HPC Tutorial 4 Report CS22B2012 K Aditya Sai

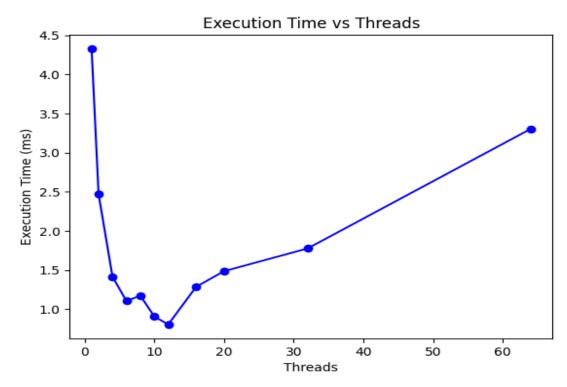
The code for Dot Product of vectors is implemented in C++ with OpenMP.

- 1. Thread Allocation: The code is executed with thread counts ranging from 1 to 64
- 2. **Dataset Generation**: A C++ code generates two files containing 1 million double-precision floating-point values randomly which are stored in input1.txt and input2.txt.
- 3. **Performance Analysis**: Execution times for the vector multiplication and scalar addition are recorded and speedup/parallelization fractions are calculated.
- 4. **Visualization**: Python scripts generate plots for execution time and speedup.

Parallel Code for Dot Product

```
double dot_product(vector<double> &A, vector<double> &B)
{
    double sum = 0.0;
    #pragma omp parallel
    {
        double prod = 0.0;
        #pragma omp for
        for (int i = 0; i < N; i++)
        {
            prod += A[i] * B[i];
        }
        #pragma omp critical
        sum += prod;
    }
    return sum;
}</pre>
```

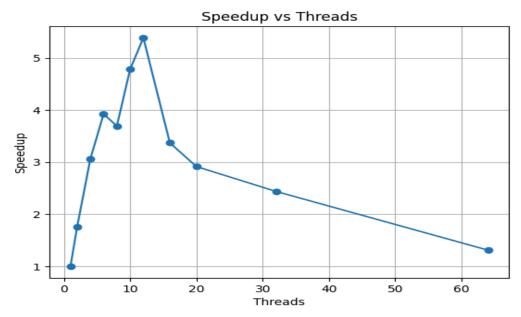
Plot Threads v/s Time:



Observations:

- 1. When increasing thread count from 2 to 12, execution time drops and there is a small irregularity from 6 cores to 8 cores and then to 10 cores.
- 2. The combined effect of both multiplication and addition and the thread management overhead results in an increase in the execution time.
- 3. Compared to the previous tutorial, we see that the increase after the 12 thread mark is much cheaper.
- 4. So we can conclude that performing multiplication and simultaneous addition is even more expensive.

Plot Threads v/s Speedup:



Observations:

- 1. The sudden spike in the overall speedup from 1 thread to 12 threads shows that for the system on which this was performed, 12 threads is the most optimal in case of vector dot product.
- 2. The speedup starts to have a steeper descent compared to both vector addition and multiplication. Since dot product involves vector multiplication and then aggregation.
- 3. The parallel construct seems to efficiently parallelize and reduce the execution time up-to 12 threads after which the CPU and thread management overheads start to negatively affect the speedup.

Inferences:

- 1. Since speedup is calculated by Amdahl's law, the speedup is inversely proportional to parallelized execution time.
- 2. If we look at the speedup and execution time graphs side by side we would notice that the slope of the descent in **speedup** looks similar to the magnitude of slope of ascent in **execution time**.

Estimated Parallelization Fraction:

```
=== Parallelization Fraction Table ===
Threads P. Fraction
   1
        1.000000
   2
         0.858727
   4
        0.897801
   6
         0.894175
   8
         0.833414
  10
         0.878704
         0.888392
  12
  16
         0.750025
  20
         0.691603
         0.608944
  32
  64
         0.240891
```

Observations:

- 1. The parallelization fraction reaches its peak at 10 threads for addition and 12 threads for multiplication..
- 2. Addition parallelization drops more sharply beyond 10 threads likely because it encounters more parallelization bottlenecks sooner.
- 3. Up to 10 threads, multiplication maintains a higher fraction (≥ 0.9) compared to addition.
- 4. This suggests multiplication scales better with increasing threads, meaning it has less synchronization or memory bottlenecks.

Conclusion:

- The optimal number of threads for this workload appears to be around 10-12.
- Beyond this point, increasing threads leads to higher overhead, lower efficiency, and even increased execution time.
- The decrease in parallel fraction with more threads suggests that parts of the computation remain sequential or suffer from synchronization bottlenecks.
- The usage of critical causes increase in execution time due to thread synchronization overhead.