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				(

```
20
18 Lines and segments
                                                          os << "[";
                                                          for (const auto &x : c)
   os << ", " + 2 * (&x == &*begin(c)) << x;
   return os << "]";</pre>
   void print(string s) { cout << endl; }</pre>
                                                   21
19 Circles
                                                         template <class H, class... T>
   21
                                                         void print(string s, const H &h, const T&... t) {
   const static string reset = "\033[0m", blue = "\033[1;34m
   19.3 Minimum enclosing circle \mathcal{O}(N) wow!! . . . . . 22
                                                              ", purple = "\033[3;95m";
   19.4 Common area circle-polygon \mathcal{O}(N) . . . . . . .
                                                          bool ok = 1;
                                                          do {
20 Polygons
                                                   22
                                                            if (s[0] == '\"') ok = 0;
                                                            else cout << blue << s[0] << reset;</pre>
   20.1 Area of polygon \mathcal{O}(N) . . . . . . . . . . . . . . . . . .
   20.2 Convex-Hull \mathcal{O}(N \cdot log N) . . . . . . . . . . . . . . .
                                                            s = s.substr(1);
                                                          } while (s.size() && s[0] != ',');
   20.3 Cut polygon by a line \mathcal{O}(N) . . . . . . . . . . .
                                                          if (ok) cout << ": " << purple << h << reset;</pre>
   20.4 Perimeter \mathcal{O}(N) . . . . . . . . . . . . . . . . .
                                                          print(s, t...);
   20.5 Point in polygon \mathcal{O}(N) . . . . . . . . . . . . . . . . . .
   20.6 Point in convex-polygon \mathcal{O}(logN) . . . . . . . .
  Randoms
                                                         mt19937 rng(chrono::steady_clock::now().time_since_epoch().
                                                   23
21 Geometry misc
                                                             count());
   template <class T>
                                                         T uid(T 1, T r) {
                                                          return uniform_int_distribution<T>(1, r)(rng);
Think twice, code once
Template
                                                        Compilation (gedit /.zshenv)
tem.cpp
                                                         touch a_in{1..9} // make files a_in1, a_in2,..., a_in9
 #pragma GCC optimize("Ofast,unroll-loops,no-stack-protector
                                                         tee {a..m}.cpp < tem.cpp // "" with tem.cpp like base</pre>
                                                         cat > a_in1 // write on file a_in1
 #include <bits/stdc++.h>
                                                         gedit a_in1 // open file a_in1
using namespace std;
                                                         rm -r a.cpp // deletes file a.cpp :'(
 #define fore(i, 1, r) for (auto i = (1) - ((1) > (r)); i !=
                                                         red='\x1B[0;31m'
     (r) - ((1) > (r)); i += 1 - 2 * ((1) > (r)))
                                                         green='\x1B[0;32m'
 #define sz(x) int(x.size())
                                                         noColor='\x1B[0m'
 #define all(x) begin(x), end(x)
                                                         alias flags='-Wall -Wextra -Wshadow -D_GLIBCXX_ASSERTIONS -
 #define f first
                                                             fmax-errors=3 -02 -w'
 #define s second
                                                         go() { g++ --std=c++11 $2 ${flags} $1.cpp && ./a.out }
#define pb push_back
                                                         debug() { go $1 - DLOCAL < $2 }
                                                         run() { go $1 "" < $2 }
using ld = long double;
using lli = long long;
                                                         random() { // Make small test cases!!!
using ii = pair<int, int>;
                                                         g++ --std=c++11 $1.cpp -o prog
using vi = vector<int>;
                                                         g++ --std=c++11 gen.cpp -o gen
                                                          g++ --std=c++11 brute.cpp -o brute
#ifdef LOCAL
                                                          for ((i = 1; i \le 200; i++)); do
 #include "debug.h"
                                                          printf "Test case #$i"
 #else
                                                          ./gen > in
 #define debug(...)
                                                          diff -uwi <(./prog < in) <(./brute < in) > $1_diff
 #endif
                                                          if [[ ! $? -eq 0 ]]; then
                                                           printf "${red} Wrong answer ${noColor}\n"
 int main() {
                                                           break
  cin.tie(0)->sync_with_stdio(0), cout.tie(0);
  // solve the problem here D:
                                                           printf "${green} Accepted ${noColor}\n"
  return 0;
                                                          fi
                                                          done
 debug.h
                                                         }
 template <class A, class B>
                                                        Bump allocator
 ostream & operator << (ostream &os, const pair<A, B> &p) {
  return os << "(" << p.first << ", " << p.second << ")";</pre>
                                                         static char buf[450 << 20];</pre>
                                                         void* operator new(size_t s) {
                                                          static size_t i = sizeof buf; assert(s < i);</pre>
 template <class A, class B, class C>
                                                          return (void *) &buf[i -= s];
basic_ostream<A, B> & operator << (basic_ostream<A, B> &os,
                                                         void operator delete(void *) {}
     const C &c) {
```

### 1 Data structures

#### 1.1 DSU with rollback

```
struct Dsu {
  vi par, tot;
  stack<ii>> mem;
 Dsu(int n = 1) : par(n + 1), tot(n + 1, 1) {
   iota(all(par), ₀);
  }
  int find(int u) {
    return par[u] == u ? u : find(par[u]);
  void unite(int u, int v) {
   u = find(u), v = find(v);
   if (u != v) {
      if (tot[u] < tot[v]) swap(u, v);</pre>
      mem.emplace(u, v);
      tot[u] += tot[v];
      par[v] = u;
    } else {
      mem.emplace(-1, -1);
  }
 void rollback() {
    auto [u, v] = mem.top();
    mem.pop();
    if (u != -1) {
      tot[u] -= tot[v];
      par[v] = v;
  }
};
```

#### 1.2 Monotone queue

```
template <class T, class F = less<T>>
struct MonotoneQueue {
  deque<pair<T, int>> pref;
  F f;

  void add(int pos, T val) {
    while (pref.size() && !f(pref.back().f, val))
        pref.pop_back();
    pref.emplace_back(val, pos);
  }

  void keep(int pos) { // >= pos
    while (pref.size() && pref.front().s < pos)
        pref.pop_front();
  }

  T query() {
    return pref.empty() ? T() : pref.front().f;
  }
};</pre>
```

#### 1.3 Stack queue

```
s.pb(s.empty() ? x : f(s.back(), x));
   }
   T pop() {
     T x = this->back();
     this->pop_back();
     s.pop_back();
     return x;
   T query() {
     return s.back();
 };
 template <class T, class F = function<T(const T&, const T&)</pre>
 struct Queue {
   Stack<T> a, b;
   Ff;
   Queue(const F &f) : a(f), b(f), f(f) {}
   void push(T x) {
     b.push(x);
   T pop() {
     if (a.empty())
       while (!b.empty())
         a.push(b.pop());
     return a.pop();
   T query() {
     if (a.empty()) return b.query();
     if (b.empty()) return a.query();
     return f(a.query(), b.query());
   }
};
      Mo's algorithm \mathcal{O}((N+Q)\cdot\sqrt{N}\cdot F)
1.4
 const int BLOCK = sqrt(N);
 sort(all(queries), [&] (Query &a, Query &b) {
   const int ga = a.l / BLOCK, gb = b.l / BLOCK;
   if (ga == gb) return a.r < b.r;</pre>
   return ga < gb;</pre>
 });
 int 1 = queries[0].1, r = 1 - 1;
 for (Query &q : queries) {
   while (r < q.r) add(++r);
   while (r > q.r) rem(r--);
   while (1 < q.1) rem(1++);
   while (1 > q.1) add(--1);
   ans[q.i] = solve();
}
To make it faster, change the order to hilbert(l,r)
 11i hilbert(int x, int y, int pw = 21, int rot = 0) {
   if (pw == 0) return 0;
   int hpw = 1 << (pw - 1);
   int k = ((x < hpw ? y < hpw ? 0 : 3 : y < hpw ? 1 : 2) +
       rot) & 3;
   const int d[4] = \{3, 0, 0, 1\};
   1li a = 1LL << ((pw << 1) - 2);</pre>
   lli b = hilbert(x & (x ^h hpw), y & (y ^h hpw), pw - 1, (
       rot + d[k]) & 3);
   return k * a + (d[k] ? a - b - 1 : b);
```

```
}
                                                                       }
       Static to dynamic \mathcal{O}(N \cdot F \cdot loq N)
                                                                       T query(int 1, int r) {
 template <class Black, class T>
                                                                         #warning Can give TLE \mathbf{D}:, change it to a log table
 struct StaticDynamic {
                                                                         int k = _{-}lg(r - 1 + 1);
   Black box[LogN];
                                                                         return f(sp[k][1], sp[k][r - (1 << k) + 1]);
   vector<T> st[LogN];
                                                                       }
                                                                    };
   void insert(T &x) {
     int p = 0;
     while (p < LogN && !st[p].empty())</pre>
                                                                           Squirtle decomposition
       p++;
                                                                   build \mathcal{O}(N \cdot \sqrt{N}), update, query: \mathcal{O}(\sqrt{N})
     st[p].pb(x);
                                                                   The perfect block size is squirtle of N
     fore (i, 0, p) {
                                                                     int blo[N], cnt[BLOCK][K], a[N];
       st[p].insert(st[p].end(), all(st[i]));
       box[i].clear(), st[i].clear();
                                                                     void update(int i, int x) {
                                                                       cnt[blo[i]][a[i]]--;
     for (auto y : st[p])
                                                                       a[i] = x;
       box[p].insert(y);
                                                                       cnt[blo[i]][a[i]]++;
     box[p].init();
                                                                     }
   }
 };
                                                                     int query(int 1, int r, int x) {
       Disjoint intervals
1.6
                                                                       int tot = 0;
                                                                       while (1 \le r)
insert, erase: \mathcal{O}(log N)
                                                                         if (1 % BLOCK == 0 && 1 + BLOCK - 1 <= r) {
 template <class T>
                                                                           tot += cnt[blo[1]][x];
 struct DisjointIntervals {
                                                                           1 += BLOCK;
   set<pair<T, T>> st;
                                                                         } else {
                                                                           tot += (a[1] == x);
   void insert(T 1, T r) {
                                                                           1++;
     auto it = st.lower_bound(\{1, -1\});
                                                                         }
     if (it != st.begin() && 1 <= prev(it)->s)
                                                                       return tot;
       1 = (--it)->f;
                                                                    }
     for (; it != st.end() && it->f <= r; st.erase(it++))</pre>
                                                                          Parallel binary search \mathcal{O}((N+Q) \cdot log N \cdot F)
                                                                   2.3
       r = max(r, it->s);
     st.insert({1, r});
                                                                     int lo[Q], hi[Q];
   }
                                                                     queue<int> solve[N];
                                                                     vector<Query> queries;
   void erase(T 1, T r) {
     auto it = st.lower_bound({1, -1});
                                                                     fore (it, 0, 1 + _{-}lg(N)) {
     if (it != st.begin() && 1 <= prev(it)->s) --it;
                                                                       fore (i, 0, sz(queries))
     T mn = 1, mx = r;
                                                                         if (lo[i] != hi[i]) {
     for (; it != st.end() && it->f <= r; st.erase(it++))</pre>
                                                                           int mid = (lo[i] + hi[i]) / 2;
       mn = min(mn, it->f), mx = max(mx, it->s);
                                                                           solve[mid].emplace(i);
     if (mn < 1) st.insert({mn, 1 - 1});</pre>
     if (r < mx) st.insert({r + 1, mx});</pre>
                                                                       fore (x, 0, n) \{ // \text{ 0th-indexed} \}
   }
                                                                         // simulate
};
                                                                         while (!solve[x].empty()) {
                                                                           int i = solve[x].front();
                                                                           solve[x].pop();
                                                                           if (can(queries[i]))
2
     Static range queries
                                                                             hi[i] = x;
                                                                           else
       Sparse table
                                                                             lo[i] = x + 1;
build: \mathcal{O}(N \cdot log N), query idempotent: \mathcal{O}(1), normal: \mathcal{O}(log N)
                                                                         }
 template <class T, class F = function<T(const T&, const T&)
                                                                       }
     >>
                                                                     }
 struct Sparse {
                                                                   3
                                                                         Dynamic range queries
   vector<vector<T>> sp;
                                                                   3.1
                                                                           Fenwick tree
   Sparse(const vector<T> &a, const F &f) : sp(1 + __lg(sz(a
                                                                     template <class T>
        ))), f(f) {
                                                                     struct Fenwick {
                                                                       vector<T> fenw;
     sp[0] = a;
     for (int k = 1; (1 << k) <= sz(sp[0]); k++) {
       sp[k].resize(sz(sp[0]) - (1 << k) + 1);
                                                                       Fenwick(int n) : fenw(n, T()) {} // 0-indexed
       fore (1, 0, sz(sp[k])) {
```

void update(int i, T v) {

fenw[i] += v;

for (; i < sz(fenw); i |= i + 1)

int r = 1 + (1 << (k - 1));

}

sp[k][1] = f(sp[k - 1][1], sp[k - 1][r]);

```
T query(int i) {
     T v = T();
                                                                     void build() {
     for (; i \ge 0; i \& i + 1, --i)
                                                                      if (1 == r)
       v += fenw[i];
                                                                        return:
     return v;
   }
   int lower_bound(T v) {
                                                                       pull();
     int pos = 0;
     fore (k, 1 + \underline{\ } \lg(sz(fenw)), 0)
       if (pos + (1 << k) <= sz(fenw) && fenw[pos + (1 << k)</pre>
            -1] < v) {
         pos += (1 << k);
                                                                         return this;
         v = fenw[pos - 1];
       }
                                                                       if (1 == r) {
     return pos + (v == 0);
                                                                         tmp->sum = v;
   }
                                                                         return tmp;
};
                                                                      }
       Dynamic segment tree
 struct Dyn {
   int 1, r;
                                                                     }
   Dyn *left, *right;
   11i sum = 0;
   Dyn(int 1, int r) : l(1), r(r), left(0), right(0) {}
                                                                         return 0;
   void pull() {
                                                                         return sum;
     sum = (left ? left->sum : 0);
     sum += (right ? right->sum : 0);
                                                                  };
   void update(int p, lli v) {
                                                                 3.4
     if (1 == r) {
                                                                  struct Wav {
       sum += v;
       return:
                                                                     int lo, hi;
     }
                                                                     Wav *left, *right;
     int m = (1 + r) >> 1;
                                                                     vector<int> amt;
     if (p <= m) {
       if (!left) left = new Dyn(1, m);
       left->update(p, v);
     } else {
       if (!right) right = new Dyn(m + 1, r);
                                                                        return;
       right->update(p, v);
     }
                                                                       amt.pb(0);
     pull();
   lli query(int ll, int rr) {
     if (rr < 1 || r < 11 || r < 1)
       return 0;
     if (ll <= l && r <= rr)
       return sum;
     int m = (1 + r) >> 1;
     return (left ? left->query(ll, rr) : 0) +
            (right ? right->query(ll, rr) : ∅);
                                                                       if (r < 1)
   }
                                                                         return 0;
 };
                                                                       if (lo == hi)
3.3
      Persistent segment tree
                                                                         return lo;
 struct Per {
   int 1, r;
   Per *left, *right;
   lli sum = 0;
   Per(int 1, int r) : 1(1), r(r), left(∅), right(∅) {}
   Per* pull() {
     sum = left->sum + right->sum;
                                                                         return 0;
                                                                       if (x <= lo && hi <= y)</pre>
     return this;
```

```
}
  int m = (1 + r) >> 1;
  (left = new Per(1, m))->build();
  (right = new Per(m + 1, r))->build();
 Per* update(int p, lli v) {
  if (p < 1 || r < p)
  Per* tmp = new Per(1, r);
  tmp->left = left->update(p, v);
  tmp->right = right->update(p, v);
  return tmp->pull();
1li query(int 11, int rr) {
  if (r < 11 || rr < 1)</pre>
  if (ll <= 1 && r <= rr)
  return left->query(ll, rr) + right->query(ll, rr);
   Wavelet tree
#define iter int* // vector<int>::iterator
Wav(int lo, int hi, iter b, iter e) : lo(lo), hi(hi) { //
     array 1-indexed
  if (lo == hi || b == e)
  amt.reserve(e - b + 1);
  int mid = (lo + hi) >> 1;
  auto leq = [mid](int x) { return x <= mid; };</pre>
  for (auto it = b; it != e; it++)
    amt.pb(amt.back() + leq(*it));
  auto p = stable_partition(b, e, leq);
 left = new Wav(lo, mid, b, p);
 right = new Wav(mid + 1, hi, p, e);
int kth(int 1, int r, int k) {
  if (k <= amt[r] - amt[l - 1])</pre>
    return left->kth(amt[l - 1] + 1, amt[r], k);
  return right->kth(l - amt[l - 1], r - amt[r], k - amt[r
      ] + amt[1 - 1]);
int count(int 1, int r, int x, int y) {
  if (r < 1 || y < x || y < lo || hi < x)
```

```
return r - 1 + 1;
                                                                     sz = left->sz + right->sz + (this != null);
     return left->count(amt[l - 1] + 1, amt[r], x, y) +
                                                                     // merge(left, this), merge(this, right)
            right->count(1 - amt[1 - 1], r - amt[r], x, y);
                                                                     return this;
   }
 };
                                                                   Treap() { left = right = null; }
3.5
       Li Chao tree
                                                                   Treap(int val) : val(val) {
 struct Fun {
                                                                     left = right = null;
  11i m = 0, c = inf;
                                                                     pull();
  lli operator ()(lli x) const { return m * x + c; }
 };
                                                                   template <class F>
 struct LiChao {
                                                                   pair<Treap*, Treap*> split(const F &leq) { // {<= val, >
  lli l, r;
   LiChao *left, *right;
                                                                     if (this == null) return {null, null};
   Fun f;
                                                                     push();
                                                                     if (leq(this)) {
  LiChao(lli 1, lli r) : l(1), r(r), left(0), right(0) {}
                                                                       auto p = right->split(leq);
                                                                       right = p.f;
   void add(Fun &g) {
                                                                       return {pull(), p.s};
     if (f(1) \le g(1) \&\& f(r) \le g(r))
                                                                     } else {
                                                                       auto p = left->split(leq);
     if (g(1) < f(1) & g(r) < f(r)) {
                                                                       left = p.s;
       f = g;
                                                                       return {p.f, pull()};
       return:
                                                                     }
     }
                                                                   }
     11i m = (1 + r) >> 1;
     if (g(m) < f(m)) swap(f, g);
                                                                   Treap* merge(Treap* other) {
     if (g(1) \le f(1))
                                                                     if (this == null) return other;
     left = left ? (left->add(g), left) : new LiChao(l, m,
                                                                     if (other == null) return this;
          g);
                                                                     push(), other->push();
     else
                                                                     if (pri > other->pri) {
     right = right ? (right->add(g), right) : new LiChao(m
                                                                       return right = right->merge(other), pull();
          + 1, r, g);
   }
                                                                       return other->left = merge(other->left), other->pull
   lli query(lli x) {
                                                                4.3
                                                                     Implicit treap (Rope)
     if (1 == r)
      return f(x);
                                                                   pair<Treap*, Treap*> leftmost(int k) {
     11i m = (1 + r) >> 1;
                                                                     return split([&](Treap* n) {
     if (x \le m)
                                                                       int sz = n->left->sz + 1;
       return min(f(x), left ? left->query(x) : inf);
                                                                       if (k >= sz) {
     return min(f(x), right ? right->query(x) : inf);
                                                                         k = sz;
   }
                                                                         return true;
 };
                                                                       return false;
4
     Binary trees
                                                                     });
                                                                   }
       Ordered tree
4.1
                                                                     Graphs
                                                                5
 #include <ext/pb_ds/assoc_container.hpp>
 #include <ext/pb_ds/tree_policy.hpp>
                                                                       Topological sort \mathcal{O}(V+E)
                                                                5.1
 using namespace __gnu_pbds;
                                                                 vi order;
 template <class K, class V = null_type>
                                                                 int indeg[N];
 using OrderedTree = tree<K, V, less<K>, rb_tree_tag,
     tree_order_statistics_node_update>;
                                                                 void topologicalSort() { // first fill the indeg[]
 #define rank order_of_key
                                                                   queue<int> qu;
 #define kth find_by_order
                                                                   fore (u, 1, n + 1)
                                                                     if (indeg[u] == 0)
4.2
       Treap
                                                                       qu.push(u);
 struct Treap {
                                                                   while (!qu.empty()) {
   static Treap *null;
                                                                     int u = qu.front();
   Treap *left, *right;
                                                                     qu.pop();
   unsigned pri = rng(), sz = 0;
                                                                     order.pb(u);
   int val = 0;
                                                                     for (int v : graph[u])
                                                                       if (--indeg[v] == 0)
   void push() {
                                                                         qu.push(v);
    // propagate like segtree, key-values aren't modified!!
                                                                   }
                                                                 }
                                                               5.2
                                                                       Tarjan algorithm (SCC) \mathcal{O}(V+E)
   Treap* pull() {
```

```
int tin[N], fup[N];
                                                                      fup[u] = min(fup[u], tin[v]);
 bitset<N> still;
                                                                    }
 stack<int> stk;
                                                                  }
 int timer = 0;
                                                                 5.5
                                                                        Two Sat \mathcal{O}(V+E)
                                                                  struct TwoSat {
 void tarjan(int u) {
                                                                    int n:
   tin[u] = fup[u] = ++timer;
                                                                    vector<vector<int>> imp;
   still[u] = true;
   stk.push(u);
                                                                    TwoSat(int _n) : n(_n + 1), imp(2 * n) {}
   for (int v : graph[u]) {
    if (!tin[v])
                                                                    void either(int a, int b) {
       tarjan(v);
                                                                      a = max(2 * a, -1 - 2 * a);
     if (still[v])
                                                                      b = max(2 * b, -1 - 2 * b);
       fup[u] = min(fup[u], fup[v]);
                                                                      imp[a ^ 1].pb(b);
                                                                      imp[b ^ 1].pb(a);
   if (fup[u] == tin[u]) {
    int v;
                                                                    }
     do {
                                                                    void implies(int a, int b) { either(~a, b); }
       v = stk.top();
                                                                    void setVal(int a) { either(a, a); }
       stk.pop();
       still[v] = false;
                                                                    vector<int> solve() {
       // u and v are in the same scc
                                                                      int k = sz(imp);
     } while (v != u);
                                                                      vector<int> s, b, id(sz(imp));
   }
 }
                                                                      function<void(int)> dfs = [&](int u) {
       Kosaraju algorithm (SCC) \mathcal{O}(V+E)
                                                                        b.pb(id[u] = sz(s));
 int scc[N], k = 0;
                                                                        s.pb(u);
 char vis[N];
                                                                        for (int v : imp[u]) {
 vi order;
                                                                          if (!id[v]) dfs(v);
                                                                          else while (id[v] < b.back()) b.pop_back();</pre>
 void dfs1(int u) {
   vis[u] = 1;
                                                                        if (id[u] == b.back())
   for (int v : graph[u])
                                                                          for (b.pop_back(), ++k; id[u] < sz(s); s.pop_back()</pre>
    if (vis[v] != 1)
       dfs1(v);
                                                                            id[s.back()] = k;
   order.pb(u);
                                                                      };
                                                                      vector<int> val(n);
 void dfs2(int u, int k) {
                                                                      fore (u, 0, sz(imp))
   vis[u] = 2, scc[u] = k;
                                                                        if (!id[u]) dfs(u);
   for (int v : rgraph[u]) // reverse graph
                                                                      fore (u, 0, n) {
    if (vis[v] != 2)
                                                                        int x = 2 * u;
       dfs2(v, k);
                                                                        if (id[x] == id[x ^ 1]) return {};
 }
                                                                        val[u] = id[x] < id[x ^ 1];
 void kosaraju() {
                                                                      return val;
   fore (u, 1, n + 1)
                                                                    }
     if (vis[u] != 1)
                                                                  };
       dfs1(u);
                                                                       Detect a cycle \mathcal{O}(V+E)
                                                                 5.6
   reverse(all(order));
                                                                  bool cycle(int u) {
   for (int u : order)
                                                                    vis[u] = 1;
     if (vis[u] != 2)
                                                                    for (int v : graph[u]) {
       dfs2(u, ++k);
                                                                      if (vis[v] == 1)
 }
                                                                        return true;
5.4
       Cutpoints and Bridges \mathcal{O}(V+E)
                                                                      if (!vis[v] && cycle(v))
 int tin[N], fup[N], timer = 0;
                                                                        return true;
 void weakness(int u, int p = -1) {
                                                                    vis[u] = 2;
   tin[u] = fup[u] = ++timer;
                                                                    return false;
   int children = 0;
                                                                  }
   for (int v : graph[u]) if (v != p) {
                                                                 5.7 Isomorphism \mathcal{O}(V+E)
    if (!tin[v]) {
                                                                  lli f(lli x) {
       ++children;
       weakness(v, u);
                                                                    // K * n <= 9e18
       fup[u] = min(fup[u], fup[v]);
                                                                    static uniform_int_distribution<lli>uid(1, K);
       if (fup[v] >= tin[u] \&\& !(p == -1 \&\& children < 2))
                                                                    if (!mp.count(x))
            // u is a cutpoint
                                                                      mp[x] = uid(rng);
       if (fup[v] > tin[u]) // bridge u -> v
                                                                    return mp[x];
     }
```

```
lli hsh(int u, int p = -1) {
  dp[u] = h[u] = 0;
  for (int v : graph[u]) {
    if (v == p)
       continue;
    dp[u] += hsh(v, u);
  }
  return h[u] = f(dp[u]);
}
```

## 5.8 Dynamic connectivity $\mathcal{O}((N+Q) \cdot logQ)$

```
struct DynamicConnectivity {
 struct Query {
   int op, u, v, at;
 };
 Dsu dsu; // with rollback
 vector<Query> queries;
 map<ii, int> mp;
 int timer = -1;
 DynamicConnectivity(int n = 0) : dsu(n) {}
 void add(int u, int v) {
   mp[minmax(u, v)] = ++timer;
   queries.pb({'+', u, v, INT_MAX});
 void rem(int u, int v) {
   int in = mp[minmax(u, v)];
   queries.pb({'-', u, v, in});
   queries[in].at = ++timer;
   mp.erase(minmax(u, v));
 }
 void query() {
   queries.push_back({'?', -1, -1, ++timer});
 }
 void solve(int 1, int r) {
   if (1 == r) {
     if (queries[1].op == '?') // solve the query here
     return;
   int m = (1 + r) >> 1;
   int before = sz(dsu.mem);
    for (int i = m + 1; i <= r; i++) {</pre>
     Query &q = queries[i];
      if (q.op == '-' && q.at < 1)
        dsu.unite(q.u, q.v);
   }
    solve(1, m);
   while (sz(dsu.mem) > before)
      dsu.rollback();
    for (int i = 1; i <= m; i++) {
      Query &q = queries[i];
      if (q.op == '+' \&\& q.at > r)
        dsu.unite(q.u, q.v);
   solve(m + 1, r);
   while (sz(dsu.mem) > before)
      dsu.rollback();
 }
};
```

## Tree queries

# 6.1 Euler tour for Mo's in a tree $\mathcal{O}((V+E)\cdot \sqrt{V})$

Mo's in a tree, extended euler tour tin[u] = ++timer, tout[u] = ++timer

- u = lca(u, v), query(tin[u], tin[v])
- $u \neq lca(u, v)$ , query(tout[u], tin[v]) + query(tin[lca], tin[lca])

## 6.2 Lowest common ancestor (LCA)

```
build: \mathcal{O}(N \cdot log N), query: \mathcal{O}(log N)
 const int LogN = 1 + _{lg(N)};
 int par[LogN][N], dep[N];
 void dfs(int u, int par[]) {
   for (int v : graph[u])
     if (v != par[u]) {
       par[v] = u;
       dep[v] = dep[u] + 1;
       dfs(v, par);
 }
 int lca(int u, int v){
   if (dep[u] > dep[v])
     swap(u, v);
   fore (k, LogN, 0)
     if (dep[v] - dep[u] >= (1 << k))
       v = par[k][v];
   if (u == v)
     return u;
   fore (k, LogN, 0)
     if (par[k][v] != par[k][u])
       u = par[k][u], v = par[k][v];
   return par[0][u];
 }
 int dist(int u, int v) {
   return dep[u] + dep[v] - 2 * dep[lca(u, v)];
 }
 void init(int r) {
   dfs(r, par[0]);
   fore (k, 1, LogN)
     fore (u, 1, n + 1)
       par[k][u] = par[k - 1][par[k - 1][u]];
 }
```

## 6.3 Virtual tree

```
build: \mathcal{O}(|ver| \cdot log N)
vector<int> virt[N];
 int virtualTree(vector<int> &ver) {
   auto byDfs = [&](int u, int v) {
     return tin[u] < tin[v];</pre>
   sort(all(ver), byDfs);
   fore (i, sz(ver), 1)
     ver.pb(lca(ver[i - 1], ver[i]));
   sort(all(ver), byDfs);
   ver.erase(unique(all(ver)), ver.end());
   for (int u : ver)
     virt[u].clear();
   fore (i, 1, sz(ver))
     virt[lca(ver[i - 1], ver[i])].pb(ver[i]);
   return ver[0];
 }
```

#### 6.4 Guni

```
Solve subtrees problems \mathcal{O}(N \cdot log N \cdot F)
 int cnt[C], color[N];
 int sz[N];
 int guni(int u, int p = -1) {
   sz[u] = 1;
   for (int &v : graph[u]) if (v != p) {
     sz[u] += guni(v, u);
     if (sz[v] > sz[graph[u][0]] || p == graph[u][0])
       swap(v, graph[u][0]);
   }
   return sz[u];
 void add(int u, int p, int x, bool skip) {
   cnt[color[u]] += x;
   for (int i = skip; i < sz(graph[u]); i++) // don't change</pre>
         it with a fore!!
     if (graph[u][i] != p)
       add(graph[u][i], u, x, 0);
 }
 void solve(int u, int p = -1, bool keep = 0) {
   fore (i, sz(graph[u]), 0)
     if (graph[u][i] != p)
       solve(graph[u][i], u, !i);
   add(u, p, +1, 1); // add
   // now cnt[i] has how many times the color i appears in
        the subtree of u
   if (!keep) add(u, p, -1, 0); // remove
 }
```

## 6.5 Centroid decomposition

```
Solves "all pairs of nodes" problems \mathcal{O}(N \cdot log N \cdot F)
 int cdp[N], sz[N];
 bitset<N> rem;
 int dfsz(int u, int p = -1) {
   sz[u] = 1;
   for (int v : graph[u])
     if (v != p && !rem[v])
       sz[u] += dfsz(v, u);
   return sz[u];
 int centroid(int u, int n, int p = -1) {
   for (int v : graph[u])
     if (v != p && !rem[v] && 2 * sz[v] > n)
       return centroid(v, n, u);
   return u;
 }
 void solve(int u, int p = -1) {
   cdp[u = centroid(u, dfsz(u))] = p;
   rem[u] = true;
   for (int v : graph[u])
     if (!rem[v])
       solve(v, u);
 }
```

# 6.6 Heavy-light decomposition and Euler tour

```
Solves subtrees and paths problems \mathcal{O}(N \cdot log N \cdot F) int par[N], nxt[N], dep[N], sz[N]; int tin[N], tout[N], who[N], timer = 0; Lazy *tree;
```

```
int dfs(int u) {
 for (auto &v : graph[u]) if (v != par[u]) {
   par[v] = u;
   dep[v] = dep[u] + 1;
    sz[u] += dfs(v);
    if (graph[u][0] == par[u] || sz[v] > sz[graph[u][0]])
      swap(v, graph[u][0]);
 }
 return sz[u];
void hld(int u) {
  tin[u] = ++timer;
  who[timer] = u;
  for (auto &v : graph[u]) if (v != par[u]) {
   nxt[v] = (v == graph[u][0] ? nxt[u] : v);
   hld(v);
  tout[u] = timer;
template <class F>
void processPath(int u, int v, F f) {
  for (; nxt[u] != nxt[v]; u = par[nxt[u]]) {
    if (dep[nxt[u]] < dep[nxt[v]]) swap(u, v);</pre>
    f(tin[nxt[u]], tin[u]);
  }
  if (dep[u] < dep[v]) swap(u, v);</pre>
 f(tin[v] + overEdges, tin[u]); // overEdges???
void updatePath(int u, int v, lli z) {
  processPath(u, v, [&](int 1, int r) {
    tree->update(1, r, z);
 });
}
void updateSubtree(int u, lli z) {
  tree->update(tin[u], tout[u], z);
}
1li queryPath(int u, int v) {
 11i sum = 0;
  processPath(u, v, [&](int 1, int r) {
   sum += tree->query(1, r);
 });
 return sum;
}
1li querySubtree(int u) {
 return tree->query(tin[u], tout[u]);
int lca(int u, int v) {
 int last = -1;
 processPath(u, v, [&](int 1, int r) {
   last = who[1];
 });
 return last;
}
```

#### 6.7 Link-Cut tree

Solves dynamic trees problems, can handle subtrees and paths maybe with a high constant  $\mathcal{O}(N \cdot log N \cdot F)$ 

```
typedef struct Node* Splay;
struct Node {
   Splay left = 0, right = 0, par = 0;
   bool rev = 0;
   int sz = 1;
```

```
int sub = 0, vsub = 0; // subtree
  int path = 0; // path
  int self = 0; // node info
  void push() {
   if (rev) {
      swap(left, right);
      if (left) left->rev ^= 1;
      if (right) right->rev ^= 1;
      rev = 0;
   }
  }
  void pull() {
    #define sub(u) (u ? u->sub : 0)
    #define path(u) (u ? u->path : 0)
    #define sz(u) (u ? u->sz : 0)
    sz = 1 + sz(left) + sz(right);
    sub = vsub + sub(left) + sub(right) + self;
    path = path(left) + self + path(right);
  void virSub(Splay v, int add) {
    vsub += 1LL * add * sub(v);
  }
};
void splay(Splay u) {
  auto assign = [&](Splay u, Splay v, bool d) {
    (d == 0 ? u \rightarrow left : u \rightarrow right) = v;
    if (v) v->par = u;
  auto dir = [&](Splay u) {
    Splay p = u->par;
    if (!p) return -1;
    return p->left == u ? 0 : (p->right == u ? 1 : -1);
  };
  auto rotate = [&](Splay u) {
    Splay p = u->par, g = p->par;
    int d = dir(u);
    assign(p, d ? u->left : u->right, d);
    if (dir(p) == -1) u->par = g;
    else assign(g, u, dir(p));
    assign(u, p, !d);
    p->pull(), u->pull();
  };
  while (~dir(u)) {
    Splay p = u-par, g = p-par;
    if (~dir(p)) g->push();
    p->push(), u->push();
    if (~dir(p)) rotate(dir(p) == dir(u) ? p : u);
    rotate(u);
  u->push(), u->pull();
}
void access(Splay u) {
  Splay last = 0;
  for (Splay v = u; v; last = v, v = v->par) {
    splay(v);
    v->virSub(v->right, +1);
    v->virSub(v->right = last, -1);
    v->pull();
  }
  splay(u);
}
void reroot(Splay u) {
  access(u);
  u->rev ^= 1;
```

```
}
 void link(Splay u, Splay v) {
   reroot(v), access(u);
   u \rightarrow virSub(v, +1);
   v->par = u;
   u->pull();
 }
 void cut(Splay u, Splay v) {
   reroot(v), access(u);
   u \rightarrow left = 0, v \rightarrow par = 0;
   u->pull();
 }
 Splay lca(Splay u, Splay v) {
   if (u == v) return u;
   access(u), access(v);
   if (!u->par) return 0;
   return splay(u), u->par ?: u;
 }
 Splay queryPath(Splay u, Splay v) {
   return reroot(u), access(v), v; // path
 Splay querySubtree(Splay u, Splay x) {
   // query subtree of u where x is outside
   return reroot(x), access(u), u; // vsub + self
      Flows
7
       Dinic \mathcal{O}(min(E \cdot flow, V^2E))
7.1
If the network is massive, try to compress it by looking for patterns.
 template <class F>
 struct Dinic {
   struct Edge {
     int v, inv;
     F cap, flow;
     Edge(int v, F cap, int inv) : v(v), cap(cap), flow(∅),
          inv(inv) {}
   F eps = (F) 1e-9;
   int s, t, n;
   vector<vector<Edge>> graph;
   vector<int> dist, ptr;
   Dinic(int n): n(n), graph(n), dist(n), ptr(n), s(n - 2),
         t(n - 1) {}
   void add(int u, int v, F cap) {
     graph[u].pb(\underline{Edge}(v, cap, sz(graph[v])));
     graph[v].pb(Edge(u, 0, sz(graph[u]) - 1));
   bool bfs() {
     fill(all(dist), -1);
     queue<int> qu({s});
     dist[s] = 0;
     while (sz(qu) \&\& dist[t] == -1) {
       int u = qu.front();
       qu.pop();
       for (Edge &e : graph[u]) if (dist[e.v] == -1)
         if (e.cap - e.flow > eps) {
           dist[e.v] = dist[u] + 1;
```

qu.push(e.v);

```
}
                                                                       while (sz(qu)) {
     return dist[t] != -1;
                                                                         int u = qu.front();
   }
                                                                         qu.pop_front();
                                                                         state[u] = 2;
                                                                         for (Edge &e : graph[u]) if (e.cap - e.flow > eps)
   F dfs(int u, F flow = numeric_limits<F>::max()) {
     if (flow <= eps || u == t)</pre>
                                                                           if (cost[u] + e.cost < cost[e.v]) {</pre>
       return max<F>(0, flow);
                                                                             cost[e.v] = cost[u] + e.cost;
     for (int &i = ptr[u]; i < sz(graph[u]); i++) {</pre>
                                                                             prev[e.v] = &e;
                                                                             if (state[e.v] == 2 || (sz(qu) && cost[qu.front()
       Edge &e = graph[u][i];
       if (e.cap - e.flow > eps && dist[u] + 1 == dist[e.v])
                                                                                  ] > cost[e.v]))
                                                                               qu.push_front(e.v);
        F pushed = dfs(e.v, min<F>(flow, e.cap - e.flow));
                                                                             else if (state[e.v] == 0)
         if (pushed > eps) {
                                                                               qu.push_back(e.v);
           e.flow += pushed;
                                                                             state[e.v] = 1;
           graph[e.v][e.inv].flow -= pushed;
                                                                           }
           return pushed;
                                                                       }
         }
                                                                       return cost[t] != numeric_limits<C>::max();
       }
     }
     return 0;
                                                                     pair<C, F> minCostFlow() {
                                                                       C cost = 0; F flow = 0;
                                                                       while (bfs()) {
   F maxFlow() {
                                                                         F pushed = numeric_limits<F>::max();
     F flow = 0;
                                                                         for (Edge* e = prev[t]; e != nullptr; e = prev[e->u])
     while (bfs()) {
                                                                           pushed = min(pushed, e->cap - e->flow);
       fill(all(ptr), 0);
                                                                         for (Edge* e = prev[t]; e != nullptr; e = prev[e->u])
       while (F pushed = dfs(s))
                                                                               {
         flow += pushed;
                                                                           e->flow += pushed;
     }
                                                                           graph[e->v][e->inv].flow -= pushed;
     return flow;
                                                                           cost += e->cost * pushed;
                                                                         flow += pushed;
   bool leftSide(int u) {
     // left side comes from sink
                                                                       return make_pair(cost, flow);
     return dist[u] != -1;
                                                                     }
   }
                                                                  };
};
                                                                         Hopcroft-Karp \mathcal{O}(E\sqrt{V})
                                                                  7.3
       Min cost flow \mathcal{O}(min(E \cdot flow, V^2E))
7.2
                                                                   struct HopcroftKarp {
If the network is massive, try to compress it by looking for patterns.
                                                                     int n. m:
 template <class C, class F>
                                                                     vector<vector<int>> graph;
 struct Mcmf {
                                                                     vector<int> dist, match;
   struct Edge {
     int u, v, inv;
                                                                     HopcroftKarp(int k) : n(k + 1), graph(n), dist(n), match(
     F cap. flow:
                                                                         n, 0) {} // 1-indexed!!
     C cost:
     Edge(int u, int v, C cost, F cap, int inv) : u(u), v(v)
                                                                     void add(int u, int v) {
          , cost(cost), cap(cap), flow(₀), inv(inv) {}
                                                                       graph[u].pb(v), graph[v].pb(u);
   };
   F eps = (F) 1e-9;
                                                                     bool bfs() {
                                                                       queue<int> qu;
   int s, t, n;
   vector<vector<Edge>> graph;
                                                                       fill(all(dist), -1);
                                                                       fore (u, 1, n) if (!match[u])
   vector<Edge*> prev;
   vector<C> cost;
                                                                         dist[u] = 0, qu.push(u);
   vector<int> state;
                                                                       while (!qu.empty()) {
                                                                         int u = qu.front(); qu.pop();
   Mcmf(int n) : n(n), graph(n), cost(n), state(n), prev(n),
                                                                         for (int v : graph[u])
         s(n - 2), t(n - 1) {}
                                                                           if (dist[match[v]] == -1) {
                                                                             dist[match[v]] = dist[u] + 1;
   void add(int u, int v, C cost, F cap) {
                                                                             if (match[v]) qu.push(match[v]);
     graph[u].pb(Edge(u, v, cost, cap, sz(graph[v])));
     graph[v].pb(Edge(v, u, -cost, 0, sz(graph[u]) - 1));
   }
                                                                       return dist[0] != -1;
   bool bfs() {
     fill(all(state), 0);
                                                                     bool dfs(int u) {
     fill(all(cost), numeric_limits<C>::max());
                                                                       for (int v : graph[u])
     deque<int> qu;
                                                                         if (!match[v] || (dist[u] + 1 == dist[match[v]] &&
     qu.push_back(s);
                                                                              dfs(match[v]))) {
     state[s] = 1, cost[s] = 0;
                                                                           match[u] = v, match[v] = u;
```

```
return 1;
                                                                      }
                                                                    }
       }
     dist[u] = 1 << 30;
     return 0;
                                                                    Hash query(int 1, int r) {
                                                                      return (h[r + 1] - h[l]) * ipw[l];
   }
                                                                    }
   int maxMatching() {
                                                                  };
     int tot = 0;
                                                                   #warning "Ensure all base[i] > alphabet"
     while (bfs())
                                                                  pw[0] = ipw[0] = \{1, 1\};
       fore (u, 1, n)
         tot += match[u] ? 0 : dfs(u);
                                                                  Hash base = \{12367453, 14567893\};
     return tot;
                                                                  Hash inv = {::inv(base[0], base.mod), ::inv(base[1], base.
   }
                                                                       mod) };
};
                                                                   fore (i, 1, N) {
                                                                    pw[i] = pw[i - 1] * base;
7.4
       Hungarian \mathcal{O}(N^3)
                                                                    ipw[i] = ipw[i - 1] * inv;
n jobs, m people
                                                                  }
 template <class C>
 pair<C, vector<int>> Hungarian(vector<vector<C>>> &a) { //
                                                                   // Save len in the struct and when you do a cut
     max assignment
                                                                  Hash merge(vector<Hash> &cuts) {
   int n = sz(a), m = sz(a[0]), p, q, j, k; // n \le m
                                                                    Hash f = \{0, 0\};
  vector<C> fx(n, numeric_limits<C>::min()), fy(m, 0);
                                                                     fore (i, sz(cuts), ∅) {
   vector<int> x(n, -1), y(m, -1);
                                                                      Hash g = cuts[i];
   fore (i, 0, n)
                                                                       f = g + f * pw[g.len];
     fore (j, ∅, m)
                                                                    }
       fx[i] = max(fx[i], a[i][j]);
                                                                    return f;
   fore (i, 0, n) {
                                                                  }
     vector<int> t(m, -1), s(n + 1, i);
                                                                 8.2
                                                                       KMP \mathcal{O}(N)
     for (p = q = 0; p \le q && x[i] < 0; p++)
                                                                 period = n - p[n - 1], period(abcabc) = 3, n \mod period \equiv 0
       for (k = s[p], j = 0; j < m && x[i] < 0; j++)
                                                                  template <class T>
         if (abs(fx[k] + fy[j] - a[k][j]) < eps && t[j] < 0)
                                                                   vector<int> lps(T &s) {
                                                                     vector<int> p(sz(s), ∅);
           s[++q] = y[j], t[j] = k;
                                                                     for (int j = 0, i = 1; i < sz(s); i++) {
           if (s[q] < 0) for (p = j; p >= 0; j = p)
                                                                       while (j \&\& s[i] != s[j]) j = p[j - 1];
             y[j] = k = t[j], p = x[k], x[k] = j;
                                                                       if (s[i] == s[j]) j++;
                                                                      p[i] = j;
     if (x[i] < 0) {
                                                                     }
       C d = numeric_limits<C>::max();
                                                                     return p;
       fore (k, 0, q + 1)
                                                                  }
         fore (j, 0, m) if (t[j] < 0)
           d = min(d, fx[s[k]] + fy[j] - a[s[k]][j]);
                                                                   // positions where t is on s
       fore (j, 0, m)
                                                                  template <class T>
         fy[j] += (t[j] < 0 ? 0 : d);
                                                                  vector<int> kmp(T &s, T &t) {
       fore (k, 0, q + 1)
                                                                     vector<int> p = lps(t), pos;
         fx[s[k]] = d;
                                                                     for (int j = 0, i = 0; i < sz(s); i++) {
                                                                       while (j \&\& s[i] != t[j]) j = p[j - 1];
     }
                                                                       if (s[i] == t[j]) j++;
   }
                                                                      if (j == sz(t)) pos.pb(i - sz(t) + 1);
   C cost = 0;
                                                                    }
   fore (i, 0, n) cost += a[i][x[i]];
                                                                     return pos;
   return make_pair(cost, x);
                                                                  }
 }
                                                                 8.3
                                                                       KMP automaton \mathcal{O}(Alphabet \cdot N)
8
     Strings
                                                                  int go[N][A];
       Hash \mathcal{O}(N)
                                                                  void kmpAutomaton(string &s) {
 struct Hash : array<int, 2> {
                                                                    s += "$";
   static constexpr int mod = 1e9 + 7;
                                                                     vi p = lps(s);
 #define oper(op) friend Hash operator op (Hash a, Hash b) {
                                                                     fore (i, 0, sz(s))
       fore (i, 0, sz(a)) a[i] = (1LL * a[i] op b[i] + mod)
                                                                       fore (c, 0, A) {
      % mod; return a; }
                                                                         if (i && s[i] != 'a' + c)
   oper(+) oper(-) oper(*)
                                                                           go[i][c] = go[p[i - 1]][c];
 } pw[N], ipw[N];
                                                                         else
                                                                           go[i][c] = i + ('a' + c == s[i]);
 struct Hashing {
                                                                       }
   vector<Hash> h;
                                                                    s.pop_back();
                                                                  }
   Hashing(string &s) : h(sz(s) + 1) {
                                                                 8.4
                                                                       Z algorithm \mathcal{O}(N)
     fore (i, 0, sz(s)) {
       int x = s[i] - 'a' + 1;
                                                                  template <class T>
       h[i + 1] = h[i] + pw[i] * Hash{x, x};
                                                                  vector<int> getZ(T &s) {
```

```
vector<int> z(sz(s), 0);
                                                                          }
   for (int i = 1, l = 0, r = 0; i < sz(s); i++) {
                                                                      }
     if (i \le r) z[i] = min(r - i + 1, z[i - 1]);
     while (i + z[i] < sz(s) \&\& s[i + z[i]] == s[z[i]]) ++z[
                                                                      int lcp(int 1, int r) {
                                                                        int k = __lg(r - ++l + 1);
          il:
     if (i + z[i] - 1 > r) l = i, r = i + z[i] - 1;
                                                                        return min(sp[k][1], sp[k][r - (1 << k) + 1]);
   }
   return z;
 }
                                                                      auto at(int i, int j) {
       Manacher algorithm \mathcal{O}(N)
8.5
 template <class T>
 vector<vi> manacher(T &s) {
                                                                      int count(T &t) {
   vector<vi> pal(2, vi(sz(s), 0));
   fore (k, 0, 2) {
                                                                        fore (i, 0, sz(t)) {
     int 1 = 0, r = 0;
                                                                          int p = 1, q = r;
     fore (i, 0, sz(s)) {
       int t = r - i + !k;
       if (i < r) pal[k][i] = min(t, pal[k][l + t]);</pre>
       int p = i - pal[k][i], q = i + pal[k][i] - !k;
       while (p \ge 1 \& q + 1 < sz(s) \& s[p - 1] == s[q + 1]
         ++pal[k][i], --p, ++q;
       if (q > r) 1 = p, r = q;
                                                                               return 0;
                                                                        }
   }
                                                                        return r - 1 + 1;
   return pal;
 }
       Suffix array \mathcal{O}(N \cdot log N)
8.6
  • Duplicates \sum_{i=1}^{n} lcp[i]
  • Longest Common Substring of various strings
    Add not Used characters between strings, i.e. a + \$ + b + \# + c
    Use two-pointers to find a range [l, r] such that all notUsed
    characters are present, then query(lcp[l+1],..,lcp[r]) for
    that window is the common length.
                                                                   };
 template <class T>
                                                                  8.7
 struct SuffixArray {
   int n;
   vector<int> sa, rank;
   vector<vi> sp;
   SuffixArray(const T &x) : n(sz(x) + 1), s(x), sa(n), rank
        (n), sp(1 + _lg(n), vi(n, 0)) {
     s.pb(0):
     fore (i, 0, n) sa[i] = i, rank[i] = s[i];
     vector<int> nsa(n), cnt(max(260, n));
     for (int k = 0; k < n && rank[sa[n - 1]] != n - 1; k ?</pre>
          k *= 2 : k++) {
       fill(all(cnt), 0);
```

fore (i, 0, n) nsa[i] = (sa[i] - k + n) % n, cnt[rank

if (prev[sa[i]] != prev[sa[i - 1]] || prev[(sa[i] +

k) % n] != prev[(sa[i - 1] + k) % n]) r++;

fore (i, n, 0) sa[--cnt[rank[nsa[i]]] = nsa[i];

for (int i = 0, j = rank[0], k = 0; i < n - 1; i++, k

sp[k][1] = min(sp[k - 1][1], sp[k - 1][r]);

while (k >= 0 && s[i] != s[sa[j - 1] + k]) sp[0][j] = k--, j = rank[sa[j] + 1];

for (int k = 1; (1 << k) < n; k++) fore (1, 0, n - (1 << (k - 1))) {

int r = 1 + (1 << (k - 1));

[i]]++;

vector<int> prev(rank);

rank[sa[i]] = r;

} }

++)

partial\_sum(all(cnt), cnt.begin());

for (int i = 1, r = 0; i < n; i++) {

```
return sa[i] + j < n ? s[sa[i] + j] : 'z' + 1;</pre>
    int 1 = 0, r = n - 1;
      for (int k = n; k > 0; k >>= 1) {
        while (p + k < r \&\& at(p + k, i) < t[i]) p += k;
        while (q - k > 1 \&\& t[i] < at(q - k, i)) q -= k;
      l = (at(p, i) == t[i] ? p : p + 1);
      r = (at(q, i) == t[i] ? q : q - 1);
      if (at(l, i) != t[i] && at(r, i) != t[i] || l > r)
  bool compare(ii a, ii b) {
    // s[a.f ... a.s] < s[b.f ... b.s]
    ii range = minmax(rank[a.f], rank[b.f]);
    int common = lcp(range.f, range.s);
    int szA = a.s - a.f + 1, szB = b.s - b.f + 1;
    if (common >= min(szA, szB)) return szA < szB;</pre>
    return rank[a.f] < rank[b.f];</pre>
      Suffix automaton \mathcal{O}(\sum s_i)
 • sam[u].len - sam[sam[u].link].len = distinct strings
 • Number of different substrings (dp)
        diff(u) = 1 + \sum_{v \in trie[u]} diff(v)
 • Total length of all different substrings (2 x dp)
        totLen(u) = \sum_{v \in trie[u]} diff(v) + totLen(v)
 • Leftmost occurrence trie[u].pos = trie[u].len - 1
   if it is {\bf clone} then trie[clone].pos = trie[q].pos
 • All occurrence positions
 • Smallest cyclic shift Construct sam of s + s, find the lexico-
    graphically smallest path of sz(s)

    Shortest non-appearing string

        nonAppearing(u) = \min_{v \in trie[u]} nonAppearing(v) + 1
struct SuffixAutomaton {
  struct Node : map<char, int> {
    int link = -1, len = 0;
  vector<Node> trie;
  int last;
  SuffixAutomaton() { last = newNode(); }
  int newNode() {
    trie.pb({});
    return sz(trie) - 1;
```

```
}
void extend(char c) {
 int u = newNode();
 trie[u].len = trie[last].len + 1;
 int p = last;
 while (p != -1 && !trie[p].count(c)) {
   trie[p][c] = u;
   p = trie[p].link;
 if (p == -1)
   trie[u].link = 0;
 else {
    int q = trie[p][c];
    if (trie[p].len + 1 == trie[q].len)
      trie[u].link = q;
   else {
      int clone = newNode();
      trie[clone] = trie[q];
      trie[clone].len = trie[p].len + 1;
      while (p != -1 \&\& trie[p][c] == q) {
        trie[p][c] = clone;
        p = trie[p].link;
      }
      trie[q].link = trie[u].link = clone;
   }
 }
 last = u:
}
string kthSubstring(lli kth, int u = 0) {
 // number of different substrings (dp)
 string s = "";
 while (kth > 0)
   for (auto &[c, v] : trie[u]) {
      if (kth <= diff(v)) {</pre>
        s.pb(c), kth--, u = v;
       break;
      }
     kth -= diff(v);
   }
 return s;
}
void occurs() {
 // trie[u].occ = 1, trie[clone].occ = 0
 vi who;
 fore (u, 1, sz(trie))
   who.pb(u);
 sort(all(who), [&](int u, int v) {
   return trie[u].len > trie[v].len;
  for (int u : who) {
   int 1 = trie[u].link;
    trie[1].occ += trie[u].occ;
 }
}
1li queryOccurences(string &s, int u = 0) {
  for (char c : s) {
   if (!trie[u].count(c))
      return 0;
   u = trie[u][c];
 }
  return trie[u].occ;
}
int longestCommonSubstring(string &s, int u = 0) {
 int mx = 0, clen = 0;
 for (char c : s) {
```

```
while (u && !trie[u].count(c)) {
        u = trie[u].link;
        clen = trie[u].len;
      if (trie[u].count(c))
        u = trie[u][c], clen++;
      mx = max(mx, clen);
    }
    return mx;
  string smallestCyclicShift(int n, int u = 0) {
    string s = "";
    fore (i, 0, n) {
      char c = trie[u].begin()->f;
      s += c;
     u = trie[u][c];
    }
    return s;
  int leftmost(string &s, int u = 0) {
    for (char c : s) {
      if (!trie[u].count(c))
        return -1;
      u = trie[u][c];
    }
    return trie[u].pos - sz(s) + 1;
  Node& operator [](int u) {
    return trie[u];
};
      Aho corasick \mathcal{O}(\sum s_i)
struct AhoCorasick {
  struct Node : map<char, int> {
    int link = 0, out = 0;
    int cnt = 0, isw = 0;
  vector<Node> trie;
  AhoCorasick() { newNode(); }
  int newNode() {
    trie.pb({});
    return sz(trie) - 1;
  void insert(string &s, int u = 0) {
    for (char c : s) {
      if (!trie[u][c])
        trie[u][c] = newNode();
      u = trie[u][c];
    }
    trie[u].cnt++, trie[u].isw = 1;
  int go(int u, char c) {
    while (u && !trie[u].count(c))
      u = trie[u].link;
    return trie[u][c];
  void pushLinks() {
    queue<int> qu;
    qu.push(∅);
    while (!qu.empty()) {
      int u = qu.front();
```

```
Dynamic Programming
      qu.pop();
      for (auto &[c, v] : trie[u]) {
                                                                9.1
                                                                       All submasks of a mask
        int l = (trie[v].link = u ? go(trie[u].link, c) : 0
                                                                  for (int B = A; B > 0; B = (B - 1) & A)
            );
        trie[v].cnt += trie[l].cnt;
                                                                       Matrix Chain Multiplication
        trie[v].out = trie[l].isw ? l : trie[l].out;
                                                                 int dp(int 1, int r) {
        qu.push(v);
                                                                    if (1 > r)
      }
                                                                      return 0LL:
   }
                                                                    int &ans = mem[l][r];
                                                                    if (!done[l][r]) {
                                                                      done[l][r] = true, ans = inf;
  int match(string &s, int u = 0) {
                                                                      fore (k, l, r + 1) // split in [l, k] [k + 1, r]
    int ans = 0;
                                                                        ans = min(ans, dp(1, k) + dp(k + 1, r) + add);
    for (char c : s) {
      u = go(u, c);
                                                                   return ans;
      ans += trie[u].cnt;
                                                                 }
      for (int x = u; x != 0; x = trie[x].out)
                                                                       Digit DP
                                                                9.3
        // pass over all elements of the implicit vector
    }
                                                                Counts the amount of numbers in [l, r] such are divisible by k.
    return ans;
                                                                (flag nonzero is for different lengths)
  }
                                                                It can be reduced to dp(i, x, small), and has to be solve like f(r) –
                                                                f(l-1)
 Node& operator [](int u) {
    return trie[u];
                                                                 #define state [i][x][small][big][nonzero]
                                                                 int dp(int i, int x, bool small, bool big, bool nonzero) {
  }
                                                                    if (i == sz(r))
};
                                                                      return x % k == 0 && nonzero;
                                                                    int &ans = mem state;
      Eertree \mathcal{O}(\sum s_i)
                                                                    if (done state != timer) {
struct Eertree {
                                                                     done state = timer;
  struct Node : map<char, int> {
                                                                     ans = 0;
    int link = 0, len = 0;
                                                                     int lo = small ? 0 : 1[i] - '0';
  }:
                                                                      int hi = big ? 9 : r[i] - '0';
                                                                      fore (y, lo, max(lo, hi) + 1) {
                                                                        bool small2 = small | (y > lo);
  vector<Node> trie;
  string s = "$";
                                                                       bool big2 = big | (y < hi);
  int last;
                                                                       bool nonzero2 = nonzero | (x > 0);
                                                                       ans += dp(i + 1, (x * 10 + y) % k, small2, big2,
 Eertree() {
   last = newNode(), newNode();
    trie[0].link = 1, trie[1].len = -1;
                                                                   }
  }
                                                                    return ans;
                                                                 }
  int newNode() {
    trie.pb({});
                                                                       Knapsack 0/1
    return sz(trie) - 1;
                                                                 for (auto &cur : items)
                                                                    fore (w, W + 1, cur.w) // [cur.w, W]
                                                                     umax(dp[w], dp[w - cur.w] + cur.cost);
  int go(int u) {
    while (s[sz(s) - trie[u].len - 2] != s.back())
                                                                       Convex Hull Trick \mathcal{O}(n^2) \Rightarrow \mathcal{O}(n)
                                                                9.5
      u = trie[u].link;
    return u;
                                                                dp[i] = \min_{j < i} (dp[j] + b[j] * a[i])
  }
                                                                dp[i][j] = \min_{k < j} (dp[i-1][k] + b[k] * a[j])
                                                                b[j] \ge b[j+1] optionally a[i] \le a[i+1]
  void extend(char c) {
                                                                 // for doubles, use INF = 1/.0, div(a,b) = a / b
    s += c;
                                                                 struct Line {
    int u = go(last);
                                                                    mutable lli m, c, p;
    if (!trie[u][c]) {
                                                                    bool operator < (const Line &l) const { return m < l.m; }</pre>
      int v = newNode();
                                                                    bool operator < (lli x) const { return p < x; }</pre>
      trie[v].len = trie[u].len + 2;
                                                                   lli operator ()(lli x) const { return m * x + c; }
      trie[v].link = trie[go(trie[u].link)][c];
                                                                 };
      trie[u][c] = v;
    }
                                                                 template <bool Max>
    last = trie[u][c];
                                                                 struct DynamicHull : multiset<Line, less<>>> {
  }
                                                                   lli div(lli a, lli b) {
                                                                     return a / b - ((a ^ b) < 0 && a % b);
  Node& operator [](int u) {
                                                                    }
    return trie[u];
  }
                                                                    bool isect(iterator x, iterator y) {
};
                                                                      if (y == end()) return x -> p = INF, 0;
```

```
if (x->m == y->m) x->p = x->c > y->c ? INF : -INF;
    else x->p = div(x->c - y->c, y->m - x->m);
    return x->p >= y->p;
  void add(lli m, lli c) {
    if (!Max) m = -m, c = -c;
    auto z = insert(\{m, c, \emptyset\}), y = z++, x = y;
    while (isect(y, z)) z = erase(z);
    if (x != begin() && isect(--x, y))
      isect(x, y = erase(y));
    while ((y = x) != begin() && (--x)->p >= y->p)
      isect(x, erase(y));
 lli query(lli x) {
    if (empty()) return 0LL;
    auto f = *lower_bound(x);
    return Max ? f(x) : -f(x);
  }
};
```

## **9.6** Divide and conquer $\mathcal{O}(kn^2) \Rightarrow \mathcal{O}(k \cdot nlogn)$

Split the array of size n into k continuous groups.  $k \le n$   $cost(a,c) + cost(b,d) \le cost(a,d) + cost(b,c)$  with  $a \le b \le c \le d$ 

```
void solve(int cut, int 1, int r, int optl, int optr) {
   if (r < 1)
      return;
   int mid = (1 + r) / 2;
   pair<lli, int> best = {INF, -1};
   fore (p, optl, min(mid, optr) + 1)
      best = min(best, {dp[~cut & 1][p - 1] + cost(p, mid), p
      });
   dp[cut & 1][mid] = best.f;
   solve(cut, 1, mid - 1, optl, best.s);
   solve(cut, mid + 1, r, best.s, optr);
}

fore (i, 1, n + 1)
   dp[1][i] = cost(1, i);
fore (cut, 2, k + 1)
   solve(cut, cut, n, cut, n);
```

## 9.7 Knuth optimization $\mathcal{O}(n^3) \Rightarrow \mathcal{O}(n^2)$

```
dp[l][r] = \min_{l < k < r} \{dp[l][k] + dp[k][r]\} + cost(l, r)
 fore (len, 1, n + 1)
   fore (1, 0, n) {
     int r = 1 + len - 1;
     if (r > n - 1)
       break;
     if (len <= 2) {
       dp[1][r] = 0;
       opt[l][r] = 1;
       continue;
     dp[1][r] = inf;
     fore (k, opt[l][r - 1], opt[l + 1][r] + 1) {
       lli cur = dp[1][k] + dp[k][r] + cost(1, r);
       if (cur < dp[l][r]) {</pre>
         dp[1][r] = cur;
         opt[1][r] = k;
     }
   }
```

## 10 Game Theory

## 10.1 Grundy Numbers

If the moves are consecutive  $S = \{1, 2, 3, ..., x\}$  the game can be solved like  $stackSize \pmod{x+1} \neq 0$ 

```
int mem[N];
int mex(set<int> &st) {
  int x = 0;
  while (st.count(x))
    χ++;
  return x;
}
int grundy(int n) {
  if (n < 0)
    return inf;
  if (n == 0)
    return 0;
  int &g = mem[n];
  if (g == -1) {
    set<int> st;
    for (int x : {a, b})
      st.insert(grundy(n - x));
    g = mex(st);
  }
  return g;
}
```

#### 11 Math

Math table				
Number	Factorial	Catalan		
0	1	1		
1	1	1		
2	2	2		
3	6	5		
4	24	14		
5	120	42		
6	720	132		
7	5,040	429		
8	40,320	1,430		
9	362,880	4,862		
10	3,628,800	16,796		
11	39,916,800	58,786		
12	479,001,600	208,012		
13	6,227,020,800	742,900		

#### 11.1 Factorial

```
void factorial(int n) {
  fac[0] = 1LL;
  fore (i, 1, n)
     fac[i] = lli(i) * fac[i - 1] % mod;
  ifac[n - 1] = fpow(fac[n - 1], mod - 2);
  fore (i, n - 1, 0)
     ifac[i] = lli(i + 1) * ifac[i + 1] % mod;
}
```

#### 11.2 Factorial mod smallPrime

```
lli facMod(lli n, int p) {
    lli r = 1LL;
    for (; n > 1; n /= p) {
        r = (r * ((n / p) % 2 ? p - 1: 1)) % p;
        fore (i, 2, n % p + 1)
            r = r * i % p;
    }
    return r % p;
}
```

#### 11.3 Lucas theorem

Changes  $\binom{n}{k}$  mod p, with  $n \geq 2e6, k \geq 2e6$  and  $p \leq 1e7$ 

#### 11.4 Stars and bars

}

Enclosing n objects in k boxes

$$\binom{n+k-1}{k-1} = \binom{n+k-1}{n}$$

#### 11.5 N choose K

```
\binom{n}{k} = \binom{n-1}{k-1} + \binom{n-1}{k}
     \binom{n}{k_1, k_2, \dots, k_m} = \frac{n!}{k_1! * k_2! * \dots * k_m!}
 lli choose(int n, int k) {
   if (n < 0 || k < 0 || n < k)</pre>
     return 0LL;
   return fac[n] * ifac[k] % mod * ifac[n - k] % mod;
 lli choose(int n, int k) {
   11i r = 1;
   int to = min(k, n - k);
   if (to < 0) return 0;</pre>
   fore (i, 0, to)
     r = r * (n - i) / (i + 1);
   return r;
11.6 Catalan
 catalan[0] = 1LL;
 fore (i, 0, N) {
   catalan[i + 1] = catalan[i] * 11i(4 * i + 2) % mod * fpow
         (i + 2, mod - 2) \% mod;
```

#### 11.7 Burnside's lemma

$$|classes| = \frac{1}{|G|} \cdot \sum_{x \in G} f(x)$$

#### Prime factors of N!

```
vector< pair<lli, int> > factorialFactors(lli n) {
  vector< pair<lli, int> > fac;
  for (lli p : primes) {
    if (n < p)
      break;
    lli mul = 1LL, k = 0;
    while (mul <= n / p) {</pre>
      mul *= p;
      k += n / mul;
    fac.emplace_back(p, k);
  }
  return fac;
}
```

## Number Theory

#### 12.1 Goldbach conjecture

- All number  $\geq 6$  can be written as sum of 3 primes
- All even number > 2 can be written as sum of 2 primes

#### Prime numbers distribution

Amount of primes approximately  $\frac{n}{\ln(n)}$ 

#### Sieve of Eratosthenes $\mathcal{O}(N \cdot loq(loqN))$ 12.3

```
To factorize divide x by factor[x] until is equal to 1
 void factorizeSieve() {
   iota(factor, factor + N, ∅);
   for (int i = 2; i * i < N; i++) if (factor[i] == i)</pre>
     for (int j = i * i; j < N; j += i)</pre>
       factor[j] = i;
 }
 map<int, int> factorize(int n) {
   map<int, int> cnt;
   while (n > 1) {
     cnt[factor[n]]++;
     n /= factor[n];
   }
   return cnt;
 }
Use it if you need a huge amount of phi[x] up to some N
 void phiSieve() {
   isPrime.set();
   iota(phi, phi + N, ∅);
   fore (i, 2, N) if (isPrime[i])
     for (int j = i; j < N; j += i) {
       isPrime[j] = (i == j);
       phi[j] = phi[j] / i * (i - 1);
     }
 }
       Phi of euler \mathcal{O}(\sqrt{N})
 lli phi(lli n) {
   if (n == 1) return 0;
   lli r = n;
   for (11i i = 2; i * i <= n; i++)
     if (n % i == 0) {
       while (n % i == 0) n /= i;
       r -= r / i;
   if (n > 1) r -= r / n;
   return r:
 }
         Miller-Rabin \mathcal{O}(Witnesses \cdot (loq N)^3)
ull mul(ull x, ull y, ull mod) {
   lli ans = x * y - mod * ull(1.L / mod * x * y);
   return ans + mod * (ans < 0) - mod * (ans >= 11i \pmod{});
 }
 // use mul(x, y, mod) inside fpow
bool miller(ull n) {
   if (n < 2 || n % 6 % 4 != 1) return (n | 1) == 3;</pre>
   ull k = \_builtin\_ctzll(n - 1), d = n >> k;
   for (ull p : {2, 325, 9375, 28178, 450775, 9780504, 17952
        65022}) {
     ull x = fpow(p % n, d, n), i = k;
     while (x != 1 && x != n - 1 && p % n && i--)
```

x = mul(x, x, n);

if (x != n - 1 && i != k) return 0;

```
}
   return 1;
 }
       Pollard-Rho \mathcal{O}(N^{1/4})
12.6
ull rho(ull n) {
   auto f = [n](ull x) { return mul(x, x, n) + 1; };
   ull x = 0, y = 0, t = 30, prd = 2, i = 1, q;
   while (t++ % 40 || __gcd(prd, n) == 1) {
     if (x == y) x = ++i, y = f(x);
     if (q = mul(prd, max(x, y) - min(x, y), n)) prd = q;
     x = f(x), y = f(f(y));
   }
   return __gcd(prd, n);
 // if used multiple times, try memorization!!
 // try factoring small numbers with sieve
 void pollard(ull n, map<ull, int> &fac) {
   if (n == 1) return;
   if (miller(n)) {
     fac[n]++;
   } else {
     ull x = rho(n);
     pollard(x, fac);
     pollard(n / x, fac);
   }
 }
         Amount of divisors \mathcal{O}(N^{1/3})
12.7
 ull amountOfDivisors(ull n) {
   ull cnt = 1;
   for (int p : primes) {
     if (1LL * p * p * p > n) break;
     if (n % p == 0) {
       ull k = 0;
       while (n > 1 \& n \% p == 0) n /= p, ++k;
       cnt *= (k + 1);
   }
   ull sq = mysqrt(n); // the last x * x \le n
   if (miller(n)) cnt *= 2;
   else if (sq * sq == n && miller(sq)) cnt *= 3;
   else if (n > 1) cnt *= 4;
   return cnt:
 }
       Bézout's identity
a_1 * x_1 + a_2 * x_2 + \dots + a_n * x_n = g
 g = \gcd(a_1, a_2, ..., a_n)
12.9 GCD
a \le b; gcd(a+k, b+k) = gcd(b-a, a+k)
12.10 LCM
x = p * lcm(a_1, a_2, ..., a_k) + q, 0 \le q \le lcm(a_1, a_2, ..., a_k)
 x \pmod{a_i} \equiv q \pmod{a_i} as a_i \mid lcm(a_1, a_2, ..., a_k)
          Euclid \mathcal{O}(log(a \cdot b))
12.11
 pair<lli, lli> euclid(lli a, lli b) {
   if (b == 0)
     return {1, 0};
   auto p = euclid(b, a % b);
   return {p.s, p.f - a / b * p.s};
         Chinese remainder theorem
 pair<lli, lli> crt(pair<lli,lli> a, pair<lli,lli> b) {
   if (a.s < b.s) swap(a, b);
   auto p = euclid(a.s, b.s);
   11i g = a.s * p.f + b.s * p.s, 1 = a.s / g * b.s;
```

**if** ((b.f - a.f) % g != 0)

```
return {-1, -1}; // no solution
p.f = a.f + (b.f - a.f) % b.s * p.f % b.s / g * a.s;
return {p.f + (p.f < 0) * 1, 1};</pre>
```

## 13 Math

## 13.1 Progressions

## Arithmetic progressions

$$a_n = a_1 + (n-1) * diff$$
  
 $\sum_{i=1}^n a_i = n * \frac{a_1 + a_n}{2}$ 

## Geometric progressions

$$a_n = a_1 * r^{n-1}$$

$$\sum_{k=1}^n a_1 * r^k = a_1 * \left(\frac{r^{n+1}-1}{r-1}\right) : r \neq 1$$

## 13.2 Fpow

```
template <class T>
T fpow(T x, lli n) {
   T r(1);
   for (; n > 0; n >>= 1) {
      if (n & 1) r = r * x;
      x = x * x;
   }
   return r;
}
```

#### 13.3 Fibonacci

$$\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}^n = \begin{bmatrix} fib_{n+1} & fib_n \\ fib_n & fib_{n-1} \end{bmatrix}$$

# 14 Probability

#### 14.1 Conditional

The event A happens and the event B has already happened

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

If independent events

$$P(A|B) = P(A), P(B|A) = P(B)$$

## 14.2 Bayes theorem

$$P(A|B) = \frac{P(B|A) \cdot P(A)}{P(B)}$$

#### 14.3 Binomial

$$B = \binom{n}{x} \cdot p^x \cdot (1-p)^{n-x}$$

n = number of trials

x = number of **success** from n trials

p = probability of success on a single trial

#### 14.4 Geometric

Probability of success at the *nth*-event after failing the others

$$G = (1 - p)^{n-1} \cdot p$$

n = number of trials

p = probability of success on a single trial

#### 14.5 Poisson

$$Po = \frac{\lambda^k \cdot e^{-\lambda}}{k!}$$

 $\lambda=$  number of times an event is expected (occurs / time) k= number of occurring events in the limited period of time

Example: The event happens 4 times per minute and we want k events to happen in 10 minutes, then  $\lambda=4\cdot 10=40$ 

## 14.6 Expected value

$$E_x = \sum_{\forall x} x \cdot p(x)$$

#### 15 Bit tricks

#### 15.1 Xor Basis

```
Keeps the set of all xors among all possible subsets
 template <int D>
 struct XorBasis {
   array<int, D> basis;
   int n = 0;
   XorBasis() { basis.fill(0); }
   bool insert(int x) {
     fore (i, D, 0) if ((x >> i) & 1) {
       if (!basis[i]) {
         basis[i] = x, n++;
         return 1;
       }
       x ^= basis[i];
     }
     return 0;
   }
   int find(int x) {
     // which number is needed to generate x
     // num ^ (num ^ x) = x
     int num = 0;
     fore (i, D, 0) if ((x >> i) & 1) {
       if (!basis[i]) return -1;
       x ^= basis[i];
       num |= (1 << i);
     }
     return num;
   }
   int operator [](lli k) {
     lli tot = (1LL \ll n);
     if (k > tot) return -1;
     int num = 0;
     fore (i, D, 0) if (basis[i]) {
       11i low = tot / 2;
       if ((low < k \& ((num >> i) \& 1) == 0) || (low >= k)
            && ((num >> i) & 1)))
         num ^= basis[i];
       if (low < k) k = low;
       tot /= 2;
     return num;
   }
 };
```

$\mathrm{Bits}++$			
Operations on int	Function		
x & -x	Least significant bit in $x$		
lg(x)	Most significant bit in $x$		
c = x&-x, r = x+c;	Next number after $x$ with same		
(((r^x) » 2)/c)   r	number of bits set		
builtin_	Function		
popcount(x)	Amount of 1's in x		
clz(x)	0's to the <b>left</b> of biggest bit		
ctz(x)	0's to the <b>right</b> of smallest bit		

#### 15.2 Bitset

Bitset <size></size>				
Operation	Function			
_Find_first()	Least significant bit			
$_{\rm Find}_{\rm next(idx)}$	First set bit after index $idx$			
any(), none(), all()	Just what the expression says			
set(), reset(), flip()	Just what the expression says x2			
to_string('.', 'A')	Print 011010 like .AA.A.			

## 16 Geometry

```
const ld eps = 1e-20;
const ld INF = 1e18;
const ld pi = acos(-1.0);
enum {ON = -1, OUT, IN, OVERLAP};

#define eq(a, b) (abs((a) - (b)) <= +eps)
#define neq(a, b) (!eq(a, b))
#define geq(a, b) ((a) - (b) >= -eps)
#define leq(a, b) ((a) - (b) <= +eps)
#define ge(a, b) ((a) - (b) > +eps)
#define le(a, b) ((a) - (b) < -eps)

int sgn(ld a) {
    return (a > eps) - (a < -eps);
}</pre>
```

#### 17 Points

#### 17.1 Points

```
struct Pt {
  ld x, y;
  explicit Pt(ld x = 0, ld y = 0) : x(x), y(y) {}
  Pt operator + (Pt p) const { return Pt(x + p.x, y + p.y);
       }
  Pt operator - (Pt p) const { return Pt(x - p.x, y - p.y);
  Pt operator * (ld k) const { return Pt(x * k, y * k); }
  Pt operator / (ld k) const { return Pt(x / k, y / k); }
  ld dot(Pt p) const {
    // 0 if vectors are orthogonal
    \ensuremath{//} - if vectors are pointing in opposite directions
    // + if vectors are pointing in the same direction
    return x * p.x + y * p.y;
  ld cross(Pt p) const {
    // 0 if collinear
    // - if b is to the right of a
    // + if b is to the left of a
    // gives you 2 * area
    return x * p.y - y * p.x;
  ld norm() const { return x * x + y * y; }
  ld length() const { return sqrtl(norm()); }
  ld angle() const {
```

```
ld ang = atan2(y, x);
     return ang + (ang < 0 ? 2 * acos(-1) : 0);
   }
   Pt perp() const { return Pt(-y, x); }
   Pt unit() const { return (*this) / length(); }
   Pt rotate(ld angle) const {
    // counter-clockwise rotation in radians
     // degree = radian * 180 / pi
     return Pt(x * cos(angle) - y * sin(angle), x * sin(
         angle) + y * cos(angle));
   int dir(Pt a, Pt b) const {
     // where am I on the line directed line ab
     return sgn((a - *this).cross(b - *this));
   }
   int cuad() const {
    if (x > 0 \&\& y >= 0) return 0;
     if (x \le 0 \& y > 0) return 1;
    if (x < 0 \& y <= 0) return 2;
    if (x \ge 0 \& y < 0) return 3;
     return -1;
   }
17.2
       Angle between vectors
 double angleBetween(Pt a, Pt b) {
   double x = a.dot(b) / a.length() / b.length();
   return acosl(max(-1.0, min(1.0, x)));
 }
17.3 Closest pair of points O(N \cdot log N)
 pair<Pt, Pt> closestPairOfPoints(vector<Pt> &pts) {
   sort(all(pts), [&](Pt a, Pt b) {
     return le(a.y, b.y);
   });
   set<Pt> st;
   ld ans = INF;
   Pt p, q;
   int pos = 0;
   fore (i, 0, sz(pts)) {
     while (pos < i && geq(pts[i].y - pts[pos].y, ans))</pre>
       st.erase(pts[pos++]);
     auto lo = st.lower_bound(Pt(pts[i].x - ans - eps, -INF)
         );
     auto hi = st.upper_bound(Pt(pts[i].x + ans + eps, -INF)
     for (auto it = lo; it != hi; ++it) {
       ld d = (pts[i] - *it).length();
       if (le(d, ans))
         ans = d, p = pts[i], q = *it;
     st.insert(pts[i]);
   }
   return {p, q};
 }
17.4 Projection
 ld proj(Pt a, Pt b) {
   return a.dot(b) / b.length();
17.5
       KD-Tree
build: \mathcal{O}(N \cdot log N), nearest: \mathcal{O}(log N)
 struct KDTree {
   // p.pos(0) = x, p.pos(1) = y, p.pos(2) = z
   #define iter Pt* // vector<Pt>::iterator
   KDTree *left, *right;
   Pt p;
   ld val;
   int k;
```

```
KDTree(iter b, iter e, int k = 0) : k(k), left(0), right(
      0) {
    int n = e - b;
    if (n == 1) {
      p = *b;
      return:
    nth_element(b, b + n / 2, e, [&](Pt a, Pt b) {
      return a.pos(k) < b.pos(k);</pre>
    val = (b + n / 2) - pos(k);
    left = new KDTree(b, b + n / 2, (k + 1) % 2);
    right = new \ KDTree(b + n / 2, e, (k + 1) \% 2);
  pair<ld, Pt> nearest(Pt q) {
    if (!left && !right) // take care if is needed a
         different one
      return make_pair((p - q).norm(), p);
    pair<ld, Pt> best;
    if (q.pos(k) <= val) {
      best = left->nearest(q);
      if (geq(q.pos(k) + sqrt(best.f), val))
        best = min(best, right->nearest(q));
    } else {
      best = right->nearest(q);
      if (leq(q.pos(k) - sqrt(best.f), val))
        best = min(best, left->nearest(q));
    return best;
};
```

## 18 Lines and segments

#### 18.1 Line

```
struct Line {
 Pt a, b, v;
  Line() {}
  Line(Pt a, Pt b) : a(a), b(b), v((b - a).unit()) {}
  bool contains(Pt p) {
   return eq((p - a).cross(b - a), ∅);
  int intersects(Line 1) {
    if (eq(v.cross(l.v), 0))
      return eq((1.a - a).cross(v), 0) ? INF : 0;
    return 1;
  }
  int intersects(Seg s) {
    if (eq(v.cross(s.v), 0))
      return eq((s.a - a).cross(v), 0) ? INF : 0;
    return sgn(v.cross(s.a - a)) != sgn(v.cross(s.b - a));
  template <class Line>
  Pt intersection(Line 1) { // can be a segment too
   return a + v * ((1.a - a).cross(1.v) / v.cross(1.v));
  Pt projection(Pt p) {
   return a + v * proj(p - a, v);
  Pt reflection(Pt p) {
```

```
return a * 2 - p + v * 2 * proj(p - a, v);
                                                                    ld 1 = (o - c.o).length() - r - c.r;
  }
                                                                    return ge(1, 0) ? OUT : eq(1, 0) ? ON : OVERLAP;
 };
                                                                   }
18.2
       Segment
                                                                   int contains(Pt p) {
 struct Seg {
                                                                    ld 1 = (p - o).length() - r;
  Pt a, b, v;
                                                                    return le(1, 0) ? IN : eq(1, 0) ? ON : OUT;
   Seg() {}
   Seg(Pt a, Pt b) : a(a), b(b), v(b - a) {}
                                                                   Pt projection(Pt p) {
                                                                    return o + (p - o).unit() * r;
   bool contains(Pt p) {
     return eq(v.cross(p - a), 0) && leq((a - p).dot(b - p),
          0):
                                                                   vector<Pt> tangency(Pt p) {
   }
                                                                    // point outside the circle
                                                                    Pt v = (p - o).unit() * r;
   int intersects(Seg s) {
                                                                    1d d2 = (p - o).norm(), d = sqrt(d2);
     int t1 = sgn(v.cross(s.a - a)), t2 = sgn(v.cross(s.b - a))
                                                                    if (leq(d, 0)) return {}; // on circle, no tangent
         a));
                                                                    Pt v1 = v * (r / d), v2 = v.perp() * (sqrt(d2 - r * r)
     if (t1 == t2)
                                                                         / d):
       return t1 == 0 && (contains(s.a) || contains(s.b) ||
                                                                    return {0 + v1 - v2, 0 + v1 + v2};
           s.contains(a) || s.contains(b)) ? INF : 0;
     return sgn(s.v.cross(a - s.a)) != sgn(s.v.cross(b - s.a
         ));
                                                                   vector<Pt> intersection(Cir c) {
   }
                                                                    ld d = (c.o - o).length();
                                                                     if (eq(d, 0) || ge(d, r + c.r) || le(d, abs(r - c.r)))
   template <class Seg>
                                                                         return {}; // circles don't intersect
   Pt intersection(Seg s) { // can be a line too
                                                                    Pt v = (c.o - o).unit();
     return a + v * ((s.a - a).cross(s.v) / v.cross(s.v));
                                                                    1d = (r * r + d * d - c.r * c.r) / (2 * d);
  }
                                                                    Pt p = o + v * a;
 };
                                                                     if (eq(d, r + c.r) || eq(d, abs(r - c.r))) return {p};
                                                                         // circles touch at one point
18.3
       Distance point-line
                                                                    1d h = sqrt(r * r - a * a);
 ld distance(Pt p, Line 1) {
                                                                    Pt q = v.perp() * h;
  Pt q = 1.projection(p);
                                                                    return {p - q, p + q}; // circles intersects twice
   return (p - q).length();
 }
18.4
       Distance point-segment
                                                                   template <class Line>
 ld distance(Pt p, Seg s) {
                                                                   vector<Pt> intersection(Line 1) {
   if (le((p - s.a).dot(s.b - s.a), 0))
                                                                    // for a segment you need to check that the point lies
     return (p - s.a).length();
                                                                         on the segment
   if (le((p - s.b).dot(s.a - s.b), 0))
                                                                    1d h2 = r * r - 1.v.cross(o - 1.a) * 1.v.cross(o - 1.a)
     return (p - s.b).length();
                                                                          / 1.v.norm();
   return abs((s.a - p).cross(s.b - p) / (s.b - s.a).length
                                                                    Pt p = 1.a + 1.v * 1.v.dot(o - 1.a) / 1.v.norm();
                                                                     if (eq(h2, 0)) return {p}; // line tangent to circle
       ());
 }
                                                                    if (le(h2, 0)) return {}; // no intersection
                                                                    Pt q = 1.v.unit() * sqrt(h2);
18.5
        Distance segment-segment
                                                                    return {p - q, p + q}; // two points of intersection (
 ld distance(Seg a, Seg b) {
                                                                         chord)
   if (a.intersects(b))
                                                                   }
     return 0.L;
   return min({distance(a.a, b), distance(a.b, b), distance(
                                                                   Cir(Pt a, Pt b, Pt c) {
       b.a, a), distance(b.b, a)});
                                                                     // find circle that passes through points a, b, c
 }
                                                                    Pt mab = (a + b) / 2, mcb = (b + c) / 2;
                                                                    Seg ab(mab, mab + (b - a).perp());
       Circles
19
                                                                    Seg cb(mcb, mcb + (b - c).perp());
                                                                    o = ab.intersection(cb);
       Circle
19.1
                                                                    r = (o - a).length();
 struct Cir {
   Pt o;
   ld r;
                                                                  ld commonArea(Cir c) {
   Cir() {}
                                                                    if (le(r, c.r))
   Cir(ld x, ld y, ld r) : o(x, y), r(r) {}
                                                                       return c.commonArea(*this);
  Cir(Pt o, ld r) : o(o), r(r) {}
                                                                    ld d = (o - c.o).length();
                                                                    if (leq(d + c.r, r)) return c.r * c.r * pi;
  int inside(Cir c) {
                                                                     if (geq(d, r + c.r)) return 0.0;
    ld l = c.r - r - (o - c.o).length();
                                                                    auto angle = [&](ld a, ld b, ld c) {
     return ge(1, 0) ? IN : eq(1, 0) ? ON : OVERLAP;
                                                                      return acos((a * a + b * b - c * c) / (2 * a * b));
                                                                    };
                                                                    auto cut = [&](ld a, ld r) {
   int outside(Cir c) {
```

```
return (a - sin(a)) * r * r / 2;
                                                                   fore (i, 0, sz(pts)) {
                                                                     while(sz(low) \ge 2 \& (low.end()[-1] - low.end()[-2]).
    };
    ld a1 = angle(d, r, c.r), a2 = angle(d, c.r, r);
                                                                          cross(pts[i] - low.end()[-1]) \le 0
     return cut(a1 * 2, r) + cut(a2 * 2, c.r);
                                                                       low.pop_back();
                                                                     low.pb(pts[i]);
   }
};
                                                                   fore (i, sz(pts), ∅) {
19.2
       Distance point-circle
                                                                     while(sz(up) \ge 2 && (up.end()[-1] - up.end()[-2]).
 ld distance(Pt p, Cir c) {
                                                                          cross(pts[i] - up.end()[-1]) \le 0
   return max(0.L, (p - c.o).length() - c.r);
                                                                       up.pop_back();
 }
                                                                     up.pb(pts[i]);
19.3
        Minimum enclosing circle \mathcal{O}(N) wow!!
                                                                   low.pop_back(), up.pop_back();
 Cir minEnclosing(vector<Pt> &pts) { // a bunch of points
                                                                   low.insert(low.end(), all(up));
   shuffle(all(pts), rng);
                                                                   return low;
   Cir c(0, 0, 0);
                                                                 }
   fore (i, 0, sz(pts)) if (!c.contains(pts[i])) {
     c = Cir(pts[i], 0);
                                                                20.3
                                                                         Cut polygon by a line \mathcal{O}(N)
     fore (j, 0, i) if (!c.contains(pts[j])) {
                                                                 vector<Pt> cut(const vector<Pt> &pts, Line 1) {
       c = Cir((pts[i] + pts[j]) / 2, (pts[i] - pts[j]).
                                                                   vector<Pt> ans;
           length() / 2);
                                                                   int n = sz(pts);
       fore (k, 0, j) if (!c.contains(pts[k]))
                                                                   fore (i, 0, n) {
         c = Cir(pts[i], pts[j], pts[k]);
                                                                      int j = (i + 1) \% n;
    }
                                                                      if (geq(l.v.cross(pts[i] - l.a), 0)) // left
   }
                                                                       ans.pb(pts[i]);
   return c;
                                                                      Seg s(pts[i], pts[j]);
                                                                      if (l.intersects(s) == 1) {
       Common area circle-polygon \mathcal{O}(N)
                                                                       Pt p = 1.intersection(s);
                                                                       if (p != pts[i] && p != pts[j])
 ld commonArea(const Cir &c, const vector<Pt> &poly) {
                                                                         ans.pb(p);
   auto arg = [&](Pt p, Pt q) {
     return atan2(p.cross(q), p.dot(q));
                                                                   }
                                                                   return ans;
   auto tri = [&](Pt p, Pt q) {
                                                                 }
    Pt d = q - p;
     1d = d.dot(p) / d.norm(), b = (p.norm() - c.r * c.r)
                                                                         Perimeter \mathcal{O}(N)
         / d.norm();
                                                                 ld perimeter(const vector<Pt> &pts){
     1d det = a * a - b;
                                                                   1d sum = 0;
     if (leq(det, 0)) return arg(p, q) * c.r * c.r;
                                                                   fore (i, 0, sz(pts))
     1d s = max(0.L, -a - sqrt(det)), t = min(1.L, -a + sqrt)
                                                                      sum += (pts[(i + 1) % sz(pts)] - pts[i]).length();
         (det));
                                                                   return sum;
     if (t < 0 || 1 <= s) return arg(p, q) * c.r * c.r;</pre>
                                                                 }
     Pt u = p + d * s, v = p + d * t;
     return u.cross(v) + (arg(p, u) + arg(v, q)) * c.r * c.r
                                                                         Point in polygon \mathcal{O}(N)
                                                                 int contains(const vector<Pt> &pts, Pt p) {
   };
                                                                   int rays = 0, n = sz(pts);
   1d sum = 0;
                                                                   fore (i, 0, n) {
   fore (i, 0, sz(poly))
                                                                     Pt a = pts[i], b = pts[(i + 1) % n];
     sum += tri(poly[i] - c.o, poly[(i + 1) % sz(poly)] - c.
                                                                      if (ge(a.y, b.y))
         0);
                                                                       swap(a, b);
   return abs(sum / 2);
                                                                      if (Seg(a, b).contains(p))
                                                                       return ON;
                                                                     rays ^= (leq(a.y, p.y) && le(p.y, b.y) && ge((a - p).
20
       Polygons
                                                                          cross(b - p), ∅));
                                                                   }
        Area of polygon \mathcal{O}(N)
20.1
                                                                   return rays & 1 ? IN : OUT;
 ld area(const vector<Pt> &pts) {
                                                                 }
   1d sum = 0;
                                                                         Point in convex-polygon \mathcal{O}(log N)
                                                                20.6
   fore (i, 0, sz(pts))
     sum += pts[i].cross(pts[(i + 1) % sz(pts)]);
                                                                 bool contains(const vector<Pt> &a, Pt p) {
   return abs(sum / 2);
                                                                   int lo = 1, hi = sz(a) - 1;
 }
                                                                   if (a[0].dir(a[lo], a[hi]) > 0)
                                                                      swap(lo, hi);
20.2
       Convex-Hull \mathcal{O}(N \cdot log N)
                                                                   if (p.dir(a[0], a[lo]) >= 0 || p.dir(a[0], a[hi]) <= 0)</pre>
 vector<Pt> convexHull(vector<Pt> pts) {
                                                                     return false;
   vector<Pt> low, up;
                                                                   while (abs(lo - hi) > 1) {
   sort(all(pts), [&](Pt a, Pt b) {
                                                                      int mid = (lo + hi) >> 1;
    return a.x == b.x ? a.y < b.y : a.x < b.x;
                                                                      (p.dir(a[0], a[mid]) > 0 ? hi : lo) = mid;
   });
   pts.erase(unique(all(pts)), pts.end());
                                                                   return p.dir(a[lo], a[hi]) < 0;</pre>
   if (sz(pts) \le 2)
                                                                 }
```

return pts;

```
20.7 Is convex \mathcal{O}(N)
 bool isConvex(const Poly &pts) {
   int n = sz(pts);
   bool pos = 0, neg = 0;
   fore (i, 0, n) {
     Pt a = pts[(i + 1) % n] - pts[i];
     Pt b = pts[(i + 2) % n] - pts[(i + 1) % n];
     int dir = sgn(a.cross(b));
     if (dir > 0) pos = 1;
     if (dir < 0) neg = 1;
   }
   return !(pos && neg);
 }
       Geometry misc
21
        Radial order
 struct Radial {
  Pt c;
   Radial(Pt c) : c(c) {}
  bool operator()(Pt a, Pt b) const {
    Pt p = a - c, q = b - c;
     if (p.cuad() == q.cuad())
      return p.y * q.x < p.x * q.y;
     return p.cuad() < q.cuad();</pre>
  }
 };
21.2 Sort along a line \mathcal{O}(N \cdot log N)
 void sortAlongLine(vector<Pt> &pts, Line 1){
   sort(all(pts), [&](Pt a, Pt b){
     return a.dot(1.v) < b.dot(1.v);</pre>
```

});
}