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15 Polygons       22         15.1 Area of polygon	<pre>const static string reset = "\033[0m", blue = "\033[ 1;34m", purple = "\033[3;95m";</pre>
15.2 Convex-Hull	bool ok = 1;
15.3 Cut polygon by a line	<pre>do {    if (s[0] == '\"') ok = 0;</pre>
15.4 Perimeter	else cout << blue << s[0] << reset;
15.5 Point in polygon	s = s.substr(1);
15.6 Point in convex-polygon	<pre>} while (s.size() &amp;&amp; s[0] != ',');</pre>
15.7 Is convex	<pre>if (ok) cout &lt;&lt; ": " &lt;&lt; purple &lt;&lt; h &lt;&lt; reset; print(s, t);</pre>
16 Geometry misc 23	}
16.1 Radial order	D I
16.2 Sort along a line	Randoms
	<pre>mt19937 rng(chrono::steady_clock::now().     time_since_epoch().count());</pre>
Think twice, code once	template <class t=""></class>
Template	T ran(T 1, T r) {
tem.cpp	<pre>return uniform_int_distribution<t>(1, r)(rng);</t></pre>
<pre>#pragma GCC optimize("Ofast,unroll-loops,no-stack-</pre>	}
protector")	Compilation (gedit /.zshenv)
<pre>#include <bits stdc++.h=""></bits></pre>	touch a_in{19} // make files a_in1, a_in2,, a_in9
using namespace std;	tee {am}.cpp < tem.cpp // "" with tem.cpp like base
#ifdef LOCAL	<pre>cat &gt; a_in1 // write on file a_in1 gedit a_in1 // open file a_in1</pre>
<pre>#include "debug.h"</pre>	rm -r a.cpp // deletes file a.cpp :'(
#else	
<pre>#define debug() #endif</pre>	red='\x1B[0;31m'
welldi	green='\x1B[0;32m' noColor='\x1B[0m'
<b>#define df</b> (b, e) ((b) > (e))	alias flags='-Wall -Wextra -Wshadow -
#define fore(i, b, e) for (auto $i = (b) - df(b, e)$ ; i	D_GLIBCXX_ASSERTIONS -fmax-errors=3 -02 -w'
!= $e - df(b, e)$ ; $i += 1 - 2 * df(b, e)$	go() { g++std=c++11 \$2 \${flags} \$1.cpp && ./a.out }
<pre>#define sz(x) int(x.size()) #define all(x) begin(x), end(x)</pre>	debug() { go \$1 -DLOCAL < \$2 }
#define f first	run() { go \$1 "" < \$2 }
#define s second	<pre>random() { // Make small test cases!!!</pre>
#define pb push_back	g++std=c++11 \$1.cpp -o prog
using lli = long long;	g++std=c++11 gen.cpp -o gen
using ld = long double;	g++std=c++11 brute.cpp -o brute
<pre>using ii = pair<int, int="">;</int,></pre>	<pre>for ((i = 1; i &lt;= 200; i++)); do printf "Test case #\$i"</pre>
<pre>using vi = vector<int>;</int></pre>	./gen > in
that make O. C.	diff -uwi <(./prog < in) <(./brute < in) > \$1_diff
<pre>int main() {   cin.tie(0)-&gt;sync_with_stdio(0), cout.tie(0);</pre>	if [[ ! \$? -eq 0 ]]; then
// solve the problem here D:	<pre>printf "\${red} Wrong answer \${noColor}\n" break</pre>
return 0;	else
}	<pre>printf "\${green} Accepted \${noColor}\n"</pre>
debug.h	fi
template <class a,="" b="" class=""> ostream &amp; operator &lt;&lt; (ostream &amp;os, const pair<a, b=""> &amp;</a,></class>	done }
p) {	
<pre>return os &lt;&lt; "(" &lt;&lt; p.first &lt;&lt; ", " &lt;&lt; p.second &lt;&lt; "</pre>	Bump allocator
)";	<pre>static char buf[450 &lt;&lt; 20]; void* operator new(size_t s) {</pre>
}	<pre>static size_t i = sizeof buf; assert(s &lt; i);</pre>
template <class a,="" b,="" c="" class=""></class>	return (void *) &buf[i -= s];
<pre>basic_ostream<a, b=""> &amp; operator &lt;&lt; (basic_ostream<a, b=""></a,></a,></pre>	}
&os, const C &c) {	<pre>void operator delete(void *) {}</pre>
os << "["; for (const auto &x : c)	1 Data structures
os << ", " + 2 * (&x == &*begin(c)) << x;	
return os << "]";	1.1 Disjoint set with rollback
}	struct Dsu {
usid maint(stains o) (t <1]	vi par, tot;
<pre>void print(string s) { cout &lt;&lt; endl; }</pre>	<pre>stack<ii> mem;</ii></pre>
template <class class="" h,="" t=""></class>	Dsu(int n = 1) : par(n + 1), tot(n + 1, 1) {
<pre>void print(string s, const H &amp;h, const T&amp; t) {</pre>	iota(all(par), 0);

```
}
   int find(int u) {
    return par[u] == u ? u : find(par[u]);
   void unite(int u, int v) {
     u = find(u), v = find(v);
     if (u != v) {
       if (tot[u] < tot[v])</pre>
         swap(u, v);
       mem.emplace(u, v);
       tot[u] += tot[v];
       par[v] = u;
     }
   }
   void rollback() {
     auto [u, v] = mem.top();
     mem.pop();
     if (u != -1) {
       tot[u] -= tot[v];
       par[v] = v;
     }
   }
};
1.2
      Min-Max queue
 struct MinQueue : deque< pair<lli, int> > {
   // add a element to the right {val, pos}
   void add(lli val, int pos) {
     while (!empty() && back().f >= val)
       pop_back();
     emplace_back(val, pos);
   // remove all less than pos
   void rem(int pos) {
     while (front().s < pos)</pre>
       pop_front();
   }
```

# 3;1.3 Sparse table

1li qmin() { return front().f; }

```
Sparse table
template <class T, class F = function<T(const T&,
    const T&)>>
struct Sparse {
  int n:
  vector<vector<T>> sp;
  Sparse(vector<T> &a, const F &f) : n(sz(a)), sp(1 +
       _lg(n)), f(f) {
    sp[0] = a;
    for (int k = 1; (1 << k) <= n; k++) {
      sp[k].resize(n - (1 << k) + 1);
      fore (1, 0, sz(sp[k])) {
        int r = 1 + (1 << (k - 1));
        sp[k][1] = f(sp[k - 1][1], sp[k - 1][r]);
      }
   }
  }
  T query(int 1, int r) {
    int k = _{-}lg(r - l + 1);
    return f(sp[k][1], sp[k][r - (1 << k) + 1]);
  }
};
```

## .4 Squirtle decomposition

The perfect block size is squirtle of N



```
int blo[N], cnt[N][B], a[N];

void update(int i, int x) {
   cnt[blo[i]][x]--;
   a[i] = x;
   cnt[blo[i]][x]++;
}

int query(int l, int r, int x) {
   int tot = 0;
   while (l <= r)
      if (l % B == 0 && l + B - 1 <= r) {
      tot += cnt[blo[l]][x];
      l += B;
   } else {
      tot += (a[l] == x);
      l++;
   }
   return tot;
}</pre>
```

### 1.5 In-Out trick

```
vector<int> in[N], out[N];
vector<Query> queries;

fore (x, 0, N) {
   for (int i : in[x])
     add(queries[i]);
   // solve
   for (int i : out[x])
     rem(queries[i]);
}
```

### 1.6 Parallel binary search

```
int lo[0], hi[0];
queue<int> solve[N];
vector<Query> queries;
fore (it, 0, 1 + _{-}lg(N)) {
  fore (i, 0, sz(queries))
    if (lo[i] != hi[i]) {
      int mid = (lo[i] + hi[i]) / 2;
      solve[mid].emplace(i);
    }
  fore (x, 0, n) {
    // simulate
    while (!solve[x].empty()) {
      int i = solve[x].front();
      solve[x].pop();
      if (can(queries[i]))
        hi[i] = x;
      else
        lo[i] = x + 1;
  }
}
```

### 1.7 Mo's algorithm

```
vector<Query> queries;
// N = 1e6, so aprox. sqrt(N) +/- C
uniform_int_distribution<int> dis(970, 1030);
const int blo = dis(rng);
sort(all(queries), [&](Query a, Query b) {
   const int ga = a.l / blo, gb = b.l / blo;
   if (ga == gb)
     return (ga & 1) ? a.r < b.r : a.r > b.r;
   return a.l < b.l;</pre>
```

```
});
 int 1 = queries[0].1, r = 1 - 1;
 for (Query &q : queries) {
  while (r < q.r)
     add(++r);
   while (r > q.r)
     rem(r--);
   while (1 < q.1)
     rem(1++);
   while (1 > q.1)
     add(--1);
   ans[q.i] = solve();
}
To make it faster, change the order to hilbert(l, r)
11i hilbert(int x, int y, int pw = 21, int rot = 0) {
   if (pw == 0)
     return 0;
   int hpw = 1 << (pw - 1);</pre>
   int k = ((x < hpw ? y < hpw ? 0 : 3 : y < hpw ? 1 :
       2) + rot) & 3;
   const int d[4] = \{3, 0, 0, 1\};
   11i a = 1LL \ll ((pw \ll 1) - 2);
   11i b = hilbert(x & (x ^h hpw), y & (y ^h hpw), pw - 1
       , (rot + d[k]) & 3);
   return k * a + (d[k] ? a - b - 1 : b);
}
      Static to dynamic
 template <class Black, class T>
struct StaticDynamic {
   Black box[LogN];
   vector<T> st[LogN];
   void insert(T &x) {
     int p = 0;
     fore (i, 0, LogN)
       if (st[i].empty()) {
         p = i;
         break;
       }
     st[p].pb(x);
     fore (i, 0, p) {
       st[p].insert(st[p].end(), all(st[i]));
       box[i].clear(), st[i].clear();
     for (auto y : st[p])
      box[p].insert(y);
     box[p].init();
   }
};
      Disjoint intervals
1.9
```

```
struct Interval {
  int 1, r;
  bool operator < (const Interval &it) const {
    return 1 < it.1;
  }
};

struct DisjointIntervals : set<Interval> {
  void add(Interval it) {
    iterator p = lower_bound(it), q = p;
    if (p != begin() && it.1 <= (--p)->r)
        it.1 = p->1, --q;
    for (; q != end() && q->1 <= it.r; erase(q++))
        it.r = max(it.r, q->r);
    insert(it);
}
```

```
void add(int 1, int r) {
     add(Interval{1, r});
   }
};
1.10
       Interval tree
 struct Interval {
  11i 1, r, i;
 };
 struct ITree {
   ITree *ls, *rs;
   vector<Interval> cur;
   11i m;
   ITree(vector<Interval> &vec, 11i 1 = LLONG_MAX, 11i
       r = LLONG_MIN) : ls(0), rs(0) {
     if (1 > r) { // not sorted yet
       sort(all(vec), [&](Interval a, Interval b) {
         return a.1 < b.1;
       });
       for (auto it : vec)
         1 = min(1, it.1), r = max(r, it.r);
     m = (1 + r) >> 1;
     vector<Interval> lo, hi;
     for (auto it : vec)
       (it.r < m ? lo : m < it.l ? hi : cur).pb(it);
     if (!lo.empty())
       ls = new ITree(lo, 1, m);
     if (!hi.empty())
       rs = new ITree(hi, m + 1, r);
   template <class F>
   void near(lli l, lli r, F f) {
     if (!cur.empty() && !(r < cur.front().1)) {</pre>
       for (auto &it : cur)
         f(it);
     if (ls && 1 <= m)</pre>
       ls->near(1, r, f);
     if (rs && m < r)
       rs->near(1, r, f);
   template <class F>
   void overlapping(lli l, lli r, F f) {
     near(1, r, [&](Interval it) {
       if (1 <= it.r && it.l <= r)</pre>
         f(it);
     });
   template <class F>
   void contained(lli l, lli r, F f) {
     near(l, r, [&](Interval it) {
       if (1 <= it.1 && it.r <= r)</pre>
         f(it);
     });
  }
 };
```

# 1.11 Ordered tree

```
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
using namespace __gnu_pbds;

template <class K, class V = null_type>
using ordered_tree = tree<K, V, less<K>, rb_tree_tag,
```

```
tree_order_statistics_node_update>;
                                                                 }
                                                                 pull();
 // less_equal<K> for multiset, multimap (?
#define rank order_of_key
                                                               }
 #define kth find_by_order
                                                               11i qsum(int 11, int rr) {
1.12 Unordered tree
                                                                 if (rr < l || r < ll || r < l)</pre>
 struct chash {
                                                                   return 0;
  const uint64_t C = uint64_t(2e18 * 3) + 71;
                                                                 if (ll <= l && r <= rr)
   const int R = rng();
                                                                   return sum;
  uint64_t operator ()(uint64_t x) const {
                                                                 int m = (1 + r) >> 1;
    return __builtin_bswap64((x ^ R) * C); }
                                                                 return (ls ? ls->qsum(ll, rr) : 0) +
                                                                        (rs ? rs->qsum(ll, rr) : ∅);
                                                              }
template <class K, class V = null_type>
                                                             };
using unordered_tree = gp_hash_table<K, V, chash>;
                                                                    Persistent segment tree
                                                            1.15
        D-dimensional Fenwick tree
                                                             struct Per {
 template <class T, int ...N>
                                                               int 1, r;
struct Fenwick {
                                                               11i sum = 0;
   T v = 0;
                                                               Per *ls, *rs;
   void update(T v) { this->v += v; }
   T query() { return v; }
                                                               Per(int 1, int r) : l(l), r(r), ls(0), rs(0) {}
};
                                                               Per* pull() {
 template <class T, int N, int ...M>
                                                                 sum = 1s->sum + rs->sum;
 struct Fenwick<T, N, M...> {
                                                                 return this:
   #define lsb(x) (x & -x)
   Fenwick<T, M...> fenw[N + 1];
                                                               void build() {
   template <typename... Args>
                                                                 if (1 == r)
   void update(int i, Args... args) {
                                                                   return;
    for (; i <= N; i += lsb(i))</pre>
                                                                 int m = (1 + r) >> 1;
       fenw[i].update(args...);
                                                                 (ls = new Per(1, m))->build();
   }
                                                                 (rs = new Per(m + 1, r)) -> build();
                                                                 pull();
   template <typename... Args>
   T query(int 1, int r, Args... args) {
    T v = 0;
                                                               Per* update(int p, lli v) {
    for (; r > 0; r -= lsb(r))
                                                                 if (p < 1 || r < p)
      v += fenw[r].query(args...);
                                                                   return this;
    for (--1; 1 > 0; 1 -= 1sb(1))
                                                                 Per* t = new Per(1, r);
      v -= fenw[1].query(args...);
                                                                 if (1 == r) {
    return v;
                                                                   t \rightarrow sum = v;
  }
                                                                   return t;
};
                                                                 }
                                                                 t->ls = ls->update(p, v);
1.14 Dynamic segment tree
                                                                 t->rs = rs->update(p, v);
 struct Dyn {
                                                                 return t->pull();
   int 1, r;
   11i sum = 0;
   Dyn *ls, *rs;
                                                               lli qsum(int ll, int rr) {
                                                                 if (r < ll || rr < l)</pre>
   Dyn(int 1, int r) : l(1), r(r), ls(0), rs(0) {}
                                                                   return 0;
                                                                 if (11 <= 1 && r <= rr)</pre>
   void pull() {
                                                                   return sum;
    sum = (1s ? 1s -> sum : 0);
    sum += (rs ? rs->sum : 0);
                                                                 return ls->qsum(ll, rr) + rs->qsum(ll, rr);
                                                              }
   }
                                                            };
   void update(int p, lli v) {
                                                           1.16
                                                                    Wavelet tree
    if (1 == r) {
                                                             struct Wav {
       sum += v;
       return;
                                                               #define iter int* // vector<int>::iterator
                                                               int lo, hi;
    }
    int m = (1 + r) >> 1;
                                                               Wav *ls, *rs;
    if (p <= m) {</pre>
                                                               vi amt;
      if (!1s) 1s = new Dyn(1, m);
      ls->update(p, v);
                                                               Wav(int lo, int hi, iter b, iter e) : lo(lo), hi(hi)
     } else {
                                                                    { // array 1-indexed
                                                                 if (lo == hi || b == e)
       if (!rs) rs = new Dyn(m + 1, r);
       rs->update(p, v);
                                                                   return;
```

```
amt.reserve(e - b + 1);
                                                               }
                                                             };
     amt.pb(0);
     int m = (lo + hi) >> 1;
                                                            1.18
                                                                     Explicit treap
     for (auto it = b; it != e; it++)
      amt.pb(amt.back() + (*it <= m));</pre>
                                                              typedef struct Node* Treap;
     auto p = stable_partition(b, e, [&](int x) {
                                                              struct Node {
      return x <= m;</pre>
                                                                Treap ch[2] = \{0, 0\}, p = 0;
     });
                                                                uint32_t pri = rng();
    ls = new Wav(lo, m, b, p);
                                                                int sz = 1, rev = 0;
     rs = new Wav(m + 1, hi, p, e);
                                                                int val, sum = 0;
                                                                void push() {
   int kth(int 1, int r, int k) {
                                                                  if (rev) {
    if (r < 1)
                                                                    swap(ch[0], ch[1]);
      return 0;
                                                                    for (auto ch : ch) if (ch != 0) {
     if (lo == hi)
                                                                      ch->rev ^= 1;
      return lo;
                                                                    }
     if (k <= amt[r] - amt[l - 1])</pre>
                                                                    rev = 0;
      return ls->kth(amt[l - 1] + 1, amt[r], k);
                                                                  }
     return rs->kth(l - amt[l - 1], r - amt[r], k - amt
                                                                }
         [r] + amt[1 - 1]);
   }
                                                                Treap pull() {
                                                                  #define gsz(t) (t ? t->sz : 0)
   int leq(int 1, int r, int mx) {
                                                                  #define gsum(t) (t ? t->sum : 0)
     if (r < 1 || mx < lo)
                                                                  sz = 1, sum = val;
       return 0;
                                                                  for (auto ch : ch) if (ch != 0) {
     if (hi <= mx)</pre>
                                                                    ch->push();
       return r - 1 + 1;
                                                                    sz += ch->sz;
     return ls->leq(amt[1 - 1] + 1, amt[r], mx) +
                                                                    sum += ch->sum;
            rs->leq(l - amt[l - 1], r - amt[r], mx);
                                                                    ch->p = this;
   }
                                                                  }
};
                                                                 p = 0;
                                                                  return this;
1.17 Li Chao tree
struct Fun {
   lli m = 0, c = inf;
                                                               Node(int val) : val(val) {}
   1li operator ()(lli x) const { return m * x + c; }
                                                             };
};
                                                              pair<Treap, Treap> split(Treap t, int val) {
 struct LiChao {
                                                                // <= val goes to the left, > val to the right
  Fun f;
                                                                if (!t)
   lli 1, r;
                                                                  return {t, t};
  LiChao *ls, *rs;
                                                                t->push();
                                                                if (val < t->val) {
   LiChao(lli l, lli r) : l(l), r(r), ls(0), rs(0) {}
                                                                  auto p = split(t->ch[0], val);
                                                                  t->ch[0] = p.s;
   void add(Fun &g) {
                                                                  return {p.f, t->pull()};
                                                                } else {
     if (f(1) \le g(1) \&\& f(r) \le g(r))
       return;
                                                                  auto p = split(t->ch[1], val);
     if (g(1) < f(1) && g(r) < f(r)) {
                                                                  t->ch[1] = p.f;
      f = g;
                                                                  return {t->pull(), p.s};
       return;
                                                             }
     11i m = (1 + r) >> 1;
     if (g(m) < f(m))
                                                             Treap merge(Treap 1, Treap r) {
      swap(f, g);
                                                                if (!l || !r)
     if (g(1) \le f(1))
                                                                  return 1 ? 1 : r;
     ls = ls ? (ls->add(g), ls) : new LiChao(l, m, g);
                                                                1->push(), r->push();
                                                                if (1->pri > r->pri)
     rs = rs ? (rs->add(g), rs) : new LiChao(m + 1, r,
                                                                  return l->ch[1] = merge(l->ch[1], r), l->pull();
                                                                else
           g);
   }
                                                                  return r->ch[0] = merge(1, r->ch[0]), r->pull();
                                                             }
  1li query(lli x) {
    if (1 == r)
                                                             Treap kth(Treap t, int k) { // 0-indexed
                                                               if (!t)
      return f(x);
     11i m = (1 + r) >> 1;
                                                                 return t;
                                                                t->push();
     if (x \le m)
       return min(f(x), ls ? ls \rightarrow query(x) : inf);
                                                                int sz = gsz(t->ch[0]);
     return min(f(x), rs ? rs->query(x) : inf);
                                                                if (sz == k)
```

```
return t;
                                                               bool isRoot() { return dir() < 0; }</pre>
   return k < sz? kth(t\rightarrow ch[0], k): kth(t\rightarrow ch[1], k\rightarrow ch[1])
        sz - 1);
                                                               friend void add(Splay u, Splay v, int d) {
                                                                 if (v) v->p = u;
                                                                 if (d \ge 0) u \ge ch[d] = v;
int rank(Treap t, int val) { // 0-indexed
   if (!t)
                                                               void rotate() {
    return -1;
   t->push();
                                                                 // assume p and p->p propagated
                                                                 assert(!isRoot());
   if (val < t->val)
    return rank(t->ch[0], val);
                                                                  int x = dir();
   if (t->val == val)
                                                                  Splay g = p;
     return gsz(t->ch[0]);
                                                                 add(g->p, this, g->dir());
   return gsz(t->ch[0]) + rank(t->ch[1], val) + 1;
                                                                 add(g, ch[x ^ 1], x);
                                                                 add(this, g, x ^ 1);
}
                                                                 g->pull(), pull();
Treap insert(Treap t, int val) {
   auto p1 = split(t, val);
   auto p2 = split(p1.f, val - 1);
                                                               void splay() {
   return merge(p2.f, merge(new Node(val), p1.s));
                                                                 // bring this to top of splay tree
                                                                 while (!isRoot() && !p->isRoot()) {
                                                                   p->p->push(), p->push(), push();
Treap erase(Treap t, int val) {
                                                                   dir() == p->dir() ? p->rotate() : rotate();
   auto p1 = split(t, val);
                                                                   rotate();
   auto p2 = split(p1.f, val - 1);
                                                                 }
   return merge(p2.f, p1.s);
                                                                 if (!isRoot()) p->push(), push(), rotate();
                                                                 push(), pull();
1.19
        Implicit treap
                                                               void pull() {
 pair<Treap, Treap> splitsz(Treap t, int sz) {
                                                                 #define gsz(t) (t ? t->sz : 0)
   // <= sz goes to the left, > sz to the right
                                                                 sz = 1 + gsz(ch[0]) + gsz(ch[1]);
  if (!t)
     return {t, t};
   t->push();
                                                               void push() {
   if (sz <= gsz(t->ch[0])) {
                                                                 if (rev) {
     auto p = splitsz(t->ch[0], sz);
                                                                    swap(ch[0], ch[1]);
     t->ch[0] = p.s;
                                                                    for (auto ch : ch) if (ch) {
     return {p.f, t->pull()};
                                                                     ch->rev ^= 1;
   } else {
                                                                   }
     auto p = splitsz(t->ch[1], sz - gsz(t->ch[0]) - 1)
                                                                   rev = 0;
                                                                 }
     t->ch[1] = p.f;
                                                               }
     return {t->pull(), p.s};
  }
                                                               void vsub(Splay t, bool add) {}
}
                                                             };
int pos(Treap t) {
                                                            \mathbf{2}
                                                                  Graphs
   int sz = gsz(t->ch[0]);
   for (; t->p; t = t->p) {
                                                            2.1
                                                                   Topological sort
    Treap p = t->p;
     if (p->ch[1] == t)
                                                             vi order;
       sz += gsz(p->ch[0]) + 1;
                                                             int indeg[N];
   return sz + 1;
                                                             void topsort() { // first fill the indeg[]
}
                                                               queue<int> qu;
                                                                fore (u, 1, n + 1)
1.20
        Splay tree
                                                                  if (indeg[u] == 0)
 typedef struct Node* Splay;
                                                                   qu.push(u);
                                                               while (!qu.empty()) {
 struct Node {
   Splay ch[2] = \{0, 0\}, p = 0;
                                                                 int u = qu.front();
   bool rev = 0;
                                                                 qu.pop();
   int sz = 1;
                                                                 order.pb(u);
                                                                  for (int v : graph[u])
                                                                   if (--indeg[v] == 0)
   int dir() {
    if (!p) return -2; // root of LCT component
                                                                     qu.push(v);
    if (p->ch[0] == this) return 0; // left child
                                                               }
    if (p->ch[1] == this) return 1; // right child
                                                             }
     return -1; // root of current splay tree
                                                            2.2
                                                                   Tarjan algorithm (SCC)
   }
                                                             int tin[N], fup[N];
```

```
bitset<N> still;
                                                              if (!p && children > 1) // u is a cutpoint
stack<int> stk;
 int timer = 0;
                                                            }
void tarjan(int u) {
                                                           2.5
                                                                  Two Sat
   tin[u] = fup[u] = ++timer;
                                                            struct TwoSat {
   still[u] = true;
                                                              int n;
   stk.push(u);
                                                              vector<vi> imp;
   for (int v : graph[u]) {
    if (!tin[v])
                                                              TwoSat(int _n) : n(_n + 1), imp(2 * n) {}
      tarjan(v);
    if (still[v])
                                                              void either(int a, int b) {
       fup[u] = min(fup[u], fup[v]);
                                                                 a = max(2 * a, -1 - 2 * a);
                                                                 b = max(2 * b, -1 - 2 * b);
   if (fup[u] == tin[u]) {
                                                                imp[a ^ 1].pb(b);
    int v;
                                                                 imp[b ^ 1].pb(a);
    do {
      v = stk.top();
      stk.pop();
                                                              void implies(int a, int b) { either(~a, b); }
       still[v] = false;
                                                              void setVal(int a) { either(a, a); }
       // u and v are in the same scc
    } while (v != u);
                                                              vi solve() {
   }
                                                                 int k = sz(imp);
}
                                                                 vi s, b, id(sz(imp));
      Kosaraju algorithm (SCC)
2.3
                                                                 function<void(int)> dfs = [&](int u) {
int scc[N], k = 0;
                                                                  b.pb(id[u] = sz(s));
char vis[N];
                                                                   s.pb(u);
vi order;
                                                                   for (int v : imp[u]) {
                                                                    if (!id[v]) dfs(v);
void dfs1(int u) {
                                                                     else while (id[v] < b.back()) b.pop_back();</pre>
  vis[u] = 1;
   for (int v : graph[u])
                                                                   if (id[u] == b.back())
    if (vis[v] != 1)
                                                                     for (b.pop_back(), ++k; id[u] < sz(s); s.</pre>
       dfs1(v);
                                                                         pop_back())
   order.pb(u);
                                                                       id[s.back()] = k;
                                                                 };
void dfs2(int u, int k) {
                                                                 fore (u, 0, sz(imp))
   vis[u] = 2, scc[u] = k;
                                                                  if (!id[u]) dfs(u);
   for (int v : rgraph[u]) // reverse graph
    if (vis[v] != 2)
                                                                 vi val(n);
       dfs2(v, k);
                                                                 fore (u, 0, n) {
                                                                  int x = 2 * u;
                                                                  if (id[x] == id[x ^ 1])
void kosaraju() {
                                                                    return {};
   fore (u, 1, n + 1)
                                                                  val[u] = id[x] < id[x ^ 1];
    if (vis[u] != 1)
                                                                 }
       dfs1(u);
                                                                 return val;
   reverse(all(order));
                                                              }
   for (int u : order)
                                                            };
    if (vis[u] != 2)
                                                           2.6
                                                                 Detect a cycle
       dfs2(u, ++k);
}
                                                            bool cycle(int u) {
                                                              vis[u] = 1;
      Cutpoints and Bridges
                                                              for (int v : graph[u]) {
int tin[N], fup[N], timer = 0;
                                                                 if (vis[v] == 1)
                                                                  return true;
void findWeakness(int u, int p = 0) {
                                                                 if (!vis[v] && cycle(v))
   tin[u] = fup[u] = ++timer;
                                                                   return true;
   int children = 0;
   for (int v : graph[u]) if (v != p) {
                                                              vis[u] = 2;
    if (!tin[v]) {
                                                              return false;
                                                            }
       ++children;
       findWeakness(v, u);
                                                                  Euler tour for Mo's in a tree
                                                           2.7
       fup[u] = min(fup[u], fup[v]);
       if (fup[v] >= tin[u] && p) // u is a cutpoint
                                                           Mo's in a tree, extended euler tour tin[u] = ++timer, tout[u]
                                                           = ++timer
       if (fup[v] > tin[u]) // bridge u -> v
                                                              • u = lca(u, v), query(tin[u], tin[v])
     fup[u] = min(fup[u], tin[v]);
                                                              • u \neq lca(u, v), query(tout[u], tin[v]) + query(tin[lca],
```

```
tin[lca])
                                                                 solve(m + 1, r);
                                                                 while (sz(dsu.mem) > before)
2.8 Isomorphism
                                                                  dsu.rollback();
11i f(11i x) {
                                                              }
  // K * n <= 9e18
                                                            };
   static uniform_int_distribution<lli> uid(1, K);
   if (!mp.count(x))
                                                           3
                                                                 Tree queries
    mp[x] = uid(rng);
                                                                  Lowest common ancestor (LCA)
   return mp[x];
                                                           3.1
                                                            const int LogN = 1 + __lg(N);
                                                            int par[LogN][N], dep[N];
lli hsh(int u, int p = 0) {
   dp[u] = h[u] = 0;
                                                             void dfs(int u, int par[]) {
   for (int v : graph[u]) {
                                                              for (int v : graph[u])
    if (v == p)
                                                                 if (v != par[u]) {
       {\color{red}\textbf{continue}};\\
                                                                  par[v] = u;
    dp[u] += hsh(v, u);
                                                                  dep[v] = dep[u] + 1;
   }
                                                                  dfs(v, par);
   return h[u] = f(dp[u]);
                                                            }
     Dynamic Connectivity
                                                            int lca(int u, int v){
struct DynamicConnectivity {
                                                              if (dep[u] > dep[v])
   struct Query {
                                                                 swap(u, v);
    int op, u, v, at;
                                                               fore (k, LogN, 0)
                                                                 if (dep[v] - dep[u] >= (1 << k))
                                                                  v = par[k][v];
   Dsu dsu; // with rollback
                                                               if (u == v)
   vector<Query> queries;
                                                                 return u;
   map<ii, int> mp;
                                                               fore (k, LogN, 0)
   int timer = -1;
                                                                 if (par[k][v] != par[k][u])
                                                                   u = par[k][u], v = par[k][v];
   DynamicConnectivity(int n = 0) : dsu(n) {}
                                                              return par[0][u];
                                                            }
   void add(int u, int v) {
    mp[minmax(u, v)] = ++timer;
                                                             int dist(int u, int v) {
    queries.pb({'+', u, v, INT_MAX});
                                                              return dep[u] + dep[v] - 2 * dep[lca(u, v)];
                                                            }
   void rem(int u, int v) {
                                                            void init(int r) {
    int in = mp[minmax(u, v)];
                                                              dfs(r, par[0]);
    queries.pb(\{'-', u, v, in\});
                                                              fore (k, 1, LogN)
    queries[in].at = ++timer;
                                                                 fore (u, 1, n + 1)
    mp.erase(minmax(u, v));
                                                                   par[k][u] = par[k - 1][par[k - 1][u]];
                                                            }
                                                           3.2
                                                                 Virtual tree
   void query() {
    queries.push_back({'?', -1, -1, ++timer});
                                                            vi virt[N];
                                                             int virtualTree(vi &ver) {
   void solve(int 1, int r) {
                                                              auto byDfs = [&](int u, int v) {
    if (1 == r) {
                                                                 return tin[u] < tin[v];</pre>
       if (queries[1].op == '?') // solve the query
                                                              };
           here
                                                              sort(all(ver), byDfs);
       return;
                                                              fore (i, sz(ver), 1)
    }
                                                                 ver.pb(lca(ver[i - 1], ver[i]));
    int m = (1 + r) >> 1;
                                                               sort(all(ver), byDfs);
    int before = sz(dsu.mem);
                                                              ver.erase(unique(all(ver)), ver.end());
     for (int i = m + 1; i <= r; i++) {
                                                              for (int u : ver)
       Query &q = queries[i];
                                                                virt[u].clear();
       if (q.op == '-' && q.at < 1)
                                                              fore (i, 1, sz(ver))
         dsu.unite(q.u, q.v);
                                                                 virt[lca(ver[i - 1], ver[i])].pb(ver[i]);
                                                              return ver[0];
     solve(1, m);
                                                            }
    while (sz(dsu.mem) > before)
                                                           3.3 Guni
       dsu.rollback();
     for (int i = 1; i <= m; i++) {</pre>
                                                            int cnt[C], color[N];
       Query &q = queries[i];
                                                            int sz[N];
       if (q.op == '+' && q.at > r)
                                                            int guni(int u, int p = 0) {
         dsu.unite(q.u, q.v);
    }
                                                              sz[u] = 1;
```

```
for (int &v : graph[u]) if (v != p) {
                                                              head[u] = h, pos[u] = ++timer, who[timer] = u;
    sz[u] += guni(v, u);
                                                              for (int &v : graph[u])
                                                                if (v != par[u])
    if (sz[v] > sz[graph[u][0]] || p == graph[u][0])
      swap(v, graph[u][0]);
                                                                  hld(v, v == graph[u][0] ? h : v);
                                                            }
  return sz[u];
                                                            template <class F>
}
                                                            void processPath(int u, int v, F f) {
void add(int u, int p, int x, bool skip) {
                                                              for (; head[u] != head[v]; v = par[head[v]]) {
                                                                if (dep[head[u]] > dep[head[v]]) swap(u, v);
  cnt[color[u]] += x;
  for (int i = skip; i < sz(graph[u]); i++) // don't</pre>
                                                                f(pos[head[v]], pos[v]);
       change it with a fore!!!
                                                              if (dep[u] > dep[v]) swap(u, v);
    if (graph[u][i] != p)
      add(graph[u][i], u, x, 0);
                                                              if (u != v) f(pos[graph[u][0]], pos[v]);
}
                                                              f(pos[u], pos[u]); // only if hld over vertices
                                                            }
void solve(int u, int p, bool keep = 0) {
  fore (i, sz(graph[u]), 0)
                                                            void updatePath(int u, int v, lli z) {
    if (graph[u][i] != p)
                                                              processPath(u, v, [&](int 1, int r) {
      solve(graph[u][i], u, !i);
                                                                tree->update(1, r, z);
  add(u, p, +1, 1); // add
                                                              });
  // now cnt[i] has how many times the color i appears
       in the subtree of u
  if (!keep) add(u, p, -1, 0); // remove
                                                            11i queryPath(int u, int v) {
}
                                                              11i sum = 0;
                                                              processPath(u, v, [\&](int 1, int r) {
     Centroid decomposition
                                                                sum += tree->qsum(1, r);
int cdp[N], sz[N];
                                                              });
bitset<N> rem;
                                                              return sum;
int dfsz(int u, int p = 0) {
  sz[u] = 1;
                                                           3.6
                                                                Link-Cut tree
  for (int v : graph[u])
                                                            void access(Splay u) {
   if (v != p && !rem[v])
                                                              \ensuremath{//} puts u on the preferred path, splay (right
      sz[u] += dfsz(v, u);
                                                                  subtree is empty)
  return sz[u];
                                                              for (Splay v = u, pre = NULL; v; v = v -> p) {
                                                                v->splay(); // now pull virtual children
                                                                if (pre) v->vsub(pre, false);
int centroid(int u, int n, int p = 0) {
                                                                if (v->ch[1]) v->vsub(v->ch[1], true);
  for (int v : graph[u])
                                                                v \rightarrow ch[1] = pre, v \rightarrow pull(), pre = v;
    if (v != p && !rem[v] && 2 * sz[v] > n)
                                                              }
      return centroid(v, n, u);
                                                              u->splay();
  return u;
                                                            }
}
                                                            void rootify(Splay u) {
void solve(int u, int p = 0) {
                                                              // make u root of LCT component
  cdp[u = centroid(u, dfsz(u))] = p;
                                                              access(u), u->rev ^= 1, access(u);
  rem[u] = true;
                                                              assert(!u->ch[0] && !u->ch[1]);
  for (int v : graph[u])
    if (!rem[v])
      solve(v, u);
                                                            Splay lca(Splay u, Splay v) {
}
                                                              if (u == v) return u;
     Heavy-light decomposition
                                                              access(u), access(v);
int par[N], dep[N], sz[N], head[N], pos[N], who[N],
                                                              if (!u->p) return NULL;
    timer = 0;
                                                              return u->splay(), u->p ?: u;
Lazy* tree;
                                                            }
int dfs(int u) {
                                                            bool connected(Splay u, Splay v) {
  sz[u] = 1, head[u] = 0;
                                                              return lca(u, v) != NULL;
  for (int &v : graph[u]) if (v != par[u]) {
                                                            }
    par[v] = u;
    dep[v] = dep[u] + 1;
                                                            void link(Splay u, Splay v) { // make u parent of v
    sz[u] += dfs(v);
                                                              if (!connected(u, v)) {
   if (sz[v] > sz[graph[u][0]])
                                                                rootify(v), access(u);
      swap(v, graph[u][0]);
                                                                add(v, u, ∅), v->pull();
  }
                                                              }
                                                            }
  return sz[u];
                                                            void cut(Splay u) {
void hld(int u, int h) {
                                                              // cut u from its parent
```

```
access(u);
                                                                     int u = qu.front();
   u \rightarrow ch[0] \rightarrow p = u \rightarrow ch[0] = NULL;
                                                                     qu.pop();
   u->pull();
                                                                     for (Edge &e : g[u]) if (dist[e.v] == -1)
                                                                       if (e.cap - e.flow > eps) {
                                                                         dist[e.v] = dist[u] + 1;
 void cut(Splay u, Splay v) { // if u, v are adjacent
                                                                         qu.push(e.v);
                                                                       }
     in the tree
   cut(depth(u) > depth(v) ? u : v);
                                                                   }
                                                                   return dist[t] != -1;
 int depth(Splay u) {
   access(u);
                                                                 F dfs(int u, F flow = numeric_limits<F>::max()) {
   return gsz(u->ch[0]);
                                                                   if (flow <= eps || u == t)</pre>
                                                                     return max<F>(0, flow);
                                                                   for (int &i = ptr[u]; i < sz(g[u]); i++) {</pre>
 Splay getRoot(Splay u) { // get root of LCT component
                                                                     Edge &e = g[u][i];
                                                                     if (e.cap - e.flow > eps && dist[u] + 1 == dist[
   access(u):
   while (u->ch[0]) u = u->ch[0], u->push();
                                                                          e.v]) {
                                                                      F pushed = dfs(e.v, min<F>(flow, e.cap - e.flow
   return access(u), u;
                                                                           ));
                                                                       if (pushed > eps) {
 Splay ancestor(Splay u, int k) {
                                                                         e.flow += pushed;
   // get k-th parent on path to root
                                                                         g[e.v][e.inv].flow -= pushed;
   k = depth(u) - k;
                                                                         return pushed;
   assert(k >= 0);
                                                                       }
   for (;; u->push()) {
                                                                     }
     int sz = gsz(u->ch[0]);
                                                                   }
     if (sz == k) return access(u), u;
                                                                   return 0;
     if (sz < k) k = sz + 1, u = u - ch[1];
     else u = u - ch[0];
                                                                 F maxFlow() {
                                                                   F flow = 0;
   assert(₀);
                                                                   while (bfs()) {
                                                                     fill(all(ptr), 0);
 Splay query(Splay u, Splay v) {
                                                                     while (F pushed = dfs(s))
   return rootify(u), access(v), v;
                                                                       flow += pushed;
 }
                                                                   return flow;
     Flows
4
                                                                 }
                                                              };
4.1
       Dinic \mathcal{O}(min(E \cdot flow, V^2E))
                                                              4.2
                                                                     Min cost flow \mathcal{O}(min(E \cdot flow, V^2E))
If the network is massive, try to compress it by looking for
                                                             If the network is massive, try to compress it by looking for
patterns.
                                                             patterns.
 template <class F>
 struct Dinic {
                                                               template <class C, class F>
                                                               struct Mcmf {
   struct Edge {
                                                                 struct Edge {
     int v, inv;
                                                                   int u, v, inv;
     F cap. flow:
     Edge(int v, F cap, int inv) : v(v), cap(cap), flow
                                                                   F cap, flow;
          (0), inv(inv) {}
                                                                   C cost:
                                                                   Edge(int u, int v, C cost, F cap, int inv) : u(u),
                                                                         v(v), cost(cost), cap(cap), flow(∅), inv(inv
   F eps = (F) 1e-9;
                                                                        ) {}
   int s, t, n, m = 0;
                                                                 };
   vector< vector<Edge> > g;
                                                                 F eps = (F) 1e-9;
   vi dist, ptr;
                                                                 int s, t, n, m = 0;
   Dinic(int n) : n(n), g(n), dist(n), ptr(n), s(n - 2)
                                                                 vector< vector<Edge> > g;
        , t(n - 1) \{ \}
                                                                 vector<Edge*> prev;
                                                                 vector<C> cost;
   void add(int u, int v, F cap) {
                                                                 vi state:
     g[u].pb(Edge(v, cap, sz(g[v])));
     g[v].pb(Edge(u, 0, sz(g[u]) - 1));
                                                                 Mcmf(int n) : n(n), g(n), cost(n), state(n), prev(n)
     m += 2;
                                                                      s(n-2), t(n-1)
   }
                                                                 void add(int u, int v, C cost, F cap) {
```

m += 2;

}

g[u].pb(Edge(u, v, cost, cap, sz(g[v])));

g[v].pb(Edge(v, u, -cost, 0, sz(g[u]) - 1));

bool bfs() {

dist[s] = 0;

fill(all(dist), -1);

queue<int> qu({s});

while (sz(qu) && dist[t] == -1) {

```
bool bfs() {
                                                                  }
                                                                  return dist[0] != -1;
     fill(all(state), 0);
     fill(all(cost), numeric_limits<C>::max());
                                                                }
     deque<int> qu;
                                                                bool dfs(int u) {
     qu.push_back(s);
     state[s] = 1, cost[s] = 0;
                                                                  for (int v : g[u])
     while (sz(qu)) {
                                                                    if (!match[v] || (dist[u] + 1 == dist[match[v]]
       int u = qu.front(); qu.pop_front();
                                                                        && dfs(match[v]))) {
                                                                      match[u] = v, match[v] = u;
       state[u] = 2;
       for (Edge &e : g[u]) if (e.cap - e.flow > eps)
                                                                      return 1;
         if (cost[u] + e.cost < cost[e.v]) {</pre>
           cost[e.v] = cost[u] + e.cost;
                                                                  dist[u] = 1 << 30;
           prev[e.v] = &e;
                                                                  return 0;
           if (state[e.v] == 2 \mid | (sz(qu) \&\& cost[qu.
                front()] > cost[e.v]))
                                                                int maxMatching() {
             qu.push_front(e.v);
           else if (state[e.v] == 0)
                                                                  int tot = 0:
             qu.push_back(e.v);
                                                                  while (bfs())
           state[e.v] = 1;
                                                                    fore (u, 1, n)
                                                                      tot += match[u] ? 0 : dfs(u);
    }
                                                                  return tot;
     return cost[t] != numeric_limits<C>::max();
   }
                                                             };
                                                            4.4
                                                                   Hungarian \mathcal{O}(N^3)
   pair<C, F> minCostFlow() {
                                                            n jobs, m people
     C cost = 0; F flow = 0;
                                                              template <class C>
     while (bfs()) {
                                                              pair<C, vi> Hungarian(vector< vector<C> > &a) {
       F pushed = numeric_limits<F>::max();
                                                                int n = sz(a), m = sz(a[0]), p, q, j, k; // n \le m
       for (Edge* e = prev[t]; e != nullptr; e = prev[e
                                                               vector<C> fx(n, numeric_limits<C>::min()), fy(m, 0);
                                                                vi x(n, -1), y(m, -1);
         pushed = min(pushed, e->cap - e->flow);
                                                                fore (i, 0, n)
       for (Edge* e = prev[t]; e != nullptr; e = prev[e
                                                                  fore (j, 0, m)
            ->u]) {
                                                                    fx[i] = max(fx[i], a[i][j]);
         e->flow += pushed;
         g[e->v][e->inv].flow -= pushed;
                                                                fore (i, 0, n) {
                                                                  vi t(m, -1), s(n + 1, i);
         cost += e->cost * pushed;
                                                                  for (p = q = 0; p \le q && x[i] \le 0; p++)
       }
                                                                    for (k = s[p], j = 0; j < m && x[i] < 0; j++)
       flow += pushed;
                                                                      if (abs(fx[k] + fy[j] - a[k][j]) < eps && t[j]</pre>
     return make_pair(cost, flow);
                                                                           < 0) {
                                                                        s[++q] = y[j], t[j] = k;
   }
                                                                        if (s[q] < 0) for (p = j; p >= 0; j = p)
};
                                                                          y[j] = k = t[j], p = x[k], x[k] = j;
4.3
      Hopcroft-Karp \mathcal{O}(E\sqrt{V})
                                                                      }
 struct HopcroftKarp {
                                                                  if (x[i] < 0) {
   int n, m = 0;
                                                                    C d = numeric_limits<C>::max();
   vector<vi> g;
                                                                    fore (k, 0, q + 1)
   vi dist, match;
                                                                      fore (j, 0, m) if (t[j] < 0)</pre>
                                                                        d = min(d, fx[s[k]] + fy[j] - a[s[k]][j]);
   HopcroftKarp(int _n) : n(_n + 5), g(n), dist(n),
                                                                    fore (j, 0, m)
       match(n, 0) {} // 1-indexed!!
                                                                      fy[j] += (t[j] < 0 ? 0 : d);
                                                                    fore (k, 0, q + 1)
   void add(int u, int v) {
                                                                      fx[s[k]] -= d;
     g[u].pb(v), g[v].pb(u);
    m += 2;
                                                                  }
   }
                                                                }
                                                                C cost = 0;
   bool bfs() {
                                                                fore (i, 0, n) cost += a[i][x[i]];
     queue<int> qu;
                                                                return make_pair(cost, x);
     fill(all(dist), -1);
                                                             }
     fore (u, 1, n)
                                                            5
                                                                  Strings
       if (!match[u])
         dist[u] = 0, qu.push(u);
                                                                  \mathbf{Hash}
                                                            5.1
     while (!qu.empty()) {
                                                              vi mod = {999727999, 999992867, 1000000123, 10000002193
       int u = qu.front(); qu.pop();
                                                                  , 1000003211, 1000008223, 1000009999, 1000027163,
       for (int v : g[u])
         if (dist[match[v]] == -1) {
                                                                   1070777777};
           dist[match[v]] = dist[u] + 1;
           if (match[v])
                                                              struct H : array<int, 2> {
                                                                #define oper(op) friend H operator op (H a, H b) { \
             qu.push(match[v]);
                                                                fore (i, 0, sz(a)) a[i] = (1LL * a[i] op b[i] + mod[
         }
```

```
i]) % mod[i]; \
                                                               return tot;
   return a; }
                                                             }
   oper(+) oper(-) oper(*)
                                                            5.3
 } pw[N], ipw[N];
 struct Hash {
   vector<H> h;
   Hash(string \&s) : h(sz(s) + 1) {
     fore (i, 0, sz(s)) {
      int x = s[i] - 'a' + 1;
       h[i + 1] = h[i] + pw[i] * H(x, x);
   }
                                                                  }
   H cut(int 1, int r) {
     return (h[r + 1] - h[l]) * ipw[l];
                                                             }
   }
 };
 int inv(int a, int m) {
   return a == 1 ? 1 : int(m - lli(inv(m, a)) * lli(m)
       / a);
 }
 const int P = uniform_int_distribution<int>(MaxAlpha +
      1, min(mod[0], mod[1]) - 1)(rng);
 pw[0] = ipw[0] = \{1, 1\};
                                                               }
 H Q = {inv(P, mod[0]), inv(P, mod[1])};
 fore (i, 1, N) {
                                                             }
   pw[i] = pw[i - 1] * H{P, P};
   ipw[i] = ipw[i - 1] * Q;
 // Save len in the struct and when you do a cut
 H merge(vector<H> &cuts) {
   F f = \{0, 0\};
   fore (i, sz(cuts), 0) {
     F g = cuts[i];
     f = g + f * pw[g.len];
   }
   return f;
 }
      KMP
5.2
period = n - p[n - 1], period(abcabc) = 3, n \mod period \equiv 0
                                                                  }
 vi lps(string &s) {
                                                               }
   vi p(sz(s), 0);
   int j = 0;
                                                             }
   fore (i, 1, sz(s)) {
     while (j && s[i] != s[j])
                                                            5.6
       j = p[j - 1];
     j += (s[i] == s[j]);
     p[i] = j;
   }
   return p;
 // how many times t occurs in s
 int kmp(string &s, string &t) {
   vi p = lps(t);
                                                               int n;
   int j = 0, tot = 0;
   fore (i, 0, sz(s)) {
     while (j && s[i] != t[j])
       j = p[j - 1];
     if (s[i] == t[j])
      j++;
     if (j == sz(t))
       tot++; // pos: i - sz(t) + 1;
   }
```

```
KMP automaton
int go[N][A];
void kmpAutomaton(string &s) {
  s += "$";
  vi p = lps(s);
  fore (i, 0, sz(s))
    fore (c, 0, A) {
      if (i && s[i] != 'a' + c)
        go[i][c] = go[p[i - 1]][c];
      else
        go[i][c] = i + ('a' + c == s[i]);
  s.pop_back();
    Z algorithm
vi zf(string &s) {
  vi z(sz(s), 0);
  for (int i = 1, l = 0, r = 0; i < sz(s); i++) {
    if (i <= r)
      z[i] = min(r - i + 1, z[i - 1]);
    while (i + z[i] < sz(s) \&\& s[i + z[i]] == s[z[i]])
      ++z[i];
    if (i + z[i] - 1 > r)
      1 = i, r = i + z[i] - 1;
  return z;
      Manacher algorithm
vector<vi> manacher(string &s) {
  vector<vi> pal(2, vi(sz(s), 0));
  fore (k, 0, 2) {
    int 1 = 0, r = 0;
    fore (i, 0, sz(s)) {
      int t = r - i + !k;
      if (i < r)
        pal[k][i] = min(t, pal[k][l + t]);
      int p = i - pal[k][i], q = i + pal[k][i] - !k;
      while (p >= 1 \& q + 1 < sz(s) \& s[p - 1] == s[
          q + 1])
        ++pal[k][i], --p, ++q;
      if (q > r)
        1 = p, r = q;
  return pal;
    Suffix array
 • Duplicates \sum_{i=1}^{n} lcp[i]
 • Longest Common Substring of various strings
   Add not Used characters between strings, i.e. a+\$+b+\#+c
   Use two-pointers to find a range [l, r] such that all not Used
   characters are present, then query(lcp[l+1],..,lcp[r]) for
   that window is the common length.
struct SuffixArray {
  string s;
  vi sa, lcp;
  SuffixArray(string &s): n(sz(s) + 1), s(s), sa(n),
      lcp(n) {
    vi top(max(256, n)), rk(n);
    fore (i, 0, n)
      top[rk[i] = s[i] & 255]++;
    partial_sum(all(top), top.begin());
```

```
fore (i, 0, n)
      sa[--top[rk[i]]] = i;
    vi sb(n);
    for (int len = 1, j; len < n; len <<= 1) {</pre>
      fore (i, 0, n) {
        j = (sa[i] - len + n) % n;
        sb[top[rk[j]]++] = j;
      sa[sb[top[0] = 0]] = j = 0;
      fore (i, 1, n) {
        if (rk[sb[i]] != rk[sb[i - 1]] || rk[sb[i] +
            len] != rk[sb[i - 1] + len])
          top[++j] = i;
        sa[sb[i]] = j;
      }
      copy(all(sa), rk.begin());
      copy(all(sb), sa.begin());
      if (j >= n - 1)
        break;
    for (int i = 0, j = rk[lcp[0] = 0], k = 0; i < n - 0
         1; i++, k++)
      while (k >= 0 && s[i] != s[sa[j - 1] + k])
        lcp[j] = k--, j = rk[sa[j] + 1];
  }
  char at(int i, int j) {
    int k = sa[i] + j;
    return k < n ? s[k] : 'z' + 1;</pre>
  int count(string &t) {
    ii lo(0, n - 1), hi(0, n - 1);
    fore (i, 0, sz(t)) {
      while (lo.f + 1 < lo.s) {
        int mid = (lo.f + lo.s) / 2;
        (at(mid, i) < t[i] ? lo.f : lo.s) = mid;
      while (hi.f + 1 < hi.s) {</pre>
        int mid = (hi.f + hi.s) / 2;
        (t[i] < at(mid, i) ? hi.s : hi.f) = mid;
      int p1 = (at(lo.f, i) == t[i] ? lo.f : lo.s);
      int p2 = (at(hi.s, i) == t[i] ? hi.s : hi.f);
      if (at(p1, i) != t[i] || at(p2, i) != t[i] || p1
           > p2)
        return 0:
      lo = hi = ii(p1, p2);
    return lo.s - lo.f + 1;
  }
};
      Suffix automaton
```

### 5.7

- sam[u].len sam[sam[u].link].len = distinct strings
- Number of different substrings (dp)

$$diff(u) = 1 + \sum_{v \in trie[u]} diff(v)$$

• Total length of all different substrings (2 x dp)

$$totLen(u) = \sum_{v \in trie[u]} diff(v) + totLen(v)$$

- Leftmost occurrence trie[u].pos = trie[u].len 1if it is **clone** then trie[clone].pos = trie[q].pos
- All occurrence positions
- Smallest cyclic shift Construct sam of s + s, find the lexicographically smallest path of sz(s)

```
    Shortest non-appearing string

        nonAppearing(u) = \min_{v \in trie[u]} nonAppearing(v) + 1
struct SuffixAutomaton {
  struct Node : map<char, int> {
    int link = -1, len = 0;
  vector<Node> trie;
  int last;
  SuffixAutomaton() { last = newNode(); }
  int newNode() {
    trie.pb({}):
    return sz(trie) - 1;
  void extend(char c) {
    int u = newNode();
    trie[u].len = trie[last].len + 1;
    int p = last;
    while (p != -1 && !trie[p].count(c)) {
      trie[p][c] = u;
      p = trie[p].link;
    if (p == -1)
      trie[u].link = 0;
    else {
      int q = trie[p][c];
      if (trie[p].len + 1 == trie[q].len)
        trie[u].link = q;
      else {
        int clone = newNode();
        trie[clone] = trie[q];
        trie[clone].len = trie[p].len + 1;
        while (p != -1 \&\& trie[p][c] == q) {
          trie[p][c] = clone;
          p = trie[p].link;
        }
        trie[q].link = trie[u].link = clone;
      }
    }
    last = u:
  string kthSubstring(lli kth, int u = 0) {
    // number of different substrings (dp)
    string s = "";
    while (kth > 0)
      for (auto &[c, v] : trie[u]) {
        if (kth <= diff(v)) {</pre>
          s.pb(c), kth--, u = v;
          break:
        }
        kth -= diff(v);
      }
    return s:
  void occurs() {
    // trie[u].occ = 1, trie[clone].occ = 0
    vi who:
    fore (u, 1, sz(trie))
      who.pb(u);
    sort(all(who), [&](int u, int v) {
      return trie[u].len > trie[v].len;
    for (int u : who) {
      int 1 = trie[u].link;
```

```
trie[l].occ += trie[u].occ;
    }
                                                                }
  }
  1li queryOccurences(string &s, int u = 0) {
    for (char c : s) {
     if (!trie[u].count(c))
        return 0;
      u = trie[u][c];
    return trie[u].occ;
  }
  int longestCommonSubstring(string &s, int u = 0) {
    int mx = 0, clen = 0;
    for (char c : s) {
      while (u && !trie[u].count(c)) {
        u = trie[u].link;
        clen = trie[u].len;
      if (trie[u].count(c))
        u = trie[u][c], clen++;
     mx = max(mx, clen);
    }
                                                                  }
    return mx;
                                                                }
  }
                                                              }
  string smallestCyclicShift(int n, int u = 0) {
    string s = "";
    fore (i, 0, n) {
      char c = trie[u].begin()->f;
      s += c;
      u = trie[u][c];
    }
    return s;
  }
                                                                }
  int leftmost(string &s, int u = 0) {
    for (char c : s) {
     if (!trie[u].count(c))
        return -1;
      u = trie[u][c];
                                                              }
    }
                                                           };
    return trie[u].pos - sz(s) + 1;
  }
  Node& operator [](int u) {
    return trie[u];
  }
                                                              };
};
     Aho corasick
struct AhoCorasick {
  struct Node : map<char, int> {
    int link = 0, out = 0;
    int cnt = 0, isw = 0;
  }:
  vector<Node> trie;
  AhoCorasick() { newNode(); }
  int newNode() {
    trie.pb({});
                                                              }
    return sz(trie) - 1;
  }
  void insert(string &s, int u = ∅) {
    for (char c : s) {
      if (!trie[u][c])
                                                              }
        trie[u][c] = newNode();
```

```
u = trie[u][c];
     trie[u].cnt++, trie[u].isw = 1;
   int go(int u, char c) {
     while (u && !trie[u].count(c))
       u = trie[u].link;
     return trie[u][c];
   void pushLinks() {
     queue<int> qu;
     qu.push(0);
     while (!qu.empty()) {
       int u = qu.front();
       qu.pop();
       for (auto &[c, v] : trie[u]) {
         int 1 = (trie[v].link = u ? go(trie[u].link, c
             ): 0);
         trie[v].cnt += trie[l].cnt;
         trie[v].out = trie[l].isw ? l : trie[l].out;
         qu.push(v);
   int match(string &s, int u = 0) {
     int ans = 0;
     for (char c : s) {
       u = go(u, c);
       ans += trie[u].cnt;
       for (int x = u; x != 0; x = trie[x].out)
         // pass over all elements of the implicit
             vector
     return ans;
   Node& operator [](int u) {
     return trie[u];
5.9 Eertree
 struct Eertree {
   struct Node : map<char, int> {
     int link = 0, len = 0;
   vector<Node> trie;
   string s = "$";
   int last;
   Eertree() {
     last = newNode(), newNode();
     trie[0].link = 1, trie[1].len = -1;
   int newNode() {
     trie.pb({});
     return sz(trie) - 1;
   int go(int u) {
     while (s[sz(s) - trie[u].len - 2] != s.back())
       u = trie[u].link;
     return u;
```

```
void extend(char c) {
     s += c;
     int u = go(last);
     if (!trie[u][c]) {
       int v = newNode();
       trie[v].len = trie[u].len + 2;
       trie[v].link = trie[go(trie[u].link)][c];
       trie[u][c] = v;
     last = trie[u][c];
   }
   Node& operator [](int u) {
     return trie[u];
   }
 };
     Dynamic Programming
6
      All submasks of a mask
 for (int B = A; B > 0; B = (B - 1) & A)
      Matrix Chain Multiplication
 int dp(int 1, int r) {
   if (1 > r)
     return OLL;
   int &ans = mem[1][r];
   if (!done[l][r]) {
     done[1][r] = true, ans = inf;
     fore (k, l, r + 1) // split in [l, k] [k + 1, r]
       ans = min(ans, dp(1, k) + dp(k + 1, r) + add);
   return ans;
 }
6.3
      Digit DP
Counts the amount of numbers in [l, r] such are divisible by k.
(flag nonzero is for different lengths)
It can be reduced to dp(i, x, small), and has to be solve like
f(r) - f(l-1)
 #define state [i][x][small][big][nonzero]
 int dp(int i, int x, bool small, bool big, bool
     nonzero) {
   if (i == sz(r))
     return x % k == 0 && nonzero;
   int &ans = mem state;
   if (done state != timer) {
     done state = timer;
     ans = 0;
     int lo = small ? 0 : 1[i] - '0';
     int hi = big ? 9 : r[i] - '0';
     fore (y, lo, max(lo, hi) + 1) {
       bool small2 = small | (y > 1o);
       bool big2 = big | (y < hi);
       bool nonzero2 = nonzero | (x > 0);
       ans += dp(i + 1, (x * 10 + y) % k, small2, big2,
             nonzero2);
     }
   }
   return ans;
     Knapsack 0/1
 for (auto &cur : items)
   fore (w, W + 1, cur.w) // [cur.w, W]
     umax(dp[w], dp[w - cur.w] + cur.cost);
6.5
      Convex Hull Trick \mathcal{O}(n^2) \Rightarrow \mathcal{O}(n)
dp[i] = \min_{j < i} (dp[j] + b[j] * a[i])
dp[i][j] = \min_{k < j} (dp[i-1][k] + b[k] * a[j])
```

```
b[j] \ge b[j+1] optionally a[i] \le a[i+1]
 // for doubles, use \inf = 1/.0, \operatorname{div}(a,b) = a / b
 struct Line {
   mutable lli m, c, p;
   bool operator < (const Line &l) const { return m < l</pre>
   bool operator < (lli x) const { return p < x; }</pre>
   lli operator ()(lli x) const { return m * x + c; }
 struct DynamicHull : multiset<Line, less<>> {
   lli div(lli a, lli b) {
     return a / b - ((a ^ b) < 0 && a % b);
   bool isect(iterator x, iterator y) {
     if (y == end())
       return x->p = inf, 0;
     if (x->m == y->m)
       x->p = (x->c > y->c ? inf : -inf);
       x->p = div(x->c - y->c, y->m - x->m);
     return x->p >= y->p;
   void add(lli m, lli c) {
     auto z = insert(\{m, c, \emptyset\}), y = z++, x = y;
     while (isect(y, z)) z = erase(z);
     if (x != begin() && isect(--x, y))
       isect(x, y = erase(y));
     while ((y = x) != begin() && (--x)->p >= y->p)
        isect(x, erase(y));
   lli query(lli x) {
     if (empty()) return OLL;
     auto f = *lower_bound(x);
     return f(x);
   }
 };
       Divide and conquer \mathcal{O}(kn^2) \Rightarrow \mathcal{O}(k \cdot nlogn)
6.6
Split the array of size n into k continuous groups. k \leq n
cost(a, c) + cost(b, d) \le cost(a, d) + cost(b, c) with a \le b \le c \le d
 void dc(int cut, int 1, int r, int optl, int optr) {
   if (r < 1)
     return;
   int mid = (1 + r) / 2;
   pair<lli, int> best = {inf, -1};
   fore (p, optl, min(mid, optr) + 1) {
     11i nxt = dp[\sim cut \& 1][p - 1] + cost(p, mid);
     if (nxt < best.f)</pre>
       best = {nxt, p};
   dp[cut & 1][mid] = best.f;
   int opt = best.s;
   dc(cut, 1, mid - 1, optl, opt);
   dc(cut, mid + 1, r, opt, optr);
 fore (i, 1, n + 1)
   dp[1][i] = cost(1, i);
 fore (cut, 2, k + 1)
   dc(cut, cut, n, cut, n);
```

### Knuth optimization $\mathcal{O}(n^3) \Rightarrow \mathcal{O}(n^2)$

```
dp[l][r] = \min_{l \le k \le r} \{dp[l][k] + dp[k][r]\} + cost(l, r)
 fore (len, 1, n + 1)
   fore (1, 0, n) {
      int r = 1 + len - 1;
      if (r > n - 1)
        break;
      if (len <= 2) {
        dp[1][r] = 0;
        opt[1][r] = 1;
        continue;
      dp[1][r] = inf;
      fore (k, opt[l][r - 1], opt[l + 1][r] + 1) {
        11i cur = dp[1][k] + dp[k][r] + cost(1, r);
        \quad \textbf{if} \ (\texttt{cur} < \texttt{dp[l][r]}) \ \{
          dp[1][r] = cur;
          opt[1][r] = k;
        }
     }
   }
```

# Game Theory

#### 7.1 **Grundy Numbers**

If the moves are consecutive  $S = \{1, 2, 3, ..., x\}$  the game can be solved like  $stackSize \pmod{x+1} \neq 0$ 

```
int mem[N];
int mex(set<int> &st) {
  int x = 0;
  while (st.count(x))
    x++:
  return x;
int grundy(int n) {
  if (n < 0)
    return inf;
  if (n == 0)
    return 0;
  int &g = mem[n];
  if (g == -1) {
    set<int> st;
    for (int x : {a, b})
      st.insert(grundy(n - x));
    g = mex(st);
  return g;
}
```

### Combinatorics

	Combinatorics	table
Number	Factorial	Catalan
0	1	1
1	1	1
2	2	2
3	6	5
4	24	14
5	120	42
6	720	132
7	5,040	429
8	40,320	1,430
9	362,880	4,862
10	3,628,800	16,796
11	39,916,800	58,786
12	479,001,600	208,012
13	6,227,020,800	742,900

#### 8.1 Factorial

```
fac[0] = 1LL;
fore (i, 1, N)
  fac[i] = 11i(i) * fac[i - 1] % mod;
ifac[N - 1] = fpow(fac[N - 1], mod - 2);
fore (i, N - 1, 0)
  ifac[i] = lli(i + 1) * ifac[i + 1] % mod;
```

### Factorial mod smallPrime

```
lli facMod(lli n, int p) {
  11i r = 1LL;
  for (; n > 1; n /= p) {
    r = (r * ((n / p) % 2 ? p - 1: 1)) % p;
    fore (i, 2, n % p + 1)
      r = r * i % p;
  return r % p;
}
```

### Lucas theorem

Changes  $\binom{n}{k}$  mod p, with  $n \geq 2e6, k \geq 2e6$  and  $p \leq 1e7$ 

### Stars and bars

Enclosing n objects in k boxes

$$\binom{n+k-1}{k-1} = \binom{n+k-1}{n}$$

### 8.5 N choose K

$$\binom{n}{k} = \binom{n-1}{k-1} + \binom{n-1}{k}$$
 
$$\binom{n}{k_1, k_2, ..., k_m} = \frac{n!}{k_1! * k_2! * ... * k_m!}$$
 lli choose(int n, int k) { if  $(n < 0 \mid \mid k < 0 \mid \mid n < k)$  return OLL; return fac[n] \* ifac[k] % mod \* ifac[n - k] % mod; }

}

### 8.7 Burnside's lemma

$$|classes| = \frac{1}{|G|} \cdot \sum_{x \in G} f(x)$$

### 8.8 Prime factors of N!

```
vector< pair<lli, int> > factorialFactors(lli n) {
  vector< pair<lli, int> > fac;
  for (lli p : primes) {
    if (n < p)
       break;
    lli mul = 1LL, k = 0;
    while (mul <= n / p) {
       mul *= p;
       k += n / mul;
    }
    fac.emplace_back(p, k);
}
return fac;
}</pre>
```

# 9 Number Theory

### 9.1 Goldbach conjecture

- All number  $\geq 6$  can be written as sum of 3 primes
- All even number > 2 can be written as sum of 2 primes

### 9.2 Prime numbers distribution

Amount of primes approximately  $\frac{n}{\ln(n)}$ 

### 9.3 Sieve of Eratosthenes

To factorize divide x by factor[x] until is equal to 1

```
void factorizeSieve() {
  iota(factor, factor + N, 0);
  for (int i = 2; i * i < N; i++) if (factor[i] == i)
    for (int j = i * i; j < N; j += i)
      factor[j] = i;
}
Use it if you need a huge amount of phi[x] up to some N
void phiSieve() {
  isPrime.set(); // bitset<N> is faster
  iota(phi, phi + N, 0);
  fore (i, 2, N) if (isPrime[i])
    for (int j = i; j < N; j += i) {
      isPrime[j] = (i == j);
}</pre>
```

### 9.4 Phi of euler

phi[j] /= i; phi[j] \*= i - 1;

```
1li phi(lli n) {
  if (n == 1)
    return 0;
  lli r = n;
```

}

```
if (n % i == 0) {
       while (n % i == ∅)
         n \neq i;
       r -= r / i;
     }
   if (n > 1)
     r = r / n;
   return r;
9.5
      Miller-Rabin
 bool miller(lli n) {
   if (n < 2 || n % 6 % 4 != 1)
     return (n | 1) == 3;
   int k = __builtin_ctzll(n - 1);
   11i d = n >> k;
   auto compo = [&](lli p) {
     11i x = fpow(p % n, d, n), i = k;
     while (x != 1 && x != n - 1 && p % n && i--)
       x = mul(x, x, n);
     return x != n - 1 && i != k;
   };
   for (11i p: {2, 3, 5, 7, 11, 13, 17, 19, 23, 29, 31
       , 37}) {
     if (compo(p))
       return 0;
     if (compo(2 + rng() % (n - 3)))
       return 0:
   return 1;
 }
     Pollard-Rho
9.6
 lli rho(lli n) {
   while (1) {
     11i x = 2 + rng() \% (n - 3), c = 1 + rng() \% 20;
     auto f = [\&](11i \ x) \{ return (mul(x, x, n) + c) \% \}
         n; };
     11i y = f(x), g;
     while ((g = \_gcd(n + y - x, n)) == 1)
       x = f(x), y = f(f(y));
     if (g != n) return g;
   }
   return -1;
 }
 void pollard(lli n, map<lli, int> &fac) {
   if (n == 1) return;
   if (n % 2 == 0) {
     fac[2]++;
     pollard(n / 2, fac);
     return;
   }
   if (miller(n)) {
     fac[n]++;
     return;
   11i x = rho(n);
   pollard(x, fac);
   pollard(n / x, fac);
 }
9.7
      Amount of divisors
 1li divs(lli n) {
   11i cnt = 1LL;
   for (lli p : primes) {
     if (p * p * p > n)
       break;
     if (n % p == 0) {
       11i k = 0;
```

for (11i i = 2; i \* i <= n; i++)

```
while (n > 1 \&\& n \% p == 0)
     n /= p, ++k;
    cnt *= (k + 1);
 }
}
11i sq = mysqrt(n); // A binary search, the last x *
if (miller(n))
 cnt *= 2;
else if (sq * sq == n && miller(sq))
 cnt *= 3;
else if (n > 1)
 cnt *= 4;
return cnt;
```

### Bézout's identity

```
a_1 * x_1 + a_2 * x_2 + \dots + a_n * x_n = g
 g = \gcd(a_1, a_2, ..., a_n)
```

#### 9.9GCD

}

 $a \le b$ ; gcd(a+k, b+k) = gcd(b-a, a+k)

### 9.10 LCM

```
x = p * lcm(a_1, a_2, ..., a_k) + q, 0 \le q \le lcm(a_1, a_2, ..., a_k)
 x \pmod{a_i} \equiv q \pmod{a_i} as a_i \mid lcm(a_1, a_2, ..., a_k)
```

### 9.11 Euclid

```
pair<lli, lli> euclid(lli a, lli b) {
  if (b == 0)
   return {1, 0};
  auto p = euclid(b, a % b);
  return {p.s, p.f - a / b * p.s};
```

### 9.12 Chinese remainder theorem

```
pair<lli, lli> crt(pair<lli, lli> a, pair<lli, lli> b)
     {
  if (a.s < b.s)
    swap(a, b);
  auto p = euclid(a.s, b.s);
  111i g = a.s * p.f + b.s * p.s, l = a.s / g * b.s;
  if ((b.f - a.f) % g != 0)
    return {-1, -1}; // no solution
 p.f = a.f + (b.f - a.f) % b.s * p.f % b.s / g * a.s;
  return {p.f + (p.f < 0) * 1, 1};</pre>
```

#### Math 10

### 10.1 Progressions

### Arithmetic progressions

$$a_n = a_1 + (n-1) * diff$$
  
$$\sum_{i=1}^{n} a_i = n * \frac{a_1 + a_n}{2}$$

### Geometric progressions

$$a_n = a_1 * r^{n-1}$$

$$\sum_{k=1}^n a_1 * r^k = a_1 * \left(\frac{r^{n+1} - 1}{r - 1}\right) : r \neq 1$$

### 10.2 Fpow

```
lli fpow(lli x, lli y, lli mod) {
  lli r = 1;
  for (; y > 0; y >>= 1) {
    if (y & 1) r = mul(r, x, mod);
    x = mul(x, x, mod);
  }
  return r;
}
```

### 10.3 Fibonacci

$$\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}^n = \begin{bmatrix} fib_{n+1} & fib_n \\ fib_n & fib_{n-1} \end{bmatrix}$$

#### Bit tricks 11

Operations on int	Function		
x & -x	Least significant bit in $x$		
lg(x)	Most significant bit in $x$		
c = x&-x, r = x+c;	Next number after $x$ with same		
(((r^x) » 2)/c)   r	number of bits set		
builtin_	Function		
popcount(x)	Amount of 1's in $x$		
clz(x)	0's to the <b>left</b> of biggest bit		
ctz(x)	0's to the <b>right</b> of smallest bit		

#### 11.1Bitset

Bitset <size></size>			
Operation	Function		
_Find_first()	Least significant bit		
_Find_next(idx)	First set bit after index $idx$		
any(), none(), all()	Just what the expression says		
set(), reset(), flip()	Just what the expression says x2		
to_string('.', 'A')	Print 011010 like .AA.A.		

#### 11.2Geometry

```
const ld eps = 1e-9;
#define eq(a, b) (abs((a) - (b)) \leftarrow +eps)
#define neq(a, b) (!eq(a, b))
#define geq(a, b) ((a) - (b) >= -eps)
#define leq(a, b) ((a) - (b) <= +eps)
#define ge(a, b) ((a) - (b) > +eps)
#define le(a, b) ((a) - (b) < -eps)
enum {ON = -1, OUT, IN, OVERLAP, INF};
```

#### 12 Points

### 12.1

```
Points
int sgn(ld a) { return (a > eps) - (a < -eps); }</pre>
struct Pt {
  ld x, y;
  explicit Pt(ld x = 0, ld y = 0) : x(x), y(y) {}
  Pt operator + (Pt p) const { return Pt(x + p.x, y +
      p.y); }
  Pt operator - (Pt p) const { return Pt(x - p.x, y -
      p.y); }
  Pt operator * (ld k) const { return Pt(x * k, y * k)
      ; }
  Pt operator / (ld k) const { return Pt(x / k, y / k)
      ; }
  ld dot(Pt p) const {
   // 0 if vectors are orthogonal
    // - if vectors are pointing in opposite
        directions
    // + if vectors are pointing in the same direction
    return x * p.x + y * p.y;
  ld cross(Pt p) const {
   // 0 if collinear
   // - if b is to the right of a
   // + if b is to the left of a
    // gives you 2 * area
    return x * p.y - y * p.x;
```

```
ld length() const { return sqrtl(norm()); }
   ld angle() const {
    1d ang = atan2(y, x);
    return ang + (ang < 0 ? 2 * acos(-1) : 0);</pre>
   Pt perp() const { return Pt(-y, x); }
   Pt unit() const { return (*this) / length(); }
   Pt rotate(ld angle) const {
     // counter-clockwise rotation in radians
     // degree = radian * 180 / pi
    return Pt(x * cos(angle) - y * sin(angle), x * sin
         (angle) + y * cos(angle));
   }
   int dir(Pt a, Pt b) const {
    return sgn((a - *this).cross(b - *this));
   int cuad() const {
    if (x > 0 \& y >= 0) return 0;
    if (x <= 0 && y > 0) return 1;
    if (x < 0 && y <= 0) return 2;
    if (x \ge 0 \& y < 0) return 3;
    return -1:
   }
12.2
       Angle between vectors
 double angleBetween(Pt a, Pt b) {
   double x = a.dot(b) / a.length() / b.length();
   return acosl(max(-1.0, min(1.0, x)));
12.3
        Closest pair of points
pair<Pt, Pt> closestPairOfPoints(Poly &pts) {
   sort(all(pts), [&](Pt a, Pt b) {
    return le(a.y, b.y);
   });
   set<Pt> st;
   ld ans = inf;
   Pt p, q;
   int pos = 0;
   fore (i, 0, sz(pts)) {
    while (pos < i && geq(pts[i].y - pts[pos].y, ans))</pre>
      st.erase(pts[pos++]);
    auto lo = st.lower_bound(Pt(pts[i].x - ans - eps,
         -inf));
    auto hi = st.upper_bound(Pt(pts[i].x + ans + eps,
         -inf));
     for (auto it = lo; it != hi; ++it) {
      ld d = (pts[i] - *it).length();
      if (le(d, ans))
        ans = d, p = pts[i], q = *it;
    }
    st.insert(pts[i]);
   }
   return {p, q};
12.4 Projection
ld proj(Pt a, Pt b) {
   return a.dot(b) / b.length();
12.5 KD-Tree
struct KDTree {
   // p.pos(0) = x, p.pos(1) = y, p.pos(2) = z
   #define iter Pt* // vector<Pt>::iterator
   KDTree *ls, *rs;
```

1d norm() const { return x \* x + y \* y; }

```
Pt p;
  ld val;
  int k;
  KDTree(iter b, iter e, int k = 0) : k(k), ls(0), rs(
      0) {
    int n = e - b;
    if (n == 1) {
      p = *b;
      return:
    nth_element(b, b + n / 2, e, [&](Pt a, Pt b) {
      return a.pos(k) < b.pos(k);</pre>
    });
    val = (b + n / 2) -> pos(k);
    ls = new KDTree(b, b + n / 2, (k + 1) % 2);
    rs = new KDTree(b + n / 2, e, (k + 1) % 2);
  pair<ld, Pt> nearest(Pt q) {
    if (!ls && !rs) // take care if is needed a
         different one
      return make_pair((p - q).norm(), p);
    pair<ld, Pt> best;
    if (q.pos(k) <= val) {
      best = ls->nearest(q);
      if (geq(q.pos(k) + sqrt(best.f), val))
        best = min(best, rs->nearest(q));
    } else {
      best = rs->nearest(q);
      if (leq(q.pos(k) - sqrt(best.f), val))
        best = min(best, ls->nearest(q));
    return best;
  }
};
```

# 13 Lines and segments

### 13.1 Line

```
struct Line {
  Pt a, b, v;
  Line() {}
  Line(Pt a, Pt b) : a(a), b(b), v((b - a).unit()) {}
  bool contains(Pt p) {
    return eq((p - a).cross(v), 0);
  int intersects(Line 1) {
    if (eq(v.cross(l.v), 0))
      return eq((1.a - a).cross(v), 0) ? INF : 0;
    return 1;
  }
  int intersects(Seg s) {
    if (eq(v.cross(s.v), 0))
      return eq((s.a - a).cross(v), 0) ? INF : 0;
    return sgn(v.cross(s.a - a)) != sgn(v.cross(s.b -
        a));
  template <class Line>
  Pt intersection(Line 1) { // can be a segment too
    return a + v * ((1.a - a).cross(1.v) / v.cross(1.v
        ));
  Pt projection(Pt p) {
```

```
return a + v * proj(p - a, v);
                                                              int inside(Cir c) {
  }
                                                                ld l = c.r - r - (o - c.o).length();
                                                                return ge(1, 0) ? IN : eq(1, 0) ? ON : OVERLAP;
  Pt reflection(Pt p) {
    return a * 2 - p + v * 2 * proj(p - a, v);
   }
};
                                                              int outside(Cir c) {
                                                                ld l = (o - c.o).length() - r - c.r;
13.2
       Segment
                                                                return ge(1, 0) ? OUT : eq(1, 0) ? ON : OVERLAP;
 struct Seg {
  Pt a, b, v;
                                                              int contains(Pt p) {
   Seg() {}
                                                                ld 1 = (p - o).length() - r;
   Seg(Pt a, Pt b) : a(a), b(b), v(b - a) {}
                                                                return le(1, 0) ? IN : eq(1, 0) ? ON : OUT;
   bool contains(Pt p) {
     return eq(v.cross(p - a), 0) && leq((a - p).dot(b
                                                              Pt projection(Pt p) {
         - p), 0);
                                                                return o + (p - o).unit() * r;
   }
   int intersects(Seg s) {
                                                              vector<Pt> tangency(Pt p) {
     int t1 = sgn(v.cross(s.a - a)), t2 = sgn(v.cross(s
                                                                // point outside the circle
         .b - a));
                                                                Pt v = (p - o).unit() * r;
    if (t1 == t2)
                                                                1d d2 = (p - o).norm(), d = sqrt(d2);
       return t1 == 0 && (contains(s.a) || contains(s.b
                                                                if (leq(d, 0)) return {}; // on circle, no tangent
           ) || s.contains(a) || s.contains(b)) ? INF
                                                                Pt v1 = v * (r / d), v2 = v.perp() * (sqrt(d2 - r))
                                                                     * r) / d);
     return sgn(s.v.cross(a - s.a)) != sgn(s.v.cross(b
                                                                return \{o + v1 - v2, o + v1 + v2\};
         - s.a));
                                                              vector<Pt> intersection(Cir c) {
   template <class Seg>
                                                                ld d = (c.o - o).length();
   Pt intersection(Seg s) { // can be a line too
                                                                if (eq(d, 0) \mid\mid ge(d, r + c.r) \mid\mid le(d, abs(r - c.
     return a + v * ((s.a - a).cross(s.v) / v.cross(s.v
                                                                     r))) return {}; // circles don't intersect
                                                                Pt v = (c.o - o).unit();
  }
                                                                1d a = (r * r + d * d - c.r * c.r) / (2 * d);
};
                                                                Pt p = o + v * a;
                                                                if (eq(d, r + c.r) \mid\mid eq(d, abs(r - c.r))) return
13.3
       Distance point-line
                                                                     {p}; // circles touch at one point
ld distance(Pt p, Line 1) {
                                                                1d h = sqrt(r * r - a * a);
   Pt q = 1.projection(p);
                                                                Pt q = v.perp() * h;
   return (p - q).length();
                                                                return {p - q, p + q}; // circles intersects twice
}
13.4 Distance point-segment
                                                              template <class Line>
ld distance(Pt p, Seg s) {
                                                              vector<Pt> intersection(Line 1) {
   if (le((p - s.a).dot(s.b - s.a), 0))
                                                                \ensuremath{//} for a segment you need to check that the point
    return (p - s.a).length();
                                                                    lies on the segment
   if (le((p - s.b).dot(s.a - s.b), 0))
                                                                1d h2 = r * r - 1.v.cross(o - 1.a) * 1.v.cross(o -
     return (p - s.b).length();
                                                                     1.a) / 1.v.norm();
   return abs((s.a - p).cross(s.b - p) / (s.b - s.a).
                                                                Pt p = 1.a + 1.v * 1.v.dot(o - 1.a) / 1.v.norm();
       length());
                                                                if (eq(h2, 0)) return {p}; // line tangent to
                                                                if (le(h2, 0)) return {}; // no intersection
13.5
       Distance segment-segment
                                                                Pt q = 1.v.unit() * sqrt(h_2);
ld distance(Seg a, Seg b) {
                                                                return {p - q, p + q}; // two points of
   if (a.intersects(b))
                                                                     intersection (chord)
     return 0.L;
   return min({distance(a.a, b), distance(a.b, b),
       distance(b.a, a), distance(b.b, a)});
                                                              Cir(Pt a, Pt b, Pt c) {
}
                                                                // find circle that passes through points a, b, c
                                                                Pt mab = (a + b) / 2, mcb = (b + c) / 2;
       Circles
14
                                                                Seg ab(mab, mab + (b - a).perp());
14.1 Circle
                                                                Seg cb(mcb, mcb + (b - c).perp());
                                                                o = ab.intersection(cb);
struct Cir {
                                                                r = (o - a).length();
   Pt o;
  ld r;
   Cir() {}
```

 $Cir(1d x, 1d y, 1d r) : o(x, y), r(r) {}$ 

Cir(Pt o, ld r) : o(o), r(r) {}

ld commonArea(Cir c) {

**if** (le(r, c.r))

```
return c.commonArea(*this);
                                                              return abs(sum / 2);
                                                           }
    1d d = (o - c.o).length();
     if (leq(d + c.r, r)) return c.r * c.r * pi;
                                                                   Convex-Hull
                                                           15.2
    if (geq(d, r + c.r)) return 0.0;
                                                           Poly convexHull(Poly pts) {
    auto angle = [&](ld a, ld b, ld c) {
      return acos((a * a + b * b - c * c) / (2 * a * b
                                                              Poly low, up;
                                                              sort(all(pts), [&](Pt a, Pt b) {
                                                                return a.x == b.x ? a.y < b.y : a.x < b.x;
    };
    auto cut = [&](ld a, ld r) {
      return (a - sin(a)) * r * r / 2;
                                                              pts.erase(unique(all(pts)), pts.end());
                                                              if (sz(pts) <= 2)
    1d a1 = angle(d, r, c.r), a2 = angle(d, c.r, r);
                                                                return pts;
                                                              fore (i, 0, sz(pts)) {
    return cut(a1 * 2, r) + cut(a2 * 2, c.r);
                                                                while(sz(low) \ge 2 \& (low.end()[-1] - low.end()[-
   }
                                                                    2]).cross(pts[i] - low.end()[-1]) <= 0)
};
                                                                  low.pop_back();
14.2
        Distance point-circle
                                                                low.pb(pts[i]);
ld distance(Pt p, Cir c) {
   return max(0.L, (p - c.o).length() - c.r);
                                                              fore (i, sz(pts), ∅) {
                                                                while(sz(up) \geq 2 \& (up.end()[-1] - up.end()[-2])
                                                                    .cross(pts[i] - up.end()[-1]) \le 0)
14.3
        Minimum enclosing circle
                                                                  up.pop_back();
 Cir minEnclosing(vector<Pt> &pts) { // a bunch of
                                                                up.pb(pts[i]);
     points
   shuffle(all(pts), rng);
                                                              low.pop_back(), up.pop_back();
   Cir c(0, 0, 0);
                                                              low.insert(low.end(), all(up));
   fore (i, 0, sz(pts)) if (c.contains(pts[i]) != OUT)
                                                              return low;
    c = Cir(pts[i], 0);
                                                          15.3
                                                                   Cut polygon by a line
     fore (j, 0, i) if (c.contains(pts[j]) != OUT) {
      c = Cir((pts[i] + pts[j]) / 2, (pts[i] - pts[j])
                                                            Poly cut(const Poly &pts, Line 1) {
           .length() / 2);
                                                              Poly ans;
      fore (k, 0, j) if (c.contains(pts[k]) != OUT)
                                                              int n = sz(pts);
        c = Cir(pts[i], pts[j], pts[k]);
                                                              fore (i, 0, n) {
    }
                                                                int j = (i + 1) \% n;
  }
                                                                if (geq(1.v.cross(pts[i] - 1.a), 0)) // left
   return c;
                                                                  ans.pb(pts[i]);
}
                                                                Seg s(pts[i], pts[j]);
                                                                if (l.intersects(s) == 1) {
14.4
        Common area circle-polygon
                                                                  Pt p = 1.intersection(s);
ld commonArea(const Cir &c, const Poly &poly) {
                                                                  if (p != pts[i] && p != pts[j])
   auto arg = [&](Pt p, Pt q) {
                                                                    ans.pb(p);
    return atan2(p.cross(q), p.dot(q));
                                                                }
   };
                                                              }
   auto tri = [&](Pt p, Pt q) {
                                                              return ans;
    Pt d = q - p;
    1d = d.dot(p) / d.norm(), b = (p.norm() - c.r *
         c.r) / d.norm();
                                                                  Perimeter
                                                           15.4
    1d det = a * a - b;
                                                            ld perimeter(const Poly &pts){
    if (leq(det, 0)) return arg(p, q) * c.r * c.r;
                                                              1d \text{ sum} = 0;
    1d s = max(0.L, -a - sqrt(det)), t = min(1.L, -a +
                                                              fore (i, ∅, sz(pts))
          sqrt(det));
                                                                sum += (pts[(i + 1) % sz(pts)] - pts[i]).length();
    if (t < 0 || 1 <= s) return arg(p, q) * c.r * c.r;</pre>
                                                              return sum;
    Pt u = p + d * s, v = p + d * t;
    return u.cross(v) + (arg(p, u) + arg(v, q)) * c.r
         * c.r:
                                                                   Point in polygon
                                                           15.5
   };
                                                            int contains(const Poly &pts, Pt p) {
   1d \text{ sum} = 0;
                                                              int rays = 0, n = sz(pts);
   fore (i, 0, sz(poly))
                                                              fore (i, 0, n) {
     sum += tri(poly[i] - c.o, poly[(i + \frac{1}{1}) % sz(poly)]
                                                                Pt a = pts[i], b = pts[(i + 1) % n];
          - c.o);
                                                                if (ge(a.y, b.y))
   return abs(sum / 2);
                                                                  swap(a, b);
}
                                                                if (Seg(a, b).contains(p))
                                                                  return ON;
                                                                rays ^= (leq(a.y, p.y) && le(p.y, b.y) && ge((a -
15
       Polygons
                                                                    p).cross(b - p), ∅));
       Area of polygon
                                                              }
ld area(const Poly &pts) {
                                                              return rays & 1 ? IN : OUT;
   1d \text{ sum} = 0;
                                                            }
   fore (i, 0, sz(pts))
                                                          15.6
                                                                   Point in convex-polygon
     sum += pts[i].cross(pts[(i + 1) % sz(pts)]);
```

```
bool contains(const Poly &a, Pt p) {
   int lo = 1, hi = sz(a) - 1;
   if (a[0].dir(a[lo], a[hi]) > 0)
     swap(lo, hi);
   if (p.dir(a[0], a[lo]) >= 0 || p.dir(a[0], a[hi]) <=</pre>
        0)
     return false;
   while (abs(lo - hi) > 1) {
     int mid = (lo + hi) >> 1;
     (p.dir(a[0], a[mid]) > 0 ? hi : lo) = mid;
   return p.dir(a[lo], a[hi]) < 0;</pre>
}
15.7
        Is convex
bool isConvex(const Poly &pts) {
   int n = sz(pts);
   bool pos = 0, neg = 0;
   fore (i, 0, n) {
     Pt a = pts[(i + 1) % n] - pts[i];
Pt b = pts[(i + 2) % n] - pts[(i + 1) % n];
     int dir = sgn(a.cross(b));
     if (dir > 0) pos = 1;
     if (dir < 0) neg = 1;
   }
  return !(pos && neg);
}
```

# 16 Geometry misc

### 16.1 Radial order

```
struct Radial {
  Pt c;
  Radial(Pt c) : c(c) {}

bool operator()(Pt a, Pt b) const {
  Pt p = a - c, q = b - c;
  if (p.cuad() == q.cuad())
      return p.y * q.x < p.x * q.y;
  return p.cuad() < q.cuad();
  }
};</pre>
```

### 16.2 Sort along a line

```
void sortAlongLine(vector<Pt> &pts, Line 1){
  sort(all(pts), [&](Pt a, Pt b){
    return a.dot(1.v) < b.dot(1.v);
  });
}</pre>
```