

Learning Transferable Features with Deep Adaptation Networks

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Introduction

- Goal: Enhance the transferability of features from task-specific layers
- Proposed a Deep Adaptation Network DAN architecture
 - General features can generalize well to a novel task; however, for specific features they cannot bridge the domain discrepancy
- Some ways to enhance feature transferability:
 - By mean-embedding matching, feature transferability can be enhanced substantially
 - Utilizing multi-layer representations across domains in a reproducing kernel Hilbert space

Main Breakthrough

- *Generalizes deep CNN to the domain adaptation*
- Deep adaptation of multiple task-specific layers, including output
- Optimal adaptation using multiple kernel two-sample matching

Deep Learning For Domain Adaptation

- None or very weak supervision in the *target* task (new domain)
 - Target classifier cannot be reliably trained due to over-fitting
 - Fine-tuning is impossible as it requires substantial supervision
- Generalize related supervised source task to the target task
 - Deep networks can learn transferable features for adaptation
- Hard to find big source task for learning deep features from scratch
 - Transfer from deep networks pre-trained on unrelated big dataset
 - Transferring features from distant tasks better than random features

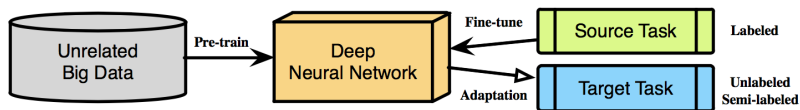


Figure: Deep Learning for Domain Adaptation Workflow

How Transferable Are Deep Features?

- Transferability is restricted by (Yosinski et al. 2014; Glorot et al. 2011)
- Specialization of higher layer neurons to original task (new task)
- Disentangling of variations in higher layers enlarges task discrepancy
- Transferability of features decreases while task discrepancy increases

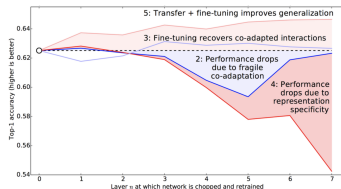


Figure: Transferability of features decreases while task discrepancy increases

Deep Adaptation Network (DAN)

Key Observations (AlexNet) (Krizhevsky et al. 2012)

- Comprised of five convolutional layers $conv1 - conv5$ and three fully connected layers $fc6 - fc8$
- Convolutional layers learn general features: safely transferable
 - Safely freeze $conv1 - conv3$ & fine tuned $conv4 - conv5$
- Fully-connected layers fit task specificity: *NOT* safely transferable
 - Deeply adapt $fc6 - fc8$ using statistically optimal two-sample matching

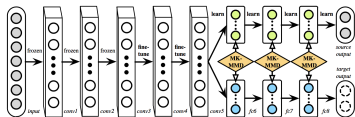


Figure: The DAN architecture for learning transferable features

Objective Function

Main Problems

- Feature transferability decreases with increasing task discrepancy
- Higher layers are tailored to specific tasks, NOT safely transferable
- Adaptation effect may vanish in back-propagation of deep networks

Deep Adaptation with Optimal Matching

- Deep adaptation: match distributions in multiple layers including output
- Optimal matching: maximize two-sample test of multiple kernels

$$\min_{\Theta} \max_{\kappa} \frac{1}{n_a} \sum_{i=1}^{n_a} J(\theta(x_i^a), y_i^a) + \lambda \sum_{\ell=l_1}^{l_2} d_k^2(D_s^{\ell}, D_t^{\ell}) \quad (1)$$

$\lambda > 0$ is a penalty, $D_*^{\ell} = \{h_i^{*\ell}\}$ is the ℓ -th layer hidden representation

MK-MMD

Theorem (Two-Sample Test (Gretton et al. 2012))

- $p = q$ iff $d_k^2(p, q) = 0$ (In practice, $d_k^2(p, q) < \epsilon$)
- $\max_{k \in \kappa} d_k^2(D_s^\ell, D_t^\ell) \sigma_k^{-2} \Leftrightarrow \min \text{Type II Error } (d_k^2(p, q) < \epsilon \text{ when } p \neq q)$

Multiple Kernel Maximum Mean Discrepancy (MK-MMD)

\triangleq RKHS distance between kernel embeddings of distributions p and q

$$d_k^2(p, q) \triangleq \|E_p[\phi(x^s)] - E_q[\phi(x^t)]\|_{\mathcal{H}_k}^2 \quad (2)$$

$k(\mathbf{x}^s, \mathbf{x}^t) = \langle \phi(\mathbf{x}^s), \phi(\mathbf{x}^t) \rangle$ is a convex combination of m PSD kernels

$$\kappa \triangleq \left\{ k = \sum_{u=1}^m \beta_u k_u : \sum_{u=1}^m \beta_u = 1, \beta_u \geq 0, \forall u \right\} \quad (3)$$

Learning CNN

Linear-Time Algorithm of MK-MMD (Streaming Algorithm)

$$O(n^2) : d_k^2(p, q) = \mathbf{E}_{\mathbf{x}^s \mathbf{x}'^s} k(\mathbf{x}^s, \mathbf{x}'^s) + \mathbf{E}_{\mathbf{x}^t \mathbf{x}'^t} k(\mathbf{x}^t, \mathbf{x}'^t) - 2\mathbf{E}_{\mathbf{x}^s \mathbf{x}^t} k(\mathbf{x}^s, \mathbf{x}^t)$$

$$d_k^2(p, q) = \frac{2}{n_s} \sum_{i=1}^{\frac{n_s}{2}} g_k(\mathbf{z}_i) \rightarrow \text{linear-time unbiased estimate}$$

- Quad-tuple: $\mathbf{z}_i \triangleq (\mathbf{x}_{2i-1}^s, \mathbf{x}_{2i}^s, \mathbf{x}_{2i-1}^t, \mathbf{x}_{2i}^t)$
- $g_k(\mathbf{z}_i) \triangleq k(\mathbf{x}_{2i-1}^s, \mathbf{x}_{2i}^s) + k(\mathbf{x}_{2i-1}^t, \mathbf{x}_{2i}^t) - k(\mathbf{x}_{2i-1}^s, \mathbf{x}_{2i}^t) - k(\mathbf{x}_{2i}^s, \mathbf{x}_{2i-1}^t)$

Stochastic Gradient Descent(SGD)

For each layer ℓ and for each quad-tuple $\mathbf{z}_i \triangleq (\mathbf{x}_{2i-1}^s, \mathbf{x}_{2i}^s, \mathbf{x}_{2i-1}^t, \mathbf{x}_{2i}^t)$

$$\nabla_{\Theta^\ell} = \frac{\partial J(z_i)}{\partial \Theta^\ell} + \lambda \frac{\partial g_k(z_i)}{\partial \Theta^\ell} \quad (4)$$

Learning Kernel

Learning optimal kernel $k = \sum_{u=1}^m \beta_u k_u$

Maximizing test power \triangleq minimizing Type II error (Gretton et al. 2012)

$$\max_{k \in \kappa} d_k^2(D_s^\ell, D_t^\ell) \sigma_k^{-2} \quad (5)$$

where $\sigma_k^2 = \mathbf{E}_{\mathbf{z}} g_k^2(\mathbf{z}) - [\mathbf{E}_{\mathbf{z}} g_k(\mathbf{z})]^2$ is the estimation variance.

Quadratic Program (QP), scaling linearly to sample size: $O(m^{2n} + m^3)$

$$\min_{\mathbf{d}^T, \beta=1, \beta \geq 0} \beta^T (Q + \epsilon I) \beta \quad (6)$$

where $\mathbf{d} = (d_1, d_2, \dots, d_m)^T$, and each d_u is MMD using base kernel k_u .

Analysis

Theorem (Adaptation Bound)

(Ben-David et al. 2010) Let $\theta \in H$ be a hypothesis, $\epsilon_s(\theta)$ and $\epsilon_t(\theta)$ be the expected risks of source and target respectively, then

$$\epsilon_t(\theta) \leq \epsilon_s(\theta) + 2d_k(p, q) + C \quad (7)$$

where C is a constant for the complexity of hypothesis space, the empirical estimate of **H**-divergence, and the risk of an ideal hypothesis for both tasks.

Two-Sample Classifier: Nonparametric vs. Parametric

- Nonparametric MMD directly approximates $d_{\mathcal{H}}(p, q)$
- Parametric classifier: adversarial training to approximate $d_{\mathcal{H}}(p, q)$

Experiment Setup

- Datasets: pre-trained on ImageNet, fined-tuned on Office&Caltech
- Tasks: 12 adaptation tasks \Rightarrow An unbiased look at dataset bias
- Variants: DAN; single-layer: DAN_7 , DAN_8 ; single-kernel: DAN_{SK}
- Protocols: unsupervised adaptation vs semi-supervised adaptation
- Parameter selection: cross-validation by jointly assessing
 - test errors of source classifier and two-sample classifier (MK-MMD)

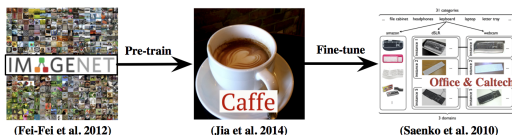


Figure: the proposed DAN model is trained by fine-tuning from the AlexNet model (Krizhevsky et al., 2012) pre-trained on ImageNet, implemented in Caffe.

Results & Discussion

Learning transferable features by deep adaptation and optimal matching

- Deep adaptation of multiple domain-specific layers (DAN) vs. shallow adaptation of one hard-to-tweak layer (DDC)
- Two samples can be matched better by MK-MMD vs. SK-MMD

Table 1. Accuracy on Office-31 dataset with standard unsupervised adaptation protocol (Gong et al., 2013).

Method	A \rightarrow W	D \rightarrow W	W \rightarrow D	A \rightarrow D	D \rightarrow A	W \rightarrow A	Average
TCA	21.5 \pm 0.0	50.1 \pm 0.0	58.4 \pm 0.0	11.4 \pm 0.0	8.0 \pm 0.0	14.6 \pm 0.0	27.3
GFK	19.7 \pm 0.0	49.7 \pm 0.0	63.1 \pm 0.0	10.6 \pm 0.0	7.9 \pm 0.0	15.8 \pm 0.0	27.8
CNN	61.6 \pm 0.5	95.4 \pm 0.3	<u>99.0</u> \pm 0.2	63.8 \pm 0.5	51.1 \pm 0.6	49.8 \pm 0.4	70.1
LapCNN	60.4 \pm 0.3	94.7 \pm 0.5	99.1 \pm 0.2	63.1 \pm 0.6	51.6 \pm 0.4	48.2 \pm 0.5	69.5
DDC	61.8 \pm 0.4	95.0 \pm 0.5	98.5 \pm 0.4	64.4 \pm 0.3	52.1 \pm 0.8	<u>52.2</u> \pm 0.4	70.6
DAN ₇	63.2 \pm 0.2	94.8 \pm 0.4	98.9 \pm 0.3	65.2 \pm 0.4	52.3 \pm 0.4	52.1 \pm 0.4	71.1
DAN ₈	<u>63.8</u> \pm 0.4	94.6 \pm 0.5	98.8 \pm 0.6	65.8 \pm 0.4	52.8 \pm 0.4	51.9 \pm 0.5	71.3
DAN _{SK}	63.3 \pm 0.3	<u>95.6</u> \pm 0.2	<u>99.0</u> \pm 0.4	<u>65.9</u> \pm 0.7	<u>53.2</u> \pm 0.5	52.1 \pm 0.4	<u>71.5</u>
DAN	68.5 \pm 0.4	96.0 \pm 0.3	<u>99.0</u> \pm 0.2	67.0 \pm 0.4	54.0 \pm 0.4	53.1 \pm 0.3	72.9

Figure: Table 1. Accuracy on Office-31 dataset with standard unsupervised adaptation protocol

Results & Discussion

Semi-supervised adaptation: source supervision vs. target supervision?

- Limited target supervision is prone to over-fitting the target task
- Source supervision can provide strong but inaccurate inductive bias
- Two-sample matching is more effective for bridging dissimilar tasks

Table 2. Accuracy on Office-10 + Caltech-10 dataset with standard unsupervised adaptation protocol (Gong et al., 2013).

Method	A \rightarrow C	W \rightarrow C	D \rightarrow C	C \rightarrow A	C \rightarrow W	C \rightarrow D	Average
TCA	42.7 \pm 0.0	34.1 \pm 0.0	35.4 \pm 0.0	54.7 \pm 0.0	50.5 \pm 0.0	50.3 \pm 0.0	44.6
GFK	41.4 \pm 0.0	26.4 \pm 0.0	36.4 \pm 0.0	56.2 \pm 0.0	43.7 \pm 0.0	42.0 \pm 0.0	41.0
CNN	83.8 \pm 0.3	76.1 \pm 0.5	80.8 \pm 0.4	91.1 \pm 0.2	83.1 \pm 0.3	89.0 \pm 0.3	84.0
LapCNN	83.6 \pm 0.6	77.8 \pm 0.5	80.6 \pm 0.4	92.1 \pm 0.3	81.6 \pm 0.4	87.8 \pm 0.4	83.9
DDC	84.3 \pm 0.5	76.9 \pm 0.4	80.5 \pm 0.2	91.3 \pm 0.3	85.5 \pm 0.3	89.1 \pm 0.3	84.6
DAN ₇	<u>84.7</u> \pm 0.3	78.2 \pm 0.5	<u>81.8</u> \pm 0.3	91.6 \pm 0.4	87.4 \pm 0.3	88.9 \pm 0.5	85.4
DAN ₈	84.4 \pm 0.3	<u>80.8</u> \pm 0.4	81.7 \pm 0.2	91.7 \pm 0.3	<u>90.5</u> \pm 0.4	89.1 \pm 0.4	<u>86.4</u>
DAN _{SK}	84.1 \pm 0.4	79.9 \pm 0.4	81.1 \pm 0.5	91.4 \pm 0.3	86.9 \pm 0.5	<u>89.5</u> \pm 0.3	85.5
DAN	86.0 \pm 0.5	81.5 \pm 0.3	82.0 \pm 0.4	<u>92.0</u> \pm 0.3	92.0 \pm 0.4	90.5 \pm 0.2	87.3

Figure: Table 2. Accuracy on Office-10 + Caltech-10 dataset with standard unsupervised adaptation protocol

Data Visualization

How transferable are DAN features? t-SNE embedding for visualization

- target points form clearer class boundaries
- target points can be classified more accurately
- Source and target categories are aligned better

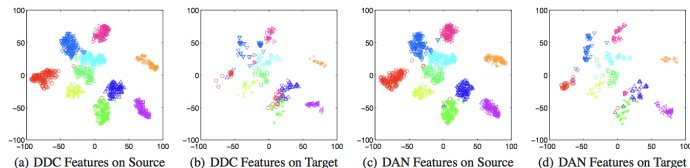


Figure: t-SNE of DDC features on source (a) and target (b) versus. t-SNE of DAN features on source (c) and target (d)

Empirical Analysis

How is generalization performance related to two-sample discrepancy?

- \hat{d}_A on CNN & DAN features $>$ \hat{d}_A on Raw features
- $\Rightarrow \hat{d}_A$ on DAN feature is much smaller than \hat{d}_A on CNN feature
- \hat{d}_A on DAN feature $<$ \hat{d}_A on CNN feature
- \Rightarrow Domain adaptation can be boosted by reducing domain discrepancy

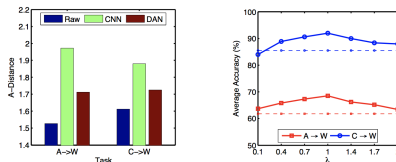


Figure: (e) A-Distance of CNN & DAN features; (f) sensitivity of λ

Summary

- DAN: A deep adaptation network for learning transferable features
- Deep adaptation of multiple task-specific layers (including output)
- Optimal adaptation using multiple kernel two-sample matching
- *A brief analysis of learning bound for the proposed deep network*