# tCCA extension for the General Linear Model in Homer3: A brief introduction

version May 2020

This document provides a brief introduction to the use of temporally embedded Canonical Correlation Analysis (tCCA) to generate more optimal nuisance regressors for the General Linear Model in fNIRS using the Homer3 toolbox. The method and its extensive evaluation and validation were published in NeuroImage 208 (2020), the manuscript can be accessed <a href="here">here</a> (DOI: 10.1016/j.neuroimage.2019.116472):

NeuroImage 208 (2020) 116472



Contents lists available at ScienceDirect

# NeuroImage





Improved physiological noise regression in fNIRS: A multimodal extension of the General Linear Model using temporally embedded Canonical Correlation Analysis



Alexander von Lühmann <sup>a,b,c,\*\*</sup>, Xinge Li <sup>a</sup>, Klaus-Robert Müller <sup>c,d,e</sup>, David A. Boas <sup>a,b</sup>, Meryem A. Yücel <sup>a,b,\*</sup>

- <sup>a</sup> Neurophotonics Center, Biomedical Engineering, Boston University, Boston, MA, 02215, USA
- b Athinoula A. Martinos Center for Biomedical Imaging, Department of Radiology, Massachusetts General Hospital, Harvard Medical School, Charlestown, MA, 02129, USA
- <sup>c</sup> Machine Learning Department, Berlin Institute of Technology, 10587, Berlin, Germany
- <sup>d</sup> Department of Brain and Cognitive Engineering, Korea University, Seoul, 02841, South Korea
- <sup>e</sup> Max Planck Institute for Informatics, Saarbrücken, 66123, Germany

## What does the method do?

- It reduces nuisance signals in fNIRS, which leads to a more robust estimation of evoked brain activity.
- GLM with tCCA flexibly combines any available auxiliary signals into optimal nuisance regressors. The most important signals to use are short distance fNIRS channels and motion (accelerometer) measured at the head.
- The method significantly improves upon conventional GLM with short separation regression and can be used comparatively easily to extend existing processing pipelines.
- GLM with tCCA improves HRF recovery particularly for low Contrast to Noise Ratios and low number of stimuli/trials.

#### How does it work?

The method consists of (at least) two different steps/runs:

- 1. A (machine) learning run, in which a resting state measurement (training run) is used to learn tCCA filters that generate the optimal nuisance regressors by linearly mixing time embedded (shifted copies of) auxiliary signals. It is important to use resting state data not experimental data with stimuli that generate brain responses to ensure the nuisance regressors fit physiological noise only. The tCCA filter matrix is saved in the group/subject folder as a text file named "tCCAfilter\_1\_xxxxx.txt", where 'xxxxx' is a tCCA parameter configuration checksum. If you change tCCA parameters, or delete the file, this filter will be newly trained.
- The analysis run(s), in which the tCCA filters are used to generate nuisance regressors for the subsequent GLM analysis of the fNIRS data that contains stimuli and corresponding brain responses.

In Homer3, this is incorporated by specifying the index of the resting run to use for training, and then running a whole subject's session. The index of the resting run can be determined by checking the order of the resting run as it appears on the "current processing element" list on Homer3 main GUI. The session should at least contain the resting run, and one analysis run. If the resting run is not the first in the processing order, the training will only happen once the resting run is analyzed. All other runs until the training are skipped. In this case, after initial execution, you will get a warning pop-up window. Just **rerun** the session to get complete results.

## What to watch out for?

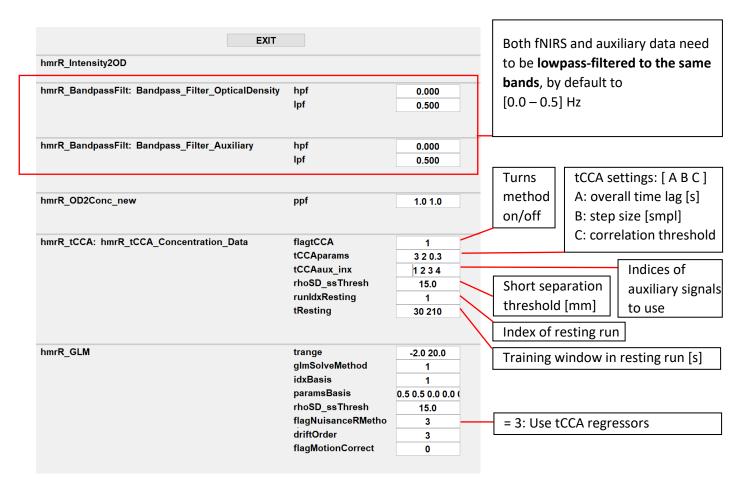
The tCCA approach is a machine learning based method with several hyperparameters. This means that the selection of the parameters can have a big impact on the performance of the method. For an exploration of the parameter space and more details, please see the NeuroImage paper cited above. In general, it is good to keep the following points in mind:

- 1. Try to avoid overfitting. If the nuisance regressors overfit the fNIRS signals, the HRFs will be underestimated. Overfitting is more likely to occur, when
  - a. The tCCA parameter set yields a large number of temporal embeddings: This happens when you use a long absolute time lag and a small step size.
  - b. The correlation threshold is low: This will result in a larger number of tCCA regressors being handed over to the GLM.
  - c. The ratio of tCCA nuisance regressors and HRF regressors is bad: For instance, if you use the GLM with canonical HRF regressor and not gaussian basis functions, you might want to reduce the number of tCCA regressors.
  - d. The auxiliary signals have high frequency components that were not filtered out well and the number of temporal embeddings is large.
- 2. Use meaningful resting data:
  - a. If the resting data contains many (non-rejected) motion artifacts, the training might be dominated by those spikes and the resulting regressors will be less optimal.
  - b. If you want to capture (and regress) slow effects of movement on fNIRS nuisance signals, use resting state data that contains such segments.

c. Don't use too short (<60s) or very long (>10min) segments for training (these values are experimental and have not been empirically investigated so far).

## How to incorporate tCCA into your Homer3 processing stream?

You can simply add the hmrR\_tCCA function to your processing stream, usually directly preceding the hmR\_GLM function. Please refer to the example processing stream tCCA\_xmpl\_procStream.cfg, that is provided with this documentation under ...\Homer3\FuncRegistry\UserFunctions\tcca\_glm\ and explained in the following:



Please note that by default we do not bandpass filter the data, but only low-pass filter by setting hpf = 0. The low frequencies are rejected by polynomial drift regression in the GLM, and the slow signals in the tCCA regressors. Also, please note that by default we use gaussian basis functions (idxBasis =1) in the GLM. To use the tCCA regressors in the hmrR\_GLM function, the flagNuisanceRMethod needs to be set to 3.

#### Remarks on parameter selection

<u>BandpassFilt</u>: You can choose any typical fNIRS band here. Please note that the tCCA step

might perform less good when higher frequency noise is not excluded (lpf high)

<u>flagtCCA</u>: Turns the tCCA method on (1) or off (0).

tCCAparams: The main parameters for tCCA analysis, as identified and evaluated in the

NeuroImage publication: [timeLag stepSize corrThresh]

<u>timeLag</u>: overall timespan in seconds, across which temporal embedding

is performed. Default: 3s.

stepSize: the step size ( $\Delta t$ ) in samples for each time shift of auxiliary

signals in the temporal embedding step. NOTE: The effective time shift will depend on your data's sample frequency!

Default: 2 samples

corrThresh: Correlation threshold (<=1). This threshold will be used to select

(keep) only those tCCA regressors for the GLM nuisance removal, that have a canonical correlation with fNIRS signals in the CCA space that is greater than corrThresh. If set to 1, all

regressors will be used. Default: 0.3.

tCCAaux\_inx: indices of the auxiliary signals in the .snirf file that are to be used for the tCCA

regression. NOTE: to not introduce additional noise, exclude auxiliary channels

that are noisy or do not carry meaningful signals.

rhoSD ssThresh: Same parameter as in the hmR GLM function. Threshold to detect short

separation channels in the data. All signals measured with a source-detector separation < rhoSD\_ssThresh will be used as short separation channels and added to the auxiliary signals to find nuisance regressors in the tCCA step.

runldxResting: Index of the run (dataset) that contains the resting data to be used for the tCCA

filter training. We recommend to position your resting state data as the first run and set runldxResting = 1. If your resting run is not the first, the tCCA function will skip all runs up to the training run to generate the tCCA filter and will not output any regressors before the filter is learnt. In that case, simply re-run the whole session after your first execution to generate results for the previous runs

as well.

tResting: Window in seconds [start stop] to be used in the resting state run for tCCA

training. We recommend setting the start time to at least a few seconds after the begin of the resting state run to make sure all signals are settled and no major artifacts are present. For better statistical performance, the window

should not be shorter than 60s. Default: [30 210] (180s).