

# Deep Convolutional Neural Network for Real Time Visual Inspection of Structural Audit

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Abstract

# Key Points

- Structural audit requires manual expertise of surveyors that can be subjective and erroneous
- Digital Image Processing needs to be hardcoded and Deep Learning has been applied for only crack detection
- There is a need for a single generalized model, which can classify more than one structural defect during the visual inspection of structural audit

## Key Points (Cont.)

- The proposed system classifies cracks, dampness and paint peel-off using a single generalized model as a part of visual inspection while doing structural audit of infrastructures
- The contribution of this work is 95% overall accuracy, 95% average precision, 95.25% average recall, and 95% average F1-score
- Usage of a non-complex model has reduced the time taken for training the model and getting predictions from the model

# Introduction

# Background

- Construction of different infrastructures is a necessity for human life
- Old buildings show cracks, paint peel off, and dampness
- Buildings need to be audited after 30 years
- Visual inspection for detection of cracks, dampness, paint peel off totally depends on the surveyor's experience and knowledge
- There may be human errors

# Literature Review

# Digital Image Processing

- MESG algorithm is use for enhancing the noisy image
- SOBEL filter is used for obtaining binary image
- CANNY edge detection is used for feature extraction
- HMRF-EM algorithm is used to increase the accuracy to label the data
- Particularly good accuracy for detection crack (up to 90% accuracy)
- Numerous algorithm available for usage: grouping different algorithms can be used to detect crack.
- Grouping of Algorithms for one problem cannot be used for another problem



# Deep Learning for Crack Detection

- Deep Convolutional Neural Network (DCNN) is capable to sense the crack robustly while dealing with complicated background images
- Hessain matrix based linear filtering approach used to increase crack area and regulate threshold gap to get crack binarization segmentation result.
- Using Internet of Things (IoT) technology for collecting video data is easy and solves the problems of high risk factor in domestic and low fracture analysis.
- Genetic Algorithm for CNN model evolved several parameters that dictate the structure of CNN

# Structural Audit

- Overall health examination of a building to ensure its safety
- It identifies parts of a building that may be in need of immediate repair, renovation or replacement
- Should be conducted once in 5 years for 15-30 years old buildings
- Should be conducted once every 3 years for 30+ years old buildings
- A structural audit is a highly recommended preventive measure to avoid any calamitous eventualities altogether

# Deep Learning on Video Images

- Using Full Convolution Network (FCN) enables pixel level classification
- Temporal features of subsequent frames can be captured using Convolutional Long Short Term Memory (Conv-LSTM)
- Faster Region-based Convolutional Neural Network (R-FCN) gives better accuracy results
- You Look Only Once (YOLO) processes the input faster and can be used in real time classification

# Problem Statement

There is a need for a single generalized model, which can classify more than one structural defect during the visual inspection of structural audit

Proposed Solution

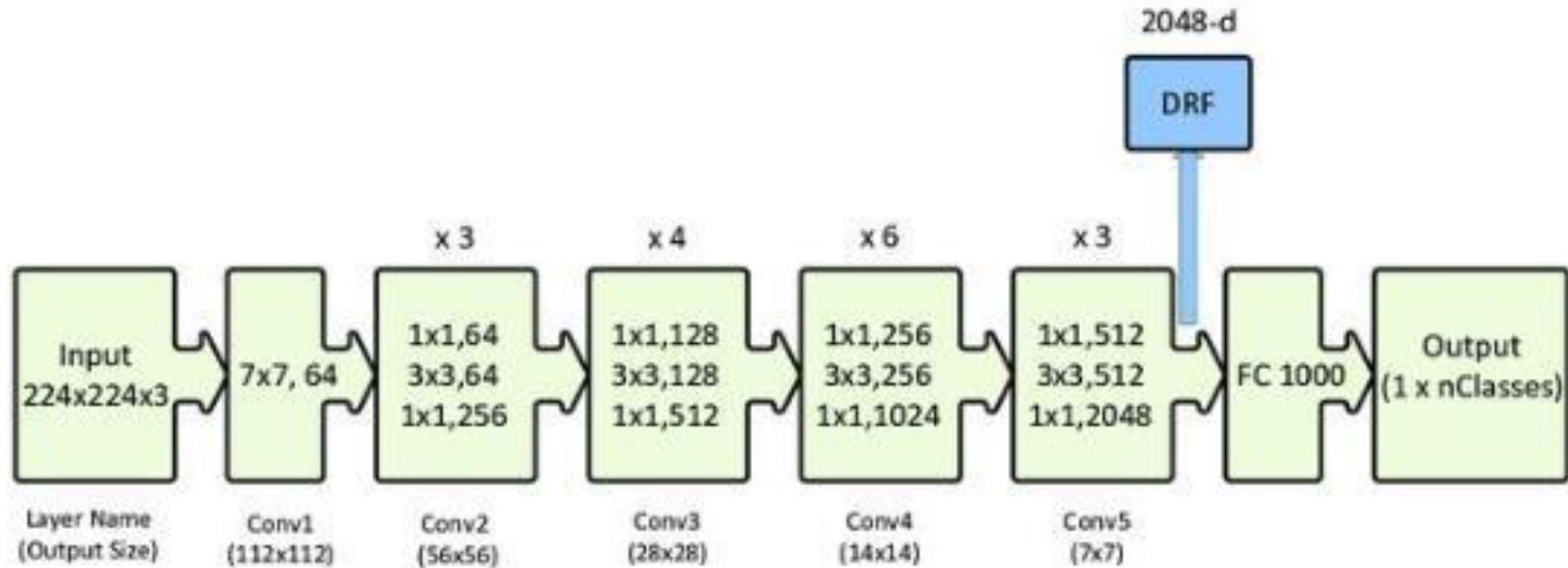
# Proposed System

The proposed system classifies cracks, dampness and paint peel-off using a single generalized model as a part of visual inspection while doing structural audit of infrastructures

# Transfer Learning

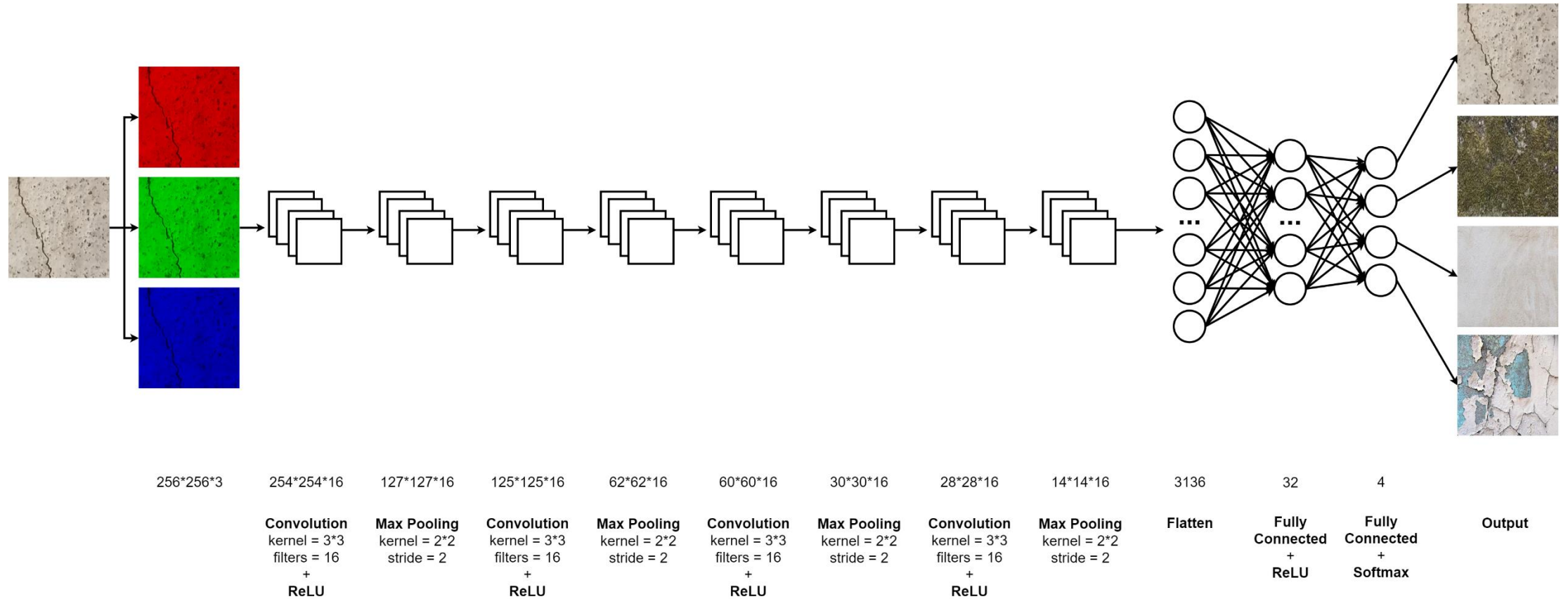
Transfer learning is a research problem in machine learning that focuses on storing knowledge gained while solving one problem and applying it to a different but related problem

# ResNet-50 Model Architecture





# Effective Defect Classifier (EDC)



# Sliding Window Mechanism

- The video is divided into frames and each frame is divided into grids
- Each sub-image in the grid is passed to the model for prediction
- The predictions are then color coded
- The color coded result is pasted along with the original video frames

# Results and Analysis

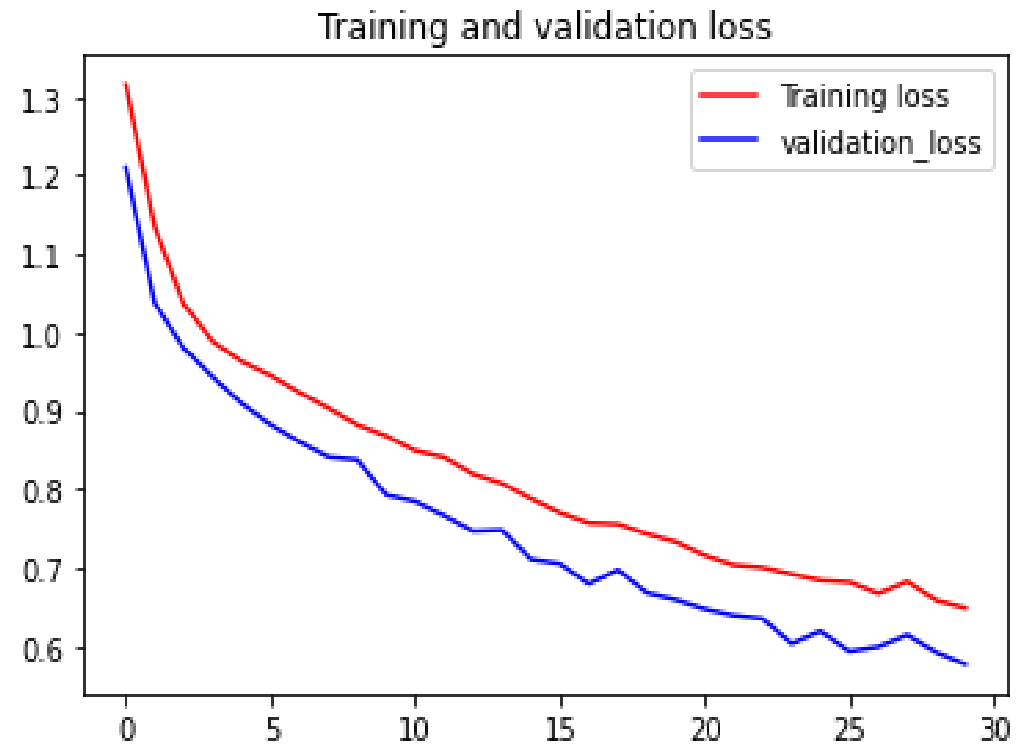
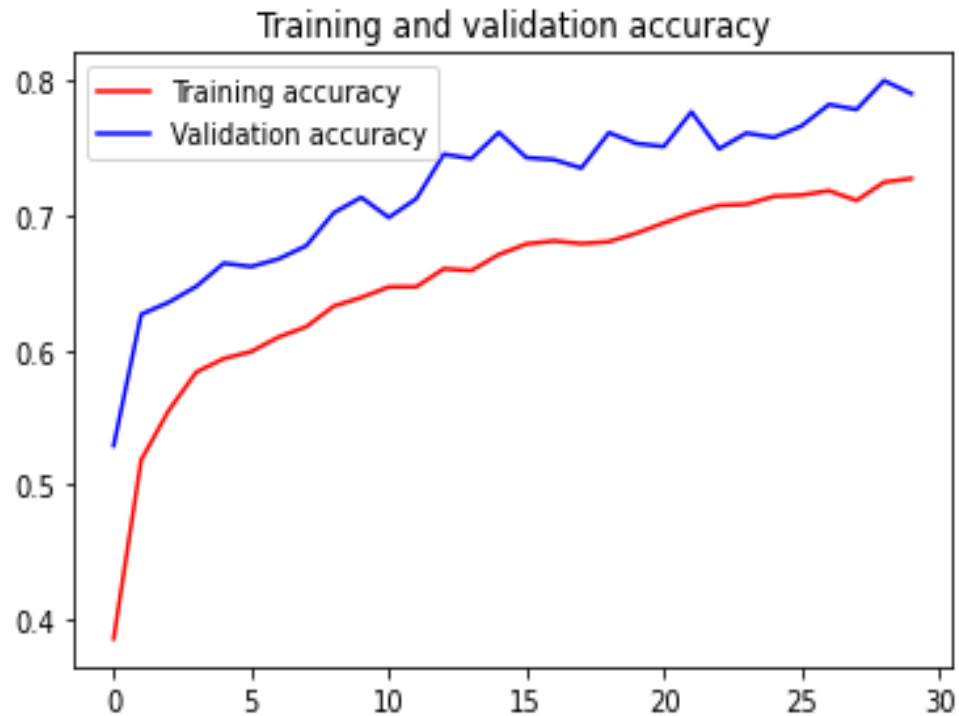
# Dataset

- 4 Classes – Crack, Dampness, Paint Peel Off, Plain Wall
- Image Dimensions –  $256 \times 256$
- Training Size – 32,000
- Testing Size – 4,000
- Non Distorting Transformations – 7
- Distorting Transformations – 2

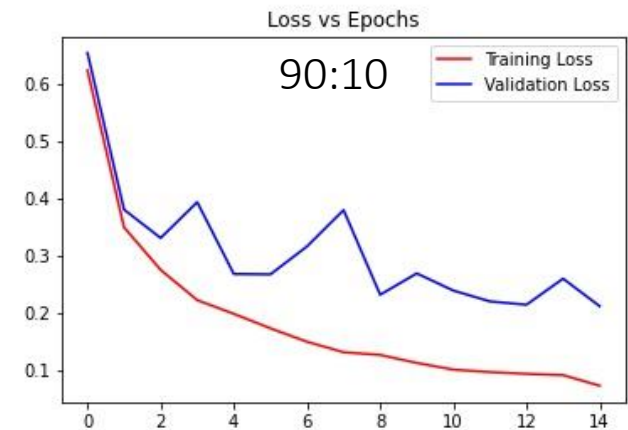
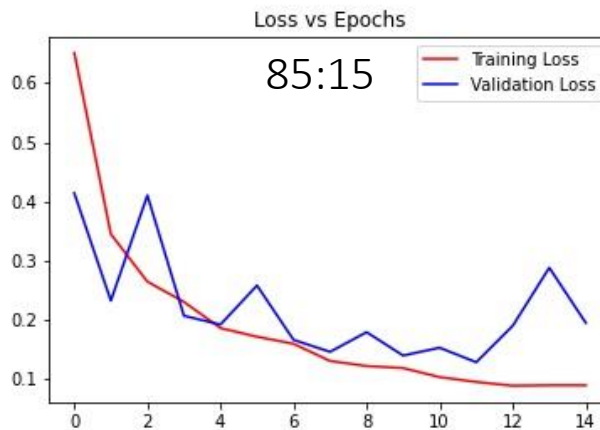
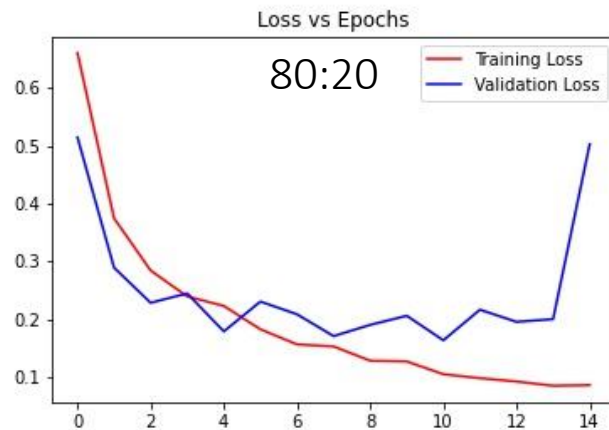
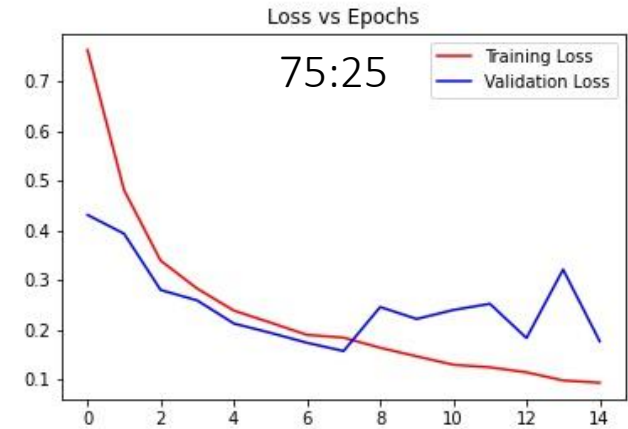
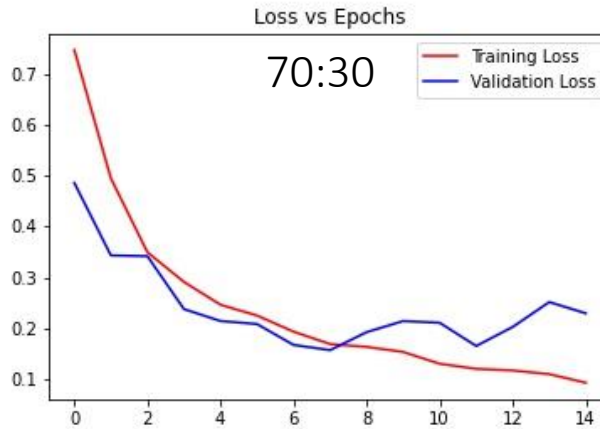
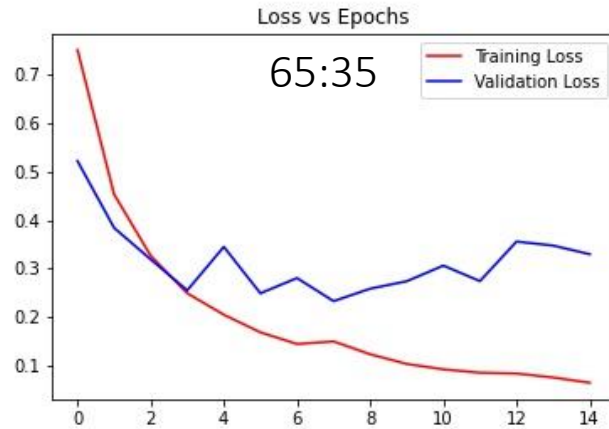
# Transfer Learning

- ResNet-50 is not similar to our problem
- Validation accuracy of the model trained was very poor
- 9 out of 10 images were incorrectly classified.

# Transfer Learning Model Accuracy and Loss



# EDC - Train and Test Split Ratio



# EDC – Confusion Matrix

Predicted→ Actual↓	C	D	N	P	Total
C	932	27	13	28	1000
D	16	966	8	10	1000
N	8	10	957	25	1000
P	24	11	19	946	1000

	C	Not C
C	TP = 932	FN = 68
Not C	FP = 48	TN = 2952

	D	Not D
D	TP = 966	FN = 34
Not D	FP = 48	TN = 2952

	N	Not N
N	TP = 957	FN = 43
Not N	FP = 40	TN = 2960

	P	Not P
P	TP = 946	FN = 54
Not P	FP = 43	TN = 2957

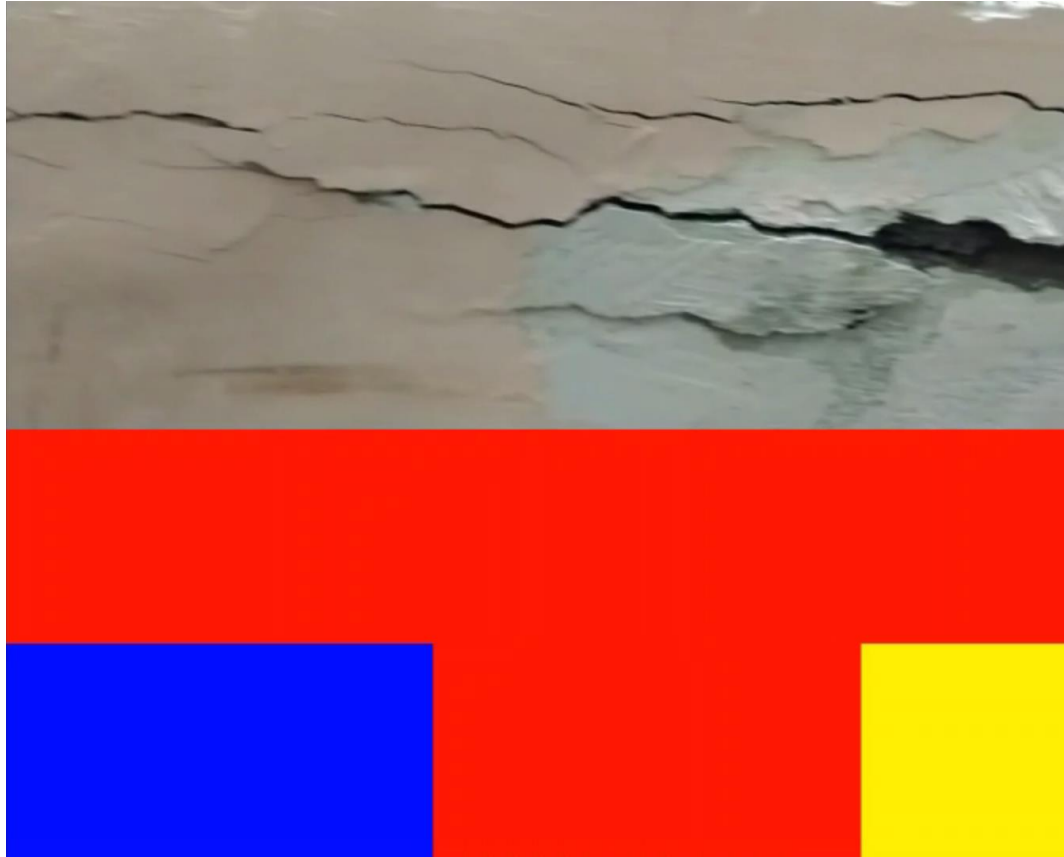


# EDC – Metrics

- Training Time – 77.6 seconds per epoch on an average
- Accuracy – 95%

	Precision	Recall	F1-Score	Total
Crack	0.95	0.93	0.94	1000
Dampness	0.95	0.97	0.96	1000
Plain Wall	0.96	0.96	0.96	1000
Paint Peel Off	0.94	0.95	0.94	1000

# Sliding Window Output Frames



Red – Crack | Green – Dampness | Blue – Plain Wall | Yellow – Paint Peel Off

# Sliding Window Output Frames Cont.



# Conclusion and Future Scope

# Conclusion

- EDC classifies more labels than existing models
- Use of non complex model has reduced training and prediction times
- Average metric for Accuracy, Precision, Recall, and F1-Score is 95%

# Future Scope

- Dataset size can be increased by doing more surveys
- More types of defects can be incorporated into the model
- Pre-processing techniques can be applied to get more features from images

# Appendix

# Training Time History

Epochs	Training Time (sec)	Epochs	Training Time (sec)
1	80	9	77
2	80	10	77
3	78	11	77
4	78	12	77
5	78	13	77
6	77	14	77
7	77	15	77
8	77	-	-
Avg. Training Time per Epoch		77.6 seconds	
Total Training Time for 15 Epochs		19 minutes 24 seconds	



# Accuracy and Loss History

Epochs	Training Accuracy (%)	Validation Accuracy (%)	Training Loss	Validation Loss
1	70.36	71.95	0.71	0.70
2	85.69	91.30	0.39	0.35
3	90.88	92.90	0.29	0.22
4	92.09	90.68	0.25	0.30
5	92.60	92.37	0.21	0.22
6	93.79	91.15	0.19	0.28
7	93.74	93.15	0.17	0.21
8	95.06	93.48	0.17	0.23

# Accuracy and Loss History (Cont.)

Epochs	Training Accuracy (%)	Validation Accuracy (%)	Training Loss	Validation Loss
9	95.06	94.67	0.13	0.17
10	95.12	94.35	0.13	0.24
11	95.51	93.48	0.12	0.27
12	96.16	94.23	0.10	0.20
13	96.57	95.15	0.09	0.23
14	96.41	94.92	0.10	0.24
15	97.12	95.07	0.08	0.26