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## Operating System Assignment 01

### PART A

Ques1 Ans modern systems still rely heavily on operating system because:-

- resource management → The OS efficiently manages hardware resources (CPU, memory, storage, I/O devices) and allocates them to different programs.

User & Application Interface → The OS provides a convenient interface b/w hardware and users / applications, enabling portability, multitasking and security.

Ques2 Ans Real - Time operating System (RTOS)

RTOS ensures timely, predictable and reliable response to inputs like heart rate signals process management on small, low power hardware - critical for health monitoring devices

Ques3 Avoid a monolithic kernel while it gives fast system calls, they lack modularity and are harder to maintain / debug. A bug in one service can crash the whole system making them unreliable for critical systems.

*ques & Ans* refute the claims, because OS structure directly impacts performance, reliability, scalability and security.

For ex:- microkernel isolates services for fault tolerance; while a layered structure improves maintainability.

Just "running process" isn't enough if the system is slow, unsecure or unstable.

*ques 5*

i) The PCB stores CPU register, program counter state and memory info. By enabling it we can detect misinitialized register, wrong state flags, incorrect program counter values that cause faulty switching.

(ii) When a task unexpectedly moves from running to waiting context switching saves the current process state (register, program counter, PCB updates) and loads the state of the next process. It ensures execution resumes correctly later.

(iii) Use an asynchronous, non blocking system call because this allows the process to continue execution while the I/O is allocated in the background preventing the CPU from idling

### PART B

Ques 1

a) Total context switching time,  
Save state = 2ms

Load state = 3ms

Scheduler overhead = 1ms

Total time =  $2+3+1 = 6\text{ms}$

b) Context switching is pure overhead (no useful work is done during this time).

Higher switching time reduces CPU efficiency as more time is spent switching than executing process

In multitasking, frequent context switches with high overhead can slow down throughput and increase response time.

Ques 2 Execution time (single threaded) = 40 sec  
Multithreading is used with ~~x~~ threads per process

Execution time estimate:

In ideal condition (perfect parallelism no overhead):

$$T_{\text{multi}} = \frac{T_{\text{single}}}{n} = \frac{40}{n} \text{ seconds}$$

Example

$$\text{if } n=2 \rightarrow 20 \text{ sec}$$

$$\text{if } n=4 \rightarrow 10 \text{ sec}$$

$$\text{if } n=8 \rightarrow 5 \text{ sec}$$

How multithreading improves performance

- It improves performance by running tasks in parallel reducing execution time.
- It keeps the CPU busy even during I/O waits avoiding idle time.

Threads shares resources, making execution faster and more efficient.

Ques 8 Process : P<sub>1</sub> P<sub>2</sub> P<sub>3</sub> P<sub>4</sub>  
Burst time 5 3 8 6

(a) FCFS

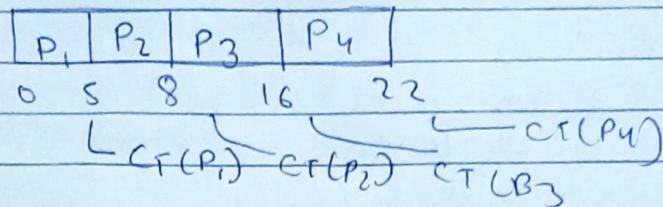
Process	Arrival time (AT)	Burst time	Completion time (CT)	Waiting time (WT)	TAT
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P <sub>1</sub>	0	5	5	5-5=0	5-5=0
P <sub>2</sub>	0	3	8	8-3=5	8-0=8
P <sub>3</sub>	0	8	16	16-8=8	16-0=16
P <sub>4</sub>	6	6	22	22-6=16	22-0=22

$WT = \text{Turnaround-Burst} (TAT - BT)$

$TAT = \text{completion-Arrival} (CT - AT)$

Grant chart,



$$\text{Avg waiting time} = (0+5+8+16)/4 = 7.25 \text{ ms}$$

$$\text{Avg turnaround time} = (5+8+16+22)/4 = 12.75 \text{ ms}$$

(b) Non-preemptive SJF

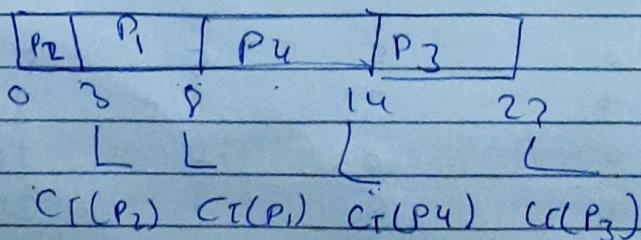
Process

Process	AT	BT	CT	WT	TAT
$P_1$	0	5	8	$8-5=3$	$8=8-0$
$P_2$	0	3	3	$3-3=0$	$3=3-0$
$P_3$	0	8	22	$22-8=14$	$22=22-0$
$P_4$	0	6	14	$14-6=8$	$14=14-0$

$$TAT = CT - AT$$

$$WT = TAT - BT$$

Grant chart



$$\text{Avg waiting time} = (3+0+14+8)/4 = 6.25 \text{ ms}$$

$$\text{Avg turnaround time} = (8+3+22+14)/4 = 11.75 \text{ ms}$$

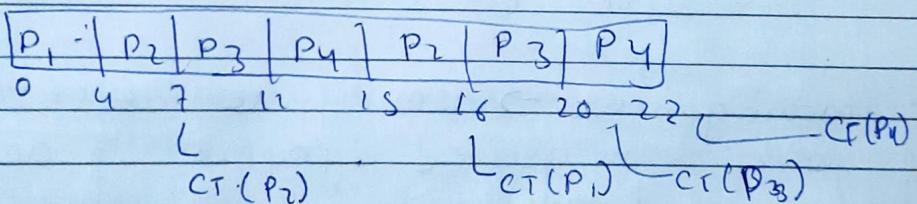
(c) round robin (quantum = 4ms)

Process	AT	BT	CT	WT	TAT
P <sub>1</sub>	0	8	16	16 - 8 = 8	16 - 0 = 16
P <sub>2</sub>	0	3	7	7 - 3 = 4	7 - 0 = 7
P <sub>3</sub>	0	8	20	20 - 8 = 12	20 - 0 = 20
P <sub>4</sub>	0	6	22	22 - 6 = 16	22 - 0 = 22

$$WT = TAT - BT$$

$$TAT = CT - AT$$

Gantt chart



$$\text{Avg waiting time} = (11+4+12+16)/4 = 10.75 \text{ ms}$$

$$\text{Avg turnaround} = (16+7+20+22)/4 = 16.25 \text{ ms}$$

- \* Non-preemptive SJF is best because it gives the lowest average waiting time (6.25 ms) and turnaround time (11.75 ms) while throughput remains the same ( $4/22$ ) in all methods. It balances turnaround and throughput better than FCFS or RR.

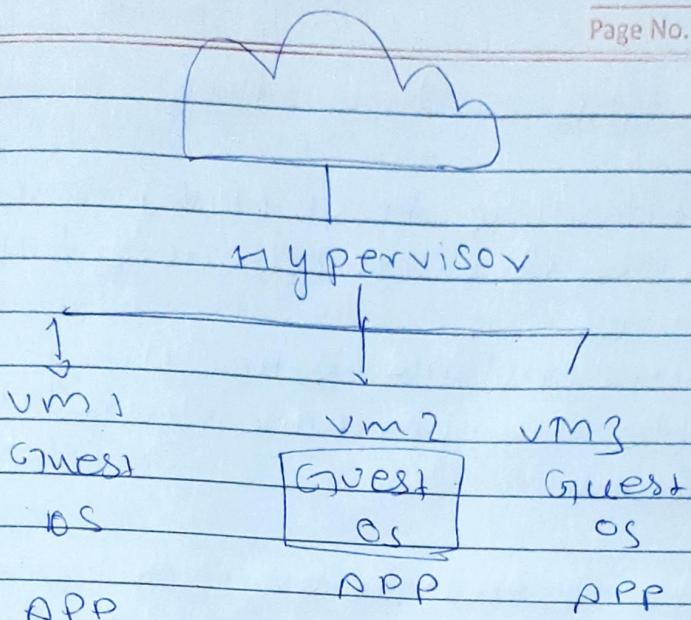
### Ques i) virtualised cloud migration

a) microkernel Architecture would be the best choice because

High Scalability → services (like drivers, file system, networking, run the user space and can be extended / updated easily)  
High security & fault isolation → failure in one service doesn't crash the entire system.

b) Role of virtual machines in migration

- Isolation → each VM runs its own OS, preventing one service failure or attack from affecting others
- management → VM can be created, paused or migrated dynamically across servers for load balancing
- resource optimization → hypervisor allocates CPU memory and I/O efficiently among VMs, ensuring better utilization and reducing wastage.



## (ii) Smart home system (iot devices)

(a) <sup>role</sup> OS sched with scheduling ~~ctrl~~ + IPC

- Process scheduling → The OS assigns higher priority to critical tasks (e.g. intrusion detection) so they preempt less urgent ones (like lighting)
- Inter process communication (IPC) → Enables devices and controller process to exchange data quickly (e.g.: camera sends motion alert → controller process reacts immediately)

b) suitable scheduling Algoriths

- Priority scheduling → ensures urgent process like security alerts prompt

## Course Note

Earliest deadline first (EDF) → useful  
because tasks must complete before specific deadlines

Rate-monotonic scheduling (RMS):  
suitable for periodic tasks, like sensor checks

Among these, PS or EDF are most effective as they guarantee timely execution of safety-critical events while maintaining system responsiveness

### smart Home controller

