```
close all;
clear variables;
clc;
```

## Read the training, validation and test partitions from the relevant

```
text files.
*** Adjust the file path as required. ***
```

```
folder = "CUB_200_2011_Subset20classes";
trainingImageNames = readtable(fullfile(folder, "train.txt"),'ReadVariableNames', false);
trainingImageNames.Properties.VariableNames = {'index', 'imageName'};

validationImageNames = readtable(fullfile(folder, "validate.txt"),'ReadVariableNames', false);
validationImageNames.Properties.VariableNames = {'index', 'imageName'};

testImageNames = readtable(fullfile(folder, "test.txt"),'ReadVariableNames', false);
testImageNames.Properties.VariableNames = {'index', 'imageName'};
```

#### Read class info from the relevant text files

```
classNames = readtable(fullfile(folder, "classes.txt"), 'ReadVariableNames', false);
classNames.Properties.VariableNames = {'index', 'className'};

imageClassLabels = readtable(fullfile(folder, "image_class_labels.txt"), 'ReadVariableNames', false);
imageClassLabels.Properties.VariableNames = {'index', 'classLabel'};
```

```
% bounding box
boundingBox = readtable(fullfile(folder, "bounding_boxes.txt"), 'ReadVariableNames', false);
boundingBox.Properties.VariableNames = {'index', 'x', 'y', 'w', 'h'};
```

# Create lists of image names for training, validation and test subsets.

To be precise, we create an array of strings containing the full file path and file names for each data partition.

```
folder = "CUB_200_2011_Subset20classes/";
trainingImageList = strings(height(trainingImageNames), 1);
for iI = 1:height(trainingImageNames)
    trainingImageList(iI) = string(fullfile(folder, "images/", ...
        string(cell2mat(trainingImageNames.imageName(iI)))));
end

validationImageList = strings(height(validationImageNames), 1);
for iI = 1:height(validationImageNames)
    validationImageList(iI) = string(folder + "images/" + ...
        string(cell2mat(validationImageNames.imageName(iI))));
end
```

```
testImageList = strings(height(testImageNames), 1);
for iI = 1:height(testImageNames)
    testImageList(iI) = string(folder + "images/" + ...
    string(cell2mat(testImageNames.imageName(iI))));
end
```

```
% mapping bounding boxes
trainingBox = return_bounding_box_mapping(trainingImageNames, boundingBox);
validationBox = return_bounding_box_mapping(validationImageNames, boundingBox);
testBox = return_bounding_box_mapping(testImageNames, boundingBox);
```

### Create image datastores for training, validation and test subsets

```
trainingImageDS = imageDatastore(trainingImageList, 'labelSource', 'foldernames', ...
    'FileExtensions', {'.jpg'});
trainingImageDS.ReadFcn = @readImagesIntoDatastore;

validationImageDS = imageDatastore(validationImageList, 'labelSource', 'foldernames', ...
    'FileExtensions', {'.jpg'});
validationImageDS.ReadFcn = @readImagesIntoDatastore;

testImageDS = imageDatastore(testImageList, 'labelSource', 'foldernames', ...
    'FileExtensions', {'.jpg'});
testImageDS.ReadFcn = @readImagesIntoDatastore;
```

```
% apply bounding box
trainingImageDS.ReadFcn = @(file_name) read_bounding_box_image_to_datastore(file_name, training
validationImageDS.ReadFcn = @(file_name) read_bounding_box_image_to_datastore(file_name, validatestImageDS.ReadFcn = @(file_name) read_bounding_box_image_to_datastore(file_name, testBox);
```

# The images all have different spatial resolutions (width x height), so

need to resize them to the same size. (Experiment with different sizes!)

```
targetSize = [100, 100];
trainingImageDS_Resized = transform(trainingImageDS, @(x) imresize(x,targetSize));
validationImageDS_Resized = transform(validationImageDS, @(x) imresize(x,targetSize));
testImageDS_Resized = transform(testImageDS, @(x) imresize(x,targetSize));

% Combine transformed datastores and labels
labelsTraining = arrayDatastore(trainingImageDS.Labels);
cdsTraining = combine(trainingImageDS_Resized, labelsTraining);
labelsValidation = arrayDatastore(validationImageDS.Labels);
cdsValidation = combine(validationImageDS_Resized, labelsValidation);
labelsTest = arrayDatastore(testImageDS.Labels);
cdsTest = combine(testImageDS_Resized, labelsTest);
```

```
% %test
```

```
% gray_img = rgb2gray(img);
%
% % Create a SURF object
% surf_obj = detectSURFFeatures(gray_img);
%
% % Extract SURF features
% [ztest_surf_features, ztest_valid_points] = extractFeatures(gray_img, surf_obj);
%
% % Compute HOG features
% ztest hog features = extractHOGFeatures(gray img, 'CellSize', [8 8]);
% [coeff_surf, score_surf, latent_surf] = pca(ztest_surf_features);
% [coeff_hog, score_hog, latent_hog] = pca(ztest_hog_features);
%
% % Use first n principal components to form feature vectors
% n = min(size(score_surf,2), size(score_hog,2));
% combined features = [score surf(:,1:n), score hog(:,1:n)];
```

```
img = cdsTraining.read{1};
```

```
[hog_8x8, vis8x8] = extractHOGFeatures(img,'CellSize',cellSize);
subplot(1, 2, 1);
imshow(img);
title('Sample Image Resized');
subplot(1, 2, 2);
imshow(rgb2gray(img)); hold on;
title('SIFT Feature Points');
plot(vis8x8);
hold off;
% noise reduction
J = imnoise(im2gray(img),'gaussian',0,0.025);
K = wiener2(J,[5 5]);
imshow(K);
```

#### Sample Image Resized





```
img_equalised = histeq(im2gray(img));
[hog_eq, vis_eq] = extractHOGFeatures(img_equalised,"CellSize", cellSize);
hog_8x8(1, 145:288) = hog_eq;
```

#### **Extract HOG features**

```
%fitcsvm
%surf
% trainingFeatures = zeros(numImagesTrain, 2200, 'single');
% reset(cdsTraining);
                     % Make sure we start with the first image
% for i = 1:numImagesTrain
%
     imgGray = im2gray(imgFromDS{1});
%
                                    % Ensure images are grayscale
%
     points = detectSURFFeatures(imgGray);
    features = extractFeatures(imgGray, points);
%
%
     sz = size(features);
%
    trainingFeatures(i, 1:sz(1)*sz(2)) = reshape(features, 1, []);
% end
```

```
% surf test
%
% numImagesTest = numel(testImageDS_Resized.UnderlyingDatastores{1, 1}.Files);
%
% testFeatures = zeros(numImagesTest, 2200, 'single');
```

```
% for i = 1:numImagesTest
%
   %
   imgGray = im2gray(imgFromDS{1});
                           % Ensure images are grayscale
%
   points = detectSURFFeatures(imgGray);
%
   features = extractFeatures(imgGray, points);
%
   sz = size(features);
%
   testFeatures(i, 1:sz(1)*sz(2)) = reshape(features, 1, []);
% end
```

```
% surfPoints = detectSURFFeatures(rgb2gray(img));
% subplot(1, 2, 1);
% imshow(img);
% subplot(1, 2, 2);
% imshow(rgb2gray(img)); hold on;
% plot(surfPoints);
% hold off;
```

```
% HOG
numImagesTrain = numel(trainingImageDS Resized.UnderlyingDatastores{1, 1}.Files);
trainingFeaturesHOG = zeros(numImagesTrain, hogFeatureSize, 'single');
                       % Make sure we start with the first image
reset(cdsTraining);
for i = 1:numImagesTrain
    imgFromDS = read(cdsTraining);    % Get item from datastore. Note, this returns a cell arra
    imgGray = im2gray(imgFromDS{1});
                                      % Ensure images are grayscale
    %imgEqul = histeq(imgGray);
   %imgflip = flip(imgGray,2);
    temp = imnoise(imgGray, "gaussian", 0, 0.025);
    reduceNoise = wiener2(temp, [5 5]);
    trainingFeaturesHOG(i, 1:144) = extractHOGFeatures(imgGray, 'CellSize', cellSize);
   %trainingFeatures(i, 145:288) = extractHOGFeatures(imgEqul, 'CellSize', cellSize);
    trainingFeaturesHOG(i, 145:288) = extractHOGFeatures(reduceNoise, 'CellSize', cellSize');
end
```

```
% HOG test
numImagesTest = numel(testImageDS_Resized.UnderlyingDatastores{1, 1}.Files);
testFeaturesHOG = zeros(numImagesTest, hogFeatureSize, 'single');
reset(cdsTest);
                    % Make sure we start with the first image
for i = 1:numImagesTest
    imgFromDS = read(cdsTest);
                                 % Get item from datastore
    imgGray = im2gray(imgFromDS{1}); % Ensure images are grayscale
    %imgEqul = histeq(imgGray);
    %imgflip = flip(imgGray,2);
    temp = imnoise(imgGray, "gaussian", 0, 0.025);
    reduceNoise = wiener2(temp, [10 10]);
    testFeaturesHOG(i, 1:144) = extractHOGFeatures(imgGray, 'CellSize', cellSize);
   %testFeatures(i, 145:288) = extractHOGFeatures(imgEqul, 'CellSize', cellSize);
    testFeaturesHOG(i, 145:288) = extractHOGFeatures(reduceNoise, 'CellSize', cellSize);
```

```
% %surf
% % imset = imageSet(cdsTraining.UnderlyingDatastores{1, 1}.UnderlyingDatastores{1, 1}.Files);
% imset = imageSet(trainingImageDS.Files);
% surfMetricThreshold = 1000;
% surfNumOctaves = 3;
% surfNumScaleLevels = 4;
% % Extract SURF features from the image set
% [surfFeatures, surfLocations] = helperExtractSURFFeaturesFromImageSet(trainingImageDS,surfMetricThreshold = 1000;
```

```
% %sift features
% numFeatures = 50;
% maxFeatures = 100;
%

% Start by extracting features from the training set via the helper function.
% % These features will be used to train the classifier.
% [trainingFeaturesSIFT, trainingLabelsSIFT] = ...
% helperExtractSIFTFeaturesFromImageSet(trainingImageDS_Resized.UnderlyingDatastores{1, 1})
```

```
% %sift test
% [testFeaturesSIFT, testLabelsSIFT] = ...
% helperExtractSIFTFeaturesFromImageSet(testImageDS_Resized.UnderlyingDatastores{1, 1},
```

Unable to resolve the name 'testImageDS\_Resized.UnderlyingDatastores'.

# Check if we have a GPU available and clear any old data from it

```
if (gpuDeviceCount() > 0)
    disp('Found GPU:');
    disp(gpuDeviceTable);
    device = gpuDevice(1);
    reset(device); % Clear previous values that might still be on the GPU
end
```

```
Found GPU:

Index Name ComputeCapability DeviceAvailable DeviceSelected

1 "GRID T4-8Q" "7.5" true true
```

```
% combinedFeatures = [trainingFeatures trainingFeaturesHOG];
% combinedFeatures = [trainingFeatures trainingFeaturesHOG trainingFeaturesSIFT];
% combinedFeatures = [trainingFeatures trainingFeaturesSIFT];
```

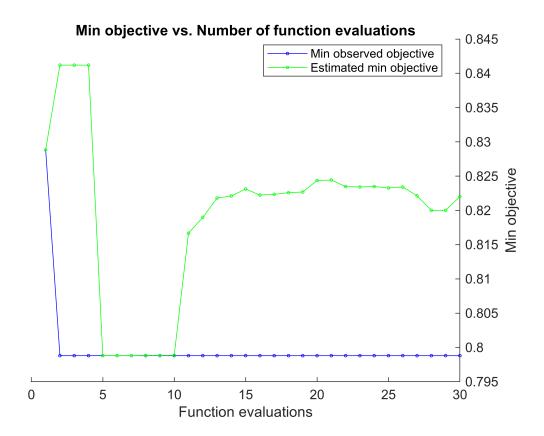
### Train a multi-class SVM

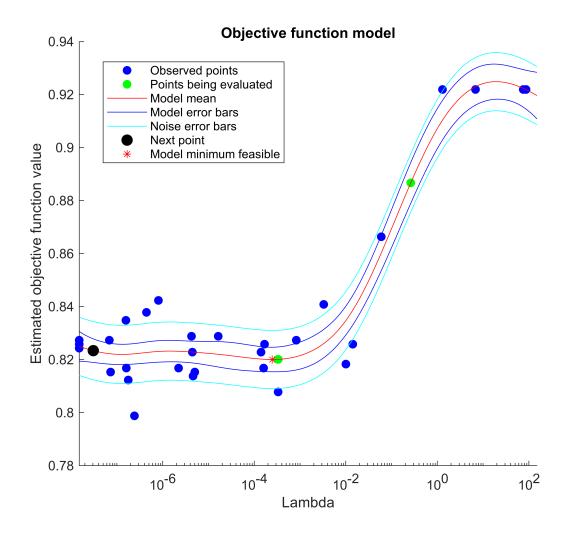
```
t = templateLinear('Solver', 'dual');
```

Starting parallel pool (parpool) using the 'Processes' profile ... Connected to the parallel pool (number of workers: 4). Copying objective function to workers...

Done copying objective function to workers.

Iter	Active	Eval	Objective	Objective	BestSoFar	BestSoFar	Lambda
	workers	result		runtime	(observed)	(estim.)	
1	4	Best	0.82883	24.859	0.82883	0.82883	1.6361e-05
2	2	Accept	0.92192	25.102	0.7988	0.8412	1.2971
3	2	Best	0.7988	25.089	0.7988	0.8412	2.4188e-07
4	2	Accept	0.81832	24.962	0.7988	0.8412	0.010054
5	4	Accept	0.92192	23.865	0.7988	0.79881	86.731
6	3	Accept	0.92192	24.847	0.7988	0.79881	75.379
7	3	Accept	0.92192	24.844	0.7988	0.79881	6.8226
8	3	Accept	0.81532	25.423	0.7988	0.79883	7.2855e-08
9	4	Accept	0.82733	14.416	0.7988	0.79883	0.0008289
10	4	Accept	0.82432	12.384	0.7988	0.79885	1.502e-08
11	4	Accept	0.84234	12.585	0.7988	0.81667	8.08e-07
12	4	Accept	0.83784	13.255	0.7988	0.81898	4.4245e-07
13	4	Accept	0.81682	14.06	0.7988	0.8218	2.2275e-06
14	4	Accept	0.84084	14.73	0.7988	0.8221	0.0032987
15	4	Accept	0.82733	14.03	0.7988	0.82312	6.8382e-08
16	4	Accept	0.82583	14.951	0.7988	0.82223	1.5041e-08
17	4	Accept	0.86637	15.918	0.7988	0.82235	0.059643
18	4	Accept	0.82733	15.817	0.7988	0.82258	1.5024e-08
19	4	Accept	0.82282	15.088	0.7988	0.82268	0.00014077
20	4	Accept	0.83483	15.468	0.7988	0.82437	1.5729e-07
======							=======================================
Iter	Active	Eval	Objective	Objective	BestSoFar	BestSoFar	Lambda
 	workers	result	l 	runtime	(observed)	(estim.)	 
21	 l 4	   Accept	   0.81532	15.623	   0.7988	   0.82443	5.0305e-06
22	4	Accept	0.81682	16.06	0.7988	0.82346	1.607e-07
23	1 4	Accept	0.82583	15.514	0.7988	0.82342	0.00016813
24	j 4	Accept	0.81682	15.06	0.7988	0.82349	0.00016028
25	4	Accept	0.81381	14.797	0.7988	0.82327	4.6144e-06
26	4	Accept	0.82883	14.983	0.7988	0.82341	4.2638e-06
27	4	Accept	0.81231	14.849	0.7988	0.82212	1.7707e-07
28	4	Accept	0.80781	15.404	0.7988	0.82001	0.00033284
29	4	Accept	0.82282	15.237	0.7988	0.82001	4.4514e-06
30	4	Accept	0.82583	15.018	0.7988	0.822	0.014221





Optimization completed.

MaxObjectiveEvaluations of 30 reached.

Total function evaluations: 30

Total elapsed time: 157.1875 seconds

Total objective function evaluation time: 524.2382

Best observed feasible point:

#### Lambda

#### 2.4188e-07

Observed objective function value = 0.7988 Estimated objective function value = 0.82221 Function evaluation time = 25.0892

Best estimated feasible point (according to models): Lambda

#### 1.5729e-07

Estimated objective function value = 0.822 Estimated function evaluation time = 15.9742

```
% combineTestFeature = [testFeatures testFeaturesHOG];
% combineTestFeature = [testFeatures testFeaturesHOG testFeaturesSIFT];
% combineTestFeature = [testFeatures testFeaturesSIFT];
```

## Test the accuracy on the test partition

```
YPred = predict(Classifier, testFeaturesHOG);
YTest = testImageDS.Labels;

% Calculate overall accuracy
accuracy = sum(YPred == YTest)/numel(YTest) % Output on command line
```

accuracy = 0.2117

```
% Show confusion matrix in figure
[m, order] = confusionmat(YTest, YPred);
figure(2);
cm = confusionchart(m, order, ...
    'ColumnSummary','column-normalized', ...
    'RowSummary','row-normalized');
title("Overall Accuracy (HOG): "+ string(round(accuracy*100, 1)) +"%");
```

