

CECS 229 Programming Assignment #6

Due Date:

Sunday, 12/1 @ 11:59 PM

Submission Instructions:

Complete the programming problems in the file named `pa6.py`. You may test your implementation on your Repl.it workspace by running `main.py`. When you are satisfied with your implementation,

1. Submit your Repl.it workspace
2. Download the file `pa6.py` and submit it to the appropriate CodePost auto-grader folder.

Objectives:

1. Apply Gaussian Elimination to solve the system $A\vec{x} = \vec{b}$.
2. Use L_p -norm to calculate the error in a solution given by applying Gaussian elimination.
3. Use the REF of the augmented matrix for the system $A\vec{x} = \vec{b}$ to determine if it has one solution, no solution, or infinitely-many solutions.
4. Determine the number of free variables that the system $A\vec{x} = \vec{b}$ has if it has infinitely-many solutions.
5. Use Gram-Schmidt Process to find an orthonormal basis for a given set of vectors.

Notes:

Unless otherwise stated in the FIXME comment, you may not change the outline of the algorithm provided by introducing new loops or conditionals, or by calling any built-in functions that perform the entire algorithm or replaces a part of the algorithm.

Problem 1

Complete the function `norm(p, v)` that returns the L_p -norm of `Vec` object `v`. Recall that the L_p -norm of an n -dimensional vector \vec{v} is given by, $\|\vec{v}\|_p = (\sum_{i=1}^n |v_i|^p)^{1/p}$. Input `p` should be of the type `int`. The output norm should be of the type `float`.

In []:

```
def norm(v, p):
    """
    returns the p-norm of Vec v
    INPUT:
        p - an integer determining the norm to be calculated
        v - the Vec object for which the norm will be applied
    OUTPUT:
        the norm as a float
    """
```

```
# TODO: implement this function
pass
```

Problem 2

Complete the helper function `_ref(A)` that applies Gaussian Elimination to create and return the Row Echelon Form of the given `Matrix` object `A`. The output must be of the type `Matrix`. The method should **NOT** modify the contents of the original `Matrix` object `A`. It should create and return a new `Matrix` object.

```
In [ ]: import copy

def _ref(A):
    """
    returns the Row Echelon Form of the Matrix A
    INPUT: Matrix A
    OUTPUT: distinct Matrix object that is the
            Row-Echelon Form of A
    """
    matrix = Matrix(copy.deepcopy(A.rowsp))
    m, n = matrix.dim()
    # TODO: Finish implementation for this function
    return matrix
```

Problem 3

Create a function `rank(A)` that returns the rank of `Matrix` object `A` as an integer.

HINT: Look at Claim 2.4.1 of the "Gaussian Elimination Lecture Notes"

```
In [ ]: def rank(A):
    """
    returns the rank of the given Matrix object
    as an integer
    """
    # TODO: implement this function
    pass
```

Problem 4

Implement the function `gauss_solve(A, b)` that solves the system $A\vec{x} = \vec{b}$. The input `A` is of the type `Matrix` and `b` is of the type `Vec`.

- If the system has a unique solution, it returns the solution as a `Vec` object.
- If the system has no solution, it returns `None`.
- If the system has infinitely many solutions, it returns the number of free variables (`int`) in the solution.

```
In [ ]: def gauss_solve(A, b):
    """
    returns the solution to the system Ax = b
    if the system has a solution. If the system
    does not have a solution, None is returned.
```

```

If the system has infinitely-many solutions,
the number of free variables as an 'int' is returned
INPUT:
    A - a Matrix object
    b - a Vec object

OUTPUT:
    Vec object if the system has a unique solution
    None if the system has no solution
    int if the system has infinitely-many solutions
"""
# TODO: Implement this function
pass

```

Problem 5

Implement the function `gram_schmidt(S)` that applies the Gram-Schmidt process to create an orthonormal set of vectors from the vectors in set `S`. The function assumes that the set `S` is linearly independent.

INPUT:

- `S` a linearly independent set of `Vec` objects

OUTPUT:

- a set of `Vec` objects representing orthonormal vectors.

HINT:

If $S = \{\vec{x}_1, \vec{x}_2, \dots, \vec{x}_n\}$ is a set of linearly independent vectors, then Gram-Schmidt process returns the set $\{\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n\}$ where,

- $\vec{u}_i = \frac{1}{\|\vec{w}_i\|_2} \vec{w}_i$ for $i = 1, 2, \dots, n$,

and

- $\vec{w}_1 = \vec{x}_1$
- $\vec{w}_i = \vec{x}_i - \sum_{j=1}^{i-1} \text{proj}_{\vec{w}_j}(\vec{x}_i)$ for $i = 2, 3, \dots, n$

```

In [ ]: def gram_schmidt(S):
        """
        returns the orthonormal basis of given set S
        INPUT: S - a set of linearly independent 'Vec' objects
        OUTPUT: An orthonormal set of 'Vec' objects
        """
        # TODO: Implement this function
        pass

```