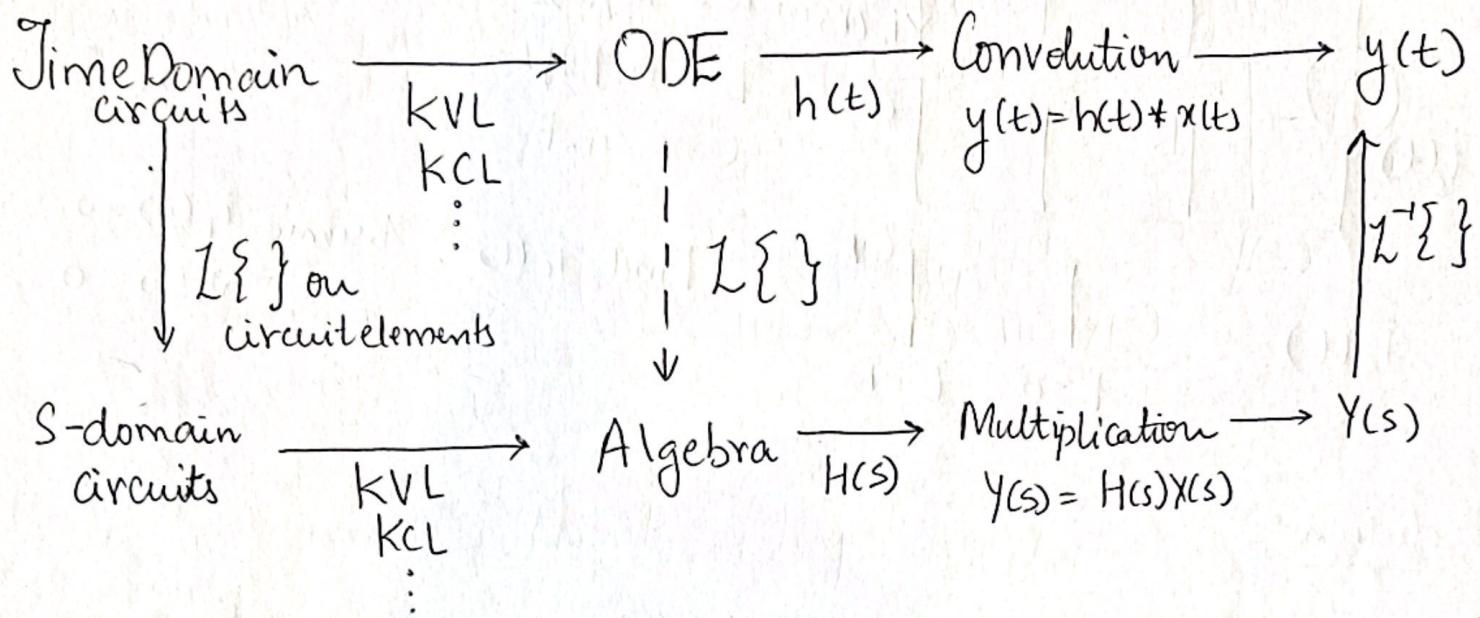


Lec 5 - Laplace Transforms & Freq. Response contd.



S-domain Circuits

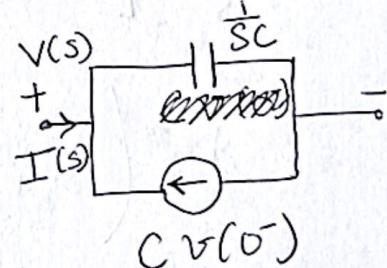
Resistors : $v(t) = R i(t) \Rightarrow V(s) = R I(s)$
 $Z(s) = R$

Inductors : $v(t) = L \frac{di(t)}{dt} \Rightarrow V(s) = sL I(s) - L i(0^-)$

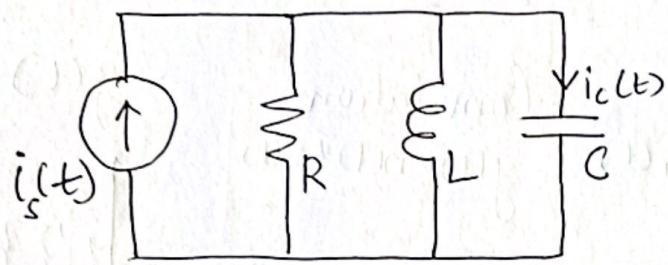
$Z(s) = sL$

Capacitors : $i(t) = C \frac{dv(t)}{dt} \Rightarrow I(s) = sC V(s) - C v(0^-)$

$Z(s) = \frac{1}{sC}$



Example



$$R = 125 \Omega$$

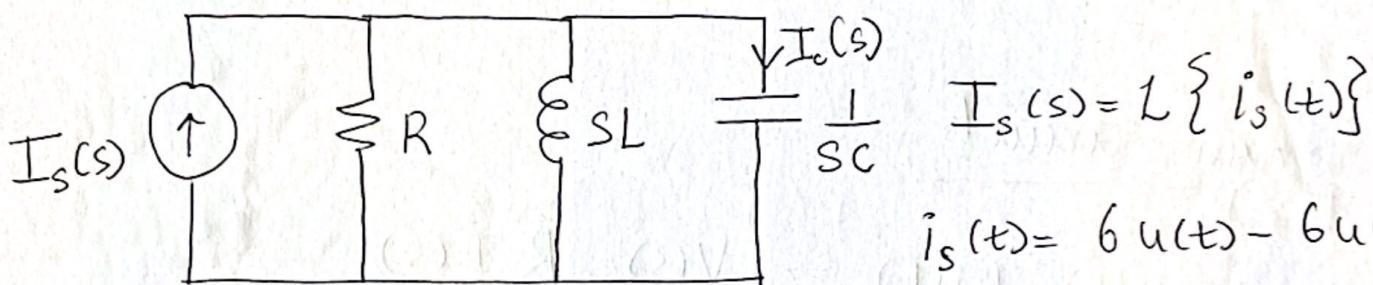
$$L = 0.1 \text{ H}$$

$$C = 4 \text{ mF}$$

$$\dot{i}_s(t) = \begin{cases} 0 & t=0 \\ 6 & t=1s \end{cases}$$

Find $i_C(t)$. Assume $i_L(0) = 0$
 $v_c(0) = 0$

Solution:



$$\dot{i}_s(t) = 6u(t) - 6u(t-1)$$

$$\Rightarrow \dot{I}_s(s) = \frac{6}{s} - \frac{6}{s} e^{-s}$$

$$\text{KCL} \Rightarrow \frac{V}{R} + \frac{V}{sL} + V_{SC} = \dot{I}_s$$

$$\begin{aligned} I_C &= \frac{V}{\frac{1}{sC}} = sC \left[\dot{I}_s \left(\frac{1}{R} + \frac{1}{sL} + sC \right) \right] \\ &= \dot{I}_s \left(\frac{s^2}{s^2 + \frac{s}{RC} + \frac{1}{LC}} \right) \end{aligned}$$

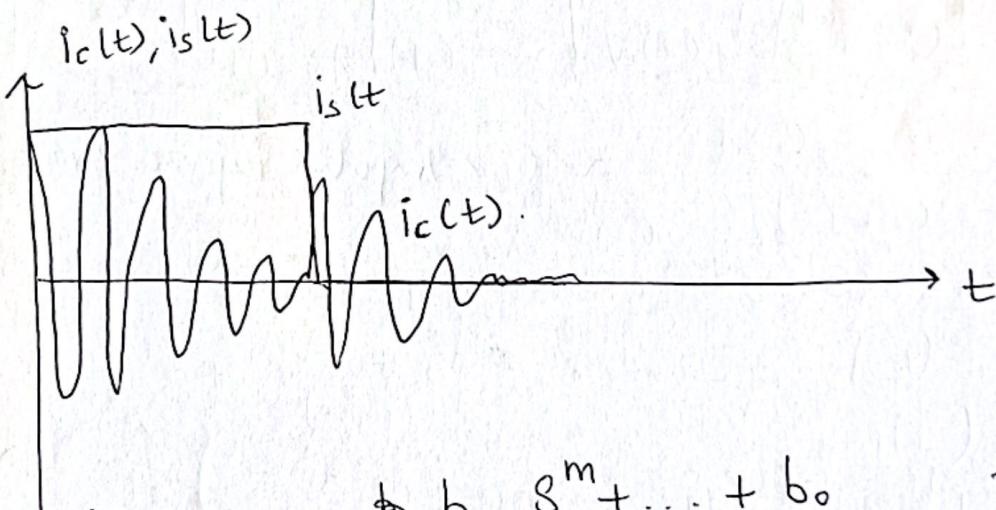
$$\Rightarrow I_c(s) = \left(\frac{s^2}{s^2 + \frac{s}{RC} + \frac{1}{LC}} \right) \left(\frac{6}{s} - \frac{6e^{-s}}{s} \right)$$

$$= \frac{6s}{s^2 + 2s + 2500} - \frac{6s}{s^2 + 2s + 2500} e^{-s}$$

↓ Partial Fraction expansion & $L^{-1}\{\cdot\}$

$$6e^{-t} \cos(50t + 1.15^\circ) u(t)$$

$$\Rightarrow i_c(t) = 6 \{ e^{-t} \cos(50t + 1.15^\circ) \} u(t) \\ - 6 e^{-(t-1)} \cos(50(t-1) + 1.15^\circ) u(t-1)$$



→ In general $H(s) = \frac{b_m s^m + \dots + b_0}{a_n s^n + \dots + a_0} \rightarrow$ Transfer Function

Zeroes \Rightarrow Values of s where Num = 0 roots of num.

Poles \Rightarrow Values of s where Den = 0 roots of den.

$$H(s) = \frac{(s-z_1)(s-z_2)\dots(s-z_m)}{(s-p_1)(s-p_2)\dots(s-p_n)}$$

~~What's the pole~~

How do we interpret $H(s)$?

$$H(s) = \frac{Y(s)}{X(s)} \Rightarrow Y(s) = H(s) X(s) \xrightarrow{\text{LT}}$$

$$\Rightarrow y(t) = \underbrace{h(t)}_{\text{impulse response}} * x(t)$$

$\Rightarrow H(s)$ is the LT of $h(t)$.

> RHP pole \Rightarrow unstable! $e^{-\alpha t} \longleftrightarrow \frac{1}{s+\alpha}$

$\alpha < 0 \Rightarrow$ impulse response grows exponentially.

$$\Rightarrow H(s) = \int_0^{\infty} h(t) e^{-st} dt$$

$$= \int_{-\infty}^{\infty} h(t) e^{-st} dt \quad \text{since } h(t) = 0 \text{ for } t < 0 \text{ due}$$

to causality!

> When $s = j\omega$ we have $H(j\omega) = \int_{-\infty}^{\infty} h(t) e^{-j\omega t} dt$

- ⇒ The imaginary axis of the S-plane, ^{for $H(s)$.} represents the Fourier Transform of $h(t)$. This axis is indeed special because it captures a very important feature of the frequency domain.

Eigenfunction excitations

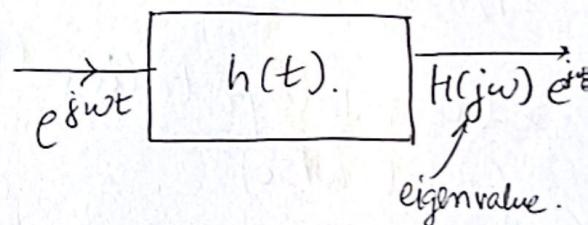
Let $x(t) = e^{j\omega t}$ → Eigenfunctions of LTI Systems.

$$\Rightarrow y(t) = \int_{-\infty}^{\infty} h(\tau) x(t - \tau) d\tau$$

$$= \int_{-\infty}^{\infty} h(\tau) e^{j\omega t} e^{-j\omega \tau} d\tau$$

$$= e^{j\omega t} H(j\omega)$$

$$= H(j\omega) e^{j\omega t}$$



$$y(t) = H(j\omega) x(t) \quad \text{when } x(t) = e^{j\omega t}$$

- ⇒ $H(j\omega)$ is the magnitude & phase added to a sinusoidal excitation at ω . → This is only true at $S = j\omega$.

Recap

$$x(t) = \delta(t) \Rightarrow y(t) = h(t) \text{ impulse response.}$$

$$x(t) = e^{j\omega t} \Rightarrow y(t) = H(j\omega) e^{j\omega t}$$

frequency response
aka transfer function
since $H(j\omega) = \frac{Y(j\omega)}{X(j\omega)}$

$$\mathcal{L}\{h(t)\} = H(s) = H(j\omega) \Big|_{s=j\omega}$$

$\mathcal{F}\{h(t)\} = H(j\omega) \rightarrow$ Bode Plot approximates this.

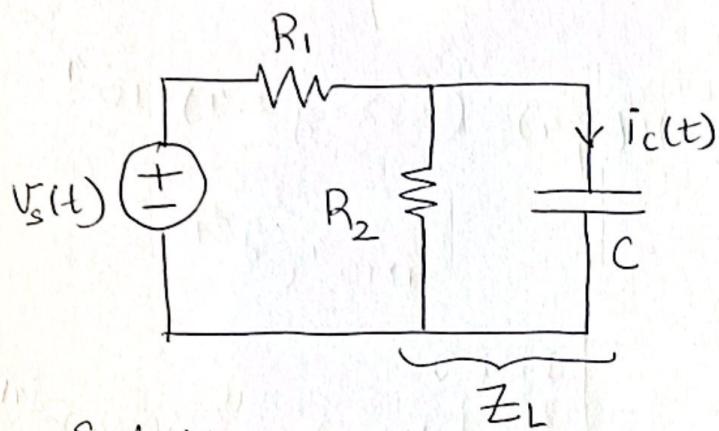
Fourier Domain $H(j\omega)$

- > Steady state sinusoidal (brother) signals $e^{j\omega t} \rightarrow$ steady state response.
- > No initial conditions.
- > Clear interpretation (Bode Plots). (point-wise)
- > Assumes stability.
- > Cannot enforce causality.
- > No ROC (implicit)

Laplace Domain $H(s)$

- > Transient signals \rightarrow transient response.
- > Can have initial conditions.
- > More complex $\mathcal{L}\{h(t)\}$. (not pointwise).
- > Stability can be tested (RHP poles).
- > Enforces causality.
- > ROC (explicit).

Example



$$R_1 = 2k\Omega, R_2 = 4k\Omega$$

$$C = 2.5 \times 10^{-4} F$$

$$V_s(t) = 5 \cos(4t)$$

Find $i_c(t)$.

Solution

$$V_s(j\omega) = \mathcal{F}\{v_s(t)\} = \frac{5\pi}{2} \left[\delta(\omega - 4) + \delta(\omega + 4) \right]$$

$$H(j\omega) = \frac{I_c(j\omega)}{V_s(j\omega)} = \frac{V_L}{V_s} \cdot \frac{I_c}{V_L}$$

$$= \frac{Z_L}{Z_L + R_1} \cdot j\omega C, \quad Z_L = R_2 \parallel Z_C = \frac{R_2}{1 + j\omega C R_2}$$

$$H(j\omega) = \frac{j\omega C R_2}{R_2 + R_1(1 + j\omega C R_2)}$$

Recall
FT of $A \cos(\omega_0 t)$ is
 $\frac{\pi A}{2} [\delta(\omega - \omega_0) + \delta(\omega + \omega_0)]$

$$I_c(j\omega) = H(j\omega) V_s(j\omega)$$

$$= H(j\omega) \left[\frac{5\pi}{2} \{ \delta(\omega - 4) + \delta(\omega + 4) \} \right]$$

$$= \frac{5\pi}{4} \left[H(j4) \delta(\omega - 4) + H(-j4) \delta(\omega + 4) \right]$$

$$H(j4) = (3.2 + j2.4) \times 10^{-4} \quad ; \quad H(-j4) = (3.2 - j2.4) \times 10^{-4}$$

$$= 4 \times 10^{-4} e^{j37^\circ}$$

$$\Rightarrow i_c(t) = FT^{-1} \{ I_c(j\omega) \}$$

$$= 2 \times 10^{-3} \cos(4t + 37^\circ) A$$

Using Eigenfunctions.

$$i_c(t) = H(j\omega) v_s(t)$$

$$= \text{Re} \{ 4 \times 10^{-4} e^{j37^\circ} \cdot 5 \times e^{j4t} \}$$

$$= \text{Re} \{ 2 \times 10^{-3} e^{j(4t + 37^\circ)} \}$$

$$= 2 \times 10^{-3} \cos(4t + 37^\circ) A$$

IFT

$$\frac{5\pi}{4} \left[H(j4) e^{j4t} + H(-j4) e^{-j4t} \right]$$

$$= \frac{5}{4} \left[24 \times 10^{-4} e^{j4t + 37^\circ} + 24 \times 10^{-4} e^{-j4t - 37^\circ} \right]$$

$$= 20 \times 10^{-4} \left[\frac{e^{j(4t + 37^\circ)} + e^{-j(4t + 37^\circ)}}{2} \right]$$

$$= 2mA \cdot \cos(4t + 37^\circ)$$