

You need

1. UBUNTU
2. PYTHON 3
3. ROS

TO RUN USER INTERFACE

1. In the first Terminal you need to run the ros
roscore
2. Before step 3 & 4 change the directory of the terminal to the UI package folder.
3. Open new terminal run the user interface program
Python3 ui_screen
4. Open third terminal run the Robot node
Python3 Robot_node.py
5. Now you can use the UI.