

uas_kelompok5

June 26, 2024

0.0.1 Import Libraries

```
[ ]: import cv2 as cv
import numpy as np
import pandas as pd
import os
from matplotlib import pyplot as plt
from sklearn.preprocessing import MinMaxScaler, OneHotEncoder
from sklearn.model_selection import train_test_split
from tensorflow import keras
from keras import datasets, layers, models
from tensorflow.keras.utils import image_dataset_from_directory
from tensorflow.keras.callbacks import ModelCheckpoint
from tensorflow.keras.preprocessing import image
import random
```

0.0.2 TAHAP PREPROCESSING

Resizing and Thresholding

```
[ ]: def thresholding(input_folder, output_folder):
    #Samakan ukuran berdasarkan pixel
    new_size = (240, 240)

    # Buat folder baru untuk menyimpan hasil resizing jika belum ada
    if not os.path.exists(output_folder):
        os.makedirs(output_folder)

    # Loop melalui semua file dalam folder
    for filename in os.listdir(input_folder):
        if filename.endswith(('.jpg', '.jpeg', '.png')): # Filter file gambar
            img_path = os.path.join(input_folder, filename)

            img = cv.imread(img_path,0)

            # Resize gambar
            img_resized = cv.resize(img, new_size, interpolation=cv.
↪INTER_LANCZOS4)
```

```

        threshold_value = 100
        ret, img_threshold = cv.threshold(img_resized, threshold_value,
↳255, cv.THRESH_TRUNC)
        #ret menyimpan nilai ambang yang digunakan dalam operasi
↳thresholding = threshold_value = 100

        # Simpan hasil thresholding ke folder output
        output_path = os.path.join(output_folder, filename)
        cv.imwrite(output_path, img_threshold)

    print("Thresholding done!")

thresholding('./data_awal/YES', './dataset/YES_thresholding')
thresholding('./data_awal/NO', './dataset/NO_thresholding')

```

Thresholding done!

Thresholding done!

Edge Detection and Normalization

```

[ ]: def edge_detection(input_folder, output_folder):
    if not os.path.exists(output_folder):
        os.makedirs(output_folder)

    for filename in os.listdir(input_folder):
        if filename.endswith((''.jpg', '.jpeg', '.png')): # Filter file gambar
            img_path = os.path.join(input_folder, filename)

            img = cv.imread(img_path)

            #Mengubahnya jadi tipe data floating point (CV_64F) u/ menghindari
↳hilangnya informasi tepi yg negatif
            sobelx_f = cv.Sobel(img, cv.CV_64F, 1, 0, ksize=3) #Gradien dalam arah
↳x hasil dari operasi Sobel
            sobely_f = cv.Sobel(img, cv.CV_64F, 0, 1, ksize=3) #Gradien dalam arah
↳y hasil dari operasi Sobel.

            magnitude = cv.magnitude(sobelx_f, sobely_f) #menghitung magnitudo
↳gradien dari hasil deteksi tepi dalam floating point
            #abs_sobel64f = np.absolute(magnitude) #mengonversi nilai absolut
↳magnitudo menjadi tipe data 64-bit floating point
            #sobel_8u = np.uint8(abs_sobel64f) #mengonversi hasil tersebut ke
↳tipe data 8-bit unsigned integer

            #img = sobel_8u

            #Normalisasi gambar
            img_normalized = cv.normalize(magnitude, None, 0, 1, cv.NORM_MINMAX)

```

```

        # Simpan hasil thresholding ke folder output
        output_path = os.path.join(output_folder, filename)
        cv.imwrite(output_path, (img_normalized * 255).astype(np.uint8))

    print("Edge detection and Normalization done!")

edge_detection('./dataset/YES_thresholding', './dataset/data/ya')
edge_detection('./dataset/NO_thresholding', './dataset/data/tidak')

```

Edge detection and Normalization done!
Edge detection and Normalization done!

```

[ ]: data = './dataset/data'
    kelas = os.listdir(data)
    print(kelas)

```

['tidak', 'ya']

Menampilkan beberapa citra beserta labelnya

```

[ ]: yes = 'dataset/data/ya'
    no = 'dataset/data/tidak'

```

Mengambil images dari folder ya dan tidak untuk diberi label 1 untuk yes, 0 untuk no, dan diletakkan ke dalam list all_images

```

[ ]: all_images = []

for filename in os.listdir(yes):
    if filename.endswith(('.jpg', '.jpeg', '.png')):
        img_path = os.path.join(yes, filename)
        all_images.append((img_path, 1))

for filename in os.listdir(no):
    if filename.endswith(('.jpg', '.jpeg', '.png')):
        img_path = os.path.join(no, filename)
        all_images.append((img_path, 0))

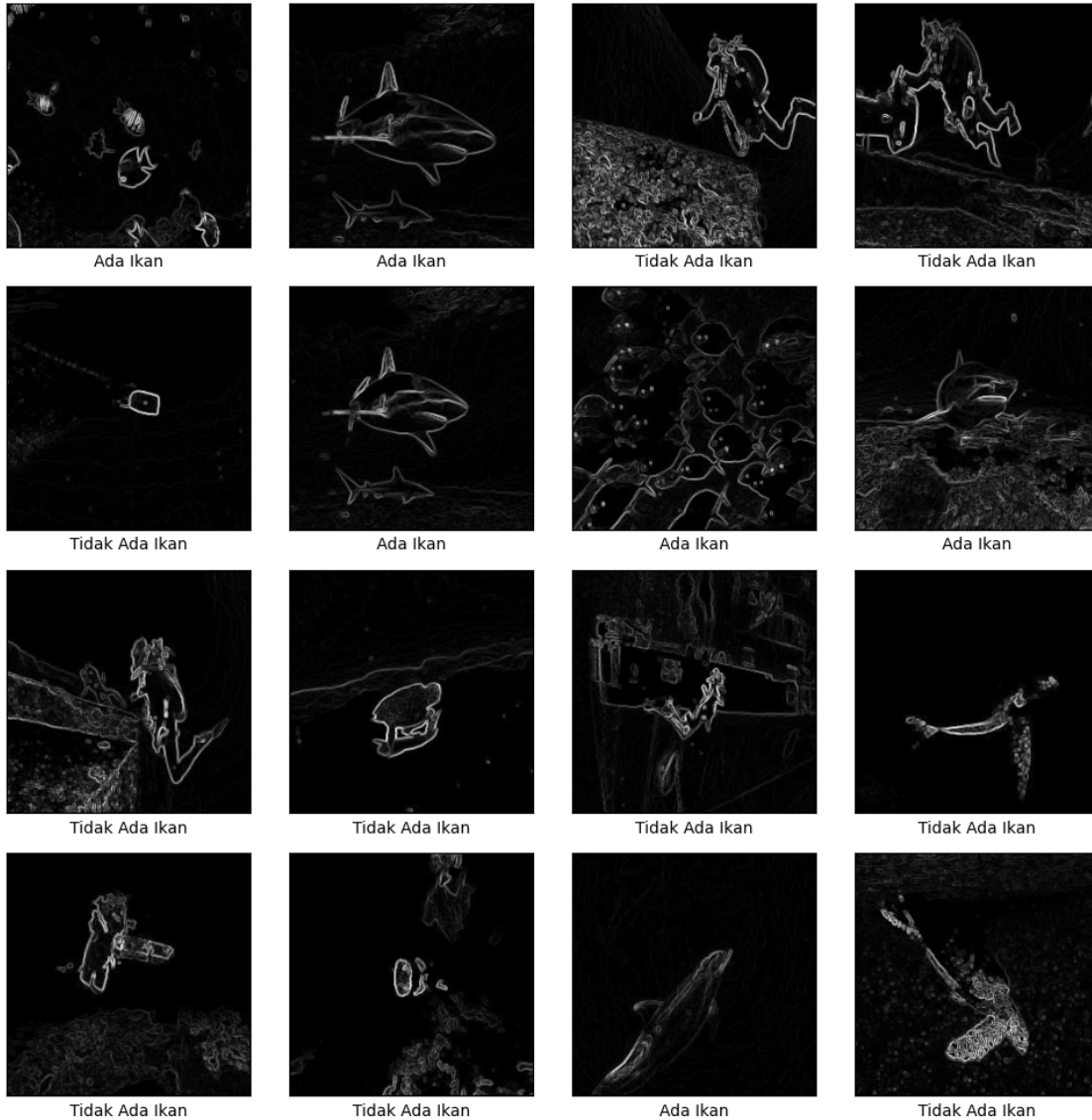
random.shuffle(all_images)

plt.figure(figsize=(10, 10))
for i in range(min(16, len(all_images))):
    img_path, label = all_images[i]
    img = cv.imread(img_path)
    plt.subplot(4, 4, i + 1)
    plt.xticks([])
    plt.yticks([])
    plt.grid(False)
    plt.imshow(img)

```

```
plt.xlabel('Ada Ikan' if label == 1 else 'Tidak Ada Ikan')

plt.tight_layout()
plt.show()
```



Membagi data menjadi data train dan data test

```
[ ]: train_datagen = image_dataset_from_directory(data,
                                                    image_size=(240,240),
                                                    subset='training',
                                                    seed = 1, #untuk konsistensi
                                                    validation_split = 0.2,
```

→ gambar mana saja yang jadi train dan test (akan selalu sama)

```

batch_size = 32)

test_datagen = image_dataset_from_directory(data,
                                           image_size=(240,240),
                                           subset='validation',
                                           seed = 1, #untuk konsistensi gambar
↳mana saja yang jadi train dan test (akan selalu sama)
                                           validation_split = 0.2,
                                           batch_size = 32)

```

Found 200 files belonging to 2 classes.
Using 160 files for training.
Using 160 files for training.
Found 200 files belonging to 2 classes.
Using 40 files for validation.

Membuat Lapisan Konvolusional diikuti MaxPooling untuk mengekstraksi fitur dari citra. Layer Flatten u/ mengubah output dari layer konvolusi menjadi vektor satu dimensi, dan layer Dense di bagian akhir untuk klasifikasi, dengan fungsi aktivasi ReLU untuk layer tersembunyi dan sigmoid untuk output

```

[ ]: img_height, img_width = 240, 240
new_size = (img_width, img_height)

# Definisikan model
model = models.Sequential()
#layer konvolusi pertama dengan 32 jumlah filter, kernel 3x3, fungsi aktivasi
↳'ReLU setelah operasi konvolusi. Input model 240, 240, 3(gambar channel 3/
↳berwarna)
model.add(layers.Conv2D(32, (3, 3), activation='relu', input_shape=(img_height,
↳img_width, 3)))
model.add(layers.MaxPooling2D((2, 2))) #ukuran jendela pooling 2x2
#layer konvolusi tambahan menggunakan 64, 128 filter dan fungsi aktivitas ReLU
model.add(layers.Conv2D(64, (3, 3), activation='relu'))
model.add(layers.MaxPooling2D((2, 2)))
model.add(layers.Conv2D(128, (3, 3), activation='relu'))
model.add(layers.MaxPooling2D((2, 2)))

#mengubah output layer sebelumnya menjadi vektor satu dimensi agar dapat jadi
↳masukan pada layer Dense (fully connected)
model.add(layers.Flatten())
model.add(layers.Dropout(0.5))

model.add(layers.Dense(256, activation='relu'))
#layer output dengan 1 unit (karena klasifikasi biner)
#fungsi sigmoid menghasilkan probabilitas 0 hingga 1
model.add(layers.Dense(1, activation='sigmoid'))

```

```

model.summary()

model.compile(
    loss='binary_crossentropy',
    optimizer='adam',
    metrics=['accuracy']
)

```

c:\Users\IKA KUSUMA\AppData\Local\Programs\Python\Python310\lib\site-packages\keras\src\layers\convolutional\base_conv.py:107: UserWarning: Do not pass an `input_shape`/`input_dim` argument to a layer. When using Sequential models, prefer using an `Input(shape)` object as the first layer in the model instead.

```
super().__init__(activity_regularizer=activity_regularizer, **kwargs)
```

Model: "sequential"

| Layer (type) | Output Shape | Param # |
|--------------------------------|----------------------|------------|
| conv2d (Conv2D) | (None, 238, 238, 32) | 896 |
| max_pooling2d (MaxPooling2D) | (None, 119, 119, 32) | 0 |
| conv2d_1 (Conv2D) | (None, 117, 117, 64) | 18,496 |
| max_pooling2d_1 (MaxPooling2D) | (None, 58, 58, 64) | 0 |
| conv2d_2 (Conv2D) | (None, 56, 56, 128) | 73,856 |
| max_pooling2d_2 (MaxPooling2D) | (None, 28, 28, 128) | 0 |
| flatten (Flatten) | (None, 100352) | 0 |
| dropout (Dropout) | (None, 100352) | 0 |
| dense (Dense) | (None, 256) | 25,690,368 |
| dense_1 (Dense) | (None, 1) | 257 |

Total params: 25,783,873 (98.36 MB)

Trainable params: 25,783,873 (98.36 MB)

Non-trainable params: 0 (0.00 B)

Callback untuk menyimpan model terbaik berdasarkan akurasi validasi

```
[ ]: checkpoint_callback = ModelCheckpoint(filepath='best_model.keras',
                                         monitor='val_accuracy',
                                         mode='max',
                                         save_best_only=True,
                                         verbose=1)
```

```
[ ]: #Pelatihan model
history = model.fit(train_datagen,
                    epochs=15,
                    validation_data=test_datagen,
                    callbacks=[checkpoint_callback])

test_loss, test_acc = model.evaluate(test_datagen, verbose=2)
print('Validation loss : ', test_loss)
print('Validation accuracy : ', test_acc)

history_df = pd.DataFrame(history.history)

# Subplot 2: Plot accuracy dan val_accuracy
plt.subplot(2, 1, 1)
history_df[['accuracy', 'val_accuracy']].plot(ax=plt.gca())
plt.xlabel('Epoch')
plt.ylabel('Accuracy')
plt.title('Training Accuracy vs Validation Accuracy')

# Subplot 2 : Plot loss dan val_loss
plt.subplot(2, 1, 2)
history_df[['loss', 'val_loss']].plot(ax=plt.gca())
plt.xlabel('Epoch')
plt.ylabel('Loss')
plt.title('Training Loss vs Validation Loss')

# Menambahkan judul utama
plt.suptitle('Accuracy and Loss')
plt.tight_layout()
plt.show()
```

Epoch 1/15

5/5 0s 9s/step -

accuracy: 0.5301 - loss: 116.8693

Epoch 1: val_accuracy improved from -inf to 0.57500, saving model to
best_model.keras

5/5 66s 12s/step -

accuracy: 0.5324 - loss: 113.9066 - val_accuracy: 0.5750 - val_loss: 4.6687

Epoch 2/15

5/5 0s 10s/step -
 accuracy: 0.6614 - loss: 2.0318
 Epoch 2: val_accuracy improved from 0.57500 to 0.62500, saving model to
 best_model.keras
 5/5 52s 12s/step -
 accuracy: 0.6574 - loss: 1.9683 - val_accuracy: 0.6250 - val_loss: 0.9704
 Epoch 3/15
 5/5 0s 6s/step -
 accuracy: 0.7579 - loss: 0.4371
 Epoch 3: val_accuracy did not improve from 0.62500
 5/5 61s 6s/step -
 accuracy: 0.7649 - loss: 0.4306 - val_accuracy: 0.6000 - val_loss: 0.6697
 Epoch 4/15
 5/5 0s 18s/step -
 accuracy: 0.9103 - loss: 0.2403
 Epoch 4: val_accuracy improved from 0.62500 to 0.77500, saving model to
 best_model.keras
 5/5 101s 21s/step -
 accuracy: 0.9169 - loss: 0.2347 - val_accuracy: 0.7750 - val_loss: 0.4871
 Epoch 5/15
 5/5 0s 12s/step -
 accuracy: 0.9907 - loss: 0.0653
 Epoch 5: val_accuracy improved from 0.77500 to 0.82500, saving model to
 best_model.keras
 5/5 117s 15s/step -
 accuracy: 0.9902 - loss: 0.0641 - val_accuracy: 0.8250 - val_loss: 0.4504
 Epoch 6/15
 5/5 0s 12s/step -
 accuracy: 1.0000 - loss: 0.0281
 Epoch 6: val_accuracy did not improve from 0.82500
 5/5 76s 13s/step -
 accuracy: 1.0000 - loss: 0.0266 - val_accuracy: 0.8250 - val_loss: 0.4974
 Epoch 7/15
 5/5 0s 12s/step -
 accuracy: 1.0000 - loss: 0.0082
 Epoch 7: val_accuracy did not improve from 0.82500
 5/5 81s 12s/step -
 accuracy: 1.0000 - loss: 0.0088 - val_accuracy: 0.8250 - val_loss: 0.7574
 Epoch 8/15
 5/5 0s 11s/step -
 accuracy: 1.0000 - loss: 0.0064
 Epoch 8: val_accuracy did not improve from 0.82500
 5/5 78s 11s/step -
 accuracy: 1.0000 - loss: 0.0063 - val_accuracy: 0.8000 - val_loss: 1.0496
 Epoch 9/15
 5/5 0s 8s/step -
 accuracy: 1.0000 - loss: 0.0039
 Epoch 9: val_accuracy did not improve from 0.82500


```

5/5          69s 8s/step -
accuracy: 1.0000 - loss: 0.0041 - val_accuracy: 0.8250 - val_loss: 1.0904
Epoch 10/15
5/5          0s 8s/step -
accuracy: 1.0000 - loss: 0.0013
Epoch 10: val_accuracy improved from 0.82500 to 0.85000, saving model to
best_model.keras
5/5          50s 10s/step -
accuracy: 1.0000 - loss: 0.0018 - val_accuracy: 0.8500 - val_loss: 1.0531
Epoch 11/15
5/5          0s 7s/step -
accuracy: 1.0000 - loss: 0.0022
Epoch 11: val_accuracy did not improve from 0.85000
5/5          38s 8s/step -
accuracy: 1.0000 - loss: 0.0026 - val_accuracy: 0.8250 - val_loss: 1.0453
Epoch 12/15
5/5          0s 7s/step -
accuracy: 1.0000 - loss: 0.0094
Epoch 12: val_accuracy did not improve from 0.85000
5/5          43s 9s/step -
accuracy: 1.0000 - loss: 0.0085 - val_accuracy: 0.8000 - val_loss: 1.0473
Epoch 13/15
5/5          0s 10s/step -
accuracy: 1.0000 - loss: 0.0031
Epoch 13: val_accuracy did not improve from 0.85000
5/5          49s 10s/step -
accuracy: 1.0000 - loss: 0.0032 - val_accuracy: 0.8000 - val_loss: 1.0119
Epoch 14/15
5/5          0s 7s/step -
accuracy: 1.0000 - loss: 0.0016
Epoch 14: val_accuracy did not improve from 0.85000
5/5          68s 7s/step -
accuracy: 1.0000 - loss: 0.0019 - val_accuracy: 0.8000 - val_loss: 0.9483
Epoch 15/15
5/5          0s 7s/step -
accuracy: 1.0000 - loss: 0.0018
Epoch 15: val_accuracy did not improve from 0.85000
5/5          44s 8s/step -
accuracy: 1.0000 - loss: 0.0021 - val_accuracy: 0.7750 - val_loss: 0.7949
2/2 - 2s - 869ms/step - accuracy: 0.7750 - loss: 0.7949
Validation loss : 0.7948988676071167
Validation accuracy : 0.7749999761581421

```



```
[ ]: best_model = keras.models.load_model('best_model.keras')
```

0.0.3 Tahap Processing Klasifikasi dan Prediksi

Fungsi preprocessing untuk prediksi

```
[ ]: def preprocess_image(input_folder, filename):
    img_path = os.path.join(input_folder, filename)

    img = cv.imread(img_path, 0)

    #resize image ke piksel 240 x 240
    img_height, img_width = 240, 240
    new_size = (img_width, img_height)
    img_resized = cv.resize(img, new_size, interpolation=cv.INTER_LANCZOS4)

    # Thresholding Trunc
    threshold_value = 100
    ret, img_threshold = cv.threshold(img_resized, threshold_value, 255, cv.
    THRESH_TRUNC)
```

```

    # Sobel u/ mendapatkan gradien dalam arah horizontal dan vertikal untuk
    ↪mendapatkan gradien dalam arah horizontal dan vertikal
    # Sobel magnitude untuk edge detection
    sobelx_f = cv.Sobel(img_threshold, cv.CV_64F, 1, 0, ksize=3)
    sobely_f = cv.Sobel(img_threshold, cv.CV_64F, 0, 1, ksize=3)
    magnitude = cv.magnitude(sobelx_f, sobely_f)

    # Normalize magnitude jadi rentang [0, 1] atau min = 0 dan max = 1 dengan
    ↪NORMALISASI MIN MAX dari openCV
    img_normalized = cv.normalize(magnitude, None, 0, 1, cv.NORM_MINMAX)

    # mengubahnya jadi RGB karena dia 3-channel sebab model butuh inputan
    ↪3-channel
    img_normalized_rgb = cv.cvtColor((img_normalized * 255).astype(np.uint8),
    ↪cv.COLOR_GRAY2RGB)

    return img_normalized_rgb

```

Fungsi untuk memampikan hasil prediksi

```

[ ]: def predict_and_plot(files):
    plt.figure(figsize=(20, 20))
    for i, file in enumerate(files):
        input_folder, filename = os.path.split(file) #di-split agar mendapatkan
        ↪jalur file sehingga didapatkan direktor dan filename

        # Tahapan preprocessing (resizing, thresholding, edge detection,
        ↪normalization)
        img_normalized = preprocess_image(input_folder, filename)

        #Memprediksi citra dengan model
        img_for_prediction = np.expand_dims(img_normalized, axis=0)
        predictions = model.predict(img_for_prediction)
        label = 'Ikan' if predictions[0][0] > 0.5 else 'Tidak ada ikan' #jika
        ↪hasil prediksi >0.5, gambar diprediksi 'Ikan' sebaliknya, 'Tidak Ada Ikan'

        plt.subplot(4, 4, i + 1)
        plt.xticks([])
        plt.yticks([])
        plt.grid(False)
        plt.imshow(img_normalized)
        plt.xlabel(label)

    plt.show()

```

Fungsi mengambil gambar acak dari data awal untuk mengecek hasil prediksi oleh model

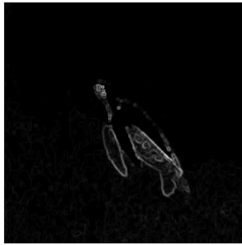
```
[ ]: def get_random_files(dataset_folder, num_files=16):
    all_files = []
    for label in ['YES', 'NO']:
        folder_path = os.path.join(dataset_folder, label)
        files = [os.path.join(folder_path, f) for f in os.listdir(folder_path)
        ↪if f.endswith(('.jpg', '.jpeg', '.png'))]
        all_files.extend(files)

    random_files = random.sample(all_files, num_files)
    return random_files
```

Data yang diprediksi adalah data random berjumlah 16 yang didapatkan dari data awal sebelum di-preprocessing

```
[ ]: dataset_folder = './data_awal'
    random_files = get_random_files(dataset_folder)
    predict_and_plot(random_files)
```

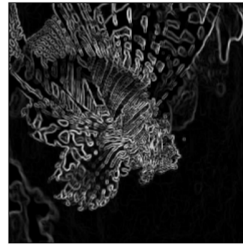
```
1/1          2s 2s/step
1/1          0s 252ms/step
1/1          0s 341ms/step
1/1          0s 347ms/step
1/1          0s 114ms/step
1/1          0s 121ms/step
1/1          0s 115ms/step
1/1          0s 137ms/step
1/1          0s 124ms/step
1/1          0s 253ms/step
1/1          0s 216ms/step
1/1          0s 304ms/step
1/1          0s 337ms/step
1/1          0s 480ms/step
1/1          1s 1s/step
1/1          1s 528ms/step
```



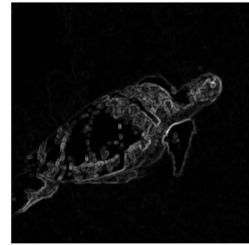
Tidak ada ikan



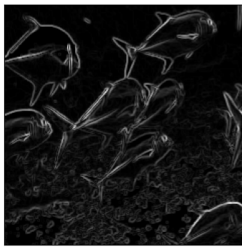
Tidak ada ikan



Ikan



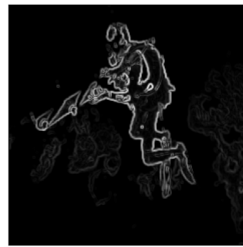
Tidak ada ikan



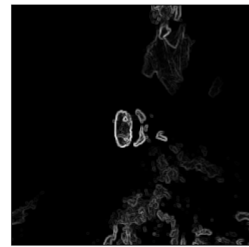
Ikan



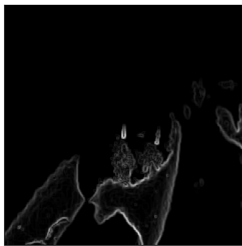
Tidak ada ikan



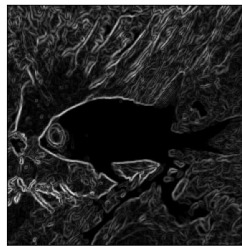
Tidak ada ikan



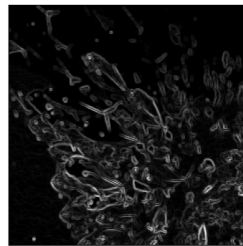
Tidak ada ikan



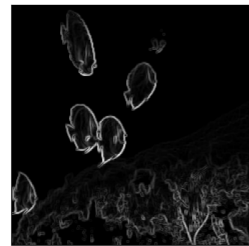
Tidak ada ikan



Ikan



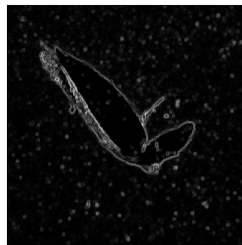
Ikan



Ikan



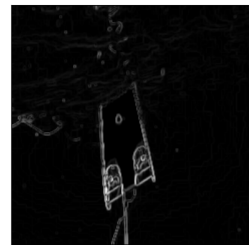
Ikan



Tidak ada ikan



Tidak ada ikan



Tidak ada ikan