

# Appendix: Actionable Insights for Multivariate Time-series for Urban Analytics

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## 1 Additional Details on Sec 3

### 1.1 Proof of Lemma 3.1

*Proof.* Following is the proof for different  $i, j$ , and  $k$ .

- **Case  $i = 1, k = T$ :** Trivial. Since, there is only one segment from 1 to  $T$  and only one path.
- **Case  $i = 1, k < T$ :** (By induction). Suppose,  $T = k + 1$ , then the number of paths is  $2^{k+1-k-1} = 2^0 = 1$ . This is trivial, because from  $s_{jk}$  there is only one possible edge  $s_{jk} - s_{k(k+1)}$  and thus there is only one possible path. Suppose, with  $T = k + q$  where  $q > k$ , the number of paths is  $2^{q-1}$ . We need to show, with  $T = k + q + 1$ , the number of paths become  $2^q$ . Since  $q + 1 > q$ , all the paths that can be possible to reach from  $s_{jk}$  to  $s_{j(k+q)}$  can also be possible to reach from  $s_{jk}$  to  $s_{j(k+q+1)}$  using the edge  $s_{j(k+q)} - s_{j(k+q+1)}$ . That is,  $2^{q-1}$  paths possible from  $s_{jk}$  to  $s_{j(k+q+1)}$  using the edge  $s_{j(k+q)} - s_{j(k+q+1)}$ . Again, by the edge construction property of  $G$ , a path ends when end timestamp of a node is  $T = k + q + 1$ . If we remove the timestamp  $k + q$  and consider only  $k, k + 1, \dots, k + q - 1, k + q + 1$ , then the number of possible paths become  $2^{q-1}$  to reach  $k + q + 1$  (by induction). Because, all edges that used nodes ended with  $k + q$  now can use nodes ended with  $k + q + 1$ . Thus, the total number of possible paths with and without using the edge  $s_{j(k+q)} - s_{j(k+q+1)}$  becomes  $2^{q-1} + 2^{q-1} = 2^{q-1+1} = 2^q$  (proved).
- **Case  $i > 1, k = T$ :** Following the above if we consider  $T = i$  and the  $k = 1$ . The number of paths is  $2^{T-k-1} = 2^{i-1-1} = 2^{i-2}$ .
- **Case otherwise:** Hence, if there are  $2^{i-2}$  paths possible to reach a node  $s_{ij}$  and  $2^{T-k-1}$  possible paths to reach timestamp  $T$  from a node  $s_{jk}$ . The total number of paths possible through the edge  $s_{ij} - s_{jk}$  or  $e_{ijk}$  is  $p_{ijk} = 2^{(i-2)+(T-k-1)}$ .

□

### 1.2 Proof of Corollary 3.1

*Proof.* According to the path property of  $G$ , every path starts from  $i = 1$  and ends at timestamp  $T$ . For  $i = 1, k = T$  there is only one path possible (the whole segmentation). For  $1 < j < T - 1$ , the first node of all other paths in  $G$  has to start from some  $s_{1j}$ . Consider  $j = k$ , using Lemma ?? we find  $p_{1kk}$ . Thus,  $K = 1 + \sum_{k=2}^{T-1} p_{1kk} = 1 + 2^{T-2} - 1 = 2^{T-2}$ . □

### 1.3 Proof of Lemma 3.2

*Proof.* We discuss separate proof for time and space complexity.

**Time complexity:** (i) *Case serial:* The first term is to calculate  $\pi_{\text{rest}}$  for each  $e_{ijk}$ . Total  $e_{ijk}$  in  $G$  is  $O(T^3)$ . The second term is to solve  $\alpha$  using Gradient Descent learning, and the third term is to solve  $\mathbf{r}_j$  for every cutpoint  $c_j$ .

(ii) *Case Parallel:* Parallelization can be applied in FindRaTSS for  $\pi_{\text{rest}}$  computation, then the total time complexity will be distributed among  $n$  processors and hence this is  $O(\frac{T^3}{n}mf)$ . However, time complexity of gradient descent and  $\mathbf{r}_j$  computation is similar as in serial cases.

**Space complexity:** (i) *Case serial:* The first term  $O(m)$  is to store  $\pi_{\text{rest}}$  and  $\pi_B$ . Since we need  $O(m)$   $\pi_{\text{rest}}$  and  $O(m)$   $\pi_B$  for  $m$  time-series. Hence  $O(m) + O(m) = O(2m) \approx O(m)$ .

(ii) *Case parallel:* To store final computation of  $\pi_{\text{rest}}$  and  $\pi_B$  it takes  $O(m)$ . Whereas the second term  $O(mn)$  is to store temporary  $\pi_{\text{rest}}$  computation for each processor among  $n$  processors,  $O(mn)$  is the number of possible edges in a segment graph  $G$ . Hence temporary space for  $n$  processor and final computation of  $\pi_B$  and  $\pi_{\text{rest}}$  is  $O(mn) + O(m) = O(m + mn)$ . □

## 2 Additional Details on Sec. 4

**Additional experiments: Feature ablation test** For feature robustness by we use feature ablation test. Tbl. 1 shows how rationalization affected on the Synthetic, ChickenDance and GrandMal dataset by removing each feature used in RaTSS.

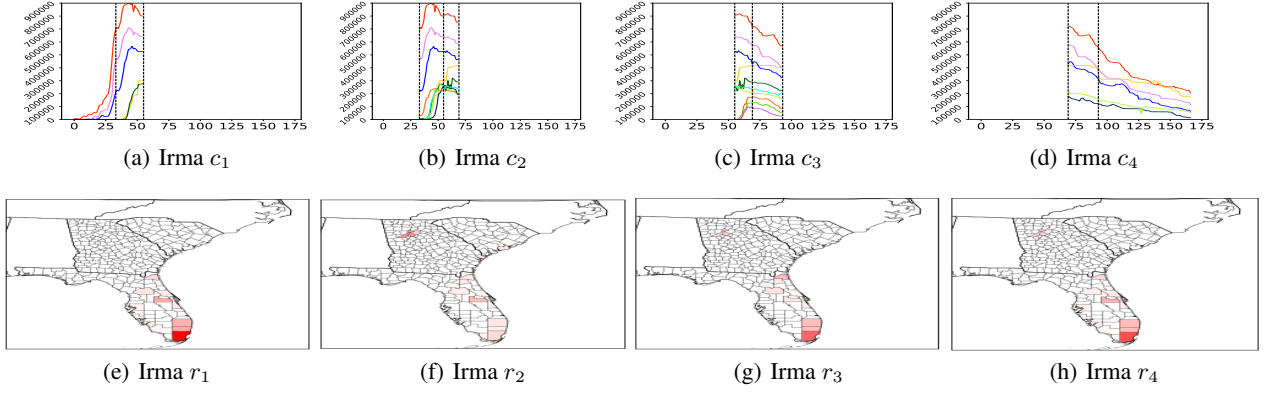


Figure 1: **Find-RaTSS** finds the most affected counties facing damage. The rationalizations  $r_j$  for corresponding  $c_j$  are mapped in US county map (Higher  $r_j^u$  with brighter red).

Table 1: **Feature Ablation test in terms of F1-score for Ground-truth datasets.**  $f_1$ : mean,  $f_2$ : variance,  $f_3$ : min,  $f_4$ : max

Dataset	Features removed			
	$f_1$	$f_2$	$f_3$	$f_4$
<i>Gaussian</i>	0.52	0.44	0.49	0.64
<i>ChickenDance</i>	0.73	0.86	0.401	0.643
<i>Great Barbet</i>	0.5	0.5	0	1.0

was published around June 2016 after  $c_1$ <sup>1</sup>. This is not easy to find such low traffic easily by visualizing the time-series or using any other baselines from Sec. ?? (as buried with other high traffic articles).

## 2.1 Additional Case-studies: Hurricane Irma

Fig. 1 shows our rationalizations for Hurricane Irma.

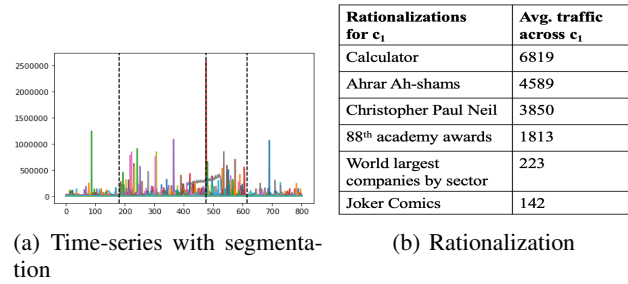


Figure 2: **Find-RaTSS** finds the rationalization from Wikipedia during the period 2015-2017.

### Additional Case-study in general dataset (Wikipedia)

To understand the importance of content and improve advertisement strategies, we consider the web traffic of 3000 Wikipedia articles from 2015 July-2017 October. The segmentation mark a different season of a year (around the end of 2015, middle of 2016, and beginning of 2017 in Fig. 2(a)). We find overall, the majority of articles/rationalizations (64%) by Find-RaTSS are eventful. Fig. 2(b) shows an example of the rationalizations by Find-RaTSS across the first cutpoint  $c_1$ . We observe Find-RaTSS considers some low-traffic articles, e.g., ‘World’s largest companies by sector’ within top 10 along with the high traffic ones. The reason is, ‘Forbes Global 2000’ for worlds largest companies

<sup>1</sup><https://www.forbes.com/sites/forbespr/2016/05/25/forbes-14th-annual-global-2000-the-worlds-biggest-public-companies-2/#21ca87643c44>