

# Part IA - Vector Calculus

## Definitions

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### **Curves in $\mathbb{R}^3$**

Parameterised curves and arc length, tangents and normals to curves in  $\mathbb{R}^3$ , the radius of curvature. [1]

### **Integration in $\mathbb{R}^2$ and $\mathbb{R}^3$**

Line integrals. Surface and volume integrals: definitions, examples using Cartesian, cylindrical and spherical coordinates; change of variables. [4]

### **Vector operators**

Directional derivatives. The gradient of a real-valued function: definition; interpretation as normal to level surfaces; examples including the use of cylindrical, spherical \*and general orthogonal curvilinear\* coordinates.

Divergence, curl and  $\nabla^2$  in Cartesian coordinates, examples; formulae for these operators (statement only) in cylindrical, spherical \*and general orthogonal curvilinear\* coordinates. Solenoidal fields, irrotational fields and conservative fields; scalar potentials. Vector derivative identities. [5]

### **Integration theorems**

Divergence theorem, Green's theorem, Stokes's theorem, Green's second theorem: statements; informal proofs; examples; application to fluid dynamics, and to electromagnetism including statement of Maxwell's equations. [5]

### **Laplace's equation**

Laplace's equation in  $\mathbb{R}^2$  and  $\mathbb{R}^3$ : uniqueness theorem and maximum principle. Solution of Poisson's equation by Gauss's method (for spherical and cylindrical symmetry) and as an integral. [4]

### **Cartesian tensors in $\mathbb{R}^3$**

Tensor transformation laws, addition, multiplication, contraction, with emphasis on tensors of second rank. Isotropic second and third rank tensors. Symmetric and antisymmetric tensors. Revision of principal axes and diagonalization. Quotient theorem. Examples including inertia and conductivity. [5]

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# 1 Introduction

## 2 Derivatives and coordinates

### 2.1 Differentiable functions $\mathbb{R} \rightarrow \mathbb{R}^n$

**Definition.** A *vector function* is a function  $\mathbf{F} : \mathbb{R} \rightarrow \mathbb{R}^n$ .

**Definition** (Derivative of vector function). A vector function  $\mathbf{F}(x)$  is *differentiable* if

$$\delta \mathbf{F} \stackrel{\text{def}}{=} \mathbf{F}(x + \delta x) - \mathbf{F}(x) = \mathbf{F}'(x)\delta x + o(\delta x)$$

for some  $\mathbf{F}'(x)$ .  $\mathbf{F}'(x)$  is called the *derivative* of  $\mathbf{F}(x)$ .

Clearly, if  $\mathbf{F}'(x)$  exists, then it is given by

$$\mathbf{F}' = \frac{d\mathbf{F}}{dx} = \lim_{\delta x \rightarrow 0} \frac{1}{\delta x} [\mathbf{F}(x + \delta x) - \mathbf{F}(x)].$$

### 2.2 Differentiable functions $\mathbb{R}^n \rightarrow \mathbb{R}$

**Definition.** A *scalar function* is a function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$ .

**Definition** (Limit of vector). The *limit of vectors* is defined using the norm. So  $\mathbf{v} \rightarrow \mathbf{c}$  iff  $|\mathbf{v} - \mathbf{c}| \rightarrow 0$ .

**Definition** (Gradient of scalar function). A scalar function  $f(\mathbf{r})$  is *differentiable* at  $\mathbf{r}$  if

$$\delta f \stackrel{\text{def}}{=} f(\mathbf{r} + \delta \mathbf{r}) - f(\mathbf{r}) = (\nabla f) \cdot \delta \mathbf{r} + o(\delta \mathbf{r})$$

for some vector  $\nabla f$ , the *gradient* of  $f$  at  $\mathbf{r}$ .

**Definition** (Directional derivative). The *directional derivative* of  $f$  along  $\mathbf{n}$  is

$$\mathbf{n} \cdot \nabla f = \lim_{h \rightarrow 0} \frac{1}{h} [f(\mathbf{r} + h\mathbf{n}) - f(\mathbf{r})],$$

It refers to how fast  $f$  changes when we move in the direction of  $\mathbf{n}$ .

### 2.3 Differentiable functions $\mathbb{R}^n \rightarrow \mathbb{R}^m$

**Definition** (Vector field). A *vector field* is a function  $\mathbf{F} : \mathbb{R}^n \rightarrow \mathbb{R}^m$ .

**Definition** (Derivative of vector field). A vector field  $\mathbf{F} : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is *differentiable* if

$$\delta \mathbf{F} \stackrel{\text{def}}{=} \mathbf{F}(\mathbf{x} + \delta \mathbf{x}) - \mathbf{F}(\mathbf{x}) = M\delta \mathbf{x} + o(\delta \mathbf{x})$$

for some  $n \times m$  matrix  $M$ .  $M$  is the *derivative* of  $\mathbf{F}$ .

**Definition.** A function is *smooth* if it can be differentiated any number of times, i.e. if all partial derivatives exist and are totally symmetric in  $i, j$  and  $k$  (i.e. the differential operation is commutative).