

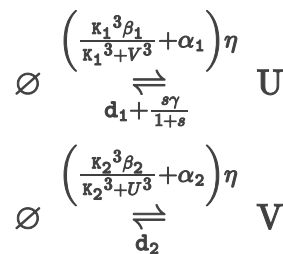
```

1 begin
2   # numerical libraries
3   using Expokit, PROPACK, Arpack, SparseArrays
4   # output and plotting
5   using ProgressLogging, JLD
6   # modelling and statistics
7   using Catalyst, JumpProcesses, StatsBase, DifferentialEquations
8   using Interpolations
9   # importing local fsp package
10  using Revise
11  local_mod = include("../src/DiscStochSim.jl")
12  using .local_mod.DiscStochSim
13 end

```

Replacing docs for `Main.var"workspace#2".DiscStochSim.FindLowestValuesPercent` :  
 : Union{Tuple{T}, Tuple{Vector{T}, Number}} where T` in module `Main.var"workspace#2".DiscStochSim`

rn =



```

1 rn = @reaction_network begin
2   (η*(α₁ + (β₁*K₁^3/(K₁^3 + V^3))), d₁+s*γ/(1+s)), 0 <--> U
3   (η*(α₂ + (β₂*K₂^3/(K₂^3 + U^3))), d₂), 0 <--> V
4 end

```

$$\left[ \left( \frac{\mathbf{K}_1^3 \beta_1}{\mathbf{K}_1^3 + (V(t))^3} + \alpha_1 \right) \eta, \left( \mathbf{d}_1 + \frac{s\gamma}{1+s} \right) U(t), \left( \frac{\mathbf{K}_2^3 \beta_2}{\mathbf{K}_2^3 + (U(t))^3} + \alpha_2 \right) \eta, \mathbf{d}_2 V(t) \right]$$

```

1 begin
2   model = DiscreteStochasticSystem(rn);
3   jumpratelaw.(Catalyst.get_rxs(rn));
4 end

```

```
def_params = 0.0:0.25:30.0
```

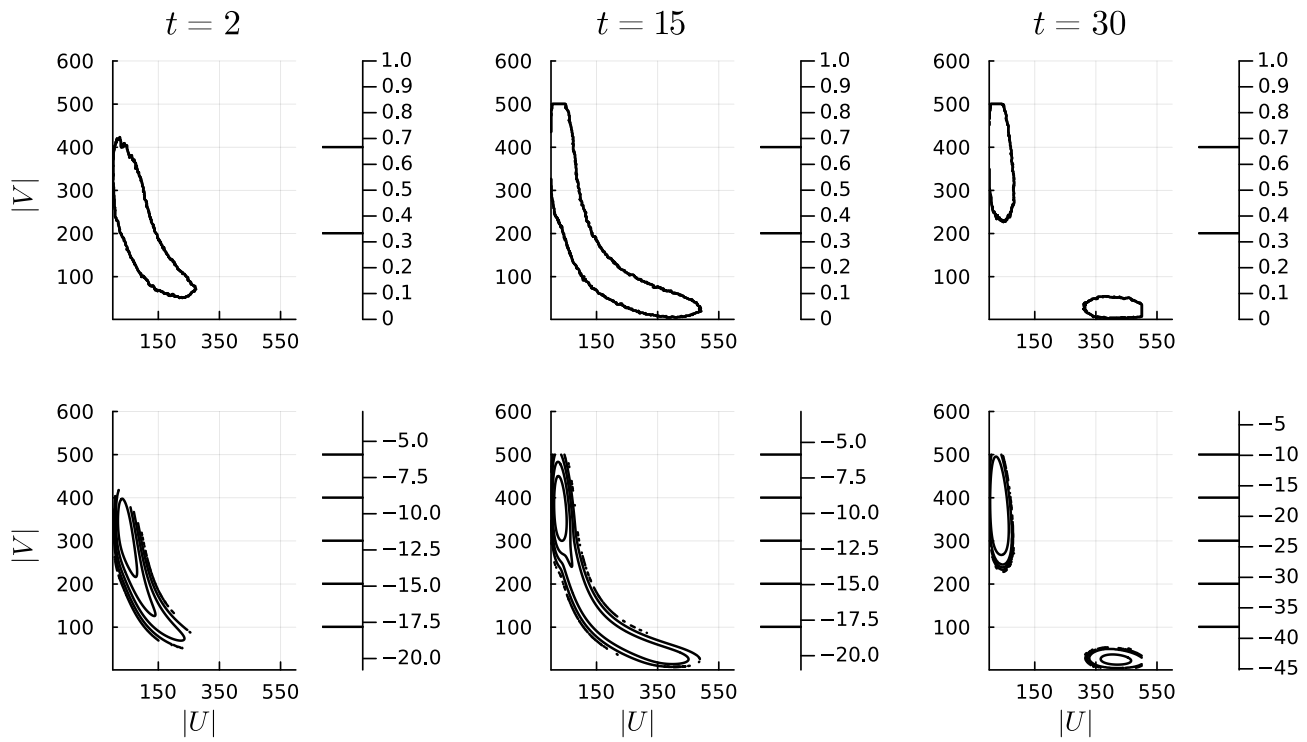
```
1 def_params = begin
2   # reaction rates
3   scale=100
4   rates = [1.0, 0.2*scale,
5            4.0*scale,
6            1.0*scale,
7            1.0,
8            0.1,
9            1.0,
10           0.2*scale,
11           4.0*scale,
12           1.0*scale,
13           1.0]
14   # boundary
15   bounds = (0, 500)  #(lower limit, upper limit)
16   boundary_condition(x) = RectLatticeBoundaryCondition(x, bounds);
17   # time interval and initial values
18   dt = 0.25
19   T = 0:dt:30
20 end
```

```
1 init_fsp_vars = begin
2   global U0 = CartesianIndex(85, 5)
3   global S0 = Set([U0])
4   global S0 = expand!(S0, model, rates, 0.0, boundary_condition, 2);
5   # initial probability vector (only for active states)
6   global p0 = zeros(S0 |> length)
7   global p0[FindElement(U0, S0)] = 1
8 end;
```

fsp\_sim =

```
1 fsp_sim = begin
2   # copy initial values
3   p_t = copy(p_0)
4   S_t = copy(S_0)
5   # time stepping loop
6   iter = 1
7   p_t = p_0
8   # variables to store simulation observables
9   size_S_t = Int.(zeros(length(I))) # system sizes
10  e_t = zeros(length(I)) #local truncation err
11  sol = Array{SparseMatrixCSC,1}(undef, length(I))
12  @progress for (iter, t) ∈ enumerate(I)
13    # expand state space
14    global S_t, p_t = expand!(S_t, p_t, model, rates , t, boundary_condition, 50)
15    global size_S_t[iter] = length(S_t)
16    A = MasterEquation(S_t, model, rates, boundary_condition, t)
17    # solve system and normalize (using expokit)
18    global p_t = expmv(δt, A, p_t)
19    # add add states in sparse arrays
20    I = [a[1] for a in S_t]
21    J = [a[2] for a in S_t]
22    global sol[iter] = sparse(I, J, p_t)
23    # purge state space
24    S_t, p_t = purge!(S_t, p_t, 1e-8)
25    e_t[iter] = 1.0 - sum(p_t)
26    p_t ./= sum(p_t)
27  end
28 end
```

100%



```
Plot{Plots.GRBackend() n=6}
```

