Optimization: Bitmap Indexes

Knowledge objectives

- Justify the usefulness of a multi-attribute index
- 2. Explain what a bitmap index is
- 3. Justify the usefulness of a bitmap index
- 4. Explain how to find the record given a bitmap position based on the Hakan factor

Understanding Objectives

- Decide when a multi-attribute index can be used in the evaluation of a predicate
- 2. Give the approximate cost of a selection on a table with a bitmap index (without coding)
- 3. Encode a bitmap index using run-length
- 4. Evaluate a simple predicate (one logical operation) using run-length encoded bitmap
- Encode a bitmap index using bitmap-sliced technique
- 6. Evaluate a simple predicate (one logical operation) using bitmap-sliced technique

MULTI-ATTRIBUTE INDEXES

Usefulness of multi-attribute trees

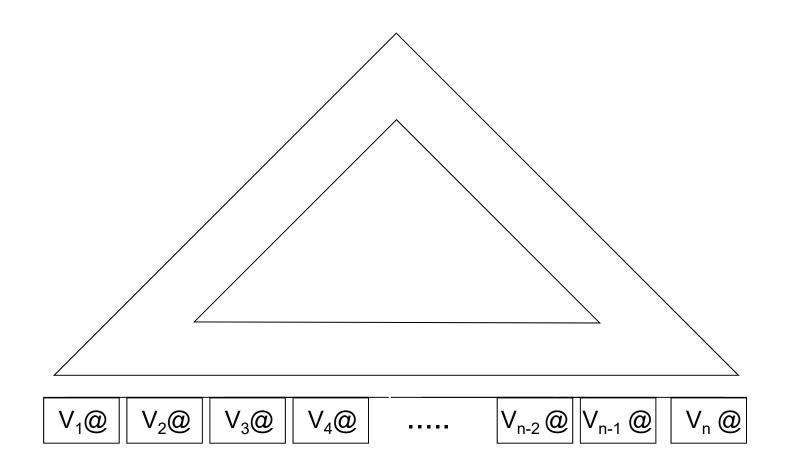
- Need more space
 - For each entry, keeps attributes A₁, ..., A_k
 - May result in more levels, worsening access time
- Modifications are more frequent
 - Every time one of the attributes in the index is modified
- It is much more efficient than intersecting RID lists (to evaluate conjunctions)
- Can be used to solve several kinds of queries
 - Equality of all first i attributes
 - Equality of all first i attributes and range of i+1
- The order of attributes in the index matters
 - We cannot evaluate condition over A_k , if there is no equality for $A_1, ..., A_{k-1}$

BITMAP INDEX

B-tree (I)

- Specially useful for simple queries
 - Without grouping, aggregations, or many joins
- Works better for very selective attributes (few repetitions per value)
 - Attributes in multidimensional queries are usually not very selective
- Order of attributes in the index is relevant
 - We can define as many indexes as we want
 - We can define only one Clustered index
 - For big tables, they may use too much space

B-tree (II)



Bitmap-index

Ballpoint	Pencil	Pen	Rubber	A4 paper	A3 paper	Chalk	Eraser
1	0	0	0	0	0	0	0
0	0	1	0	0	0	0	0
0	1	0	0	0	0	0	0
0	0	0	0	0	0	0	1
0	0	0	0	1	0	0	0
1	0	0	0	0	0	0	0
0	0	0	0	0	1	0	0
0	0	1	0	0	0	0	0
0	0	0	0	0	0	1	0
0	1	0	0	0	0	0	0

Catalunya	León	o o Madrid	Andalucía
1	0	0	0
1	0	0	0
0	0	0	1
0	0	1	0
0 0	1	0 1 0	0
1	0	0	0
0	0	0 0	1
0	0 0 1		0
1	0	0	0 1 0 0
1	0	0	0

Querying with bitmaps

SELECT COUNT(*)

. .

WHERE articleName IN ['Ballpoint', 'Pencil'] AND region='Catalunya'

Ballpoi	lpoint Pencil				Cata	alunya			
1		0		1		1		1	
0		0		0		1		0	
0		1		1		0		0	
0		0		0		0		0	
0	OR	0	_	0	AND	0	_	0	
1	OIX	0	=	1	AND	1	=	1	
0		0		0		0		0	
0		0		0		0		0	
0		0		0		1		0	
0		1		1		1		1	

Updating bitmaps

- Two cases of insertion:
 - Without domain expansion:
 - □ Add "1"
 - With domain expansion:
 - Add a new vector
- One case of deletion:
 - Change "1" for "0"

Catalunya León Madrid Andalucía Euskadi

0	0	0	0	0
1	0	0	0	0
0	0	0	1	0
0	0	1	0	0
0	1	0	0	0
1	0	0	0	0
0	0	0	1	0
0	1	0	0	0
1	0	0	0	0
1	0	0	0	0
0	0	1	0	0
0	0	0	0	1

Probabilities with a bitmap

- Probability of a tuple fulfilling PSF
- Probability of a tuple NOT fulfilling P1-SF
- □ Probability of none of the tuples in a block fulfilling P (1-SF)·(1-SF)· ... ·(1-SF) = (1-SF)^R
- Probability of some tuple in a block fulfilling P
 1-(1-SF)^R

Cost of bitmap per operation

- Table scan
 - ndist·[|T|/bits]·D+B·D
- Search for some tuples
 - v·「|T|/bits]·D+(B·(1-(1-SF)^R))·D
 - Examples:
 - Search for several tuples (given one value): SF=1/ndist
 - 「|T|/bits¬·D+(B·(1-((ndist-1)/ndist)^R))·D
 - Search for several tuples (given several values): SF=v/ndist
 - v·[|T|/bits]·D+(B·(1-((ndist-v)/ndist)^R))·D
 - Search for one tuple: SF=1/|T|
 - 「|T|/bits¬D+D

bits: bits per index block ndist: different values

v: number of queried values

Comparison

- Better than B-tree for multi-value queries
- Optimum performance for several conditions over more than one attribute (each with a low selectivity)
- Orders of magnitude of improvement compared to a table scan (specially for SF<1%)</p>
- May be useful even for range queries
- Sometimes used to manage NULL values
- Useful for non-unique attributes (specially for ndist<|T|/100, i.e. hundreds of repetitions)</p>
- Bad performance for concurrent INSERT, UPDATE and DELETE
- Use more space than RID lists for domains of 32 values or more (may be better with compression), assuming uniform distribution and 4 bytes per RID

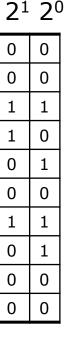
BITMAP COMPRESSION

Bitmap compression variants

- Bitmap-encoded index
 - Create a look-up table coding values into integers
 - Facilitates coding hierarchies
 - 0 to 3 for Catalan provinces (mask 00xx)
 - 4 to 7 for Galician provinces (mask 01xx)
 - 8 to 15 for Andalucian provinces (mask 1xxx)
- Bit-sliced index
 - Code each value into binary
 - Each bit goes to the corresponding bit-vector
 - We only have \[log_2 ndist \] bit-vectors
 - ANDing either the bit or the negated for each column you can check the value:
 - □ A IN (1,3) \Rightarrow (v₀=1 AND v₁=0) OR (v₀=1 AND v₁=1) \Rightarrow v₀=1

Bitmap-encoded-sliced: example

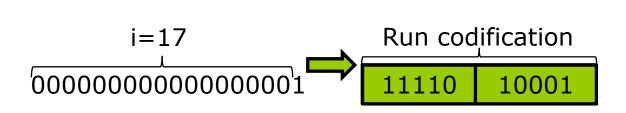


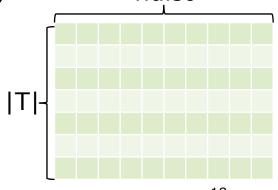


Slicing

Run-length encoding

- □ A "run" is a set of *i* zeros followed by "1"
 - We codify it by a suitable binary encoding of i
- Codification of a run
 - a) Content: Binary coding (e.g., 17=10001)
 - b) Length: n-1 ones and a zero (e.g., 5=11110)
- Size gain
 - Size for coding i: 2√log₂i
 - Average value of i: $|T| \cdot (ndist-1)/|T| = ndist-1$
 - Size of a bitmap: |T|·2·\[log_2(ndist-1)\]

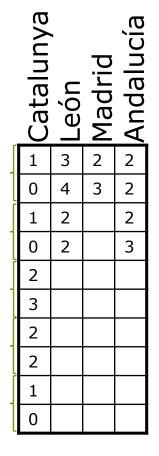


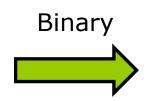


ndist

Run-length encoding example

Run-length





Cataluny	León	1 Madrid	Andalucía
0	[1	[1	[1
0	1	0	0
0	0	1	1
0	1 0	1	0
1	0		0
0	0		0
1	0		1
1	0		1
[1	1		
0	0		
1			
0			
1 0 0 0			
0			

 $\boldsymbol{\omega}$

 $\boldsymbol{\omega}$

Operating run-length encoded bit-vectors

- We need to decode
 - Not necessarily the whole vector at once
 - One run at a time

A OR B \Rightarrow Being $I_A(i)$ and $I_B(j)$ the length of the runs plus one, we know that the $\Sigma_1{}^k I_X(i)$ record must be in the output, for X being both A and B

$$\{a|\exists x, a=\Sigma_1^{\times} I_A(i)\} \cup \{a|\exists x, a=\Sigma_1^{\times} I_B(i)\}$$

A AND B \Rightarrow Being $I_A(i)$ and $I_B(j)$ the length of the runs plus one in both indexes, we must generate in the output:

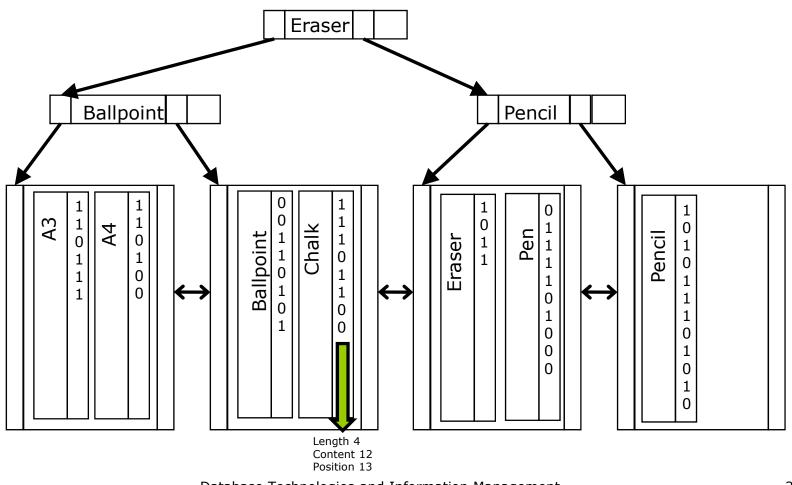
{a|
$$\exists x \exists y, a = \Sigma_1^{\times} I_A(i) = \Sigma_1^{Y} I_B(j)$$
}

Bitmap indexes in Oracle: Declaration

```
CREATE
[{UNIQUE|BITMAP}] INDEX <name>
ON  (<column>[,column]*);
```

- Allowed even for unique attributes
- Does not allow to check uniqueness

Bitmap-index in Oracle: Storage



Database Technologies and Information Management (https://www.essi.upc.edu/dtim)

Finding records of variable length

- a) Maintain a secondary structure
 - Having the position as key
 - Pointing to the disk address of the record
- b) Block-wise implementation
 - Fix the number of bits used per block
 - Use Hakan factor
 - Describes the expected maximum number of rows that a block can hold (e.g., 3)
 - Derived from column definition (and statistics)
 - Affected by
 - Number of columns
 - Column data types and lengths
 - NOT NULL constraints



Setting Hakan factor in Oracle

ALTER TABLE < name > [MINIMIZE | NOMINIMIZE] RECORDS_PER_BLOCK;

- The table cannot be empty
- The table cannot have any bitmap index

CLOSING

Summary

- Multi-attribute index
- Bitmap-index
 - Cost
 - Encoding
 - □ Bitmap-encoded
 - □ Bit-sliced
 - □ Run-length encoding

Bibliography

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