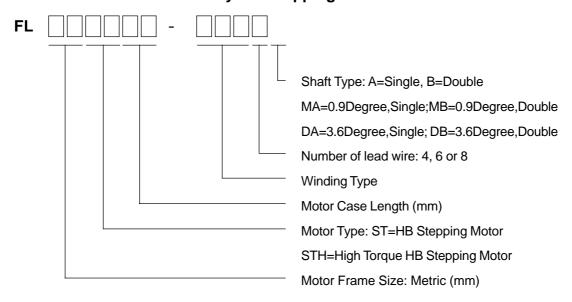
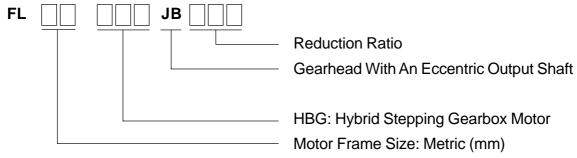


# HB Stepping Motor and HB Stepping Gearmotor

### **Product Number Code For Hybrid Stepping Motor**



### **Product Number Code For Stepping Gear motor**





### **General Specification for High Torque Hybrid Stepping Motor**

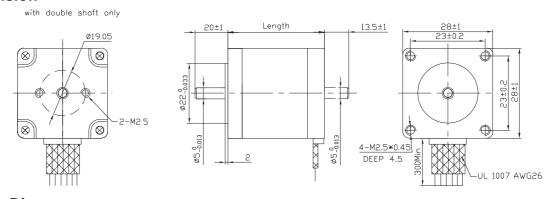
Item	Specifications
Step Angle	1.8
Step Angle Accuracy	$\pm$ 5% (full step, no load)
Resistance Accuracy	± 10%
Inductance Accuracy	± 20%
Temperature Rise	80°C Max.(rated current,2 phase on)
Ambient Temperature	-20°C~+50°C
Insulation Resistance	100M Ω Min. ,500VDC
Dielectric Strength	500VAC for one minute
Shaft Radial Play	0.02Max. (450 g-load)
Shaft Axial Play	0.08Max. (450 g-load)
Max. radial force	28N (20mm from the flange)
Max. axial force	10N
Rotation	CW( See from Front Flange)

### **Size 28mm High Torque Hybrid Stepping Motor Specifications**

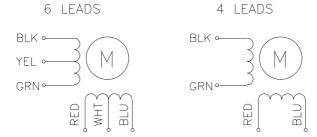
6 LEADS

Model No.		Rated	Current	Resistance	Inductance	Holding	# of	Rotor	Weight	Longth
Mod	el No.	Voltage	/Phase	/Phase	/Phase	Torque	Leads	Inertia	vveigni	Lengin
Single Shaft	Double Shaft	V	Α	Ω	mH	g. cm		kg-m²	kg	mm
FL28STH32-0956A	FL28STH32-0956B	2.66	0.95	2.8	1	430	6	9x10 <sup>-7</sup>	0.11	31.5
FL28STH32-0674A	FL28STH32-0674B	3.8	0.67	5.6	4.2	600	4	J J A 10	0	01.0
FL28STH45-0956A	FL28STH45-0956B	3.4	0.95	3.4	1.2	750	6	12x10 <sup>-7</sup>	0.14	44.5
FL28STH45-0674A	FL28STH45-0674B	4.56	0.67	6.8	4.9	950	4	12/10	0	11.0
FL28STH51-0956A	FL28STH51-0956B	4.4	0.95	4.6	1.8	900	6	18x10 <sup>-7</sup>	-7 <b>0.2</b>	50.5
FL28STH51-0674A	FL28STH51-0674B	6.2	0.67	9.2	7.2	1200	4	10210	0.2	50.5

### **Dimension**

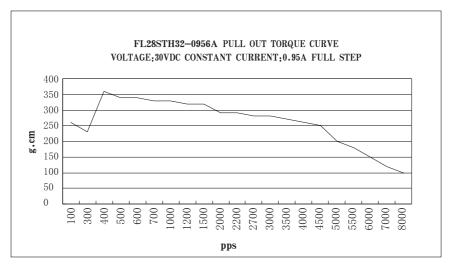


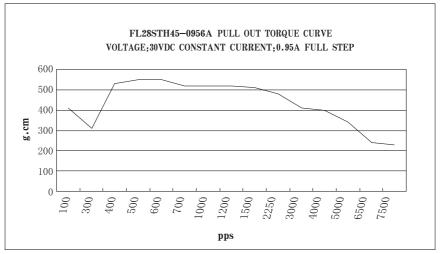
### Wiring Diagram:

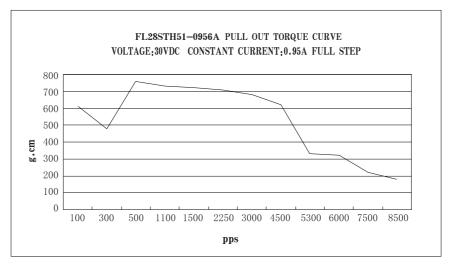




### Pull out torque:









# 1.8 Size 35mm Hybrid Stepping Motor

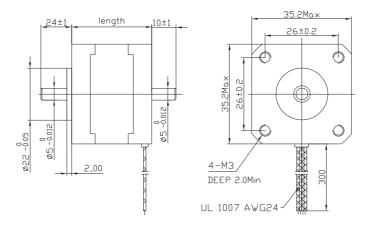
### General Specification for Hybrid Stepping Motor

Item	Specifications
Step Angle	1.8.
Step Angle Accuracy	$\pm$ 5% (full step, no load)
Resistance Accuracy	± 10%
Inductance Accuracy	± 20%
Temperature Rise	80°C Max.(rated current,2 phase on)
Ambient Temperature	-20°C~+50°C
Insulation Resistance	100M Ω Min. ,500VDC
Dielectric Strength	500VAC for one minute
Shaft Radial Play	0.02Max. (450 g-load)
Shaft Axial Play	0.08Max. (450 g-load)
Max. radial force	28N (20mm from the flange)
Max. axial force	10N
Rotation	CW( See from Front Flange)

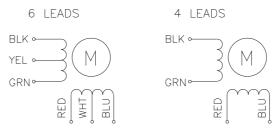
### Size 35mm Hybrid Stepping Motor Specifications

Mod	Model No.		Current	Resistance	Inductance	Holding	# of	Rotor		Detent	
IVIOU	ei No.	Voltage	/Phase	/Phase	/Phase	Torque	Leads	Inertia	Weight	Torque	Length
Single shaft	Double shaft	V	Α	Ω	mΗ	g-cm		g-cm <sup>2</sup>	kg	g-cm	m m
FL35ST22-0804A	FL35ST22-0804B	3.2	0.8	4	2.3	500	4	8	0.10	60	22
FL35ST26-0284A	FL35ST26-0284B	7.4	0.28	26	19.2	650	4	10	0.13	60	26
FL35ST28-0504A	FL35ST28-0504B	10	0.5	20	13.5	1000	4	10	0.14	80	28
FL35ST28-0406A	FL35ST28-0406B	11.2	0.4	28	10	500	6	10	0.14	00	20
FL35ST36-0704A	FL35ST36-0704B	1.4	0.7	2	2.9	920	4	14	0.18	100	36
FL35ST36-1004A	FL35ST36-1004B	2.7	1.0	2.7	4.3	1400	4	14	0.10	100	30

### Dimension



### Wiring Diagram



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# 1.8 Size 39mm Hybrid Stepping Motor

### General Specification for Hybrid Stepping Motor

Item	Specifications
Step Angle	1.8.
Step Angle Accuracy	$\pm$ 5% (full step, no load)
Resistance Accuracy	± 10%
Inductance Accuracy	± 20%
Temperature Rise	80°C Max.(rated current,2 phase on)
Ambient Temperature	-20°C~+50°C
Insulation Resistance	100M Ω Min. ,500VDC
Dielectric Strength	500VAC for one minute
Shaft Radial Play	0.02Max. (450 g-load)
Shaft Axial Play	0.08Max. (450 g-load)
Max. radial force	28N (20mm from the flange)
Max. axial force	10N
Rotation	CW( See from Front Flange)

### Size 39mm Hybrid Stepping Motor Specifications

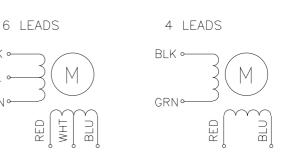
Mode	Model No.		Current	Resistance	Inductance	Holding	# of	Rotor	144 . 14	Detent	
Iviode	I INO.	Voltage	/Phase	/Phase	/Phase	Torque	Leads	Inertia	Weight	Torque	Length
Single shaft	Double shaft	V	Α	Ω	тН	g-cm		g-cm <sup>2</sup>	kg	g-cm	mm
FL39ST20-0404A	FL39ST20-0404B	2.64	0.4	6.6	7.5	650	4	11	0.12	50	20
FL39ST20-0506A	FL39ST20-0506B	6.5	0.5	13	7.5	800	6				
FL39ST34-0654A	FL39ST34-0654B	4.55	0.65	7.0	9.3	1800	4				
FL39ST34-0404A	FL39ST34-0404B	12	0.4	30	32	2100	4	20	0.18	120	34
FL39ST34-0604A	FL39ST34-0604B	9	0.6	15	16	2200	4	20	0.10		34
FL39ST34-0306A	FL39ST34-0306B	12	0.3	40	20	1300	6				
FL39ST34-0166A	FL39ST34-0166B	12	0.16	75	50	1100	6				
FL39ST38-0504A	FL39ST38-0504B	12	0.5	24	45	2900	4	24	0.2	180	38
FL39ST38-0806A	FL39ST38-0806B	6	0.8	7.5	6	2000	6	24	0.2	100	50
FL39ST44-0304A	FL39ST44-0304B	12	0.3	40	100	2800	4	40	0.25	250	44

#### Dimension

9

### 39.3Max 39.3Max 31±0.2 31±0.2 30+1E 2,00 4-M3 DEEP 4.5Min UL 1007 AWG24

### **Wiring Diagram**



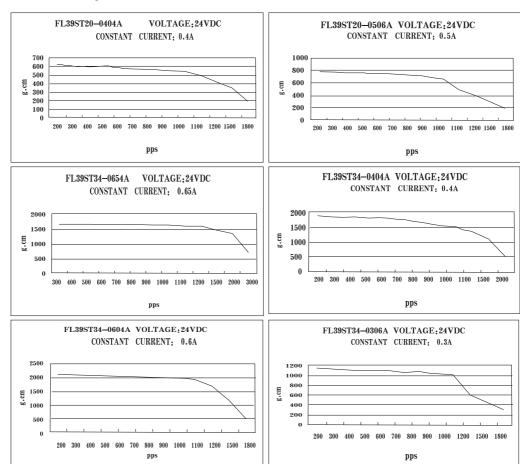
TEL: +44(0) 1202 599922 Email: sales@motioncontrolproducts.com FAX: +44(0) 1202 599955 Home Page: www.motioncontrolproducts.com

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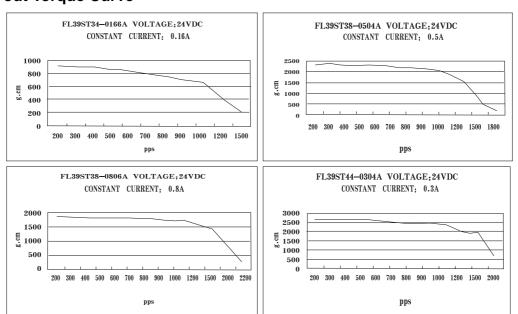


# 1.8 Size 39mm Hybrid Stepping Motor

# Pull out Torque Curve



### Pull out Torque Curve





### General Specification for High Torque Hybrid Stepping Motor

Item	Specifications
Step Angle	0.9.
Step Angle Accuracy	$\pm$ 5% (full step, no load)
Resistance Accuracy	± 10%
Inductance Accuracy	± 20%
Temperature Rise	80°C Max.(rated current,2 phase on)
Ambient Temperature	-20°C~+50°C
Insulation Resistance	100M $\Omega$ Min. ,500VDC
Dielectric Strength	500VAC for one minute
Shaft Radial Play	0.02Max. (450 g-load)
Shaft Axial Play	0.08Max. (450 g-load)
Max. radial force	28N (20mm from the flange)
Max. axial force	10N
Rotation	CW( See from Front Flange)

### Size 42mm High Torque Hybrid Stepping Motor Specifications

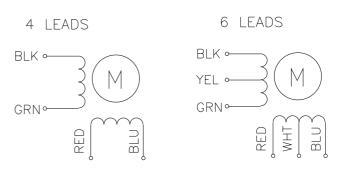
Mode	Model No.		Current	Resistance	Inductance	Holding	# of	Rotor	\\/a:= at	Detent	Operating	l ava avtla	
l wied	51140.	Voltage	/Phase	/Phase	/Phase	Torque	Leads	Inertia	Weight	Torque	Curve	Length	
Single Shaft	Double Shaft	V	Α	Ω	mH	Kg-cm		g-cm <sup>2</sup>	kg	g-cm		mm	
FL42STH33-0956MA	FL42STH33-0956MB	4	0.95	4.2	4						а		
FL42STH33-0606MA	FL42STH33-0606MB	6	0.6	10	9.5	1.58	6	35	0.22	200	b	33	
FL42STH33-0316MA	FL42STH33-0316MB	12	0.31	38.5	33				0.22		С		
FL42STH33-1334MA	FL42STH33-1334MB	2.8	1.33	2.1	4.2	2.2	4				d		
FL42STH38-1206MA	FL42STH38-1206MB	4	1.2	3.3	3.2						е		
FL42STH38-0806MA	FL42STH38-0806MB	6	0.8	7.5	6.7	2.59	6		0.00	000	f	38	
FL42STH38-0404MA	FL42STH38-0404MB	12	0.4	30	30			54	0.28	220	g		
FL42STH38-1684MA	FL42STH38-1684MB	2.8	1.68	1.65	3.2	3.6	4				h		
FL42STH47-1206MA	FL42STH47-1206MB	4	1.2	3.3	4						i		
FL42STH47-0806MA	FL42STH47-0806MB	6	0.8	7.5	6.3	3.17	6 68	68	0.35	250	j	47	
FL42STH47-0406MA	FL42STH47-0406MB	12	0.4	30	38			- 00	0.33	250	k	] "	
FL42STH47-1684MA	FL42STH47-1684MB	2.8	1.68	1.65	4.1	4.4	4				I		

### Dimension

11

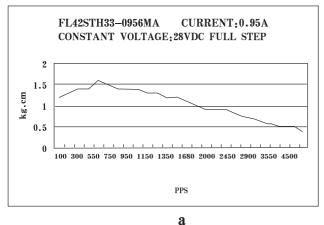
# 24±1 length 10±1 31±0.2 31±0.2 31±0.2 4-M3 DEEP 4.5Min UL 1007 AWG24

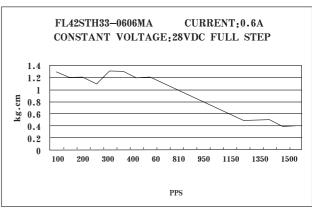
### **Wiring Diagram**





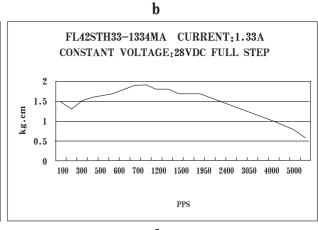
### Pull out Torque Curve





FL42STH33-0316MA CURRENT: 0.31A CONSTANT VOLTAGE: 24VDC FULL STEP ₩ 0.6 0.4 0.2 100 300 900 1100 1350 1500 1750 1900 2300 PPS

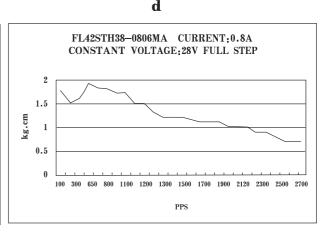
C



FL42STH38-1206MA CURRENT;1.2A
CONSTANT VOLTAGE;28V FULL STEP

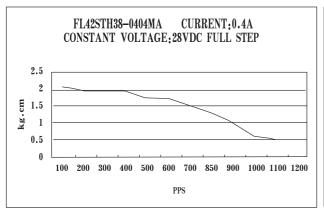
2
5
1.5
2
1
0.5
0
100 350 1000 1400 1600 1900 2300 2750 3500 5000 7000

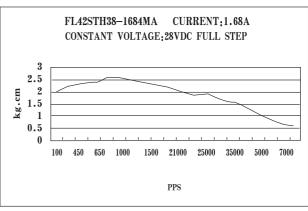
PPS



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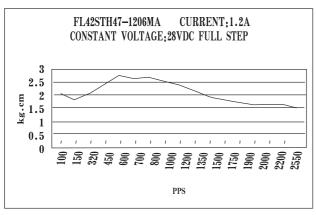


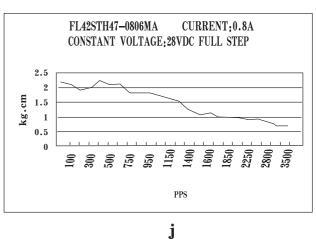




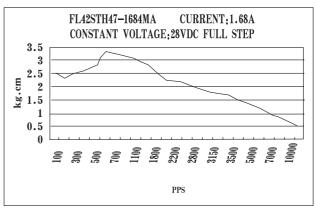
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### Pull out Torque Curve





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### • General Specification for High Torque Hybrid Stepping Motor

Item	Specifications
Step Angle	1.8
Step Angle Accuracy	$\pm$ 5% (full step, no load)
Resistance Accuracy	± 10%
Inductance Accuracy	± 20%
Temperature Rise	80°C Max.(rated current,2 phase on)
Ambient Temperature	-20°C~+50°C
Insulation Resistance	100M Ω Min. ,500VDC
Dielectric Strength	500VAC for one minute
Shaft Radial Play	0.02Max. (450 g-load)
Shaft Axial Play	0.08Max. (450 g-load)
Max. radial force	28N (20mm from the flange)
Max. axial force	10N
Rotation	CW( See from Front Flange)

### Size 42mm High Torque Hybrid Stepping Motor Specifications

42.3Ma.x

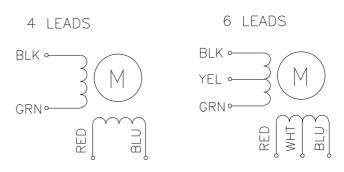
NAI-	.I.N.I	Rated	Current	Resistance	Inductance	Holding	# of	Rotor		Detent	
Mode	el No.	Voltage	/Phase	/Phase	/Phase	Torque	Leads	Inertia	Weight	Torque	Length
Single Shaft	Double Shaft	V	Α	Ω	mH	Kg-cm		g-cm²	kg	g-cm	mm
FL42STH25-0404A	FL42STH25-0404B	9.6	0.4	24	36	1.7	4	20	0.15	200	25
FL42STH33-0404A	FL42STH34-0404B	12	0.4	30	37	2.5	4		0.2		
FL42STH33-0956A	FL42STH34-0956B	3.99	0.95	4.2	2.8	4.0	6	38		120	34
FL42STH33-0476A	FL42STH34-0476B	6.392	0.47	13.6	9.8	1.6					
FL42STH38-0406A	FL42STH38-0406B	12	0.4	30	24	2.5	6			150	40
FL42STH38-0804A	FL42STH38-0804B	8	0.8	10	17	3.2	4		0.24		
FL42STH38-1206A	FL42STH38-1206B	3.96	1.2	3.3	2.4	2.4	•	57			
FL42STH38-0806A	FL42STH38-0806B	6.0	0.8	7.5	7.0	2.8	6				
FL42STH47-1006A	FL42STH48-1006B	4.6	1.0	4.6	4.0	3.4	•				
FL42STH47-0406A	FL42STH48-0406B	12	0.4	30	28	3.8	6	00			48
FL42STH47-1204A	FL42STH48-1204B	3.84	1.2	3.2	6.0	4.5		82	0.34	200	
FL42STH47-0854A	FL42STH48-0854B	5.61	0.85	6.6	11	4.5	4				

### Dimension

# 24±1 length 10±1 31±0.2

UL 1007 AWG24-

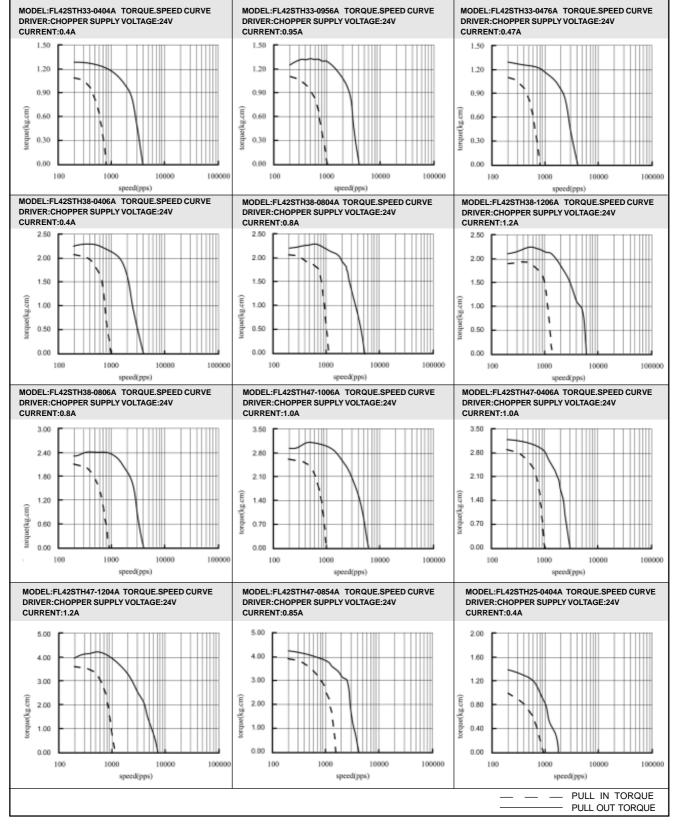
### **Wiring Diagram**





### Pull out Torque Curve 42sth

#### SERIES MOTOR DYNAMIC CHARACTERISTICS





### 1.8 Size 42mm High Torque Hybrid Stepping Motor With Thread Shaft

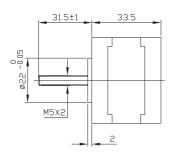
### • General Specification for High Torque Hybrid Stepping Motor With Thread

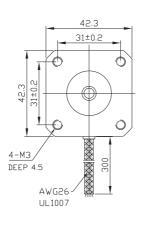
Item	Specifications
Step Angle	1.8
Step Angle Accuracy	$\pm$ 5% (full step, no load)
Resistance Accuracy	± 10%
Inductance Accuracy	± 20%
Temperature Rise	80°C Max.(rated current,2 phase on)
Ambient Temperature	-20°C~+50°C
Insulation Resistance	100M Ω Min. ,500VDC
Dielectric Strength	500VAC for one minute
Shaft Radial Play	0.02Max. (450 g-load)
Shaft Axial Play	0.08Max. (450 g-load)
Max. radial force	28N (20mm from the flange)
Max. axial force	10N
Rotation	CW( See from Front Flange)

### • Size 42mm High Torque Hybrid Stepping Motor Specifications With Thread

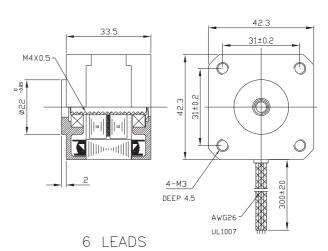
Model No.		Current /Phase	Resistance /Phase	Inductance /Phase	Holding Torque	# of Leads	Rotor Inertia	Weight	Detent Torque	Length
Single Shaft	V	Α	Ω	mΗ	g-cm		g-cm²	kg	g-cm	m m
FL42STH33T-0554A	1.8	0.55	3.2	4.5	900	4	35	0.2	120	34
FL42STH33S-0956A	4.0	0.95	4.2	2.5	1580	6	35	0.2	120	34

### Dimension

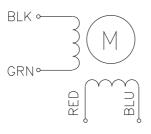


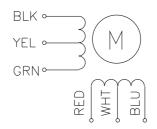


4 LEADS



### Wiring Diagram





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# 3.6 Size 42mm Hybrid Stepping Motor

### General Specification for High Torque Hybrid Stepping Motor

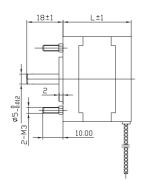
Item	Specifications
Step Angle	3.6
Step Angle Accuracy	$\pm$ 5% (full step, no load)
Resistance Accuracy	± 10%
Inductance Accuracy	± 20%
Temperature Rise	80°CMax.(rated current,2 phase on)
Ambient Temperature	-20°C~+50°C
Insulation Resistance	100M Ω Min. ,500VDC
Dielectric Strength	500VAC for one minute
Shaft Radial Play	0.02Max. (450 g-load)
Shaft Axial Play	0.08Max. (450 g-load)
Max. radial force	28N (20mm from the flange)
Max. axial force	10N
Rotation	CW( See from Front Flange)

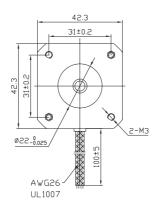
### Size 42mm Hybrid Stepping Motor Specifications

Mod	el No.		Current /Phase	Resistance /Phase	Inductance /Phase	Holding Torque	# of Leads	Rotor Inertia	Weight	Detent Torque	Length
Single Shaft	Double Shaft	V	A	Ω	mH	g-cm	Loudo	g-cm <sup>2</sup>	kg	g-cm	mm
FL42ST34-0954DA	FL42ST34-0954DB	9.31	0.095	98	200	530	4	20	0.20	150	34
FL42ST38-0954DA	FL42ST38-0954DB	9.98	0.095	105	330	700	4	23	0.23	150	38

### Dimension

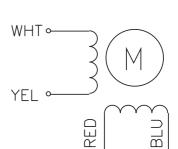
17



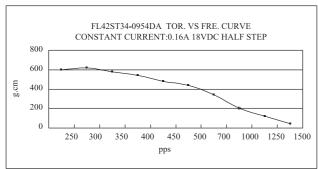


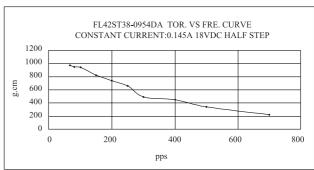
### **Wiring Diagram:**

4 LEADS



### Pull out Torque Curve:







## General Specification for High Torque Hybrid Stepping Motor

Item	Specifications
Step Angle	0.9°
Step Angle Accuracy	$\pm$ 5% (full step, no load)
Resistance Accuracy	± 10%
Inductance Accuracy	± 20%
Temperature Rise	80°C Max.(rated current,2 phase on)
Ambient Temperature	-20°C~+50°C
Insulation Resistance	100M Ω Min. ,500VDC
Dielectric Strength	500VAC for one minute
Shaft Radial Play	0.02Max. (450 g-load)
Shaft Axial Play	0.08Max. (450 g-load)
Max. radial force	75N (20mm from the flange)
Max. axial force	15N
Rotation	CW( See from Front Flange)

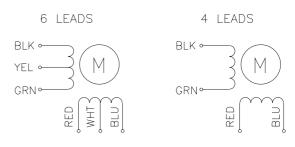
### Size 57mm High Torque Hybrid Stepping Motor Specifications

Mad	Model No.		Current	Resistance	Inductance	Holding	# of	Rotor	\A/=:=l=4		Operating	
IVIOG	ei No.	Voltage	/Phase	/Phase	/Phase	Torque	Leads	Inertia	Weight	Torque	Curve	Length
Single Shaft	Double Shaft	V	Α	Ω	mH	kg-cm		g-cm <sup>2</sup>	kg	kg-cm		mm
FL57STH39-1006MA	FL57STH39-1006MB	5.7	1	5.7	5.4						a	
FL57STH39-2006MA	FL57STH39-2006MB	2.8	2	1.4	1.4	3.9	6	400	0.45	0.04	b	20
FL57STH39-3006MA	FL57STH39-3006MB	1.9	3	0.63	0.6			120	0.45	0.21	С	39
FL57STH39-2804MA	FL57STH39-2804MB	2	2.8	0.7	1.4	5.5	4				d	
FL57STH56-1006MA	FL57STH56-1006MB	7.4	1	7.4	10				0.7	0.4	е	56
FL57STH56-2006MA	FL57STH56-2006MB	3.6	2	1.8	2.5	9.0	6	200			f	
FL57STH56-3006MA	FL57STH56-3006MB	2.3	3	0.75	1.1			300	0.7		g	
FL57STH56-2804MA	FL57STH56-2804MB	2.5	2.8	0.9	2.5	12.6	4				h	
FL57STH76-1006MA	FL57STH76-1006MB	8.6	1	8.6	14						i	
FL57STH76-2006MA	FL57STH76-2006MB	4.5	2	2.25	3.6	13.5	13.5 6	400		0.68	j	70
FL57STH76-3006MA	FL57STH76-3006MB	3	3	1	1.6			480	1		k	76
FL57STH76-2804MA	FL57STH76-2804MB	3.2	2.8	1.13	3.6	18.9	4				I	

### Dimension

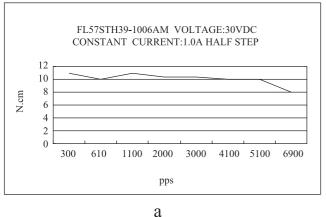
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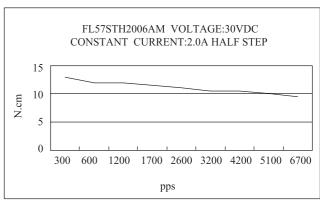
### **Wiring Diagram**





### Pull out Torque Curve

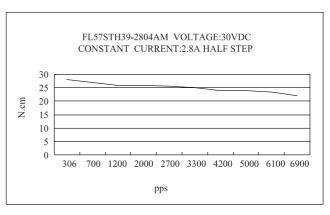




FL57STH39-3006AM VOLTAGE:30VDC CONSTANT CURRENT:3.0A HALF STEP

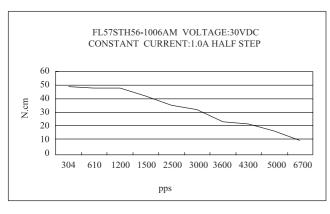
15
10
5
0
300 730 1200 2100 3200 4100 5400 6700

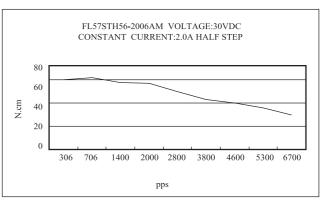
pps



b

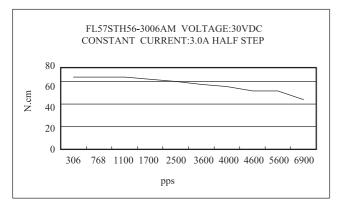
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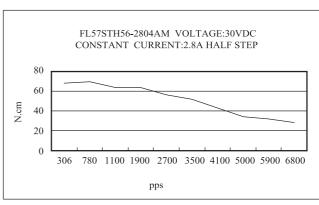


e f



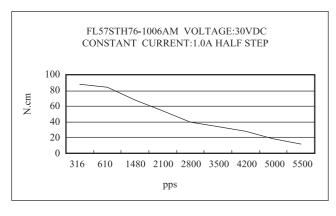


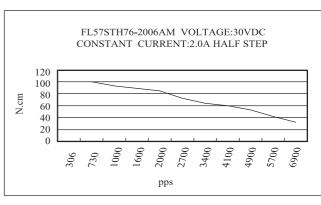
g



h

### Pull out Torque Curve

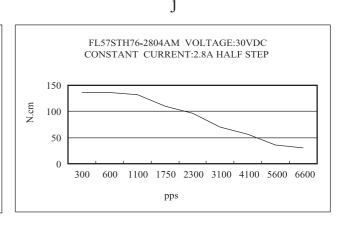




FL57STH76-3006AM VOLTAGE:30VDC CONSTANT CURRENT:3.0A HALF STEP

120
100
8 80
2 60
40
20
0 309 700 1400 1970 2500 3200 4100 5000 5900 6700
pps

i



k 1



# 1.8 Size 57mm Hybrid Stepping Motor

### General Specification for Hybrid Stepping Motor

Item	Specifications
Step Angle	1.8°
Step Angle Accuracy	$\pm$ 5% (full step, no load)
Resistance Accuracy	± 10%
Inductance Accuracy	± 20%
Temperature Rise	80°C Max.(rated current,2 phase on)
Ambient Temperature	-20°C~+50°C
Insulation Resistance	100M Ω Min. ,500VDC
Dielectric Strength	500VAC for one minute
Shaft Radial Play	0.02Max. (450 g-load)
Shaft Axial Play	0.08Max. (450 g-load)
Max. radial force	75N (20mm from the flange)
Max. axial force	15N
Rotation	CW( See from Front Flange)

### • Size 57mm Hybrid Stepping Motor Specifications

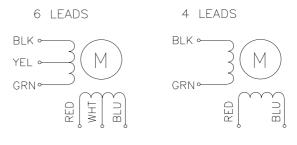
Mode	al Nie	Rated	Current	Resistance	Inductance	Holding	# of	Rotor		Detent	
IVIOGE	el No.	Voltage	/Phase	/Phase	/Phase	Torque	Leads	Inertia	Weight	Torque	Length
Single Shaft	Double Shaft	V	Α	Ω	mН	kg-cm		g-cm²	kg	kg-cm	mm
FL57ST41-1106A	FL57ST41-1106B	4	1.1	3.6	3.6	2.88	6				
FL57ST41-0406A	FL57ST41-0406B	12	0.4	30	30	2.00	0	57	0.54	0.18	41
FL57ST41-1564A	FL57ST41-1564B	2.8	1.56	1.8	3.6	4.0	4				
FL57ST51-0856A	FL57ST51-0856B	6	0.85	7.1	9	4.97	6		0.60	0.35	
FL57ST51-0426A	FL57ST51-0426B	12	0.42	29	36	4.97	0	110			51
FL57ST51-2804A	FL57ST51-2804B	1.8	2.8	0.65	1.6	6.9	4				
FL57ST56-1206A	FL57ST56-1206B	6	1.2	5	8	6.05	6				
FL57ST56-0606A	FL57ST56-0606B	12	0.6	20	32	0.05	0	135	0.65	0.42	56
FL57ST56-2554A	FL57ST56-2554B	2.8	2.55	1.1	3.6	8.4	4				
FL57ST76-1506A	FL57ST76-1506B	5.4	1.5	3.6	6	9	6		0.95	0.72	76
FL57ST76-0686A	FL57ST76-0686B	12	0.68	17.7	30	9	0	200			
FL57ST76-3304A	FL57ST76-3304B	2.7	3.3	0.85	3	2.5	4				

### Dimension

21

# 

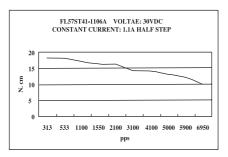
### **Wiring Diagram**

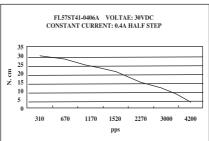


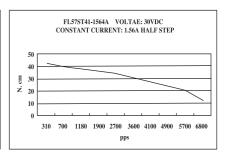


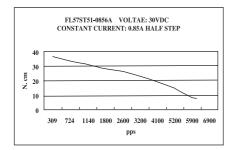
# 1.8 Size 57mm Hybrid Stepping Motor

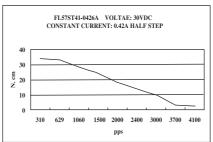
### Pull out Torque Curve

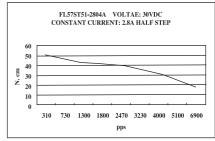


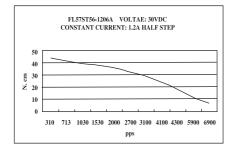


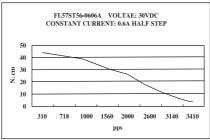


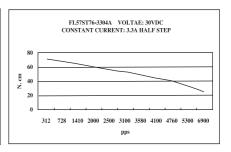


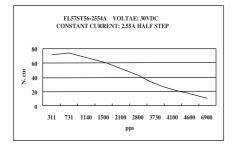


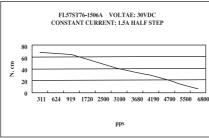


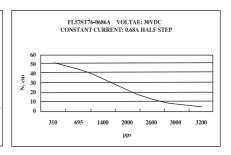














# General Specification for High Torque Hybrid Stepping Motor

Item	Specifications
Step Angle	1.8 ⋅
Step Angle Accuracy	$\pm$ 5% (full step, no load)
Resistance Accuracy	± 10%
Inductance Accuracy	± 20%
Temperature Rise	80°CMax.(rated current,2 phase on)
Ambient Temperature	-20°C~+50°C
Insulation Resistance	100M Ω Min. ,500VDC
Dielectric Strength	500VAC for one minute
Shaft Radial Play	0.02Max. (450 g-load)
Shaft Axial Play	0.08Max. (450 g-load)
Max. radial force	75N (20mm from the flange)
Max. axial force	15N
Rotation	CW( See from Front Flange)

### Size 57mm High Torque Hybrid Stepping Motor Specifications

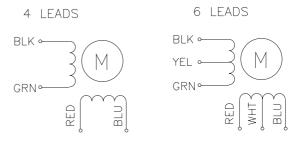
Mad	al Na	Rated	Current	Resistance	Inductance	Holding	# of	Rotor	\\/-:l-4	Detent	l au autla
IVIOG	el No.	Voltage	/Phase	/Phase	/Phase	Torque	Leads	Inertia	Weight	Torque	Length
Single Shaft	Double Shaft	V	Α	Ω	mH	kg-cm		g-cm²	kg	kg-cm	mm
FL57STH41-1006A	FL57STH41-1006B	5.7	1	5.7	5.4						
FL57STH41-2006A	FL57STH41-2006B	2.8	2	1.4	1.4	3.9	6	120	0.45	0.21	41
FL57STH41-3006A	FL57STH41-3006B	1.9	3	0.63	0.6						
FL57STH41-2804A	FL57STH41-2804B	2	2.8	0.7	1.4	5.5	4				
FL57STH51-1006A	FL57STH51-1006B	6.6	1	6.6	8.2			275		0.36	
FL57STH51-2006A	FL57STH51-2006B	3.3	2	1.65	2.2	7.2	6		0.65		51
FL57STH51-3006A	FL57STH51-3006B	2.2	3	0.74	0.9						01
FL57STH51-2804A	FL57STH51-2804B	2.3	2.8	0.83	2.2	10.1	4				
FL57STH56-1006A	FL57STH56-1006B	7.4	1	7.4	10						
FL57STH56-2006A	FL57STH56-2006B	3.6	2	1.8	2.5	9.0	6	300	0.7	0.4	56
FL57STH56-3006A	FL57STH56-3006B	2.3	3	0.75	1.1			000	0.7	0.4	
FL57STH56-2804A	FL57STH56-2804B	2.5	2.8	0.9	2.5	12.6	4				
FL57STH76-1006A	FL57STH76-1006B	8.6	1	8.6	14						
FL57STH76-2006A	FL57STH76-2006B	4.5	2	2.25	3.6	13.5	6	480	1	0.68	76
FL57STH76-3006A	FL57STH76-3006B	3	3	1	1.6			400	'	0.68	'0
FL57STH76-2804A	FL57STH76-2804B	3.2	2.8	1.13	3.6	18.9	4				ı

### Dimension

23

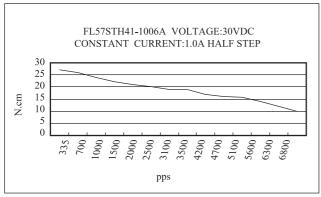
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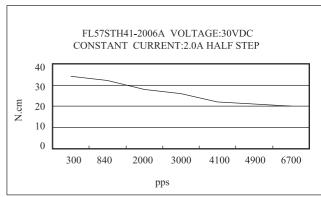
### **Wiring Diagram**

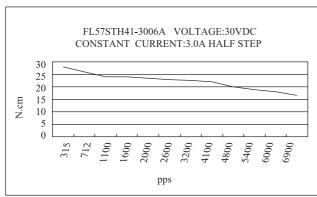


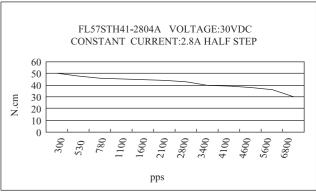


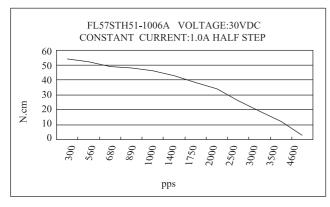
### Pull out Torque Curve

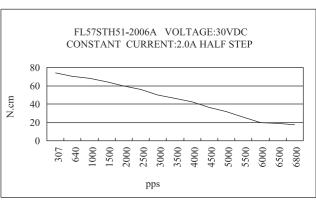


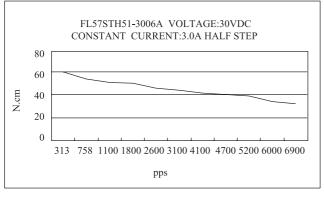


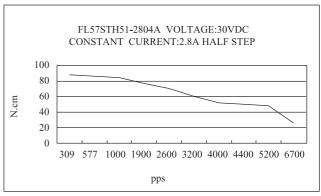






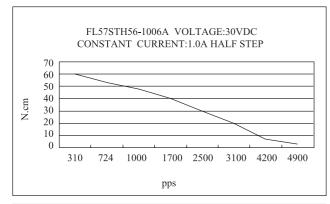


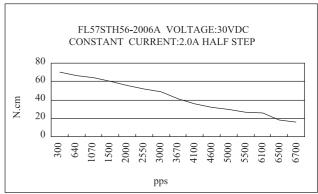


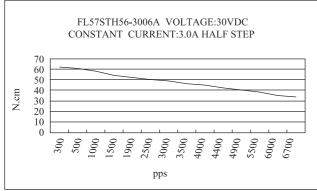


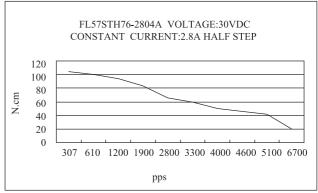


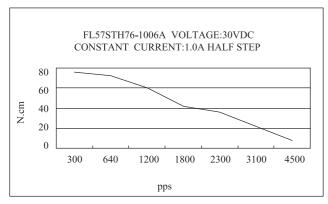
### Pull out Torque Curve

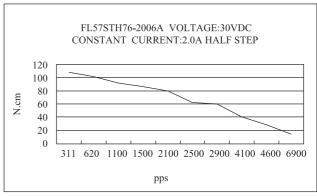


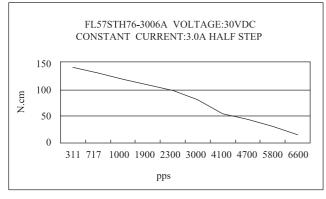


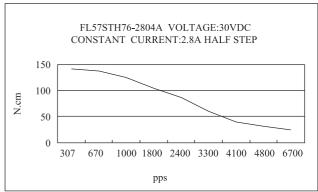














# 1.8 Size 86mm Hybrid Stepping Motor

# General Specification for Hybrid Stepping Motor

Item	Specifications
Step Angle	1.8-
Step Angle Accuracy	$\pm$ 5% (full step, no load)
Resistance Accuracy	± 10%
Inductance Accuracy	± 20%
Temperature Rise	80°C Max.(rated current,2 phase on)
Ambient Temperature	-20°C~+50°C
Insulation Resistance	100M <sup>Ω</sup> Min. ,500VDC
Dielectric Strength	500VAC for one minute
Shaft Radial Play	0.02Max. (450 g-load)
Shaft Axial Play	0.08Max. (450 g-load)
Max. radial force	220N (20mm from the flange)
Max. axial force	60N
Rotation	CW( See from Front Flange)

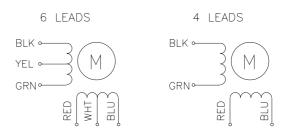
### • Size 86mm High Torque Hybrid Stepping Motor Specifications

Model No.		Rated	Current	Resistance	Inductance	Holding	# of	Rotor		Detent	
Wiod	CITYO.	Voltage	/Phase	/Phase	/Phase	Torque	Leads	Inertia	Weight	Torque	Length
Single Shaft	Double Shaft	V	Α	Ω	mН	Kg.cm		g-cm <sup>2</sup>	kg	kg-cm	mm
FL86ST62-4506A	FL86ST62-4506B	1.8	4.5	0.4	1.4	13	6				
FL86ST62-1256A	FL86ST62-1256B	5.5	1.25	4.4	14	13	6	FC0	4.5	0.0	60
FL86ST62-1406A	FL86ST62-1406B	0.7	14	20	60	13	6	560	1.5	0.8	62
FL86ST62-5904A	FL86ST62-5904B	1.33	5.9	0.23	1.5	18	4				
FL86ST94-4006A	FL86ST94-4006B	3.0	4.0	0.75	4.5	26	6			2.4	
FL86ST94-2006A	FL86ST94-2006B	6.0	2.0	3.0	18	26	6	4400	2.6		94
FL86ST94-1006A	FL86ST94-1006B	12	1	12	72	26	6	1100	2.6		94
FL86ST94-5606A	FL86ST94-5606B	2.1	5.6	0.38	3.9	35	4				
FL86ST134-6706A	FL86ST134-6706B	3.0	6.7	0.45	2	36	6				
FL86ST134-4006A	FL86ST134-4006B	5.0	4.0	1.25	6.6	36	6	1800	3.6	26	124
FL86ST134-1806A	FL86ST134-1806B	12	1.8	6.5	41	36	6	1000	3.0	3.6	134
FL86ST134-5606A	FL86ST134-5606B	3.5	5.6	0.63	6.6	50	4				

### Dimension

# 

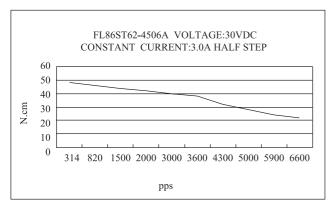
### **Wiring Diagram**

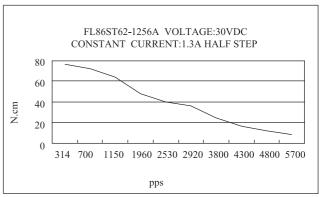


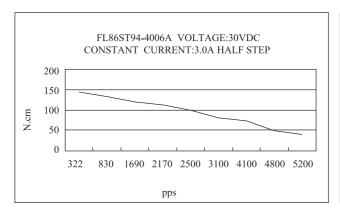


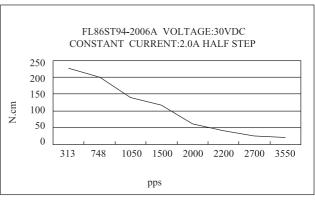
# 1.8 Size 86mm Hybrid Stepping Motor

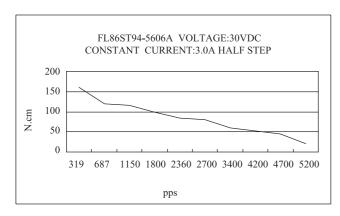
### Pull out Torque Curve

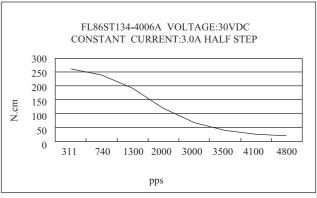














### General Specification for High Torque Hybrid Stepping Motor

Item	Specifications
Step Angle	1.8
Step Angle Accuracy	$\pm$ 5% (full step, no load)
Resistance Accuracy	± 10%
Inductance Accuracy	± 20%
Temperature Rise	80°CMax.(rated current,2 phase on)
Ambient Temperature	-20°C~+50°C
Insulation Resistance	100M <sup>Ω</sup> Min. ,500VDC
Dielectric Strength	500VAC for one minute
Shaft Radial Play	0.02Max. (450 g-load)
Shaft Axial Play	0.08Max. (450 g-load)
Max. radial force	220N (20mm from the flange)
Max. axial force	60N
Rotation	CW( See from Front Flange)

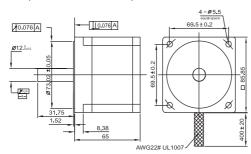
### Size 86mm High Torque Hybrid Stepping Motor Specifications

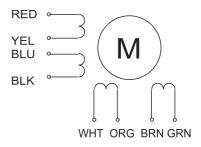
Model No.		Rated	Current	Resistance	Inductance	Holding	# of	Rotor		Detent	
		Voltage	/Phase	/Phase	/Phase	Torque	Leads	Inertia	Weight	Torque	Length
Single Shaft	Double Shaft	V	Α	Ω	mН	Kg.cm		g-cm <sup>2</sup>	kg	kg-cm	mm
FL86STH65-5904A	FL86STH65-5904B	1.652	5.9	0.28	1.7	34	4 parallel				
FL86STH65-3004A	FL86STH65-3004B	4.2	3	1.14	6.8	34	4 series	1000	1.7	0.8	65
FL86STH65-4206A	FL86STH65-4206B	2.394	4.2	0.57	1.7	26	6 unipolar				
FL86STH80-5504A	FL86STH80-5504B	2.3	5.5	0.42	3.5	46	4	1400	2.3	1.2	80
FL86STH118-6004A	FL86STH118-6004B	2.7	6	0.45	5.1	87	4	2700	3.8	2.4	118
FL86STH156-6204A	FL86STH156-6204B	3.5	6.2	0.56	6.4	128	4	4000	5.4	3.6	156
FL86STH195-8504A	FL86STH195-8504B	2.8	8.5	0.33	4.7	153	4	5300	6.9	4	195

### Dimension

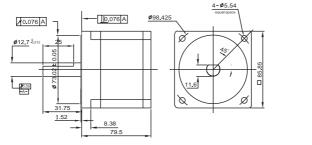
### **Wiring Diagram**







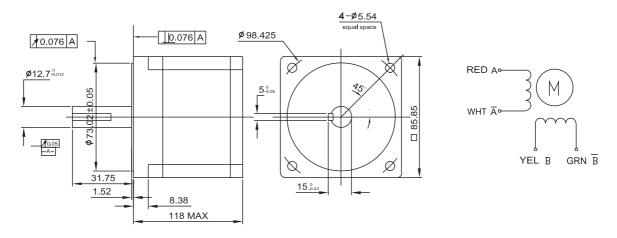
FL86STH80-5504A



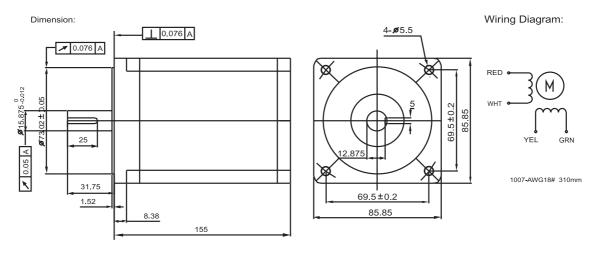




#### FL86STH118-6004A

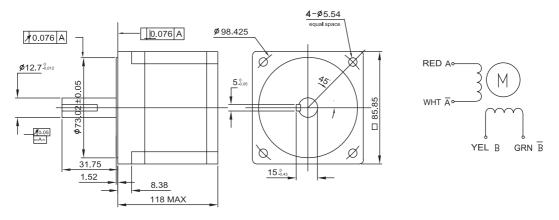


### FL86STH156-6204A



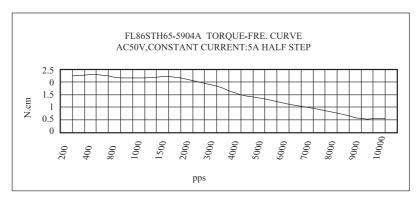
#### FL86STH195-8504A

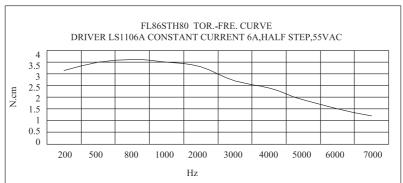
29

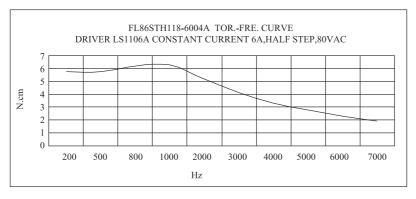


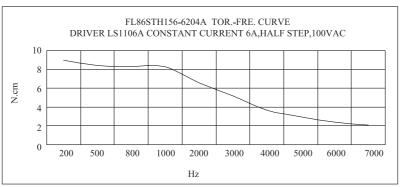


## Pull out Torque Curve











# 3-Phase Size 86mm Hybrid Stepping Motor

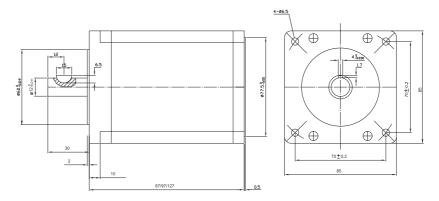
## General Specification for High Torque Hybrid Stepping Motor

Item	Specifications
Step Angle	1.8°, 0.9°, 0.72°, 0.36°
Step Angle Accuracy	$\pm$ 5% (full step, no load)
Resistance Accuracy	± 10%
Inductance Accuracy	± 20%
Temperature Rise	125°CMax.
Ambient Temperature	-20°C~+50°C
Insulation Resistance	100M Ω Min. ,500VDC
Dielectric Strength	2200VAC for one second
Shaft Radial Play	0.02Max. (450 g-load)
Shaft Axial Play	0.08Max. (450 g-load)
Max. radial force	220N (20mm from the flange)
Max. axial force	60N

### Specification

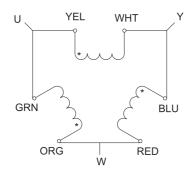
	Voltage/	Current	Resistance	Inductance	Holding	# of	Rotor	144 : 14
Model No.	Phase	/Phase	/Phase	/Phase	Torque	Leads	Inertia	Weight
Single shaft	VAC	Α	Ω	mΗ	N.m		g-cm <sup>2</sup>	kg
FL863P67-01		1.75	4.25	12.3	2.26		1100	1.65
FL863P97-01	325	2	5.4	23	4.52	6	2200	2.7
FL863P127-01		2.25	9	41	6.78		3300	3.8

### Dimension



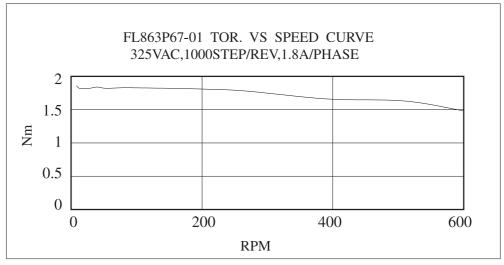
### Wiring Diagram

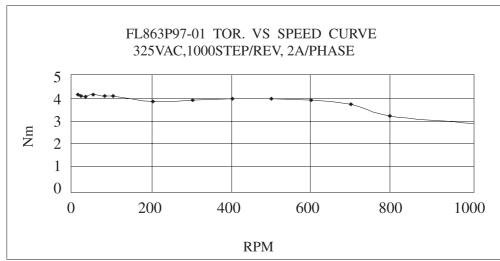
31

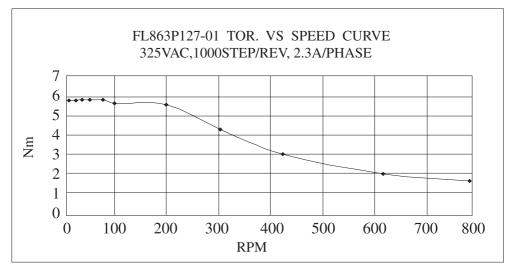




### Pull out Torque Curve









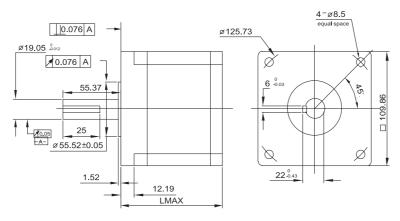
### General Specification for High Torque Hybrid Stepping Motor

Item	Specifications
Step Angle	1.8·
Step Angle Accuracy	$\pm$ 5% (full step, no load)
Resistance Accuracy	± 10%
Inductance Accuracy	± 20%
Temperature Rise	80°C Max.(rated current,2 phase on)
Ambient Temperature	-20°C ~+50°C
Insulation Resistance	100M Ω Min. ,500VDC
Dielectric Strength	500VAC for one minute
Shaft Radial Play	0.02Max. (450 g-load)
Shaft Axial Play	0.08Max. (450 g-load)
Max. radial force	220N (20mm from the flange)
Max. axial force	60N
Rotation	CW( See from Front Flange)

### • Size 110mm High Torque Hybrid Stepping Motor Specifications

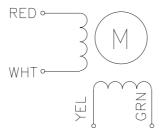
	Rated	Current	Resistance	Inductance	Holding	# of	Rotor	14/ - ! l- 1	Detent	Lanath
Model No.	Voltage	/Phase	/Phase	/Phase	Torque	Leads	Inertia	Weight	Torque	Length
Single shaft	V	Α	Ω	mΗ	N.m		g-cm <sup>2</sup>	kg	kg-cm	m m
FL110STH995504A	3.2	5.5	0.58	10.1	11.5	4	5500	5	3	99
FL110STH150-6504A	3.9	6.5	0.6	12.8	22	4	10900	8.4	5.9	150
FL110STH201-8004A	4	8	0.5	11	30	4	16200	11.7	7.5	201

#### Dimension



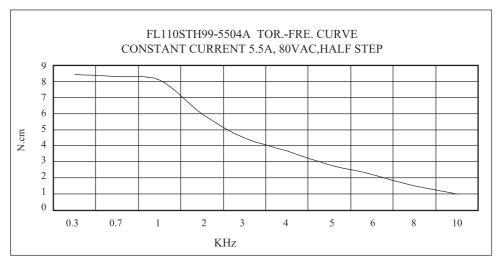
### Wiring Diagram

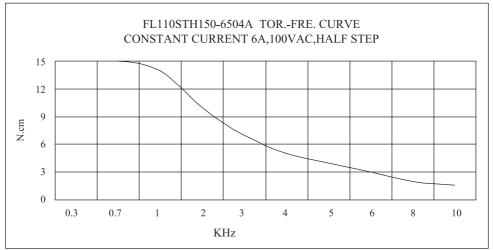
4 LEADS

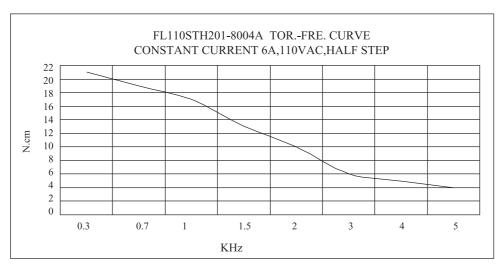




### Pull out Torque Curve









## 1.8 $^{\circ}$ and 0.9 $^{\circ}$ or 0.72 $^{\circ}$ and 0.36 $^{\circ}$ Size 110mm Hybrid Stepping Motor

### • General Specification for Hybrid Stepping Motor

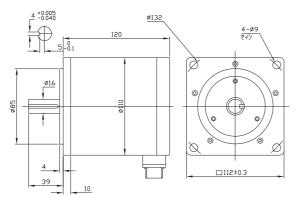
Item	Specifications
Step Angle	1.8° or 0.9°,0.72° or 0.36°
Step Angle Accuracy	$\pm$ 5% (full step, no load)
Resistance Accuracy	± 10%
Inductance Accuracy	± 20%
Temperature Rise	80°C Max.(rated current,2 phase on)
Ambient Temperature	-20°C~+50°C
Insulation Resistance	100M Ω Min. ,500VDC
Dielectric Strength	500VAC for one minute
Shaft Radial Play	0.02Max. (450 g-load)
Shaft Axial Play	0.08Max. (450 g-load)
Max. radial force	220N (20mm from the flange)
Max. axial force	60N
Rotation	CW( See from Front Flange)

### Size 110mm Hybrid Stepping Motor Specifications

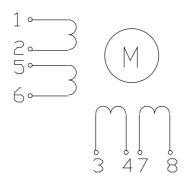
Madal	No. of	Step	Rated	Current	Resistance	Inductance	Holding	Rotor	\A/=:=l=4	Detent	
Model	phase	angle	Voltage	/Phase	/Phase	/Phase	Torque	Inertia	Weight	Torque	Length
Single shaft		degree	V	Α	Ω	mH	N.m	kg-cm <sup>2</sup>	kg	N.m	mm
FL110ST130-6008A	4	1.8	80-200	6	0.18	2	4.5	3.8	3.8	0.3	130
FL110ST130-6008MA	4	0.9	80-200	6	0.18	2	4.5	3.8	3.8	0.3	130
FL110ST192-6008A	4	1.8	80-200	6	0.22	2.1	7.1	7.5	7.5	0.6	192
FL110ST192-6008MA	4	0.9	80-200	6	0.22	2.1	7.1	7.5	7.5	0.6	192
FL110ST192-50010A	5	0.72	130	5	0.3	1.9	6.8	7.5	7.5	0.6	192
FL110ST192-50010MA	5	0.36	130	5	0.3	1.9	6.8	7.5	7.5	0.6	192
FL110ST192-30010A	5	0.72	130	3	0.5	5.3	6.8	7.5	7.5	0.6	192
FL110ST192-30010MA	5	0.36	130	3	0.5	5.3	6.8	7.5	7.5	0.6	192
FL110ST240-6008A	4	1.8	80-200	6	0.3	3.2	10.3	11.5	11.5	0.9	240
FL110ST240-6008MA	4	0.9	80-200	6	0.3	3.2	10.3	11.5	11.5	0.9	240
FL110ST240-50010A	5	0.72	130	5	0.37	3.4	10.3	11.5	11.5	0.9	240
FL110ST240-50010MA	5	0.36	130	5	0.37	3.4	10.3	11.5	11.5	0.9	240
FL110ST240-30010A	5	0.72	130	3	0.62	9.5	10.3	11.5	11.5	0.9	240
FL110ST240-30010MA	5	0.36	130	3	0.62	9.5	10.3	11.5	11.5	0.9	240

### Dimension

35



### **Wiring Diagram**



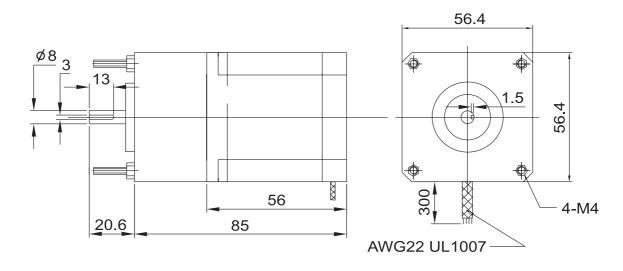


# **FL57HBGJB Gearbox Stepping Motor**

### General Specification

Model	Unit	FL57HBGJB								
Wodei		6	10	18	36	50	100			
Phase		4								
Manner of distribution			2-2							
Motor's stepping angle	deg		1.8							
Resistance/phase	ohms		80 ± 10%							
Exciting voltage	V	24								
Static torque	N.cm	6.2								
Reduction ratio		6	10	18	36	50	100			
Number of gear trains		2	3	4	4	5	5			
Efficiency	%	81	72	66	66	59	59			
No load starting frequency	pps	380	370	350	350	330	330			
No load operating frequency	pps	400	385	360	360	350	350			
Load starting frequency	1kg/pps	360	380	400	400	430	430			
Max. permissible load	Kg.cm	25								
Stepping angle with a gearbox	deg	0.3	0.18	0.1	0.05	0.36	0.018			

### Dimension



### Wiring Diagram

