

# Advanced case study options

GMSE: an R package for generalised management strategy evaluation (Supporting Information 4)

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## Fine-tuning simulation conditions using `gmse_apply`

Here we demonstrate how simulations in GMSE can be more fine-tuned to specific empirical situations through the use of `gmse_apply`. To do this, we use the same scenario described in [Supporting Information 3](#); we first recreate the basic scenario run in `gmse` using `gmse_apply`, and then build in additional modelling details including (1) [custom placement of user land](#), (2) [parameterisation of individual user budgets](#), and (3) [density-dependent movement of resources](#). We emphasise that these simulations are provided only to demonstrate the use of GMSE, and specifically to show the flexibility of the `gmse_apply` function, not to accurately recreate the dynamics of a specific system or make management recommendations.

We reconsider the case of a protected waterfowl population that exploits agricultural land (e.g., [Fox and Madsen, 2017](#); [Mason et al., 2017](#); [Tulloch et al., 2017](#); [Cusack et al., 2018](#)). The manager attempts to keep the waterfowl at a target abundance, while users (farmers) attempt to maximise agricultural yield on the land that they own. We again parameterise our model using demographic information from the Taiga Bean Goose (*Anser fabalis fabalis*), as reported by [Johnson et al. \(2018\)](#) and [AEWA \(2016\)](#). Relevant parameter values are listed in the table below.

Table 1: GMSE simulation parameter values inspired by [Johnson et al. \(2018\)](#) and [AEWA \(2016\)](#)

Parameter	Value	Description
<code>remove_pr</code>	0.122	Goose density-independent mortality probability
<code>lambda</code>	0.275	Expected offspring production per time step
<code>res_death_K</code>	93870	Goose carrying capacity (on adult mortality)
<code>RESOURCE_ini</code>	35000	Initial goose abundance
<code>manage_target</code>	70000	Manager’s target goose abundance
<code>res_death_type</code>	3	Mortality (density and density-independent sources)

Additionally, we continue to use the following values for consistency, except in the case of `stakeholders`, where we reduce the number of farmers to `stakeholders = 8`. This is done to for two reasons. First, it speeds up simulations for the purpose of demonstration; second, it makes the presentation of landscape ownership easier (see below).

Table 2: Non-default GMSE parameter values chosen by authors

Parameter	Value	Description
<code>manager_budget</code>	10000	Manager’s budget for setting policy options
<code>user_budget</code>	10000	Users’ budgets for actions
<code>public_land</code>	0.4	Proportion of the landscape that is public

Parameter	Value	Description
stakeholders	8	Number of stakeholders
land_ownership	TRUE	Users own landscape cells
res_consume	0.02	Landscape cell output consumed by a resource
observe_type	3	Observation model type (survey)
agent_view	1	Cells managers can see when conducting a survey

All other values are set to GMSE defaults, except where specifically noted otherwise.

## Re-creating gmse simulations using gmse\_apply

We now recreate the simulations in [Supporting Information 3](#), which were run using the `gmse` function, in `gmse_apply`. Doing so requires us to first initialise simulations using one call of `gmse_apply`, then loop through multiple time steps that again call `gmse_apply`; results of interest are recorded in a data frame (`sim_sum_1`). Following the protocol introduced in [Supporting Information 2](#), we can call the initialising simulation `sim_old`, and use the code below to read in the relevant parameter values.

```
sim_old <- gmse_apply(get_res = "Full", remove_pr = 0.122, lambda = 0.275,
                     res_death_K = 93870, RESOURCE_ini = 35000,
                     manage_target = 70000, res_death_type = 3,
                     manager_budget = 10000, user_budget = 100000,
                     public_land = 0.4, stakeholders = 8, res_consume = 0.02,
                     res_birth_K = 200000, land_ownership = TRUE,
                     observe_type = 3, agent_view = 1, converge_crit = 0.01,
                     ga_mingen = 200);
```

Note that the argument `get_res = "Full"` causes `sim_old` retain all of the relevant data structures for simulating a new time step and recording simulation results. This includes the key simulation output, which is located in `sim_old$basic_output`, which is printed below.

```
## $resource_results
## [1] 34281
##
## $observation_results
## [1] 34281
##
## $manager_results
##      resource_type scaring culling castration feeding help_offspring
## policy_1          1      NA    515          NA      NA              NA
##
## $user_results
##      resource_type scaring culling castration feeding help_offspring
## Manager          1      NA      0          NA      NA              NA
## user_1            1      NA    189          NA      NA              NA
## user_2            1      NA    188          NA      NA              NA
## user_3            1      NA    189          NA      NA              NA
## user_4            1      NA    188          NA      NA              NA
## user_5            1      NA    189          NA      NA              NA
## user_6            1      NA    189          NA      NA              NA
## user_7            1      NA    188          NA      NA              NA
## user_8            1      NA    188          NA      NA              NA
##
##      tend_crops kill_crops
```

```
## Manager      NA      NA
## user_1       NA      NA
## user_2       NA      NA
## user_3       NA      NA
## user_4       NA      NA
## user_5       NA      NA
## user_6       NA      NA
## user_7       NA      NA
## user_8       NA      NA
```

We can then loop over 30 time steps to recreate the simulations from [Supporting Information 3](#). In these simulations, we are specifically interested in the resource and observation outputs, as well as the manager policy and user actions for culling, which we record below in the data frame `sim_sum`. The inclusion of the argument `old_list` tells `gmse_apply` to use parameters and values from the list `sim_old` in the new time step.

```
sim_sum_1 <- matrix(data = NA, nrow = 30, ncol = 5);
for(time_step in 1:30){
  sim_new <- gmse_apply(get_res = "Full", old_list = sim_old);
  sim_sum_1[time_step, 1] <- time_step;
  sim_sum_1[time_step, 2] <- sim_new$basic_output$resource_results[1];
  sim_sum_1[time_step, 3] <- sim_new$basic_output$observation_results[1];
  sim_sum_1[time_step, 4] <- sim_new$basic_output$manager_results[3];
  sim_sum_1[time_step, 5] <- sum(sim_new$basic_output$user_results[,3]);
  sim_old <- sim_new;
}
colnames(sim_sum_1) <- c("Time", "Pop_size", "Pop_est", "Cull_cost",
                        "Cull_count");
print(sim_sum_1);
```

```
##      Time Pop_size Pop_est Cull_cost Cull_count
## [1,]   1   32690   32690     842      930
## [2,]   2   32119   32119     957      818
## [3,]   3   32242   32242     985      796
## [4,]   4   33087   33087    1001      785
## [5,]   5   37318   37318     989      794
## [6,]   6   38590   38590    1006      782
## [7,]   7   40054   40054    1000      786
## [8,]   8   41853   41853     995      790
## [9,]   9   43863   43863    1003      785
## [10,] 10   45793   45793     999      786
## [11,] 11   48318   48318     986      797
## [12,] 12   50664   50664     995      791
## [13,] 13   53132   53132     995      789
## [14,] 14   55813   55813    1002      785
## [15,] 15   58850   58850     991      793
## [16,] 16   62289   62289     997      786
## [17,] 17   65855   65855     996      788
## [18,] 18   69412   69412     998      786
## [19,] 19   73371   73371      10    29268
## [20,] 20   47258   47258    1010      778
## [21,] 21   49768   49768     999      786
## [22,] 22   52332   52332     993      793
## [23,] 23   55254   55254    1004      785
## [24,] 24   58236   58236    1002      785
```

```
## [25,] 25 61620 61620 996 787
## [26,] 26 64819 64819 1001 785
## [27,] 27 68333 68333 997 787
## [28,] 28 71910 71910 10 29205
## [29,] 29 45677 45677 1010 778
## [30,] 30 48148 48148 995 788
```

The above output from `sim_sum_1` shows the data frame that holds the information we were interested in pulling out of our simulation results. All of this information was available under the list element `sim_new$basic_output`, but other list elements of `sim_new` might also be useful to record. It is important to remember that this example of `gmse_apply` is using the default resource, observation, manager, and user submodels. Custom submodels could produce different outputs in `sim_new` (see [Supporting Information 2](#) for examples). For default submodels, there are some list elements that might be especially useful. These elements can potentially be edited *within the above loop* to dynamically adjust simulations.

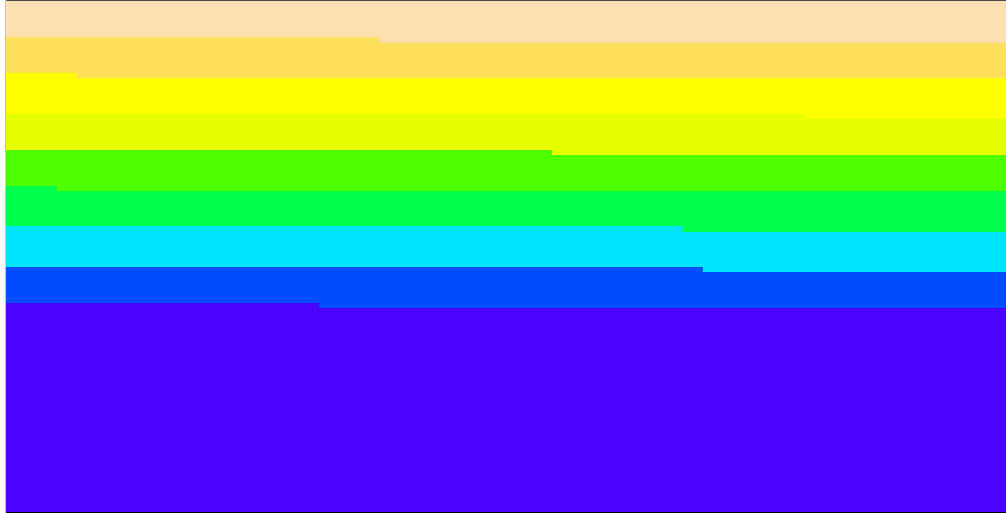
- `sim_new$resource_array`: A table holding all information on resources. Rows correspond to discrete resources, and columns correspond to resource properties: (1) ID, (2-4) types (not currently in use), (5) x-location, (6) y-location, (7) movement parameter, (8) time, (9) density independent mortality parameter (`remove_pr`), (10) reproduction parameter (`lambda`), (11) offspring number, (12) age, (13-14) observation columns, (15) consumption rate (`res_consume`), and (16-20) recorded experiences of user actions (e.g., was the resource culled or scared?).
- `sim_new$AGENTS`: A table holding basic information on agents (manager and users). Rows correspond to a unique agent, and columns correspond to agent properties: (1) ID, (2) type (0 for the manager, 1 for users), (3-4) additional type options not currently in use, (5-6), x and y locations (usually ignored), (7) movement parameter (usually ignored), (8) time, (9) agent's viewing ability in cells (`agent_view`), (10) error parameter, (11-12) values for holding marks and tallies of resources, (13-15) values for holding observations, (16) yield from landscape cells, (17) budget (`manager_budget` and `user_budget`).
- `sim_new$observation_vector`: Estimate of total resource number from the observation model (`observation_array` also holds this information in a different way depending on `observe_type`)
- `sim_new$LAND`: The landscape on which interactions occur, which is stored as a 3D array with `land_dim_1` rows, `land_dim_2` columns, and 3 layers. Layer 1 (`sim_new$LAND[,1]`) is not currently used in default submodels, but could be used to store values that affect resources and agents. Layer 2 (`sim_new$LAND[,2]`) stores crop yield from a cell, and layer 3 (`sim_new$LAND[,3]`) stores the owner of the cell (value corresponds to the agent's ID).
- `sim_new$manage_vector`: The cost of each action as set by the manager. For even more fine-tuning, individual costs for the actions of each agent can be set for each user in `sim_new$manager_array`.
- `sim_new$user_vector`: The total number of actions performed by each user. A more detailed breakdown of actions by individual users is held in `sim_new$user_array`.

Next, we show how to adjust the landscape to manually set land ownership in `gmse_apply`.

## 1. Custom placement of user land

By default, all farmers in GMSE are allocated the same number of landscape cells, which are simply placed in order of the farmer's ID. Public land is produced by placing landscape cells that are technically owned by the manager, and therefore have landscape cell values of 1. The image below shows this landscape for the eight farmers from `sim_old`.

```
image(x = sim_old$LAND[,3], col = topo.colors(9), xaxt = "n", yaxt = "n");
```

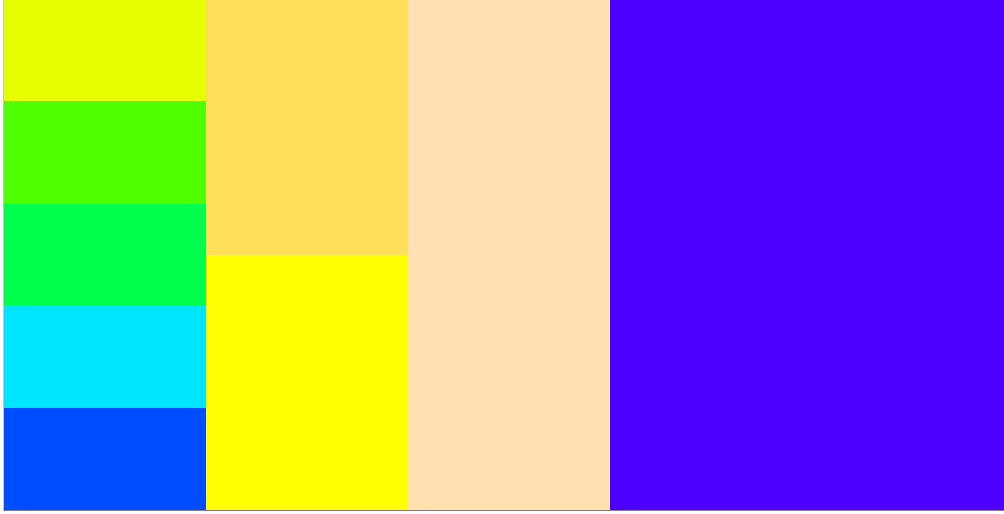


We can change the ownership of cells by manipulating `sim_old$LAND[,3]`. First we initialise a new `sim_old` below.

```
sim_old <- gmse_apply(get_res = "Full", remove_pr = 0.122, lambda = 0.275,
  res_death_K = 93870, RESOURCE_ini = 35000,
  manage_target = 70000, res_death_type = 3,
  manager_budget = 10000, user_budget = 10000,
  public_land = 0.4, stakeholders = 8, res_consume = 0.02,
  res_birth_K = 200000, land_ownership = TRUE,
  observe_type = 3, agent_view = 1, converge_crit = 0.01,
  ga_mingen = 200);
```

Because we have not specified landscape dimensions in the above, the landscape reverts to the default size of 100 by 100 cells. We can then manually assign landscape cells to the eight farmers, whose IDs range from 2-9 (ID value 1 is the manager). Below we do this to make eight different sized farms.

```
sim_old$LAND[1:20, 1:20, 3] <- 2;
sim_old$LAND[1:20, 21:40, 3] <- 3;
sim_old$LAND[1:20, 41:60, 3] <- 4;
sim_old$LAND[1:20, 61:80, 3] <- 5;
sim_old$LAND[1:20, 81:100, 3] <- 6;
sim_old$LAND[21:40, 1:50, 3] <- 7;
sim_old$LAND[21:40, 51:100, 3] <- 8;
sim_old$LAND[41:60, 1:100, 3] <- 9;
sim_old$LAND[61:100, 1:100, 3] <- 1; # Public land
image(x = sim_old$LAND[,3], col = topo.colors(9), xaxt = "n", yaxt = "n");
```



The above image shows the modified landscape stored in `sim_old`, which can now be incorporated into simulations using `gmse_apply`. We can think of all the plots on the left side of the landscape as farms of various sizes, while the blue area of the landscape on the right is public land.

## 2. Parameterisation of individual user budgets

Perhaps we want to assume that farmers have different budgets, which are correlated in some way to the number of landscape cells that they own. Custom user budgets can be set by manipulating `sim_old$AGENTS`, the last column of which (column 17) holds the budget for each user. Agent IDs (as stored on the landscape above) correspond to rows of `sim_old$AGENTS`, so individual budgets can be directly input as desired. We can do this manually (e.g., `sim_old$AGENTS[2, 17] <- 4000`), or, alternatively, if farmer budget positively correlates to landscape owned, we can use a loop to input values as below.

```
for(ID in 2:9){
  cells_owned      <- sum(sim_old$LAND[,3] == ID);
  sim_old$AGENTS[ID, 17] <- 100 * cells_owned;
}
```

The number of cells owned by each farmer is therefore listed in the table below.

ID	1	2	3	4	5	6	7	8	9
Budget	10000	40000	40000	40000	40000	40000	1e+05	1e+05	2e+05

As with `sim_old$LAND` values, changes to `sim_old$AGENTS` will be retained in simulations looped through `gmse_apply`.

## 3. Density-dependent movement of resources

Lastly, we consider a more nuanced change to simulations, in which the rules for movement of resources are modified to account for density-dependence. Assume that geese tend to avoid aggregating, such that if a goose is located on the same cell as too many other geese, then it will move at the start of a time step. Programming this movement rule can be accomplished by creating a new function to apply to the resource data array `sim_old$resource_array`. Below, a custom function is defined that causes a goose to move up

to 5 cells in any direction if it finds itself on a cell with more than 10 other geese. As with default GMSE simulations, movement is based on a torus landscape.

```
avoid_aggregation <- function(goose_table, land_dim_1 = 100, land_dim_2 = 100){
  goose_number <- dim(goose_table)[1] # How many geese are there?
  for(goose in 1:goose_number){ # Loop through all rows of geese
    x_loc <- goose_table[goose, 5];
    y_loc <- goose_table[goose, 6];
    shared <- sum(goose_table[,5] == x_loc & goose_table[,6] == y_loc);
    if(shared > 10){
      new_x <- x_loc + sample(x = -5:5, size = 1);
      new_y <- y_loc + sample(x = -5:5, size = 1);
      if(new_x < 0){ # The 'if' statements below apply the torus
        new_x <- land_dim_1 + new_x;
      }
      if(new_x >= land_dim_1){
        new_x <- new_x - land_dim_1;
      }
      if(new_y < 0){
        new_y <- land_dim_2 + new_y;
      }
      if(new_y >= land_dim_2){
        new_y <- new_y - land_dim_2;
      }
      goose_table[goose, 5] <- new_x;
      goose_table[goose, 6] <- new_y;
    }
  }
  return(goose_table);
}
```

With the above function written, we can apply the new movement rule along with our [custom farm placement](#) and [custom farmer budgets](#) to the simulation of goose population dynamics.

## Simulation with custom farms, budgets, and goose movement

Below shows an example of `gmse_apply` with custom landscapes, farmer budgets, and density-dependent goose movement rules.

```
# First initialise a simulation
sim_old <- gmse_apply(get_res = "Full", remove_pr = 0.122, lambda = 0.275,
  res_death_K = 93870, RESOURCE_ini = 35000,
  manage_target = 70000, res_death_type = 3,
  manager_budget = 10000, user_budget = 10000,
  public_land = 0.4, stakeholders = 8, res_consume = 0.02,
  res_birth_K = 200000, land_ownership = TRUE,
  observe_type = 3, agent_view = 1, converge_crit = 0.01,
  ga_mingen = 200, res_move_type = 0);

# By setting `res_move_type = 0`, no resource movement will occur in gmse_apply
# Adjust the landscape ownership below
sim_old$LAND[1:20, 1:20, 3] <- 2;
sim_old$LAND[1:20, 21:40, 3] <- 3;
sim_old$LAND[1:20, 41:60, 3] <- 4;
sim_old$LAND[1:20, 61:80, 3] <- 5;
```

```

sim_old$LAND[1:20, 81:100, 3] <- 6;
sim_old$LAND[21:40, 1:50, 3] <- 7;
sim_old$LAND[21:40, 51:100, 3] <- 8;
sim_old$LAND[41:60, 1:100, 3] <- 9;
sim_old$LAND[61:100, 1:100, 3] <- 1;
# Change the budgets of each farmer based on the land they own
for(ID in 2:9){
  cells_owned <- sum(sim_old$LAND[,3] == ID);
  sim_old$AGENTS[ID, 17] <- 10 * cells_owned;
}
# Begin simulating time steps for the system
sim_sum_2 <- matrix(data = NA, nrow = 30, ncol = 5);
for(time_step in 1:30){
  # Apply the new movement rules at the beginning of the loop
  sim_old$resource_array <- avoid_aggregation(sim_old$resource_array);
  # Next, move on to simulate (old_list remembers that res_move_type = 0)
  sim_new <- gmse_apply(get_res = "Full", old_list = sim_old);
  sim_sum_2[time_step, 1] <- time_step;
  sim_sum_2[time_step, 2] <- sim_new$basic_output$resource_results[1];
  sim_sum_2[time_step, 3] <- sim_new$basic_output$observation_results[1];
  sim_sum_2[time_step, 4] <- sim_new$basic_output$manager_results[3];
  sim_sum_2[time_step, 5] <- sum(sim_new$basic_output$user_results[,3]);
  sim_old <- sim_new;
}
colnames(sim_sum_2) <- c("Time", "Pop_size", "Pop_est", "Cull_cost",
  "Cull_count");
print(sim_sum_2);

```

```

##      Time Pop_size Pop_est Cull_cost Cull_count
## [1,]    1   33540   33540     803         68
## [2,]    2   33850   33850     907         61
## [3,]    3   34721   34721     963         60
## [4,]    4   36212   36212     982         60
## [5,]    5   41647   41647    1010         52
## [6,]    6   43663   43663     996         57
## [7,]    7   46223   46223     976         60
## [8,]    8   49013   49013     987         60
## [9,]    9   52160   52160     995         57
## [10,]   10   55547   55547     989         60
## [11,]   11   59070   59070    1003         52
## [12,]   12   62683   62683     994         58
## [13,]   13   66605   66605     983         60
## [14,]   14   70734   70734     455        124
## [15,]   15   75227   75227     398        149
## [16,]   16   80078   80078     343        170
## [17,]   17   85126   85126     399        149
## [18,]   18   90496   90496     349        167
## [19,]   19   96170   96170     389        150
## [20,]   20  100865  100865     421        138
## [21,]   21  102243  102243     415        139
## [22,]   22  102901  102901     392        150
## [23,]   23  102708  102708     397        146
## [24,]   24  103526  103526     384        153
## [25,]   25  103785  103785     349        168

```



## [26,]	26	103845	103845	385	151
## [27,]	27	103778	103778	415	139
## [28,]	28	103534	103534	408	141
## [29,]	29	103557	103557	436	134
## [30,]	30	103769	103769	424	137

## Conclusions

In this example, we showed how the built-in resource, observation, manager, and user sub-models can be customised by manipulating the data within the data structures that they use. The goal was to show how software users can work with these existing sub-models and data structures to customise GMSE simulations. Software users seeking even greater flexibility (e.g., replacing an entire built-in submodel with a custom submodel) should refer to the [Supporting Information 2](#) that introduces `gmse_apply` more generally. Future versions of GMSE are likely to expand on the built-in options available for simulation; requests for such expansions, or contributions, can be submitted to [GitHub](#).

## References

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