

# Titanic

How can deep learning on irregular domains help to save lives?

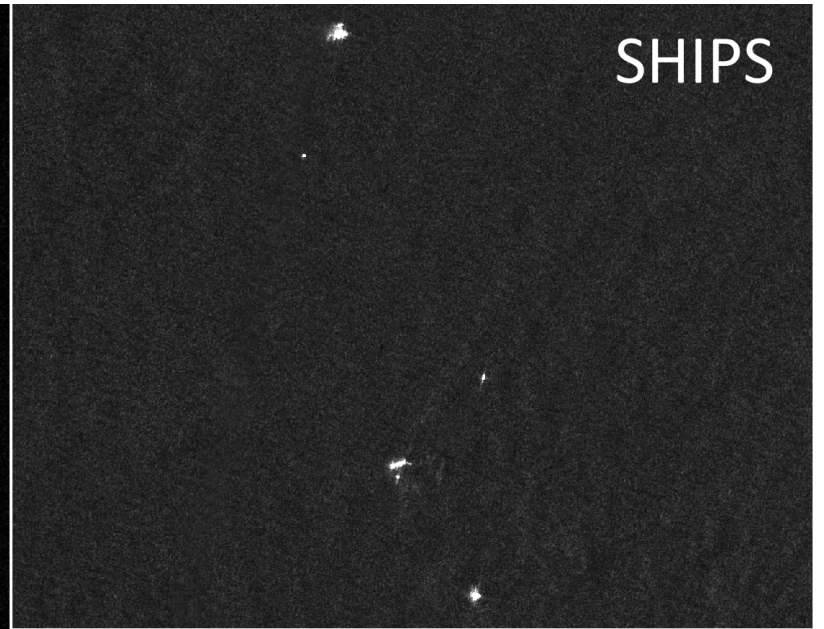
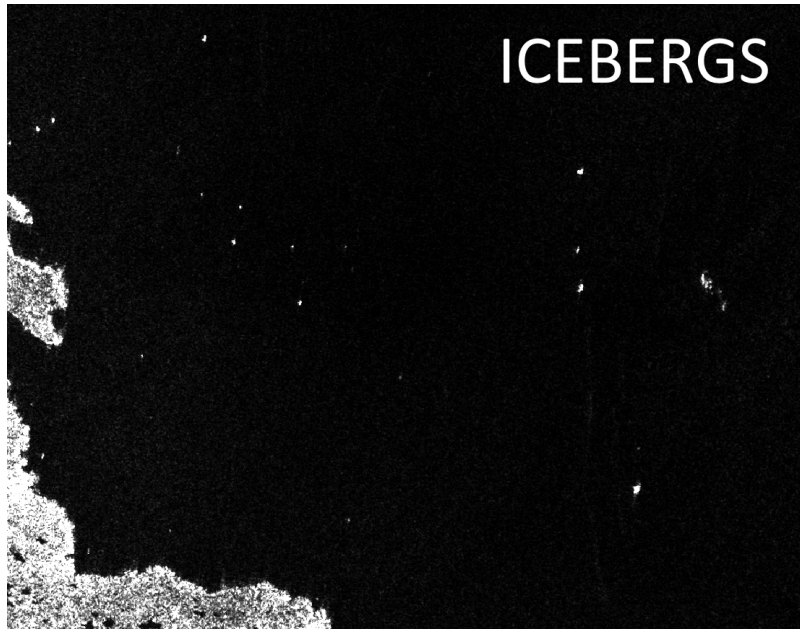
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# 1 - Introduction

© Statoil/C-CORE - Icebergs and ships examples



## 2 - Data source

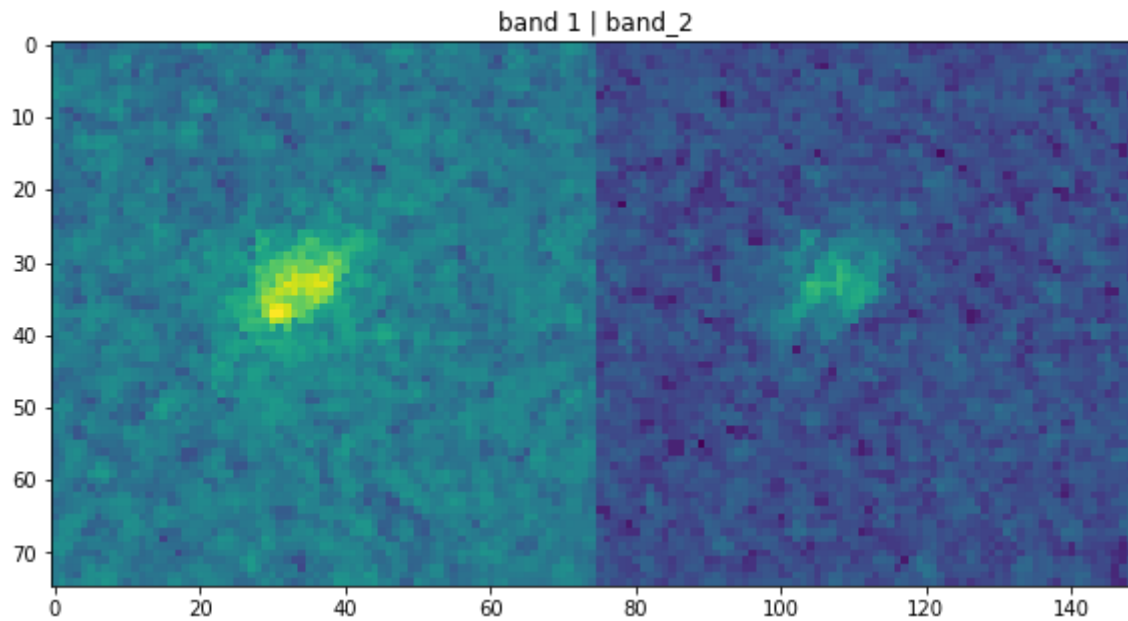
10 ' 028 iceberg or ship cases with only 1 ' 604 labelled

## Description

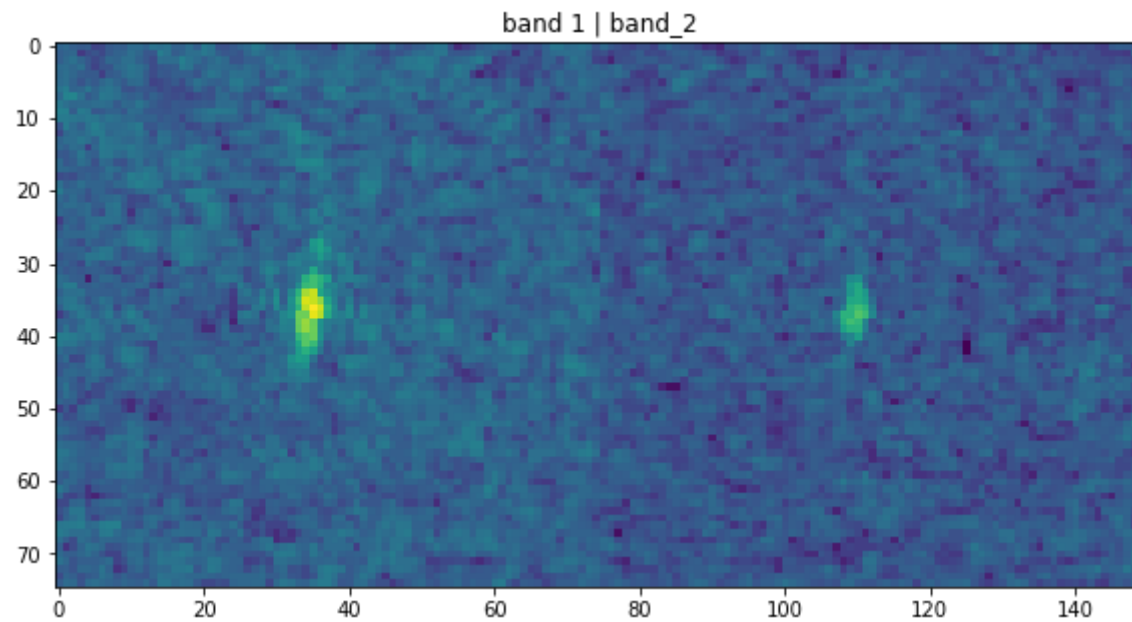
Feature	Description	Type	Has N/A	Comment
id	image identifier	String	No	
band_1	horizontal plane	Float array	No	HH
band_2	vertical plane	Float array	No	HV
inc_angle	measurement angle	Float	Yes (~10%)	Unit in degrees
is_iceberg	iceberg or not	Boolean (0/1)	No	Label

# Exploration

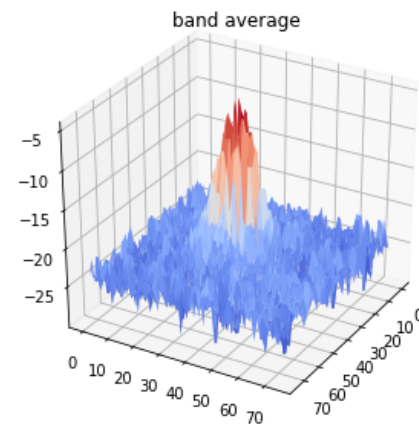
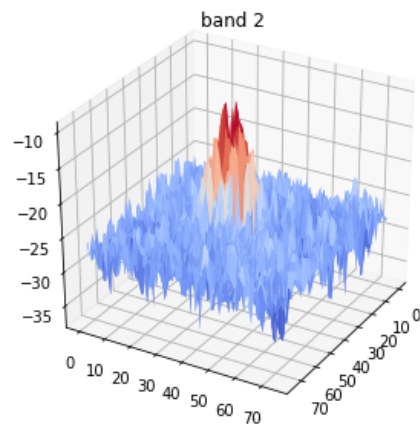
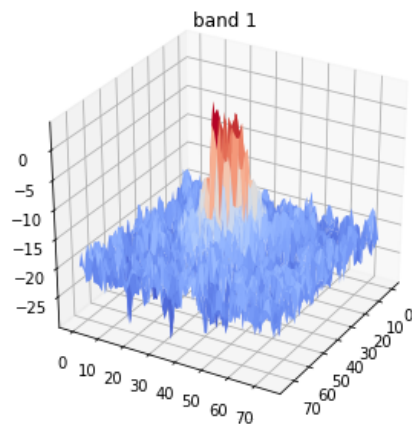
```
In [10]: viz.plot_bands(example_iceberg)
```



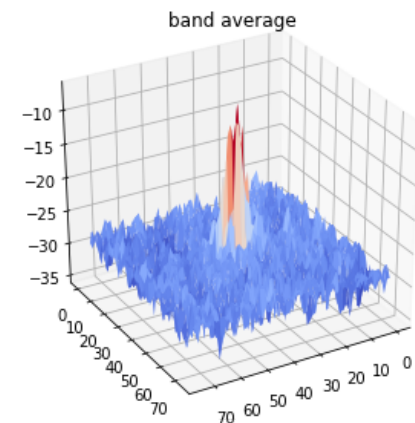
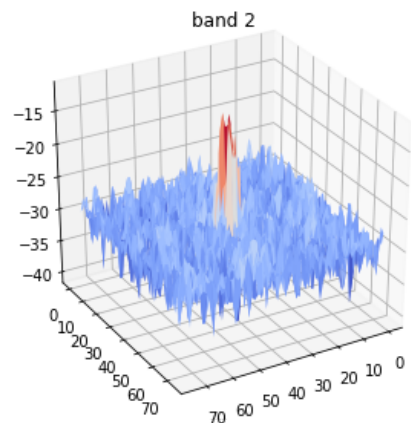
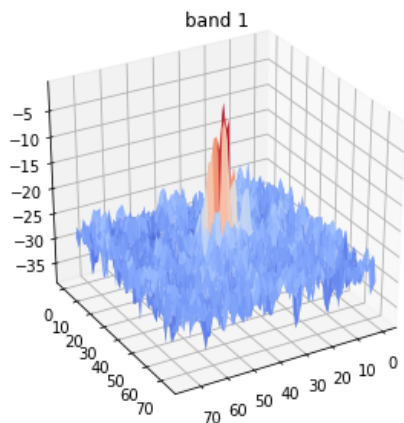
```
In [13]: viz.plot_bands(example_ship)
```



```
In [11]: viz.plot_bands_3d(example_iceberg)
```

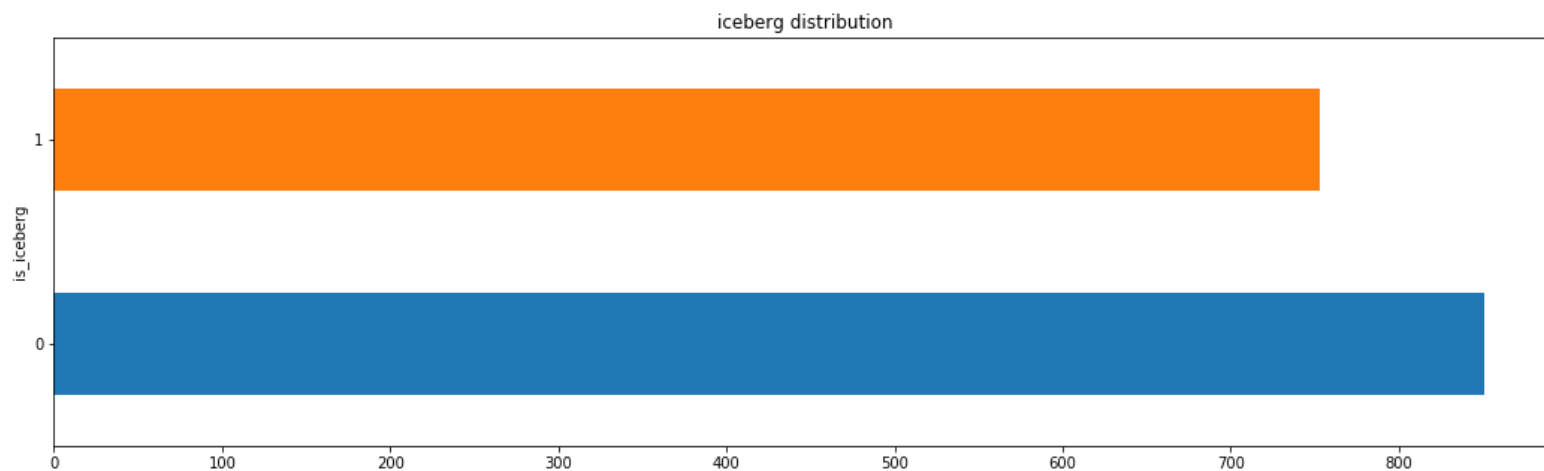


```
In [14]: viz.plot_bands_3d(example_ship, angle=60)
```

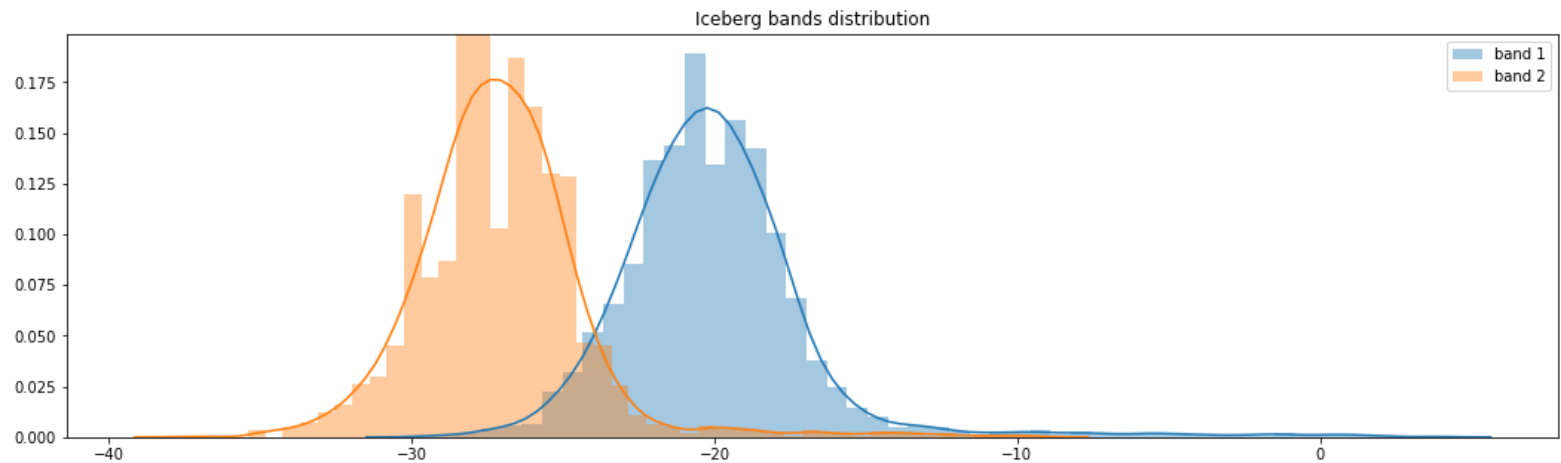




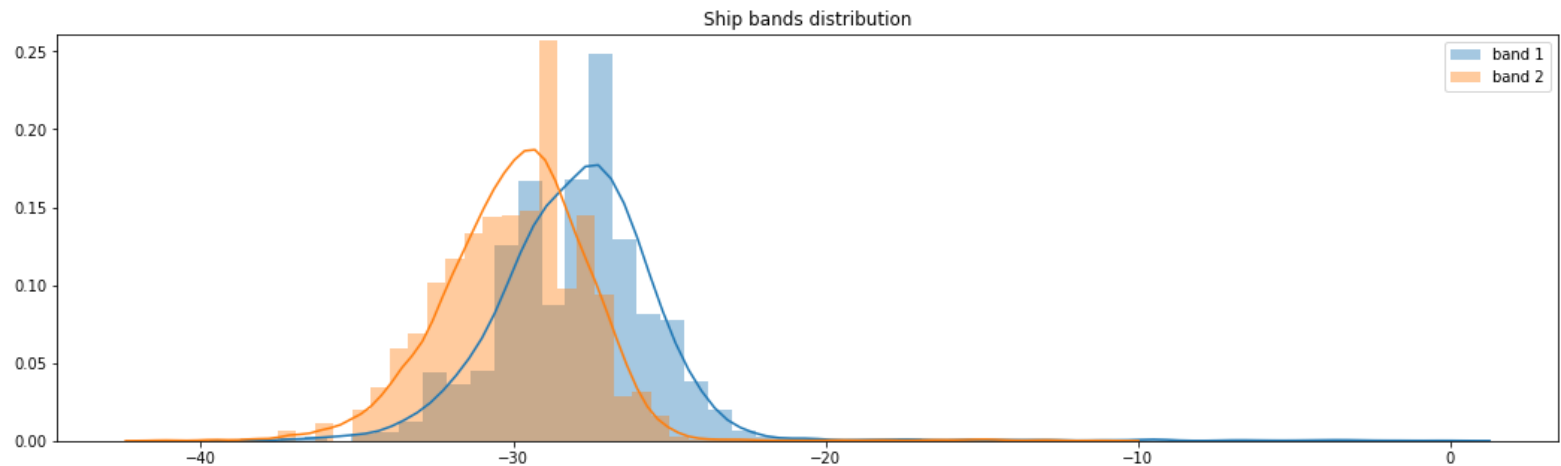
```
In [15]: plt.title('iceberg distribution')
measures.groupby(measures.is_iceberg).is_iceberg.count().plot.barh();
```



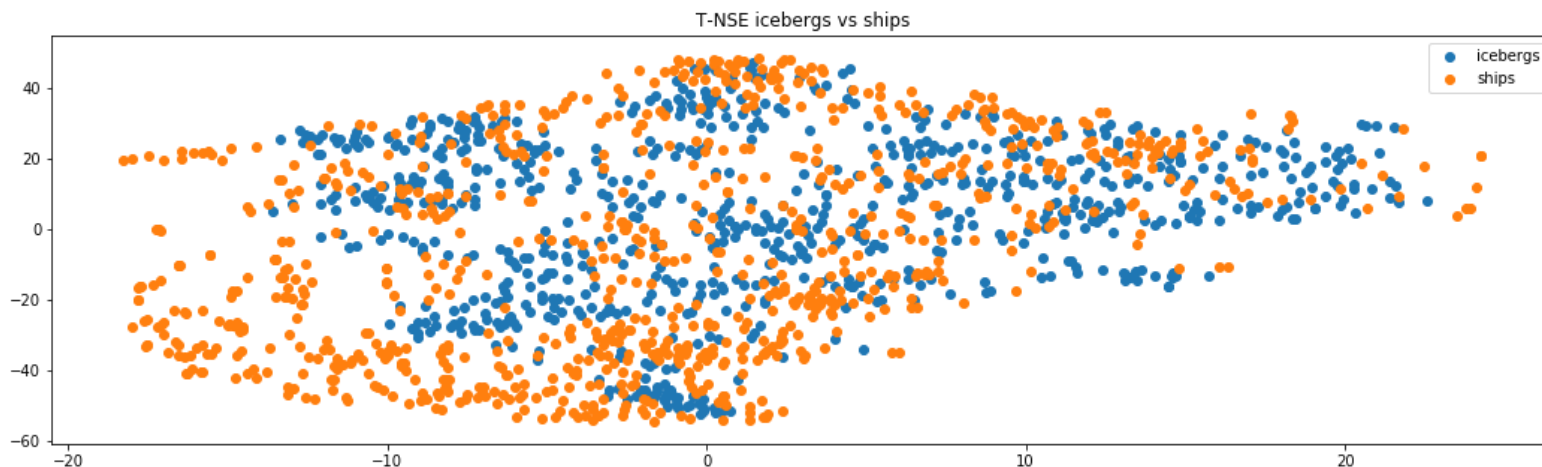
```
In [18]: plt.title('Iceberg bands distribution')
sns.distplot(example_iceberg.band_1, label='band 1')
sns.distplot(example_iceberg.band_2, label='band 2')
plt.legend();
```



```
In [19]: plt.title('Ship bands distribution')
sns.distplot(example_ship.band_1, label='band 1')
sns.distplot(example_ship.band_2, label='band 2')
plt.legend();
```

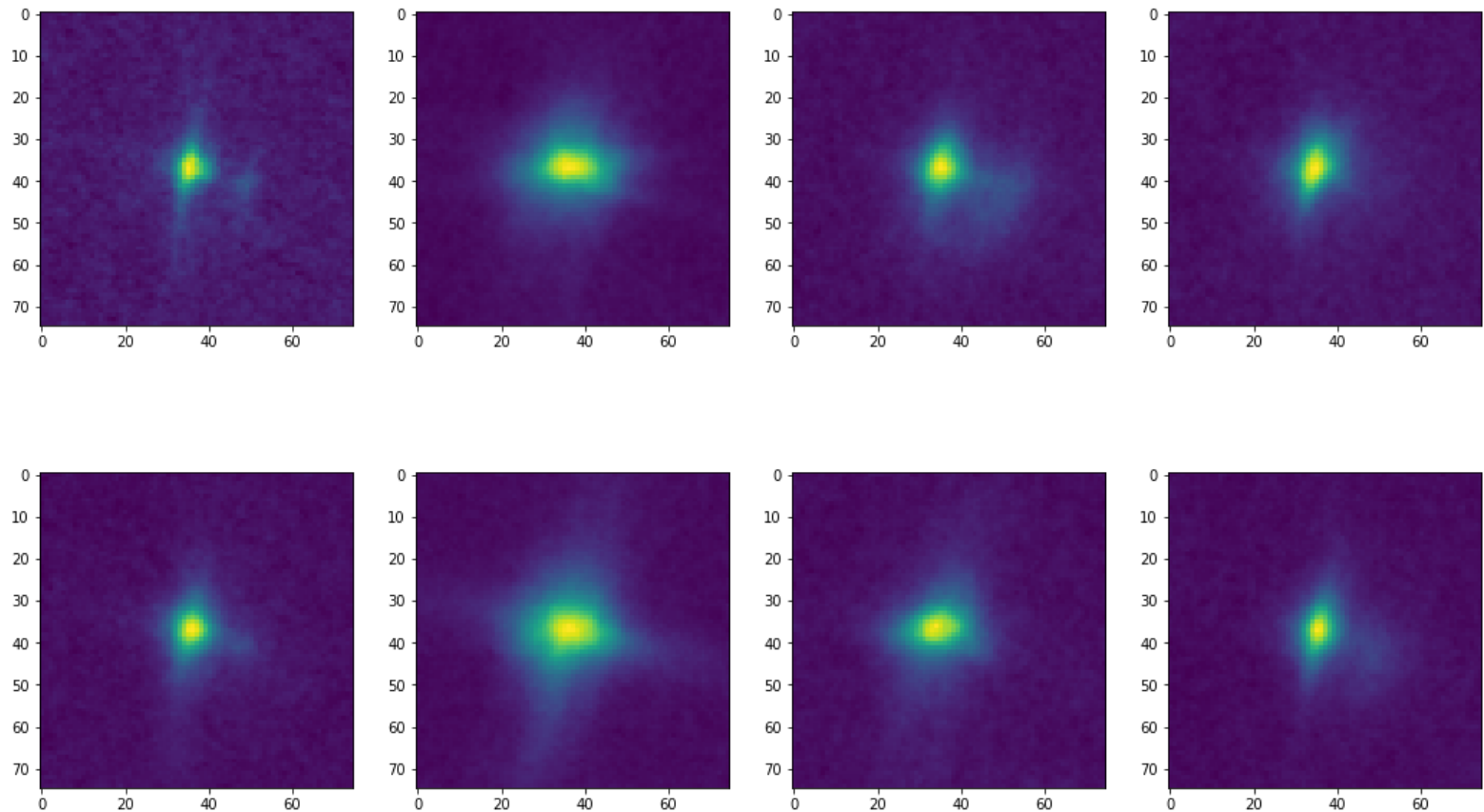


```
In [23]: plt.title('T-NSE icebergs vs ships')
plt.scatter(tsne[measures.is_iceberg == 1, 0], tsne[measures.is_iceberg == 1, 1],
            label='icebergs')
plt.scatter(tsne[measures.is_iceberg == 0, 0], tsne[measures.is_iceberg == 0, 1],
            label='ships')
plt.legend();
```



**Prototypes**

```
In [26]: for i, center in enumerate(kmeans_centers):  
        plt.subplot(1, 4, i % 4 + 1)  
        plt.imshow(center.reshape(75, 75))  
        if i % 4 == 3:  
            plt.show()
```



## 3 - Preprocessing

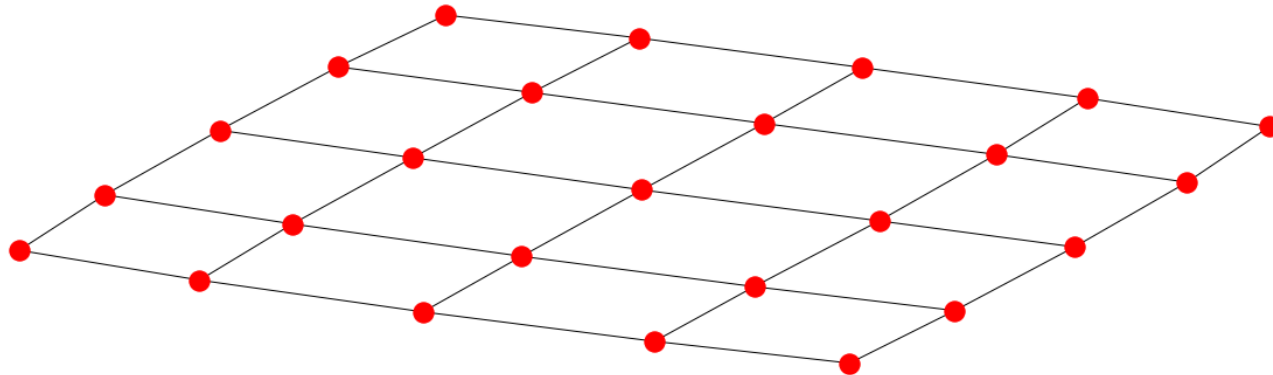
- No filtering
- No data augmentation
- Rescaling between 0 and 1
- Replacing missing angle by 0

## 4 - Graphs



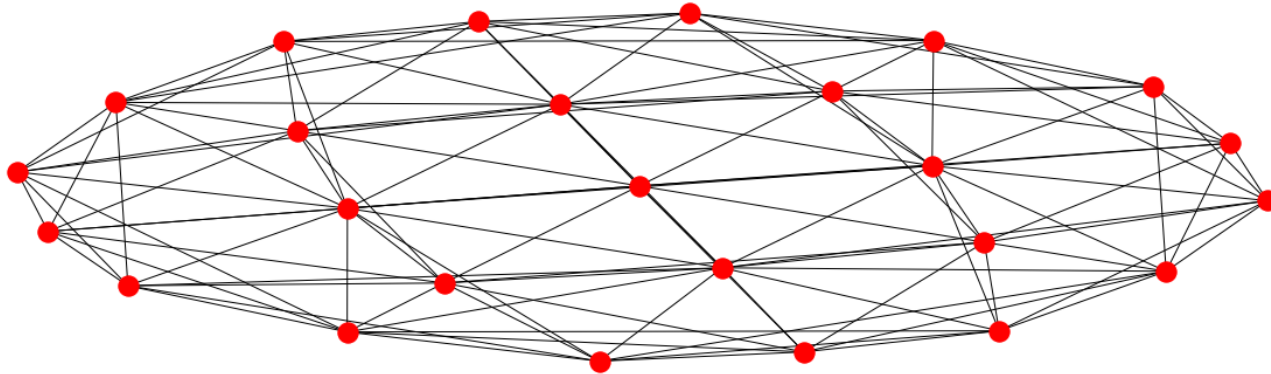
## Classical 2D grid

```
In [39]: small_grid = nx.grid_graph([5, 5])  
nx.draw(small_grid)
```



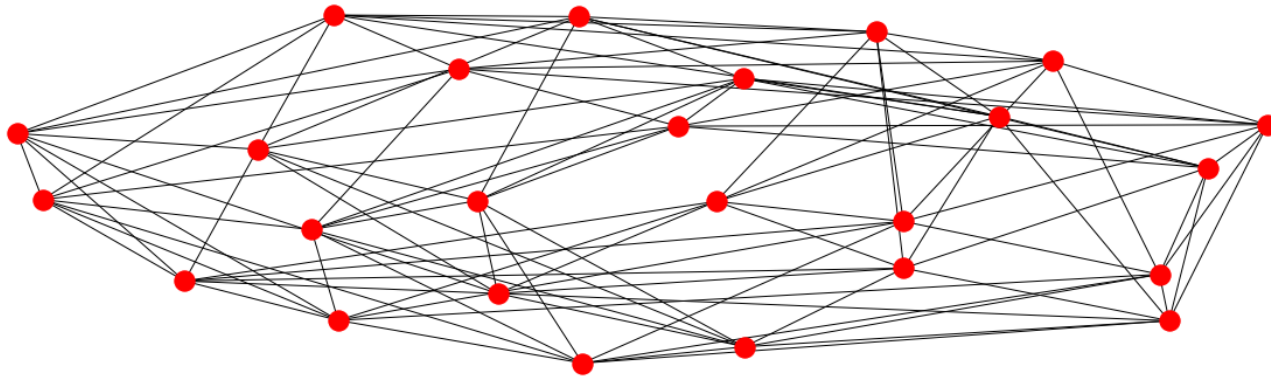
## Knn 2D grid

```
In [40]: small_knn = graph.knn(graph.grid_coordinates(5), k=8, metric='cityblock')  
         nx.draw(small_knn)
```



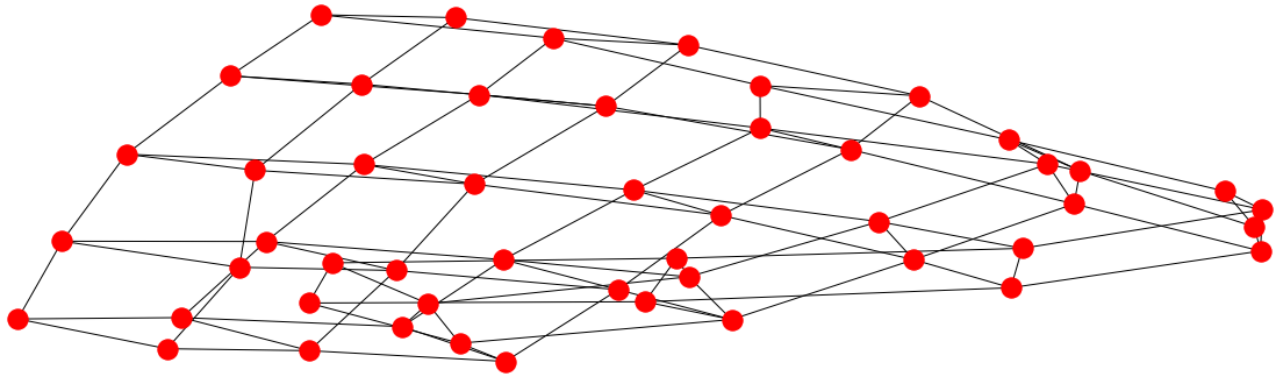
## Wrap-around Knn 2D grid

```
In [41]: small_wraps = graph.kwraps(5, kd=1)  
         nx.draw(small_wraps)
```



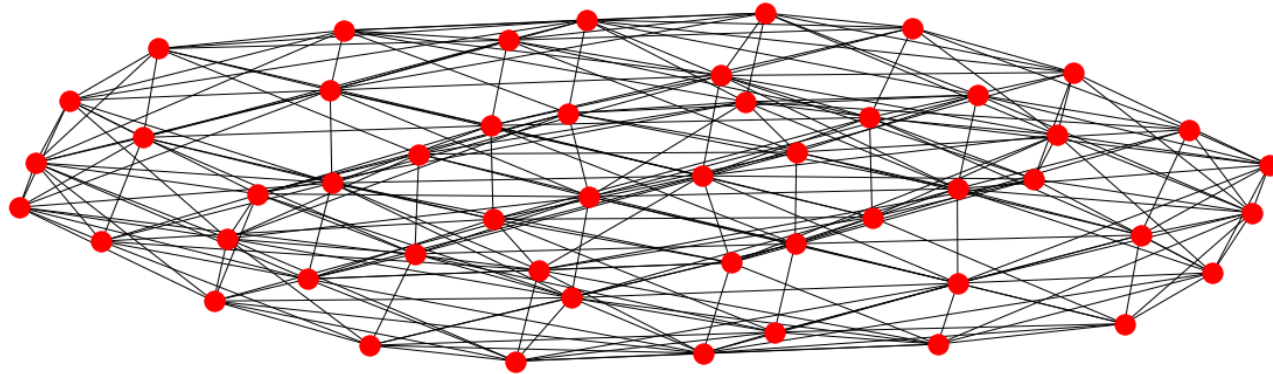
## Classical 3D grid

```
In [42]: small_grid3d = nx.grid_graph([5, 5, 2])  
nx.draw(small_grid3d)
```



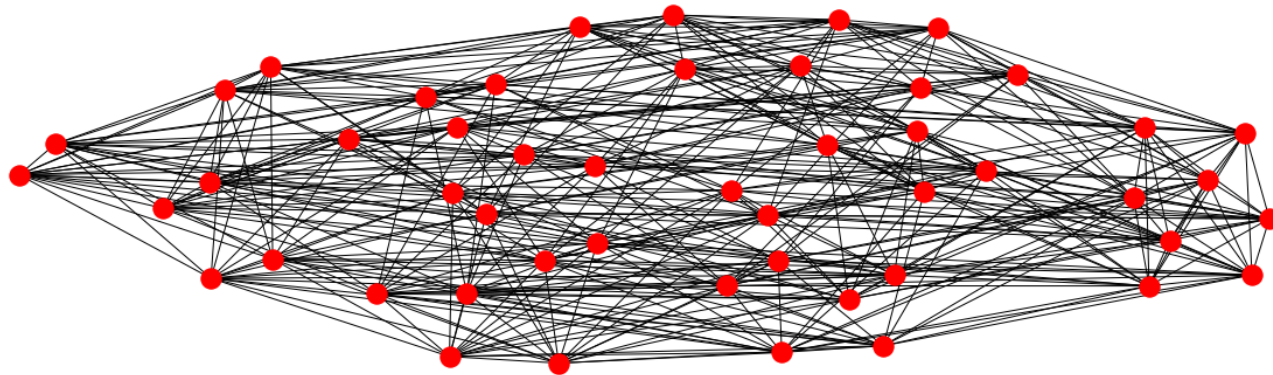
## Knn 3D grid

```
In [43]: small_knn3d = graph.knn3d(graph.grid_coordinates(5), k=8, metric='cityblock', d=2)  
         nx.draw(small_knn3d)
```



## 3D wrap-around grid

```
In [44]: small_wraps3d = graph.kwraps3d(5, kd=1, d=2)  
         nx.draw(small_wraps3d)
```

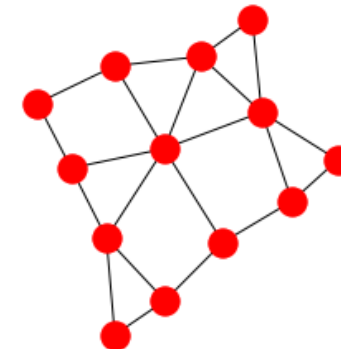
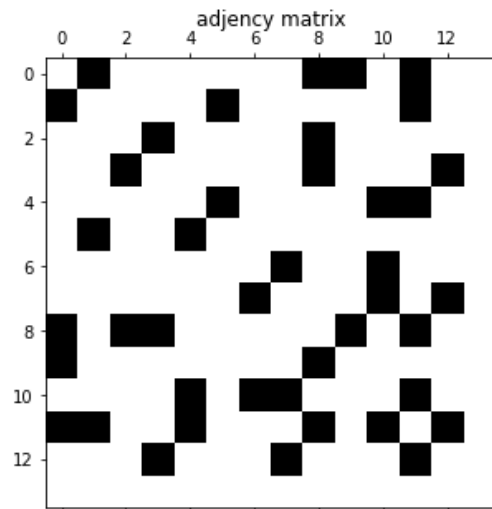
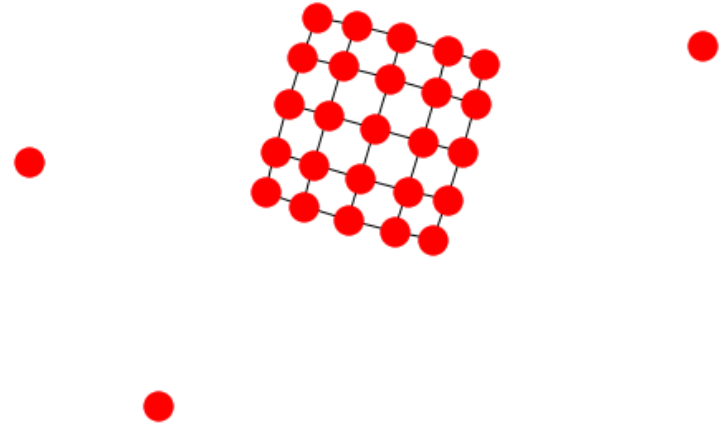
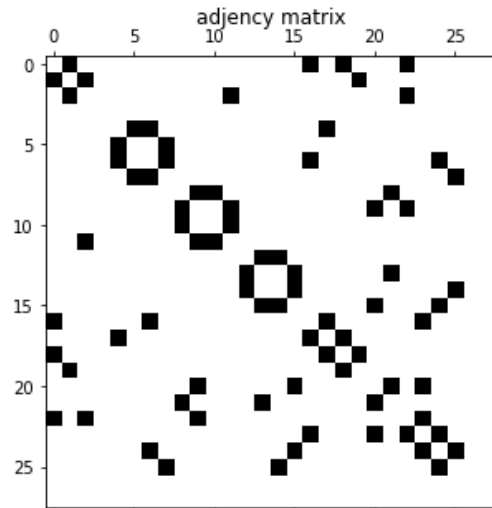


**Coarsening**

**Gracius**

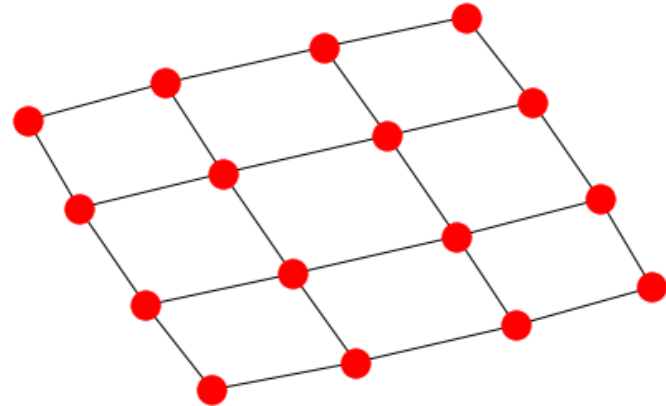
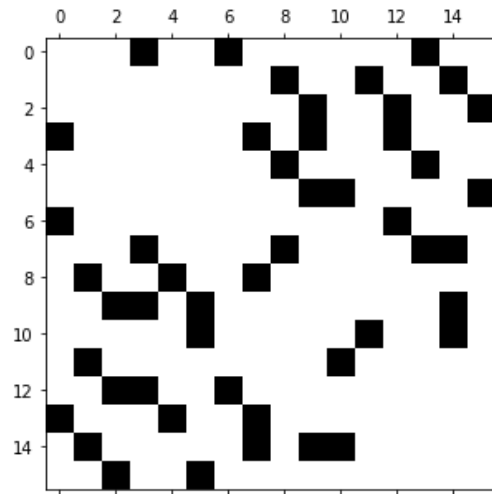


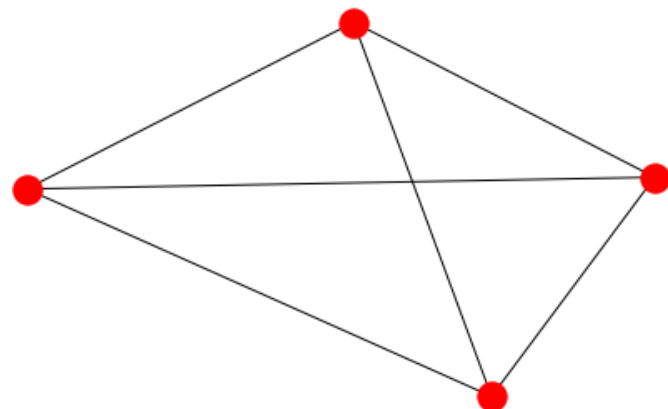
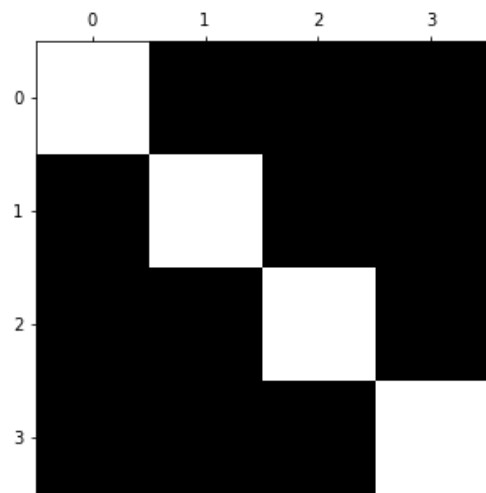
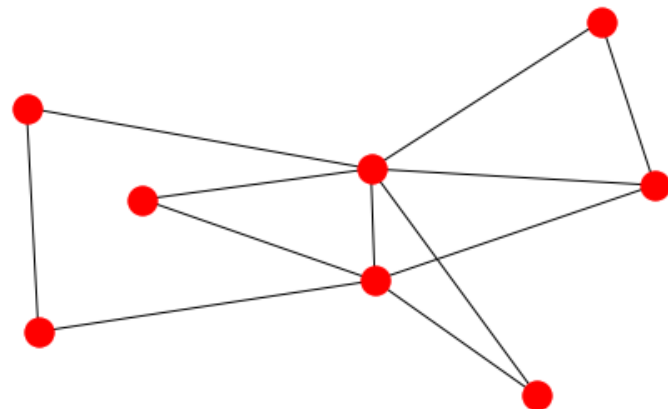
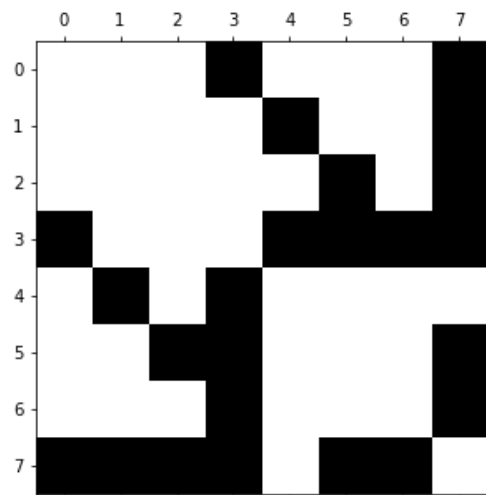
```
In [50]: viz.plot_graph_steps(graclus_levels)
```



## Algebraic multigrid

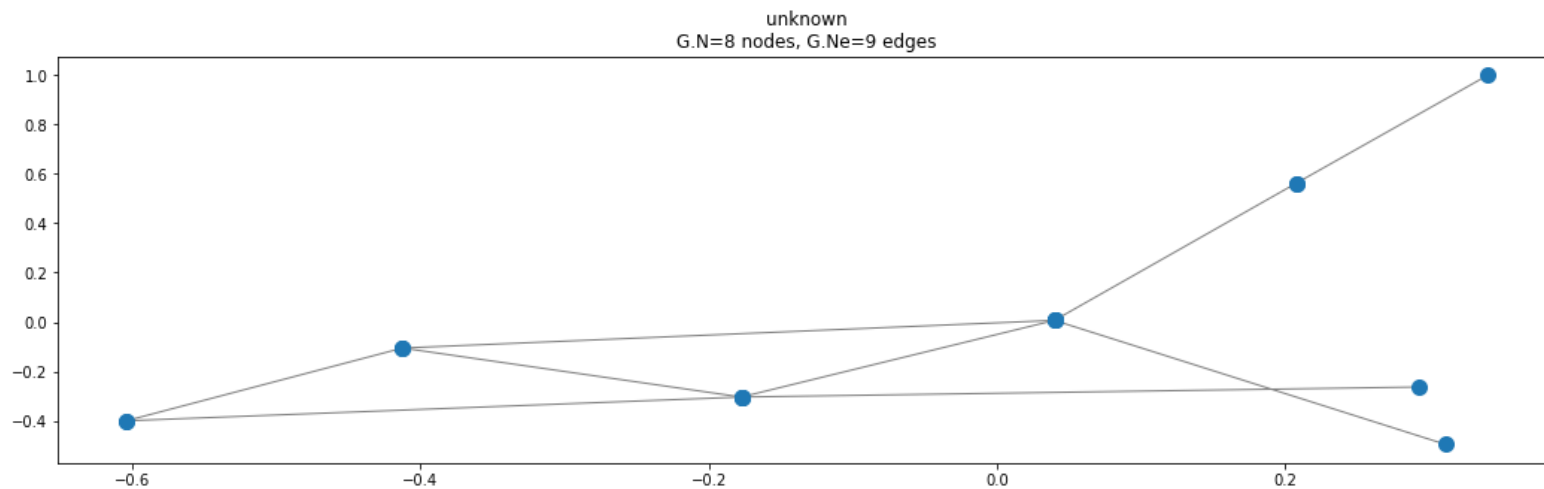
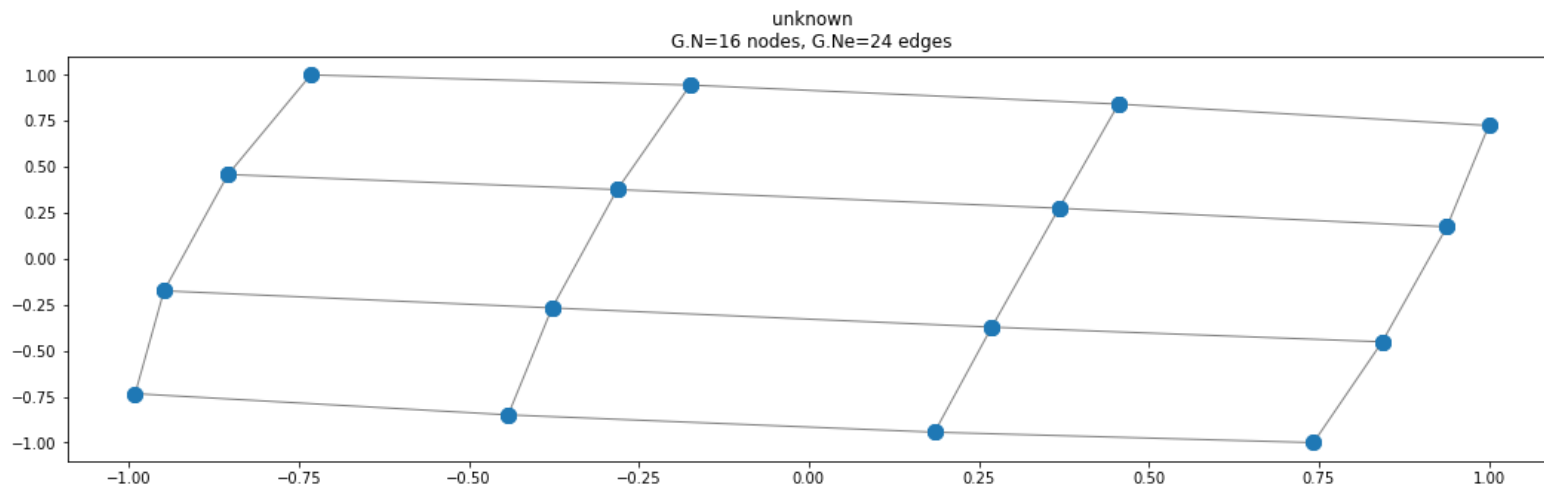
```
In [53]: for g in graphs:
          plt.subplot(121)
          plt.spy(g.todense())
          plt.subplot(122)
          nx.draw(nx.from_numpy_array(g.todense()))
          plt.show()
```





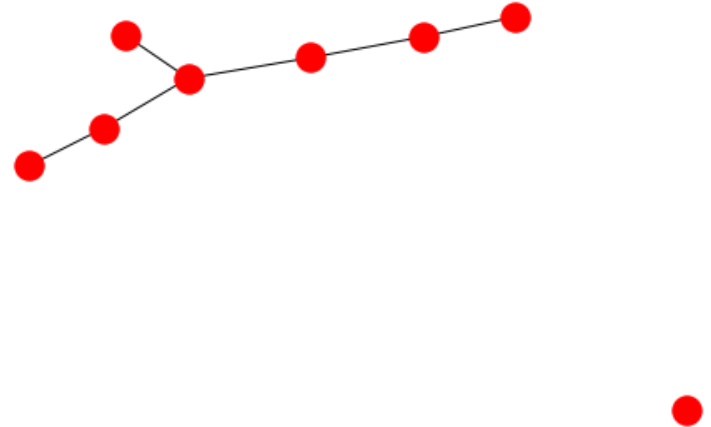
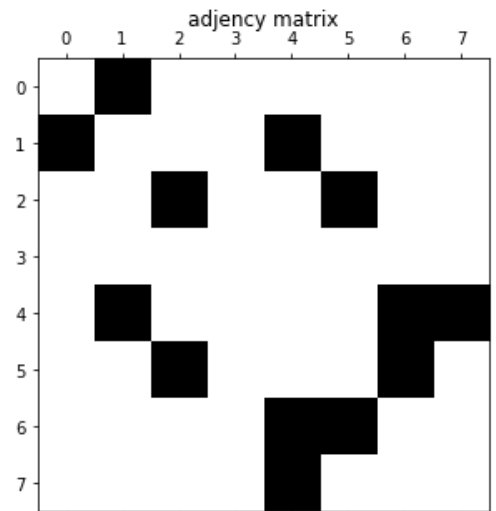
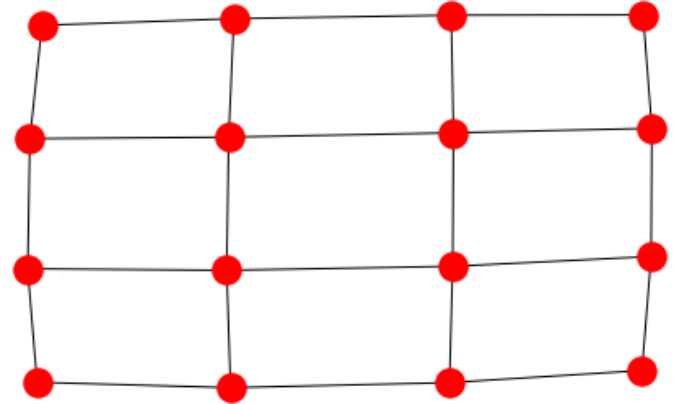
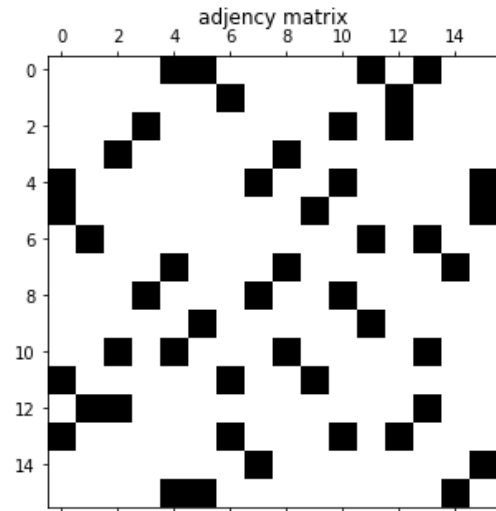
## Kron reduction

```
In [56]: for g in kron_levels:
          g.set_coordinates()
          g.plot()
```



## Maximum spanning tree

```
In [59]: viz.plot_graph_steps(mst_levels)
```





## 5 - Models

## Convolution baseline

Layer	Output shape	Input connected to
Convolution2d	16	Convolution2d_input
MaxPool2d	4	Convolution2d
Convolution2d	32	MaxPool2d
MaxPool2d	4	Convolution2d
Linear	256	MaxPool2d
Linear	128	Linear
Linear	1	Linear

## Graph convolution (Graclus)

Layer	Output shape	Input connected to
GraphFourierConv / GraphChebyshevConv	16	GraphFourierConv_input / GraphChebyshevConv_input
MaxPool2d	4	GraphFourierConv / GraphChebyshevConv
GraphFourierConv / GraphChebyshevConv	32	MaxPool2d
MaxPool2d	4	GraphFourierConv / GraphChebyshevConv
Linear	256	MaxPool2d
Linear	128	Linear
Linear	1	Linear

## 6 - Evaluation

In [99]:

```
scores
```

Out[99]:

	accuracy	precision	recall	f1
name				
baseline	0.502075	0.470085	0.486726	0.478261
knn	0.684647	0.645669	0.725664	0.683333
logistic	0.775934	0.725191	0.840708	0.778689
conv	0.854772	0.848214	0.840708	0.844444
gcnn_grid	0.788382	0.822917	0.699115	0.755981
gcnn_kwraps	0.780083	0.705479	0.911504	0.795367

## 7 - Conclusion

### Possible improvements

- sparse operations
- better and more detailed comparison
- speedup to improve both coarsening algorithms and training
- graph deconvolution and inspect what the filter actually does

## 8 - References

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- BRONSTEIN, Michael M., BRUNA, Joan, LECUN, Yann, et al. Geometric deep learning: going beyond euclidean data. IEEE Signal Processing Magazine, 2017, vol. 34, no 4, p. 18-42.
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- NGUYEN Ha Q., DO Minh N, et al. Downsampling of Signal on Graphs Via Maximum Spanning Trees. IEEE Transactions on Signal Processing, 2015, vol. 63, no 1.
- DORFLER Florain, BULLO Francesco. Kron reduction of graphs with applications to electrical networks. 2011.