CECS 229 Programming Assignment #4

Due Date:

Sunday, 11/03 @ 11:59 PM

Submission Instructions:

Complete the programming problems in the file named pa4.py .

1. Download the file pa4.py and submit it to the appropriate CodePost auto-grader folder.

Objectives:

- 1. Apply vector operations to translate, scale, and rotate a set of points representing an image.
- 2. Perform various operations with or on vectors: addition, subtraction, dot product, norm.

NOTES:

- 1. Unless otherwise stated in the FIXME comment, you may not change the outline of the algorithm provided by introducing new loops or conditionals, or by calling any built-in functions that perform the entire algorithm or replaces a part of the algorithm.
- 2. You may import and use the Python $\[$ math $\]$ module to obtain the value for e and to calculate sine, cosine, and tangent functions, if needed.

Problem 1:

Create a function translate(S, z0) that translates the points in the input set S by $z_0 = a_0 + b_0 i$. The function should satisfy the following:

- 1. INPUT:
 - S set S
 - z0 complex number
- 2. OUT:
 - T set T consisting of points in S translated by z_0

```
:return: set type; a set consisting of points in S translated by z0
"""
# FIXME: Implement this function
# FIXME: Return correct output
return None
```

Problem 2:

Create a function scale(S, k) that scales the points in the input set S by a factor of k:

- 1. INPUT:
 - S set S
 - k positive float, raises ValueError if $k \le 0$.
- 2. OUTPUT:
 - a set consisting of points in S scaled by k.

```
In [ ]: def scale(S, k):
    """
    scales the complex numbers of set S by k.
    :param S: set type; a set of complex numbers
    :param k: float type; positive real number
    :return: set type; a set consisting of points in S scaled by k
    :raise: raises ValueError if k <= 0
    """
    # FIXME: Implement this function.
    # FIXME: Return correct output
    return None</pre>
```

Problem 3:

Create a function rotate(S, tau) that rotates the points in the input set S by τ radians:

- 1. INPUT:
 - S set S
 - tau float. If negative, the rotation is clockwise. If positive the rotation is counterclockwise. If zero, no rotation.
- 2. OUT:
 - a set consisting of points in S rotated by au

Problem 4:

Finish the implementation of class Vec which instantiates row-vector objects with defined operations of addition, subtraction, scalar multiplication, and dot product. In addition, Vec class overloads the Python built-in function abs() so that when it is called on a Vec object, it returns the Euclidean norm of the vector.

```
In [ ]:
        class Vec:
             def __init__(self, contents = []):
                 Constructor defaults to empty vector
                 INPUT: list of elements to initialize a vector object, defaults to empty list
                 self.elements = contents
                 return
             def __abs__(self):
                 Overloads the built-in function abs(v)
                 :returns: float type; the Euclidean norm of vector v
                 # FIXME: Implement this method
                 # FIXME: Return correct output
                 return None
            def __add__(self, other):
                 overloads the + operator to support Vec + Vec
                 :raises: ValueError if vectors are not same length
                 :returns: Vec type; a Vec object that is the sum vector of this Vec and 'other
                 # FIXME: Finish the implementation
                 # FIXME: Return correct output
                 return None
            def __sub__(self, other):
                 overloads the - operator to support Vec - Vec
                 :raises: ValueError if vectors are not same length
                 :returns: Vec type; a Vec object that is the difference vector of this Vec and
                 # FIXME: Finish the implementation
                 # FIXME: Return correct output
                 return None
             def __mul__(self, other):
                 Overloads the * operator to support
                     - Vec * Vec (dot product) raises ValueError if vectors are not
                       same length in the case of dot product; returns scalar

    Vec * float (component-wise product); returns Vec object

                     - Vec * int (component-wise product); returns Vec object
```

```
if type(other) == Vec: #define dot product
        # FIXME: Complete the implementation
        # FIXME: Return the correct output
        return None
    elif type(other) == float or type(other) == int: #scalar-vector multiplication
        # FIXME: Complete the implementation
        # FIXME: Return the correct output
        return None
def __rmul__(self, other):
    """Overloads the * operation to support
        - float * Vec; returns Vec object
        - int * Vec; returns Vec object
    # FIXME: Complete the implementation
    # FIXME: Return the correct output
    return None
def __str__(self):
    """returns string representation of this Vec object"""
    return str(self.elements) # does NOT need further implementation
```