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Think twice, code once Template

```
tem.cpp
 #pragma GCC optimize("Ofast,unroll-loops,no-stack-
     protector")
#include <bits/stdc++.h>
using namespace std;
#ifdef LOCAL
 #include "debug.h"
 #else
 #define debug(...)
 #endif
 #define df(b, e) ((b) > (e))
 #define fore(i, b, e) for (auto i = (b) - df(b, e); i
     != e - df(b, e); i += 1 - 2 * df(b, e))
 #define sz(x) int(x.size())
 #define all(x) begin(x), end(x)
 #define f first
 #define s second
 #define pb push_back
 typedef long long lli;
 typedef long double ld;
 typedef pair<int, int> ii;
 typedef vector<int> vi;
 int main() {
   cin.tie(0)->sync_with_stdio(0), cout.tie(0);
   // solve the problem here D:
   return 0;
 debug.h
 template <class A, class B>
ostream & operator << (ostream& os, pair<A, B> p) {
   return os << "(" << p.first << ", " << p.second << "</pre>
       )";
 template <class A, class B, class C>
basic_ostream<A, B>& operator << (basic_ostream<A, B>&
      os, const C& c) {
   os << "[";
   for (const auto &x : c)
    os << ", " + 2 * (&x == &*begin(c)) << x;
   return os << "]";</pre>
}
void print(string s) { cout << endl; }</pre>
 template <class H, class... T>
 void print(string s, H h, T... t) {
   do { cout << s[0]; s = s.substr(1);</pre>
   } while (s.size() && s[0] != ',');
  cout << ": " << h;
  print(s, t...);
 #define debug(...) print(#__VA_ARGS__, __VA_ARGS__)
Randoms
 mt19937 rng(chrono::steady_clock::now().
     time_since_epoch().count());
uniform_int_distribution<int> uid(A, B);
Fastio
namespace fastio {
  int ptr, ye;
   char temp[25], str[32333667], out[15333667];
```

```
void init() { // init() first
     ptr = 0, ye = 0;
     fread(str, 1, 32333667, stdin);
   inline int number() { // x = number()
     int i, j, val = 0;
     while (str[ptr] < 45 || str[ptr] > 57)
       ptr++;
     while (str[ptr] > 47 && str[ptr] < 58)</pre>
       val = (val * 10) + (str[ptr++] - 48);
     return val;
   inline void convert(int x) { // convert(x) then
       print(
     int i, d = 0;
     if (x < 0)
       x = -x, out[ye++] = 45;
     do {
       temp[++d] = (x \% 10) + 48, x /= 10;
     } while (x > 0);
     for (i = d; i; i--)
       out[ye++] = temp[i];
     out[ye++] = 10;
   inline void print() {
     fwrite(out, 1, ye, stdout);
 using namespace fastio;
Compilation
 touch a_in{1..9} // make files a_in1, a_in2,..., a_in9
 tee {a..m}.cpp < tem.cpp // "" with tem.cpp like base
 cat > a_in1 // write on file a_in1
 gedit a_in1 // open file a_in1
 rm -r a.cpp // deletes file a.cpp :'(
 gedit ~/.zshenv // Write here everything that's below
 alias FLAGS='-Wall -Wextra -Wshadow -
     D_GLIBCXX_ASSERTIONS -fmax-errors=3 -02 -w'
 go() {
 g++ --std=c++11 $2 ${FLAGS} $1.cpp && ./a.out
 }
 debug() { go $1 -DLOCAL < $2 }</pre>
 run() { go $1 "" < $2 }
 random() { // Make small test cases!!!
  g++ --std=c++11 $1.cpp -o prog
  g++ --std=c++11 gen.cpp -o gen
  g++ --std=c++11 brute.cpp -o brute
  for ((i = 1; i \le 200; i++)); do
   printf "Test case #$i"
   ./gen > in
   diff -uwi <(./prog < in) <(./brute < in) > $1_diff
   if [[ ! $? -eq 0 ]]; then
   printf "Wrong answer\n"
   break
   else
   printf "Accepted\n"
   fi
  done
 }
 test() {
  g++ --std=c++11 $1.cpp -o prog
  for ((i = 1; i \le 50; i++)); do
```

```
[[ -f $1_in$i ]] || break
   printf "Test case #$i"
                                                            int query(int 1, int r) {
   diff -uwi <(./prog < $1_in$i) $1_out$i > $1_diff
                                                              int k = \lg[r - 1 + 1];
                                                              return min(sp[k][1], sp[k][r - (1 << k) + 1]);
   if [[ ! $? -eq 0 ]]; then
   printf "Wrong answer\n"
                                                            }
   else
   printf "Accepted\n"
                                                            void sparse() {
   fi
                                                              fore (i, 2, N + 1)
  done
                                                                lg[i] = lg[i >> 1] + 1;
                                                              fore (i, 0, n)
                                                                sp[0][i] = a[i];
Bump allocator
                                                              for (int k = 1; (1 << k) <= n; k++)
 static char buf[450 << 20];</pre>
                                                                fore (1, 0, n - (1 << k) + 1) {
                                                                  int r = 1 + (1 << (k - 1));
 void* operator new(size_t s) {
   static size_t i = sizeof buf; assert(s < i);</pre>
                                                                  sp[k][1] = min(sp[k - 1][1], sp[k - 1][r]);
   return (void *) &buf[i -= s];
                                                            }
 void operator delete(void *) {}
                                                           1.3
                                                                 Min-Max queue
     Data structures
1
                                                            template <class T>
                                                            struct MinQueue : deque< pair<T, int> > {
     Disjoint set with rollback
                                                              // add a element to the right {val, pos}
 struct Dsu {
                                                              void add(T val, int pos) {
   vector<int> pr, tot;
                                                                while (!empty() && back().f >= val)
   stack<ii> what;
                                                                  pop_back();
                                                                emplace_back(val, pos);
   Dsu(int n = 0) : pr(n + 5), tot(n + 5, 1) {
    iota(all(pr), ∅);
                                                              // remove all less than pos
   }
                                                              void rem(int pos) {
                                                                while (front().s < pos)</pre>
   int find(int u) {
                                                                  pop_front();
    return pr[u] == u ? u : find(pr[u]);
                                                              T qmin() { return front().f; }
   void unite(int u, int v) {
                                                            };
     u = find(u), v = find(v);
                                                                  Squirtle decomposition
     if (u == v)
      what.emplace(-1, -1);
                                                           The perfect block size is squirtle of N
     else {
       if (tot[u] < tot[v])</pre>
                                                            int blo[N], cnt[N][B], a[N];
         swap(u, v);
      what.emplace(u, v);
                                                            void update(int i, int x) {
       tot[u] += tot[v];
                                                              cnt[blo[i]][x]--;
       pr[v] = u;
                                                              a[i] = x;
                                                              cnt[blo[i]][x]++;
   }
   ii rollback() {
                                                            int query(int 1, int r, int x) {
     ii last = what.top();
                                                              int tot = 0;
     what.pop();
                                                              while (1 \le r)
     int u = last.f, v = last.s;
                                                                if (1 % B == 0 && 1 + B - 1 <= r) {</pre>
     if (u != -1) {
                                                                  tot += cnt[blo[1]][x];
       tot[u] -= tot[v];
                                                                  1 += B;
      pr[v] = v;
                                                                } else {
                                                                  tot += (a[1] == x);
     return last;
                                                                  1++;
 };
                                                              return tot;
                                                            }
      Sparse table
 int lg[N + 1], sp[1 + __lg(N)][N];
                                                                In-Out trick
 int query(int 1, int r) {
                                                            vector<int> in[N], out[N];
   int sum = OLL;
   fore (k, 1 + lg[N], 0)
                                                            vector<Query> queries;
    if (1 + (1 << k) - 1 <= r) {
       sum += sp[k][1];
                                                            fore (x, 0, N) {
      1 += (1 << k);
                                                              for (int i : in[x])
                                                                add(queries[i]);
   return sum;
```

for (int i : out[x])

```
updatesSoFar)
     rem(queries[i]);
 }
                                                              • If the update lies inside the current query, update the
                                                                 data structure properly
      Parallel binary search
1.6
 int lo[Q], hi[Q];
                                                                struct Update {
 queue<int> solve[N];
                                                                  int pos, prv, nxt;
 vector<Query> queries;
 fore (it, 0, 1 + __lg(N)) {
                                                                void undo(Update &u) {
                                                                  if (1 <= u.pos && u.pos <= r) {</pre>
   fore (i, 0, sz(queries))
     if (lo[i] != hi[i]) {
                                                                    rem(u.pos);
       int mid = (lo[i] + hi[i]) / 2;
                                                                    a[u.pos] = u.prv;
       solve[mid].emplace(i);
                                                                    add(u.pos);
                                                                  } else {
     }
   fore (x, 0, n) {
                                                                    a[u.pos] = u.prv;
     // simulate
                                                                  }
     while (!solve[x].empty()) {
                                                                }
       int i = solve[x].front();
                                                              • Solve the problem :D
       solve[x].pop();
       if (can(queries[i]))
                                                                l = queries[0].1, r = 1 - 1, upd = sz(updates) - 1;
         hi[i] = x;
                                                                for (Query &q : queries) {
                                                                  while (upd < q.upd)</pre>
         lo[i] = x + 1;
                                                                    dodo(updates[++upd]);
     }
                                                                  while (upd > q.upd)
   }
                                                                    undo(updates[upd--]);
 }
                                                                  // write down the normal Mo's algorithm
                                                                }
1.7
       Mo's algorithm
 vector<Query> queries;
 // N = 1e6, so aprox. sqrt(N) +/- C
                                                            1.8
                                                                   Ordered tree
 uniform_int_distribution<int> dis(970, 1030);
                                                             #include <ext/pb_ds/assoc_container.hpp>
 const int blo = dis(rng);
                                                             #include <ext/pb_ds/tree_policy.hpp>
 sort(all(queries), [&](Query a, Query b) {
                                                             using namespace __gnu_pbds;
   const int ga = a.l / blo, gb = b.l / blo;
   if (ga == gb)
                                                             template <class K, class V = null_type>
     return (ga & 1) ? a.r < b.r : a.r > b.r;
                                                             using ordered_tree = tree<K, V, less<K>, rb_tree_tag,
   return a.1 < b.1;
                                                                  tree_order_statistics_node_update>;
 });
                                                             // less_equal<K> for multiset, multimap (?
 int 1 = queries[0].1, r = 1 - 1;
                                                             #define grank order_of_key
 for (Query &q : queries) {
                                                             #define qkth find_by_order
   while (r < q.r)
                                                            1.9 Unordered tree
     add(++r);
   while (r > q.r)
                                                             struct chash {
     rem(r--);
                                                               const uint64_t C = uint64_t(2e18 * 3) + 71;
   while (1 < q.1)
                                                               const int R = rng();
     rem(1++);
                                                               uint64_t operator ()(uint64_t x) const {
   while (1 > q.1)
                                                                 return __builtin_bswap64((x ^ R) * C); }
     add(--1);
                                                             };
   ans[q.i] = solve();
                                                             template <class K, class V = null_type>
                                                             using unordered_tree = gp_hash_table<K, V, chash>;
To make it faster, change the order to hilbert(l, r)
                                                                    D-dimensional Fenwick tree
 11i hilbert(int x, int y, int pw = 21, int rot = 0) {
                                                             template <class T, int ...N>
   if (pw == 0)
                                                             struct Fenwick {
     return 0;
                                                               T v = 0;
   int hpw = 1 << (pw - 1);
                                                               void update(T v) { this->v += v; }
   int k = ((x < hpw ? y < hpw ? 0 : 3 : y < hpw ? 1 :
                                                               T query() { return v; }
       2) + rot) & 3;
                                                             };
   const int d[4] = \{3, 0, 0, 1\};
   11i a = 1LL << ((pw << 1) - 2);</pre>
                                                             template <class T, int N, int ...M>
   111 b = hilbert(x & (x ^{hpw}), y & (y ^{hpw}), pw - 1
                                                             struct Fenwick<T, N, M...> {
        , (rot + d[k]) & 3);
                                                               #define lsb(x) (x & -x)
   return k * a + (d[k] ? a - b - 1 : b);
                                                               Fenwick<T, M...> fenw[N + 1];
Mo's algorithm with updates in \mathcal{O}(n^{\frac{5}{3}})
                                                               template <typename... Args>
                                                               void update(int i, Args... args) {
  • Choose a block of size n^{\frac{2}{3}}
                                                                 for (; i <= N; i += lsb(i))</pre>
  • Do a normal Mo's algorithm, in the Query definition
                                                                   fenw[i].update(args...);
```

}

add an extra variable for the updatesSoFar

• Sort the queries by the order (l/block, r/block,

```
template <typename... Args>
                                                                    (R = new Per(m + 1, r)) -> build();
   T query(int 1, int r, Args... args) {
                                                                    pull();
     T v = 0;
                                                                  }
     for (; r > 0; r -= lsb(r))
                                                                  Per* update(int p, lli v) {
       v += fenw[r].query(args...);
     for (--1; 1 > 0; 1 -= lsb(1))
                                                                    if (p < 1 || r < p)
       v -= fenw[1].query(args...);
                                                                      return this;
     return v;
                                                                    Per* t = new Per(1, r);
   }
                                                                    if (1 == r) {
};
                                                                      t->sum = v;
                                                                      return t;
1.11 Dynamic segment tree
 struct Dyn {
                                                                    t \rightarrow L = L \rightarrow update(p, v);
   int 1, r;
                                                                    t \rightarrow R = R \rightarrow update(p, v);
   11i sum = 0;
                                                                    return t->pull();
   Dyn *L, *R;
   Dyn(\textbf{int } 1, \textbf{ int } r) : 1(1), r(r), L(0), R(0) \{ \}
                                                                  1li qsum(int 11, int rr) {
                                                                    if (r < ll || rr < l)
   void pull() {
                                                                      return 0;
     sum = (L ? L->sum : 0);
                                                                    if (ll <= l && r <= rr)</pre>
     sum += (R ? R->sum : 0);
                                                                      return sum;
                                                                    return L->qsum(11, rr) + R->qsum(11, rr);
                                                                 }
   void update(int p, lli v) {
                                                               };
     if (1 == r) {
       sum += v;
                                                               Per *tree[T];
       return;
     }
                                                                       Wavelet tree
                                                              1.13
     int m = (1 + r) / 2;
                                                               struct Wav {
     if (p <= m) {
                                                                  #define iter int * // vector<int>::iterator
       if (!L)
                                                                  int lo, hi;
         L = new Dyn(1, m);
                                                                  Wav *L, *R;
       L->update(p, v);
                                                                  vi amt;
     } else {
       if (!R)
                                                                  Wav(int lo, int hi) : lo(lo), hi(hi), L(0), R(0) {}
         R = new Dyn(m + 1, r);
       R->update(p, v);
                                                                  void build(iter b, iter e) { // array 1-indexed
     }
                                                                    if (lo == hi || b == e)
     pull();
                                                                      return;
                                                                    amt.reserve(e - b + 1);
                                                                    amt.pb(0);
   lli qsum(int ll, int rr) {
                                                                    int m = (lo + hi) / 2;
     if (rr < 1 || r < 11 || r < 1)</pre>
                                                                    for (auto it = b; it != e; it++)
       return 0;
                                                                      amt.pb(amt.back() + (*it <= m));</pre>
     if (ll <= l && r <= rr)
                                                                    auto p = stable_partition(b, e, [=](int x) {
       return sum;
                                                                      return x <= m;</pre>
     int m = (1 + r) / 2;
                                                                    });
     return (L ? L->qsum(ll, rr) : 0) +
                                                                    (L = new Wav(lo, m))->build(b, p);
            (R ? R->qsum(11, rr) : 0);
                                                                    (R = new Wav(m + 1, hi)) -> build(p, e);
   }
};
        Persistent segment tree
                                                                  int qkth(int 1, int r, int k) {
 struct Per {
                                                                    if (r < 1)
   int 1, r;
                                                                      return 0;
   11i sum = 0;
                                                                    if (lo == hi)
   Per *L, *R;
                                                                      return lo;
                                                                    if (k <= amt[r] - amt[l - 1])</pre>
   Per(int 1, int r) : 1(1), r(r), L(0), R(0) {}
                                                                      return L->qkth(amt[1 - 1] + 1, amt[r], k);
                                                                    return R->qkth(l - amt[l - 1], r - amt[r], k - amt
   Per* pull() {
                                                                         [r] + amt[1 - 1]);
     sum = L -> sum + R -> sum;
     return this;
   }
                                                                  int qleq(int 1, int r, int mx) {
                                                                    if (r < 1 || mx < lo)</pre>
   void build() {
                                                                      return 0;
     if (1 == r)
                                                                    if (hi <= mx)</pre>
       return;
                                                                      return r - 1 + 1;
                                                                    return L->qleq(amt[l - 1] + 1, amt[r], mx) +
     int m = (1 + r) / 2;
                                                                           R \rightarrow qleq(l - amt[l - 1], r - amt[r], mx);
     (L = new Per(1, m))->build();
```

```
}
};
                                                             pair<Treap, Treap> split(Treap t, int val) {
                                                               // <= val goes to the left, > val to the right
1.14
      Li Chao tree
                                                               if (!t)
struct Fun {
                                                                 return {t, t};
  11i m = 0, c = inf;
                                                               push(t);
  1li operator ()(lli x) const { return m * x + c; }
                                                               if (val < t->val) {
                                                                 auto p = split(t->ch[0], val);
                                                                 t->ch[0] = p.s;
struct LiChao {
                                                                 return {p.f, pull(t)};
  Fun f;
   11i 1, r;
                                                               auto p = split(t->ch[1], val);
  LiChao *L, *R;
                                                               t->ch[1] = p.f;
                                                               return {pull(t), p.s};
  LiChao(int 1, int r, Fun f = {}) :
                                                             }
    l(1), r(r), f(f), L(0), R(0) {}
                                                             pair<Treap, Treap> splitsz(Treap t, int sz) {
   void add(Fun &g) {
                                                               // <= sz goes to the left, > sz to the right
     if (f(1) \le g(1) \&\& f(r) \le g(r))
                                                               if (!t)
                                                                 return {t, t};
     if (g(1) < f(1) && g(r) < f(r)) {
                                                               push(t);
      f = g;
                                                               if (sz <= gsz(t->ch[0])) {
       return;
                                                                 auto p = splitsz(t->ch[0], sz);
                                                                 t->ch[0] = p.s;
    11i m = (1 + r) / 2;
                                                                 return {p.f, pull(t)};
     if (g(m) < f(m))
      swap(f, g);
                                                               auto p = splitsz(t->ch[1], sz - gsz(t->ch[\emptyset]) - 1);
     if (g(1) \le f(1))
                                                               t->ch[1] = p.f;
      L = L ? (L->add(g), L) : new LiChao(1, m, g);
                                                               return {pull(t), p.s};
     R = R ? (R->add(g), R) : new LiChao(m + 1, r, g);
   }
                                                             Treap merge(Treap 1, Treap r) {
                                                               if (!1 || !r)
  1li query(lli x) {
                                                                 return 1 ? 1 : r;
     if (1 == r)
                                                               push(l), push(r);
      return f(x);
                                                               if (l->pri > r->pri)
     int m = (1 + r) / 2;
                                                                 return 1->ch[1] = merge(1->ch[1], r), pull(1);
     if (x \le m)
                                                               else
      return min(f(x), L ? L->query(x) : inf);
                                                                 return r->ch[0] = merge(1, r->ch[0]), pull(r);
     return min(f(x), R ? R->query(x) : inf);
                                                             }
   }
};
                                                             Treap qkth(Treap t, int k) { // 0-indexed
                                                               if (!t)
1.15
       Treap
                                                                 return t;
 typedef struct Node* Treap;
                                                               push(t);
 struct Node {
                                                               int sz = gsz(t->ch[0]);
   uint32_t pri = rng();
                                                               if (sz == k)
   int val;
                                                                 return t;
   Treap ch[2] = \{0, 0\};
                                                               return k < sz? qkth(t->ch[0], k) : qkth(t->ch[1], k
   int sz = 1, flip = 0;
                                                                     - sz - 1);
  Node(int val) : val(val) {}
                                                             }
                                                             int qrank(Treap t, int val) { // 0-indexed
void push(Treap t) {
                                                               if (!t)
  if (!t)
                                                                 return -1;
     return:
                                                               push(t);
   if (t->flip) {
                                                               if (val < t->val)
     swap(t->ch[0], t->ch[1]);
                                                                 return qrank(t->ch[0], val);
     for (Treap ch : t->ch) if (ch)
                                                               if (t->val == val)
      ch->flip ^= 1;
                                                                 return gsz(t->ch[0]);
     t\rightarrow flip = 0;
                                                               return gsz(t->ch[0]) + qrank(t->ch[1], val) + 1;
  }
                                                             }
}
                                                             Treap insert(Treap t, int val) {
Treap pull(Treap t) {
                                                               auto p1 = split(t, val);
  #define gsz(t) (t ? t->sz : 0)
                                                               auto p2 = split(p1.f, val - 1);
   t->sz = 1;
                                                               return merge(p2.f, merge(new Node(val), p1.s));
   for (Treap ch : t->ch)
                                                             }
    push(ch), t\rightarrow sz += gsz(ch);
   return t;
                                                             Treap erase(Treap t, int val) {
}
```

```
auto p1 = split(t, val);
   auto p2 = split(p1.f, val - 1);
                                                             void implication(int u, int v) {
   return merge(p2.f, p1.s);
                                                               \#define neg(u) ((n) + (u))
                                                               add(u, v);
}
                                                               add(neg(v), neg(u));
\mathbf{2}
     Graphs
                                                             }
      Tarjan algorithm (SCC)
2.1
                                                             pair<bool, vi> satisfy(int n) {
vector<vi> scc;
                                                               kosaraju(2 * n); // size of the two-sat is 2 * n
int tin[N], fup[N];
                                                               vi ans(n + 1, 0);
bitset<N> still;
                                                               fore (u, 1, n + 1) {
stack<int> stk;
                                                                 if (scc[u] == scc[neg(u)])
 int timer = 0;
                                                                   return {0, ans};
                                                                 ans[u] = scc[u] > scc[neg(u)];
void tarjan(int u) {
   tin[u] = fup[u] = ++timer;
                                                               return {1, ans};
   still[u] = true;
                                                             }
   stk.push(u);
                                                            2.4
                                                                  Topological sort
   for (int v : graph[u]) {
    if (!tin[v])
                                                             vi order:
       tarjan(v);
                                                             int indeg[N];
    if (still[v])
       fup[u] = min(fup[u], fup[v]);
                                                             void topsort() { // first fill the indeg[]
                                                               fore (u, 1, n + 1)
   if (fup[u] == tin[u]) {
                                                                 if (indeg[u] == 0)
    scc.pb({});
                                                                   order.pb(u);
    int v;
                                                               fore (i, ∅, sz(order)) {
    do {
                                                                 int u = order[i];
       v = stk.top();
                                                                 for (int v : graph[u])
      stk.pop();
                                                                   if (--indeg[v] == 0)
       still[v] = false;
                                                                     order.pb(v);
       scc.back().pb(v);
    } while (v != u);
                                                             }
   }
                                                            2.5
                                                                   Cutpoints and Bridges
}
                                                             int tin[N], fup[N], timer = 0;
2.2
      Kosaraju algorithm (SCC)
int scc[N], k = 0;
                                                             void findWeakness(int u, int p = 0) {
char vis[N];
                                                               tin[u] = fup[u] = ++timer;
vi order;
                                                               int children = 0;
                                                               for (int v : graph[u]) if (v != p) {
 void dfs1(int u) {
                                                                 if (!tin[v]) {
   vis[u] = 1;
                                                                   ++children;
   for (int v : graph[u])
                                                                   findWeakness(v, u);
    if (vis[v] != 1)
                                                                   fup[u] = min(fup[u], fup[v]);
       dfs1(v);
                                                                   if (fup[v] >= tin[u] && p) // u is a cutpoint
   order.pb(u);
                                                                   if (fup[v] > tin[u]) // bridge u -> v
                                                                 fup[u] = min(fup[u], tin[v]);
void dfs2(int u, int k) {
   vis[u] = 2, scc[u] = k;
                                                               if (!p && children > 1) // u is a cutpoint
   for (int v : rgraph[u]) // reverse graph
                                                             }
     if (vis[v] != 2)
                                                            2.6 Detect a cycle
       dfs2(v, k);
                                                             bool cycle(int u) {
                                                               vis[u] = 1;
                                                               for (int v : graph[u]) {
void kosaraju() {
                                                                 if (vis[v] == 1)
   fore (u, 1, n + 1)
    if (vis[u] != 1)
                                                                   return true:
                                                                 if (!vis[v] && cycle(v))
       dfs1(u);
                                                                   return true;
   reverse(all(order));
   for (int u : order)
                                                               vis[u] = 2;
    if (vis[u] != 2)
                                                               return false;
       dfs2(u, ++k);
                                                             }
                                                                   Euler tour for Mo's in a tree
2.3
     Two Sat
                                                            Mo's in a tree, extended euler tour tin[u] = ++timer, tout[u]
void add(int u, int v) {
                                                            = \underset{\bullet}{+} + \underset{u = lca(u, \ v), \ query(tin[u], \ tin[v])}{+}
  graph[u].pb(v);
   rgraph[v].pb(u);
                                                              • u \neq lca(u, v), query(tout[u], tin[v]) + query(tin[lca],
}
```

tin[lca]

```
Lowest common ancestor (LCA)
                                                                  rem(color[who[i]]);
 const int LogN = 1 + __lg(N);
                                                            }
int pr[LogN][N], dep[N];
                                                           2.10
                                                                  Centroid decomposition
                                                           int cdp[N], sz[N];
void dfs(int u, int pr[]) {
                                                           bitset<N> rem;
   for (int v : graph[u])
     if (v != pr[u]) {
                                                            int dfsz(int u, int p = 0) {
      pr[v] = u;
                                                              sz[u] = 1;
      dep[v] = dep[u] + 1;
                                                              for (int v : graph[u])
      dfs(v, pr);
                                                                if (v != p && !rem[v])
                                                                  sz[u] += dfsz(v, u);
}
                                                              return sz[u];
int lca(int u, int v){
  if (dep[u] > dep[v])
                                                            int centroid(int u, int n, int p = 0) {
    swap(u, v);
                                                              for (int v : graph[u])
   fore (k, LogN, 0)
                                                                if (v != p && !rem[v] && 2 * sz[v] > n)
    if (dep[v] - dep[u] >= (1 << k))
                                                                  return centroid(v, n, u);
      v = pr[k][v];
                                                              return u;
   if (u == v)
    return u;
   fore (k, LogN, 0)
                                                            void solve(int u, int p = 0) {
    if (pr[k][v] != pr[k][u])
                                                              cdp[u = centroid(u, dfsz(u))] = p;
      u = pr[k][u], v = pr[k][v];
                                                              rem[u] = true;
   return pr[0][u];
                                                              for (int v : graph[u])
}
                                                                if (!rem[v])
                                                                  solve(v, u);
 int dist(int u, int v) {
                                                            }
  return dep[u] + dep[v] - 2 * dep[lca(u, v)];
                                                                  Heavy-light decomposition
                                                            int pr[N], dep[N], sz[N], heavy[N], head[N], pos[N],
void init(int r) {
                                                                who[N], timer = 0;
  dfs(r, pr[0]);
                                                            Lazy* tree; // generally a lazy segtree
   fore (k, 1, LogN)
     fore (u, 1, n + 1)
                                                            int dfs(int u) {
      pr[k][u] = pr[k - 1][pr[k - 1][u]];
                                                              sz[u] = 1, heavy[u] = head[u] = 0;
}
                                                              for (int v : graph[u]) if (v != pr[u]) {
                                                                pr[v] = u;
2.9
     Guni
                                                                dep[v] = dep[u] + 1;
 int tin[N], tout[N], who[N], sz[N], heavy[N], color[N
                                                                sz[u] += dfs(v);
                                                                if (sz[v] > sz[heavy[u]])
int timer = 0;
                                                                  heavy[u] = v;
                                                              }
 int dfs(int u, int pr = 0){
                                                              return sz[u];
   sz[u] = 1;
                                                            }
   tin[u] = ++timer, who[timer] = u;
   for (int v : graph[u]) if (v != pr) {
                                                            void hld(int u, int h) {
    sz[u] += dfs(v, u);
                                                              head[u] = h, pos[u] = ++timer, who[timer] = u;
    if (sz[v] > sz[heavy[u]])
                                                              if (heavy[u] != 0)
                                                                hld(heavy[u], h);
      heavy[u] = v;
                                                              for (int v : graph[u])
   tout[u] = timer;
                                                                if (v != pr[u] && v != heavy[u])
   return sz[u];
                                                                  hld(v, v);
                                                            }
void guni(int u, int pr = 0, bool keep = 0) {
                                                            template <class F>
   for (int v : graph[u])
                                                            void processPath(int u, int v, F fun) {
     if (v != pr && v != heavy[u])
                                                              for (; head[u] != head[v]; v = pr[head[v]]) {
      guni(v, u, ⁰);
                                                                if (dep[head[u]] > dep[head[v]])
   if (heavy[u])
                                                                  swap(u, v);
    guni(heavy[u], u, 1);
                                                                fun(pos[head[v]], pos[v]);
   for (int v : graph[u])
    if (v != pr && v != heavy[u])
                                                              if (dep[u] > dep[v])
      fore (i, tin[v], tout[v] + 1)
                                                                swap(u, v);
        add(color[who[i]]);
                                                              if (u != v)
   add(color[u]);
                                                                fun(pos[heavy[u]], pos[v]);
   for (Query &q : queries[u])
                                                              fun(pos[u], pos[u]); // process lca(u, v) too?
                                                            }
    ans[q.i] = sum;
   if (keep == 0)
```

void updatePath(int u, int v, lli z) {

fore (i, tin[u], tout[u] + 1)

```
processPath(u, v, [&](int 1, int r) {
                                                               push(u);
     tree->update(1, r, z);
                                                             }
}
                                                             // puts u on the preferred path, splay (right subtree
                                                                  is empty)
                                                             void access(Splay u) {
11i queryPath(int u, int v) {
  11i sum = 0;
                                                               for (Splay v = u, last = 0; v; v = v -> p) {
   processPath(u, v, [&](int 1, int r) {
                                                                 splay(v); // now switch virtual children, i don't
                                                                      know what this means!!
    sum += tree->qsum(1, r);
                                                                 // if (last) v->vsub -= last->sub;
  });
   return sum;
                                                                  // if (v->ch[1]) v->vsub += v->ch[1]->sub;
                                                                 v \rightarrow ch[1] = last, pull(v), last = v;
2.12
       Link-Cut tree
                                                               splay(u);
                                                             }
 typedef struct Node* Splay;
 struct Node {
                                                             void rootify(Splay u) {
   int val, mx = 0;
                                                               access(u), u->flip ^= 1, access(u);
   Splay ch[2] = \{0, 0\}, p = 0;
   int sz = 1, flip = 0;
  Node(int val) : val(val), mx(val) {}
                                                             Splay lca(Splay u, Splay v) {
                                                               if (u == v) return u;
                                                               access(u), access(v);
void push(Splay u) {
                                                               if (!u->p) return 0;
  if (!u || !u->flip)
                                                               return splay(u), u->p ?: u;
    return:
   swap(u->ch[0], u->ch[1]);
   for (Splay v : u->ch)
                                                             bool connected(Splay u, Splay v) {
    if (v) v->flip ^= 1;
                                                               return lca(u, v);
   u->flip = 0;
}
                                                             void link(Splay u, Splay v) { // make u parent of v,
void pull(Splay u) {
                                                                  make sure they aren't connected
   #define gsz(t) (t ? t->sz : 0)
                                                               if (!connected(u, v)) {
   u->sz = 1, u->mx = u->val:
                                                                 rootify(v), access(u);
   for (Splay v : u->ch) if (v) {
                                                                 add(v, u, ∅), pull(v);
    push(v);
                                                               }
    u->sz += gsz(v);
                                                             }
     u->mx = max(u->mx, v->mx);
  }
                                                             void cut(Splay u) { // cut u from its parent
}
                                                               access(u);
                                                               u - ch[0] = u - ch[0] - p = 0;
int dir(Splay u) {
                                                               pull(u);
  if (!u->p) return -2; // root of the LCT component
                                                             }
   if (u->p->ch[0] == u) return 0; // left child
  if (u->p->ch[1] == u) return 1; // right child
                                                             void cut(Splay u, Splay v) { // if u, v adj in tree
  return -1; // root of current splay tree
                                                               rootify(u), access(v), cut(v);
                                                             }
void add(Splay u, Splay v, int d) {
                                                             Splay getRoot(Splay u) {
   if (v) v->p = u;
                                                               access(u);
   if (d \ge 0) u \ge ch[d] = v;
                                                               while (u->ch[0])
                                                                 u = u \rightarrow ch[0], push(u);
                                                               return access(u), u;
void rot(Splay u) { // assume p and p->p propagated
                                                             }
   int x = dir(u);
   Splay g = u - p;
                                                             Splay lift(Splay u, int k) {
   add(g->p, u, dir(g));
                                                               push(u);
   add(g, u->ch[x ^ 1], x);
                                                               int sz = gsz(u->ch[0]);
   add(u, g, x^{1});
                                                               if (sz == k)
  pull(g), pull(u);
                                                                 return splay(u), u;
}
                                                               return k < sz? lift(u->ch[0], k) : lift(u->ch[1], k
                                                                     - sz - 1);
void splay(Splay u) {
                                                             }
   #define isRoot(u) (dir(u) < 0)
   while (!isRoot(u) && !isRoot(u->p)) {
                                                             Splay ancestor(Splay u, int k) {
     push(u->p->p), push(u->p), push(u);
                                                               return access(u), lift(u, gsz(u->ch[0]) - k);
     rot(dir(u) == dir(u->p) ? u->p : u);
     rot(u);
                                                             Splay query(Splay u, Splay v) {
   if (!isRoot(u)) push(u->p), push(u), rot(u);
```

```
return rootify(u), access(v), v;
                                                                }
}
                                                                F maxFlow() {
                                                                   F flow = 0;
Splay lct[N];
                                                                   for (lim = scaling ? lim : 1; lim > eps; lim /= 2)
3
     Flows
                                                                    while (bfs()) {
      \mathbf{Dinic} \ \mathcal{O}(min(E \cdot flow, V^2E))
                                                                       fill(all(ptr), 0);
3.1
                                                                       while (F pushed = dfs(s))
If the network is massive, try to compress it by looking for
                                                                         flow += pushed;
patterns. Dinic with scaling works in \mathcal{O}(EV \cdot log(maxCap)).
 template <class F>
                                                                   return flow;
struct Dinic {
                                                                }
   struct Edge {
                                                              };
     int v, inv;
                                                             3.2
                                                                    Min cost flow \mathcal{O}(min(E \cdot flow, V^2E))
     F cap, flow;
     Edge(int v, F cap, int inv) :
                                                             If the network is massive, try to compress it by looking for
       v(v), cap(cap), flow(₀), inv(inv){}
                                                             patterns.
                                                              template <class C, class F>
                                                              struct Mcmf {
   F eps = (F) 1e-9, lim = (F) 1e-9;
                                                                static constexpr F eps = (F) 1e-9;
   const bool scaling = 0;
                                                                struct Edge {
   int s, t, n, m = 0;
                                                                   int u, v, inv;
                                                                   F cap, flow;
   vector< vector<Edge> > g;
   vi dist, ptr;
                                                                   C cost:
                                                                   Edge(int u, int v, C cost, F cap, int inv) :
  Dinic(int n, int ss = -1, int tt = -1) :
                                                                     u(u), v(v), cost(cost), cap(cap), flow(∅), inv(
    n(n), g(n + 5), dist(n + 5), ptr(n + 5) {
                                                                         inv) {}
     s = ss == -1 ? n + 1 : ss;
                                                                };
     t = tt == -1 ? n + 2 : tt;
   }
                                                                int s, t, n, m = 0;
                                                                vector< vector<Edge> > g;
   void add(int u, int v, F cap) {
                                                                vector<Edge*> prev;
                                                                vector<C> cost;
     g[u].pb(Edge(v, cap, sz(g[v])));
     g[v].pb(Edge(u, 0, sz(g[u]) - 1));
                                                                vi state;
    lim = (scaling ? max(lim, cap) : lim);
    m += 2;
                                                                Mcmf(int n, int ss = -1, int tt = -1):
   }
                                                                   n(n), g(n + 5), cost(n + 5), state(n + 5), prev(n + 5)
                                                                      + 5) {
   bool bfs() {
                                                                   s = ss == -1 ? n + 1 : ss;
     fill(all(dist), -1);
                                                                   t = tt == -1 ? n + 2 : tt;
     queue<int> qu({s});
     dist[s] = 0;
     while (sz(qu) && dist[t] == -1) {
                                                                void add(int u, int v, C cost, F cap) {
       int u = qu.front(); qu.pop();
                                                                   g[u].pb(Edge(u, v, cost, cap, sz(g[v])));
       for (Edge &e : g[u]) if (dist[e.v] == -1)
                                                                   g[v].pb(Edge(v, u, -cost, 0, sz(g[u]) - 1));
         if (scaling ? e.cap - e.flow >= lim : e.cap -
                                                                  m += 2;
              e.flow > eps) {
           dist[e.v] = dist[u] + 1;
           qu.push(e.v);
                                                                bool bfs() {
                                                                   fill(all(state), 0);
                                                                   fill(all(cost), numeric_limits<C>::max());
     return dist[t] != -1;
                                                                   deque<int> qu;
                                                                   qu.push_back(s);
                                                                   state[s] = 1, cost[s] = 0;
   F dfs(int u, F flow = numeric_limits<F>::max()) {
                                                                   while (sz(qu)) {
     if (flow <= eps || u == t)
                                                                     int u = qu.front(); qu.pop_front();
       return max<F>(0, flow);
                                                                     state[u] = 2;
     for (int &i = ptr[u]; i < sz(g[u]); i++) {</pre>
                                                                     for (Edge &e : g[u]) if (e.cap - e.flow > eps)
       Edge &e = g[u][i];
                                                                       if (cost[u] + e.cost < cost[e.v]) {</pre>
       if (e.cap - e.flow > eps && dist[u] + 1 == dist[
                                                                         cost[e.v] = cost[u] + e.cost;
                                                                         prev[e.v] = &e;
        F pushed = dfs(e.v, min<F>(flow, e.cap - e.flow
                                                                         if (state[e.v] == 2 \mid | (sz(qu) \&\& cost[qu.
                                                                             front()] > cost[e.v]))
         if (pushed > eps) {
                                                                           qu.push_front(e.v);
           e.flow += pushed;
                                                                         else if (state[e.v] == 0)
           g[e.v][e.inv].flow -= pushed;
                                                                           qu.push_back(e.v);
           return pushed;
                                                                         state[e.v] = 1;
                                                                       }
         }
       }
                                                                   }
     }
                                                                   return cost[t] != numeric_limits<C>::max();
     return 0;
```

```
pair<C, F> minCostFlow() {
                                                          n jobs, m people
    C cost = 0; F flow = 0;
                                                           template <class C>
    while (bfs()) {
                                                           pair<C, vi> Hungarian(vector< vector<C> > &a) {
      F pushed = numeric_limits<F>::max();
                                                             int n = sz(a), m = sz(a[0]), p, q, j, k; // n \le m
      for (Edge* e = prev[t]; e != nullptr; e = prev[e
                                                            vector<C> fx(n, numeric_limits<C>::min()), fy(m, 0);
           ->u1)
                                                             vi x(n, -1), y(m, -1);
        pushed = min(pushed, e->cap - e->flow);
                                                              fore (i, 0, n)
      for (Edge* e = prev[t]; e != nullptr; e = prev[e
                                                                fore (j, 0, m)
           ->u]) {
                                                                 fx[i] = max(fx[i], a[i][j]);
        e->flow += pushed;
                                                              fore (i, 0, n) {
        g[e->v][e->inv].flow -= pushed;
                                                               vi t(m, -1), s(n + 1, i);
        cost += e->cost * pushed;
                                                                for (p = q = 0; p \le q \&\& x[i] \le 0; p++)
                                                                  for (k = s[p], j = 0; j < m && x[i] < 0; j++)
     flow += pushed;
                                                                    < 0) {
    return make_pair(cost, flow);
                                                                      s[++q] = y[j], t[j] = k;
  }
                                                                      if (s[q] < 0) for (p = j; p >= 0; j = p)
};
                                                                       y[j] = k = t[j], p = x[k], x[k] = j;
     Hopcroft-Karp \mathcal{O}(E\sqrt{V})
                                                               if (x[i] < 0) {</pre>
struct HopcroftKarp {
                                                                 C d = numeric_limits<C>::max();
  int n, m = 0;
                                                                  fore (k, 0, q + 1)
  vector<vi> g;
                                                                    fore (j, 0, m) if (t[j] < 0)
  vi dist, match;
                                                                     d = min(d, fx[s[k]] + fy[j] - a[s[k]][j]);
                                                                  fore (j, 0, m)
  HopcroftKarp(int _n) : n(5 + _n), g(n + 5), dist(n +
                                                                   fy[j] += (t[j] < 0 ? 0 : d);
       5), match(n + 5, 0) {}
                                                                  fore (k, 0, q + 1)
                                                                   fx[s[k]] = d;
  void add(int u, int v) {
    g[u].pb(v), g[v].pb(u);
                                                               }
    m += 2:
                                                             }
  }
                                                             C cost = 0;
                                                             fore (i, 0, n) cost += a[i][x[i]];
  bool bfs() {
                                                             return make_pair(cost, x);
    queue<int> qu;
                                                           }
    fill(all(dist), -1);
    fore (u, 1, n + 1)
                                                                Strings
                                                          4
      if (!match[u])
                                                                \operatorname{Hash}
        dist[u] = 0, qu.push(u);
                                                          4.1
    while (!qu.empty()) {
                                                           vi p = {10006793, 1777771, 10101283, 10101823, 1013635
      int u = qu.front(); qu.pop();
                                                                9, 10157387, 10166249};
                                                           vi mod = {999992867, 1070777777, 999727999, 1000008223
      for (int v : g[u])
                                                                , 1000009999, 1000003211, 1000027163, 1000002193,
        if (dist[match[v]] == -1) {
          dist[match[v]] = dist[u] + 1;
                                                                 10000001233:
                                                           int pw[2][N];
          if (match[v])
            qu.push(match[v]);
                                                           struct Hash {
    }
                                                             vector<vi> h:
    return dist[0] != -1;
                                                             Hash(string &s) : h(2, vi(sz(s) + 1, 0)) {
                                                                fore (i, 0, 2)
  bool dfs(int u) {
                                                                  fore (j, 0, sz(s))
                                                                    h[i][j + 1] = (h[i][j] + 11i(s[j] - 'a' + 1) *
    for (int v : g[u])
      if (!match[v] || (dist[u] + 1 == dist[match[v]]
                                                                         pw[i][j]) % mod[i];
          && dfs(match[v]))) {
                                                             }
        match[u] = v, match[v] = u;
        return 1;
                                                             lli query(int 1, int r) {
      }
                                                               11i f[2] = \{0, 0\};
    dist[u] = 1 << 30;
                                                                fore (i, 0, 2)
                                                                 f[i] = 1LL * (h[i][r + 1] - h[i][l] + mod[i]) %
    return 0:
  }
                                                                      mod[i] * pw[i][N - 1 - 1] % mod[i];
                                                               return (f[0] << 32) | f[1];
  int maxMatching() {
                                                             }
    int tot = 0;
                                                           };
    while (bfs())
      fore (u, 1, n + 1)
                                                            shuffle(all(p), rng), shuffle(all(mod), rng);
                                                           fore (i, 0, 2) {
        tot += match[u] ? 0 : dfs(u);
    return tot;
                                                             pw[i][0] = 1LL;
  }
                                                             fore (j, 1, N)
};
                                                                pw[i][j] = 1LL * p[0] * pw[i][j - 1] % mod[i];
```

3.4 Hungarian $\mathcal{O}(N^3)$

```
}
      KMP
period = n - lps[n-1], period(abcabc) = 3, n \mod period \equiv 0
 int lps[N];
 void pre(string &s) {
   int j = (lps[0] = 0);
   fore (i, 1, sz(s)) {
     while (j && s[i] != s[j])
       j = lps[j - 1];
     if (s[i] == s[j])
      j++;
    lps[i] = j;
   }
 }
 // how many times t occurs in s
 int kmp(string &s, string &t) {
   pre(t);
   int j = 0, tot = 0;
   fore (i, 0, sz(s)) {
     while (j && s[i] != t[j])
       j = lps[j - 1];
     if (s[i] == t[j])
      j++;
     if (j == sz(t))
       tot++; // pos: i - sz(t) + 1;
   }
   return tot;
      KMP automaton
4.3
 int go[N][A];
 void kmpAutomaton(string &s) {
   s += "$";
   fore (i, 0, sz(s))
     fore (c, 0, A) {
       if (i && s[i] != 'a' + c)
         go[i][c] = go[lps[i - 1]][c];
       else
         go[i][c] = i + ('a' + c == s[i]);
     }
   s.pop_back();
     Z algorithm
4.4
 int z[N];
 void zf(string &s) {
   for (int i = 1, l = 0, r = 0; i < sz(s); i++) {
     if (i <= r)
       z[i] = min(r - i + 1, z[i - 1]);
     while (i + z[i] < sz(s) \&\& s[i + z[i]] == s[z[i]])
       ++z[i];
     if (i + z[i] - 1 > r)
       l = i, r = i + z[i] - 1;
   }
4.5
      Manacher algorithm
int aba[2][N];
 void manacher(string &s) {
   fore (k, 0, 2) {
     int 1 = 0, r = 0;
     fore (i, 0, sz(s)) {
       if (i < r)
         aba[k][i] = min(r - i + !k, aba[k][l + r - i +
              !k]);
       int p = i - aba[k][i], q = i + aba[k][i] - !k;
```

```
while (p \ge 1 \& q + 1 < sz(s) \& s[p - 1] == s[
            q + 1]
          ++aba[k][i], --p, ++q;
       if (q > r)
         1 = p, r = q;
     }
   }
 }
4.6
       Suffix array
  • Duplicates \sum_{i=1}^{n} lcp[i]

    Longest Common Substring of various strings
```

Add not Used characters between strings, i.e. a+\$+b+#+cUse two-pointers to find a range [l, r] such that all notUsedcharacters are present, then query(lcp[l+1],..,lcp[r]) for that window is the common length.

```
struct SuffixArray {
  int n;
  string s;
  vi sa, lcp;
  SuffixArray(string &s): n(sz(s) + 1), s(s), sa(n),
      lcp(n) {
    vi top(max(256, n)), rk(n);
    fore (i, 0, n)
      top[rk[i] = s[i] & 255]++;
    partial_sum(all(top), top.begin());
    fore (i, 0, n)
      sa[--top[rk[i]]] = i;
    vi sb(n);
    for (int len = 1, j; len < n; len <<= 1) {</pre>
      fore (i, 0, n) {
        j = (sa[i] - len + n) % n;
        sb[top[rk[j]]++] = j;
      }
      sa[sb[top[0] = 0]] = j = 0;
      fore (i, 1, n) {
        if (rk[sb[i]] != rk[sb[i - 1]] || rk[sb[i] +
             len] != rk[sb[i - 1] + len])
          top[++j] = i;
        sa[sb[i]] = j;
      copy(all(sa), rk.begin());
      copy(all(sb), sa.begin());
      if (j >= n - 1)
        break;
    for (int i = 0, j = rk[lcp[0] = 0], k = 0; i < n - 0
          1; i++, k++)
      while (k \ge 0 \&\& s[i] != s[sa[j - 1] + k])
        lcp[j] = k--, j = rk[sa[j] + 1];
  char at(int i, int j) {
    int k = sa[i] + j;
    return k < n ? s[k] : 'z' + 1;
  bool count(string &t) {
    ii lo(0, n - 1), hi(0, n - 1);
    fore (i, 0, sz(t)) {
      while (lo.f + 1 < lo.s) {</pre>
        int mid = (lo.f + lo.s) / 2;
        if (at(mid, i) < t[i])</pre>
          lo.f = mid;
        else
          lo.s = mid:
      while (hi.f + 1 < hi.s) {</pre>
        int mid = (hi.f + hi.s) / 2;
```

4.7 Suffix automaton

- len[u] len[link[u]] = distinct strings
- Number of different substrings (dp)

$$diff(u) = 1 + \sum_{v \in trie[u]} diff(v)$$

• Total length of all different substrings (2 x dp)

$$totLen(u) = \sum_{v \in trie[u]} diff(v) + totLen(v)$$

- Leftmost occurrence pos[u] = len[u] 1if is **clone** then pos[clone] = pos[q]
- All occurrence positions
- Smallest cyclic shift Construct sam of s + s, find the lexicographically smallest path of sz(s)
- Shortest non-appearing string

```
nonAppearing(u) = \min_{v \in trie[u]} nonAppearing(v) + 1
struct SuffixAutomaton {
  vector< map<char, int> > trie;
  vi link, len;
  int last;
  SuffixAutomaton() { last = newNode(); }
  int newNode() {
    trie.pb({}), link.pb(-1), len.pb(0);
    return sz(trie) - 1;
  void extend(char c) {
    int u = newNode();
    len[u] = len[last] + 1;
    int p = last;
    while (p != -1 && !trie[p].count(c)) {
      trie[p][c] = u;
      p = link[p];
    if (p == -1)
      link[u] = 0;
    else {
      int q = trie[p][c];
      if (len[p] + 1 == len[q])
        link[u] = q;
      else {
        int clone = newNode();
        len[clone] = len[p] + 1;
        trie[clone] = trie[q];
        link[clone] = link[q];
        while (p != -1 && trie[p][c] == q) {
          trie[p][c] = clone;
          p = link[p];
```

```
link[q] = link[u] = clone;
   }
  }
 last = u;
string qkthSubstring(lli kth, int u = 0) {
  // number of different substrings (dp)
  string s = "";
  while (kth > 0)
    for (auto &[c, v] : trie[u]) {
      if (kth <= diff(v)) {</pre>
        s.pb(c), kth--, u = v;
        break;
      kth -= diff(v);
   }
  return s;
void occurs() {
  // occ[u] = 1, occ[clone] = 0
  vi who;
  fore (u, 1, sz(trie))
   who.pb(u);
  sort(all(who), [&](int u, int v) {
   return len[u] > len[v];
  });
  for (int u : who)
    occ[link[u]] += occ[u];
int qocc(string &s, int u = 0) {
  for (char c : s) {
   if (!trie[u].count(c))
      return 0;
   u = trie[u][c];
  }
  return occ[u];
int longestCommonSubstring(string &s, int u = 0) {
  int mx = 0, clen = 0;
  for (char c : s) {
   while (u && !trie[u].count(c)) {
      u = link[u];
      clen = len[u];
   }
    if (trie[u].count(c))
     u = trie[u][c], clen++;
   mx = max(mx, clen);
  return mx;
string smallestCyclicShift(int n, int u = 0) {
  string s = "";
  fore (i, 0, n) {
   char c = trie[u].begin()->f;
   s += c;
   u = trie[u][c];
  }
  return s;
int leftmost(string &s, int u = 0) {
  for (char c : s) {
    if (!trie[u].count(c))
      return -1;
```

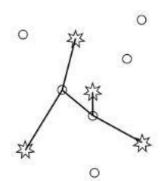
```
u = trie[u][c];
     }
     return pos[u] - sz(s) + 1;
   }
 } sam;
4.8
      Aho corasick
 struct AhoCorasick {
   vector< map<char, int> > trie;
   vi link, cnt;
   AhoCorasick() { newNode(); }
   int newNode() {
     trie.pb({}), link.pb(0), cnt.pb(0);
     return sz(trie) - 1;
   void insert(string &s, int u = 0) {
     for (char c : s) {
       if (!trie[u][c])
         trie[u][c] = newNode();
       u = trie[u][c];
     }
    cnt[u]++;
   }
   int go(int u, char c) {
     while (u && !trie[u].count(c))
       u = link[u];
     return trie[u][c];
   }
   void pushLinks() {
     queue<int> qu;
     qu.push(∅);
     while (!qu.empty()) {
       int u = qu.front();
       qu.pop();
       for (auto &[c, v] : trie[u]) {
         if (v == 0) {
           v = trie[link[u]][c];
           continue;
         link[v] = u ? go(link[u], c) : 0;
         cnt[v] += cnt[link[v]];
         qu.push(v);
       }
    }
   }
   int match(string &s, int u = 0) {
     int ans = 0;
     for (char c : s)
       u = go(u, c), ans += cnt[u];
     return ans;
   }
 } aho;
4.9 Eertree
 struct Eertree {
   vector< map<char, int> > trie;
   vi link, len;
   string s = "$";
   int last;
   Eertree() {
    last = newNode(), newNode();
     link[0] = 1, len[1] = -1;
   }
```

```
int newNode() {
    trie.pb(\{\}), link.pb(\emptyset), len.pb(\emptyset);
    return sz(trie) - 1;
  int go(int u) {
    while (s[sz(s) - len[u] - 2] != s.back())
      u = link[u];
    return u;
  void extend(char c) {
    s += c;
    int u = go(last);
    if (!trie[u][c]) {
      int v = newNode();
      len[v] = len[u] + 2;
      link[v] = trie[go(link[u])][c];
      trie[u][c] = v;
    last = trie[u][c];
  }
} eert;
```

5 Dynamic Programming

5.1 Steiner-tree DP

n nodes, k terminal nodes, unite all terminal nodes doing a Steiner tree



```
fore (u, k, n)
  fore (a, 0, k)
    umin(dp[u][1 << a], dist[u][a]);

fore (A, 0, (1 << k))
  fore (u, k, n) {
    for (int B = A; B > 0; B = (B - 1) & A)
        umin(dp[u][A], dp[u][B] + dp[u][A ^ B]);
    fore (v, k, n)
        umin(dp[v][A], dp[u][A] + dist[u][v]);
  }
```

5.2 Matrix Chain Multiplication

```
int dp(int l, int r) {
   if (l > r)
      return OLL;
   int &ans = mem[l][r];
   if (!done[l][r]) {
      done[l][r] = true, ans = inf;
      fore (k, l, r + 1) // split in [l, k] [k + 1, r]
        ans = min(ans, dp(l, k) + dp(k + 1, r) + add);
   }
   return ans;
}
```

5.3 Digit DP

Counts the amount of numbers in [l, r] such are divisible by k. (flag nonzero is for different lengths)

It can be reduced to dp(i, x, small), and has to be solve like f(r) - f(l-1)

#define state [i][x][small][big][nonzero]

```
int dp(int i, int x, bool small, bool big, bool
     nonzero) {
                                                                  }
   if (i == sz(r))
                                                               };
     return x % k == 0 && nonzero;
   int &ans = mem state;
   if (done state != timer) {
     done state = timer;
     ans = 0;
     int lo = small ? 0 : 1[i] - '0';
     int hi = big ? 9 : r[i] - '0';
     fore (y, lo, max(lo, hi) + 1) {
       bool small2 = small | (y > lo);
       bool big2 = big | (y < hi);
       bool nonzero2 = nonzero | (x > 0);
       ans += dp(i + 1, (x * 10 + y) % k, small2, big2,
             nonzero2);
     }
   }
   return ans;
}
5.4
       Knapsack 0/1
 for (auto &cur : items)
   fore (w, W + 1, cur.w) // [cur.w, W]
     umax(dp[w], dp[w - cur.w] + cur.cost);
       Convex Hull Trick \mathcal{O}(n^2) \Rightarrow \mathcal{O}(n)
    dp[i] = \min_{i \le i} (dp[j] + b[j] * a[i])
    dp[i][j] = \min_{k < j} (dp[i-1][k] + b[k] * a[j])
    b[j] \ge b[j+1] optionally a[i] \le a[i+1]
                                                              5.7
 // for doubles, use inf = 1/.0, div(a,b) = a / b
 struct Line {
   mutable lli m, c, p;
   bool operator < (const Line &1) const { return m < 1</pre>
                                                               6
                                                               6.1
   bool operator < (lli x) const { return p < x; }</pre>
  lli operator ()(lli x) const { return m * x + c; }
};
11i divi(11i a, 11i b) { return a / b - ((a ^ b) < 0</pre>
     && a % b); }
1li bet(const Line &a, const Line &b) {
                                                                    χ++;
   if (a.m == b.m)
     return a.c > b.c ? inf : -inf;
                                                                }
   return divi(b.c - a.c, a.m - b.m);
 struct DynamicHull : multiset<Line, less<>>> {
   bool isect(iterator x, iterator y) {
     if (y == end()) {
       x->p = inf;
       return 0;
     x->p = bet(*x, *y);
     return x->p >= y->p;
   }
                                                                    g = mex(st);
                                                                  }
   void add(lli m, lli c) {
                                                                  return g;
     auto z = insert(\{m, c, \emptyset\}), y = z++, x = y;
                                                                }
     while (isect(y, z)) z = erase(z);
     if (x != begin() && isect(--x, y))
       isect(x, y = erase(y));
     while ((y = x) != begin() && (--x)->p >= y->p)
                                                               7.1
       isect(x, erase(y));
   }
   lli query(lli x) {
     if (empty()) return OLL;
     auto f = *lower_bound(x);
```

```
return f(x);
       Divide and conquer \mathcal{O}(kn^2) \Rightarrow \mathcal{O}(k \cdot nlogn)
Split the array of size n into k continuous groups. k \leq n
cost(a, c) + cost(b, d) \le cost(a, d) + cost(b, c) with a \le b \le c \le d
 void dc(int cut, int 1, int r, int opt1, int optr) {
   if (r < 1)
     return;
   int mid = (1 + r) / 2;
   pair<lli, int> best = {inf, -1};
   fore (p, optl, min(mid, optr) + 1) {
     11i nxtGroup = dp[~cut & 1][p - 1] + cost(p, mid);
     if (nxtGroup < best.f)</pre>
       best = {nxtGroup, p};
   dp[cut & 1][mid] = best.f;
   int opt = best.s;
   dc(cut, 1, mid - 1, optl, opt);
   dc(cut, mid + 1, r, opt, optr);
 fore (i, 1, n + 1)
   dp[1][i] = cost(1, i);
 fore (cut, 2, k + 1)
   dc(cut, cut, n, cut, n);
       Do all submasks of a mask A
 for (int B = A; B > 0; B = (B - 1) & A)
     Game Theory
       Grundy Numbers
If the moves are consecutive S = \{1, 2, 3, ..., x\} the game can be
solved like stackSize \pmod{x+1} \neq 0
 int mem[N];
 int mex(set<int> &st) {
   int x = 0;
   while (st.count(x))
   return x;
 int grundy(int n) {
   if (n < 0)
     return inf;
   if (n == 0)
     return 0;
   int &g = mem[n];
   if (g == -1) {
     set<int> st;
     for (int x : {a, b})
       st.insert(grundy(n - x));
```

Combinatorics

Factorial

```
fac[0] = 1LL;
fore (i, 1, N)
  fac[i] = 11i(i) * fac[i - 1] % mod;
ifac[N - 1] = fpow(fac[N - 1], mod - 2);
fore (i, N - 1, 0)
```

```
ifac[i] = 11i(i + 1) * ifac[i + 1] % mod;
       Factorial mod smallPrime
lli facMod(lli n, int p) {
   11i r = 1LL;
   for (; n > 1; n /= p) {
     r = (r * ((n / p) % 2 ? p - 1: 1)) % p;
     fore (i, 2, n \% p + 1)
       r = r * i % p;
   }
   return r % p;
}
7.3
      Lucas theorem
Convierte \binom{n}{k} mod p, con n, k \geq 2e6 y p \leq 1e7
lli lucas(lli n, lli k) {
   if (k == 0)
     return 1LL;
   return lucas(n / mod, k / mod) * choose(n % mod, k %
         mod) % mod:
}
     N choose K
     \binom{n}{k} = \binom{n-1}{k-1} + \binom{n-1}{k}
     \binom{n}{k_1, k_2, \dots, k_m} = \frac{n!}{k_1! * k_2! * \dots * k_m!}
lli choose(int n, int k) {
   if (n < 0 || k < 0 || n < k)</pre>
     return OLL;
   return fac[n] * ifac[k] % mod * ifac[n - k] % mod;
11i choose(int n, int k) {
   double r = 1;
   fore (i, 1, k + 1)
     r = r * (n - k + i) / i;
   return lli(r + 0.01);
}
7.5
       Catalan
catalan[0] = 1LL;
fore (i, 0, N) {
   catalan[i + 1] = catalan[i] * 111(4 * i + 2) % mod *
         fpow(i + 2, mod - 2) \% mod;
}
      Prime factors of N!
vector< pair<lli, int> > factorialFactors(int n) {
   vector< pair<lli, int> > fac;
   for (lli p : primes) {
     if (n < p)
       break;
     lli mul = 1LL, k = 0;
     while (mul <= n / p) {</pre>
       mul *= p;
       k += n / mul;
     fac.emplace_back(p, k);
```

8 Number Theory

return fac;

8.1 Goldbach conjecture

- All number ≥ 6 can be written as sum of 3 primes
- All even number > 2 can be written as sum of 2 primes

```
8.2 Sieve of Eratosthenes
```

```
Numbers up to 2e8
 int erat[N >> 6];
 #define bit(i) ((i >> 1) & 31)
 #define prime(i) !(erat[i >> 6] >> bit(i) & 1)
 void bitSieve() {
   for (int i = 3; i * i < N; i += 2) if (prime(i))</pre>
     for (int j = i * i; j < N; j += (i << 1))
       erat[j >> 6] |= 1 << bit(j);
 }
To factorize divide x by factor[x] until is equal to 1
 void factorizeSieve() {
   iota(factor, factor + N, ∅);
   for (int i = 2; i * i < N; i++) if (factor[i] == i)</pre>
     for (int j = i * i; j < N; j += i)
       factor[j] = i;
 }
Use it if you need a huge amount of phi[x] up to some N
 void phiSieve() {
   isp.set(); // bitset<N> is faster
   iota(phi, phi + N, 0);
   fore (i, 2, N) if (isp[i])
     for (int j = i; j < N; j += i) {
       isp[j] = (i == j);
       phi[j] /= i;
       phi[j] *= i - 1;
  }
8.3
     Phi of euler
 lli phi(lli n) {
   if (n == 1)
     return 0;
   11i r = n;
   for (11i i = 2; i * i <= n; i++)
     if (n % i == 0) {
       while (n % i == ∅)
         n \neq i;
       r -= r / i;
     }
   if (n > 1)
     r -= r / n;
   return r;
 }
8.4 Miller-Rabin
 bool compo(lli p, lli d, lli n, lli k) {
   11i x = fpow(p % n, d, n), i = k;
   while (x != 1 && x != n - 1 && p % n && i--)
     x = mul(x, x, n);
   return x != n - 1 && i != k;
 }
 bool miller(lli n) {
   if (n < 2 || n % 6 % 4 != 1)
     return (n | 1) == 3;
   int k = __builtin_ctzll(n - 1);
   lli d = n >> k;
   for (11i p: {2, 3, 5, 7, 11, 13, 17, 19, 23, 29, 31
       , 37}) {
     if (compo(p, d, n, k))
       return 0;
     if (compo(2 + rng() % (n - 3), d, n, k))
       return 0:
   return 1;
```

```
11i f(11i x, 11i c, 11i mod) {
                                                                  return {p.s, p.f - a / b * p.s};
   return (mul(x, x, mod) + c) % mod;
                                                               }
                                                                      Chinese remainder theorem
                                                               pair<lli, 1li> crt(pair<lli, 1li> a, pair<lli, 1li> b)
 lli rho(lli n) {
   while (1) {
                                                                  if (a.s < b.s)
     11i x = 2 + rng() \% (n - 3), c = 1 + rng() \% 20, y
                                                                    swap(a, b);
          = f(x, c, n), g;
                                                                  auto p = euclid(a.s, b.s);
     while ((g = \_gcd(n + y - x, n)) == 1)
                                                                  11i g = a.s * p.f + b.s * p.s, l = a.s / g * b.s;
       x = f(x, c, n), y = f(f(y, c, n), c, n);
                                                                  if ((b.f - a.f) % g != 0)
     if (g != n) return g;
                                                                    return {-1, -1}; // no solution
   }
                                                                 p.f = a.f + (b.f - a.f) % b.s * p.f % b.s / g * a.s;
   return -1;
                                                                  return \{p.f + (p.f < 0) * 1, 1\};
 }
 void pollard(lli n, map<lli, int> &fac) {
                                                              9
                                                                    Math
   if (n == 1) return;
                                                                    Progressions
                                                              9.1
   if (n % 2 == 0) {
                                                              Arithmetic progressions
     fac[2]++;
     pollard(n / 2, fac);
                                                                   a_n = a_1 + (n-1) * diff
     return;
                                                                   \sum a_i = n * \frac{a_1 + a_n}{2}
   if (miller(n)) {
     fac[n]++;
                                                              Geometric progressions
     return:
                                                                   a_n = a_1 * r^{n-1}
   }
   11i x = rho(n);
                                                                   \sum_{k=1}^{n} a_1 * r^k = a_1 * \left(\frac{r^{n+1} - 1}{r - 1}\right) : r \neq 1
   pollard(x, fac);
                                                              9.2 Mod multiplication
   pollard(n / x, fac);
                                                               lli mul(lli x, lli y, lli mod) {
     Amount of divisors
                                                                 11i r = 0LL;
 lli divs(lli n) {
                                                                  for (x \% = mod; y > 0; y >>= 1) {
                                                                    if (y \& 1) r = (r + x) \% mod;
   11i cnt = 1LL;
   for (lli p: primes) {
                                                                    x = (x + x) \% mod;
                                                                 }
     if (p * p * p > n)
       break;
                                                                  return r;
                                                               }
     if (n % p == 0) {
       11i k = 0;
                                                              9.3 Fpow
       while (n > 1 \&\& n \% p == 0)
                                                               11i fpow(11i x, 11i y, 11i mod) {
         n /= p, ++k;
                                                                 11i r = 1;
       cnt *= (k + 1);
                                                                  for (; y > 0; y >>= 1) {
     }
                                                                    if (y & 1) r = mul(r, x, mod);
   }
                                                                    x = mul(x, x, mod);
   1li sq = mysqrt(n); // A binary search, the last x *
                                                                 }
        x <= n
                                                                  return r;
   if (miller(n))
                                                               }
     cnt *= 2:
   else if (sq * sq == n && miller(sq))
                                                                    Fibonacci
                                                              9.4
     cnt *= 3;
                                                                            = \begin{bmatrix} fib_{n+1} & fib_n \\ fib_n & fib_{n-1} \end{bmatrix}
   else if (n > 1)
     cnt *= 4;
   return cnt;
                                                              10
                                                                      Geometry
8.7
      Bézout's identity
                                                                       Point
a_1 * x_1 + a_2 * x_2 + \dots + a_n * x_n = g
                                                               const ld eps = 1e-9;
 g = \gcd(a_1, a_2, ..., a_n)
                                                               #define eq(a, b) fabs((a) - (b)) \leq eps
                                                                #define neq(a, b) fabs((a) - (b)) > eps
                                                                #define geq(a, b) (a) - (b) \ge -eps
8.8
     GCD
                                                                #define ge(a, b) (a) - (b) > eps
a \le b; gcd(a+k, b+k) = gcd(b-a, a+k)
                                                                #define le(a, b) (b) - (a) > eps
8.9
      _{
m LCM}
                                                                #define leq(a, b) (b) - (a) \geq= -eps
                                                               #define sq(x)(x) * (x)
x = p * lcm(a_1, a_2, ..., a_k) + q, 0 \le q \le lcm(a_1, a_2, ..., a_k)
 x \pmod{a_i} \equiv q \pmod{a_i} as a_i \mid lcm(a_1, a_2, ..., a_k)
                                                               int sgn(ld x) {
8.10 Euclid
                                                                 return x > 0 ? 1 : (x < 0 ? -1 : 0);
 pair<lli, lli> euclid(lli a, lli b) {
   if (b == 0)
                                                               template <class T>
     return {1, 0};
```

auto p = euclid(b, a % b);

8.5

Pollard-Rho

```
struct Point {
                                                              return eq((p - a).cross(v), 0);
   typedef Point<T> P;
                                                            }
   T x, y;
                                                            bool pointInSegment(const P &a, const P &b, const P &p
   explicit Point(T x = \emptyset, T y = \emptyset) : x(x), y(y) {}
                                                                ) {
   P operator + (const P &p) const {
                                                              return pointInLine(a, b - a, p) && leq((a - p).dot(b
    return P(x + p.x, y + p.y); }
                                                                   - p), 0);
   P operator - (const P &p) const {
                                                            }
    return P(x - p.x, y - p.y); }
                                                            int pointInCircle(const P &c, ld r, const P &p) {
   P operator * (T k) const {
                                                              ld 1 = (p - c).length() - r;
    return P(x * k, y * k); }
                                                              return (le(1, 0) ? 1 : (eq(1, 0) ? -1 : 0));
   P operator / (T k) const {
    return P(x / k, y / k); }
                                                            vector<P> intersectSegmentCircle(const P &a, const P &
                                                                 b, const point &c, 1d r) {
   T dot(const P &p) { return x * p.x + y * p.y; }
                                                              vector<P> points = intersectLineCircle(a, b - a, c,
   T cross(const P &p) { return x * p.y - y * p.x; }
                                                                  r), ans;
                                                              for (const P &p : points) {
   double length() const { return sqrtl(norm()); }
   T norm() const { return sq(x) + sq(y); } // double ?
                                                                if (pointInSegment(a, b, p)) ans.pb(p);
   double angle() { return atan2(y, x); }
                                                              return ans;
   P perp() const { return P(-y, x); }
   P unit() const { return (*this) / length(); }
                                                            ld signed_angle(const P &a, const P &b) {
   P rotate (double angle) const {
                                                              return sgn(a.cross(b)) * acosl(a.dot(b) / (a.length
     return P(x * cos(angle) - y * sin(angle),
                                                                   () * b.length()));
              x * sin(angle) + y * cos(angle)); }
                                                            1d intersectPolygonCircle(const vector<P> &points,
                                                                 const P &c, ld r) {
   bool operator == (const P &p) const {
    return eq(x, p.x) && eq(y, p.y); }
                                                              int n = points.size();
   bool operator != (const P &p) const {
                                                              1d ans = 0;
    return neq(x, p.x) || neq(y, p.y); }
                                                              for (int i = 0; i < n; ++i) {
                                                                P p = points[i], q = points[(i + 1) % n];
   friend ostream & operator << (ostream &os, P &p) {</pre>
                                                                bool p_inside = (pointInCircle(c, r, p) != 0);
     return os << "(" << p.x << ", " << p.y << ")";
                                                                bool q_inside = (pointInCircle(c, r, q) != 0);
                                                                if (p_inside && q_inside) {
};
                                                                  ans += (p - c).cross(q - c);
 typedef Point<double> P;
                                                                } else if (p_inside && !q_inside) {
                                                                  P s1 = intersectSegmentCircle(p, q, c, r)[0];
                                                                  P s2 = intersectSegmentCircle(c, q, c, r)[0];
double ccw(P a, P b, P c) {
  return (b - a).cross(c - a);
                                                                  ans += (p - c).cross(s1 - c) + r * r *
}
                                                                       signed_angle(s1 - c, s2 - c);
                                                                } else if (!p_inside && q_inside) {
10.2
       Angle Between Vectors
                                                                  P s1 = intersectSegmentCircle(c, p, c, r)[0];
double angleBetween(P a, P b) {
                                                                  P s2 = intersectSegmentCircle(p, q, c, r)[0];
   double x = a.dot(b) / a.length() / b.length();
                                                                  ans += (s_2 - c).cross(q - c) + r * r *
   return acos(max(1d(-1.0), min(1d(1.0), 1d(x))));
                                                                       signed_angle(s1 - c, s2 - c);
                                                                } else {
                                                                  auto info = intersectSegmentCircle(p, q, c, r);
       Area Poligon
10.3
                                                                  if (info.size() <= 1) {</pre>
 double area(vector<P> &p) {
                                                                    ans += r * r * signed_angle(p - c, q - c);
   double sum = 0;
                                                                  } else {
   fore (i, 0, n)
                                                                    P s2 = info[0], s3 = info[1];
     sum += p[i].cross(p[(i + 1) % sz(p)]);
                                                                    P s1 = intersectSegmentCircle(c, p, c, r)[0];
   return abs(sum / 2);
                                                                    P s4 = intersectSegmentCircle(c, q, c, r)[0];
}
                                                                    ans += (s_2 - c).cross(s_3 - c) + r * r * (
                                                                         signed_angle(s1 - c, s2 - c) +
       Area Poligon In Circle
                                                                         signed_angle(s3 - c, s4 - c));
 vector<P> intersectLineCircle(const P &a, const P &v,
                                                                  }
     const P &c, ld r) {
                                                                }
   1d h^2 = r * r - v.cross(c - a) * v.cross(c - a) / v.
                                                              }
                                                              return abs(ans) / 2;
   P p = a + v * v.dot(c - a) / v.norm();
   if (eq(h2, 0))
     return {p}; // line tangent to circle
                                                           10.5
                                                                   Closest Pair Of Points
   else if (le(h2, 0))
                                                            pair<P, P> cpp(vector<P> points) {
    return {}; // no intersection
                                                              sort(all(points), [&](P a, P b) {
    point u = v.unit() * sqrt(h2);
                                                                return le(a.y, b.y);
    return {p - u, p + u}; // two points of
                                                              });
         intersection (chord)
                                                              set<P> st;
  }
                                                              ld ans = inf;
                                                              P p, q;
bool pointInLine(const P &a, const P &v, const P &p) {
                                                              int pos = 0, n = sz(points);
```

```
}
   fore (i, 0, n) {
    while (pos < i && geq(points[i].y - points[pos].y,</pre>
                                                                     Intersects Line Segment
                                                          10.10
                                                           int intersectLineSegmentInfo(P a, P v, P c, P d) {
      st.erase(points[pos++]);
                                                             P v2 = d - c;
     auto lo = st.lower_bound({points[i].x - ans - eps,
                                                             1d \det = v.cross(v2);
          -inf}):
                                                              if (det == 0) {
    auto hi = st.upper_bound({points[i].x + ans + eps,
                                                                if ((c - a).cross(v) == 0)
          -inf});
                                                                 return -1; // infinity points
     for (auto it = lo; it != hi; ++it) {
      ld d = (points[i] - *it).length();
                                                                 return 0; //no points
       if (le(d, ans))
                                                             } else
        ans = d, p = points[i], q = *it;
                                                                 return sgn(v.cross(c - a)) != sgn(v.cross(d - a))
    st.insert(points[i]);
                                                           }
   }
  return {p, q};
                                                          10.11
                                                                     Intersects Segment
}
                                                           int intersectSegmentsInfo(const P &a, const P &b,
                                                                const P &c, const P &d) {
10.6
        Convex Hull
                                                             P v1 = b - a, v2 = d - c;
 vector<P> convexHull(vector<P> &pts) {
                                                             int t = sgn(v1.cross(c - a)), u = sgn(v1.cross(d - a))
   int n = sz(pts);
                                                                  ));
   vector<P> low, up;
                                                             if (t == u) {
   sort(all(pts), [&](P a, P b) {
                                                                if (t == 0) {
    return a.x == b.x ? a.y < b.y : a.x < b.x;
                                                                  if (PInSegment(a, b, c) || PInSegment(a, b, d)
   });
                                                                      || PInSegment(c, d, a) || PInSegment(c, d,
   pts.erase(unique(all(pts)), pts.end());
                                                                      b))
   if (n <= 2)
                                                                    return -1; // infinity Ps
    return pts;
                                                                  else
   fore (i, 0, n) {
                                                                    return 0; // no P
    while(sz(low) >= 2 && (low.end()[-1] - low.end()[-
                                                                } else
         2]).cross(pts[i] - low.end()[-1]) <= 0)
                                                                  return 0; // no P
      low.pop back():
                                                             } else
    low.pb(pts[i]);
                                                                  return sgn(v2.cross(a - c)) != sgn(v2.cross(b -
                                                                      c)); // 1: single P 0: no P
   fore (i, n, 0) {
                                                           }
     while(sz(up) \ge 2 && (up.end()[-1] - up.end()[-2])
         .cross(pts[i] - up.end()[-1]) \le 0)
                                                          10.12
                                                                     Is Convex
       up.pop_back();
                                                           bool isConvex(vector<P> points) {
    up.pb(pts[i]);
                                                             int n = sz(points);
   }
                                                             bool hasPos = false, hasNeg = false;
   low.pop_back(), up.pop_back();
                                                              fore (i, 0, n) {
   low.insert(low.end(), all(up));
                                                                P first = points[(i+1)%n] - points[i];
   return low;
                                                                P second = points[(i+2)%n] - points[(i+1)%n];
                                                                double sign = first.cross(second);
                                                                if (sign > 0) hasPos = true;
        Distance Point Line
10.7
                                                                if (sign < 0) hasNeg = true;</pre>
 double distance_P_line(P a, P v, P p){
  return (proj(p - a, v) - (p - a)).length();
                                                             return !(hasPos && hasNeg);
                                                           }
10.8 Get Circle
                                                          10.13
                                                                     Perimeter
pair<P, double> getCircle(P m, P n, P p){
                                                            double perimeter(vector<P> points){
   P c = intersectLines((n + m) / 2, (n - m).perp(), (p)
                                                             int n = sz(points);
        + m) / 2, (p - m).perp());
                                                             double sum = 0;
   double r = (c - m).length();
                                                              fore (i, 0, n)
   return {c, r};
                                                                sum += (points[(i + 1) % n] - points[i]).length();
                                                             return sum;
                                                           }
10.9
       Intersects Line
                                                                     Point In Convex Polygon logN
                                                          10.14
 int intersectLinesInfo (P a1, P v1, P a2, P v2) { // v
     1 = b - a, v2 = d - c
   if (v1.cross(v2) == 0)
                                                           // first preprocess: seg = process(points)
     return (a2 - a1).cross(v1) == 0 ? -1 : 0; // -1:
                                                           // for each query: PInConvexPolygon(seg, p - Ps[0])
                                                           vector<P> process(const vector<P> &Ps) {
         infinity Ps, 0: no Ps
   else
                                                             int n = sz(Ps);
                                                             rotate(Ps.begin(), min_element(all(Ps), [&](P a, P b
     return 1; // single P
                                                                  ) {
                                                                return a.x == b.x ? a.y < b.y : a.x < b.x;
P intersectLines (P a1, P v1, P a2, P v2) {
                                                             }), Ps.end());
   return a1 + v1 * ((a2 - a1).cross(v2) / v1.cross(v2)
                                                              vector < P > seg(n - 1);
       );
                                                              fore (i, 0, n - 1)
```

```
seg[i] = Ps[i + 1] - Ps[0];
  return seg;
}
bool PInConvexPolygon(const vector<P> &seg, const P &p
     ) {
  int n = sz(seg);
  if (neq(seg[0].cross(p), 0) && sgn(seg[0].cross(p))
       != sgn(seg[0].cross(seg[n - 1])))
    return false;
  if (neq(seg[n - 1].cross(p), 0) && sgn(seg[n - 1].
       cross(p)) != sgn(seg[n - 1].cross(seg[0])))
    return false;
  if (eq(seg[0].cross(p), 0))
    return geq(seg[0].length(), p.length());
  int 1 = 0, r = n - 1;
  while (r - 1 > 1) {
    int m = 1 + ((r - 1) >> 1);
    if (geq(seg[m].cross(p), 0))
      1 = m;
    else
      r = m;
  }
  return eq(fabs(seg[l].cross(seg[l + 1])), fabs((p -
       seg[1]).cross(p - seg[1 + 1])) +
          fabs(p.cross(seg[1])) + fabs(p.cross(seg[1 +
}
10.15
          Point In Polygon
int pointInPolygon(const vector<P> &points, P p) { //
     O(N)
 int n = sz(points), ans = 0;
 fore (i, 0, n) {
  P a = points[i], b = points[(i + 1) % n];
  if (pointInSegment(a, b, p))
      return -1; // on perimeter
  if (a.y > b.y)
      swap(a,b);
  if (a.y <= p.y && b.y > p.y && (a - p).cross(b - p)
      > 0)
      ans ^= 1;
 return ans ? 1 : 0; // inside, outside
          Point In Segment
10.16
bool pointInSegment(P a, P b, P p){
  return (b - a).cross(p - a) == 0 && (a - p).dot(b -
       p) <= 0;
}
10.17
          Points Of Tangency
pair<P, P> PsOfTangency(P c, double r, P p){
  P v = (p - c).unit() * r;
  double cos_theta = r / (p - c).length();
  double theta = acos(max(-1.0, min(1.0, cos_theta)));
  return {c + v.rotate(-theta), c + v.rotate(theta)};
}
10.18
          Projection
P proj(P a, P v){
    v = v / v.unit();
    return v * a.dot(v);
}
10.19
          Projection Line
P proj_line(P a, P v, P p){
  return a + proj(p - a, v);
}
10.20
          Reflection Line
```

```
P reflection_line(P a, P v, P p){
  return a*2 - p + proj(p - a, v)*2;
}
10.21
          Signed Distance Point Line
double signed_distance_P_line(P a, P v, P p){
  return v.cross(p - a) / v.length();
}
10.22
          Sort Along Line
void sort_along_line(P a, P v, vector<P> & Ps){
  sort(Ps.begin(), Ps.end(), [](P u, P w){
    return u.dot(v) < w.dot(v);</pre>
  });
}
10.23
          Intersects Line Circle
vector<P> intersectLineCircle(P a, P v, P c, double r)
  P p = proj_line(a, v, c);
  double d = (p - c).length();
  double h = sq(r) - sq(d);
  if(h == 0)
   return {p}; //line tangent to circle
  else if(h < 0)
  return {}; //no intersection
    P u = v.unit() * sqrt(h);
     return {p - u, p + u}; //two Ps of intersection (
         chord)
}
```

11 Bit tricks

$\mathrm{Bits}++$				
Operations on int	Function			
x & -x	Least significant bit in x			
lg(x)	Most significant bit in x			
c = x&-x, r = x+c;	Next number after x with same			
(((r^x) » 2)/c) r	number of bits set			
builtin_	Function			
popcount(x)	Amount of 1's in x			
clz(x)	0's to the left of biggest bit			
ctz(x)	0's to the right of smallest bit			

11.1 Bitset

Bitset <size></size>					
Operation	Function				
_Find_first()	Least significant bit				
_Find_next(idx)	First set bit after index idx				
any(), none(), all()	Just what the expression says				
set(), reset(), flip()	Just what the expression says x2				
to_string('.', 'A')	Print 011010 like .AA.A.				