

GMSE: an R package for generalised management strategy evaluation

Supporting Information 4

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Fine-tuning simulation conditions using `gmse_apply`

Here we demonstrate how simulations in GMSE can be more fine-tuned to specific empirical situations through the use of `gmse_apply`. To do this, we use the same scenario described in [Supporting Information 3](#); we first recreate the basic scenario run in `gmse` using `gmse_apply`, and then build in additional modelling details including (1) [custom placement of user land](#), (2) [parameterisation of individual user budgets](#), and (3) [density-dependent movement of resources](#). We emphasise that these simulations are provided only to demonstrate the use of GMSE, and specifically to show the flexibility of the `gmse_apply` function, not to accurately recreate the dynamics of a specific system or make management recommendations.

We reconsider the case of a protected waterfowl population that exploits agricultural land (e.g., [Fox and Madsen, 2017](#); [Mason et al., 2017](#); [Tulloch et al., 2017](#); [Cusack et al., 2018](#)). The manager attempts to keep the waterfowl at a target abundance, while users (farmers) attempt to maximise agricultural yield on the land that they own. We again parameterise our model using demographic information from the Taiga Bean Goose (*Anser fabalis fabalis*), as reported by [Johnson et al. \(2018\)](#) and [AEWA \(2016\)](#). Relevant parameter values are listed in the table below.

Table 1: GMSE simulation parameter values inspired by [Johnson et al. \(2018\)](#) and [AEWA \(2016\)](#)

Parameter	Value	Description
<code>remove_pr</code>	0.122	Goose density-independent mortality probability
<code>lambda</code>	0.275	Expected offspring production per time step
<code>res_death_K</code>	93870	Goose carrying capacity (on adult mortality)
<code>RESOURCE_ini</code>	35000	Initial goose abundance
<code>manage_target</code>	70000	Manager’s target goose abundance
<code>res_death_type</code>	3	Mortality (density and density-independent sources)

Additionally, we continue to use the following values for consistency, except in the case of `stakeholders`, where we reduce the number of farmers to `stakeholders = 8`. This is done to for two reasons. First, it speeds up simulations for the purpose of demonstration; second, it makes the presentation of landscape ownership easier (see below).

Table 2: Non-default GMSE parameter values chosen by authors

Parameter	Value	Description
<code>manager_budget</code>	10000	Manager’s budget for setting policy options
<code>user_budget</code>	10000	Users’ budgets for actions

Parameter	Value	Description
public_land	0.4	Proportion of the landscape that is public
stakeholders	8	Number of stakeholders
land_ownership	TRUE	Users own landscape cells
res_consume	0.02	Landscape cell output consumed by a resource
observe_type	3	Observation model type (survey)
agent_view	1	Cells managers can see when conducting a survey

All other values are set to GMSE defaults, except where specifically noted otherwise.

Re-creating gmse simulations using gmse_apply

We now recreate the simulations in [Supporting Information 3](#), which were run using the `gmse` function, in `gmse_apply`. Doing so requires us to first initialise simulations using one call of `gmse_apply`, then loop through multiple time steps that again call `gmse_apply`; results of interest are recorded in a data frame (`sim_sum_1`). Following the protocol introduced in [Supporting Information 2](#), we can call the initialising simulation `sim_old`, and use the code below to read in the relevant parameter values.

```
sim_old <- gmse_apply(get_res = "Full", remove_pr = 0.122, lambda = 0.275,
                     res_death_K = 93870, RESOURCE_ini = 35000,
                     manage_target = 70000, res_death_type = 3,
                     manager_budget = 10000, user_budget = 100000,
                     public_land = 0.4, stakeholders = 8, res_consume = 0.02,
                     res_birth_K = 200000, land_ownership = TRUE,
                     observe_type = 3, agent_view = 1, converge_crit = 0.01,
                     ga_mingen = 200);
```

Note that the argument `get_res = "Full"` causes `sim_old` retain all of the relevant data structures for simulating a new time step and recording simulation results. This includes the key simulation output, which is located in `sim_old$basic_output`, which is printed below.

```
## $resource_results
## [1] 34366
##
## $observation_results
## [1] 34366
##
## $manager_results
##      resource_type scaring culling castration feeding help_offspring
## policy_1          1      NA     514         NA      NA             NA
##
## $user_results
##      resource_type scaring culling castration feeding help_offspring
## Manager          1      NA      0         NA      NA             NA
## user_1            1      NA    189         NA      NA             NA
## user_2            1      NA    189         NA      NA             NA
## user_3            1      NA    189         NA      NA             NA
## user_4            1      NA    189         NA      NA             NA
## user_5            1      NA    189         NA      NA             NA
## user_6            1      NA    188         NA      NA             NA
## user_7            1      NA    189         NA      NA             NA
## user_8            1      NA    188         NA      NA             NA
```

```
##          tend_crops kill_crops
## Manager      NA      NA
## user_1       NA      NA
## user_2       NA      NA
## user_3       NA      NA
## user_4       NA      NA
## user_5       NA      NA
## user_6       NA      NA
## user_7       NA      NA
## user_8       NA      NA
```

We can then loop over 30 time steps to recreate the simulations from [Supporting Information 3](#). In these simulations, we are specifically interested in the resource and observation outputs, as well as the manager policy and user actions for culling, which we record below in the data frame `sim_sum`. The inclusion of the argument `old_list` tells `gmse_apply` to use parameters and values from the list `sim_old` in the new time step.

```
sim_sum_1 <- matrix(data = NA, nrow = 30, ncol = 5);
for(time_step in 1:30){
  sim_new <- gmse_apply(get_res = "Full", old_list = sim_old);
  sim_sum_1[time_step, 1] <- time_step;
  sim_sum_1[time_step, 2] <- sim_new$basic_output$resource_results[1];
  sim_sum_1[time_step, 3] <- sim_new$basic_output$observation_results[1];
  sim_sum_1[time_step, 4] <- sim_new$basic_output$manager_results[3];
  sim_sum_1[time_step, 5] <- sum(sim_new$basic_output$user_results[,3]);
  sim_old <- sim_new;
}
colnames(sim_sum_1) <- c("Time", "Pop_size", "Pop_est", "Cull_cost",
                        "Cull_count");
print(sim_sum_1);
```

```
##      Time Pop_size Pop_est Cull_cost Cull_count
## [1,]   1   32805   32805     530     1467
## [2,]   2   31760   31760     511     1519
## [3,]   3   31200   31200     512     1516
## [4,]   4   31024   31024     518     1496
## [5,]   5   33860   33860     520     1495
## [6,]   6   34075   34075     482     1607
## [7,]   7   34236   34236     500     1549
## [8,]   8   34676   34676     526     1475
## [9,]   9   35507   35507     509     1525
## [10,] 10   36472   36472     516     1505
## [11,] 11   37294   37294     495     1565
## [12,] 12   38154   38154     504     1537
## [13,] 13   39066   39066     505     1530
## [14,] 14   40082   40082     505     1535
## [15,] 15   41032   41032     514     1509
## [16,] 16   42433   42433     497     1560
## [17,] 17   43534   43534     508     1527
## [18,] 18   44917   44917     513     1514
## [19,] 19   46314   46314     513     1512
## [20,] 20   47751   47751     502     1544
## [21,] 21   49353   49353     500     1552
## [22,] 22   50880   50880     505     1536
## [23,] 23   52684   52684     514     1508
```

## [24,]	24	54566	54566	488	1588
## [25,]	25	56622	56622	507	1529
## [26,]	26	58969	58969	519	1497
## [27,]	27	61355	61355	511	1519
## [28,]	28	64053	64053	506	1533
## [29,]	29	66975	66975	514	1514
## [30,]	30	70171	70171	509	1526

The above output from `sim_sum_1` shows the data frame that holds the information we were interested in pulling out of our simulation results. All of this information was available under the list element `sim_new$basic_output`, but other list elements of `sim_new` might also be useful to record. It is important to remember that this example of `gmse_apply` is using the default resource, observation, manager, and user submodels. Custom submodels could produce different outputs in `sim_new` (see [Supporting Information 2](#) for examples). For default submodels, there are some list elements that might be especially useful. These elements can potentially be edited *within the above loop* to dynamically adjust simulations.

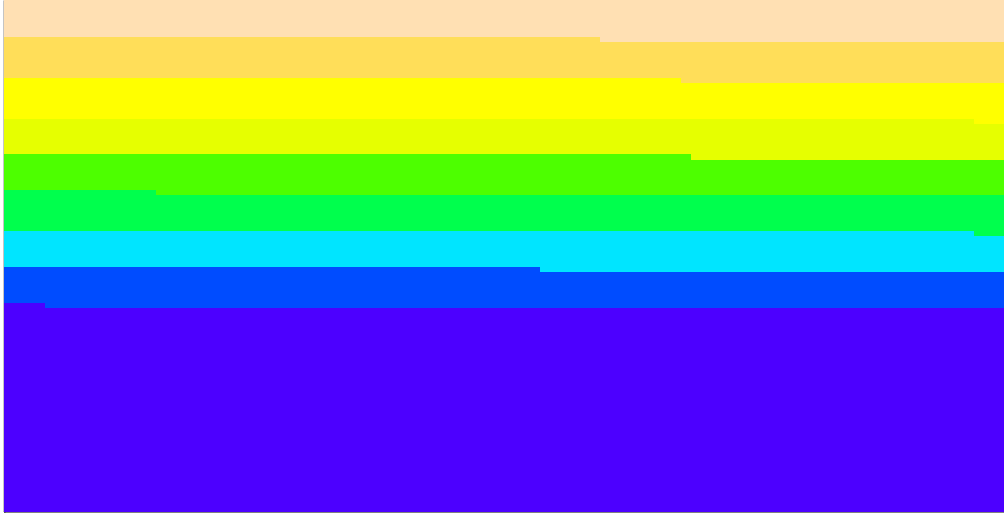
- `sim_new$resource_array`: A table holding all information on resources. Rows correspond to discrete resources, and columns correspond to resource properties: (1) ID, (2-4) types (not currently in use), (5) x-location, (6) y-location, (7) movement parameter, (8) time, (9) density independent mortality parameter (`remove_pr`), (10) reproduction parameter (`lambda`), (11) offspring number, (12) age, (13-14) observation columns, (15) consumption rate (`res_consume`), and (16-20) recorded experiences of user actions (e.g., was the resource culled or scared?).
- `sim_new$AGENTS`: A table holding basic information on agents (manager and users). Rows correspond to a unique agent, and columns correspond to agent properties: (1) ID, (2) type (0 for the manager, 1 for users), (3-4) additional type options not currently in use, (5-6), x and y locations (usually ignored), (7) movement parameter (usually ignored), (8) time, (9) agent's viewing ability in cells (`agent_view`), (10) error parameter, (11-12) values for holding marks and tallies of resources, (13-15) values for holding observations, (16) yield from landscape cells, (17) budget (`manager_budget` and `user_budget`).
- `sim_new$observation_vector`: Estimate of total resource number from the observation model (`observation_array` also holds this information in a different way depending on `observe_type`)
- `sim_new$LAND`: The landscape on which interactions occur, which is stored as a 3D array with `land_dim_1` rows, `land_dim_2` columns, and 3 layers. Layer 1 (`sim_new$LAND[,1]`) is not currently used in default submodels, but could be used to store values that affect resources and agents. Layer 2 (`sim_new$LAND[,2]`) stores crop yield from a cell, and layer 3 (`sim_new$LAND[,3]`) stores the owner of the cell (value corresponds to the agent's ID).
- `sim_new$manage_vector`: The cost of each action as set by the manager. For even more fine-tuning, individual costs for the actions of each agent can be set for each user in `sim_new$manager_array`.
- `sim_new$user_vector`: The total number of actions performed by each user. A more detailed breakdown of actions by individual users is held in `sim_new$user_array`.

Next, we show how to adjust the landscape to manually set land ownership in `gmse_apply`.

1. Custom placement of user land

By default, all farmers in GMSE are allocated the same number of landscape cells, which are simply placed in order of the farmer's ID. Public land is produced by placing landscape cells that are technically owned by the manager, and therefore have landscape cell values of 1. The image below shows this landscape for the eight farmers from `sim_old`.

```
image(x = sim_old$LAND[,3], col = topo.colors(9), xaxt = "n", yaxt = "n");
```

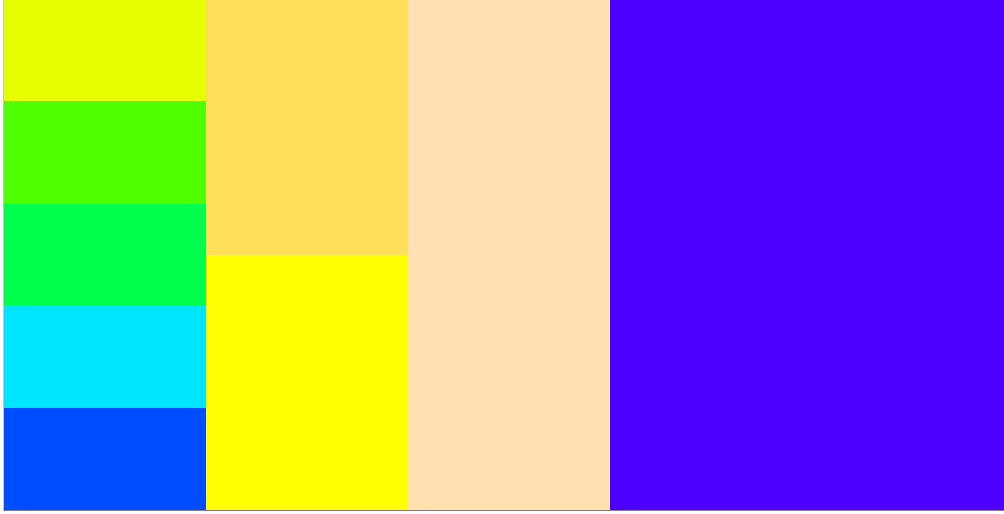


We can change the ownership of cells by manipulating `sim_old$LAND[,3]`. First we initialise a new `sim_old` below.

```
sim_old <- gmse_apply(get_res = "Full", remove_pr = 0.122, lambda = 0.275,
  res_death_K = 93870, RESOURCE_ini = 35000,
  manage_target = 70000, res_death_type = 3,
  manager_budget = 10000, user_budget = 10000,
  public_land = 0.4, stakeholders = 8, res_consume = 0.02,
  res_birth_K = 200000, land_ownership = TRUE,
  observe_type = 3, agent_view = 1, converge_crit = 0.01,
  ga_mingen = 200);
```

Because we have not specified landscape dimensions in the above, the landscape reverts to the default size of 100 by 100 cells. We can then manually assign landscape cells to the eight farmers, whose IDs range from 2-9 (ID value 1 is the manager). Below we do this to make eight different sized farms.

```
sim_old$LAND[1:20, 1:20, 3] <- 2;
sim_old$LAND[1:20, 21:40, 3] <- 3;
sim_old$LAND[1:20, 41:60, 3] <- 4;
sim_old$LAND[1:20, 61:80, 3] <- 5;
sim_old$LAND[1:20, 81:100, 3] <- 6;
sim_old$LAND[21:40, 1:50, 3] <- 7;
sim_old$LAND[21:40, 51:100, 3] <- 8;
sim_old$LAND[41:60, 1:100, 3] <- 9;
sim_old$LAND[61:100, 1:100, 3] <- 1; # Public land
image(x = sim_old$LAND[, , 3], col = topo.colors(9), xaxt = "n", yaxt = "n");
```



The above image shows the modified landscape stored in `sim_old`, which can now be incorporated into simulations using `gmse_apply`. We can think of all the plots on the left side of the landscape as farms of various sizes, while the blue area of the landscape on the right is public land.

2. Parameterisation of individual user budgets

Perhaps we want to assume that farmers have different budgets, which are correlated in some way to the number of landscape cells that they own. Custom user budgets can be set by manipulating `sim_old$AGENTS`, the last column of which (column 17) holds the budget for each user. Agent IDs (as stored on the landscape above) correspond to rows of `sim_old$AGENTS`, so individual budgets can be directly input as desired. We can do this manually (e.g., `sim_old$AGENTS[2, 17] <- 4000`), or, alternatively, if farmer budget positively correlates to landscape owned, we can use a loop to input values as below.

```
for(ID in 2:9){
  cells_owned      <- sum(sim_old$LAND[,3] == ID);
  sim_old$AGENTS[ID, 17] <- 100 * cells_owned;
}
```

The number of cells owned by each farmer is therefore listed in the table below.

ID	1	2	3	4	5	6	7	8	9
Budget	10000	40000	40000	40000	40000	40000	1e+05	1e+05	2e+05

As with `sim_old$LAND` values, changes to `sim_old$AGENTS` will be retained in simulations looped through `gmse_apply`.

3. Density-dependent movement of resources

Lastly, we consider a more nuanced change to simulations, in which the rules for movement of resources are modified to account for density-dependence. Assume that geese tend to avoid aggregating, such that if a goose is located on the same cell as too many other geese, then it will move at the start of a time step. Programming this movement rule can be accomplished by creating a new function to apply to the resource data array `sim_old$resource_array`. Below, a custom function is defined that causes a goose to move up

to 5 cells in any direction if it finds itself on a cell with more than 10 other geese. As with default GMSE simulations, movement is based on a torus landscape.

```
avoid_aggregation <- function(goose_table, land_dim_1 = 100, land_dim_2 = 100){
  goose_number <- dim(goose_table)[1] # How many geese are there?
  for(goose in 1:goose_number){ # Loop through all rows of geese
    x_loc <- goose_table[goose, 5];
    y_loc <- goose_table[goose, 6];
    shared <- sum(goose_table[,5] == x_loc & goose_table[,6] == y_loc);
    if(shared > 10){
      new_x <- x_loc + sample(x = -5:5, size = 1);
      new_y <- y_loc + sample(x = -5:5, size = 1);
      if(new_x < 0){ # The 'if' statements below apply the torus
        new_x <- land_dim_1 + new_x;
      }
      if(new_x >= land_dim_1){
        new_x <- new_x - land_dim_1;
      }
      if(new_y < 0){
        new_y <- land_dim_2 + new_y;
      }
      if(new_y >= land_dim_2){
        new_y <- new_y - land_dim_2;
      }
      goose_table[goose, 5] <- new_x;
      goose_table[goose, 6] <- new_y;
    }
  }
  return(goose_table);
}
```

With the above function written, we can apply the new movement rule along with our [custom farm placement](#) and [custom farmer budgets](#) to the simulation of goose population dynamics.

Simulation with custom farms, budgets, and goose movement

Below shows an example of `gmse_apply` with custom landscapes, farmer budgets, and density-dependent goose movement rules.

```
# First initialise a simulation
sim_old <- gmse_apply(get_res = "Full", remove_pr = 0.122, lambda = 0.275,
  res_death_K = 93870, RESOURCE_ini = 35000,
  manage_target = 70000, res_death_type = 3,
  manager_budget = 10000, user_budget = 10000,
  public_land = 0.4, stakeholders = 8, res_consume = 0.02,
  res_birth_K = 200000, land_ownership = TRUE,
  observe_type = 3, agent_view = 1, converge_crit = 0.01,
  ga_mingen = 200, res_move_type = 0);

# By setting `res_move_type = 0`, no resource movement will occur in gmse_apply
# Adjust the landscape ownership below
sim_old$LAND[1:20, 1:20, 3] <- 2;
sim_old$LAND[1:20, 21:40, 3] <- 3;
sim_old$LAND[1:20, 41:60, 3] <- 4;
sim_old$LAND[1:20, 61:80, 3] <- 5;
```

```

sim_old$LAND[1:20, 81:100, 3] <- 6;
sim_old$LAND[21:40, 1:50, 3] <- 7;
sim_old$LAND[21:40, 51:100, 3] <- 8;
sim_old$LAND[41:60, 1:100, 3] <- 9;
sim_old$LAND[61:100, 1:100, 3] <- 1;
# Change the budgets of each farmer based on the land they own
for(ID in 2:9){
  cells_owned <- sum(sim_old$LAND[,3] == ID);
  sim_old$AGENTS[ID, 17] <- 10 * cells_owned;
}
# Begin simulating time steps for the system
sim_sum_2 <- matrix(data = NA, nrow = 30, ncol = 5);
for(time_step in 1:30){
  # Apply the new movement rules at the beginning of the loop
  sim_old$resource_array <- avoid_aggregation(sim_old$resource_array);
  # Next, move on to simulate (old_list remembers that res_move_type = 0)
  sim_new <- gmse_apply(get_res = "Full", old_list = sim_old);
  sim_sum_2[time_step, 1] <- time_step;
  sim_sum_2[time_step, 2] <- sim_new$basic_output$resource_results[1];
  sim_sum_2[time_step, 3] <- sim_new$basic_output$observation_results[1];
  sim_sum_2[time_step, 4] <- sim_new$basic_output$manager_results[3];
  sim_sum_2[time_step, 5] <- sum(sim_new$basic_output$user_results[,3]);
  sim_old <- sim_new;
}
colnames(sim_sum_2) <- c("Time", "Pop_size", "Pop_est", "Cull_cost",
  "Cull_count");
print(sim_sum_2);

```

```

##      Time Pop_size Pop_est Cull_cost Cull_count
## [1,]    1   33677   33677     532      107
## [2,]    2   34012   34012     486      120
## [3,]    3   35004   35004     510      111
## [4,]    4   36584   36584     503      111
## [5,]    5   42003   42003     502      112
## [6,]    6   43882   43882     515      111
## [7,]    7   46362   46362     517      110
## [8,]    8   49292   49292     509      112
## [9,]    9   52495   52495     529      108
## [10,]  10   56195   56195     520      108
## [11,]  11   60134   60134     499      115
## [12,]  12   63871   63871     503      111
## [13,]  13   67890   67890     504      111
## [14,]  14   72295   72295     501      112
## [15,]  15   77120   77120     501      112
## [16,]  16   82235   82235     490      120
## [17,]  17   87883   87883     504      111
## [18,]  18   93802   93802     514      110
## [19,]  19   99877   99877     489      120
## [20,]  20  102104  102104     519      108
## [21,]  21  102777  102777     520      110
## [22,]  22  102917  102917     486      120
## [23,]  23  103306  103306     515      111
## [24,]  24  103335  103335     506      112
## [25,]  25  103564  103564     509      111

```


## [26,]	26	103414	103414	496	116
## [27,]	27	103525	103525	505	112
## [28,]	28	103824	103824	502	111
## [29,]	29	103512	103512	498	112
## [30,]	30	103699	103699	521	109

Conclusions

In this example, we showed how the built-in resource, observation, manager, and user sub-models can be customised by manipulating the data within the data structures that they use. The goal was to show how software users can work with these existing sub-models and data structures to customise GMSE simulations. Software users seeking even greater flexibility (e.g., replacing an entire built-in submodel with a custom submodel) should refer to the [Supporting Information 2](#) that introduces `gmse_apply` more generally. Future versions of GMSE are likely to expand on the built-in options available for simulation; requests for such expansions, or contributions, can be submitted to [GitHub](#).

References

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