C	contents		7 (abinatorics	16
1	Data structures	3		7.1 7.2	Factorial \dots Factorial mod $smallPrime$ \dots	16 16
_	1.1 Disjoint set with rollback	3			Lucas theorem	16
	1.2 Min-Max queue	3			Stars and bars	16
	1.3 Sparse table	3			N choose K	16
	1.4 Squirtle decomposition	3		.6 '.6	Catalan	16
	1.5 In-Out trick	3		-	Burnside's lemma	16
	1.6 Parallel binary search	3	7		Prime factors of N!	16
	1.7 Mo's algorithm	4				
	1.8 Static to dynamic	4	8 1		aber Theory	16
	1.9 Disjoint intervals	4			Goldbach conjecture	16
	1.10 Ordered tree	4		3.2	Sieve of Eratosthenes	16
	1.11 Unordered tree	5			Phi of euler	17
	1.12 D-dimensional Fenwick tree	5			Miller-Rabin	17
	1.13 Dynamic segment tree	5	_		Pollard-Rho	17
	1.14 Persistent segment tree	5		3.6	Amount of divisors	17
	1.15 Wavelet tree	5			Bézout's identity	17 17
	1.16 Li Chao tree	6			LCM	17
	1.17 Treap	6	-		Euclid	17
					Chinese remainder theorem	17
2	Graphs	7		,.11	Chinese remainder theorem	11
	2.1 Tarjan algorithm (SCC)	7	9 1	Mat	h	18
	2.2 Kosaraju algorithm (SCC)	7	9	0.1	Progressions	18
	2.3 Two Sat	7	9		Mod multiplication	18
	2.4 Topological sort	7	9		Fpow	18
	2.5 Cutpoints and Bridges	8	9	0.4	Fibonacci	18
	2.6 Detect a cycle	8	10.6	~		10
	2.7 Euler tour for Mo's in a tree	8			metry	18 18
	2.8 Lowest common ancestor (LCA)	8			Real	18
	2.9 Guni	8			Angle Between Vectors	18
	2.10 Centroid decomposition	8			Area Poligon	18
	2.11 Heavy-light decomposition	8			Area Poligon In Circle	18
	2.12 Link-Cut tree	9			Closest Pair Of Points	19
_					Convex Hull	19
3		10			Distance Point Line	19
	* * * * * * * * * * * * * * * * * * * *	10	1	0.9	Get Circle	19
		10	1	0.10	Intersects Line	19
	1 ()	11	1	0.11	Intersects Line Segment	19
	3.4 Hungarian $\mathcal{O}(N^3)$	11	1	0.12	2 Intersects Segment	20
1	Strings	11			Is Convex	20
4	_	11			Perimeter	20
		12			Point In Convex Polygon logN	20
		12			Point In Polygon	20
		12			Point In Segment	20
	<u> </u>	12			3 Points Of Tangency	20
	9	12			Projection	20
	· ·	13			Projection Line	20 20
		14			Signed Distance Point Line	$\frac{20}{21}$
		14			S Sort Along Line	21
	1.0 Ectification				Intersects Line Circle	21
5	Dynamic Programming	14	1	.0.47	Zarozoeto Zaro Ciroto III. III. III. III. III. III. III. I	⊿ 1
		14	11 I	3it 1	tricks	21
		15	1	1.1	Bitset	21
		15				
	- /	15				
		15				
		15				
		15				
6	· ·	16				
	6.1 Grundy Numbers	16				

Think twice, code once Template

```
tem.cpp
 #pragma GCC optimize("Ofast,unroll-loops,no-stack-
     protector")
 #include <bits/stdc++.h>
using namespace std;
#ifdef LOCAL
 #include "debug.h"
 #else
 #define debug(...)
 #endif
#define df(b, e) ((b) > (e))
#define fore(i, b, e) for (auto i = (b) - df(b, e); i
     != e - df(b, e); i += 1 - 2 * df(b, e))
 #define sz(x) int(x.size())
 #define all(x) begin(x), end(x)
 #define f first
 #define s second
 #define pb push_back
using 1li = long long;
using ld = long double;
using ii = pair<int, int>;
using vi = vector<int>;
 int main() {
   cin.tie(∅)->sync_with_stdio(∅), cout.tie(∅);
   // solve the problem here D:
   return 0;
  debug.h
 template <class A, class B>
ostream & operator << (ostream &os, const pair<A, B> &
   return os << "(" << p.first << ", " << p.second << "</pre>
       )";
}
 template <class A, class B, class C>
basic_ostream<A, B> & operator << (basic_ostream<A, B>
      &os, const C &c) {
   os << "[";
   for (const auto &x : c)
    os << ", " + 2 * (&x == &*begin(c)) << x;
   return os << "]";</pre>
void print(string s) { cout << endl; }</pre>
 template <class H, class... T>
 void print(string s, const H &h, const T&... t) {
   const static string reset = "\033[0m";
   bool ok = 1;
   do {
     if (s[0] == '\"') ok = 0;
     else cout << "\033[1;34m" << s[0] << reset;</pre>
    s = s.substr(1);
   } while (s.size() && s[0] != ',');
   if (ok) cout << ": " << "\033[3;95m" << h << reset;</pre>
  print(s, t...);
Randoms
mt19937 rng(chrono::steady_clock::now().
```

```
time_since_epoch().count());
uniform_int_distribution<>(1, r)(rng);
```

Fastio

```
char gc() { return getchar_unlocked(); }
 void readInt() {}
 template <class H, class... T>
 void readInt(H &h, T&&... t) {
   char c, s = 1;
   while (isspace(c = gc()));
   if (c == '-') s = -1, c = gc();
   for (h = c - '0'; isdigit(c = gc()); h = h * 10 + c
   h *= s;
   readInt(t...);
 }
 void readFloat() {}
 template <class H, class... T>
 void readFloat(H &h, T&&... t) {
   int c, s = 1, fp = 0, fpl = 1;
   while (isspace(c = gc()));
   if (c == '-') s = -1, c = gc();
   for (h = c - '0'; isdigit(c = gc()); h = h * 10 + c
       - '0');
  h *= s;
   if (h == '.')
     for (; isdigit(c = gc()); fp = fp * 10 + c - '0',
         fpl *= 10):
   h += (double)fp / fpl;
   readFloat(t...);
Compilation (gedit /.zshenv)
 touch a_in{1..9} // make files a_in1, a_in2,..., a_in9
 tee {a..m}.cpp < tem.cpp // "" with tem.cpp like base</pre>
 cat > a_in1 // write on file a_in1
 gedit a_in1 // open file a_in1
 rm -r a.cpp // deletes file a.cpp :'(
 red='\x1B[0;31m'
 green='\x1B[0;32m'
 noColor='\x1B[0m'
 alias flags='-Wall -Wextra -Wshadow -
     D_GLIBCXX_ASSERTIONS -fmax-errors=3 -02 -w'
 go() { g++ --std=c++11 $2 ${flags} $1.cpp && ./a.out }
 debug() { go $1 -DLOCAL < $2 }</pre>
 run() { go $1 "" < $2 }
 random() { // Make small test cases!!!
  g++ --std=c++11 $1.cpp -o prog
  g++ --std=c++11 gen.cpp -o gen
  g++ --std=c++11 brute.cpp -o brute
  for ((i = 1; i <= 200; i++)); do
   printf "Test case #$i"
   ./gen > in
   diff -uwi <(./prog < in) <(./brute < in) > $1_diff
   if [[ ! $? -eq 0 ]]; then
   printf "${red} Wrong answer ${noColor}\n"
   break
   printf "${green} Accepted ${noColor}\n"
   fi
  done
 test() {
  g++ --std=c++11 $1.cpp -o prog
  for ((i = 1; i \le 50; i++)); do
   [[ -f $1_in$i ]] || break
   printf "Test case #$i'
   diff -uwi <(./prog < $1_in$i) $1_out$i > $1_diff
```

```
if [[ ! $? -eq 0 ]]; then
                                                              T qmin() { return front().f; }
   printf "${red} Wrong answer ${noColor}\n"
                                                            };
                                                           1.3
                                                                 Sparse table
   printf "${green} Accepted ${noColor}\n"
                                                            template <class T, class F = function<T(const T&,</pre>
   fi
                                                                 const T&)>>
 done
                                                            struct Sparse {
}
                                                              int n;
Bump allocator
                                                              vector<vector<T>> sp;
static char buf[450 << 20];</pre>
                                                              F f:
void* operator new(size_t s) {
   static size_t i = sizeof buf; assert(s < i);</pre>
                                                              Sparse(vector<T> &a, const F &f) : n(sz(a)), sp(1 +
                                                                   _{lg(n)}, f(f) {
  return (void *) &buf[i -= s];
                                                                sp[0] = a;
void operator delete(void *) {}
                                                                for (int k = 1; (1 << k) <= n; k++) {
                                                                  sp[k].resize(n - (1 << k) + 1);
     Data structures
                                                                  fore (1, 0, sz(sp[k])) {
                                                                    int r = 1 + (1 << (k - 1));
     Disjoint set with rollback
                                                                    sp[k][1] = f(sp[k - 1][1], sp[k - 1][r]);
struct Dsu {
   vector<int> pr, tot;
                                                                }
   stack<ii> what;
   Dsu(int n = 0) : pr(n + 5), tot(n + 5, 1) {
                                                              T query(int 1, int r) {
    iota(all(pr), ∅);
                                                                int k = _{-}lg(r - l + 1);
   }
                                                                return f(sp[k][1], sp[k][r - (1 << k) + 1]);
                                                              }
   int find(int u) {
                                                            };
    return pr[u] == u ? u : find(pr[u]);
                                                                  Squirtle decomposition
                                                           1.4
   }
                                                           The perfect block size is squirtle of N
   void unite(int u, int v) {
    u = find(u), v = find(v);
                                                            int blo[N], cnt[N][B], a[N];
    if (u == v)
      what.emplace(-1, -1);
                                                            void update(int i, int x) {
    else {
                                                              cnt[blo[i]][x]--;
      if (tot[u] < tot[v])</pre>
                                                              a[i] = x;
         swap(u, v);
                                                              cnt[blo[i]][x]++;
      what.emplace(u, v);
                                                            }
      tot[u] += tot[v];
      pr[v] = u;
                                                            int query(int 1, int r, int x) {
    }
                                                              int tot = 0:
   }
                                                              while (1 \le r)
                                                                if (1 % B == 0 && 1 + B - 1 <= r) {
   ii rollback() {
                                                                  tot += cnt[blo[1]][x];
    ii last = what.top();
                                                                  1 += B;
    what.pop();
                                                                } else {
    int u = last.f, v = last.s;
                                                                  tot += (a[1] == x);
    if (u != -1) {
                                                                  1++;
      tot[u] -= tot[v];
                                                                }
      pr[v] = v;
                                                              return tot;
    }
                                                            }
    return last;
                                                           1.5 In-Out trick
   }
};
                                                            vector<int> in[N], out[N];
                                                            vector<Query> queries;
1.2
     Min-Max queue
 template <class T>
                                                            fore (x, 0, N) {
struct MinQueue : deque< pair<T, int> > {
                                                              for (int i : in[x])
   // add a element to the right {val, pos}
                                                                add(queries[i]);
   void add(T val, int pos) {
                                                              // solve
    while (!empty() && back().f >= val)
                                                              for (int i : out[x])
      pop_back();
                                                                rem(queries[i]);
    emplace_back(val, pos);
                                                            }
                                                           1.6 Parallel binary search
   // remove all less than pos
  void rem(int pos) {
                                                            int lo[Q], hi[Q];
    while (front().s < pos)</pre>
                                                            queue<int> solve[N];
      pop_front();
                                                            vector<Query> queries;
```

fore (it, 0, 1 + __lg(N)) {

}

```
fore (i, 0, sz(queries))
                                                                   if (1 <= u.pos && u.pos <= r) {
     if (lo[i] != hi[i]) {
                                                                     rem(u.pos);
       int mid = (lo[i] + hi[i]) / 2;
                                                                     a[u.pos] = u.prv;
       solve[mid].emplace(i);
                                                                     add(u.pos);
                                                                   } else {
   fore (x, 0, n) {
                                                                    a[u.pos] = u.prv;
     // simulate
     while (!solve[x].empty()) {
                                                                 }
       int i = solve[x].front();
                                                               • Solve the problem :D
       solve[x].pop();
       if (can(queries[i]))
                                                                 l = queries[0].l, r = l - 1, upd = sz(updates) - 1;
         hi[i] = x;
                                                                 for (Query &q : queries) {
       else
                                                                   while (upd < q.upd)</pre>
         lo[i] = x + 1;
                                                                     dodo(updates[++upd]);
     }
                                                                   while (upd > q.upd)
   }
                                                                    undo(updates[upd--]);
 }
                                                                   // write down the normal Mo's algorithm
1.7
      Mo's algorithm
                                                            1.8
 vector<Query> queries;
                                                                   Static to dynamic
 // N = 1e6, so aprox. sqrt(N) +/- C
                                                              template <class Black, class T>
                                                              struct StaticDynamic {
 uniform_int_distribution<int> dis(970, 1030);
 const int blo = dis(rng);
                                                               Black box[LogN];
 sort(all(queries), [&](Query a, Query b) {
                                                               vector<T> st[LogN];
   const int ga = a.1 / blo, gb = b.1 / blo;
   if (ga == gb)
                                                               void insert(T &x) {
     return (ga & 1) ? a.r < b.r : a.r > b.r;
                                                                  int p = 0;
   return a.1 < b.1;
                                                                  fore (i, ∅, LogN)
 });
                                                                    if (st[i].empty()) {
 int 1 = queries[0].1, r = 1 - 1;
                                                                      p = i;
 for (Query &q : queries) {
                                                                      break:
   while (r < q.r)
                                                                   }
     add(++r);
                                                                  st[p].pb(x);
   while (r > q.r)
                                                                  fore (i, 0, p) {
     rem(r--);
                                                                    st[p].insert(st[p].end(), all(st[i]));
   while (1 < q.1)
                                                                    box[i].clear(), st[i].clear();
     rem(1++);
   while (1 > q.1)
                                                                  for (auto y : st[p])
     add(--1);
                                                                   box[p].insert(y);
   ans[q.i] = solve();
                                                                  box[p].init();
                                                               }
                                                             };
To make it faster, change the order to hilbert(l, r)
                                                                  Disjoint intervals
                                                            1.9
 11i hilbert(int x, int y, int pw = 21, int rot = 0) {
                                                             struct Range {
   if (pw == 0)
                                                               int 1, r;
     return 0;
                                                               bool operator < (const Range& rge) const {</pre>
   int hpw = 1 << (pw - 1);
                                                                  return 1 < rge.1;</pre>
   int k = ((x < hpw ? y < hpw ? 0 : 3 : y < hpw ? 1 :
       2) + rot) & 3;
                                                             };
   const int d[4] = \{3, 0, 0, 1\};
   11i a = 1LL << ((pw << 1) - 2);
                                                              struct DisjointIntervals : set<Range> {
   111 b = hilbert(x & (x ^{hpw}), y & (y ^{hpw}), pw - 1
                                                               void add(Range rge) {
       , (rot + d[k]) & 3);
                                                                  iterator p = lower\_bound(rge), q = p;
   return k * a + (d[k] ? a - b - 1 : b);
                                                                  if (p != begin() && rge.1 <= (--p)->r)
 }
                                                                    rge.1 = p->1, --q;
Mo's algorithm with updates in \mathcal{O}(n^{\frac{5}{3}})
                                                                  for (; q != end() && q->l <= rge.r; erase(q++))</pre>
                                                                   rge.r = max(rge.r, q->r);
  • Choose a block of size n^{\frac{2}{3}}
                                                                  insert(rge);
  • Do a normal Mo's algorithm, in the Query definition
    add an extra variable for the updatesSoFar
  • Sort the queries by the order (l/block, r/block,
                                                               void add(int 1, int r) {
    updatesSoFar)
                                                                  add(Range{1, r});
  • If the update lies inside the current query, update the
                                                               }
                                                             };
    data structure properly
                                                                     Ordered tree
                                                            1.10
    struct Update {
      int pos, prv, nxt;
                                                             #include <ext/pb_ds/assoc_container.hpp>
```

};

void undo(Update &u) {

#include <ext/pb_ds/tree_policy.hpp>

using namespace __gnu_pbds;

```
template <class K, class V = null_type>
                                                                    if (!rs) rs = new Dyn(m + 1, r);
using ordered_tree = tree<K, V, less<K>, rb_tree_tag,
                                                                    rs->update(p, v);
     tree_order_statistics_node_update>;
                                                                  }
 // less_equal<K> for multiset, multimap (?
                                                                  pull();
#define qrank order_of_key
                                                                }
 #define qkth find_by_order
                                                                1li qsum(int 11, int rr) {
1.11 Unordered tree
                                                                  if (rr < 1 || r < 11 || r < 1)</pre>
 struct chash {
                                                                    return 0;
  const uint64_t C = uint64_t(2e18 * 3) + 71;
                                                                  if (ll <= l && r <= rr)</pre>
   const int R = rng();
                                                                    return sum;
  uint64_t operator ()(uint64_t x) const {
                                                                  int m = (1 + r) >> 1;
     return __builtin_bswap64((x ^ R) * C); }
                                                                  return (ls ? ls->qsum(ll, rr) : 0) +
                                                                         (rs ? rs->qsum(l1, rr) : 0);
                                                                }
template <class K, class V = null_type>
                                                              };
using unordered_tree = gp_hash_table<K, V, chash>;
                                                             1.14
                                                                     Persistent segment tree
        D-dimensional Fenwick tree
                                                              struct Per {
 template <class T, int ...N>
                                                                int 1, r;
struct Fenwick {
                                                                lli sum = 0;
   T v = 0;
                                                                Per *L, *R;
   void update(T v) { this->v += v; }
   T query() { return v; }
                                                                Per(int 1, int r) : 1(1), r(r), L(0), R(0) {}
};
                                                                Per* pull() {
 template <class T, int N, int ...M>
                                                                  sum = L - > sum + R - > sum;
 struct Fenwick<T, N, M...> {
                                                                  return this;
   #define lsb(x) (x & -x)
   Fenwick<T, M...> fenw[N + 1];
                                                                void build() {
   template <typename... Args>
                                                                  if (1 == r)
   void update(int i, Args... args) {
                                                                    return;
     for (; i <= N; i += lsb(i))</pre>
                                                                  int m = (1 + r) >> 1;
       fenw[i].update(args...);
                                                                  (L = new Per(1, m))->build();
                                                                  (R = new Per(m + 1, r)) -> build();
                                                                  pull();
   template <typename... Args>
   T query(int 1, int r, Args... args) {
    T v = 0;
                                                                Per* update(int p, lli v) {
     for (; r > 0; r -= lsb(r))
                                                                  if (p < 1 || r < p)
      v += fenw[r].query(args...);
                                                                    return this;
     for (--1; 1 > 0; 1 -= 1sb(1))
                                                                  Per* t = new Per(1, r);
      v -= fenw[1].query(args...);
                                                                  if (1 == r) {
     return v:
                                                                    t->sum = v;
   }
                                                                    return t;
};
                                                                  }
1.13
        Dynamic segment tree
                                                                  t \rightarrow L = L \rightarrow update(p, v);
                                                                  t \rightarrow R = R \rightarrow update(p, v);
 struct Dyn {
                                                                  return t->pull();
   int 1, r;
   11i \text{ sum} = 0;
   Dyn *ls, *rs;
                                                                1li qsum(int 11, int rr) {
                                                                  if (r < 11 || rr < 1)</pre>
  Dyn(int 1, int r) : l(1), r(r), ls(0), rs(0) {}
                                                                    return 0;
                                                                  if (ll <= l && r <= rr)
   void pull() {
                                                                    return sum;
    sum = (1s ? 1s -> sum : 0);
                                                                  return L->qsum(ll, rr) + R->qsum(ll, rr);
     sum += (rs ? rs->sum : 0);
                                                                }
   }
                                                              };
   void update(int p, lli v) {
                                                            1.15
                                                                     Wavelet tree
     if (1 == r) {
                                                              struct Wav {
       sum += v;
                                                                #define iter int* // vector<int>::iterator
       return;
                                                                int lo, hi;
     }
     int m = (1 + r) >> 1;
                                                                Wav *ls, *rs;
     if (p <= m) {
                                                                vi amt:
       if (!ls) ls = new Dyn(1, m);
                                                                Wav(int lo, int hi) : lo(lo), hi(hi), ls(0), rs(0)
       ls->update(p, v);
     } else {
                                                                    {}
```

```
void build(iter b, iter e) { // array 1-indexed
                                                                  11i m = (1 + r) >> 1;
     if (lo == hi || b == e)
                                                                  if (x <= m)
                                                                    return min(f(x), ls ? ls->query(x) : inf);
       return:
     amt.reserve(e - b + 1);
                                                                  return min(f(x), rs ? rs->query(x) : inf);
     amt.pb(∅);
                                                                }
     int m = (lo + hi) >> 1;
                                                              };
     for (auto it = b; it != e; it++)
                                                                     Treap
                                                             1.17
      amt.pb(amt.back() + (*it <= m));</pre>
     auto p = stable_partition(b, e, [&](int x) {
                                                              typedef struct Node* Treap;
      return x <= m;</pre>
                                                              struct Node {
                                                                uint32_t pri = rng();
     (ls = new Wav(lo, m))->build(b, p);
                                                                int val:
     (rs = new Wav(m + 1, hi)) -> build(p, e);
                                                                Treap ch[2] = \{0, 0\};
   }
                                                                int sz = 1, flip = 0;
                                                                Node(int val) : val(val) {}
   int qkth(int 1, int r, int k) {
                                                              };
     if (r < 1)
      return 0;
                                                              void push(Treap t) {
     if (lo == hi)
                                                                if (!t)
       return lo;
                                                                  return;
     if (k <= amt[r] - amt[l - 1])</pre>
                                                                if (t->flip) {
       return ls->qkth(amt[1 - 1] + 1, amt[r], k);
                                                                  swap(t->ch[0], t->ch[1]);
     return rs->qkth(1 - amt[1 - 1], r - amt[r], k -
                                                                  for (Treap ch : t->ch) if (ch)
         amt[r] + amt[l - 1]);
                                                                    ch->flip ^= 1;
                                                                  t\rightarrow flip = 0;
                                                                }
   int qleq(int 1, int r, int mx) {
                                                              }
     if (r < 1 || mx < lo)</pre>
       return 0;
                                                              Treap pull(Treap t) {
     if (hi <= mx)
                                                                #define gsz(t) (t ? t->sz : 0)
       return r - 1 + 1;
                                                                t->sz = 1;
     return ls->qleq(amt[1 - 1] + 1, amt[r], mx) +
                                                                for (Treap ch : t->ch)
            rs->qleq(1 - amt[1 - 1], r - amt[r], mx);
                                                                  push(ch), t->sz += gsz(ch);
  }
                                                                return t;
};
                                                              }
       Li Chao tree
1.16
                                                              pair<Treap, Treap> split(Treap t, int val) {
 struct Fun {
                                                                // <= val goes to the left, > val to the right
  11i m = 0, c = inf;
                                                                if (!t)
  1li operator ()(lli x) const { return m * x + c; }
                                                                  return {t, t};
                                                                push(t);
                                                                if (val < t->val) {
 struct LiChao {
                                                                  auto p = split(t->ch[0], val);
  Fun f;
                                                                  t->ch[0] = p.s;
   11i 1, r;
                                                                  return {p.f, pull(t)};
  LiChao *ls, *rs;
                                                                auto p = split(t->ch[1], val);
  LiChao(lli l, lli r) : l(l), r(r), ls(0), rs(0) {}
                                                                t->ch[1] = p.f;
                                                                return {pull(t), p.s};
   void add(Fun &g) {
                                                              }
     if (f(1) \le g(1) \&\& f(r) \le g(r))
       return;
                                                              pair<Treap, Treap> splitsz(Treap t, int sz) {
     if (g(1) < f(1) \&\& g(r) < f(r)) {
                                                                // <= sz goes to the left, > sz to the right
                                                                if (!t)
      f = g;
       return:
                                                                  return {t, t};
                                                                push(t):
     11i m = (1 + r) >> 1;
                                                                if (sz <= gsz(t->ch[0])) {
     if (g(m) < f(m))
                                                                  auto p = splitsz(t->ch[0], sz);
                                                                  t->ch[0] = p.s;
       swap(f, g);
     if (g(1) \le f(1))
                                                                  return {p.f, pull(t)};
      ls = ls ? (ls \rightarrow add(g), ls) : new LiChao(l, m, g)
                                                                auto p = splitsz(t->ch[1], sz - gsz(t->ch[0]) - 1);
     else
                                                                t->ch[1] = p.f;
       rs = rs ? (rs->add(g), rs) : new LiChao(m + 1, r)
                                                                return {pull(t), p.s};
            , g);
   }
                                                              Treap merge(Treap 1, Treap r) {
   lli query(lli x) {
                                                                if (!l || !r)
     if (1 == r)
                                                                  return 1 ? 1 : r;
```

return f(x);

```
2.2 Kosaraju algorithm (SCC)
  push(1), push(r);
  if (1->pri > r->pri)
                                                           int scc[N], k = 0;
    return l->ch[1] = merge(l->ch[1], r), pull(l);
                                                           char vis[N];
                                                           vi order;
    return r->ch[0] = merge(1, r->ch[0]), pull(r);
                                                           void dfs1(int u) {
                                                             vis[u] = 1:
Treap qkth(Treap t, int k) { // 0-indexed
                                                             for (int v : graph[u])
  if (!t)
                                                               if (vis[v] != 1)
    return t;
                                                                 dfs1(v);
  push(t);
                                                             order.pb(u);
  int sz = gsz(t->ch[0]);
                                                           }
  if (sz == k)
    return t;
                                                           void dfs2(int u, int k) {
  vis[u] = 2, scc[u] = k;
        - sz - 1);
                                                             for (int v : rgraph[u]) // reverse graph
}
                                                               if (vis[v] != 2)
                                                                 dfs2(v, k);
int qrank(Treap t, int val) { // 0-indexed
                                                           }
  if (!t)
    return -1;
                                                           void kosaraju() {
  push(t);
                                                             fore (u, 1, n + 1)
  if (val < t->val)
                                                               if (vis[u] != 1)
    return qrank(t->ch[0], val);
                                                                 dfs1(u);
  if (t->val == val)
                                                             reverse(all(order));
    return gsz(t->ch[0]);
                                                             for (int u : order)
  return gsz(t->ch[0]) + qrank(t->ch[1], val) + 1;
                                                               if (vis[u] != 2)
                                                                 dfs2(u, ++k);
                                                           }
Treap insert(Treap t, int val) {
                                                          2.3
                                                                Two Sat
  auto p1 = split(t, val);
  auto p2 = split(p1.f, val - 1);
                                                           void add(int u, int v) {
  return merge(p2.f, merge(new Node(val), p1.s));
                                                             graph[u].pb(v);
                                                             rgraph[v].pb(u);
                                                           }
Treap erase(Treap t, int val) {
  auto p1 = split(t, val);
                                                           void implication(int u, int v) {
  auto p2 = split(p1.f, val - 1);
                                                             \#define neg(u) ((n) + (u))
  return merge(p2.f, p1.s);
                                                             add(u, v);
                                                             add(neg(v), neg(u));
                                                           }
\mathbf{2}
     Graphs
2.1
      Tarjan algorithm (SCC)
                                                           pair<bool, vi> satisfy(int n) {
vector<vi> scc;
                                                             kosaraju(2 * n); // size of the two-sat is 2 * n
                                                             vi ans(n + 1, 0);
int tin[N], fup[N];
                                                             fore (u, 1, n + 1) {
bitset<N> still;
                                                               if (scc[u] == scc[neg(u)])
stack<int> stk;
int timer = 0;
                                                                 return {0, ans};
                                                               ans[u] = scc[u] > scc[neg(u)];
void tarjan(int u) {
  tin[u] = fup[u] = ++timer;
                                                             return {1, ans};
                                                           }
  still[u] = true;
  stk.push(u);
                                                                Topological sort
                                                          2.4
  for (int v : graph[u]) {
                                                           vi order;
    if (!tin[v])
                                                           int indeg[N];
      tarjan(v);
    if (still[v])
                                                           void topsort() { // first fill the indeg[]
      fup[u] = min(fup[u], fup[v]);
                                                             queue<int> qu;
  if (fup[u] == tin[u]) {
                                                             fore (u, 1, n + 1)
    scc.pb({});
                                                               if (indeg[u] == 0)
    int v;
                                                                 qu.push(u);
    do {
                                                             while (!qu.empty()) {
      v = stk.top();
                                                               int u = qu.front();
      stk.pop();
                                                               qu.pop();
      still[v] = false;
                                                               order.pb(u);
      scc.back().pb(v);
                                                               for (int v : graph[u])
    } while (v != u);
                                                                 if (--indeg[v] == 0)
  }
                                                                   qu.push(v);
}
```

```
}
                                                            void init(int r) {
                                                              dfs(r, pr[0]);
2.5
      Cutpoints and Bridges
                                                              fore (k, 1, LogN)
 int tin[N], fup[N], timer = 0;
                                                                fore (u, 1, n + 1)
                                                                  pr[k][u] = pr[k - 1][pr[k - 1][u]];
 void findWeakness(int u, int p = 0) {
                                                            }
   tin[u] = fup[u] = ++timer;
                                                           2.9
                                                                 Guni
   int children = 0;
   for (int v : graph[u]) if (v != p) {
                                                            int tin[N], tout[N], who[N], sz[N], heavy[N], color[N
     if (!tin[v]) {
                                                                 1:
       ++children;
                                                            int timer = 0;
       findWeakness(v, u);
       fup[u] = min(fup[u], fup[v]);
                                                            int dfs(int u, int pr = 0){
       if (fup[v] >= tin[u] && p) // u is a cutpoint
                                                              sz[u] = 1, tin[u] = ++timer, who[timer] = u;
       if (fup[v] > tin[u]) // bridge u -> v
                                                              for (int v : graph[u]) if (v != pr) {
                                                                sz[u] += dfs(v, u);
     fup[u] = min(fup[u], tin[v]);
                                                                if (sz[v] > sz[heavy[u]])
   }
                                                                  heavy[u] = v;
   if (!p && children > 1) // u is a cutpoint
                                                              return tout[u] = timer, sz[u];
                                                            }
2.6
     Detect a cycle
 bool cycle(int u) {
                                                            void guni(int u, int pr = 0, bool keep = 0) {
   vis[u] = 1;
                                                              for (int v : graph[u])
   for (int v : graph[u]) {
                                                                if (v != pr && v != heavy[u])
    if (vis[v] == 1)
                                                                  guni(v, u, ⁰);
       return true;
                                                              if (heavy[u])
     if (!vis[v] && cycle(v))
                                                                guni(heavy[u], u, 1);
       return true;
                                                              for (int v : graph[u])
                                                                if (v != pr && v != heavy[u])
   vis[u] = 2;
                                                                  fore (i, tin[v], tout[v] + 1)
   return false;
                                                                    add(color[who[i]]);
                                                              add(color[u]);
                                                              // Solve the subtree queries here
      Euler tour for Mo's in a tree
                                                              if (keep == 0)
Mo's in a tree, extended euler tour tin[u] = ++timer, tout[u]
                                                                fore (i, tin[u], tout[u] + 1)
= + + timer

\bullet u = lca(u, v), query(tin[u], tin[v])
                                                                  rem(color[who[i]]);
  • u \neq lca(u, v), query(tout[u], tin[v]) + query(tin[lca],
    tin[lca]
                                                           2.10 Centroid decomposition
     Lowest common ancestor (LCA)
                                                            int cdp[N], sz[N];
 const int LogN = 1 + __lg(N);
                                                            bitset<N> rem;
 int pr[LogN][N], dep[N];
                                                            int dfsz(int u, int p = 0) {
 void dfs(int u, int pr[]) {
                                                              sz[u] = 1;
   for (int v : graph[u])
                                                              for (int v : graph[u])
     if (v != pr[u]) {
                                                                if (v != p && !rem[v])
       pr[v] = u;
                                                                  sz[u] += dfsz(v, u);
       dep[v] = dep[u] + 1;
                                                              return sz[u];
       dfs(v, pr);
                                                            }
 }
                                                            int centroid(int u, int n, int p = 0) {
                                                              for (int v : graph[u])
 int lca(int u, int v){
                                                                if (v != p && !rem[v] && 2 * sz[v] > n)
   if (dep[u] > dep[v])
                                                                  return centroid(v, n, u);
     swap(u, v);
                                                              return u;
   fore (k, LogN, 0)
     if (dep[v] - dep[u] >= (1 << k))
       v = pr[k][v];
                                                            void solve(int u, int p = 0) {
   if (u == v)
                                                              cdp[u = centroid(u, dfsz(u))] = p;
     return u;
                                                              rem[u] = true;
   fore (k, LogN, 0)
                                                              for (int v : graph[u])
     if (pr[k][v] != pr[k][u])
                                                                if (!rem[v])
       u = pr[k][u], v = pr[k][v];
                                                                  solve(v, u);
   return pr[0][u];
                                                            }
 }
                                                           2.11 Heavy-light decomposition
                                                            int pr[N], dep[N], sz[N], heavy[N], head[N], pos[N],
 int dist(int u, int v) {
   return dep[u] + dep[v] - 2 * dep[lca(u, v)];
                                                                who[N], timer = \emptyset;
 }
                                                            Lazy* tree; // generally a lazy segtree
```

```
int dfs(int u) {
                                                                  u->mx = max(u->mx, v->mx);
   sz[u] = 1, heavy[u] = head[u] = 0;
                                                               }
   for (int v : graph[u]) if (v != pr[u]) {
                                                             }
     pr[v] = u;
     dep[v] = dep[u] + 1;
                                                             int dir(Splay u) {
     sz[u] += dfs(v);
                                                               if (!u->p) return -2; // root of the LCT component
    if (sz[v] > sz[heavy[u]])
                                                                if (u->p->ch[0] == u) return 0; // left child
      heavy[u] = v;
                                                                if (u->p->ch[1] == u) return 1; // right child
                                                                return -1; // root of current splay tree
  }
   return sz[u];
                                                              void add(Splay u, Splay v, int d) {
                                                                if (v) v->p = u;
 void hld(int u, int h) {
   head[u] = h, pos[u] = ++timer, who[timer] = u;
                                                               if (d \ge 0) u \ge ch[d] = v;
   if (heavy[u] != 0)
                                                             }
     hld(heavy[u], h);
   for (int v : graph[u])
                                                              void rot(Splay u) { // assume p and p->p propagated
     if (v != pr[u] && v != heavy[u])
                                                                int x = dir(u);
       hld(v, v);
                                                                Splay g = u - p;
                                                                add(g->p, u, dir(g));
                                                                add(g, u\rightarrow ch[x ^ 1], x);
 template <class F>
                                                                add(u, g, x ^ 1);
void processPath(int u, int v, F f) {
                                                                pull(g), pull(u);
   for (; head[u] != head[v]; v = pr[head[v]]) {
                                                             }
     if (dep[head[u]] > dep[head[v]]) swap(u, v);
     f(pos[head[v]], pos[v]);
                                                             void splay(Splay u) {
   }
                                                                #define isRoot(u) (dir(u) < 0)
   if (dep[u] > dep[v]) swap(u, v);
                                                                while (!isRoot(u) && !isRoot(u->p)) {
   if (u != v) f(pos[heavy[u]], pos[v]);
                                                                  push(u->p->p), push(u->p), push(u);
   f(pos[u], pos[u]); // process lca(u, v) too?
                                                                  rot(dir(u) == dir(u->p) ? u->p : u);
                                                                  rot(u);
void updatePath(int u, int v, lli z) {
                                                                if (!isRoot(u)) push(u->p), push(u), rot(u);
   processPath(u, v, [&](int 1, int r) {
                                                                push(u);
     tree->update(1, r, z);
                                                             }
  });
}
                                                             // puts u on the preferred path, then splay
                                                             void access(Splay u) {
lli queryPath(int u, int v) {
                                                                for (Splay v = u, last = 0; v; v = v -> p) {
   11i sum = 0:
                                                                  splay(v);
   processPath(u, v, [&](int 1, int r) {
                                                                  v \rightarrow ch[1] = last, pull(v), last = v;
     sum += tree->qsum(1, r);
                                                                splay(u);
  });
   return sum;
                                                             }
}
                                                             void rootify(Splay u) {
2.12
        Link-Cut tree
                                                               access(u), u->flip ^= 1, access(u);
                                                             }
 typedef struct Node* Splay;
 struct Node {
                                                             Splay lca(Splay u, Splay v) {
   int val, mx = 0;
                                                               if (u == v) return u;
   Splay ch[2] = \{0, 0\}, p = 0;
                                                                access(u), access(v);
   int sz = 1, flip = 0;
                                                                if (!u->p) return 0;
  Node(int val) : val(val), mx(val) {}
                                                                return splay(u), u->p ?: u;
};
                                                             }
void push(Splay u) {
                                                             bool connected(Splay u, Splay v) {
   if (!u || !u->flip)
                                                               return lca(u, v);
     return;
   swap(u->ch[0], u->ch[1]);
   for (Splay v : u->ch)
                                                             void link(Splay u, Splay v) { // make u parent of v,
    if (v) v->flip ^= 1;
                                                                  make sure they aren't connected
  u \rightarrow flip = 0;
                                                                if (!connected(u, v)) {
}
                                                                  rootify(v), access(u);
                                                                  add(v, u, ∅), pull(v);
void pull(Splay u) {
   #define gsz(t) (t ? t->sz : 0)
                                                             }
   u->sz = 1, u->mx = u->val;
   for (Splay v : u->ch) if (v) {
                                                             void cut(Splay u) { // cut u from its parent
     push(v);
                                                                access(u);
     u \rightarrow sz += gsz(v);
```

```
u - ch[0] = u - ch[0] - p = 0;
                                                                     qu.pop();
                                                                     for (Edge &e : g[u]) if (dist[e.v] == -1)
   pull(u);
 }
                                                                       if (e.cap - e.flow > eps) {
                                                                         dist[e.v] = dist[u] + 1;
 void cut(Splay u, Splay v) { // if u, v adj in tree
                                                                         qu.push(e.v);
                                                                       }
   rootify(u), access(v), cut(v);
                                                                   }
                                                                   return dist[t] != -1;
 Splay getRoot(Splay u) {
   access(u);
   while (u->ch[0])
                                                                F dfs(int u, F flow = numeric_limits<F>::max()) {
     u = u - ch[0], push(u);
                                                                   if (flow <= eps || u == t)
   return access(u), u;
                                                                     return max<F>(0, flow);
                                                                   for (int &i = ptr[u]; i < sz(g[u]); i++) {</pre>
                                                                     Edge &e = g[u][i];
 Splay lift(Splay u, int k) {
                                                                     if (e.cap - e.flow > eps && dist[u] + 1 == dist[
   push(u):
                                                                         e.v]) {
   int sz = gsz(u->ch[0]);
                                                                      F pushed = dfs(e.v, min<F>(flow, e.cap - e.flow
   if (sz == k)
                                                                          ));
     return splay(u), u;
                                                                       if (pushed > eps) {
   return k < sz? lift(u->ch[0], k) : lift(u->ch[1], k
                                                                         e.flow += pushed;
        - sz - 1);
                                                                         g[e.v][e.inv].flow -= pushed;
 }
                                                                         return pushed;
 Splay ancestor(Splay u, int k) {
                                                                     }
   return access(u), lift(u, gsz(u->ch[0]) - k);
                                                                   }
                                                                   return 0;
 Splay query(Splay u, Splay v) {
   return rootify(u), access(v), v;
                                                                F maxFlow() {
                                                                   F flow = 0;
                                                                   while (bfs()) {
 Splay lct[N];
                                                                     fill(all(ptr), 0);
                                                                     while (F pushed = dfs(s))
     \mathbf{Flows}
                                                                       flow += pushed;
3.1
     Dinic \mathcal{O}(min(E \cdot flow, V^2E))
                                                                   }
                                                                   return flow;
If the network is massive, try to compress it by looking for
                                                                }
patterns. Dinic with scaling works in \mathcal{O}(EV \cdot log(maxCap)).
                                                              };
 template <class F>
                                                             3.2
                                                                    Min cost flow \mathcal{O}(min(E \cdot flow, V^2E))
 struct Dinic {
                                                             If the network is massive, try to compress it by looking for
   struct Edge {
                                                             patterns.
     int v, inv;
     F cap, flow;
                                                              template <class C, class F>
     Edge(int v, F cap, int inv) :
                                                              struct Mcmf {
       v(v), cap(cap), flow(⁰), inv(inv){}
                                                                static constexpr F eps = (F) 1e-9;
                                                                struct Edge {
   };
                                                                   int u, v, inv;
   F eps = (F) 1e-9;
                                                                   F cap, flow;
   int s, t, n, m = 0;
   vector< vector<Edge> > g;
                                                                   Edge(int u, int v, C cost, F cap, int inv) :
   vi dist, ptr;
                                                                     u(u), v(v), cost(cost), cap(cap), flow(♥), inv(
                                                                         inv) {}
  Dinic(int n, int ss = -1, int tt = -1) :
     n(n), g(n + 5), dist(n + 5), ptr(n + 5) {
     s = ss == -1 ? n + 1 : ss;
                                                                int s, t, n, m = 0;
     t = tt == -1 ? n + 2 : tt;
                                                                vector< vector<Edge> > g;
                                                                vector<Edge*> prev;
                                                                vector<C> cost;
   void add(int u, int v, F cap) {
                                                                vi state;
     g[u].pb(Edge(v, cap, sz(g[v])));
     g[v].pb(Edge(u, 0, sz(g[u]) - 1));
                                                                Mcmf(int n, int ss = -1, int tt = -1):
     m += 2;
                                                                   n(n), g(n + 5), cost(n + 5), state(n + 5), prev(n + 5)
   }
                                                                       + 5) {
                                                                   s = ss == -1 ? n + 1 : ss;
                                                                   t = tt == -1 ? n + 2 : tt;
   bool bfs() {
     fill(all(dist), -1);
     queue<int> qu({s});
     dist[s] = 0;
                                                                void add(int u, int v, C cost, F cap) {
     while (sz(qu) && dist[t] == -1) {
                                                                   g[u].pb(Edge(u, v, cost, cap, sz(g[v])));
       int u = qu.front();
                                                                   g[v].pb(Edge(v, u, -cost, 0, sz(g[u]) - 1));
```

```
m += 2;
                                                                        if (match[v])
   }
                                                                          qu.push(match[v]);
                                                                      }
   bool bfs() {
                                                                 }
                                                                 return dist[0] != -1;
     fill(all(state), 0);
     fill(all(cost), numeric_limits<C>::max());
     deque<int> qu;
     qu.push_back(s);
                                                               bool dfs(int u) {
                                                                  for (int v : g[u])
     state[s] = 1, cost[s] = 0;
                                                                    if (!match[v] || (dist[u] + 1 == dist[match[v]]
     while (sz(qu)) {
       int u = qu.front(); qu.pop_front();
                                                                        && dfs(match[v]))) {
       state[u] = 2;
                                                                      match[u] = v, match[v] = u;
       for (Edge &e : g[u]) if (e.cap - e.flow > eps)
                                                                      return 1;
         if (cost[u] + e.cost < cost[e.v]) {</pre>
           cost[e.v] = cost[u] + e.cost;
                                                                 dist[u] = 1 << 30;
           prev[e.v] = &e;
                                                                 return 0;
           if (state[e.v] == 2 || (sz(qu) \&\& cost[qu.
               front()] > cost[e.v]))
             qu.push_front(e.v);
                                                               int maxMatching() {
           else if (state[e.v] == 0)
                                                                 int tot = 0;
             qu.push_back(e.v);
                                                                 while (bfs())
                                                                    fore (u, 1, n + 1)
           state[e.v] = 1;
         }
                                                                      tot += match[u] ? 0 : dfs(u);
     }
                                                                  return tot;
     return cost[t] != numeric_limits<C>::max();
                                                               }
                                                             };
                                                            3.4
                                                                   Hungarian \mathcal{O}(N^3)
   pair<C, F> minCostFlow() {
                                                            n jobs, m people
     C cost = 0; F flow = 0;
                                                             template <class C>
     while (bfs()) {
                                                             pair<C, vi> Hungarian(vector< vector<C> > &a) {
       F pushed = numeric_limits<F>::max();
                                                               int n = sz(a), m = sz(a[0]), p, q, j, k; // n \le m
       for (Edge* e = prev[t]; e != nullptr; e = prev[e
                                                              vector<C> fx(n, numeric_limits<C>::min()), fy(m, ∅);
           ->u])
                                                               vi x(n, -1), y(m, -1);
         pushed = min(pushed, e->cap - e->flow);
                                                               fore (i, 0, n)
       for (Edge* e = prev[t]; e != nullptr; e = prev[e
                                                                  fore (j, 0, m)
           ->u]) {
                                                                   fx[i] = max(fx[i], a[i][j]);
         e->flow += pushed;
                                                                fore (i, 0, n) {
         g[e->v][e->inv].flow -= pushed;
                                                                  vi t(m, -1), s(n + 1, i);
         cost += e->cost * pushed;
                                                                  for (p = q = 0; p \le q \&\& x[i] \le 0; p++)
                                                                    for (k = s[p], j = 0; j < m && x[i] < 0; j++)
       flow += pushed;
                                                                      if (abs(fx[k] + fy[j] - a[k][j]) < eps && t[j]</pre>
                                                                           < 0) {
     return make_pair(cost, flow);
                                                                        s[++q] = y[j], t[j] = k;
   }
                                                                        if (s[q] < 0) for (p = j; p >= 0; j = p)
};
                                                                          y[j] = k = t[j], p = x[k], x[k] = j;
3.3
      Hopcroft-Karp \mathcal{O}(E\sqrt{V})
                                                                      }
 struct HopcroftKarp {
                                                                 if (x[i] < 0) {
   int n, m = 0;
                                                                    C d = numeric_limits<C>::max();
   vector<vi> g;
                                                                    fore (k, 0, q + 1)
   vi dist, match;
                                                                      fore (j, 0, m) if (t[j] < 0)
                                                                        d = min(d, fx[s[k]] + fy[j] - a[s[k]][j]);
   HopcroftKarp(int _n) : n(5 + _n), g(n + 5), dist(n +
                                                                    fore (j, 0, m)
        5), match(n + 5, 0) {}
                                                                      fy[j] += (t[j] < 0 ? 0 : d);
                                                                    fore (k, 0, q + 1)
   void add(int u, int v) {
                                                                     fx[s[k]] = d;
     g[u].pb(v), g[v].pb(u);
                                                                   i--;
    m += 2;
                                                                 }
   }
                                                               }
                                                               C cost = 0;
   bool bfs() {
                                                               fore (i, 0, n) cost += a[i][x[i]];
     queue<int> qu;
                                                               return make_pair(cost, x);
     fill(all(dist), -1);
                                                             }
     fore (u, 1, n + 1)
                                                                  Strings
                                                            4
       if (!match[u])
                                                                 \mathbf{Hash}
                                                            4.1
         dist[u] = 0, qu.push(u);
                                                             vi p = {10006793, 1777771, 10101283, 10101823, 1013635
     while (!qu.empty()) {
       int u = qu.front(); qu.pop();
                                                                  9, 10157387, 10166249};
       for (int v : g[u])
                                                             vi mod = {999992867, 1070777777, 999727999, 1000008223
         if (dist[match[v]] == -1) {
                                                                  , 1000009999, 1000003211, 1000027163, 1000002193,
           dist[match[v]] = dist[u] + 1;
                                                                   1000000123};
```

```
int pw[2][N], ipw[2][N];
                                                               fore (i, 0, sz(s)) {
 struct Range : array<lli, 2> {
  int 1, r;
                                                                   j = p[j - 1];
                                                                 if (s[i] == t[j])
   Range(int 1, int r) : 1(1), r(r) { fill(0); }
                                                                   j++;
                                                                 if (j == sz(t))
 struct Hash {
   vector<vi> h;
                                                               return tot;
   Hash(string &s) : h(2, vi(sz(s) + 1, ∅)) {
                                                             }
     fore (i, 0, 2)
                                                            4.3
       fore (j, 0, sz(s)) {
                                                             int go[N][A];
         lli x = s[j] - 'a' + 1;
         h[i][j + 1] = (h[i][j] + x * pw[i][j]) % mod[i]
             ];
                                                               s += "$";
       }
                                                               vi p = lps(s);
   }
                                                               fore (i, 0, sz(s))
                                                                 fore (c, 0, A) {
   Range cut(int 1, int r) {
     Range f(1, r);
     fore (i, 0, 2) {
       f[i] = (h[i][r + 1] - h[i][1] + mod[i]) % mod[i]
       f[i] = f[i] * ipw[i][1] % mod[i];
                                                               s.pop_back();
    }
                                                             }
     return f;
   }
                                                            4.4 Z algorithm
 };
                                                             vi zf(string &s) {
                                                               vi z(sz(s), ₀);
 Range merge(vector<Range>& cuts) {
   Range g(-1, -1);
                                                                 if (i <= r)
   fore (j, sz(cuts), 0) { // downward!!
    Range f = cuts[j];
     fore (i, 0, 2) {
                                                                   ++z[i];
       f[i] += g[i] * pw[i][f.r - f.l + 1] % mod[i];
       f[i] %= mod[i];
    }
                                                               }
    swap(f, g);
                                                               return z;
   }
                                                             }
   return g;
                                                            4.5
 shuffle(all(p), rng), shuffle(all(mod), rng);
 fore (i, 0, 2) {
                                                               fore (k, 0, 2) {
   ipw[i][0] = inv(pw[i][0] = 1LL, mod[i]);
                                                                 int 1 = 0, r = 0;
   int q = inv(p[0], mod[i]);
   fore (j, 1, N) {
     pw[i][j] = 1LL * pw[i][j - 1] * p[0] % mod[i];
                                                                   if (i < r)
     ipw[i][j] = 1LL * ipw[i][j - 1] * q % mod[i];
   }
 }
                                                                       q + 1]
      KMP
4.2
                                                                   if (q > r)
period = n - p[n - 1], period(abcabc) = 3, n \mod period \equiv 0
                                                                     1 = p, r = q;
 vi lps(string &s) {
                                                                 }
   vi p(sz(s), ∅);
                                                               }
   int j = 0;
                                                               return pal;
   fore (i, 1, sz(s)) {
                                                             }
     while (j && s[i] != s[j])
       j = p[j - 1];
                                                                   Suffix array
     if (s[i] == s[j])
       j++;
    p[i] = j;
   }
   return p;
 }
 // how many times t occurs in s
 int kmp(string &s, string &t) {
                                                             struct SuffixArray {
   vi p = lps(t);
                                                               int n;
```

```
int j = 0, tot = 0;
    while (j && s[i] != t[j])
      tot++; // pos: i - sz(t) + 1;
    KMP automaton
void kmpAutomaton(string &s) {
      if (i && s[i] != 'a' + c)
        go[i][c] = go[p[i - 1]][c];
        go[i][c] = i + ('a' + c == s[i]);
  for (int i = 1, l = 0, r = 0; i < sz(s); i++) {
      z[i] = min(r - i + 1, z[i - 1]);
    while (i + z[i] < sz(s) \&\& s[i + z[i]] == s[z[i]])
    if (i + z[i] - 1 > r)
      l = i, r = i + z[i] - 1;
     Manacher algorithm
vector<vi> manacher(string &s) {
  vector<vi> pal(2, vi(sz(s), 0));
    fore (i, 0, sz(s)) {
      int t = r - i + !k;
        pal[k][i] = min(t, pal[k][l + t]);
      int p = i - pal[k][i], q = i + pal[k][i] - !k;
      while (p \ge 1 \& q + 1 < sz(s) \& s[p - 1] == s[
        ++pal[k][i], --p, ++q;
 • Duplicates \sum_{i=1}^{n} lcp[i]
 \bullet\, Longest Common Substring of various strings
   Add not Used characters between strings, i.e. a+\$+b+\#+c
   Use two-pointers to find a range [l, r] such that all notUsed
   characters are present, then query(lcp[l+1],..,lcp[r]) for
   that window is the common length.
```

```
string s;
  vi sa, lcp;
  SuffixArray(string &s) : n(sz(s) + 1), s(s), sa(n),
      lcp(n) {
    vi top(max(256, n)), rk(n);
    fore (i, 0, n)
      top[rk[i] = s[i] & 255]++;
    partial_sum(all(top), top.begin());
    fore (i, 0, n)
      sa[--top[rk[i]]] = i;
    vi sb(n);
    for (int len = 1, j; len < n; len <<= 1) {</pre>
      fore (i, 0, n) {
        j = (sa[i] - len + n) % n;
        sb[top[rk[j]]++] = j;
      }
      sa[sb[top[0] = 0]] = j = 0;
      fore (i, 1, n) {
        if (rk[sb[i]] != rk[sb[i - 1]] || rk[sb[i] +
            len] != rk[sb[i - 1] + len])
          top[++j] = i;
        sa[sb[i]] = j;
      }
      copy(all(sa), rk.begin());
      copy(all(sb), sa.begin());
      if (j >= n - 1)
        break:
    for (int i = 0, j = rk[lcp[0] = 0], k = 0; i < n - 0
          1; i++, k++)
      while (k >= 0 && s[i] != s[sa[j - 1] + k])
        lcp[j] = k--, j = rk[sa[j] + 1];
  }
  char at(int i, int j) {
    int k = sa[i] + j;
    return k < n ? s[k] : 'z' + 1;
  }
  bool count(string &t) {
    ii lo(0, n - 1), hi(0, n - 1);
    fore (i, 0, sz(t)) {
      while (lo.f + 1 < lo.s) {</pre>
        int mid = (lo.f + lo.s) / 2;
        (at(mid, i) < t[i] ? lo.f : lo.s) = mid;
      }
      while (hi.f + 1 < hi.s) {</pre>
        int mid = (hi.f + hi.s) / 2;
        (t[i] < at(mid, i) ? hi.s : hi.f) = mid;
      int p1 = (at(lo.f, i) == t[i] ? lo.f : lo.s);
      int p2 = (at(hi.s, i) == t[i] ? hi.s : hi.f);
      if (at(p1, i) != t[i] || at(p2, i) != t[i] || p1
           > p2)
        return 0;
      lo = hi = ii(p1, p2);
    return lo.s - lo.f + 1;
  }
};
      Suffix automaton
 • len[u] - len[link[u]] = distinct strings
 • Number of different substrings (dp)
```

4.7

$$diff(u) = 1 + \sum_{v \in trie[u]} diff(v)$$

• Total length of all different substrings (2 x dp)

$$totLen(u) = \sum_{v \in trie[u]} diff(v) + totLen(v)$$

- Leftmost occurrence pos[u] = len[u] 1if is **clone** then pos[clone] = pos[q]
- All occurrence positions
- Smallest cyclic shift Construct sam of s + s, find the lexicographically smallest path of sz(s)
- Shortest non-appearing string

```
nonAppearing(u) = \min_{v \in trie[u]} nonAppearing(v) + 1
struct SuffixAutomaton {
 vector< map<char, int> > trie;
 vi link, len;
 int last;
 SuffixAutomaton() { last = newNode(); }
 int newNode() {
    trie.pb(\{\}), link.pb(-1), len.pb(\emptyset);
    return sz(trie) - 1;
 void extend(char c) {
    int u = newNode();
    len[u] = len[last] + 1;
    int p = last;
    while (p != -1 && !trie[p].count(c)) {
      trie[p][c] = u;
      p = link[p];
    if (p == -1)
      link[u] = 0;
    else {
      int q = trie[p][c];
      if (len[p] + 1 == len[q])
        link[u] = q;
      else {
        int clone = newNode();
        len[clone] = len[p] + 1;
        trie[clone] = trie[q];
        link[clone] = link[q];
        while (p != -1 && trie[p][c] == q) {
          trie[p][c] = clone;
          p = link[p];
        link[q] = link[u] = clone;
    }
    last = u;
  string qkthSubstring(lli kth, int u = 0) {
    // number of different substrings (dp)
    string s = "";
    while (kth > 0)
      for (auto &[c, v] : trie[u]) {
        if (kth <= diff(v)) {</pre>
          s.pb(c), kth--, u = v;
          break;
        kth -= diff(v);
      }
    return s;
 void occurs() {
```

```
// \text{ occ[u]} = 1, \text{ occ[clone]} = 0
    vi who;
    fore (u, 1, sz(trie))
     who.pb(u);
    sort(all(who), [&](int u, int v) {
     return len[u] > len[v];
    });
    for (int u : who)
      occ[link[u]] += occ[u];
  int queryOccurences(string &s, int u = 0) {
    for (char c : s) {
      if (!trie[u].count(c))
        return 0;
      u = trie[u][c];
    }
    return occ[u];
  }
  int longestCommonSubstring(string &s, int u = 0) {
    int mx = 0, clen = 0;
    for (char c : s) {
      while (u && !trie[u].count(c)) {
        u = link[u];
        clen = len[u];
      }
      if (trie[u].count(c))
        u = trie[u][c], clen++;
      mx = max(mx, clen);
    }
    return mx;
  }
  string smallestCyclicShift(int n, int u = 0) {
    string s = "";
    fore (i, 0, n) {
      char c = trie[u].begin()->f;
      s += c;
      u = trie[u][c];
    }
    return s;
  }
  int leftmost(string &s, int u = 0) {
    for (char c : s) {
      if (!trie[u].count(c))
        return -1;
     u = trie[u][c];
    }
    return pos[u] - sz(s) + 1;
 }
};
     Aho corasick
struct AhoCorasick {
  vector< map<char, int> > trie;
  vi link, cnt;
  AhoCorasick() { newNode(); }
  int newNode() {
    trie.pb(\{\}), link.pb(\emptyset), cnt.pb(\emptyset);
    return sz(trie) - 1;
  void insert(string &s, int u = 0) {
    for (char c : s) {
      if (!trie[u][c])
        trie[u][c] = newNode();
      u = trie[u][c];
```

```
}
     cnt[u]++;
   }
   int go(int u, char c) {
     while (u && !trie[u].count(c))
       u = link[u];
     return trie[u][c];
   void pushLinks() {
     queue<int> qu;
     qu.push(∅);
     while (!qu.empty()) {
       int u = qu.front();
       qu.pop();
       for (auto &[c, v] : trie[u]) {
         link[v] = u ? go(link[u], c) : 0;
         cnt[v] += cnt[link[v]];
         qu.push(v);
     }
   }
   int match(string &s, int u = 0) {
     int ans = 0;
     for (char c : s)
       u = go(u, c), ans += cnt[u];
     return ans;
 };
4.9
     Eertree
 struct Eertree {
   vector< map<char, int> > trie;
   vi link, len;
   string s = "$";
   int last;
   Eertree() {
     last = newNode(), newNode();
     link[0] = 1, len[1] = -1;
   }
   int newNode() {
     trie.pb(\{\}), link.pb(\emptyset), len.pb(\emptyset);
     return sz(trie) - 1;
   int go(int u) {
     while (s[sz(s) - len[u] - 2] != s.back())
       u = link[u];
     return u;
   void extend(char c) {
     s += c;
     int u = go(last);
     if (!trie[u][c]) {
       int v = newNode();
       len[v] = len[u] + 2;
       link[v] = trie[go(link[u])][c];
       trie[u][c] = v;
     }
     last = trie[u][c];
   }
 };
```

5 Dynamic Programming

5.1 Matrix Chain Multiplication

```
int dp(int 1, int r) {
                                                                   }
   if (1 > r)
     return 0LL;
                                                                   void add(lli m, lli c) {
   int &ans = mem[l][r];
                                                                     auto z = insert(\{m, c, \emptyset\}), y = z++, x = y;
                                                                     while (isect(y, z)) z = erase(z);
   if (!done[1][r]) {
                                                                     if (x != begin() && isect(--x, y))
     done[l][r] = true, ans = inf;
                                                                       isect(x, y = erase(y));
     fore (k, l, r + 1) // split in [l, k] [k + 1, r]
       ans = min(ans, dp(1, k) + dp(k + 1, r) + add);
                                                                     while ((y = x) != begin() && (--x)->p >= y->p)
   }
                                                                       isect(x, erase(y));
   return ans;
 }
                                                                   lli query(lli x) {
5.2
       Digit DP
                                                                     if (empty()) return 0LL;
Counts the amount of numbers in [l, r] such are divisible by k.
                                                                     auto f = *lower_bound(x);
(flag nonzero is for different lengths)
                                                                     return f(x);
It can be reduced to dp(i, x, small), and has to be solve like
                                                                  }
f(r) - f(l-1)
                                                                };
 #define state [i][x][small][big][nonzero]
 int dp(int i, int x, bool small, bool big, bool
                                                                      Divide and conquer \mathcal{O}(kn^2) \Rightarrow \mathcal{O}(k \cdot nlogn)
                                                               5.5
     nonzero) {
   if (i == sz(r))
                                                               Split the array of size n into k continuous groups. k \leq n
     return x % k == 0 && nonzero;
                                                               cost(a, c) + cost(b, d) \le cost(a, d) + cost(b, c) with a \le b \le c \le d
   int &ans = mem state;
                                                                void dc(int cut, int 1, int r, int optl, int optr) {
   if (done state != timer) {
                                                                   if (r < 1)
     done state = timer;
                                                                     return;
     ans = 0;
                                                                   int mid = (1 + r) / 2;
     int lo = small ? 0 : 1[i] - '0';
                                                                   pair<lli, int> best = {inf, -1};
     int hi = big ? 9 : r[i] - '0';
                                                                   fore (p, optl, min(mid, optr) + 1) {
     fore (y, lo, max(lo, hi) + 1) {
                                                                     11i nxtGroup = dp[~cut & 1][p - 1] + cost(p, mid);
       bool small2 = small | (y > 1o);
                                                                     if (nxtGroup < best.f)</pre>
       bool big2 = big | (y < hi);
                                                                       best = {nxtGroup, p};
       bool nonzero2 = nonzero | (x > 0);
       ans += dp(i + 1, (x * 10 + y) % k, small2, big2,
                                                                   dp[cut & 1][mid] = best.f;
             nonzero2);
                                                                   int opt = best.s;
     }
                                                                   dc(cut, 1, mid - 1, optl, opt);
   }
                                                                   dc(cut, mid + 1, r, opt, optr);
   return ans;
                                                                }
5.3
       Knapsack 0/1
                                                                 fore (i, 1, n + 1)
 for (auto &cur : items)
                                                                  dp[1][i] = cost(1, i);
   fore (w, W + 1, cur.w) // [cur.w, W]
                                                                 fore (cut, 2, k + 1)
     umax(dp[w], dp[w - cur.w] + cur.cost);
                                                                  dc(cut, cut, n, cut, n);
      Convex Hull Trick \mathcal{O}(n^2) \Rightarrow \mathcal{O}(n)
                                                                     Knuth optimization \mathcal{O}(n^3) \Rightarrow \mathcal{O}(n^2)
dp[i] = \min_{j < i} (dp[j] + b[j] * a[i])
dp[i][j] = \min_{k < j} (dp[i-1][k] + b[k] * a[j])
                                                               dp[l][r] = \min_{l \le k \le r} \{dp[l][k] + dp[k][r]\} + cost(l, r)
b[j] \ge b[j+1] optionally a[i] \le a[i+1]
                                                                 fore (len, 1, n + 1)
 // for doubles, use inf = 1/.0, div(a,b) = a / b
                                                                   fore (1, 0, n) {
 struct Line {
                                                                     int r = 1 + len - 1;
   mutable lli m, c, p;
                                                                     if (r > n - 1)
   bool operator < (const Line &1) const { return m < 1</pre>
                                                                       break;
                                                                     if (len <= 2) {
   bool operator < (lli x) const { return p < x; }</pre>
                                                                       dp[1][r] = 0;
   lli operator ()(lli x) const { return m * x + c; }
                                                                       opt[1][r] = 1;
 };
                                                                       continue;
 struct DynamicHull : multiset<Line, less<>> {
                                                                     dp[1][r] = inf;
   lli div(lli a, lli b) {
                                                                     fore (k, opt[l][r - 1], opt[l + 1][r] + 1) {
     return a / b - ((a ^ b) < 0 && a % b);
                                                                       lli cur = dp[l][k] + dp[k][r] + cost(l, r);
   }
                                                                       if (cur < dp[l][r]) {</pre>
                                                                         dp[1][r] = cur;
   bool isect(iterator x, iterator y) {
                                                                         opt[1][r] = k;
     if (y == end())
       return x->p = inf, 0;
                                                                    }
     if (x->m == y->m)
                                                                   }
       x->p = (x->c > y->c ? inf : -inf);
     else
                                                                     Do all submasks of a mask
       x->p = div(x->c - y->c, y->m - x->m);
                                                                for (int B = A; B > 0; B = (B - 1) & A)
     return x->p >= y->p;
```

6 Game Theory

6.1 Grundy Numbers

```
If the moves are consecutive S = \{1, 2, 3, ..., x\} the game can be
solved like stackSize \pmod{x+1} \neq 0
 int mem[N];
 int mex(set<int> &st) {
   int x = 0;
   while (st.count(x))
     x++;
   return x;
 }
 int grundy(int n) {
   if (n < 0)
     return inf:
   if (n == 0)
     return 0;
   int &g = mem[n];
   if (g == -1) {
     set<int> st;
     for (int x : {a, b})
       st.insert(grundy(n - x));
     g = mex(st);
   }
```

7 Combinatorics

return g;

Combinatorics table					
Number	Factorial	Catalan			
0	1	1			
1	1	1			
2	2	2			
3	6	5			
4	24	14			
5	120	42			
6	720	132			
7	5,040	429			
8	40,320	1,430			
9	362,880	4,862			
10	3,628,800	16,796			
11	39,916,800	58,786			
12	479,001,600	208,012			
13	6,227,020,800	742,900			

7.1 Factorial

```
fac[0] = 1LL;
fore (i, 1, N)
  fac[i] = lli(i) * fac[i - 1] % mod;
ifac[N - 1] = fpow(fac[N - 1], mod - 2);
fore (i, N - 1, 0)
  ifac[i] = lli(i + 1) * ifac[i + 1] % mod;
```

7.2 Factorial mod smallPrime

```
lli facMod(lli n, int p) {
    lli r = 1LL;
    for (; n > 1; n /= p) {
        r = (r * ((n / p) % 2 ? p - 1: 1)) % p;
        fore (i, 2, n % p + 1)
            r = r * i % p;
    }
    return r % p;
}
```

7.3 Lucas theorem

Changes $\binom{n}{k}$ mod p, with $n \ge 2e6, k \ge 2e6$ and $p \le 1e7$

$$\binom{n}{k} \equiv \prod_{i=0}^{n} \binom{n_i}{k_i} \bmod p$$

7.4 Stars and bars

Enclosing n objects in k boxes

$$\binom{n+k-1}{k-1} = \binom{n+k-1}{n}$$

7.5 N choose K

```
\binom{n}{k} = \binom{n-1}{k-1} + \binom{n-1}{k}
\binom{n}{k_1, k_2, \dots, k_m} = \frac{n!}{k_1! * k_2! * \dots * k_m!}
lli choose(int n, int k) {
    if (n < 0 || k < 0 || n < k)
        return OLL;
    return fac[n] * ifac[k] % mod * ifac[n - k] % mod;
}

lli choose(int n, int k) {
    double r = 1;
    fore (i, 1, k + 1)
        r = r * (n - k + i) / i;
    return lli(r + 0.01);
}

7.6 Catalan
```

7.7 Burnside's lemma

$$|classes| = \frac{1}{|G|} \cdot \sum_{x \in G} f(x)$$

7.8 Prime factors of N!

```
vector< pair<lli, int> > factorialFactors(int n) {
  vector< pair<lli, int> > fac;
  for (lli p : primes) {
    if (n < p)
       break;
    lli mul = 1LL, k = 0;
    while (mul <= n / p) {
       mul *= p;
       k += n / mul;
    }
    fac.emplace_back(p, k);
}
return fac;
}</pre>
```

8 Number Theory

8.1 Goldbach conjecture

- All number > 6 can be written as sum of 3 primes
- All even number > 2 can be written as sum of 2 primes

8.2 Sieve of Eratosthenes

```
Numbers up to 2e8
int erat[N >> 6];
#define bit(i) ((i >> 1) & 31)
#define prime(i) !(erat[i >> 6] >> bit(i) & 1)
void bitSieve() {
```

```
for (int i = 3; i * i < N; i += 2) if (prime(i))</pre>
                                                                  111 x = 2 + rng() \% (n - 3), c = 1 + rng() \% 20, y
     for (int j = i * i; j < N; j += (i << 1))
                                                                       = f(x, c, n), g;
       erat[j >> 6] |= 1 << bit(j);
                                                                  while ((g = \_gcd(n + y - x, n)) == 1)
                                                                   x = f(x, c, n), y = f(f(y, c, n), c, n);
                                                                  if (g != n) return g;
To factorize divide x by factor[x] until is equal to 1
 void factorizeSieve() {
                                                                return -1;
   iota(factor, factor + N, ∅);
                                                              }
   for (int i = 2; i * i < N; i++) if (factor[i] == i)</pre>
     for (int j = i * i; j < N; j += i)</pre>
                                                              void pollard(lli n, map<lli, int> &fac) {
       factor[j] = i;
                                                                if (n == 1) return;
 }
                                                                if (n % 2 == 0) {
                                                                  fac[2]++;
Use it if you need a huge amount of phi[x] up to some N
                                                                  pollard(n / 2, fac);
 void phiSieve() {
                                                                  return;
   isp.set(); // bitset<N> is faster
   iota(phi, phi + N, 0);
                                                                if (miller(n)) {
   fore (i, 2, N) if (isp[i])
                                                                  fac[n]++;
     for (int j = i; j < N; j += i) {
                                                                  return;
       isp[j] = (i == j);
       phi[j] /= i;
                                                                11i x = rho(n);
       phi[j] *= i - 1;
                                                                pollard(x, fac);
     }
                                                                pollard(n / x, fac);
  }
                                                             }
                                                                   Amount of divisors
8.3
     Phi of euler
 lli phi(lli n) {
                                                             lli divs(lli n) {
                                                                11i cnt = 1LL;
   if (n == 1)
     return 0;
                                                                for (lli p : primes) {
   11i r = n;
                                                                  if(p*p*p>n)
   for (11i i = 2; i * i <= n; i++)
                                                                    break:
                                                                  if (n % p == 0) {
     if (n % i == 0) {
       while (n % i == 0)
                                                                    11i k = 0;
         n /= i;
                                                                    while (n > 1 \&\& n \% p == 0)
       r = r / i;
                                                                     n /= p, ++k;
     }
                                                                    cnt *= (k + 1);
   if (n > 1)
                                                                  }
                                                                }
     r = r / n;
                                                                11i sq = mysqrt(n); // A binary search, the last x *
   return r;
                                                                if (miller(n))
      Miller-Rabin
8.4
                                                                 cnt *= 2;
 bool compo(lli p, lli d, lli n, lli k) {
                                                                else if (sq * sq == n && miller(sq))
  11i x = fpow(p % n, d, n), i = k;
                                                                  cnt *= 3;
   while (x != 1 && x != n - 1 && p % n && i--)
                                                                else if (n > 1)
     x = mul(x, x, n);
                                                                  cnt *= 4;
   return x != n - 1 && i != k;
                                                                return cnt;
                                                              }
                                                                  Bézout's identity
 bool miller(lli n) {
                                                             a_1 * x_1 + a_2 * x_2 + \dots + a_n * x_n = g
   if (n < 2 || n % 6 % 4 != 1)
                                                              g = \gcd(a_1, a_2, ..., a_n)
     return (n | 1) == 3;
   int k = __builtin_ctzll(n - 1);
   lli d = n >> k;
                                                             8.8 GCD
   for (lli p: {2, 3, 5, 7, 11, 13, 17, 19, 23, 29, 31
                                                             a \le b; gcd(a+k, b+k) = gcd(b-a, a+k)
       , 37}) {
                                                                  _{
m LCM}
     if (compo(p, d, n, k))
       return 0;
                                                             x = p * lcm(a_1, a_2, ..., a_k) + q, 0 \le q \le lcm(a_1, a_2, ..., a_k)
     if (compo(2 + rng() % (n - 3), d, n, k))
                                                              x \pmod{a_i} \equiv q \pmod{a_i} as a_i \mid lcm(a_1, a_2, ..., a_k)
       return 0;
                                                             8.10
                                                                    Euclid
   }
                                                              pair<lli, lli> euclid(lli a, lli b) {
   return 1;
 }
                                                                if (b == 0)
                                                                  return {1, 0};
     Pollard-Rho
                                                                auto p = euclid(b, a % b);
11i f(1li x, 1li c, 1li mod) {
                                                                return {p.s, p.f - a / b * p.s};
  return (mul(x, x, mod) + c) % mod;
                                                                    Chinese remainder theorem
 1li rho(lli n) {
                                                              pair<lli, lli> crt(pair<lli, lli> a, pair<lli, lli> b)
   while (1) {
                                                                   {
```

```
if (a.s < b.s)
    swap(a, b);
  auto p = euclid(a.s, b.s);
  11i g = a.s * p.f + b.s * p.s, l = a.s / g * b.s;
  if ((b.f - a.f) % g != ∅)
    return {-1, -1}; // no solution
 p.f = a.f + (b.f - a.f) % b.s * p.f % b.s / g * a.s;
  return \{p.f + (p.f < 0) * 1, 1\};
    Math
9.1 Progressions
Arithmetic progressions
```

9

```
a_n = a_1 + (n-1) * diff
\sum_{i=1}^{n} a_i = n * \frac{a_1 + a_n}{2}
```

Geometric progressions

```
a_n = a_1 * r^{n-1}
\sum_{k=1}^{n} a_1 * r^k = a_1 * \left(\frac{r^{n+1} - 1}{r - 1}\right) : r \neq 1
```

$9.2^{\frac{1}{k-1}}$ Mod multiplication

```
lli mul(lli x, lli y, lli mod) {
  11i r = 0LL;
  for (x \%= mod; y > 0; y >>= 1) {
    if (y \& 1) r = (r + x) \% mod;
    x = (x + x) \% mod;
  }
  return r;
```

9.3Fpow

```
1li fpow(lli x, lli y, lli mod) {
  lli r = 1;
  for (; y > 0; y >>= 1) {
    if (y & 1) r = mul(r, x, mod);
    x = mul(x, x, mod);
  }
  return r;
}
```

9.4 Fibonacci

$$\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}^n = \begin{bmatrix} fib_{n+1} & fib_n \\ fib_n & fib_{n-1} \end{bmatrix}$$

10 Geometry

10.1 Real

```
const ld eps = 1e-9;
#define eq(a, b) abs((a) - (b)) \le eps
#define neq(a, b) !eq(a, b)
#define geq(a, b) (a) - (b) \ge eps
#define leq(a, b) (a) - (b) \leq eps
#define ge(a, b) (a) - (b) > eps
#define le(a, b) (a) - (b) < -eps
```

10.2 Point

```
int sgn(ld x) {
  return x > 0 ? 1 : (x < 0 ? -1 : 0);
template <class T>
struct Point {
 typedef Point<T> P;
  T x, y;
  explicit Point(T x = 0, T y = 0) : x(x), y(y) {}
  P operator + (const P &p) const {
   return P(x + p.x, y + p.y); }
  P operator - (const P &p) const {
```

```
return P(x - p.x, y - p.y); }
   P operator * (T k) const {
     return P(x * k, y * k); }
   P operator / (T k) const {
     return P(x / k, y / k); }
   T dot(const P &p) { return x * p.x + y * p.y; }
   T cross(const P &p) { return x * p.y - y * p.x; }
   double length() const { return sqrtl(norm()); }
   T norm() const { return x * x + y * y; }
   double angle() { return atan2(y, x); }
   P perp() const { return P(-y, x); }
   P unit() const { return (*this) / length(); }
   P rotate (double angle) const {
     return P(x * cos(angle) - y * sin(angle),
             x * sin(angle) + y * cos(angle)); }
   bool operator == (const P &p) const {
     return eq(x, p.x) && eq(y, p.y); }
   bool operator != (const P &p) const {
     return neq(x, p.x) \mid\mid neq(y, p.y); }
   friend ostream & operator << (ostream &os, P &p) {</pre>
     return os << "(" << p.x << ", " << p.y << ")";
   friend istream & operator >> (istream &is, P &p) {
     return cin >> p.x >> p.y;
 };
 using P = Point<double>;
 double ccw(P a, P b, P c) {
   return (b - a).cross(c - a);
 }
10.3
       Angle Between Vectors
double angleBetween(P a, P b) {
   double x = a.dot(b) / a.length() / b.length();
   return acos(max(-1.0, min(1.0, x)));
 }
10.4 Area Poligon
 double area(vector<P> &pts) {
   double sum = 0;
   fore (i, 0, n)
     sum += pts[i].cross(pts[(i + 1) % sz(pts)]);
   return abs(sum / 2);
 }
       Area Poligon In Circle
 vector<P> intersectLineCircle(const P &a, const P &v,
     const P &c, ld r) {
   1d h_2 = r * r - v.cross(c - a) * v.cross(c - a) / v.
   P p = a + v * v.dot(c - a) / v.norm();
   if (eq(h2, 0))
     return {p}; // line tangent to circle
   else if (le(h2, 0))
     return {}; // no intersection
     point u = v.unit() * sqrt(h2);
     return {p - u, p + u}; // two points of
         intersection (chord)
 bool pointInLine(const P &a, const P &v, const P &p) {
   return eq((p - a).cross(v), 0);
```

```
bool pointInSegment(const P &a, const P &b, const P &p
                                                                     ans))
     ) {
                                                                  st.erase(points[pos++]);
   return pointInLine(a, b - a, p) && leq((a - p).dot(b
                                                                auto lo = st.lower_bound({points[i].x - ans - eps,
        - p), 0);
                                                                     -inf});
                                                                auto hi = st.upper_bound({points[i].x + ans + eps,
 int pointInCircle(const P &c, ld r, const P &p) {
                                                                     -inf});
   ld 1 = (p - c).length() - r;
                                                                for (auto it = lo; it != hi; ++it) {
   return (le(1, 0) ? 1 : (eq(1, 0) ? -1 : 0));
                                                                  ld d = (points[i] - *it).length();
                                                                  if (le(d, ans))
 vector<P> intersectSegmentCircle(const P &a, const P &
                                                                    ans = d, p = points[i], q = *it;
     b, const point &c, ld r) {
   vector<P> points = intersectLineCircle(a, b - a, c,
                                                                st.insert(points[i]);
       r), ans;
                                                              }
   for (const P &p : points) {
                                                              return {p, q};
    if (pointInSegment(a, b, p)) ans.pb(p);
                                                            }
   }
                                                           10.7
                                                                   Convex Hull
  return ans;
                                                            vector<P> convexHull(vector<P> &pts) {
}
                                                              int n = sz(pts);
 1d signed_angle(const P &a, const P &b) {
                                                              vector<P> low, up;
   return sgn(a.cross(b)) * acosl(a.dot(b) / (a.length
                                                              sort(all(pts), [&](P a, P b) {
       () * b.length()));
                                                                return a.x == b.x ? a.y < b.y : a.x < b.x;
1d intersectPolygonCircle(const vector<P> &points,
                                                              pts.erase(unique(all(pts)), pts.end());
     const P &c, ld r) {
                                                              if (n <= 2)
   int n = points.size();
                                                                return pts;
   1d ans = 0;
                                                              fore (i, 0, n) {
   for (int i = 0; i < n; ++i) {
                                                                while(sz(low) \ge 2 && (low.end()[-1] - low.end()[-
    P p = points[i], q = points[(i + 1) % n];
                                                                    2]).cross(pts[i] - low.end()[-1]) <= 0)
    bool p_inside = (pointInCircle(c, r, p) != 0);
                                                                  low.pop_back();
    bool q_inside = (pointInCircle(c, r, q) != 0);
                                                                low.pb(pts[i]);
     if (p_inside && q_inside) {
      ans += (p - c).cross(q - c);
                                                              fore (i, n, 0) {
     } else if (p_inside && !q_inside) {
                                                                while(sz(up) \ge 2 \& (up.end()[-1] - up.end()[-2])
      P s1 = intersectSegmentCircle(p, q, c, r)[0];
                                                                    .cross(pts[i] - up.end()[-1]) \le 0)
      P s2 = intersectSegmentCircle(c, q, c, r)[0];
      ans += (p - c).cross(s1 - c) + r * r *
                                                                  up.pop_back();
                                                                up.pb(pts[i]);
           signed_angle(s1 - c, s2 - c);
     } else if (!p_inside && q_inside) {
                                                              low.pop_back(), up.pop_back();
      P s1 = intersectSegmentCircle(c, p, c, r)[0];
                                                              low.insert(low.end(), all(up));
      P s2 = intersectSegmentCircle(p, q, c, r)[0];
                                                              return low;
       ans += (s_2 - c).cross(q - c) + r * r *
           signed_angle(s1 - c, s2 - c);
    } else {
                                                                   Distance Point Line
      auto info = intersectSegmentCircle(p, q, c, r);
                                                            double distancePointLine(P a, P v, P p){
       if (info.size() <= 1) {</pre>
                                                              return (proj(p - a, v) - (p - a)).length();
        ans += r * r * signed_angle(p - c, q - c);
      } else {
        P s2 = info[0], s3 = info[1];
                                                           10.9
                                                                  Get Circle
        P s1 = intersectSegmentCircle(c, p, c, r)[0];
                                                            pair<P, double> getCircle(P m, P n, P p){
        P s4 = intersectSegmentCircle(c, q, c, r)[0];
                                                              P c = intersectLines((n + m) / 2, (n - m).perp(), (p)
        ans += (s_2 - c).cross(s_3 - c) + r * r * (
                                                                   + m) / 2, (p - m).perp());
             signed_angle(s1 - c, s2 - c) +
                                                              double r = (c - m).length();
             signed_angle(s3 - c, s4 - c));
                                                              return {c, r};
      }
                                                            }
    }
                                                           10.10
                                                                   Intersects Line
   }
   return abs(ans) / 2;
                                                            int intersectLinesInfo (P a1, P v1, P a2, P v2) { // v
                                                                 1 = b - a, v2 = d - c
                                                              if (v1.cross(v2) == 0)
10.6
        Closest Pair Of Points
                                                                return (a2 - a1).cross(v1) == 0 ? -1 : 0; // -1:
                                                                    infinity Ps, 0: no Ps
 pair<P, P> cpp(vector<P> points) {
                                                              else
   sort(all(points), [&](P a, P b) {
                                                                return 1; // single P
    return le(a.y, b.y);
                                                            }
   });
   set<P> st;
                                                            P intersectLines (P a1, P v1, P a2, P v2) {
   ld ans = inf;
                                                              return a1 + v1 * ((a2 - a1).cross(v2) / v1.cross(v2)
   P p, q;
                                                                  );
   int pos = 0, n = sz(points);
                                                            }
   fore (i, 0, n) {
     while (pos < i && geq(points[i].y - points[pos].y,</pre>
                                                          10.11
                                                                     Intersects Line Segment
```

```
}
 int intersectLineSegmentInfo(P a, P v, P c, P d) {
  P v2 = d - c;
   ld det = v.cross(v2);
                                                           bool PInConvexPolygon(const vector<P> &seg, const P &p
   if (det == 0) {
                                                               ) {
    if ((c - a).cross(v) == 0)
                                                             int n = sz(seg);
     return -1; // infinity points
                                                             if (neq(seg[0].cross(p), 0) && sgn(seg[0].cross(p))
                                                                  != sgn(seg[0].cross(seg[n - 1])))
     return 0; //no points
                                                               return false;
                                                             if (neq(seg[n - 1].cross(p), 0) && sgn(seg[n - 1].
   } else
     return sgn(v.cross(c - a)) != sgn(v.cross(d - a))
                                                                 cross(p)) != sgn(seg[n - 1].cross(seg[0])))
                                                               return false:
}
                                                             if (eq(seg[0].cross(p), 0))
                                                               return geq(seg[0].length(), p.length());
          Intersects Segment
10.12
                                                             int 1 = 0, r = n - 1;
 int intersectSegmentsInfo(const P &a, const P &b,
                                                             while (r - 1 > 1) {
     const P &c, const P &d) {
                                                               int m = 1 + ((r - 1) >> 1);
   P v1 = b - a, v2 = d - c;
                                                               if (geq(seg[m].cross(p), 0))
   int t = sgn(v1.cross(c - a)), u = sgn(v1.cross(d - a))
                                                                 1 = m;
       ));
                                                               else
   if (t == u) {
                                                                 r = m:
     if (t == 0) {
      if (PInSegment(a, b, c) || PInSegment(a, b, d)
                                                             return eq(fabs(seg[1].cross(seg[1 + 1])), fabs((p -
           || PInSegment(c, d, a) || PInSegment(c, d,
                                                                  seg[1]).cross(p - seg[1 + 1])) +
                                                                     fabs(p.cross(seg[1])) + fabs(p.cross(seg[1 +
        return -1; // infinity Ps
                                                                           1])));
                                                           }
         return 0; // no P
                                                          10.16
                                                                     Point In Polygon
     } else
                                                           int pointInPolygon(const vector<P> &pts, P p) { // O(N
       return 0; // no P
   } else
       return sgn(v2.cross(a - c)) != sgn(v2.cross(b -
                                                            int n = sz(pts), ans = 0;
                                                            fore (i, 0, n) {
           c)); // 1: single P 0: no P
                                                             P = pts[i], b = pts[(i + 1) % n];
}
                                                             if (pointInSegment(a, b, p))
          Is Convex
10.13
                                                                 return -1; // on perimeter
bool isConvex(vector<P> pts) {
                                                             if (a.y > b.y)
   int n = sz(pts);
                                                                 swap(a,b);
   bool hasPos = false, hasNeg = false;
                                                             if (a.y <= p.y && b.y > p.y && (a - p).cross(b - p)
   fore (i, 0, n) {
                                                                 > 0)
    P first = pts[(i + 1) % n] - pts[i];
                                                                 ans ^= 1;
    P second = pts[(i + 2) % n] - pts[(i + 1) % n];
    double sign = first.cross(second);
                                                            return ans ? 1 : 0; // inside, outside
    if (sign > 0) hasPos = true;
    if (sign < 0) hasNeg = true;</pre>
                                                                     Point In Segment
   }
                                                           bool pointInSegment(P a, P b, P p){
  return !(hasPos && hasNeg);
                                                             return (b - a).cross(p - a) == 0 && (a - p).dot(b -
}
                                                                 p) <= 0;
10.14
          Perimeter
                                                           }
 double perimeter(vector<P> &pts){
                                                          10.18
                                                                     Points Of Tangency
   int n = sz(pts);
                                                           pair<P, P> pointsOfTangency(P c, double r, P p){
   double sum = 0;
                                                             P v = (p - c).unit() * r;
   fore (i, 0, n)
                                                             double cos_theta = r / (p - c).length();
     sum += (pts[(i + 1) % n] - pts[i]).length();
                                                             double theta = acos(max(-1.0, min(1.0, cos_theta)));
   return sum;
                                                             return {c + v.rotate(-theta), c + v.rotate(theta)};
                                                           }
10.15
          Point In Convex Polygon logN
                                                          10.19
                                                                     Projection
                                                           P proj(P a, P v){
// first preprocess: seg = process(points)
                                                             v = v / v.unit();
 // for each query: PInConvexPolygon(seg, p - pts[0])
                                                             return v * a.dot(v);
vector<P> process(const vector<P> &pts) {
                                                           }
   int n = sz(pts);
   rotate(pts.begin(), min_element(all(pts), [&](P a, P
                                                          10.20
                                                                     Projection Line
                                                           P projLine(P a, P v, P p){
    return a.x == b.x ? a.y < b.y : a.x < b.x;
                                                             return a + proj(p - a, v);
   }), pts.end());
                                                           }
   vector < P > seg(n - 1);
                                                                     Reflection Line
                                                          10.21
   fore (i, 0, n - 1)
                                                           P reflectionLine(P a, P v, P p){
    seg[i] = pts[i + 1] - pts[0];
                                                             return a * 2 - p + proj(p - a, v) * 2;
   return seg;
```

```
}
```

10.22 Signed Distance Point Line

```
double signedDistancePointLine(P a, P v, P p){
  return v.cross(p - a) / v.length();
}
```

10.23 Sort Along Line

```
void sortAlongLine(P a, P v, vector<P> & pts){
  sort(pts.begin(), pts.end(), [&](P u, P w){
    return u.dot(v) < w.dot(v);
  });
}</pre>
```

10.24 Intersects Line Circle

11 Bit tricks

$\mathrm{Bits}++$				
Operations on int	Function			
x & -x	Least significant bit in x			
lg(x)	Most significant bit in x			
c = x&-x, r = x+c;	Next number after x with same			
(((r^x) » 2)/c) r	number of bits set			
builtin_	Function			
popcount(x)	Amount of 1's in x			
clz(x)	0's to the left of biggest bit			
ctz(x)	0's to the right of smallest bit			

11.1 Bitset

Operation	Function			
_Find_first()	Least significant bit			
_Find_next(idx)	First set bit after index idx			
any(), none(), all()	Just what the expression says			
set(), reset(), flip()	Just what the expression says x2			
to_string('.', 'A')	Print 011010 like .AA.A.			