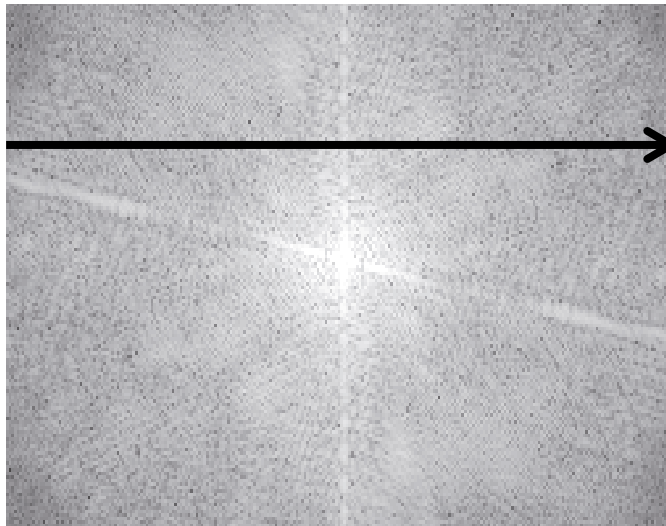


# Repetition



# Learning objectives

Understand important effects of finite  
k-space velocity on Cartesian MRI



Chemical shift, field inhomogeneities,  $T_2$  relaxation

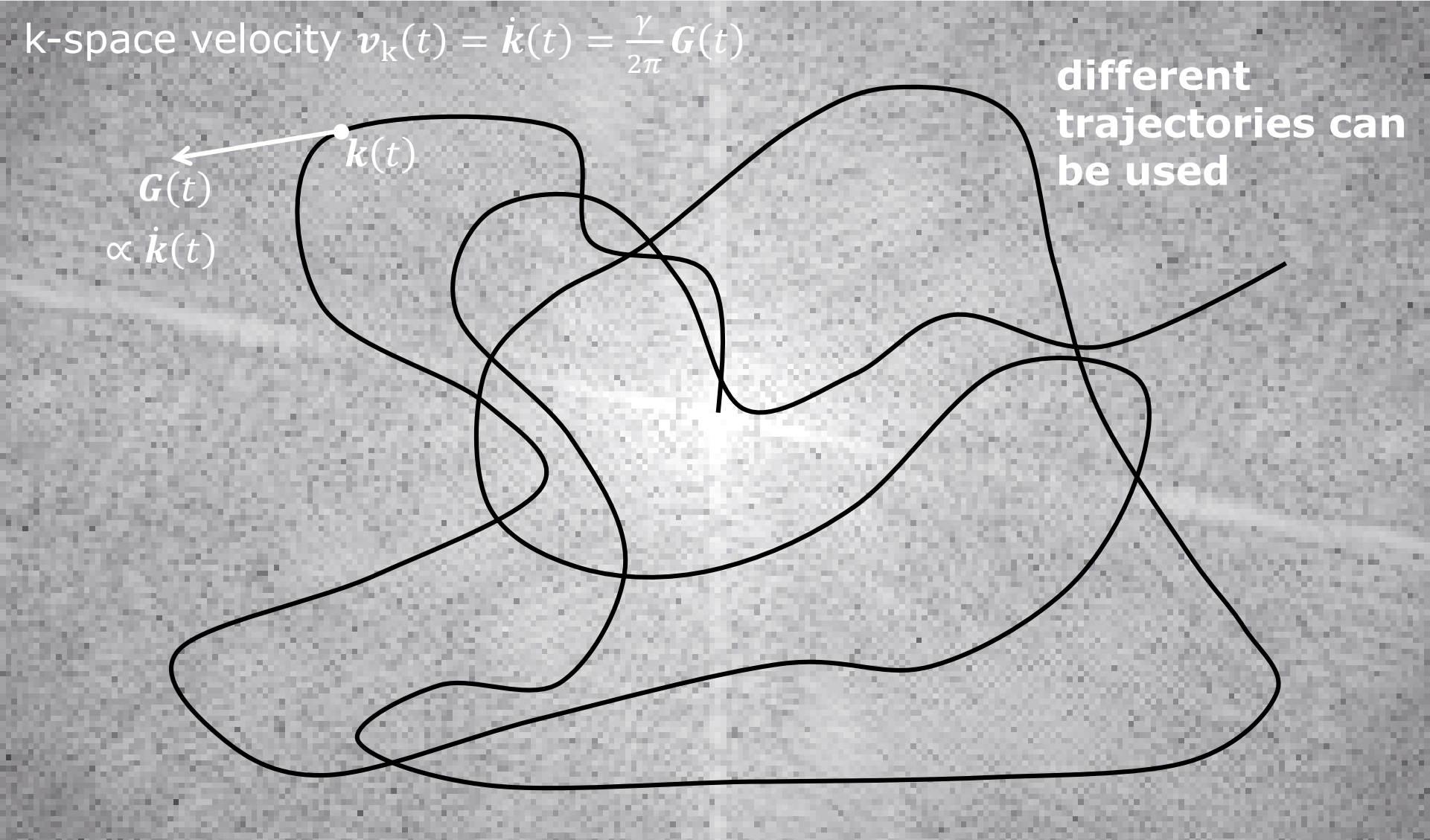


# We can sample arbitrary trajectories

$$\mathbf{k}(t) = \frac{\gamma}{2\pi} \int_{t_0}^t \mathbf{G}(t') dt'$$

k-space velocity  $\mathbf{v}_k(t) = \dot{\mathbf{k}}(t) = \frac{\gamma}{2\pi} \mathbf{G}(t)$

$\mathbf{G}(t)$   
 $\propto \dot{\mathbf{k}}(t)$

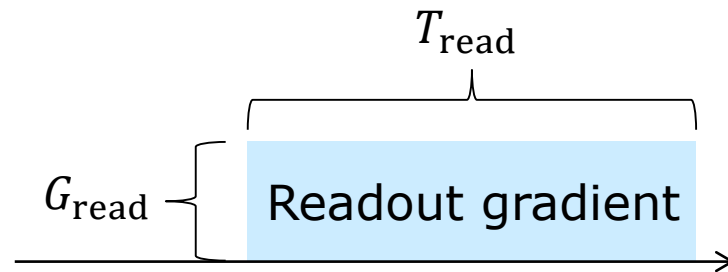


**different  
trajectories can  
be used**



# Summary

$$\mathbf{k}(t) = \frac{\gamma}{2\pi} \int_0^t \mathbf{G}(t') dt'$$



$$k_{\text{read}}(t) = \frac{\gamma}{2\pi} G_{\text{read}} t - k_{\text{max}}$$

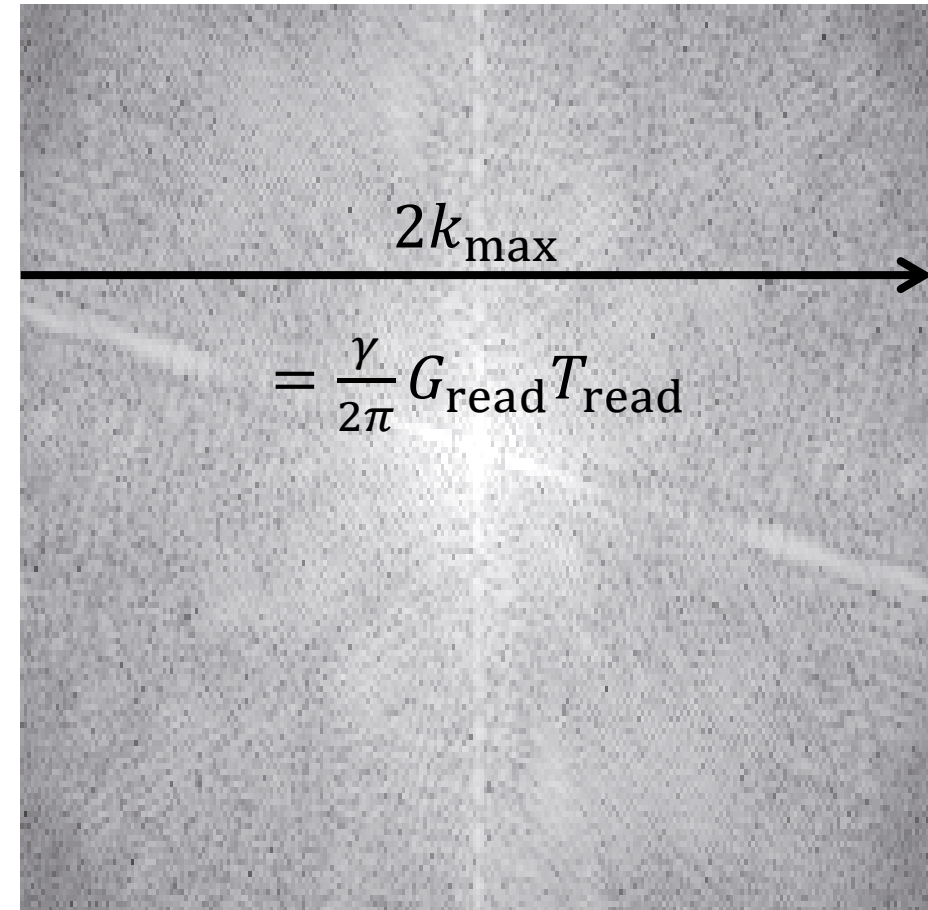
k-space velocity  $v_{k,\text{read}} = \dot{k}_{\text{read}}(t) = \frac{\gamma}{2\pi} G_{\text{read}}$

Alternatively:  $v_{k,\text{read}} = \frac{k_{\text{read}}(T_{\text{read}}) - k_{\text{read}}(0)}{T_{\text{read}}}$

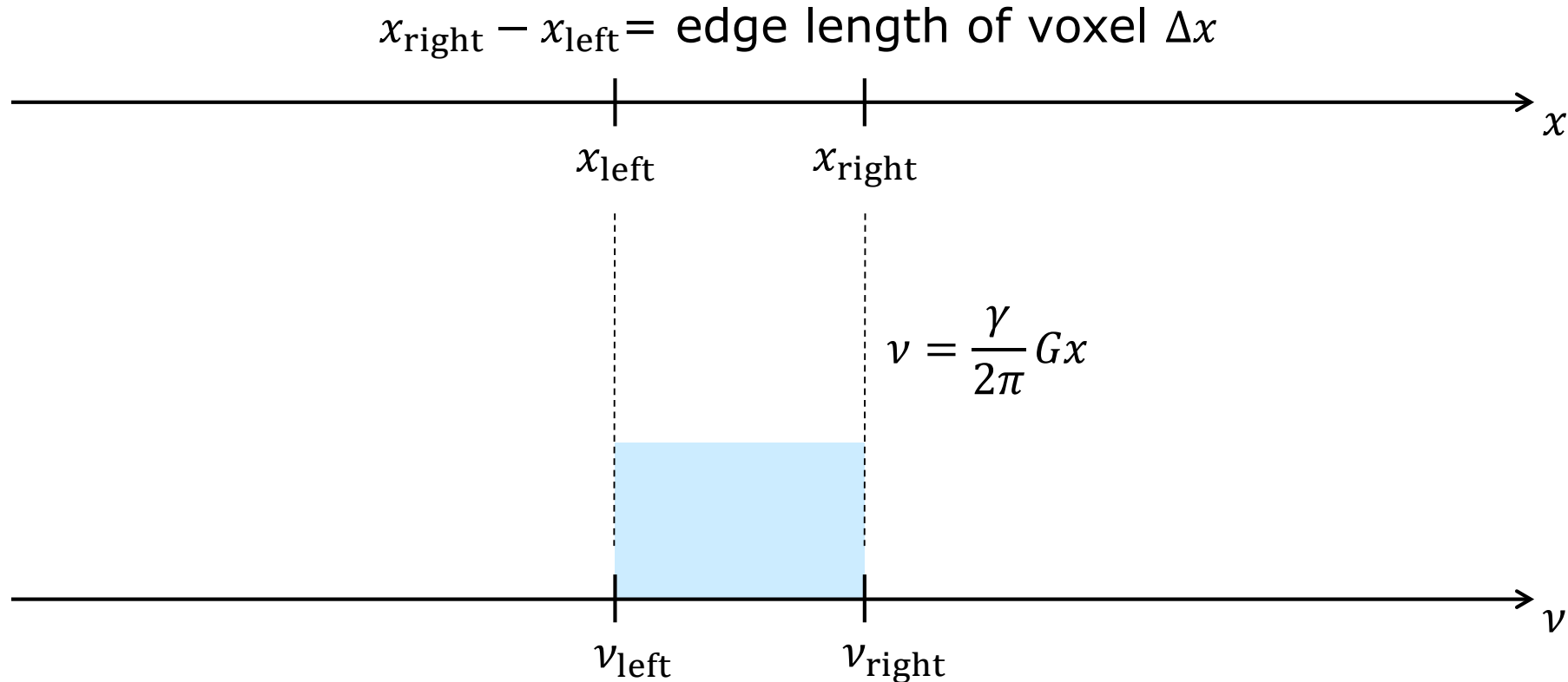
Three  
measures  
of speed  
in k-space

$$= \frac{2k_{\text{max}}}{T_{\text{read}}} = \frac{\gamma}{2\pi} G_{\text{read}}$$

indirect



# Bandwidth



Fourth  
measure  
of speed  
in k-space

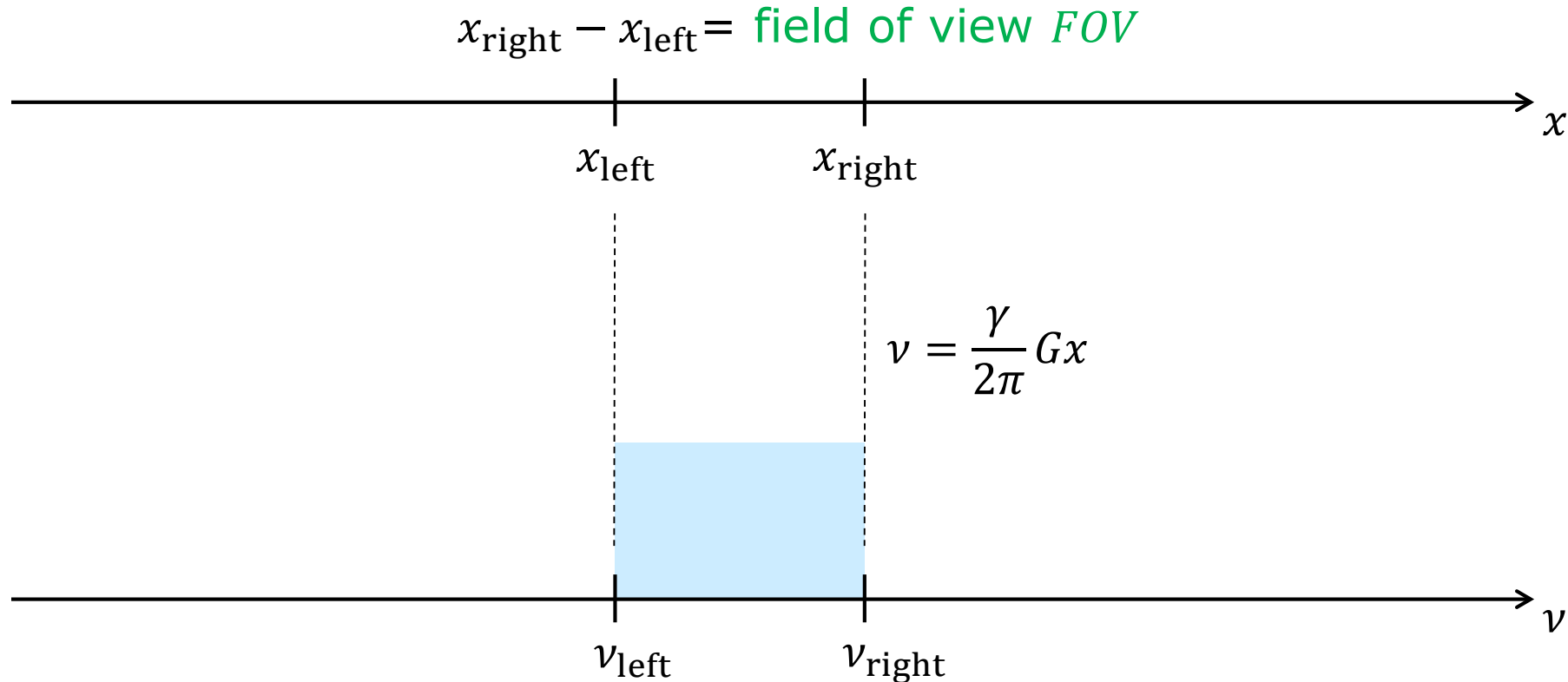
Acquisition bandwidth  $BW = \nu_{\text{right}} - \nu_{\text{left}} = \frac{1}{T_{\text{read}}}$

indirect indirect



# Bandwidth

2nd definition, not used in this course



Fourth  
measure  
of speed  
in k-space

Acquisition bandwidth  $BW = v_{\text{right}} - v_{\text{left}} = \frac{N_{\text{voxel}}}{T_{\text{read}}}$

indirect

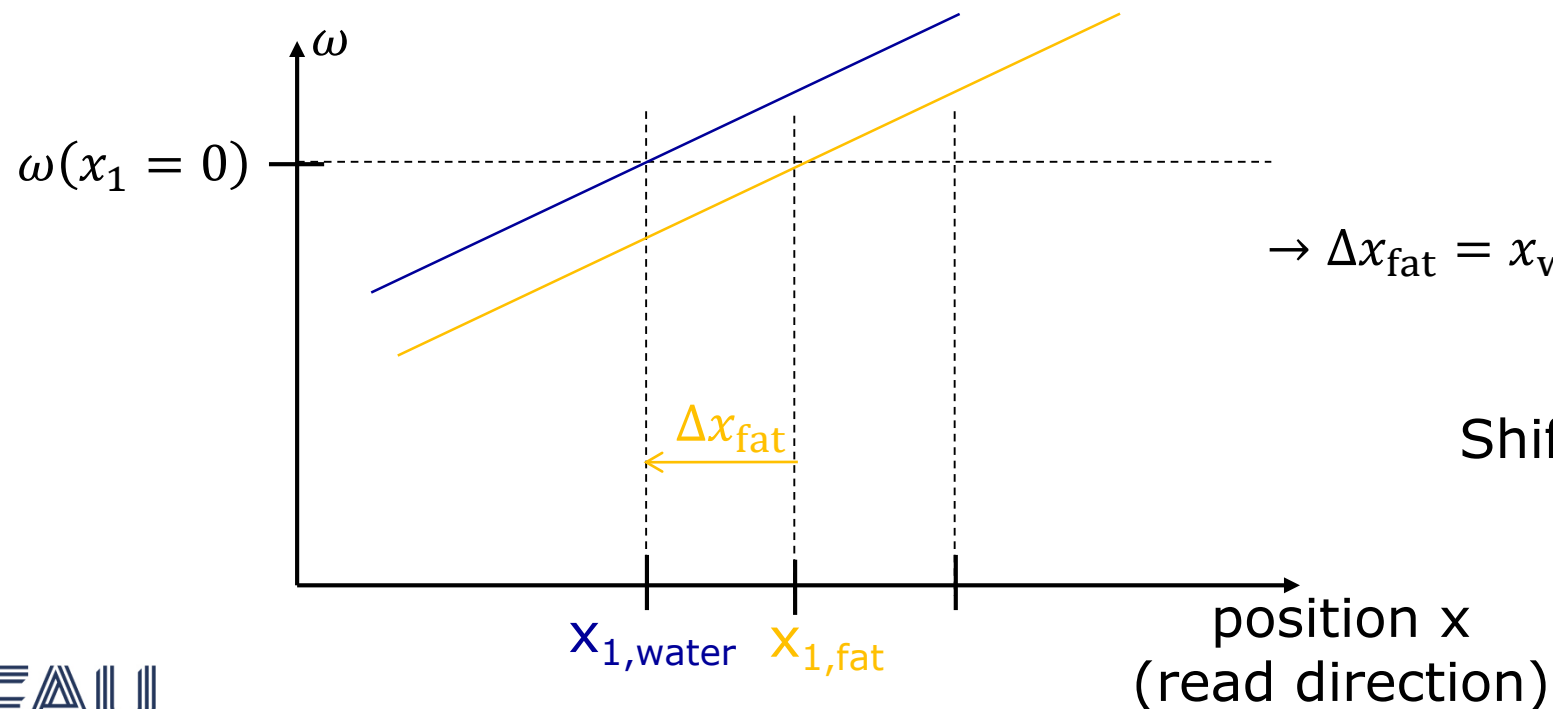
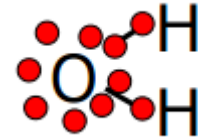
indirect



# Chemical shift

$$\nu_{0, \text{of a certain chemical group}} = \frac{\gamma}{2\pi} B_0 \cdot (1 + \delta)$$

$\delta$  is the chemical shift

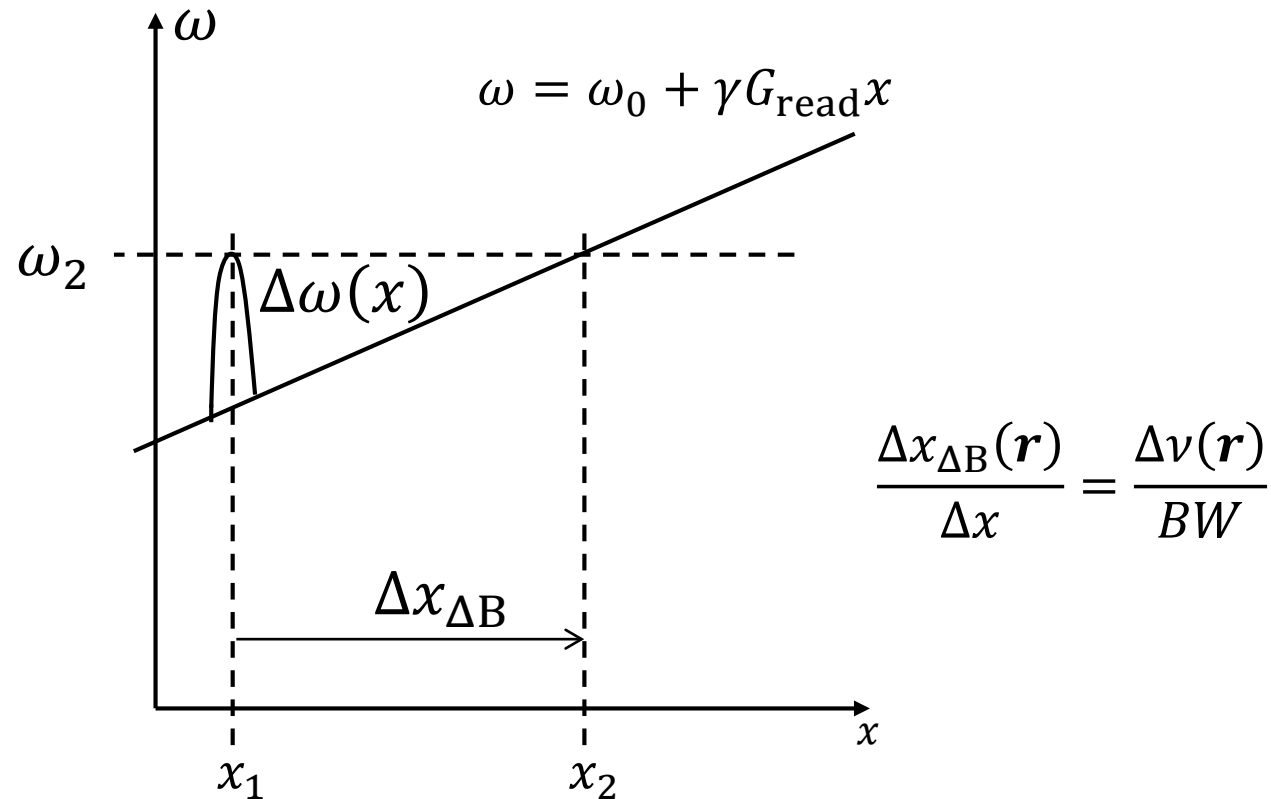


$$\rightarrow \Delta x_{\text{fat}} = x_{\text{water}} - x_{\text{fat}} = \frac{B_0 \cdot (\delta_{\text{fat}} - \delta_{\text{water}})}{G_{\text{read}}}$$

$$\text{Shift in \#voxel} = \frac{\Delta x_{\text{fat}}}{\Delta x} = \frac{\Delta \nu_{\text{fat}}}{BW}$$



# Field inhomogeneity



In the image:  
point  $x_1$  is shifted to  $x_2$





# Summary

## Physical Effect

Chemical shift:

$$\omega \rightarrow \gamma B_0 \cdot (1 + \delta)$$

Field inhomogeneity:

$$\mathbf{B}_0 \rightarrow \mathbf{B}_0 + \Delta \mathbf{B}(\mathbf{r})$$



# Summary

Physical Effect	Effect on Cartesian MRI	$\propto B_0$	$\propto BW^{-1}$	$\propto G_{\text{read}}^{-1}$	$\propto v_k^{-1}$
Chemical shift: $\omega \rightarrow \gamma B_0 \cdot (1 + \delta)$	Shift of fat signal by $\Delta x_{\text{fat}}$	✓	✓	✓	✓
Field inhomogeneity: $B_0 \rightarrow B_0 + \Delta B(\mathbf{r})$	Shift of signal by $\Delta x_{\Delta B}(\mathbf{r})$	✓	✓	✓	✓

$$\text{SNR} \propto T_{\text{read}}^{1/2} \propto BW^{-1/2}$$

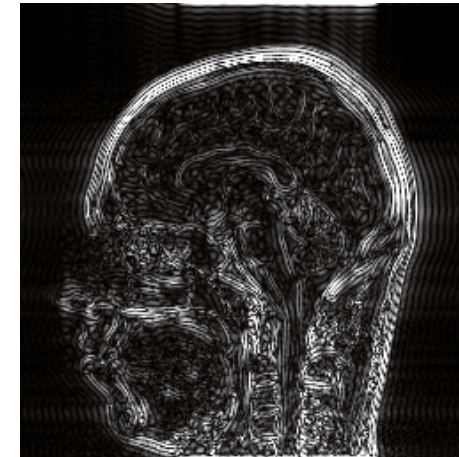
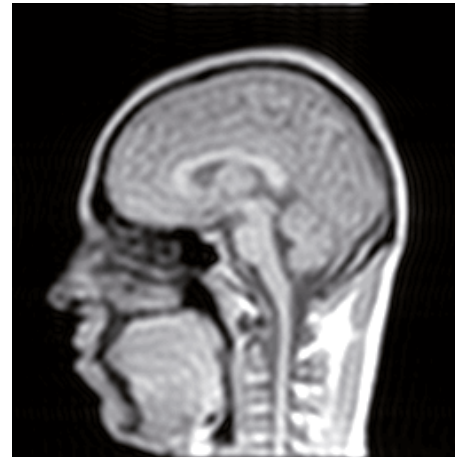
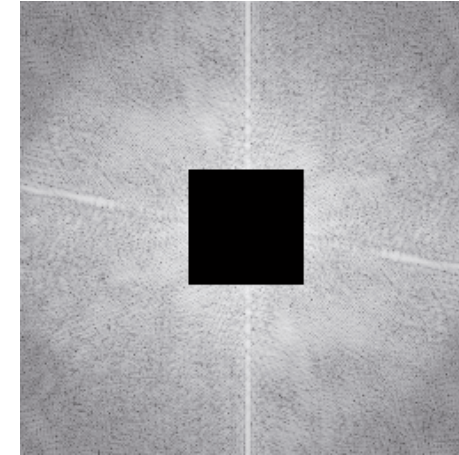
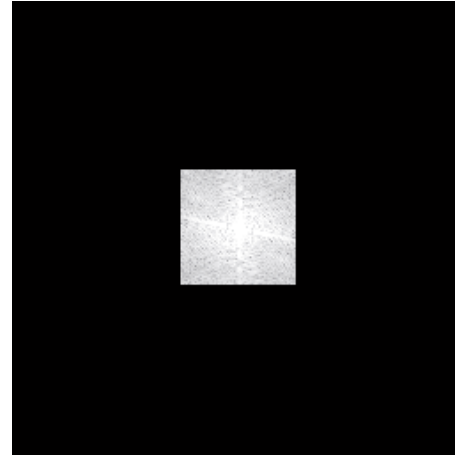
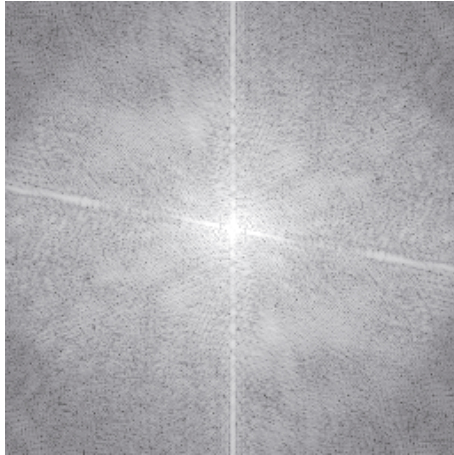
→ Reduction of these artifacts by a factor of 2  
is paid with a factor  $\sqrt{2}$  of SNR



# 1.5. Transversal relaxation

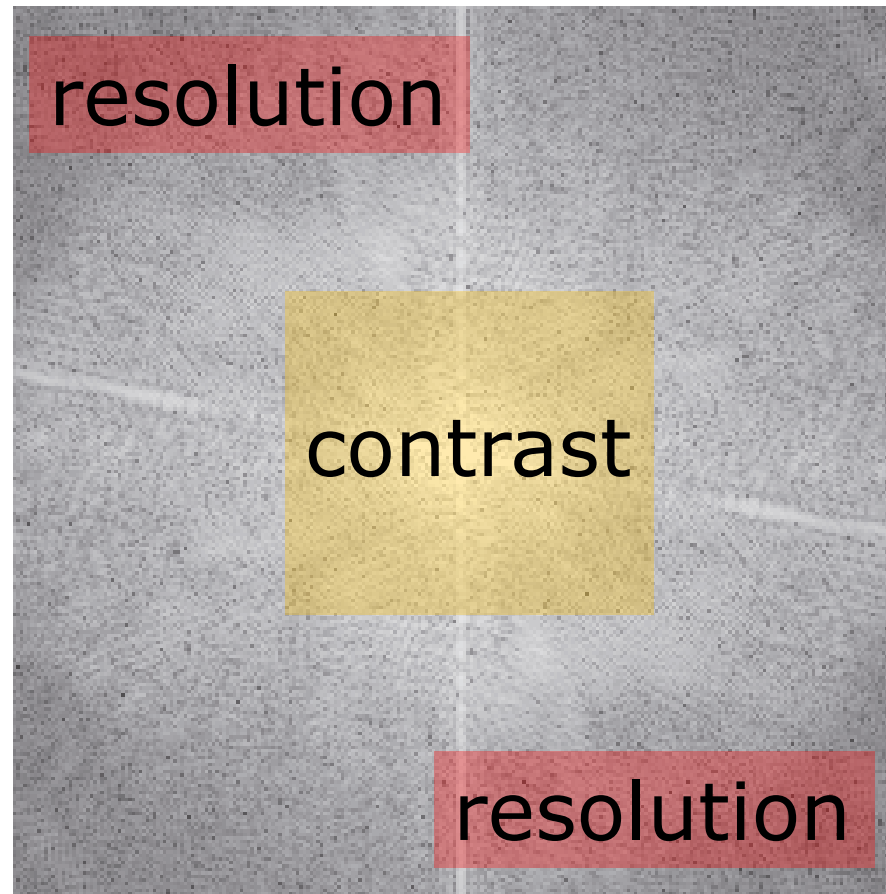


# Reminder: k-Space & image space



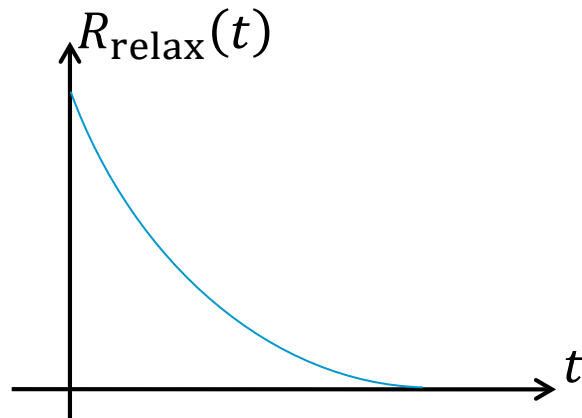
# Reminder:

## k-Space: resolution and contrast



# Transversal relaxation and relation to k-space position

- Due to  $T_2$  relaxation, the transversal magnetization decays as  $M_{\perp}(t) = M_{\perp}(0)e^{-t/T_2} = M_{\perp}(0)R_{\text{relax}}(t)$
- If  $\Delta B(\mathbf{r}) \neq 0 \rightarrow R_{\text{relax}}(t)$  might take a different functional form



Say that k-space is sampled with  $\mathbf{k}(t)$ .

How much time has evolved until a certain k-space position is reached?  
 $\rightarrow$  find  $t(\mathbf{k})$

The one can define  
 $\tilde{R}_{\text{relax},\mathbf{k}}(\mathbf{k}) := R_{\text{relax}}(t(\mathbf{k}))$



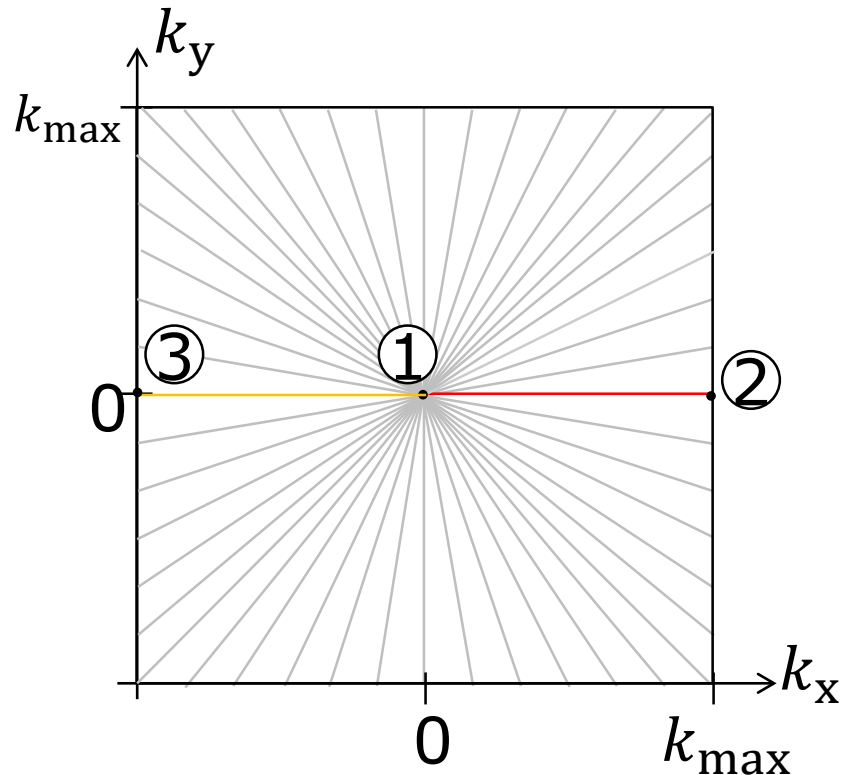
# T2 blurring

depends on k-space path  $\mathbf{k}(t)$

- In general:  $\tilde{S}_{\text{MRI, with T}_2}(\mathbf{k}) = \tilde{S}_{\text{MRI, without T}_2}(\mathbf{k}) \tilde{R}_{\text{relax,k}}(\mathbf{k})$
- Associated signal  $S_{\text{MRI, with T}_2}(\mathbf{r}) = \mathcal{F}^{-1}\{\tilde{S}_{\text{MRI, without T}_2}(\mathbf{k}) \tilde{R}_{\text{relax,k}}(\mathbf{k})\}$
- Convolution theorem:  $\mathcal{F}^{-1}\{\tilde{f}(\mathbf{k}) \cdot \tilde{g}(\mathbf{k})\} = f(\mathbf{r}) * g(\mathbf{r})$
- $S_{\text{MRI, with T}_2}(\mathbf{r}) = S_{\text{MRI, without T}_2}(\mathbf{k}) * \mathcal{F}^{-1}\{\tilde{R}_{\text{relax,k}}(\mathbf{k})\}$
- I.e. a „T<sub>2</sub> blurring“ results
- T<sub>2</sub> blurring depends on position  $\mathbf{r}$  if T<sub>2</sub> depends  $\mathbf{r}$
- The larger  $v_k \propto G_{\text{read}} \propto \text{BW}$  and the larger T<sub>2</sub>, the smaller is the blurring



# Example: Radial sampling, exponential signal decay, 1D case



1st excitation:

From ① to ② :  $k(t) = \frac{1}{2\pi} \gamma G_{\text{read}} t$

2nd excitation:

From ① to ③ :  $k(t) = \frac{1}{2\pi} \gamma \cdot (-G_{\text{read}}) t$

$$\rightarrow t(k) = \frac{2\pi|k|}{\gamma G_{\text{read}}}$$

$$R_{\text{relax}}(t) = \exp(-t(k)/T_2)$$

$$\tilde{R}_{\text{relax},k}(k) := \exp\left(-\frac{2\pi|k|}{\gamma G_{\text{read}} T_2}\right)$$

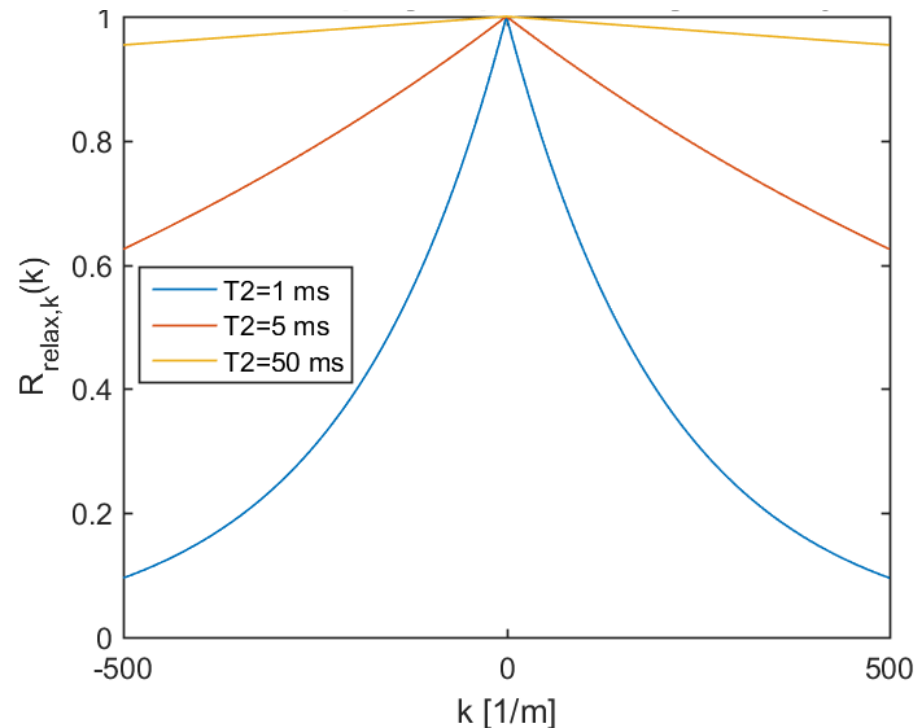
$$\mathcal{F}^{-1}\{\tilde{R}_{\text{relax},k}(k)\} = \frac{1}{\pi} \frac{\gamma G_{\text{read}} T_2}{1 + \gamma^2 G_{\text{read}}^2 T_2^2 x^2}$$



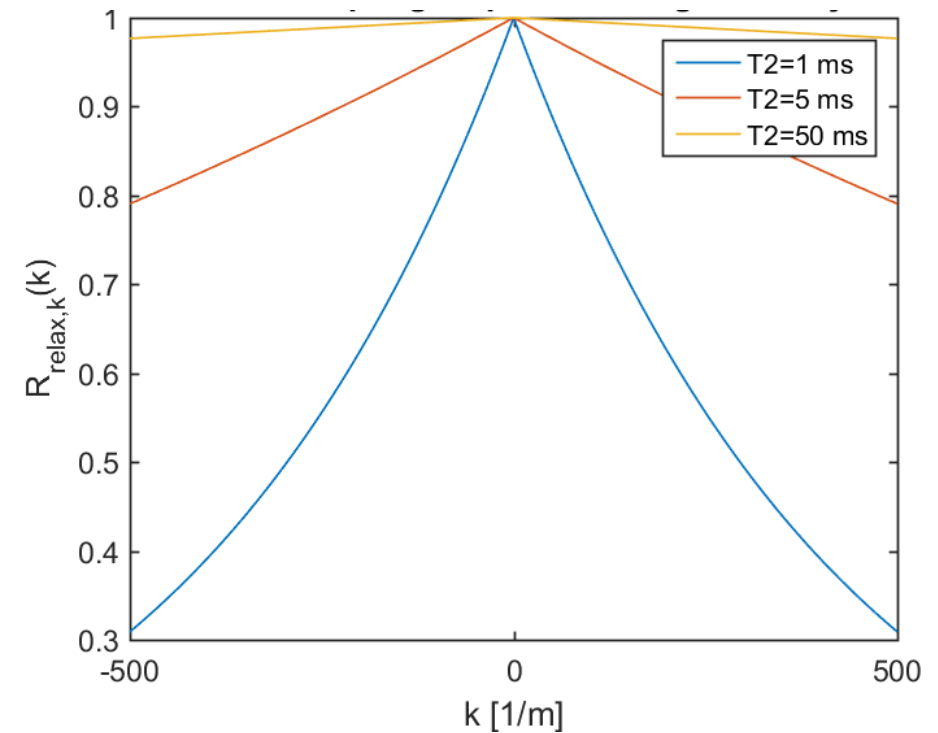


# Example: Radial sampling, exponential signal decay, 1D case, 201 voxels

$G_{\text{read}} = 5 \text{ mT/m}$ ,  $T_{\text{read}} \approx 2.3 \text{ ms}$

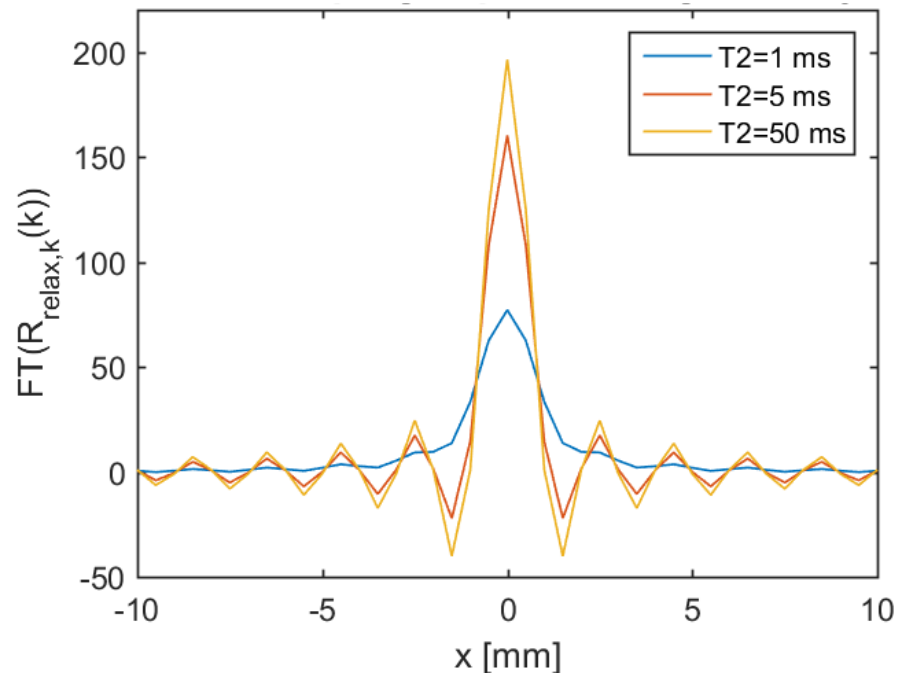


$G_{\text{read}} = 10 \text{ mT/m}$ ,  $T_{\text{read}} \approx 1.2 \text{ ms}$

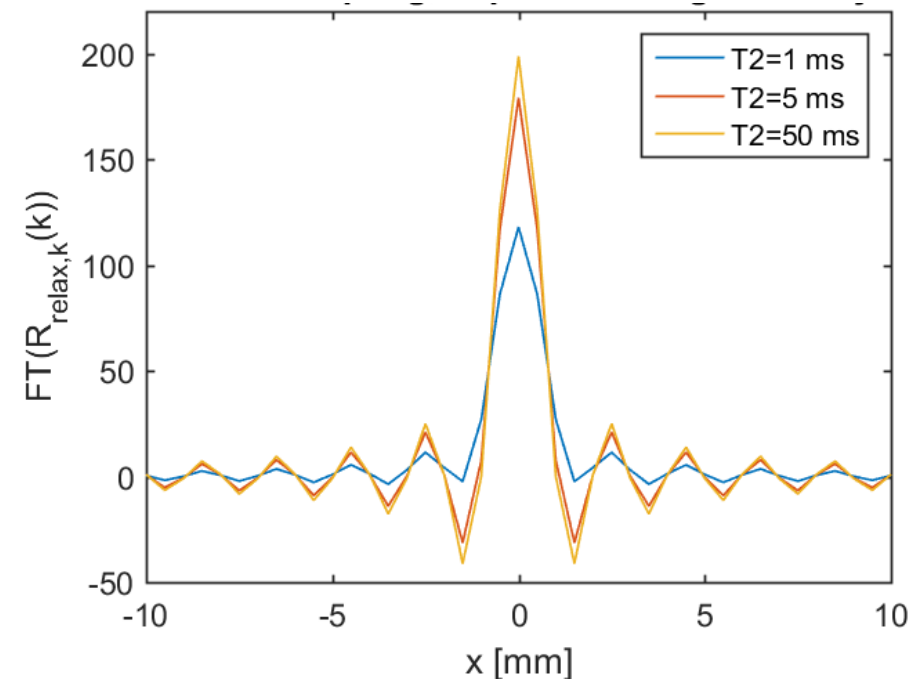


# Example: Radial sampling, exponential signal decay, 1D case, 201 voxels

$G_{\text{read}} = 5 \text{ mT/m}$ ,  $T_{\text{read}} \approx 2.3 \text{ ms}$



$G_{\text{read}} = 10 \text{ mT/m}$ ,  $T_{\text{read}} \approx 1.2 \text{ ms}$

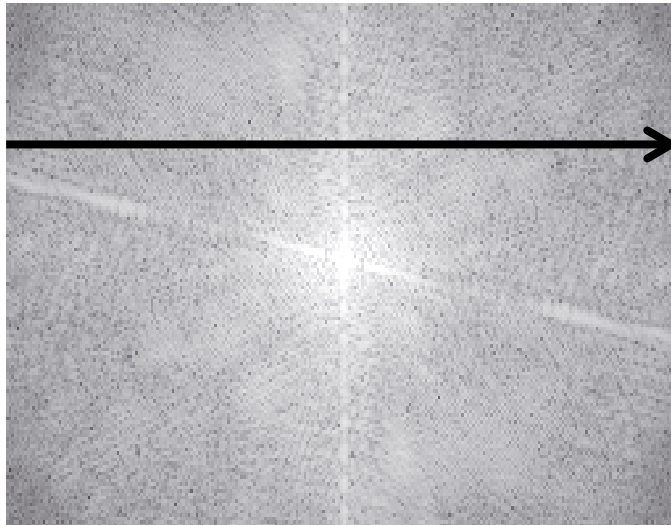


# Summary



# Summary

We discussed three effects  
of finite k-space velocity



# Summary

## Physical Effect

Chemical shift:

$$\omega \rightarrow \gamma B_0 \cdot (1 + \delta)$$

Field inhomogeneity:

$$\mathbf{B}_0 \rightarrow \mathbf{B}_0 + \Delta \mathbf{B}(\mathbf{r})$$

T<sub>2</sub> relaxation



# Summary

Physical Effect	Effect on Cartesian MRI	$\propto B_0$	$\propto BW^{-1}$	$\propto G_{\text{read}}^{-1}$	$\propto v_k^{-1}$
Chemical shift: $\omega \rightarrow \gamma B_0 \cdot (1 + \delta)$	Shift of fat signal by $\Delta x_{\text{fat}}$	✓	✓	✓	✓
Field inhomogeneity: $B_0 \rightarrow B_0 + \Delta B(\mathbf{r})$	Shift of signal by $\Delta x_{\Delta B}(\mathbf{r})$	✓	✓	✓	✓
T <sub>2</sub> relaxation	T <sub>2</sub> blurring		✓	✓	✓

$$\text{SNR} \propto T_{\text{read}}^{1/2} \propto BW^{-1/2}$$

→ Reduction of these artifacts by a factor of 2  
is paid with a factor  $\sqrt{2}$  of SNR



# Echo planar imaging (EPI): The principle



# Which vehicle would like to drive?



Porsche Diesel  
 $v_{\max} = 27.9 \text{ km/h}$



Porsche 911  
 $v_{\max} > 300 \text{ km/h}$





# Best vehicle depends on the intended purpose



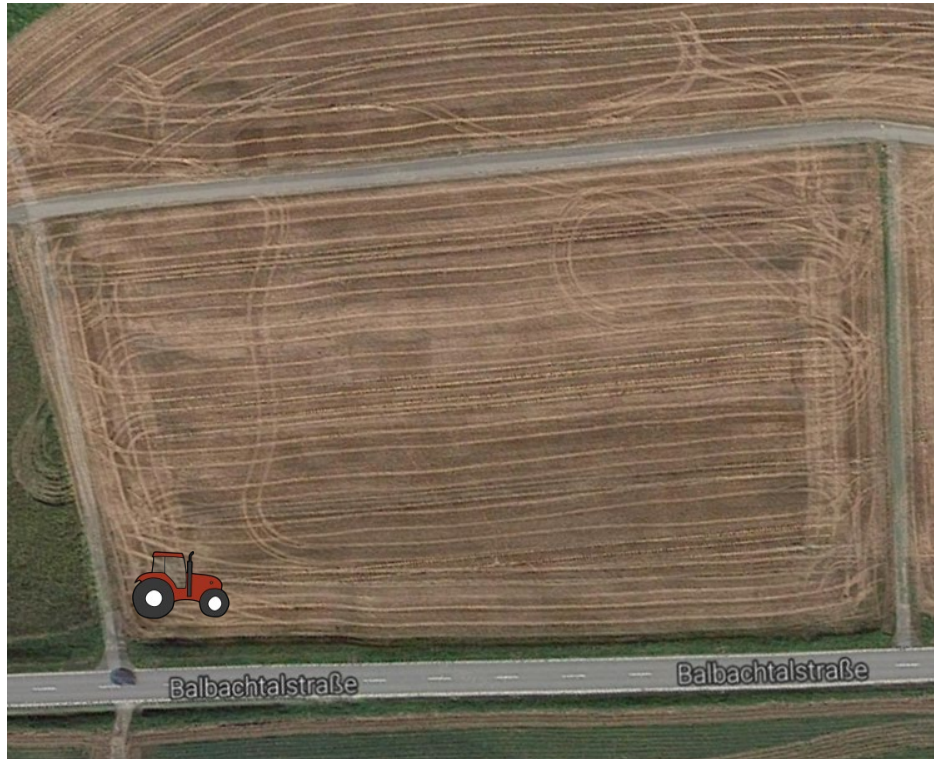
<https://de.wiktionary.org/wiki/Acker>



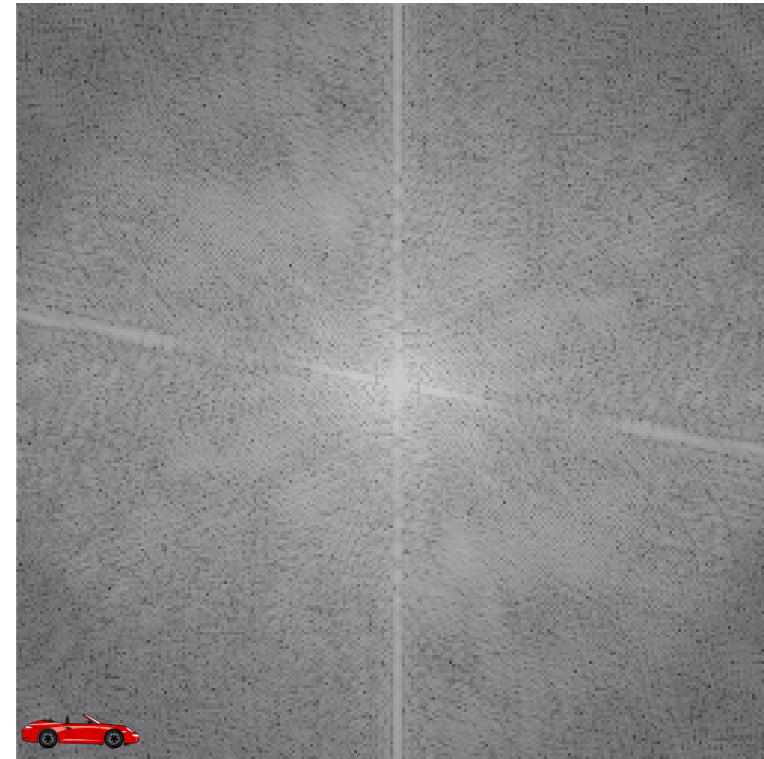
<https://de.wikipedia.org/wiki/Nordschleife>



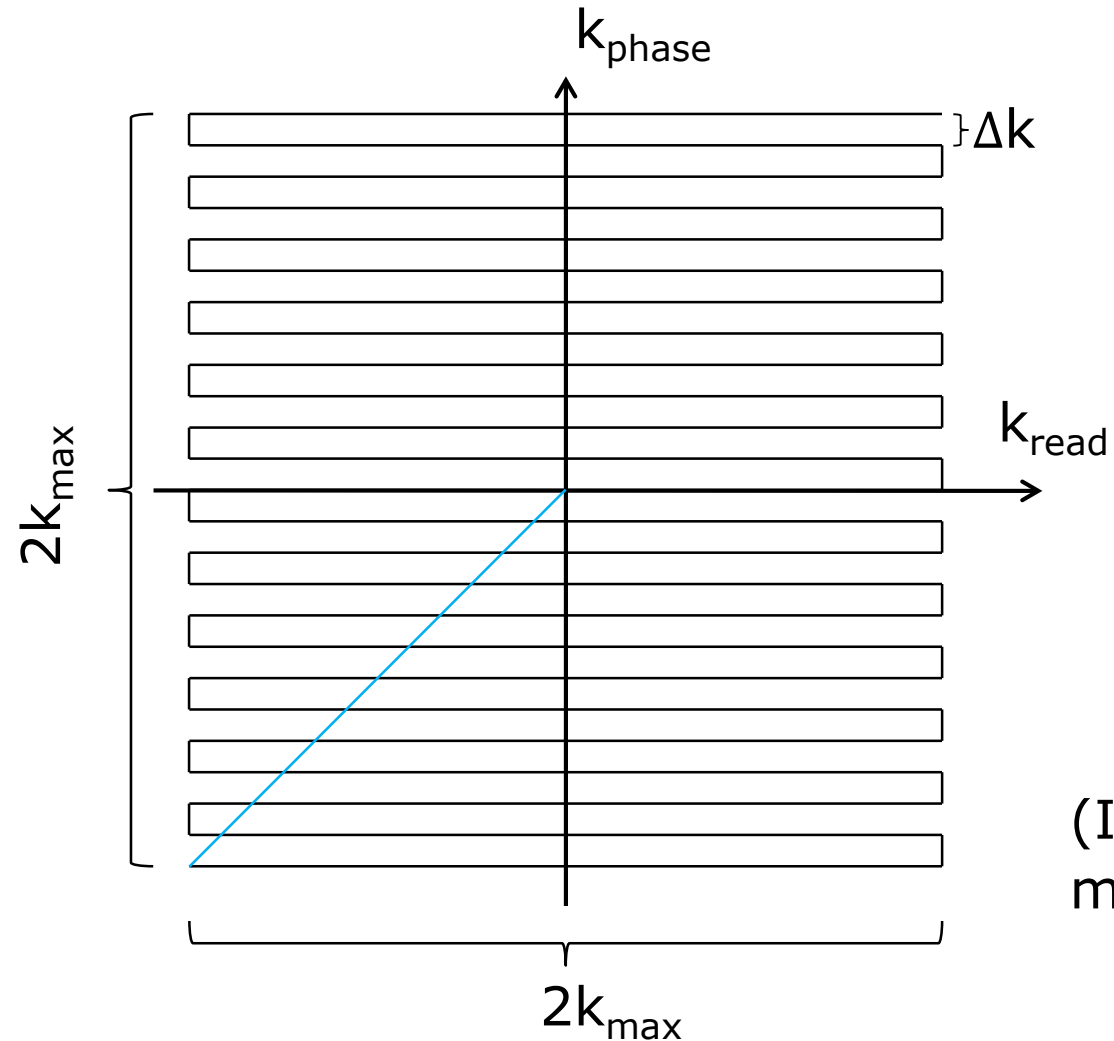
# Definition EPI



EPI: A snail through k-space



# EPI trajectory

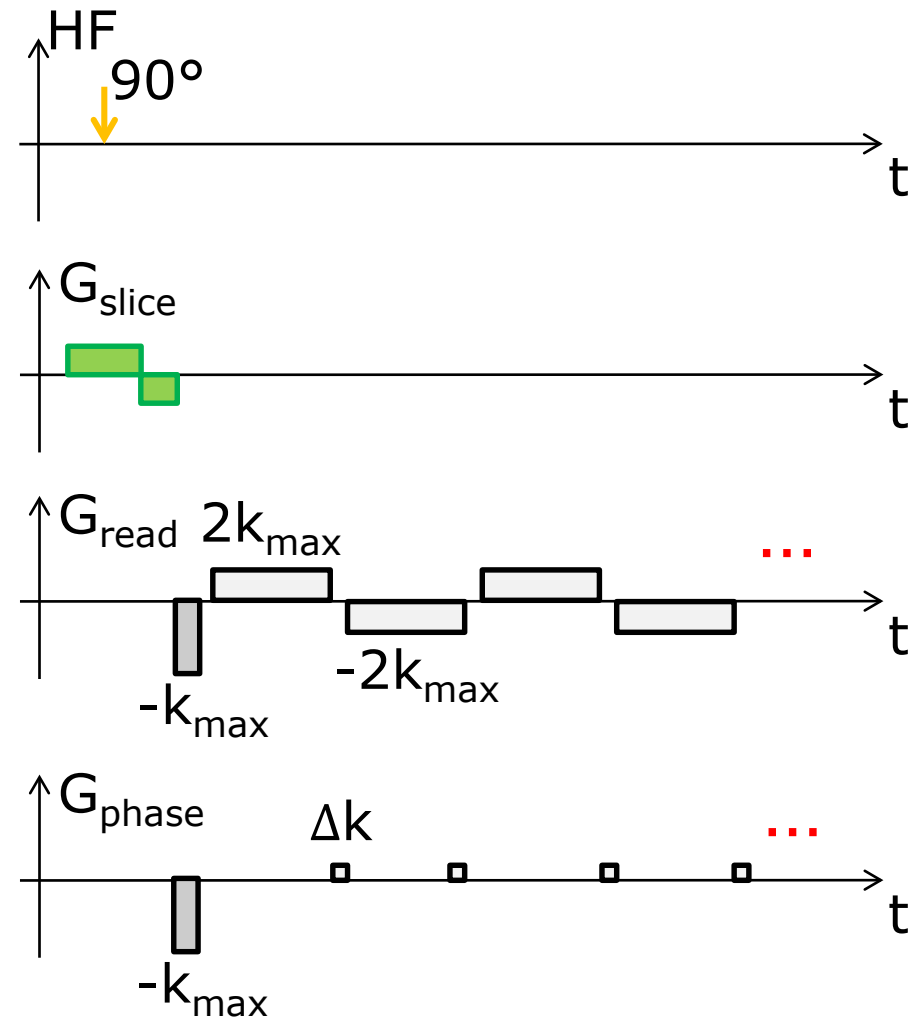
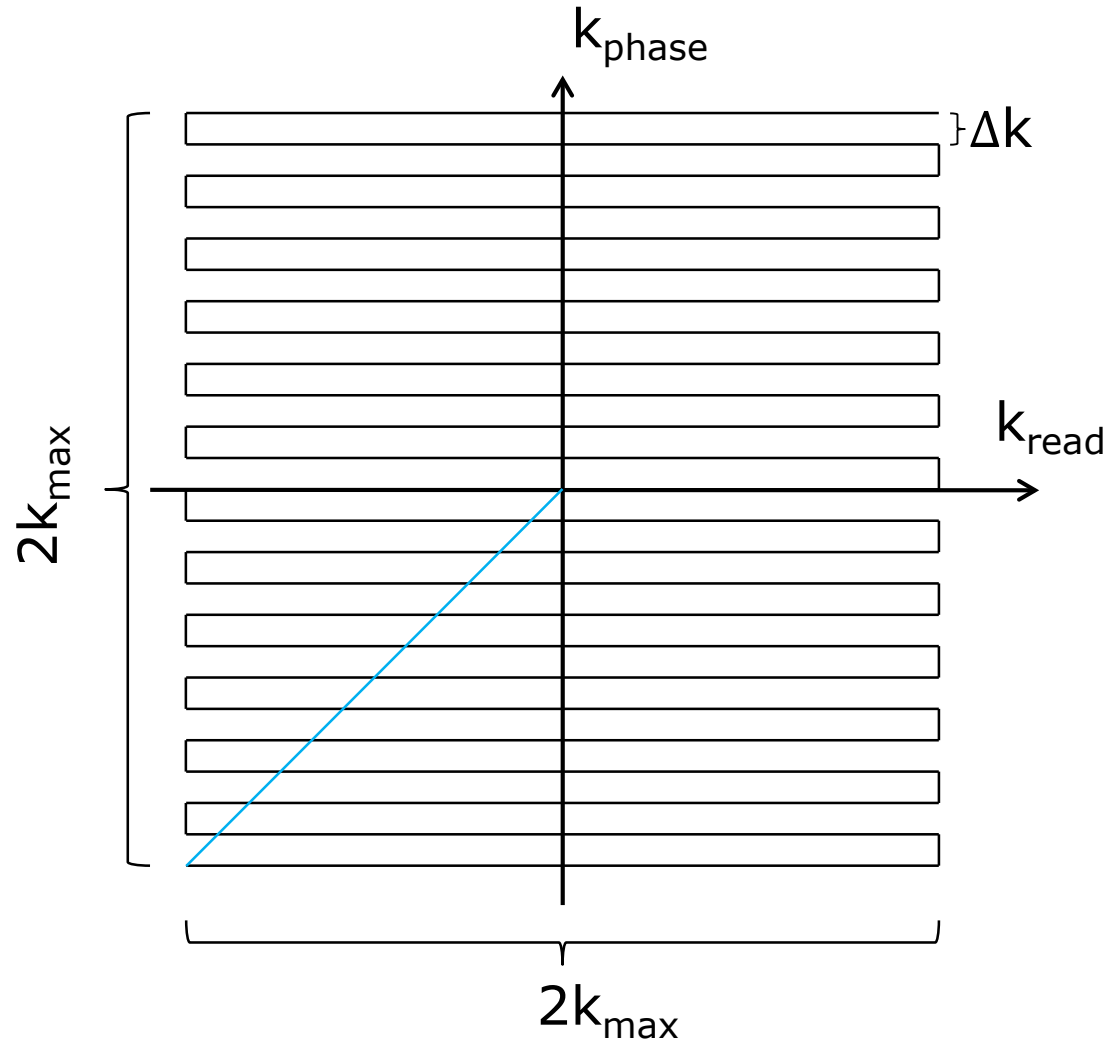


(In general,  $k_{\text{max,phase}}$  may be  $\neq k_{\text{max,read}}$ )



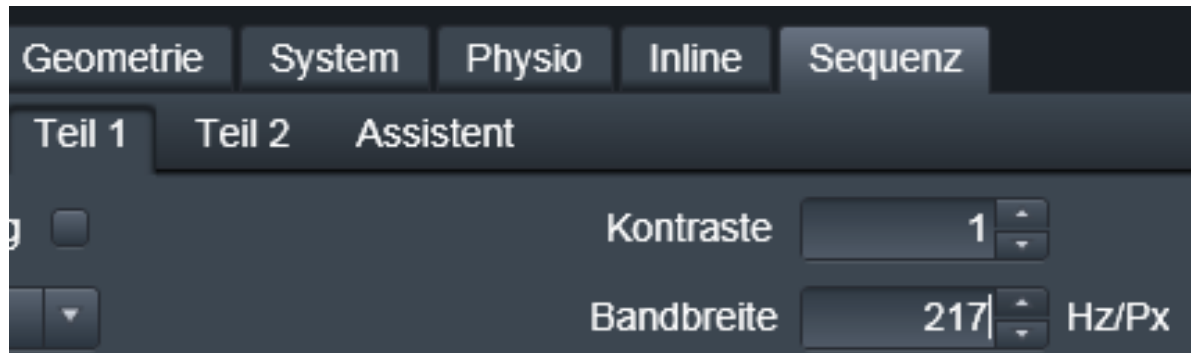
# EPI timing table

$$\mathbf{k}(t) = \frac{\gamma}{2\pi} \int_0^t \mathbf{G}(t') dt' \cdot \mathbf{r}$$

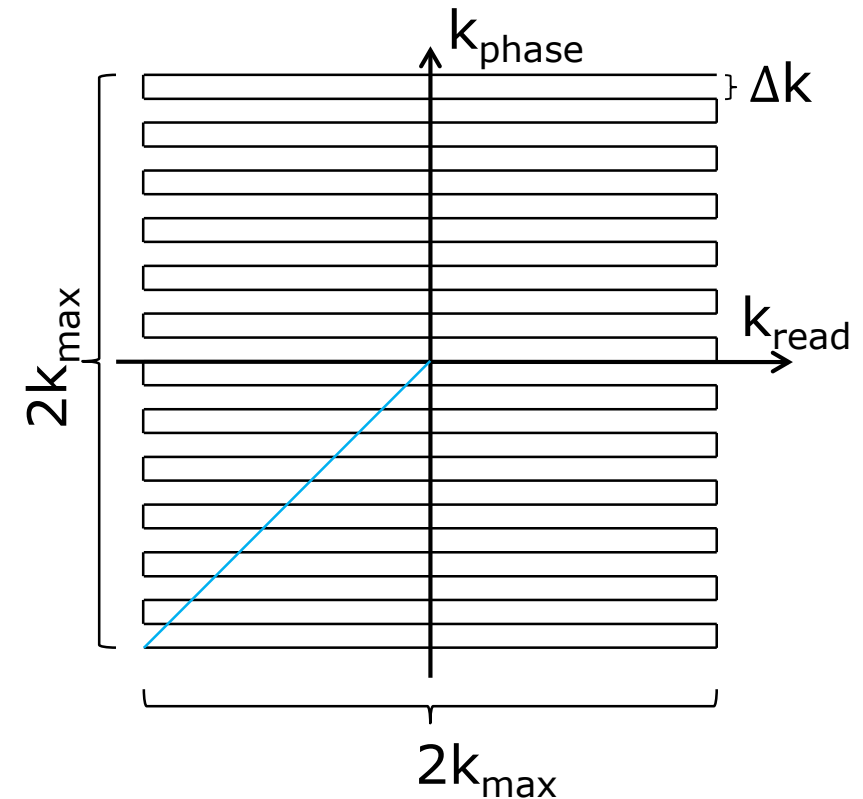


# Bandwidth in EPI

Bandwidth is defined as for a single line sequence



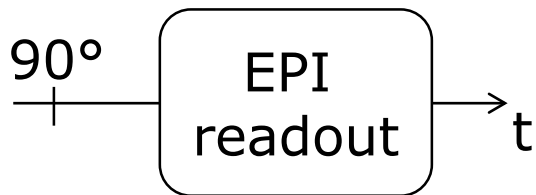
$$BW = \frac{1}{T_{\text{read}}}$$



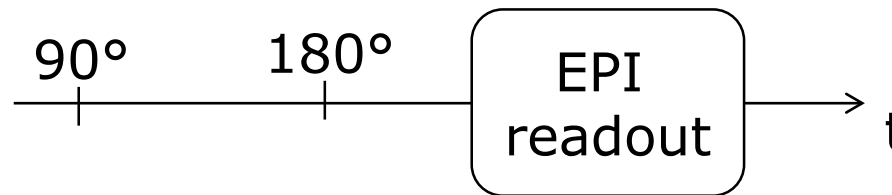
# Properties of EPI

- Echo time TE is defined as the time when the k-space center is reached
- Excitation angle  $< 90^\circ$  possible
- Typical acquisition time for one image: 0.1 s  $\rightarrow$  fast technique
- It is a “single-shot technique”
- Can be run as spin echo or gradient echo sequence

gradient echo:



spin echo:



# Advantages and Disadvantages of EPI

- Advantages:
  - Very fast
  - SNR-efficient
  - Very good for some special applications (diffusion imaging, fMRI, ...)
- Disadvantages:
  - Long echo train makes EPI prone to artifacts
  - not well-suited for high-resolution imaging



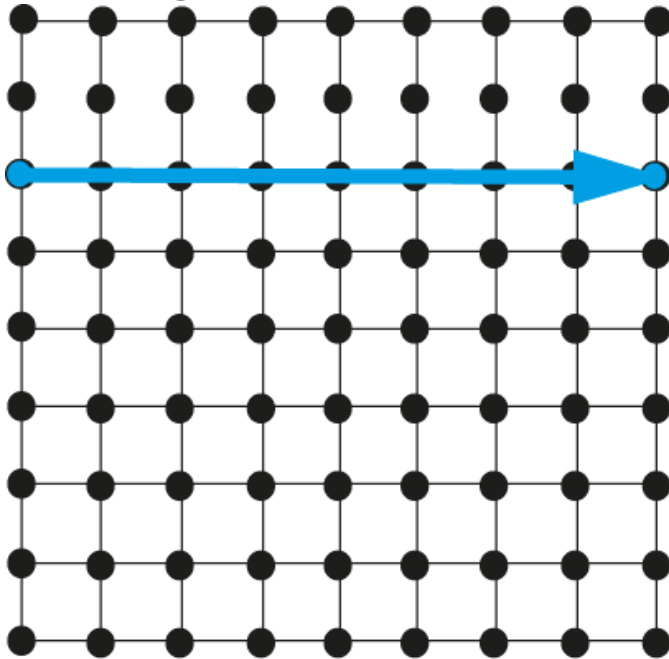
# EPI and chemical shift





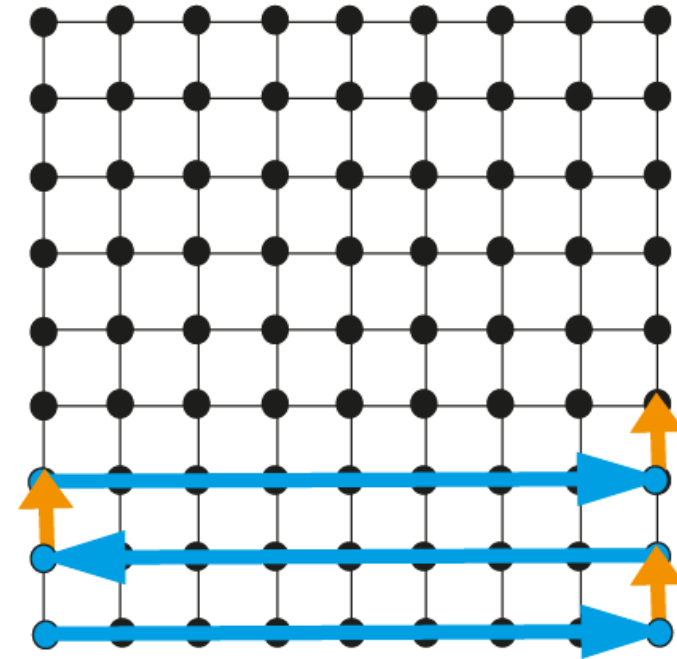
# Fat - water shift in EPI

single line readout



$$\Delta x_{\text{fat}} = \frac{\gamma B_0 \cdot (\sigma_{\text{fat}} - \sigma_{\text{water}})}{2\pi v_{k,\text{read}}} e_{\text{read}}$$

EPI

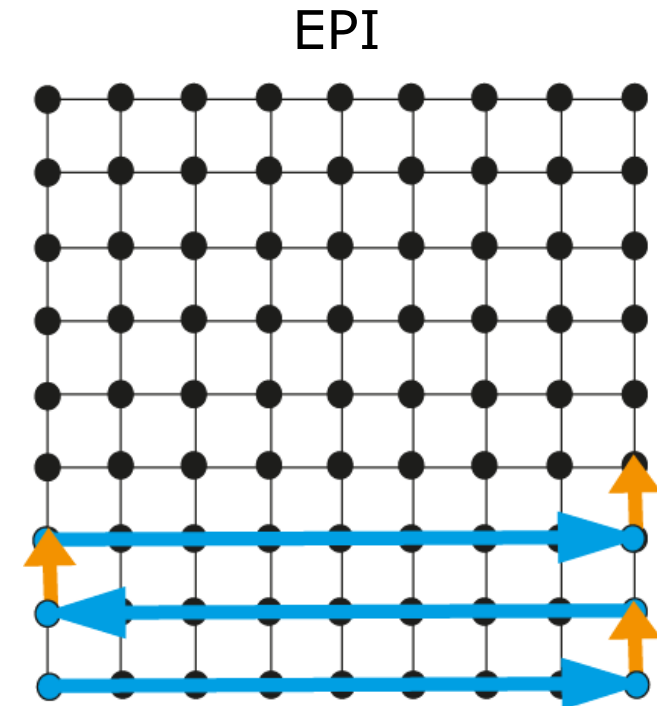


$$\Delta x_{\text{fat}} = ?$$



# Fat - water shift in EPI

- read direction:
  - time needed for one line is  $T_{\text{read}}$
  - travelled distance is  $2k_{\text{max,read}}$
  - the k-space velocity is  $v_{k,\text{read}} = \frac{2k_{\text{max,read}}}{T_{\text{read}}}$
- phase direction:
  - $N$  lines must be acquired
  - needed time is  $N \cdot T_{\text{read}}$
  - travelled distance is  $2k_{\text{max,phase}}$
  - the k-space velocity is  $v_{k,\text{phase}} = \frac{2k_{\text{max,phase}}}{N \cdot T_{\text{read}}}$
- $v_{k,\text{phase}} = v_{k,\text{read}}/N$ 
  - The chemical shift artifact is  $N$  times larger for EPI



$$\Delta x_{\text{fat}} = ?$$

$$\Delta x_{\text{fat}} \propto v_k^{-1}$$

# Fat - water shift in EPI

$$\frac{\Delta x_{\text{fat}}}{\Delta x} = \frac{\Delta v_{\text{fat}}}{BW}$$

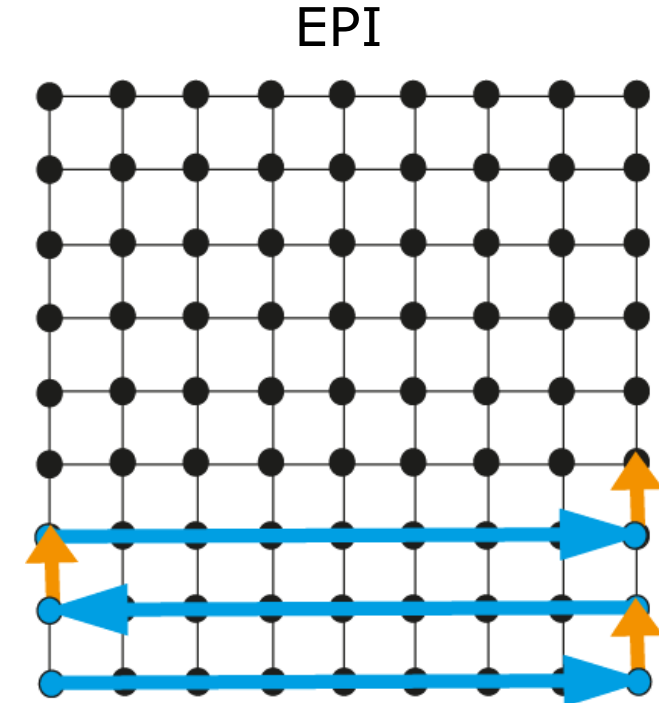
- Single line encoding:

$$\Delta \mathbf{x}_{\text{fat},1\text{line}} = \frac{\Delta x \cdot \Delta v_{\text{fat}}}{BW} \mathbf{e}_{\text{read}}$$

- EPI: just adapt this formula

$$\begin{aligned}\Delta \mathbf{x}_{\text{fat,EPI}} &= \frac{N \cdot \Delta x \cdot \Delta \nu_{\text{fat}}}{BW} \mathbf{e}_{\text{phase}} \\ &= \frac{FOV_{\text{phase}} \cdot \Delta \nu_{\text{fat}}}{BW} \mathbf{e}_{\text{phase}}\end{aligned}$$

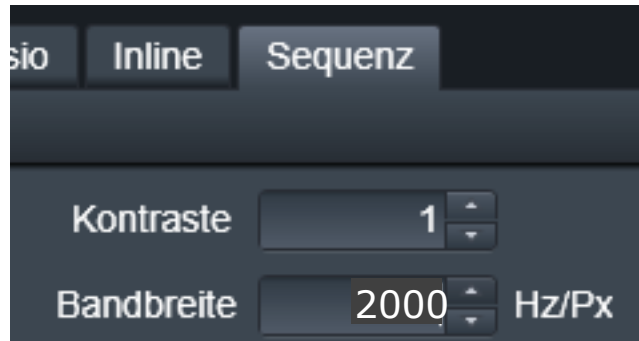
- The shift in read direction is much smaller and somewhat more involved because of travelling back and forth. We neglect it.



# Options to minimize $\Delta x_{\text{fat}}$ in EPI

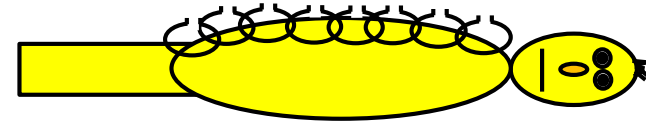
$$\Delta x_{\text{fat,EPI}} = \frac{FOV_{\text{phase}} \cdot \Delta \nu_{\text{fat}}}{BW} \mathbf{e}_{\text{phase}}$$

**increase the BW**

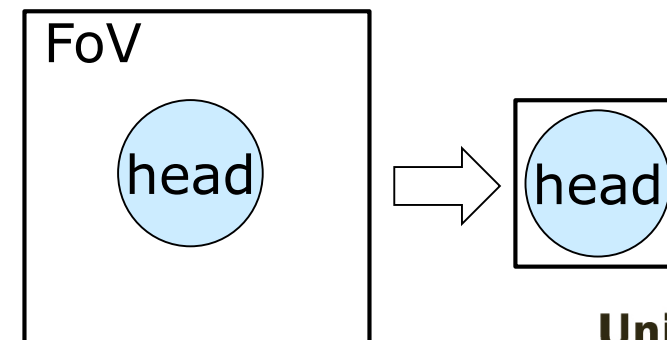
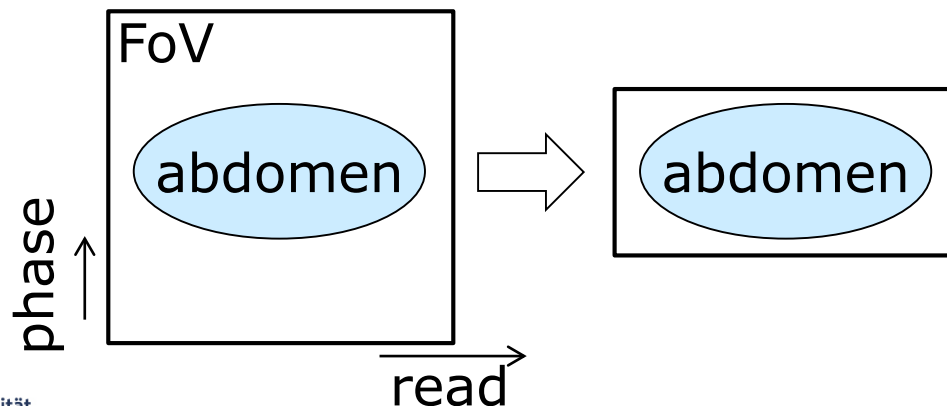


Typical BW  $\approx 2000$  Hz/Px

**use parallel imaging**  
(discussed later in the course)



**reduce the field of view along phase direction**



# No free lunch

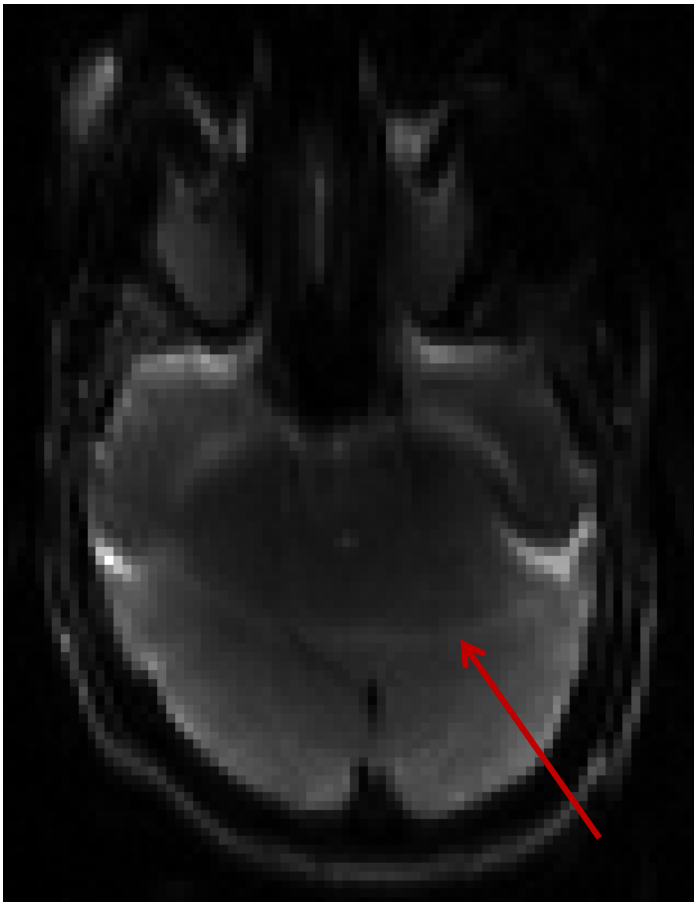
$$\Delta x_{\text{fat,EPI}} = \frac{FOV_{\text{phase}} \cdot \Delta \nu_{\text{fat}}}{BW} \mathbf{e}_{\text{phase}}$$

- $\Delta x_{\text{fat}} \propto BW^{-1} \propto T_{\text{data acquisition}}$
- $\Delta x_{\text{fat}} \propto FOV_{\text{phase}} \propto T_{\text{data acquisition}}$
- $\Delta x_{\text{fat}} \propto (\text{parallel imaging acceleration factor})^{-1} \propto T_{\text{data acquisition}}$
- All these factors have in common: they reduce the time spend on acquiring data, i.e.  $T_{\text{data acquisition}}$
- The price one has to pay:  
signal-to-noise ratio  $\text{SNR} \propto \sqrt{T_{\text{data acquisition}}}$

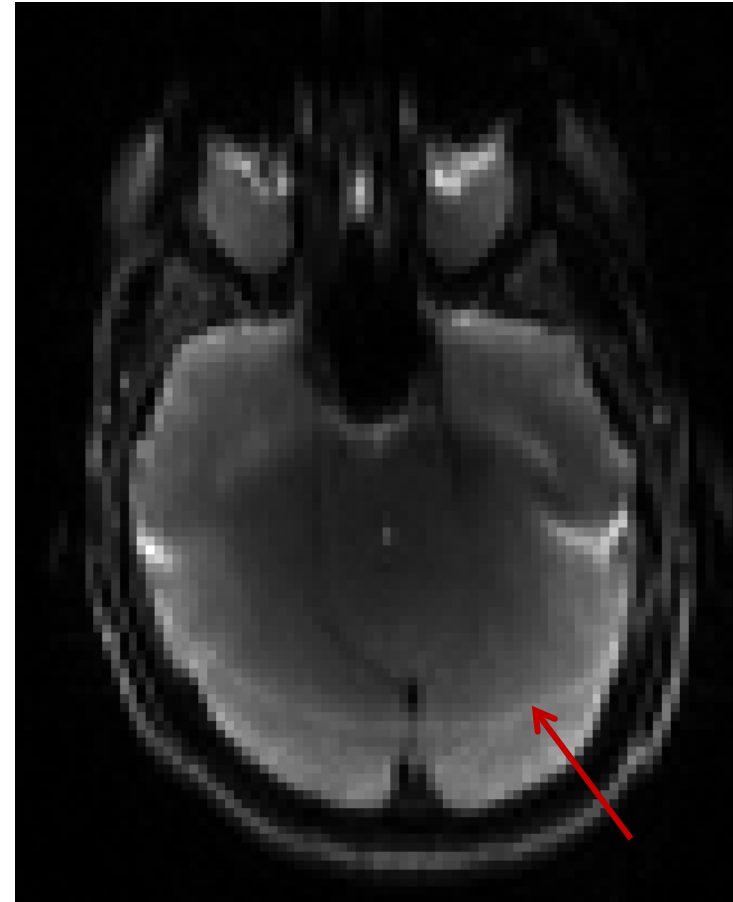


# Fat-water shift in the brain

BW = 1000 Hz/Px



BW = 2000 Hz/Px  
(only half the shift)

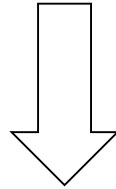


# EPI and magnetic field inhomogeneities



$\Delta x_{\Delta B}$  formulas for EPI  
(just replace  $B_0 \cdot (\sigma_{\text{fat}} - \sigma_{\text{water}})$  with  $\Delta B_z(\mathbf{r})$ )

$$\Delta \mathbf{x}_{\text{fat,EPI}} = \frac{\gamma B_0 \cdot (\sigma_{\text{fat}} - \sigma_{\text{water}}) \cdot \text{FoV}_{\text{phase}}}{2\pi BW} \mathbf{e}_{\text{phase}}$$

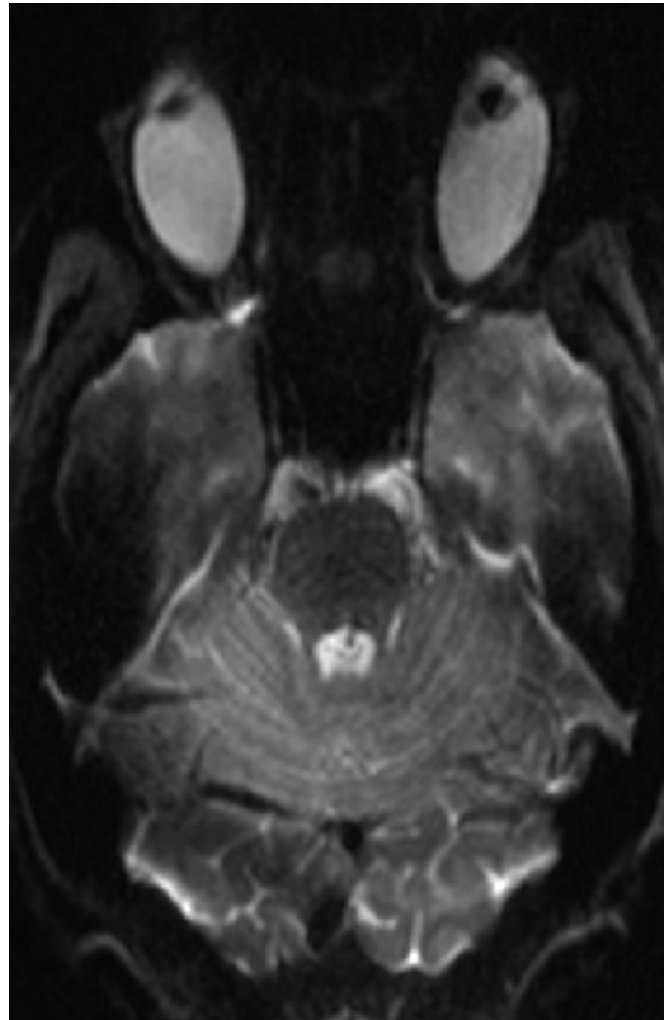


$$\Delta \mathbf{x}_{\Delta B,\text{EPI}} = \frac{\gamma \Delta B_z(\mathbf{r}) \cdot \text{FoV}_{\text{phase}}}{2\pi BW} \mathbf{e}_{\text{phase}}$$





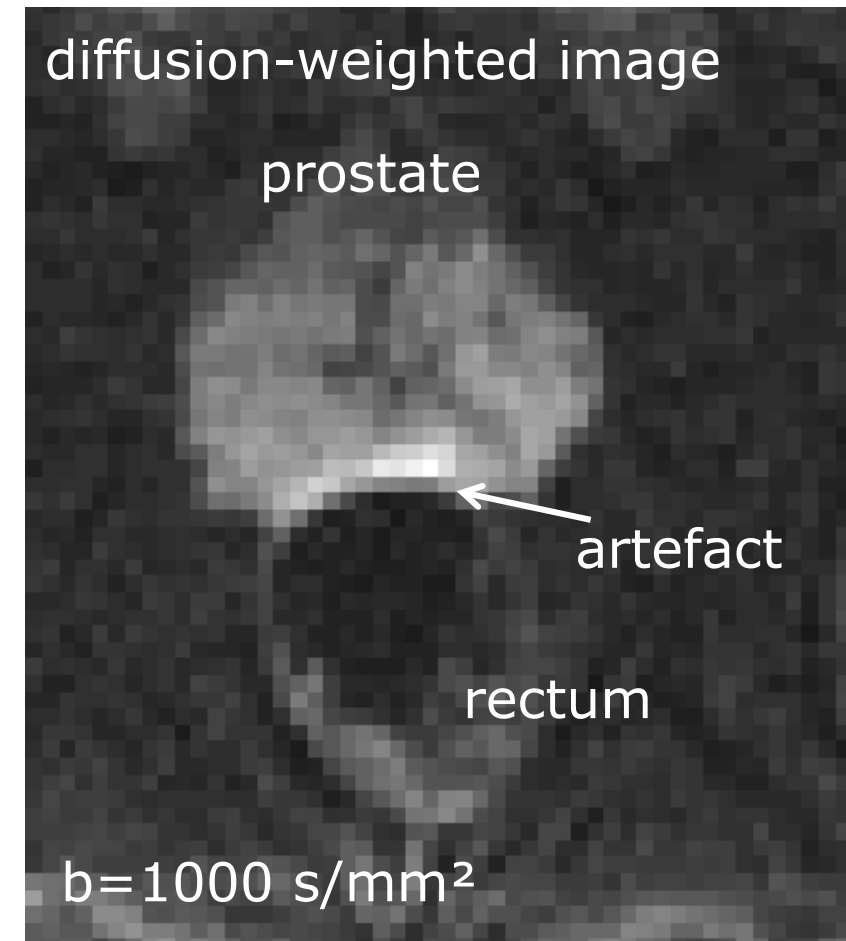
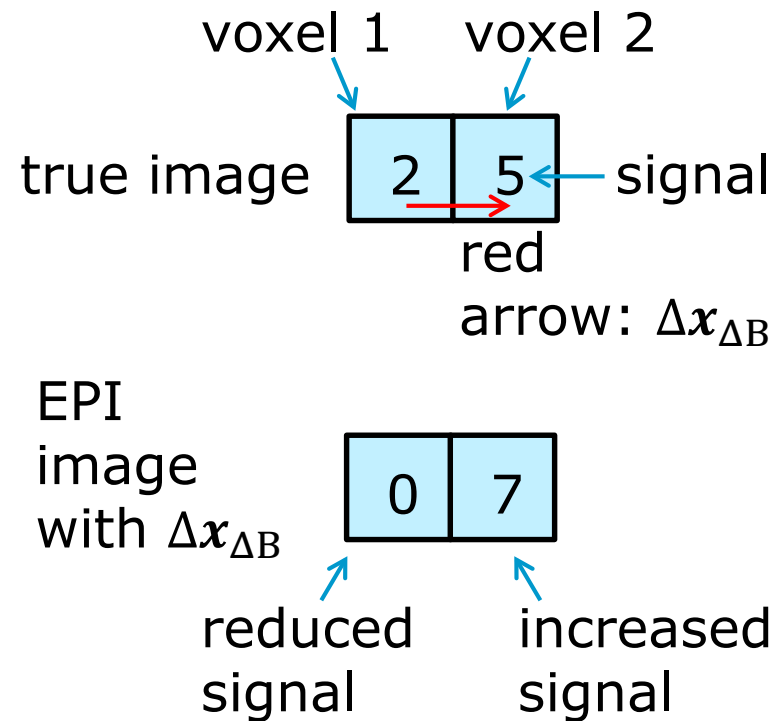
# Effect 1: image shift



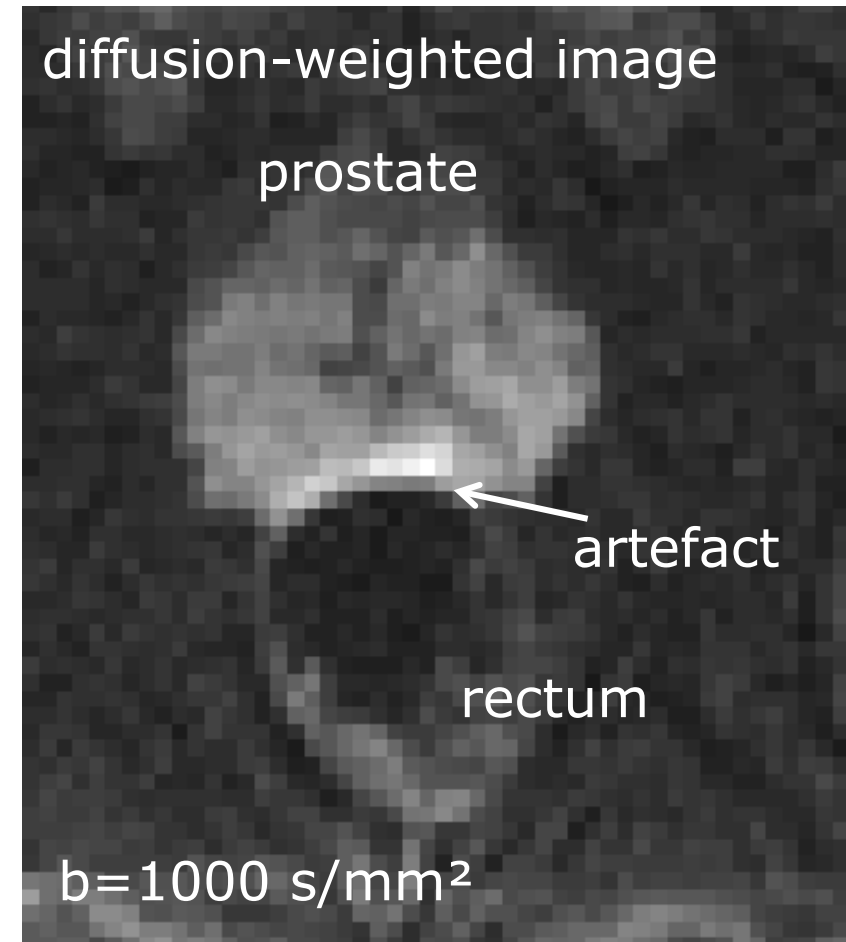
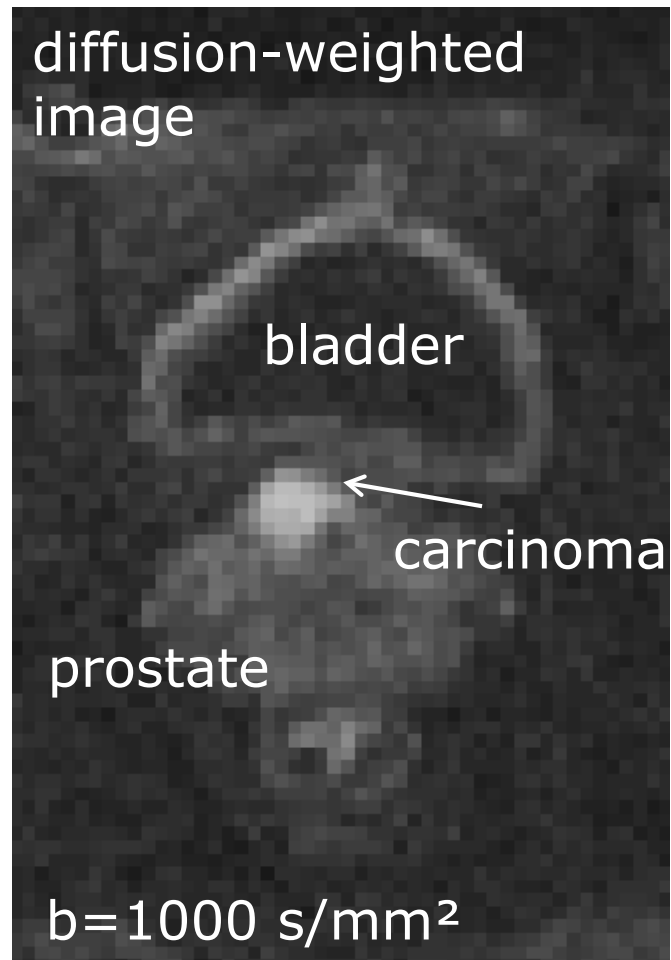
squeezed eye balls



## Effect 2: Intensity variation



## Effect 2: Intensity variation



# Transversal relaxation



# T2 blurring

- $S_{\text{MRI, with T}_2}(\mathbf{r}) = S_{\text{MRI, without T}_2}(\mathbf{r}) * \mathcal{F}^{-1}\{\tilde{R}_{\text{relax},k}(\mathbf{k})\}$
- Again a „T<sub>2</sub> blurring“ occurs
- Unlike for single-line encoding: along phase encoding direction for EPI
- For EPI, the T<sub>2</sub> blurring is  $N \cdot \frac{k_{\text{max,read}}}{k_{\text{max,phase}}}$  times worse
- In EPI, actually T<sub>2</sub><sup>\*</sup> blurring



# Echo spacing



# Echo spacing

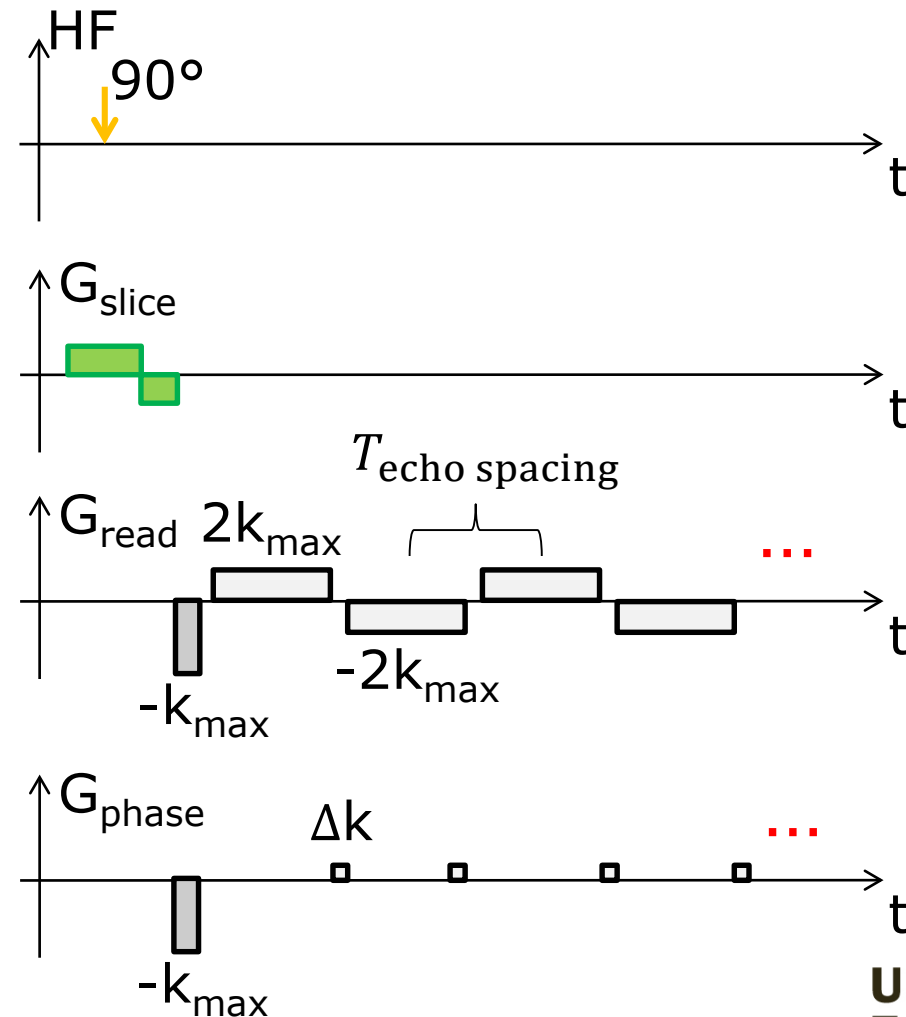
$$\Delta x_{\text{fat,EPI}} = \frac{FOV_{\text{phase}} \cdot \Delta \nu_{\text{fat}}}{BW} \mathbf{e}_{\text{phase}}$$

$$BW = T_{\text{read}}^{-1}$$

A bit more correct:  
use echo spacing

$$\Delta x_{\text{fat,EPI}}$$

$$= FOV_{\text{phase}} \Delta \nu_{\text{fat}} T_{\text{echo spacing}} \mathbf{e}_{\text{phase}}$$



# Variations of EPI



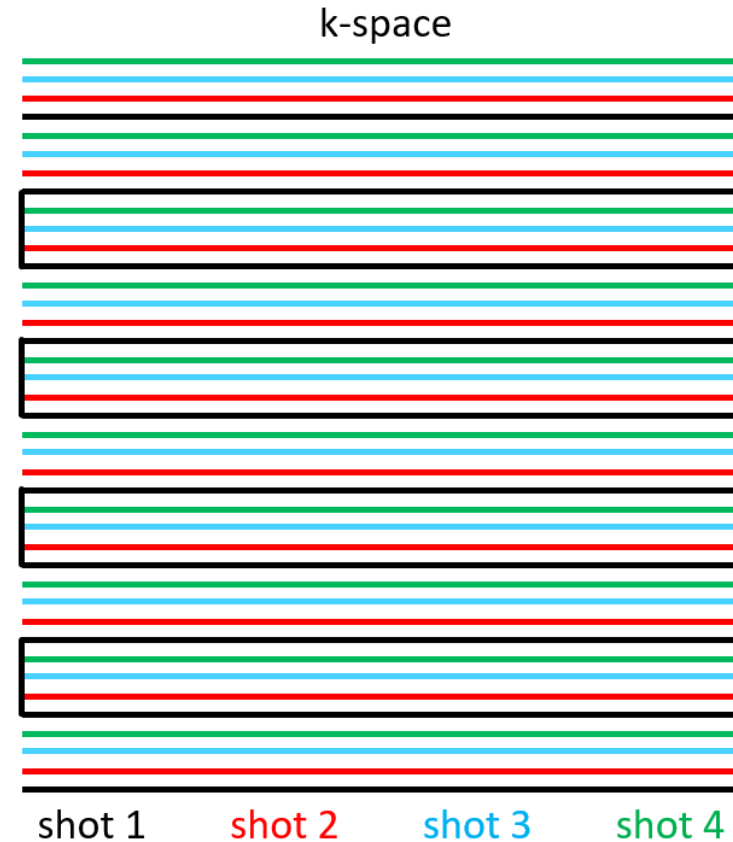


# Interleaved EPI



# Interleaved EPI

- Advantage:
  - The discussed artifacts go down by a factor  $N_{\text{shot}}$
- Disadvantage:
  - More prone to patient motion
  - Acquisition time goes up

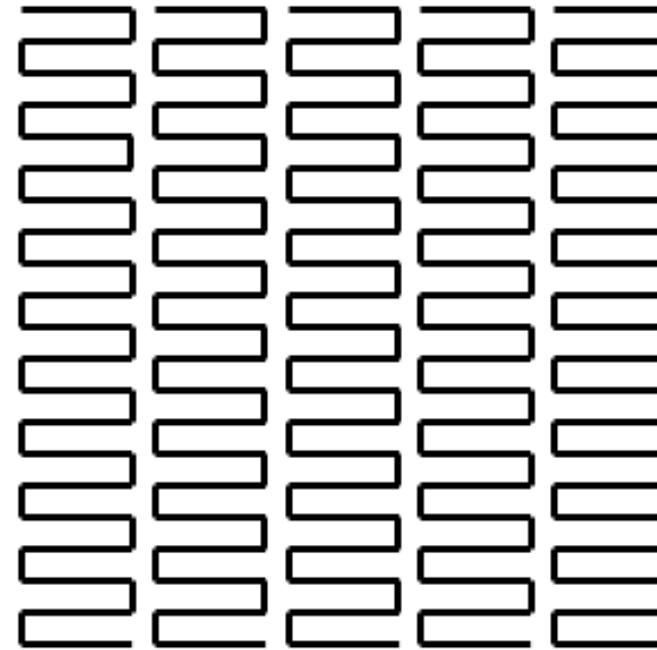


# Readout-segmented EPI



# Readout-segmented EPI

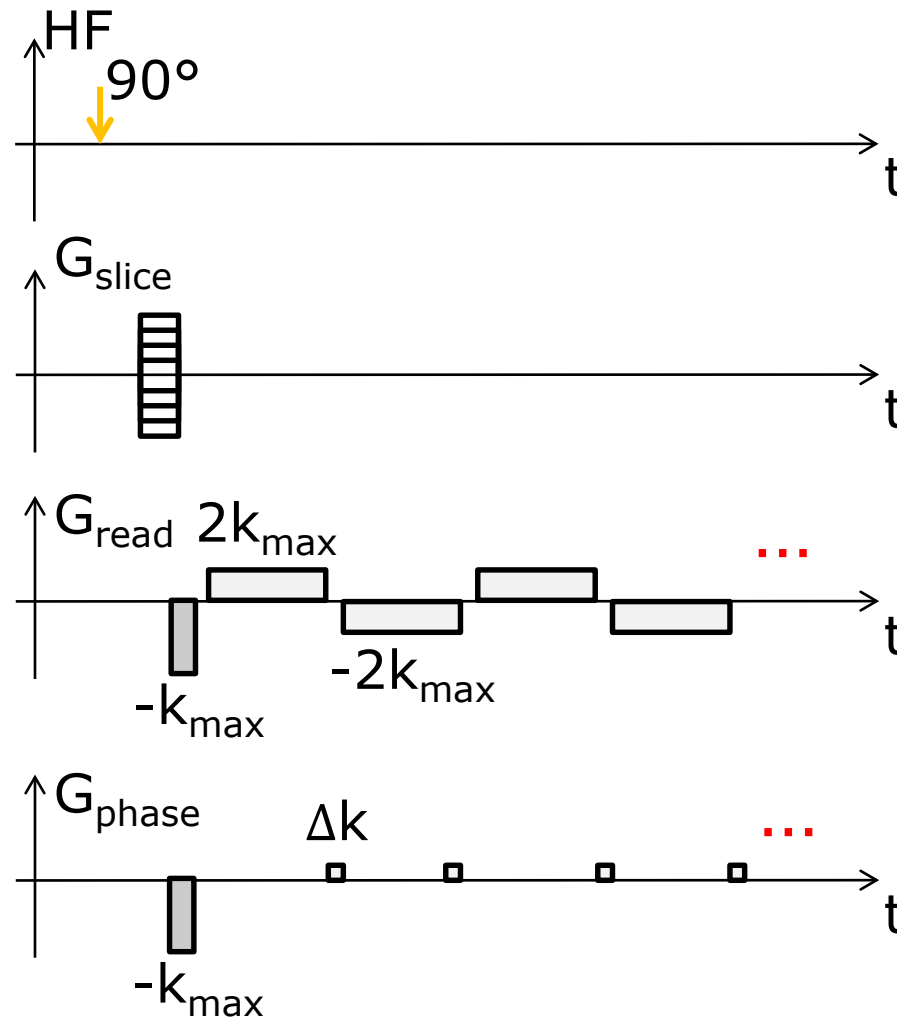
- Advantage:
  - The discussed artifacts go down by a factor  $N_{\text{shot}}$
- Disadvantage:
  - More prone to patient motion
  - Acquisition time goes up



# 3D EPI



# 3D EPI



# Summary



# Summary

- EPI is fast (acquisition time)
- EPI is slow (long readout train)
  - $\Delta x_{\text{fat}}, \Delta x_{\Delta B}, T_2$  blurring worse by factor  $N$
  - These artifacts: along phase direction
- $N/2$  ghost may arise

