

Advanced case study options

GMSE: an R package for generalised management strategy evaluation (Supporting Information 4)

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Fine-tuning simulation conditions using `gmse_apply`

Here we demonstrate how simulations in GMSE can be more fine-tuned to specific empirical situations through the use of `gmse_apply`. To do this, we use the same scenario described in [SI3](#); we first recreate the basic scenario run in `gmse` using `gmse_apply`, and then build in additional modelling details including (1) custom placement of user land, (2) parameterisation of individual user budgets, and (3) density-dependent movement of resources. We emphasise that these simulations are provided only to demonstrate the use of GMSE, and specifically to show the flexibility of the `gmse_apply` function, not to accurately recreate the dynamics of a specific system or make management recommendations.

We reconsider the case of a protected waterfowl population that exploits agricultural land (e.g., [Fox and Madsen, 2017](#); [Mason et al., 2017](#); [Tulloch et al., 2017](#); [Cusack et al., 2018](#)). The manager attempts to keep the waterfowl at a target abundance, while users (farmers) attempt to maximise agricultural yield on the land that they own. We again parameterise our model using demographic information from the Taiga Bean Goose (*Anser fabalis fabalis*), as reported by [Johnson et al. \(2018\)](#) and [AEWA \(2016\)](#). Relevant parameter values are listed in the table below.

Table 1: GMSE simulation parameter values inspired by [Johnson et al. \(2018\)](#) and [AEWA \(2016\)](#)

Parameter	Value	Description
<code>remove_pr</code>	0.122	Goose density-independent mortality probability
<code>lambda</code>	0.275	Expected offspring production per time step
<code>res_death_K</code>	93870	Goose carrying capacity (on adult mortality)
<code>RESOURCE_ini</code>	35000	Initial goose abundance
<code>manage_target</code>	70000	Manager’s target goose abundance
<code>res_death_type</code>	3	Mortality (density and density-independent sources)

Additionally, we continue to use the following values for consistency, except in the case of `stakeholders`, where we reduce the number of farmers to `stakeholders = 8`. This is done to for two reasons. First, it speeds up simulations for the purpose of demonstration; second, it makes the presentation of our custom landscape ownership easier to visualise (see below).

Table 2: Non-default GMSE parameter values chosen by authors

Parameter	Value	Description
<code>manager_budget</code>	10000	Manager’s budget for setting policy options
<code>user_budget</code>	10000	Users’ budgets for actions
<code>public_land</code>	0.4	Proportion of the landscape that is public

Parameter	Value	Description
stakeholders	8	Number of stakeholders
land_ownership	TRUE	Users own landscape cells
res_consume	0.02	Landscape cell output consumed by a resource
observe_type	3	Observation model type (survey)
agent_view	1	Cells managers can see when conducting a survey

27 All other values are set to GMSE defaults, except where specifically noted otherwise.

28 Re-creating gmse simulations using gmse_apply

29 We now recreate the simulations in [SI3](#), which were run using the `gmse` function, in `gmse_apply`. Doing
30 so requires us to first initialise simulations using one call of `gmse_apply`, then loop through multiple time
31 steps that again call `gmse_apply`; results of interest are recorded in a data frame (`sim_sum_1`). Following the
32 protocol introduced in [SI2](#), we can call the initialising simulation `sim_old`, and use the code below to read in
33 the relevant parameter values.

```
sim_old <- gmse_apply(get_res = "Full", remove_pr = 0.122, lambda = 0.275,
                     res_death_K = 93870, RESOURCE_ini = 35000,
                     manage_target = 70000, res_death_type = 3,
                     manager_budget = 10000, user_budget = 100000,
                     public_land = 0.4, stakeholders = 8, res_consume = 0.02,
                     res_birth_K = 200000, land_ownership = TRUE,
                     observe_type = 3, agent_view = 1, converge_crit = 0.01,
                     ga_mingen = 200);
```

34 Note that the argument `get_res = "Full"` causes `sim_old` to retain all of the relevant data structures for
35 simulating a new time step and recording simulation results. This includes the key simulation output, which
36 is located in `sim_old$basic_output`, which is printed below.

```
37 ## $resource_results
38 ## [1] 34298
39 ##
40 ## $observation_results
41 ## [1] 34298
42 ##
43 ## $manager_results
44 ##      resource_type scaring culling castration feeding help_offspring
45 ## policy_1          1      NA      519      NA      NA      NA
46 ##
47 ## $user_results
48 ##      resource_type scaring culling castration feeding help_offspring
49 ## Manager           1      NA       0      NA      NA      NA
50 ## user_1             1      NA     187      NA      NA      NA
51 ## user_2             1      NA     187      NA      NA      NA
52 ## user_3             1      NA     187      NA      NA      NA
53 ## user_4             1      NA     187      NA      NA      NA
54 ## user_5             1      NA     186      NA      NA      NA
55 ## user_6             1      NA     187      NA      NA      NA
56 ## user_7             1      NA     187      NA      NA      NA
57 ## user_8             1      NA     187      NA      NA      NA
58 ##      tend_crops kill_crops
```

```

59 ## Manager      NA      NA
60 ## user_1       NA      NA
61 ## user_2       NA      NA
62 ## user_3       NA      NA
63 ## user_4       NA      NA
64 ## user_5       NA      NA
65 ## user_6       NA      NA
66 ## user_7       NA      NA
67 ## user_8       NA      NA

```

We can then loop over 30 time steps to recreate the simulations from [SI3](#). In these simulations, we are specifically interested in the resource and observation outputs, as well as the manager policy and user actions for culling, which we record below in the data frame `sim_sum_1`. The inclusion of the argument `old_list` tells `gmse_apply` to use parameters and values from the list `sim_old` in the new time step.

```

sim_sum_1 <- matrix(data = NA, nrow = 30, ncol = 5);
for(time_step in 1:30){
  sim_new <- gmse_apply(get_res = "Full", old_list = sim_old);
  sim_sum_1[time_step, 1] <- time_step;
  sim_sum_1[time_step, 2] <- sim_new$basic_output$resource_results[1];
  sim_sum_1[time_step, 3] <- sim_new$basic_output$observation_results[1];
  sim_sum_1[time_step, 4] <- sim_new$basic_output$manager_results[3];
  sim_sum_1[time_step, 5] <- sum(sim_new$basic_output$user_results[,3]);
  sim_old <- sim_new;
}
colnames(sim_sum_1) <- c("Time", "Pop_size", "Pop_est", "Cull_cost",
                        "Cull_count");
print(sim_sum_1);

```

```

72 ##      Time Pop_size Pop_est Cull_cost Cull_count
73 ## [1,]    1   32552   32552     850      923
74 ## [2,]    2   31858   31858     962      817
75 ## [3,]    3   32148   32148     992      793
76 ## [4,]    4   32880   32880    1003      785
77 ## [5,]    5   36942   36942     993      793
78 ## [6,]    6   37813   37813     999      786
79 ## [7,]    7   39377   39377     992      793
80 ## [8,]    8   41191   41191    1010      778
81 ## [9,]    9   43159   43159     992      793
82 ## [10,]  10   45467   45467     999      786
83 ## [11,]  11   47967   47967     995      791
84 ## [12,]  12   50382   50382    1005      782
85 ## [13,]  13   52880   52880     999      786
86 ## [14,]  14   55727   55727    1000      786
87 ## [15,]  15   58790   58790    1002      785
88 ## [16,]  16   61875   61875     996      787
89 ## [17,]  17   65338   65338    1009      778
90 ## [18,]  18   69151   69151    1000      786
91 ## [19,]  19   72844   72844      10    29117
92 ## [20,]  20   46524   46524    1009      778
93 ## [21,]  21   48882   48882     994      792
94 ## [22,]  22   51356   51356    1000      786
95 ## [23,]  23   54149   54149     996      788
96 ## [24,]  24   57007   57007     988      794
97 ## [25,]  25   60142   60142     992      793

```

```

98 ## [26,] 26 63232 63232 996 789
99 ## [27,] 27 66920 66920 996 786
100 ## [28,] 28 70537 70537 10 29127
101 ## [29,] 29 44168 44168 1009 778
102 ## [30,] 30 46049 46049 991 793

```

The above output from `sim_sum_1` shows the data frame that holds the information we were interested in pulling out of our simulation results. All of this information was available under the list element `sim_new$basic_output`, but other list elements of `sim_new` might also be useful to record. It is important to remember that this example of `gmse_apply` is using the default resource, observation, manager, and user sub-models. Custom sub-models could produce different outputs in `sim_new` (see [SI2](#) for examples). For default sub-models, there are some list elements that might be especially useful. These elements can potentially be edited *within the above loop* to dynamically adjust simulations. For more explanation of built-in GMSE data arrays, see [SI7](#).

- `sim_new$resource_array`: A table holding all information on resources. Rows correspond to discrete resources, and columns correspond to resource properties: (1) ID, (2-4) types (not currently in use), (5) x-location, (6) y-location, (7) movement parameter, (8) time, (9) density independent mortality parameter (`remove_pr`), (10) reproduction parameter (`lambda`), (11) offspring number, (12) age, (13-14) observation columns, (15) consumption rate (`res_consume`), and (16-20) recorded experiences of user actions (e.g., was the resource culled or scared?).
- `sim_new$AGENTS`: A table holding basic information on agents (manager and users). Rows correspond to a unique agent, and columns correspond to agent properties: (1) ID, (2) type (0 for the manager, 1 for users), (3-4) additional type options not currently in use, (5-6), x and y locations (usually ignored), (7) movement parameter (usually ignored), (8) time, (9) agent's viewing ability in cells (`agent_view`), (10) error parameter, (11-12) values for holding marks and tallies of resources, (13-15) values for holding observations, (16) yield from landscape cells, (17) budget (`manager_budget` and `user_budget`).
- `sim_new$observation_vector`: Estimate of total resource number from the observation model (`observation_array` also holds this information in a different way depending on `observe_type`)
- `sim_new$LAND`: The landscape on which interactions occur, which is stored as a 3D array with `land_dim_1` rows, `land_dim_2` columns, and 3 layers. Layer 1 (`sim_new$LAND[,1]`) is not currently used in default sub-models, but could be used to store values that affect resources and agents. Layer 2 (`sim_new$LAND[,2]`) stores crop yield from a cell, and layer 3 (`sim_new$LAND[,3]`) stores the owner of the cell (value corresponds to the agent's ID).
- `sim_new$manage_vector`: The cost of each action as set by the manager. For even more fine-tuning, individual costs for the actions of each agent can be set for each user in `sim_new$manager_array`.
- `sim_new$user_vector`: The total number of actions performed by each user. A more detailed breakdown of actions by individual users is held in `sim_new$user_array`.

Next, we show how to adjust the landscape to manually set land ownership in `gmse_apply`.

1. Custom placement of user land

By default, all farmers in GMSE are allocated the same number of landscape cells, which are simply placed in order of the farmer's ID. Public land is produced by placing landscape cells that are technically owned by the manager, and therefore have landscape cell values of 1. The image below shows this landscape for the eight farmers from `sim_old`.

```
image(x = sim_old$LAND[,3], col = topo.colors(9), xaxt = "n", yaxt = "n");
```

We can change the ownership of cells by manipulating `sim_old$LAND[,3]`. First we initialise a new `sim_old` below.

```
sim_old <- gmse_apply(get_res = "Full", remove_pr = 0.122, lambda = 0.275,
                     res_d4eath_K = 93870, RESOURCE_ini = 35000,
```

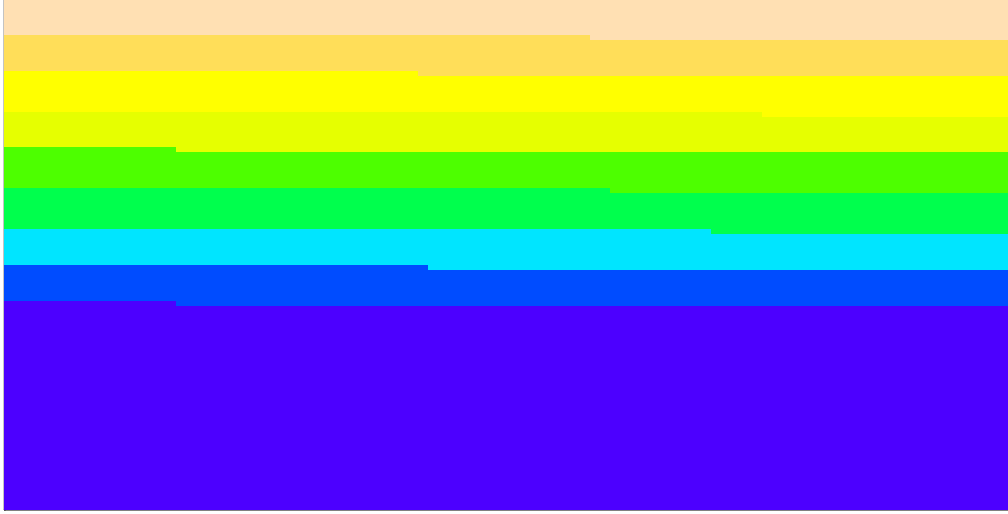


Figure 1: Default position of land ownership by farmers.

```
manage_target = 70000, res_death_type = 3,
manager_budget = 10000, user_budget = 10000,
public_land = 0.4, stakeholders = 8, res_consume = 0.02,
res_birth_K = 200000, land_ownership = TRUE,
observe_type = 3, agent_view = 1, converge_crit = 0.01,
ga_mingen = 200);
```

Because we have not specified landscape dimensions in the above, the landscape reverts to the default size of 100 by 100 cells. We can then manually assign landscape cells to the eight farmers, whose IDs range from 2-9 (ID value 1 is the manager). Below we do this to make eight different sized farms.

```
sim_old$LAND[1:20, 1:20, 3] <- 2;
sim_old$LAND[1:20, 21:40, 3] <- 3;
sim_old$LAND[1:20, 41:60, 3] <- 4;
sim_old$LAND[1:20, 61:80, 3] <- 5;
sim_old$LAND[1:20, 81:100, 3] <- 6;
sim_old$LAND[21:40, 1:50, 3] <- 7;
sim_old$LAND[21:40, 51:100, 3] <- 8;
sim_old$LAND[41:60, 1:100, 3] <- 9;
sim_old$LAND[61:100, 1:100, 3] <- 1; # Public land
image(x = sim_old$LAND[, , 3], col = topo.colors(9), xaxt = "n", yaxt = "n");
```

The above image shows the modified landscape stored in `sim_old`, which can now be incorporated into simulations using `gmse_apply`. We can think of all the plots on the left side of the landscape as farms of various sizes, while the blue area of the landscape on the right is public land.

2. Parameterisation of individual user budgets

Perhaps we want to assume that farmers have different budgets, which are correlated in some way to the number of landscape cells that they own. Custom user budgets can be set by manipulating `sim_old$AGENTS`, the last column of which (column 17) holds the budget for each user. Agent IDs (as stored on the landscape above) correspond to rows of `sim_old$AGENTS`, so individual budgets can be directly input as desired. We can do this manually (e.g., `sim_old$AGENTS[2, 17] <- 4000`), or, alternatively, if farmer budget positively

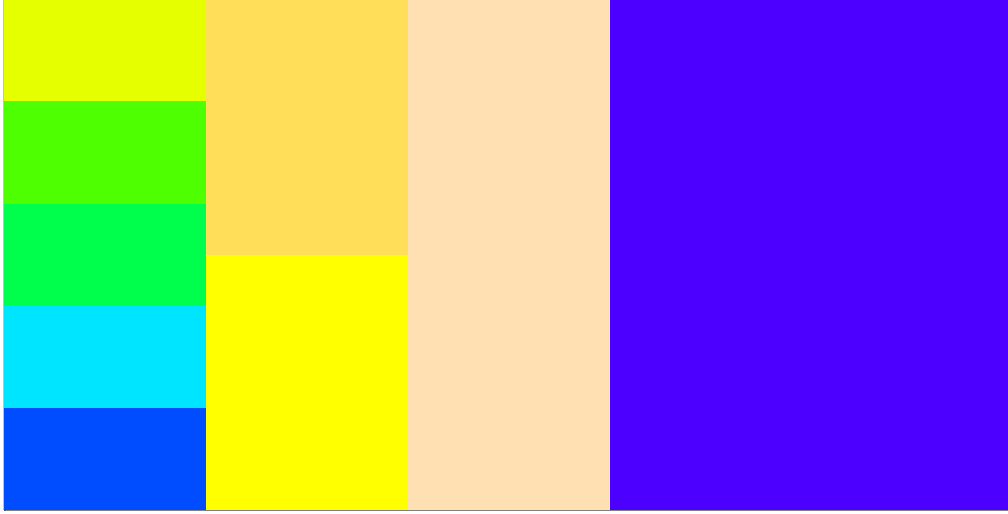


Figure 2: Land ownership by farmers as customised in `gmse_apply`.

correlates to landscape owned, we can use a loop to input values as below.

```
for(ID in 2:9){
  cells_owned      <- sum(sim_old$LAND[,3] == ID);
  sim_old$AGENTS[ID, 17] <- 10 * cells_owned;
}
```

The number of cells owned by the manager (1) and each farmer (2-8) is therefore listed in the table below.

ID	1	2	3	4	5	6	7	8	9
Budget	10000	4000	4000	4000	4000	4000	10000	10000	20000

As with `sim_old$LAND` values, changes to `sim_old$AGENTS` will be retained in simulations looped through `gmse_apply`.

3. Density-dependent movement of resources

Lastly, we consider a more nuanced change to simulations, in which the rules for movement of resources are modified to account for density-dependence. Assume that geese tend to avoid aggregating, such that if a goose is located on the same cell as too many other geese, then it will move at the start of a time step. Programming this movement rule can be accomplished by creating a new function to apply to the resource data array `sim_old$resource_array`. Below, a custom function is defined that causes a goose to move up to 5 cells in any direction if it finds itself on a cell with more than 10 other geese. As with default GMSE simulations, movement is based on a torus landscape (where no landscape edge exists, so that if resources move off of one side of the landscape they appear on the opposite side).

```

avoid_aggregation <- function(goose_table, land_dim_1 = 100, land_dim_2 = 100){
  goose_number <- dim(goose_table)[1] # How many geese are there?
  for(goose in 1:goose_number){      # Loop through all rows of geese
    x_loc <- goose_table[goose, 5];
    y_loc <- goose_table[goose, 6];
    shared <- sum(goose_table[,5] == x_loc & goose_table[,6] == y_loc);
    if(shared > 10){
      new_x <- x_loc + sample(x = -5:5, size = 1);
      new_y <- y_loc + sample(x = -5:5, size = 1);
      if(new_x < 0){ # The 'if' statements below apply the torus
        new_x <- land_dim_1 + new_x;
      }
      if(new_x >= land_dim_1){
        new_x <- new_x - land_dim_1;
      }
      if(new_y < 0){
        new_y <- land_dim_2 + new_y;
      }
      if(new_y >= land_dim_2){
        new_y <- new_y - land_dim_2;
      }
      goose_table[goose, 5] <- new_x;
      goose_table[goose, 6] <- new_y;
    }
  }
  return(goose_table);
}

```

167 With the above function written, we can apply the new movement rule along with our custom farm placement
 168 and custom farmer budgets to the simulation of goose population dynamics.

169 Simulation with custom farms, budgets, and goose movement

170 Below shows an example of gmse_apply with custom landscapes, farmer budgets, and density-dependent
 171 goose movement rules.

```

# First initialise a simulation
sim_old <- gmse_apply(get_res = "Full", remove_pr = 0.122, lambda = 0.275,
  res_death_K = 93870, RESOURCE_ini = 35000,
  manage_target = 70000, res_death_type = 3,
  manager_budget = 10000, user_budget = 10000,
  public_land = 0.4, stakeholders = 8, res_consume = 0.02,
  res_birth_K = 200000, land_ownership = TRUE,
  observe_type = 3, agent_view = 1, converge_crit = 0.01,
  ga_mingen = 200, res_move_type = 0);

# By setting `res_move_type = 0`, no resource movement will occur in gmse_apply
# Adjust the landscape ownership below
sim_old$LAND[1:20, 1:20, 3] <- 2;
sim_old$LAND[1:20, 21:40, 3] <- 3;
sim_old$LAND[1:20, 41:60, 3] <- 4;
sim_old$LAND[1:20, 61:80, 3] <- 5;
sim_old$LAND[1:20, 81:100, 3] <- 6;
sim_old$LAND[21:40, 1:50, 3] <- 7;

```

```

sim_old$LAND[21:40, 51:100, 3] <- 8;
sim_old$LAND[41:60, 1:100, 3] <- 9;
sim_old$LAND[61:100, 1:100, 3] <- 1;
# Change the budgets of each farmer based on the land they own
for(ID in 2:9){
  cells_owned <- sum(sim_old$LAND[,3] == ID);
  sim_old$AGENTS[ID, 17] <- 10 * cells_owned;
}
# Begin simulating time steps for the system
sim_sum_2 <- matrix(data = NA, nrow = 30, ncol = 5);
for(time_step in 1:30){
  # Apply the new movement rules at the beginning of the loop
  sim_old$resource_array <- avoid_aggregation(sim_old$resource_array);
  # Next, move on to simulate (old_list remembers that res_move_type = 0)
  sim_new <- gmse_apply(get_res = "Full", old_list = sim_old);
  sim_sum_2[time_step, 1] <- time_step;
  sim_sum_2[time_step, 2] <- sim_new$basic_output$resource_results[1];
  sim_sum_2[time_step, 3] <- sim_new$basic_output$observation_results[1];
  sim_sum_2[time_step, 4] <- sim_new$basic_output$manager_results[3];
  sim_sum_2[time_step, 5] <- sum(sim_new$basic_output$user_results[,3]);
  sim_old <- sim_new;
}
colnames(sim_sum_2) <- c("Time", "Pop_size", "Pop_est", "Cull_cost",
  "Cull_count");
print(sim_sum_2);

```

```

172 ##      Time Pop_size Pop_est Cull_cost Cull_count
173 ## [1,]    1   34028   34028     772        74
174 ## [2,]    2   34392   34392     893        64
175 ## [3,]    3   35556   35556     948        60
176 ## [4,]    4   37342   37342     994        59
177 ## [5,]    5   43088   43088     979        60
178 ## [6,]    6   45071   45071    1006        52
179 ## [7,]    7   47392   47392    1006        52
180 ## [8,]    8   50150   50150     993        58
181 ## [9,]    9   53412   53412    1008        52
182 ## [10,]   10   57276   57276     989        60
183 ## [11,]   11   61590   61590     988        60
184 ## [12,]   12   65871   65871     982        60
185 ## [13,]   13   70540   70540     438       132
186 ## [14,]   14   75486   75486     393       150
187 ## [15,]   15   80592   80592     440       134
188 ## [16,]   16   85830   85830     414       139
189 ## [17,]   17   91558   91558     400       147
190 ## [18,]   18   97105   97105     346       168
191 ## [19,]   19  100909  100909     390       150
192 ## [20,]   20  102198  102198     403       142
193 ## [21,]   21  102823  102823     393       150
194 ## [22,]   22  102823  102823     357       165
195 ## [23,]   23  103318  103318     382       151
196 ## [24,]   24  103465  103465     354       167
197 ## [25,]   25  103403  103403     392       150
198 ## [26,]   26  103362  103362     359       162
199 ## [27,]   27  103764  103764     395       148

```


200	## [28,]	28	103832	103832	404	142
201	## [29,]	29	103786	103786	421	138
202	## [30,]	30	103564	103564	433	135

203 Conclusions

204 In this example, we showed how the built-in resource, observation, manager, and user sub-models can be
205 customised by manipulating the data within the data structures that they use. The goal was to show how
206 software users can work with these existing sub-models and data structures to customise GMSE simulations.
207 Readers seeking even greater flexibility (e.g., replacing an entire built-in sub-model with a custom sub-model)
208 should refer to [SI2](#) that introduces `gmse_apply` more generally. Future versions of GMSE are likely to
209 expand on the built-in options available for simulation; requests for such expansions, or contributions, can be
210 submitted to [GitHub](#).

211 References

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