Reading Materials

1. URDF Model:
   - Document tutorial given in TASK-1.1 folder.
   - Chapter 3**:** Simulating Robots Using ROS and Gazebo from **Mastering ROS for Robotics Programming by Lentin Joseph**
   - Visit link here: http://wiki.ros.org/urdf/Tutorials
2. Navigation and Path planning:
   - Chapter 8 : Navigation, Path Planning and SLAM   from **ROS By Example by R. PATRICK GOEBEL**
   - Visit link here: http://wiki.ros.org/navigation
3. Transformation(tf):
   - Visit link here: http://wiki.ros.org/tf/Tutorials