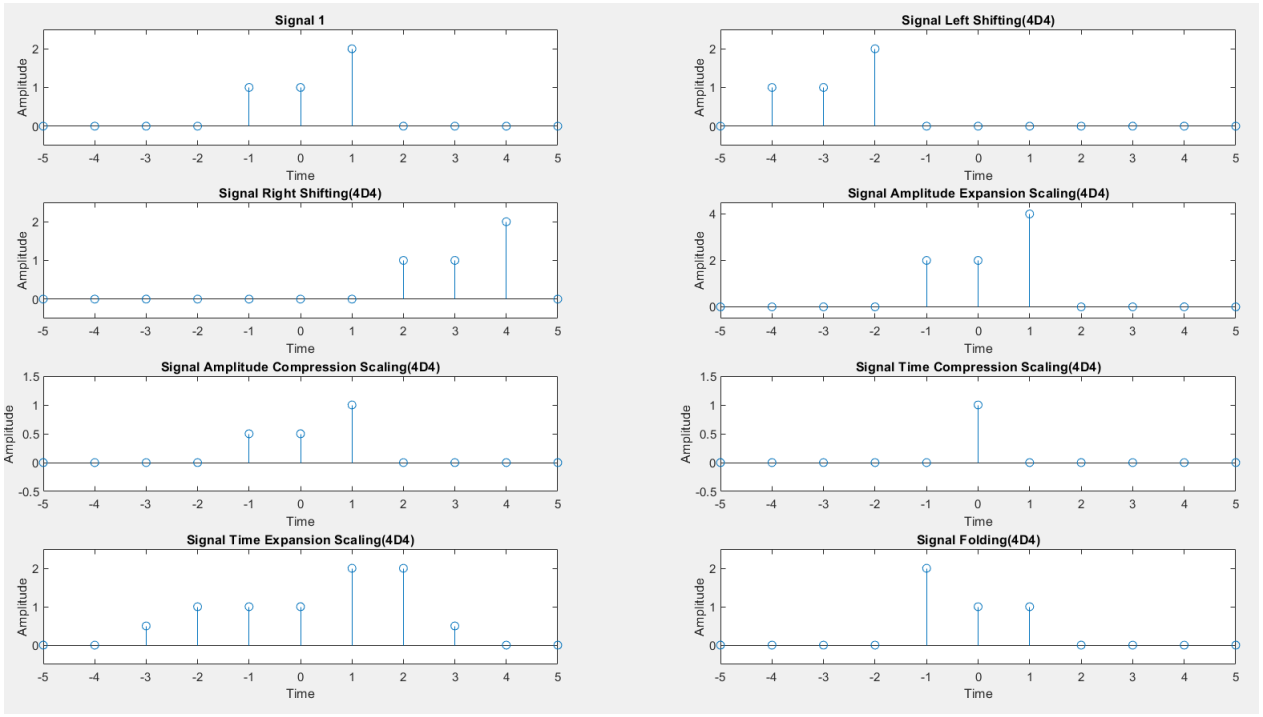


Other Operations on Signals

Continuous Time Signal



Arithmetic Operations on Signals



Other Operations on Signals

Discrete Time Signal

```
>> Energy_Power_of_Signal
Energy:1000Joule
Power:50Watts
```

Computation of Energy and Power

RESULTS:
Successfully Implemented Operations on signals and sequences such as Addition, Multiplication, Scaling, Shifting, Folding, Computation of Energy and Average Power.

Experiment No. 04

Aim: Finding the Even and Odd parts of Signal / Sequence and Real and imaginary parts of Signal.

Software used: MATLAB.

THEORY:

Continuous Time Signal[CTS]:

$x(t)= x_e(t)+x_0(t)$----------(1)

$x(-t)= x_e(-t)+x_0(-t) = x_e(t)-x_0(t)$----------(2)

(1) + (2)

$2x_e(t) = x(t)+ x(-t)$

$x_e(t) = [x(t)+ x(-t)]/2$

$2x_o(t) = x(t)-x(-t)$

$x_o(t) = [x(t)-x(-t)]/2$

Discrete Time Signal[DTS]:

$x(n)= x_e(n)+x_0(n)$----------(3)

$x(-n)= x_e(-t)+x_0(-n) = x_e(n)-x_0(n)$ ---------(4)

(3) + (4)

$2x_e(n) = x(n)+ x(-n)$

$x_e(n) = [x(n)+ x(-n)]/2$

$2x_o(n) = x(n)-x(-n)$

$x_o(n) = [x(n)-x(-n)]/2$

let $x(t) = e^{j2\pi t}$

MATLAB CODE:

Continuous Time Signal [CTS]:

```
clear all
close all

t = -5:0.001:5;

x1 = exp(1i*2*pi.*t);  %Exponential Signal
%x1 = cos(t);           Cosine Signal
%x1 = sin(t);           Sine Signal
subplot(3,2,1);
plot(t,x1);
xlabel("Time");
ylabel("Amplitude");
title("Signal 1");grid;

x2 = exp((-1i)*2*pi.*t);   %Exponential Signal
%x2 = cos(-t);           Cosine Signal
%x2  = sin(-t);          Sine Signal
subplot(3,2,2);
plot(t,x2);
xlabel("Time");
ylabel("Amplitude");
```

```
title("Signal 2");grid;

if(x1==x2)
    disp("The given Signal is Even");

else if(x1==-x2)
    disp("The given Signal is Odd");

else
    disp("The given Signal is Neither Even Nor Odd");

end
end
xe = (x1+x2)/2;

subplot(3,2,3);
plot(t,xe);
xlabel("Time");
ylabel("Amplitude");
title("Even Signal");grid;

xo = (x1-x2)/2;

subplot(3,2,4);
plot(t,xo);
xlabel("Time");
ylabel("Amplitude");
title("Odd Signal");grid;

Real = real(x1);

subplot(3,2,5);
plot(t,Real);
xlabel("Time");
ylabel("Amplitude");
title("Real Part of Signal");grid;

Imagimary = imag(x2);

subplot(3,2,6);
plot(t,Imagimary);
xlabel("Time");
ylabel("Amplitude");
title("Imagimary Part of Signal");grid;
```

Discrete Time Signal [DTS]:

```
clear all
close all

t = -5:1:5;

x1 = exp(1i*2*pi.*t);  %Exponential Signal
%x1 = cos(t);            Cosine Signal
%x1 = sin(t);            Sine Signal
subplot(2,2,1);
stem(t,x1);
xlabel("Time");
ylabel("Amplitude");
title("Signal 1");grid;

%x2 = exp((-1i)*2*pi.*t);   Exponential Signal
%x2 = cos(-t);             Cosine Signal
x2  = sin(-t);            %Sine Signal
subplot(2,2,2);
stem(t,x2);
xlabel("Time");
ylabel("Amplitude");
title("Signal 2");grid;

if(x1==x2)
    disp("The given Signal is Even");

else if(x1==-x2)
    disp("The given Signal is Odd");

else
    disp("The given Signal is Neither Even Nor Odd");

end
end
xe = (x1+x2)/2;

subplot(2,2,3);
stem(t,xe);
xlabel("Time");
ylabel("Amplitude");
title("Even Signal");grid;

xo = (x1-x2)/2;

subplot(2,2,4);
stem(t,xo);
xlabel("Time");
ylabel("Amplitude");
title("Odd Signal");grid;
```

LAB PROCEDURE:

1. Open the MATLAB® software by double clicking its icon.
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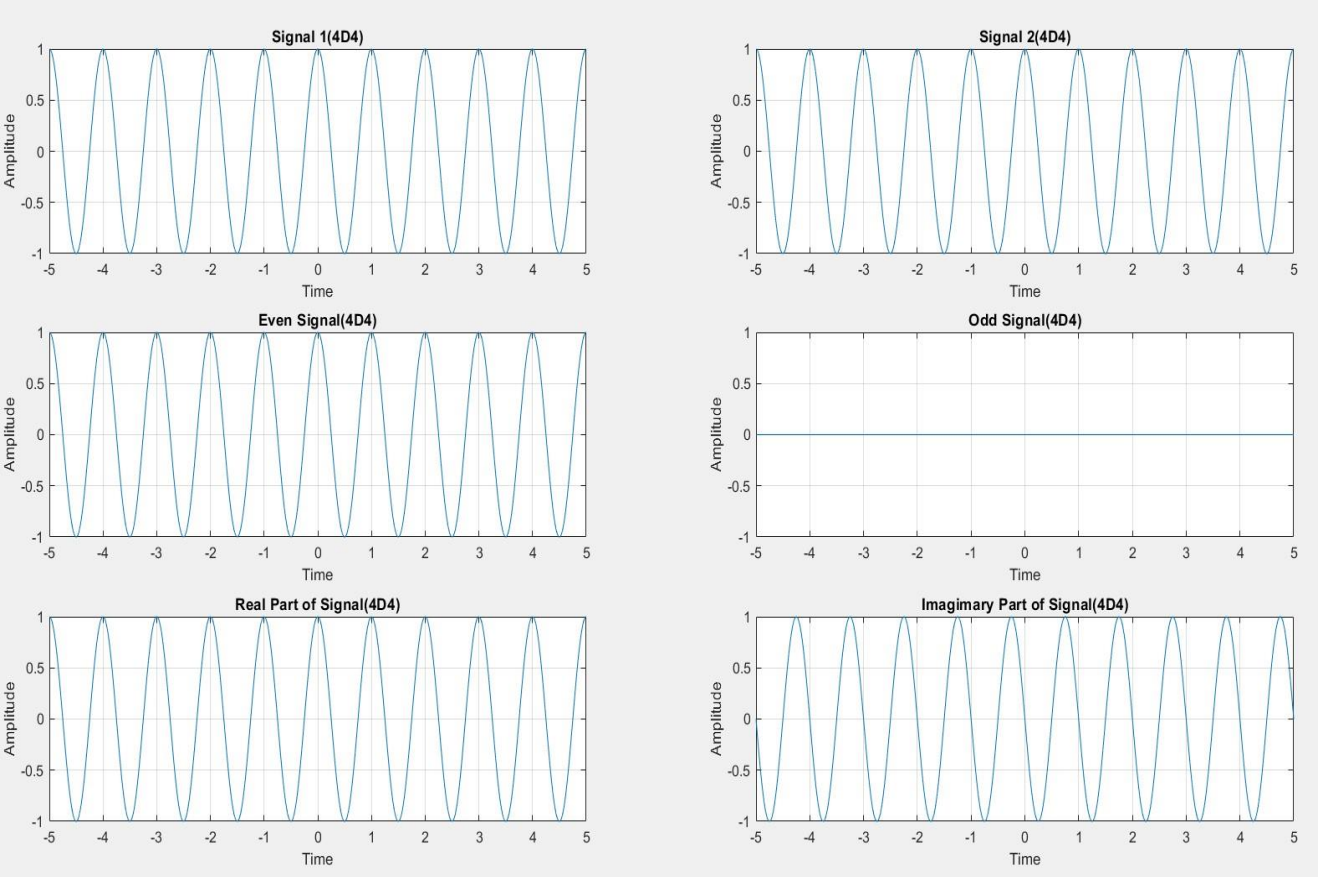
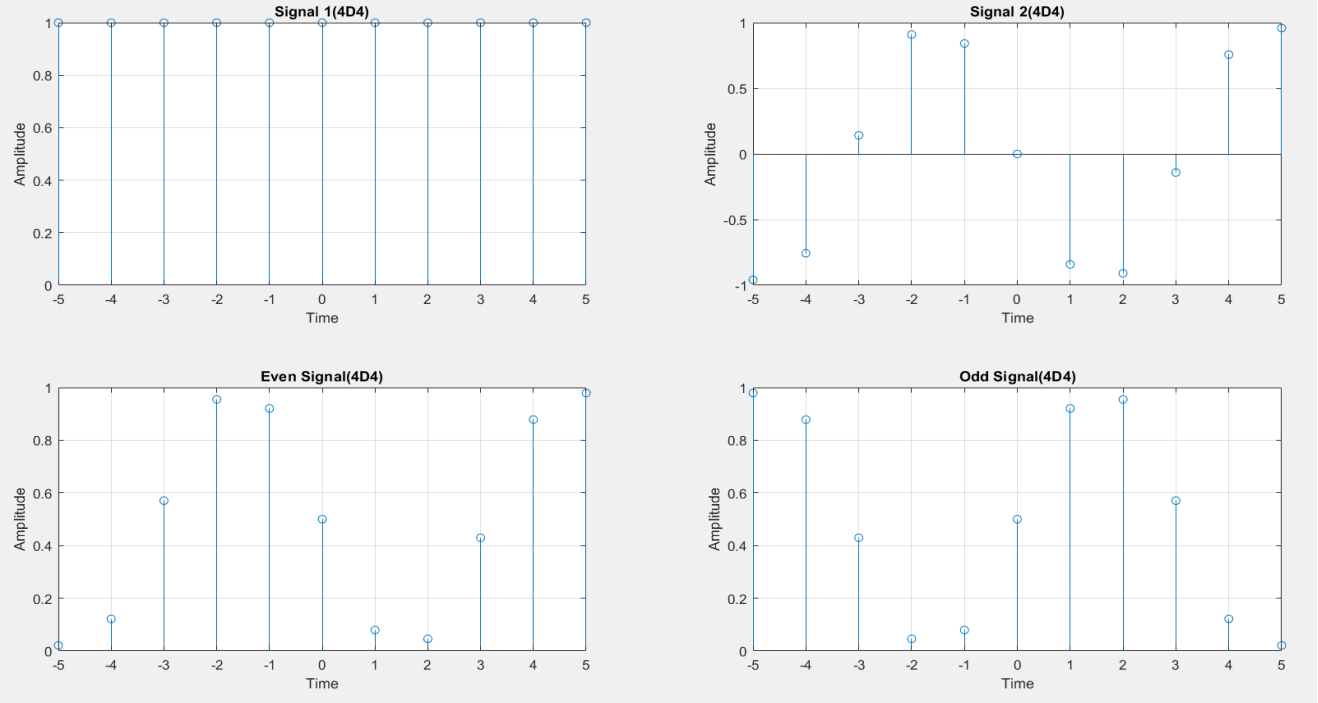
6. After execution output will appear in the Command window. If there is an error then with an alarm, type of error will appear in red color.
7. Rectify the error if any and go to Debug Menu and select Run.

OUTPUT WAVEFORMS /GRAPHS:



Continuous Time Signal



Discrete Time Signal

RESULTS:

Successfully Implemented Finding the Even and Odd parts of Signal / Sequence and Real and imaginary parts of Signal.

Experiment No. 05

Aim: Verification of Gibb‟s Phenomenon.

S**oftware used:** MATLAB.

THEORY:

Gibbs phenomenon, also known as the Gibbs phenomenon or ringing artifacts, is a phenomenon that occurs in signal processing and image processing. It is named after J. Willard Gibbs, the American physicist and mathematician who first described it. The Gibbs phenomenon is characterized by the presence of oscillations or ringing artifacts near the edges of a signal or an image when it is subjected to certain types of processing.

One common scenario where the Gibbs phenomenon is observed is in the Fourier analysis of signals. When a signal with sharp transitions or discontinuities is subjected to Fourier transformation, the resulting spectrum exhibits overshoots and undershoots, leading to ringing artifacts. This is because the ideal step function (which has abrupt changes) cannot be perfectly represented by a finite number of sinusoidal components

MATLAB CODE:

```
t=-3:0.01:3;
w=2*pi;
c0=zeros(1,length(t));
for i = 1:4
    x=c0;
    N=input("Enter no of Oscillations:");
    for n=1:N
        cn=(2/n*pi)*sin(n*pi/2);
        cnn=cn;
        x=x+(cn)*exp(1i*n*w.*t)+(cnn)*exp(-1i*n*w.*t);
    end
    subplot(2,2,i);
    plot(t,x);
    xlabel("time");
    ylabel("Amplitude");
    title("Gibbs Phenomenon for N=",num2str(N));
    grid
end
```

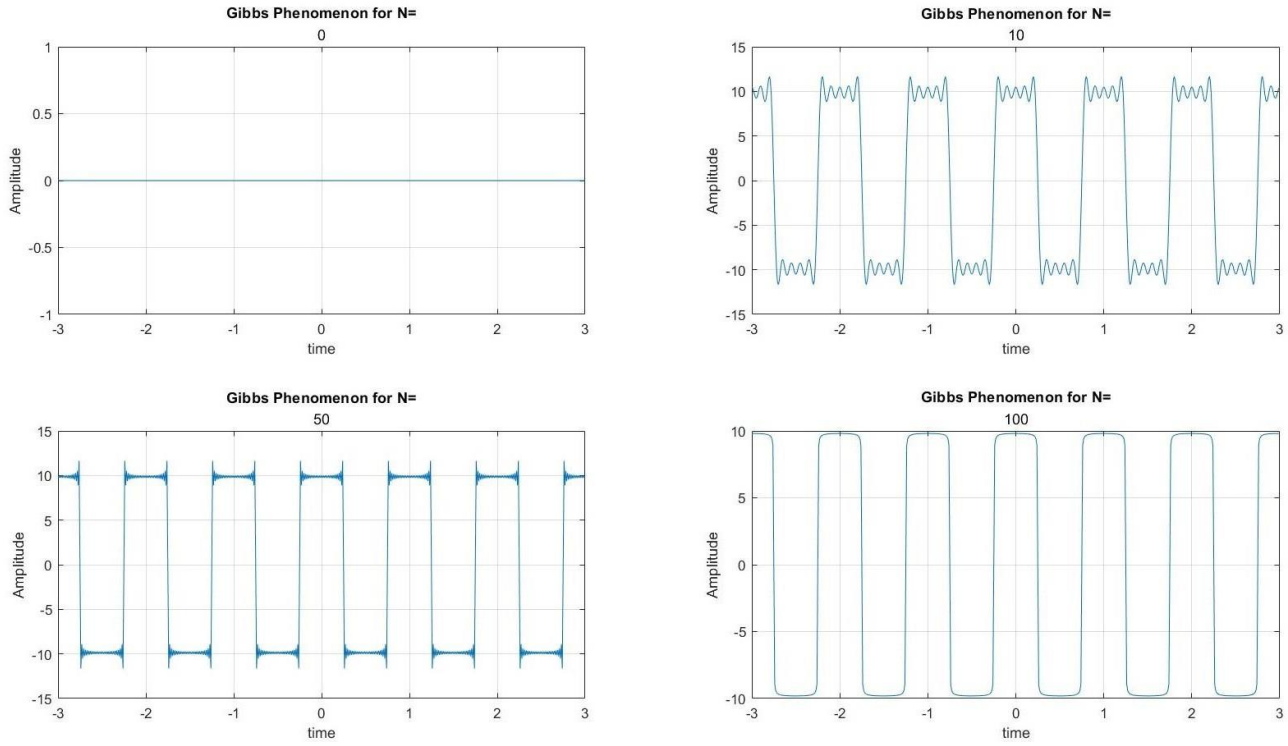
LAB PROCEDURE:

1. Open the MATLAB® software by double clicking its icon.
2. MATLAB®logo will appear and after few moments Command Prompt will appear.
3. Go to the File Menu and select a New M-file. (File →New →M-file) or in the left-hand corner a blank white paper icon will be there. Click it once.
4. A blank M-file will appear with a title „untitled‟
5. Now start typing your program. After completing, save the M-file with appropriate name. To execute the program Press F5 or go to Debug Menu and select Run.
6. After execution output will appear in the Command window. If there is an error then with an

alarm, type of error will appear in red color.

7. Rectify the error if any and go to Debug Menu and select Run.

OUTPUT WAVEFORMS /GRAPHS:



Gibb‟s Phenomenon

RESULTS:

Successfully Verified Gibb‟s Phenomenon using Matlab.

Experiment No. 06

Aim: Finding the Fourier Transform of a given signal and plotting its magnitude and phase spectrum.

Software used: MATLAB.

THEORY:

The Fourier transform is a mathematical formula that transforms a signal sampled in time or space to the same signal sampled in temporal or spatial frequency. In signal processing, the Fourier transform can reveal important characteristics of a signal, namely, its frequency components.

$X(\omega)=\int_{-\infty}^{\infty} x(t)e^{-J\omega t}\,dt$

where x(t)=given Signal and X(ω)=given signal in Frequency Domain

$X(\omega)=\sum_{-\infty}^{\infty} x(t)e^{-j\omega t}$

MATLAB CODE:

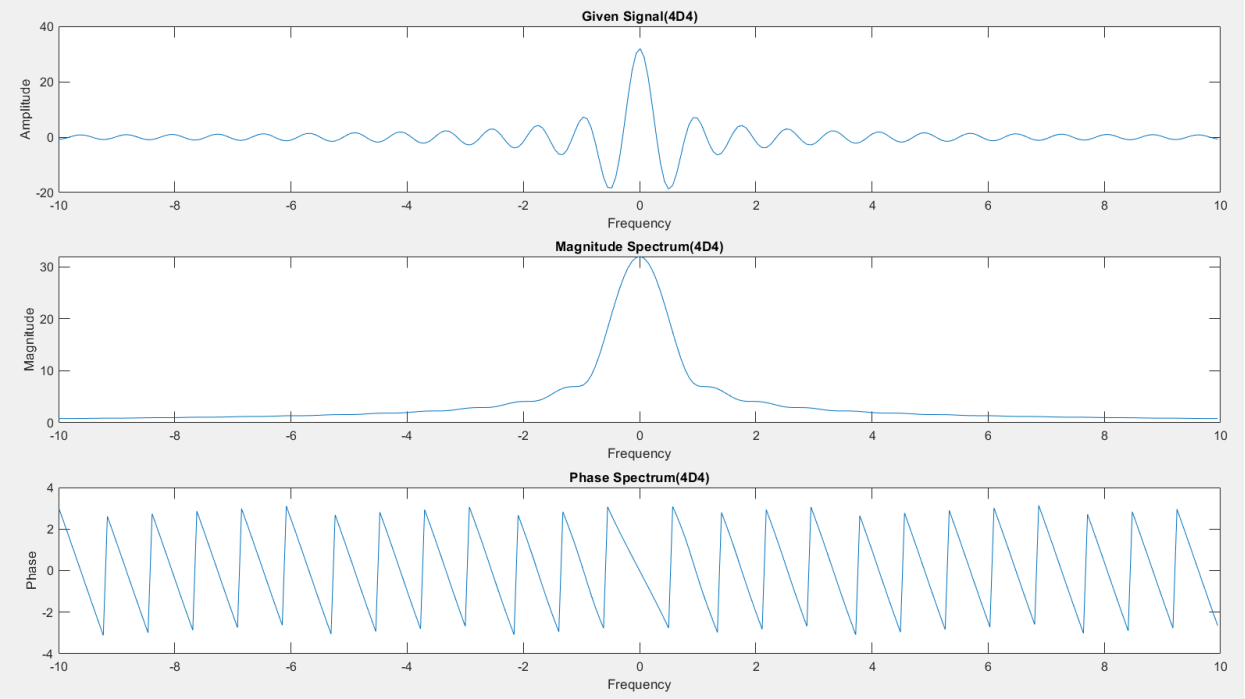
```
t = -10:0.1:10;
syms t w;

x = int(t*exp(-1i*w*t),t,[0,8]);
w1 = -10:0.07:10;
x1 = subs(x,w,w1);
mgx = abs(x1);
phx = angle(x1);

subplot(3,1,1);
plot(w1,x1);
xlabel("Frequency");
ylabel("Amplitude");
title("Given Signal");

subplot(3,1,2);
plot(w1,mgx);
xlabel("Frequency");
ylabel("Magnitude");
title("Magnitude Spectrum");

subplot(3,1,3);
plot(w1,phx);
xlabel("Frequency");
ylabel("Phase");
title("Phase Spectrum");
```

LAB PROCEDURE:

1. Open the MATLAB® software by double clicking its icon.
2. MATLAB®logo will appear and after few moments Command Prompt will appear.
3. Go to the File Menu and select a New M-file. (File →New →M-file) or in the left-hand corner a blank white paper icon will be there. Click it once.
4. A blank M-file will appear with a title „untitled"

5. Now start typing your program. After completing, save the M-file with appropriate name. To execute the program Press F5 or go to Debug Menu and select Run.
6. After execution output will appear in the Command window. If there is an error then with an alarm, type of error will appear in red color.
7. Rectify the error if any and go to Debug Menu and select Run.

OUTPUT WAVEFORMS /GRAPHS:



Fourier Transform of Signal

RESULTS:

Successfully Implemented Finding the Fourier Transform of a given signal and plotting its magnitude and phase spectrum.

Experiment No. 07

Aim: Finding the Convolution between (i) Signals (ii) Sequences

S**oftware used:** MATLAB.

THEORY:

Convolution is a mathematical operation that combines two signals to produce a third signal. It is a fundamental operation in signal processing and mathematics, widely used in various fields including physics, engineering, and computer science. The convolution of two signals f(t) and g(t) is denoted by (f∗g)(t) and is defined as follows:

$(f*g)(t)=\int_{-\infty}^{\infty} f(\tau).g(t-\tau)d\tau$

This integral represents the area under the product of the two signals as one is shifted with respect to the other. Here are some key points about convolution:

Continuous Convolution:

For continuous signals, the convolution integral is used.
The integral is taken over the entire real line $(-\infty,\infty)(-\infty,\infty)$.

$(f*g)(t)=\int_{-\infty}^{\infty} f(\tau).g(t-\tau)d\tau$

Discrete Convolution:

For discrete signals, the convolution sum is used.
The sum is taken over all possible values of the discrete variable.

$(f*g)[n]=\sum_{k=-\infty}^{\infty} f[k].g[n-k]$

Convolution is used in various applications, such as filtering, signal processing, and solving differential equations. In image processing, for example, convolution is often employed for tasks like blurring, sharpening, and edge detection using convolution kernels or masks.

In practice, convolution is frequently implemented using discrete methods for numerical efficiency. For continuous signals, the convolution integral may be computed using numerical methods or approximated using discrete techniques like the Fast Fourier Transform (FFT).

MATLAB CODE:
Continuous Time Signal [CTS]:

```
clear all;
close all;
t1=-2:0.01:2;
x=exp(-2.*t1).*(t1>=0) + 0.*(t1<0);
t2=-1:0.01:3;
h=1.*(t2>=0) + 0.*(t2<0);
y=conv(x,h);
a=min(t1)+min(t2);
b=max(t1)+max(t2);
t3=a:0.01:b;
```

```
subplot(3,1,1);
plot(t1,x);
xlabel("time t");
ylabel("amplitude x");
title("input signal");
subplot(3,1,2);
plot(t2,h);
xlabel("time t");
ylabel("amplitude x");
title("system response");
subplot(3,1,3);
plot(t3,y)
xlabel("time t");
ylabel("amplitude x");
title("convloution");
```

Discrete Time Signal [DTS]:

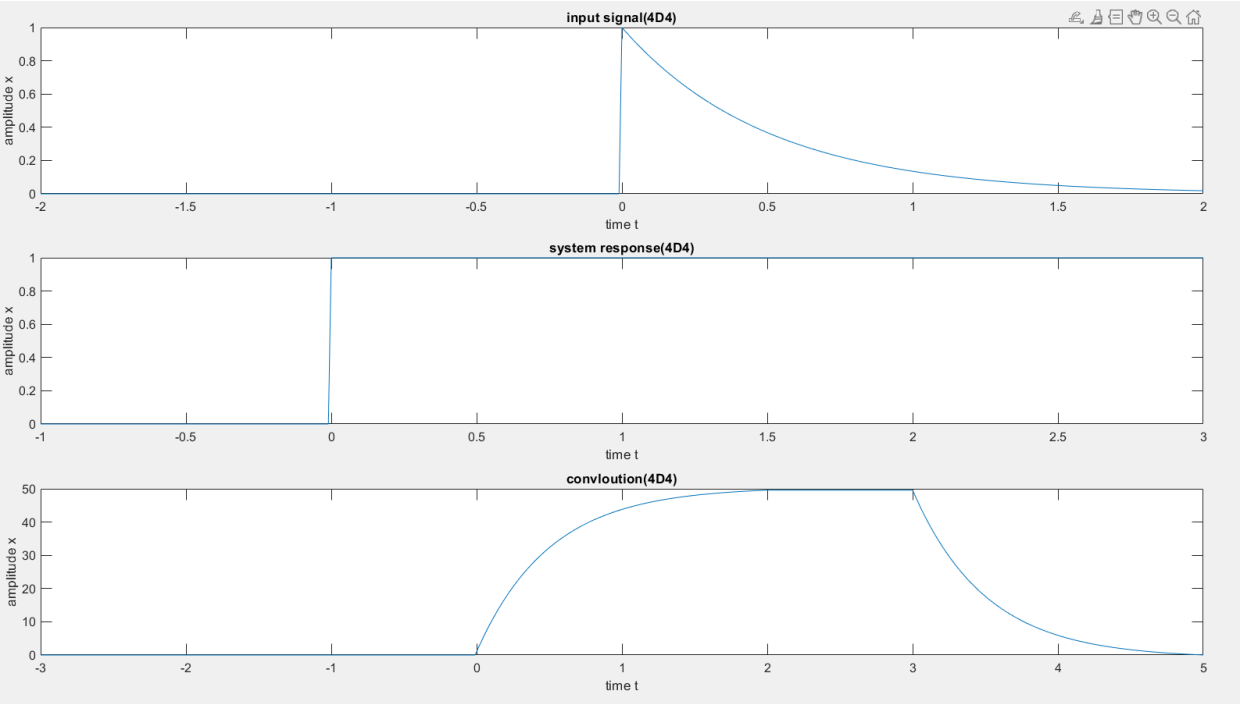
```
clear all;
close all;
n1=-1:1:2;
x=[1 2 3 -1];
n2=0:1:4;
h=[2 -1 -2 4 3];
y=conv(x,h);
a=min(n1)+min(n2);
b=max(n1)+max(n2);
n3=a:1:b;

subplot(3,1,1);
stem(n1,x);
xlabel("time t");
ylabel("amplitude x");
title("input signal");
subplot(3,1,2);
stem(n2,h);
xlabel("time t");

ylabel("amplitude x");
title("system response");
subplot(3,1,3);
stem(n3,y)
xlabel("time t");
ylabel("amplitude x");
title("convloution");
```

LAB PROCEDURE:

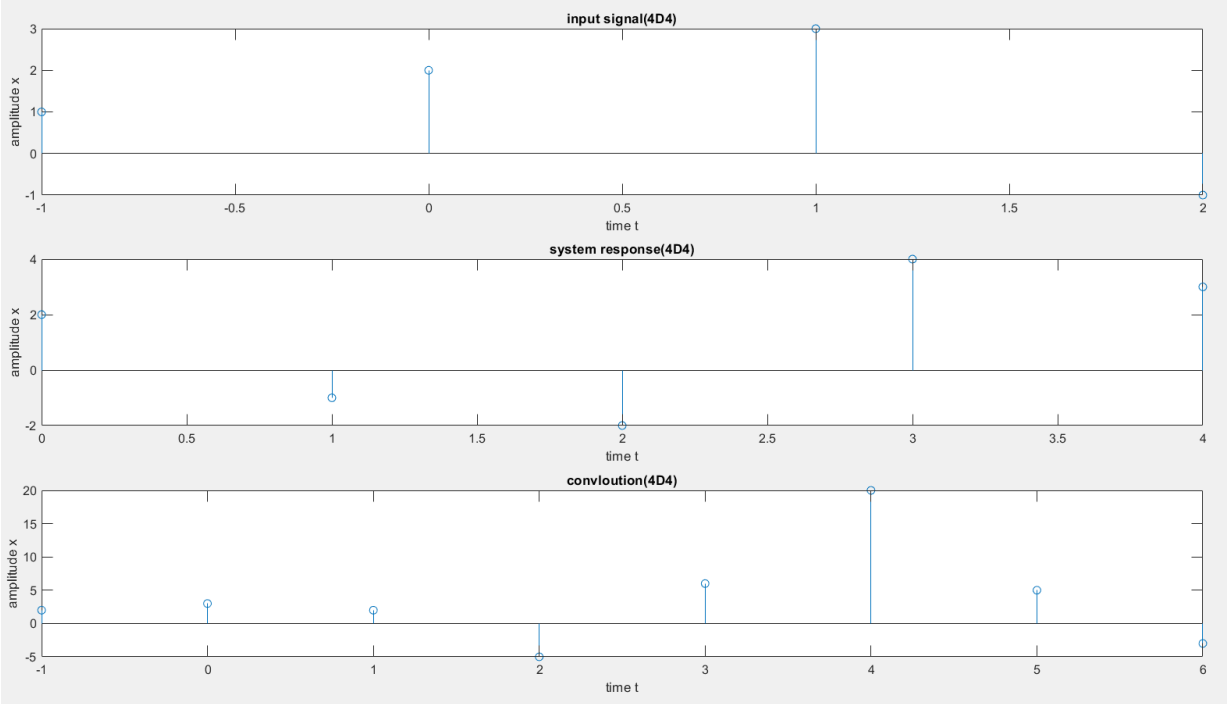
1. Open the MATLAB® software by double clicking its icon.
2. MATLAB®logo will appear and after few moments Command Prompt will appear.
3. Go to the File Menu and select a New M-file. (File →New →M-file) or in the left-hand corner a blank white paper icon will be there. Click it once.
4. A blank M-file will appear with a title „untitled"
5. Now start typing your program. After completing, save the M-file with appropriate name. To execute the program Press F5 or go to Debug Menu and select Run.
6. After execution output will appear in the Command window. If there is an error then with an alarm, type of error will appear in red color.

7. Rectify the error if any and go to Debug Menu and select Run.

OUTPUT WAVEFORMS /GRAPHS:



Continuous Time Signal



Discrete Time Signal

RESULTS:

Successfully Implemented Finding the Convolution between (i) Signals (ii) Sequences

Experiment No. 08

Aim: Finding the Auto Correlation and Cross Correlation of (i) Signals (ii) Sequences

S**oftware used:** MATLAB.

THEORY:

Correlation is another fundamental operation in signal processing that measures the similarity between two signals or sequences. There are two main types of correlation: cross-correlation and auto-correlation.

1) Cross Correlation:

Cross-correlation measures the similarity between two signals as one signal is shifted with respect to the other. For two continuous signals f(t) and g(t), the cross-correlation Rfg(τ) is defined as:

$R_{fg}(\tau)=\int_{-\infty}^{\infty} f^{*}(t)\cdot g(t+\tau)dt$

where f∗(t) is the complex conjugate of f(t). For discrete signals, the cross-correlation $R_{fg}[m]$ is given by:
$R_{fg}[m] = \sum_{n=-\infty}^{\infty} f*[n] \cdot g[n+m]$

2) Auto Correlation:

Auto-correlation measures the similarity of a signal with itself as it is shifted in time. For a

continuous signal f(t), the auto-correlation Rff(τ) is defined as:

$R_{ff}(\tau)=\int_{-\infty}^{\infty} f*(t)\cdot f(t+\tau)dt$

For a discrete signal, the auto-correlation Rff[m] is given by:

$Rff[m] = \sum_{n=-\infty}^{\infty} f^{*}[n]\cdot f[n+m]$

MATLAB CODE:

Continuous Time Signal [CTS]:

```
close all
clear all

t1 = -3:0.01:3;
x = 1.*((t1>=0)&(t1<=2))+0.*((t1<0)&(t1>2));

t2 = -t1;

a = min(t1)+min(t2);
b = max(t1)+max(t2);

t = a:0.01:b;
RXX = xcorr(x,x);

subplot(2,3,1);
plot(t1,x);
xlabel("Time");
ylabel("Amplitude");
title("Input Signal");
```

```
subplot(2,3,2);
plot(t2,x);
xlabel("Time");
ylabel("Amplitude");
title("Received Signal");

subplot(2,3,3);
plot(t,RXX);
xlabel("Time");
ylabel("Amplitude");
title("Auto Correlation");

%Cross Correlation
t1 = -3:0.01:3;
x = 1.*((t1>=0)&(t1<=2))+0.*((t1<0)&(t1>2));

t2 = -3:0.01:3;
y = 1.*((t2>=0)&(t2<=3))+0.*((t2<0)&(t2>3));
t3 = -t2;

a = min(t1)+min(t3);
b = max(t1)+max(t3);

t = a:0.01:b;
RXY = xcorr(x,y);

subplot(2,3,4);
plot(t1,x);
xlabel("Time");
ylabel("Amplitude");
title("Input Signal");

subplot(2,3,5);
plot(t3,y);
xlabel("Time");
ylabel("Amplitude");
title("Received Signal");

subplot(2,3,6);
plot(t,RXY);
xlabel("Time");
ylabel("Amplitude");
title("Cross Correlation");
```

Discrete Time Signal [DTS]:

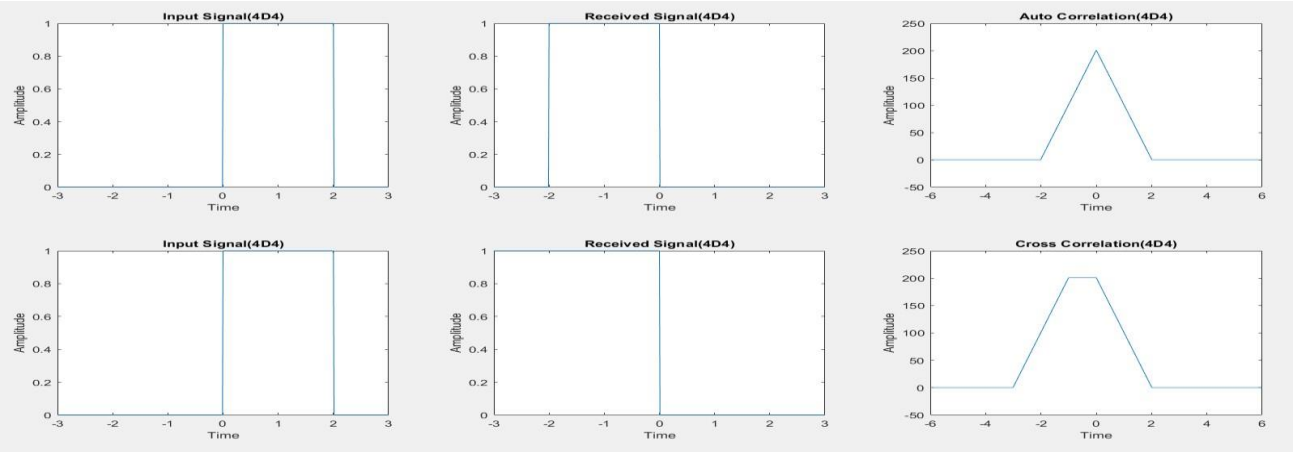
```
close all
clear all

n1 = -3:1:3;
x = [1,2,3,4,5,6,7];

n2 = -n1;

a = min(n1)+min(n2);
b = max(n1)+max(n2);

n = a:1:b;
RXX = xcorr(x,x);

subplot(2,3,1);
stem(n1,x);
xlabel("Time");
ylabel("Amplitude");
title("Input Signal");
```

```
subplot(2,3,2);
stem(n2,x);
xlabel("Time");
ylabel("Amplitude");
title("Received Signal");
subplot(2,3,3);
stem(n,RXX);
xlabel("Time");
ylabel("Amplitude");
title("Auto Correlation");

%Cross Correlation
n1 = -3:1:3;
x = [1,2,3,4,5,6,7];

n2 = -3:1:3;
y = [2,5,8,7,9,3,6];
n3 = -n2;

a = min(n1)+min(n3);
b = max(n1)+max(n3);

n = a:1:b;
RXY = xcorr(x,y);

subplot(2,3,4);
stem(n1,x);
xlabel("Time");
ylabel("Amplitude");
title("Input Signal");

subplot(2,3,5);
stem(n3,y);
xlabel("Time");
ylabel("Amplitude");
title("Received Signal");

subplot(2,3,6);
stem(n,RXY);
xlabel("Time");
ylabel("Amplitude");
title("Cross Correlation");
```

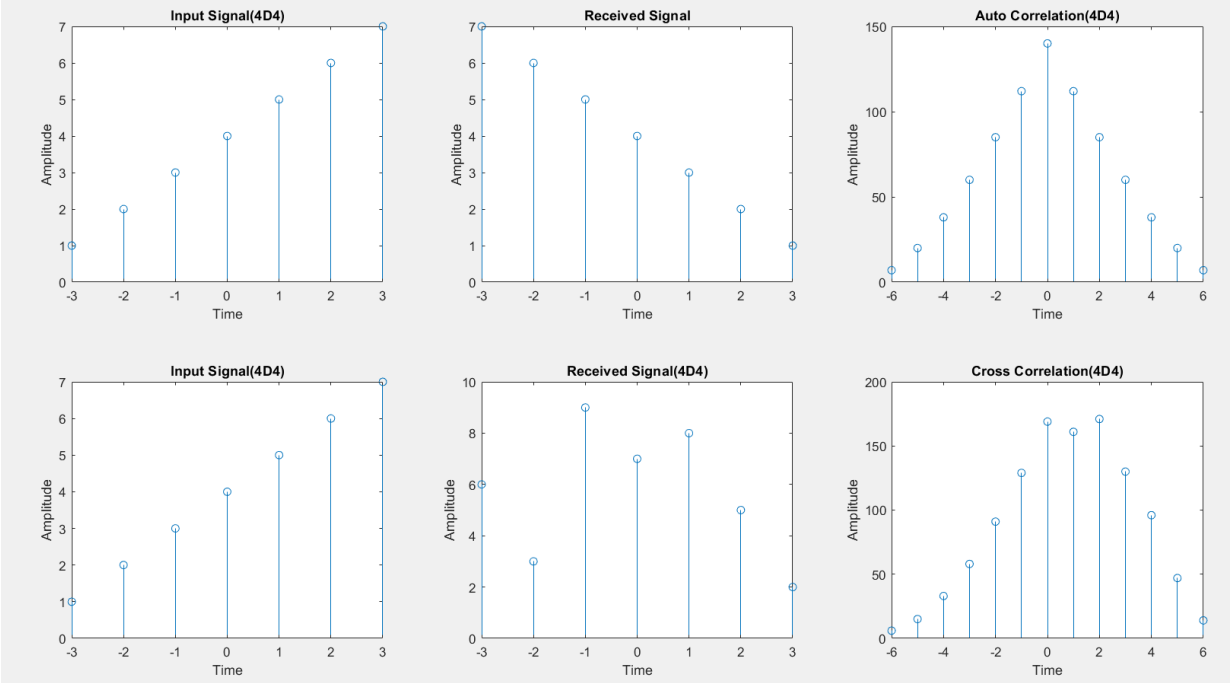
LAB PROCEDURE:

1. Open the MATLAB® software by double clicking its icon.
2. MATLAB®logo will appear and after few moments Command Prompt will appear.
3. Go to the File Menu and select a New M-file. (File →New →M-file) or in the left-hand corner a blank white paper icon will be there. Click it once.
4. A blank M-file will appear with a title „untitled"
5. Now start typing your program. After completing, save the M-file with appropriate name. To execute the program Press F5 or go to Debug Menu and select Run.
6. After execution output will appear in the Command window. If there is an error then with an alarm, type of error will appear in red color.
7. Rectify the error if any and go to Debug Menu and select Run.

OUTPUT WAVEFORMS /GRAPHS:



Continuous Time Signal



Discrete Time Signal

RESULTS:

Successfully Implemented Finding the Auto Correlation and Cross Correlation of (i) Signals (ii) Sequences

Experiment No. 09

Aim: Verification of Linearity and Time Invariance Properties of a given Continuous/Discrete System

S**oftware used:** MATLAB.

THEORY:

Linearity and time invariance are fundamental properties that characterize the behavior of systems in signal processing and control theory.

1. Linearity:

A system is linear if it satisfies two important properties:

Homogeneity (Scaling):

If y1(t) is the response of the system to the input x1(t), then the response to ax1(t) is ay1(t), where a is a constant.

If y1(t)=L{x1(t)}, then L{ax1(t)}=aL{x1(t)}

Additivity (Superposition):

If y1(t) is the response to x1(t) and y2(t) is the response to x2(t), then the response to x1(t)+x2(t) is y1 (t)+y2(t).

If y1(t)=L{x1(t)} and y2(t)=L{x2(t)}, then L{x1(t)+x2(t)}=y1(t)+y2(t)

In the context of linear time-invariant (LTI) systems, linearity is a crucial property. Many physical systems, such as electrical circuits and mechanical systems, exhibit linear behavior under certain conditions.

2. Time Invariance:

A system is time-invariant if a time shift in the input signal results in a corresponding time shift in the output signal.

If y(t)=L{x(t)}, then L{x(t−τ)}=y(t−τ)

In other words, the behavior of the system does not change over time. This property is particularly important because it allows for the use of techniques like convolution in analyzing and solving linear time-invariant systems.

3. Combined Linearity and Time Invariance (LTI) Systems:

In many practical applications, systems are both linear and time-invariant. LTI systems have the advantage of being well understood and characterized mathematically. The convolution integral is a key concept in the analysis of LTI systems.

MATLAB CODE:

Linearity:

```
N=5;
x1=[1,2,-1,-3,2];
x2=[2,-1,3,-4,3];
a1=2;
a2=3;
n=0:1:N-1;
x3=a1*x1+a2*x2;
y01=n.*(x3);
y1=n.*(x1);
y2=n.*(x2);
y02=a1*y1+a2*y2;
disp(' the otput sequence y01 is :');
disp(y01);
disp('the output sequence y02 is:');
```

```
disp(y02);
if(y01==y02)
    disp('y01==y02 .hence the system is linear');
else
    disp('y01~=y02 .hence the system is non linear');
end

subplot(3,2,1);
stem(n,x1);
xlabel("time");
ylabel("amplitude");
title(" 1st input signal");
subplot(3,2,2);
stem(n,x2);
xlabel("time");
ylabel("amplitude");
title(" 2nd input signal");
subplot(3,2,3);
stem(n,y1);
xlabel("time");
ylabel("amplitude");
title(" 1s input response");
subplot(3,2,4);
stem(n,y1);
xlabel("time");
ylabel("amplitude");
title(" 2nd input signal");
subplot(3,2,5);
stem(n,y01);
xlabel("time");
ylabel("amplitude");
title(" total weighted sum of response");
subplot(3,2,6);
stem(n,y02);
xlabel("time");
ylabel("amplitude");
title(" weighted sum of individual response");
```

Time Invariance:

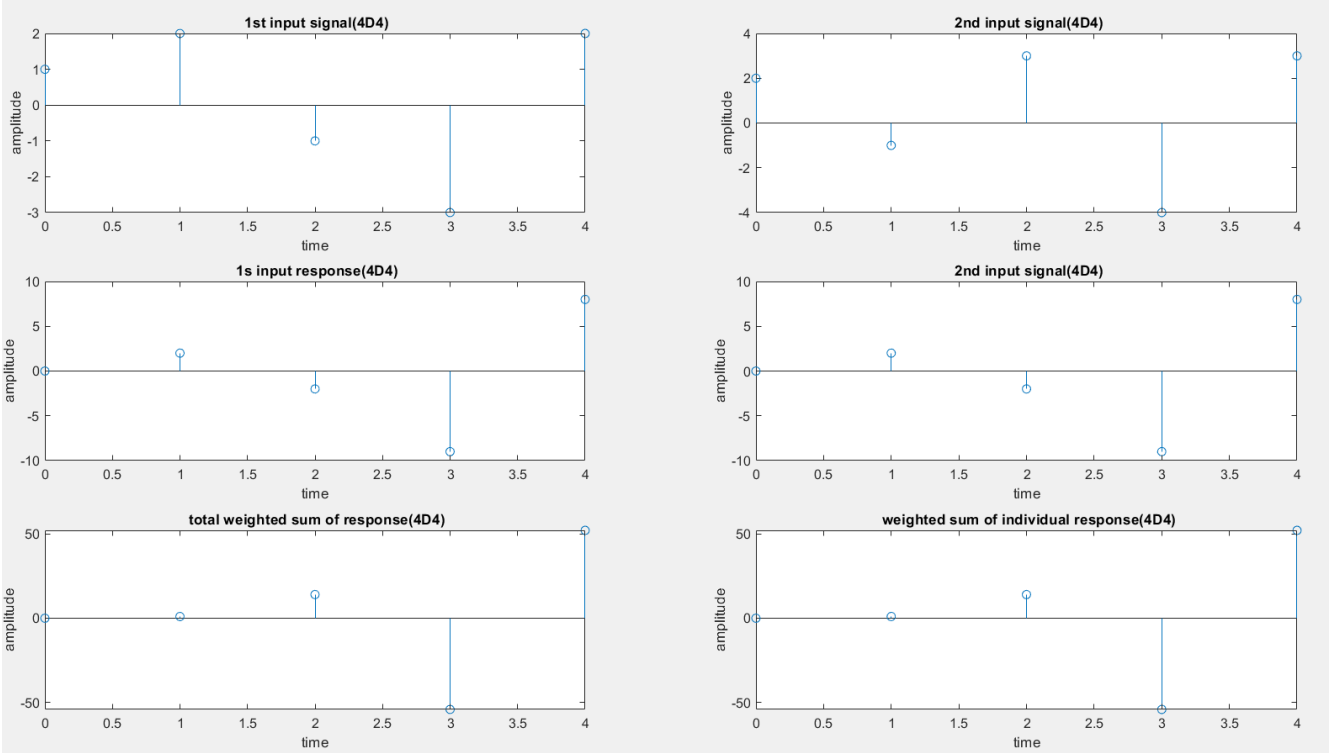
```
x=[1,2,-1,3,-2];
n=0:length(x)-1;
d=2;
y=n.*(x.^2);
xd=[zeros(1,d),x];
disp(length(n));
nd=0:length(xd)-1;
xp=[x,zeros(1,d)];
yp=nd.*(xd.^2);
disp(' the otput sequence yp is :');
disp(yp);
yd=[zeros(1,d),y];
disp(' the otput sequence yd is :');
disp(yd);
if(yp==yd)
    disp('y1==y2. hence the system is time  inveriant');
else
    disp('y1~=y2 . hence the system is time veriant');
end
subplot(3,2,1);
stem(n,x);
xlabel("time");
ylabel("amplitude");
title(" input sequence");
subplot(3,2,2);
```

```
stem(n,y);
xlabel("time");
ylabel("amplitude");
title(" output sequence");
subplot(3,2,3);
stem(nd,xd);

xlabel("time");
ylabel("amplitude");
title(" input delay by 2 units");
subplot(3,2,4);
stem(nd,xp);
xlabel("time");
ylabel("amplitude");
title(" dummy");
subplot(3,2,5);
stem(nd,yp);
xlabel("time");
ylabel("amplitude");
title(" response to be input delay");
subplot(3,2,6);
stem(nd,yd);
xlabel("time");
ylabel("amplitude");
title(" delayed output response");
```

LAB PROCEDURE:

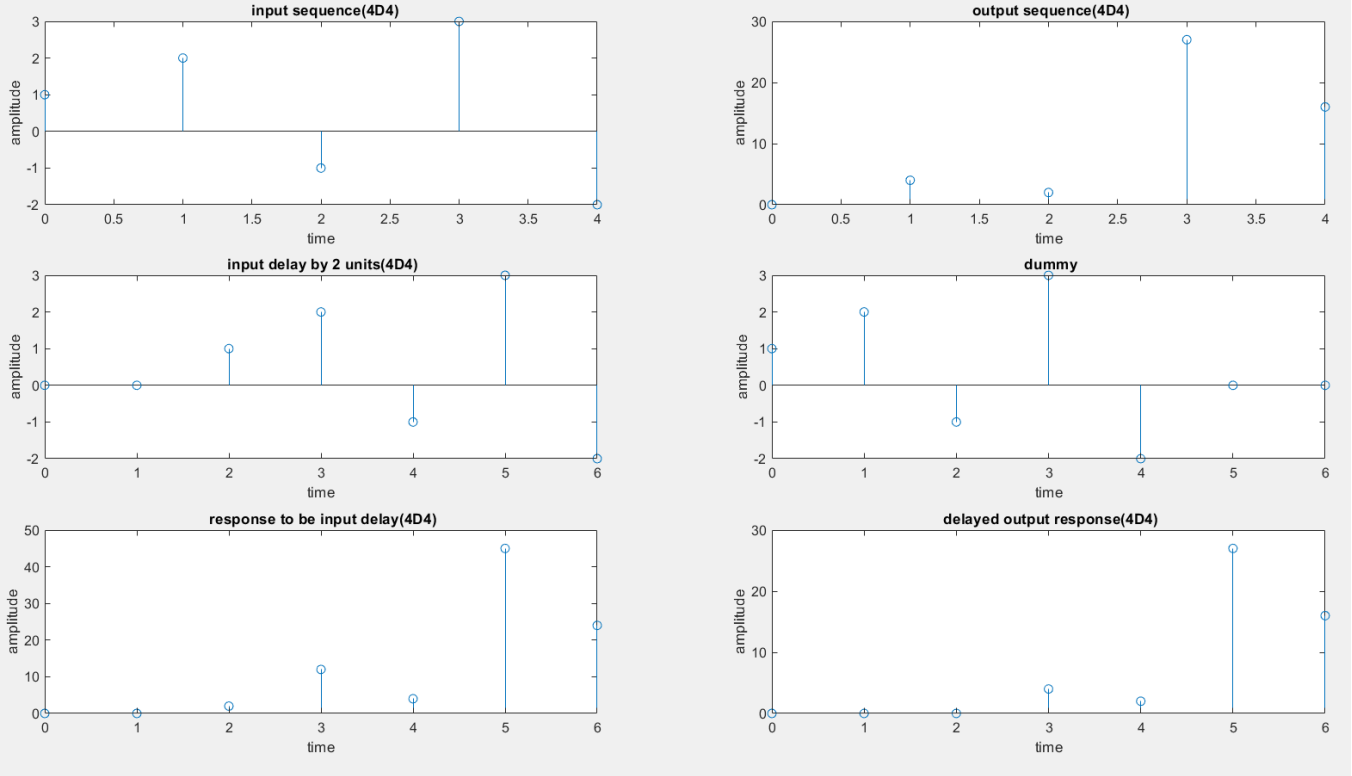
1. Open the MATLAB® software by double clicking its icon.
2. MATLAB®logo will appear and after few moments Command Prompt will appear.
3. Go to the File Menu and select a New M-file. (File →New →M-file) or in the left-hand corner a blank white paper icon will be there. Click it once.
4. A blank M-file will appear with a title „untitled"
5. Now start typing your program. After completing, save the M-file with appropriate name. To execute the program Press F5 or go to Debug Menu and select Run.
6. After execution output will appear in the Command window. If there is an error then with an alarm, type of error will appear in red color.
7. Rectify the error if any and go to Debug Menu and select Run.

OUTPUT WAVEFORMS /GRAPHS:




```
>> Linear_System
 the otput sequence y01 is :
     0     1    14   -54    52

the output sequence y02 is:
     0     1    14   -54    52

y01==y02 .hence the system is linear
```

Linearity of a System




```
the otput sequence yp is :
    0     0     2    12     4    45    24

the otput sequence yd is :
    0     0     0     4     2    27    16

y1~=y2 . hence the system is time veriant
```

Time Invariance of a System

RESULTS:

Successfully Verified the Linearity and Time Invariance Properties of a given Continuous/Discrete System

Experiment No. 10

Aim: Computation of Unit sample, Unit step and sinusoidal responses of the given LTI system and Verifying its Physical realizability and stability properties.

Software used: MATLAB.

MATLAB CODE:

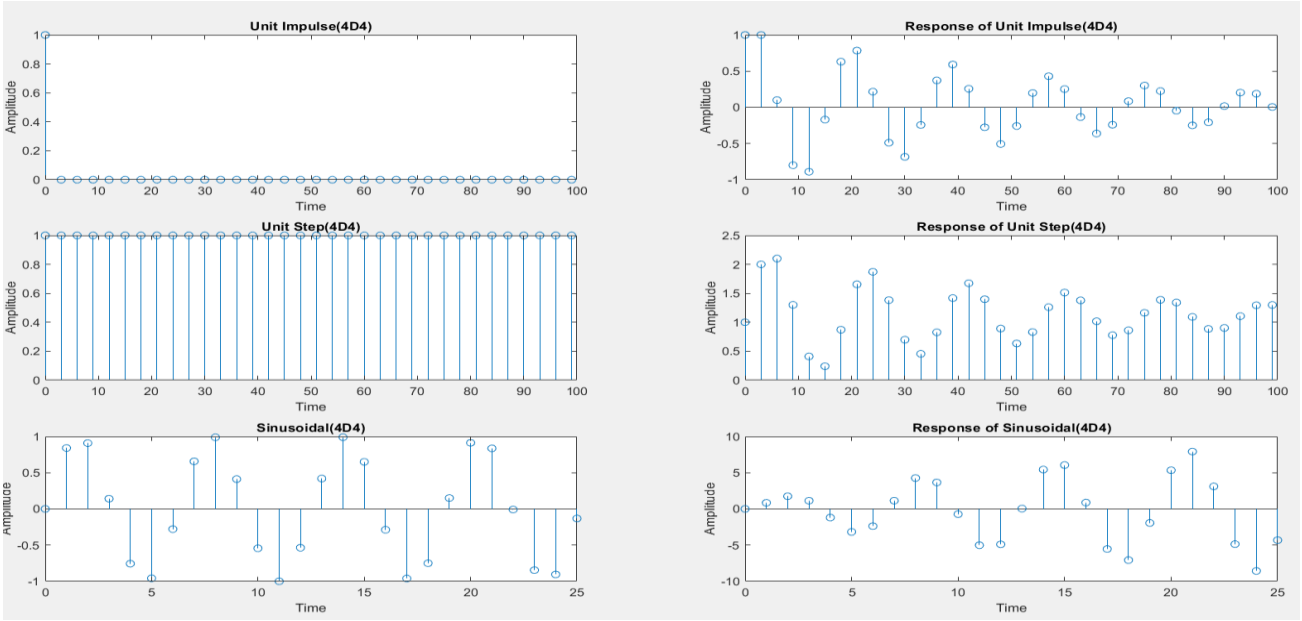
```
close all
clear all

b = [1];

a = [1 -1 0.9];

n = 0:3:100;

x1 = 1.*(n==0)+0.*(n~=0);
y1 = filter(b,a,x1);

subplot(3,2,1);
stem(n,x1);
xlabel("Time");
ylabel("Amplitude");
title("Unit Impulse");

subplot(3,2,2);
stem(n,y1);
xlabel("Time");
ylabel("Amplitude");
title("Response of Unit Impulse");

x2 = 1.*(n>=0)+0.*(n<0);
y2 = filter(b,a,x2);

subplot(3,2,3);
stem(n,x2);
xlabel("Time");
ylabel("Amplitude");
title("Unit Step");

subplot(3,2,4);
stem(n,y2);
xlabel("Time");
ylabel("Amplitude");
title("Response of Unit Step");n =

0:1:8*pi;

x3 = sin(n);
y3 = filter(b,a,x3);

subplot(3,2,5);
stem(n,x3);
xlabel("Time");
ylabel("Amplitude");
```

```
title("Sinusoidal");

subplot(3,2,6);
stem(n,y3);
xlabel("Time");
ylabel("Amplitude");
title("Response of Sinusoidal");


figure;
zplane(b,a);
```

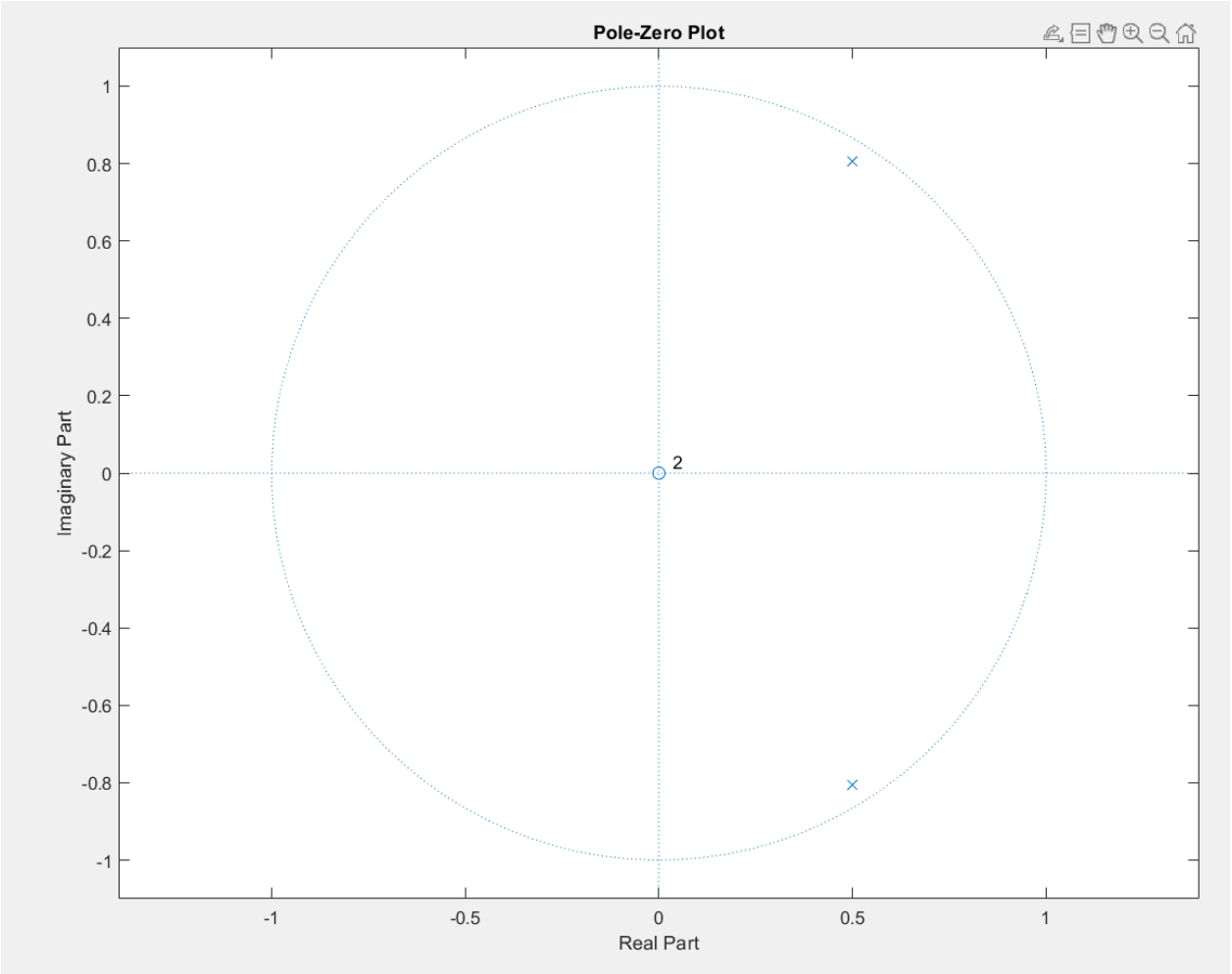
LAB PROCEDURE:

1. Open the MATLAB® software by double clicking its icon.
2. MATLAB®logo will appear and after few moments Command Prompt will appear.
3. Go to the File Menu and select a New M-file. (File →New →M-file) or in the left-hand corner a blank white paper icon will be there. Click it once.
4. A blank M-file will appear with a title „untitled"
5. Now start typing your program. After completing, save the M-file with appropriate name. To execute the program Press F5 or go to Debug Menu and select Run.
6. After execution output will appear in the Command window. If there is an error then with an alarm, type of error will appear in red color.
7. Rectify the error if any and go to Debug Menu and select Run.

OUTPUT WAVEFORMS /GRAPHS:



Responses of a LTI System for various I/P Signals



Z-Plane

RESULTS:

Successfully Implemented Computation of Unit sample, Unit step and sinusoidal responses of the given LTI system and Verifying its Physical realizability and stability properties.

Experiment No. 11

Aim: Verifying the applications of Correlation: Removal of noise by Autocorrelation & Cross correlation.

S**oftware used:** MATLAB.

MATLAB CODE:
Auto Correlation:

```
close all
clear all

t = 0:0.1:8*pi;
s = sin(t);

n  = randn([1 252]);

f = s+n;

subplot(3,2,1);
plot(s);
xlabel("Time");
ylabel("Amplitude");
title("Input Signal");

subplot(3,2,2);
plot(f);
xlabel("Time");
ylabel("Amplitude");
title("Combined Signal");

Rs = xcorr(s,s);
Rn = xcorr(n,n);
Rf = xcorr(f,f);

R = Rs+Rn;

subplot(3,2,3);
plot(Rs);
xlabel("Time");
ylabel("Amplitude");
title("Auto Correlation Rsc");

subplot(3,2,4);
plot(Rn);
xlabel("Time");
ylabel("Amplitude");
title("Auto Correlation Rnc");

subplot(3,2,5);
plot(Rf);
xlabel("Time");
ylabel("Amplitude");
title("Auto Correlation Rfc");

subplot(3,2,6);
plot(R);
```

```
xlabel("Time");
ylabel("Amplitude");
title("Auto Correlation R");
```

Cross Correlation:

```
close all
clear all

t = 0:0.1:8*pi;
s = sin(t);

n  = randn([1 252]);

f = s+n;

c = cos(t);

subplot(4,2,1);
plot(s);
xlabel("Time");
ylabel("Amplitude");
title("Input Signal");

subplot(4,2,2);
plot(f);
xlabel("Time");
ylabel("Amplitude");
title("Combined Signal");

subplot(4,2,3);
plot(c);
xlabel("Time");
ylabel("Amplitude");
title("Constant Signal");

Rsc = xcorr(s,c);
Rnc = xcorr(n,c);
Rfc = xcorr(f,c);

R = Rsc+Rnc;

subplot(4,2,4);
plot(Rsc);
xlabel("Time");
ylabel("Amplitude");
title("Cross Correlation Rsc");

subplot(4,2,5);
plot(Rnc);
xlabel("Time");
ylabel("Amplitude");
title("Cross Correlation Rnc");

subplot(4,2,6);
plot(Rfc);
xlabel("Time");
ylabel("Amplitude");
title("Cross Correlation Rfc");

subplot(4,2,7);
```

```
plot(R);
xlabel("Time");
ylabel("Amplitude");
title("Cross Correlation R");
```

LAB PROCEDURE:

1. Open the MATLAB® software by double clicking its icon.
2. MATLAB®logo will appear and after few moments Command Prompt will appear.
3. Go to the File Menu and select a New M-file. (File →New →M-file) or in the left-hand corner a blank white paper icon will be there. Click it once.
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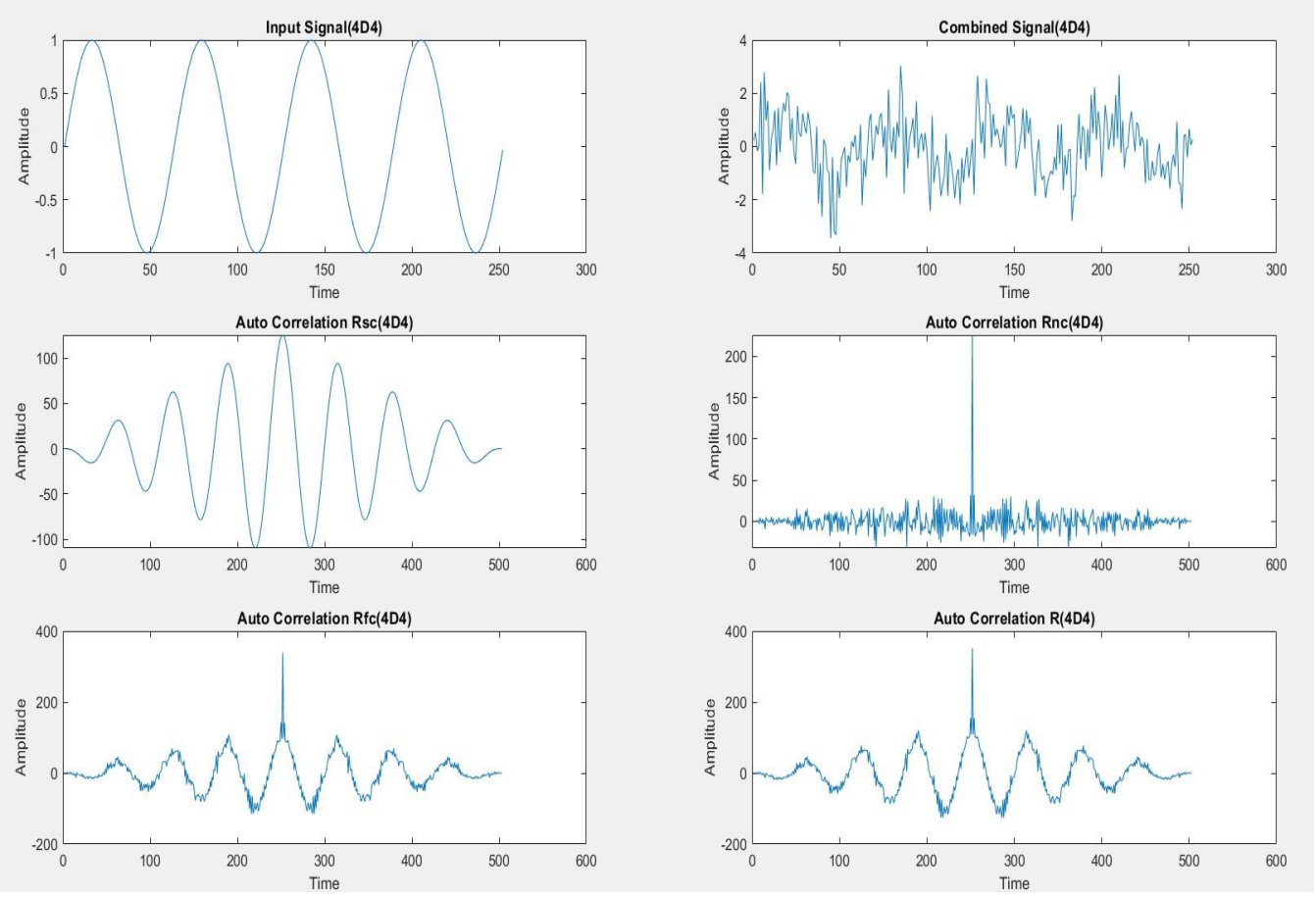
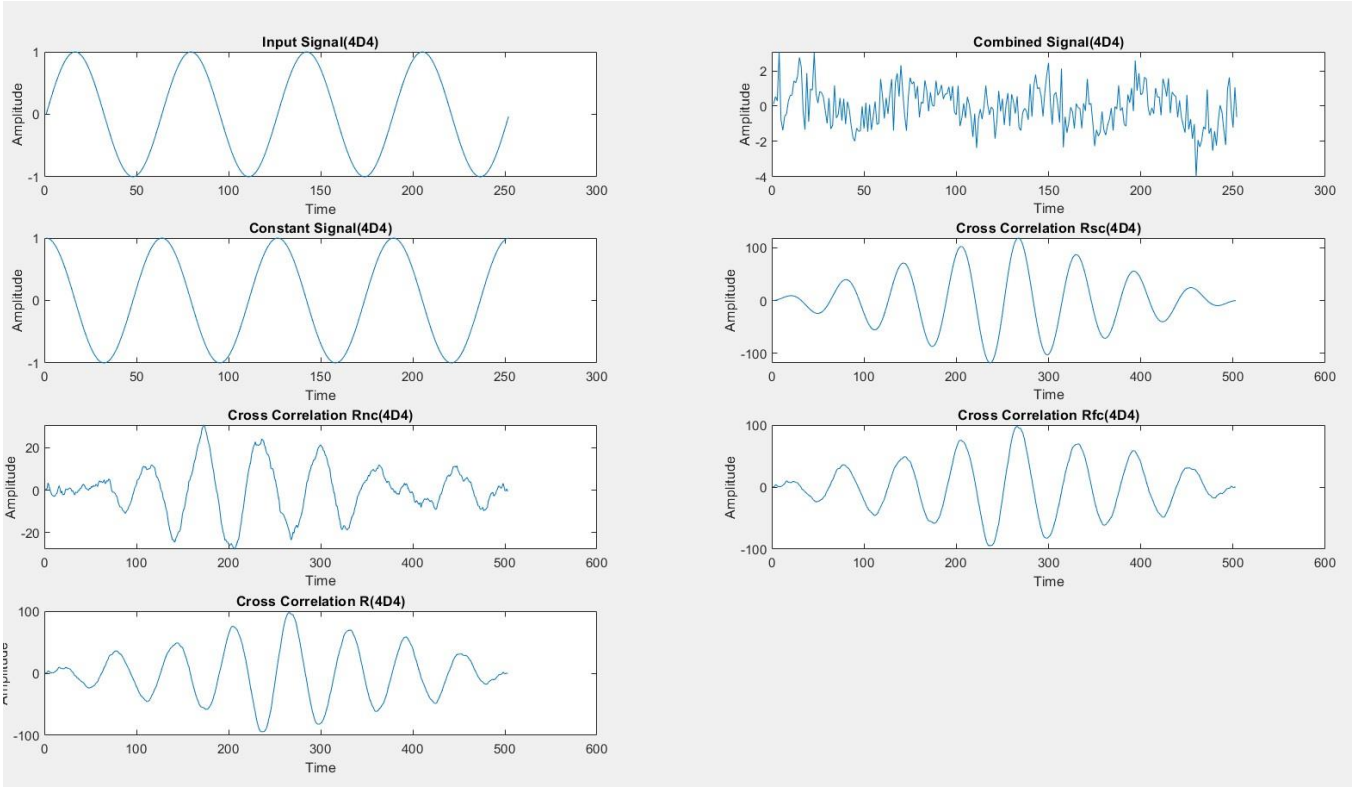
6. After execution output will appear in the Command window. If there is an error then with an alarm, type of error will appear in red color.
7. Rectify the error if any and go to Debug Menu and select Run.

OUTPUT WAVEFORMS /GRAPHS:



Auto Correlation



Cross Correlation

RESULTS:

Successfully verified the applications of Correlation: Removal of noise by Autocorrelation and Cross correlation.

Experiment 12

Aim: Verification of Sampling Theorem

Software used: MATLAB.

THEORY:
Continuous Signals can be represented in its Samples and recovered back when the sampling frequency is greater than or equal to the highest frequency component of the message signal f_m
i.e, $f_s > 2f_m$

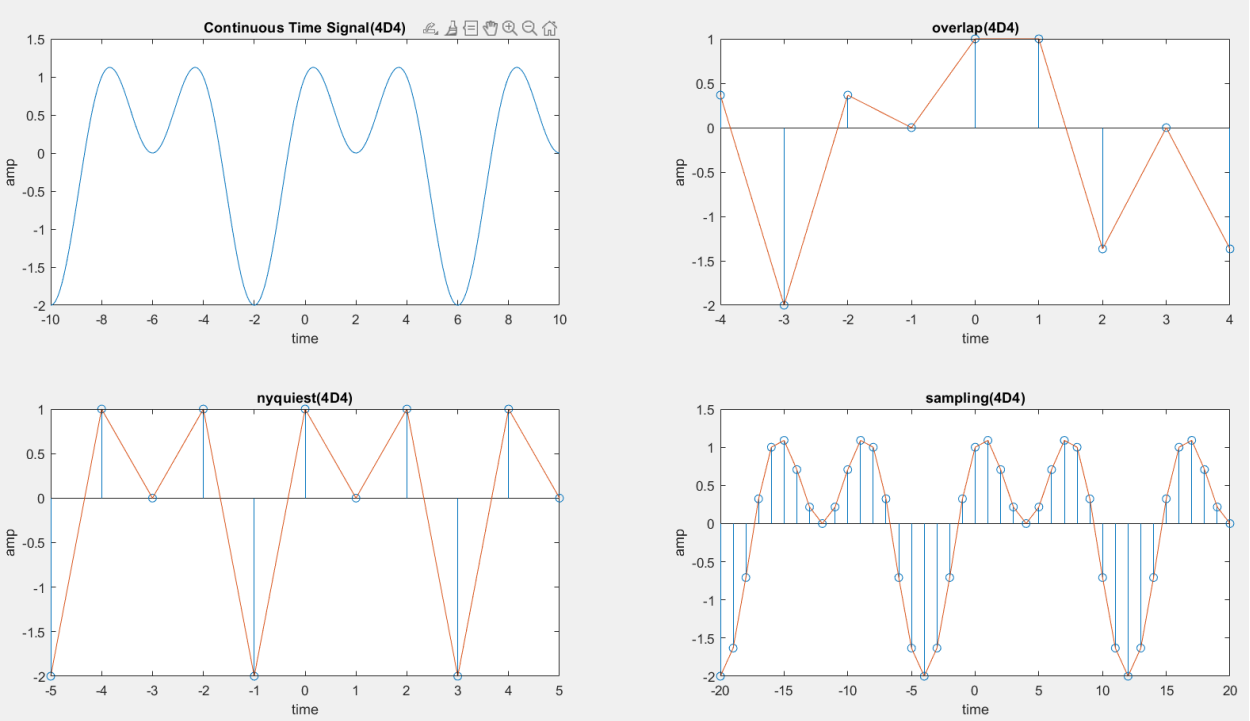
MATLAB CODE:

```
clear all
close all
t=-10:0.01:10; T=4; fm=1/T;
x=sin(pi*fm*t)+cos(2*pi*fm*t);
subplot(2,2,1);
plot(t,x);
xlabel("time");
ylabel("amp");
title("Continuous Time Signal");
fs1=1.2*fm;
fs2=2*fm;
fs3=8*fm;
n1=-4:1:4;
x1=sin(pi*fm*n1/fs1)+cos(2*pi*fm*n1/fs1);
subplot(2,2,2);
stem(n1,x1);
hold on;
subplot(2,2,2);
plot(n1,x1);
xlabel("time");
ylabel("amp");
title("overlap");
n2=-5:1:5;
x2=sin(pi*fm*n2/fs2)+cos(2*pi*fm*n2/fs2);
subplot(2,2,3);
stem(n2,x2); hold on;
subplot(2,2,3);
plot(n2,x2);
xlabel("time");
ylabel("amp");
title("nyquiest");
n3=-20:1:20;
x3=sin(pi*fm*n3/fs3)+cos(2*pi*fm*n3/fs3);
subplot(2,2,4);
stem(n3,x3);
hold on;
subplot(2,2,4);
plot(n3,x3);
xlabel("time");
ylabel("amp");
title("sampling");
```

LAB PROCEDURE:

1. Open the MATLAB® software by double clicking its icon.
2. MATLAB®logo will appear and after few moments Command Prompt will appear.
3. Go to the File Menu and select a New M-file. (File →New →M-file) or in the left-hand corner a blank white paper icon will be there. Click it once.
4. A blank M-file will appear with a title 'untitled'
5. Now start typing your program. After completing, save the M-file with appropriate name. To execute the program Press F5 or go to Debug Menu and select Run.
6. After execution output will appear in the Command window. If there is an error then with an alarm, type of error will appear in red color.
7. Rectify the error if any and go to Debug Menu and select Run.

OUTPUT WAVEFORMS /GRAPHS:



RESULTS:
Sampling Theorem Verified