# Medical Image Processing for Interventional Applications

Super-Resolution: Regularization

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# **Topics**

#### Maximum A Posteriori Estimation

Image Priors

Summary

Take Home Messages Further Readings







# **Super-Resolution and III-posed Problems**

#### ML estimation on a synthetic example:

- Super-resolution is an **ill-posed** problem
- → ML reconstruction might lead to unstable solutions with amplified noise.





Figure 1: Example for insufficient result from ML estimation







# **Super-Resolution and III-posed Problems**

#### ML estimation on a synthetic example:

- Super-resolution is an **ill-posed** problem
  - → ML reconstruction might lead to unstable solutions with amplified noise.
- Way out: Incorporate prior knowledge into super-resolution algorithm.





Figure 1: Example for insufficient result from ML estimation







#### **Maximum A Posteriori Estimation**

#### Extension of the ML estimation to MAP estimation:

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- According to Bayes formula, we have:

$$\hat{\mathbf{x}}_{MAP} = \underset{\mathbf{x}}{\operatorname{arg\,max}} p(\mathbf{x}) p(\mathbf{y} | \mathbf{x}) = \underset{\mathbf{x}}{\operatorname{arg\,min}} \left\{ -\log p(\mathbf{x}) - \log p(\mathbf{y} | \mathbf{x}) \right\}.$$







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For additive Gaussian noise, MAP estimation is equivalent to:

$$\hat{\mathbf{x}}_{MAP} = \underset{\mathbf{x}}{\operatorname{arg\,min}} \sum_{k=1}^{K} \left| \left| \mathbf{y}^{(k)} - \mathbf{W}^{(k)} \mathbf{x} \right| \right|_{2}^{2} - \log p(\mathbf{x}) = \underset{\mathbf{x}}{\operatorname{arg\,min}} \left| \left| \mathbf{y} - \mathbf{W} \mathbf{x} \right| \right|_{2}^{2} - \log p(\mathbf{x}).$$







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## **Image Prior and Regularization Term**

#### Mathematical framework for image priors in super-resolution:

• We define the prior distribution according to the exponential form:

$$p(\mathbf{x}) = \frac{1}{Z} \exp(-\lambda R(\mathbf{x})),$$

where Z is a normalization constant, and R(x) denotes a regularization term with regularization weight  $\lambda \geq 0$ .







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- The regularizer R(x) can be defined such that it penalizes large variations in x.
- The regularization weight  $\lambda$  measures the impact of the prior:
  - $\lambda = 0$ : simple ML estimation,
  - $\lambda \to \infty$ : estimation dominated by the prior distribution.







#### Gaussian prior (Tikhonov regularization):

•  $p(\mathbf{x})$  is a normal distribution, i. e.,  $\mathbf{x} \sim \mathcal{N}(0, \mathbf{\Sigma})$  and accordingly:

$$p(\mathbf{x}) = \frac{1}{(2\pi)^{N/2} |\mathbf{\Sigma}|^{1/2}} \exp\left(-\frac{1}{2}\mathbf{x}^T \mathbf{\Sigma}^{-1} \mathbf{x}\right).$$







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- This regularization favors smooth solutions for x.
- It facilitates a closed-form solution, but does not preserve discontinuities.







## Total variation (TV):

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$$p(x) \propto \exp(-\lambda R(x))$$
, where  $R(x) = \sqrt{||Q_u x||_2^2 + ||Q_v x||_2^2}$ .

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• It favors piecewise constant solutions for x (edge preserving regularization).







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- BTV is a generalization of the TV prior
- Compare **x** to multiple shifted versions as generalization of the gradient in a  $(2P+1) \times (2P+1)$  window:

$$p(\mathbf{x}) \propto \exp\left(-\lambda \sum_{u=-P}^{P} \sum_{v=-P}^{P} \alpha^{|u|+|v|} \left|\left|\mathbf{x} - \mathbf{S}_{i}^{u} \mathbf{S}_{j}^{v} \mathbf{x}\right|\right|_{1}\right).$$

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• It reduces "'staircasing" artifacts which occur using the common TV prior.







## Huber prior:

• p(x) is modeled by the Huber loss function:

$$p(\mathbf{x}) \propto \exp\left(-\lambda \sum_{i=1}^{N} h_{\tau}([\mathbf{Q}\mathbf{x}]_{i})\right),$$
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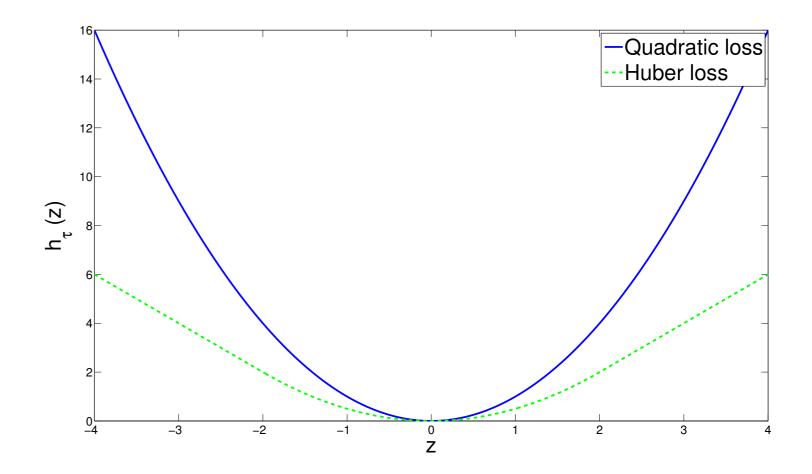


Figure 2: Comparison of quadratic loss and Huber loss







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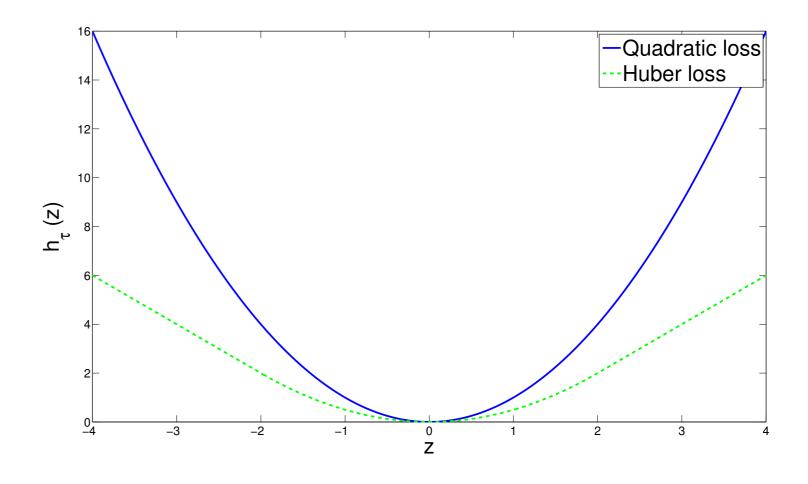


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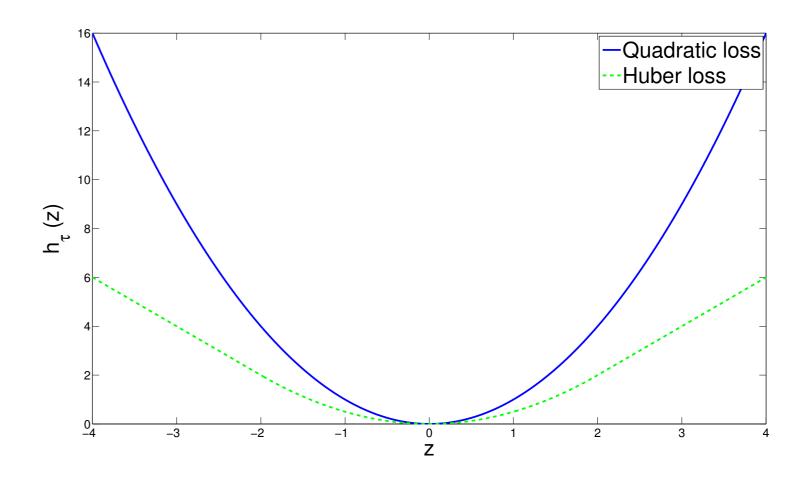


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# **ML** and **MAP** Estimation: Discussion





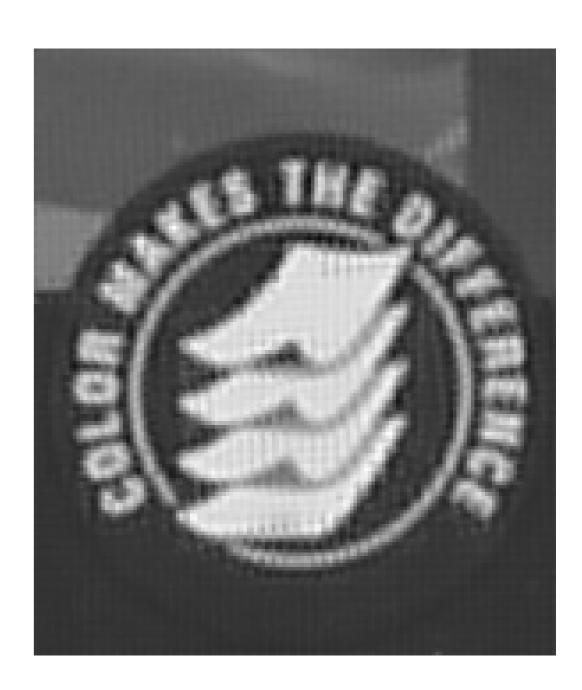


Figure 3: Low-resolution frame (left), ML estimation (middle), MAP estimation with TV prior (right)







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# **Take Home Messages**

- Super-resolution is an ill-posed problem, so using regularization by utilizing prior knowledge is a good idea.
- We introduced several regularizers: Tikhonov, TV, BTV, and the edge-preserving approach using the Huber loss function.
- Regularization needs extra thought when implementing, but it is an important method to achieve adequate image quality.







## **Further Readings**

Theory of image super-resolution (books and review articles):

- Hayit Greenspan. "Super-Resolution in Medical Imaging". In: *The Computer Journal* 52.1 (Feb. 2008), pp. 43–63. DOI: 10.1093/comjnl/bxm075
- Peyman Milanfar, ed. Super-Resolution Imaging. Digital Imaging and Computer Vision. CRC Press, 2011
- Sina Farsiu et al. "Advances and Challenges in Super-Resolution". In: *International Journal of Imaging Systems and Technology* 14.2 (Aug. 2004), pp. 47–57. DOI: 10.1002/ima.20007
- Sung Cheol Park, Min Kyu Park, and Moon Gi Kang. "Super-Resolution Image Reconstruction: A Technical Overview". In: *IEEE Signal Processing Magazine* 20.3 (May 2003), pp. 21–36. DOI: 10.1109/MSP.2003.1203207

#### ML/MAP super-resolution:

- Lyndsey C. Pickup. "Machine Learning in Multi-frame Image Super-resolution". PhD Thesis. Robotics Research Group, University of Oxford, 2007
- Michael Elad and Arie Feuer. "Restoration of a Single Superresolution Image from Several Blurred, Noisy, and Undersampled Measured Images". In: *IEEE Transactions on Image Processing* 6.12 (Dec. 1997), pp. 1646–1658. DOI: 10.1109/83.650118