

Advanced Machine Learning Seminar 5

Exercise 1 (exercise 8.1 in the book)

Let \mathcal{H} be the class of intervals on the line (formally equivalent to axis aligned rectangles in dimension $n = 1$). Propose an implementation of the $\text{ERM}_{\mathcal{H}}$ learning rule (in the agnostic case) that given a training set of size m , runs in time $\mathcal{O}(m^2)$. Hint: Use dynamic programming.

Solution.

$$\mathcal{H}_{\text{intervals}} = \mathcal{H}_{\text{rec}}^1 = \left\{ h_{a,b}: \mathbb{R} \rightarrow \mathbb{R}, h_{a,b} = \mathbb{1}_{[a,b]}, h_{a,b}(x) = \begin{cases} 1 & x \in [a,b] \\ 0 & \text{otherwise} \end{cases}, a, b \in \mathbb{R} \right\}$$

Consider a training set S of size m :

$$S = \{(x_1, y_1), (x_2, y_2), \dots, (x_m, y_m) \mid x_i \in \mathbb{R}, y_i \in \{0, 1\}, i = \overline{1, m}\}$$

Propose an implementation of the $\text{ERM}_{\mathcal{H}}$ learning rule in the agnostic case that runs in $\mathcal{O}(m^2) \Leftrightarrow$ find a hypothesis h_{a_S, b_S} with the smallest empirical risk.

Example:

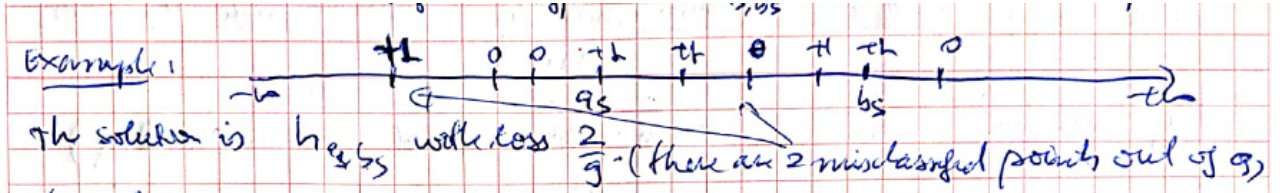


Figure 1: Example for agnostic case: 9 points scattered on the real line with some labels (5 positives and 4 negatives).

The solution for the example in Figure 2 is h_{a_S, b_S} with loss $\frac{2}{9}$ (there are 2 misclassified points out of 9).

Observations

1. We are in the agnostic case:

- it might be the case that there is no labeling function but instead we are dealing with a distribution (same point might have different labels);
- if there is a labeling function, it might not be in $\mathcal{H}_{\text{intervals}}$

2. If all points are negative, we should return an interval not containing any point in S

3. If all points are positive, we should return an interval containing all points in S

We will first sort the training set S in ascending order of x' s.

We obtain $S = \{(x_{\sigma(1)}, y_{\sigma(1)}), (x_{\sigma(2)}, y_{\sigma(2)}), \dots, (x_{\sigma(m)}, y_{\sigma(m)})\}$ with $x_{\sigma(1)} \leq x_{\sigma(2)} \leq \dots \leq x_{\sigma(m)}$.

As we are in the agnostic case, we can have $x_{\sigma(i)} = x_{\sigma(i+1)}$ and $y_{\sigma(i)} \neq y_{\sigma(i+1)}$.

Consider the set Z containing the values of x' with no repetition:

$$Z = \{z_1, z_2, \dots, z_n\}$$

$$z_1 = x_{\sigma(1)} < z_2 < \dots < z_n = x_{\sigma(m)} \quad n \leq m$$

If all initial x values are different, then $z_1 = x_{\sigma(1)}, \dots, z_n = x_{\sigma(m)}, n = m$.

Idea of the implementation of $\text{ERM}_{\mathcal{H}}$

1. If all $y_i = 0$, return an interval not containing any point x : $[z_1 - 2, z_1 - 1]$.

2. Consider all possible intervals $Z_{i,j} = [z_i, z_j]$ $i = \overline{1, n}, j = \overline{i, n}$

There are $n + (n-1) + (n-2) + \dots + 1 = \frac{n(n+1)}{2}$ such intervals.

Determine the interval $Z^* = Z_{i^*, j^*}$ with the smallest empirical risk. $Z_{i^*, j^*} = \underset{i=\overline{1, n}, j=\overline{i, n}}{\operatorname{argmin}} \operatorname{Loss}(Z_{i,j})$

How to compute very fast $\operatorname{Loss}(Z_{i,j})$? Use dynamic programming!

$\operatorname{Loss}(Z_{i,j}) = \frac{\# \text{ negative points inside } Z_{i,j} + \# \text{ positive points outside } Z_{i,j}}{m}$

Key observation: $\operatorname{Loss}(Z_{i,j+1})$ can be computed based on $\operatorname{Loss}(Z_{i,j})$.

Simple case: there is just one point (x_k, y_k) in the training set S such that $x_k = z_{j+1}$.

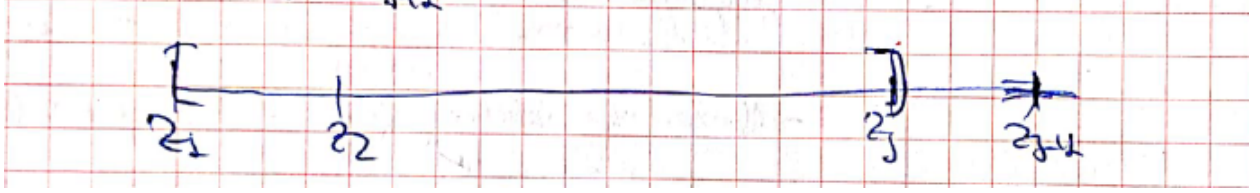


Figure 2: Sorted values z_1, z_2, \dots, z_{j+1} .

If $y_k = +1$ then $\operatorname{Loss}(Z_{i,j+1}) = \operatorname{Loss}(Z_{i,j}) - \frac{1}{m}$ (the loss decreases)

If $y_k = 0$ then $\operatorname{Loss}(Z_{i,j+1}) = \operatorname{Loss}(Z_{i,j}) + \frac{1}{m}$ (the loss increases)

General case (in the agnostic scenario)

We have multiple points $x_{k_1}, x_{k_2}, \dots, x_{k_l} = z_{j+1}$ (l points)

Then: some of the points will have label $1 = p_{j+1}$ some of the points will have label $0 = n_{j+1}$
 $p_{j+1} + n_{j+1} = l$

In this case we have that:

$$\operatorname{Loss}(Z_{i,j+1}) = \operatorname{Loss}(Z_{i,j}) - \frac{p_{j+1}}{m} + \frac{n_{j+1}}{m}$$

as p_{j+1} points will be labeled correctly now and n_{j+1} points will be labeled incorrectly now
 (if $l = 1$, we have $p_{j+1} + n_{j+1} = 1$, so we have just one point labeled positive or negative)

Efficient implementation of the ERM_H rule for $\mathcal{H}_{\text{intervals}}$

1. Sort S and obtain $x_{\sigma(1)} \leq x_{\sigma(2)} \leq \dots \leq x_{\sigma(m)}$. Build set Z containing value x without repetition:

$$Z = \{z_1, z_2, \dots, z_n\}, z_1 = x_{\sigma(1)} < z_2 < \dots < z_n = x_{\sigma(m)}$$

2. Check if all y_i $i = \overline{1, m}$ have value 0. If so, return h_{a_S, b_S} , where $a_S = z_1 - 2$, $b_S = z_1 - 1$. Compute $P = \sum_{i=1}^m y_i$ (# positive examples)

3. For $j = \overline{1, n}$

compute values $p_j = \# \text{ points } x_i = z_j \text{ with label } y_i = 1$
 $n_j = \# \text{ points } x_i = z_j \text{ with label } y_i = 0$

4. $\min_error = \frac{m}{m} = 1$, $i^* = \emptyset$, $j^* = \emptyset$

for $i = \overline{1, m}$

for $j = \overline{i, n}$

$$Z_{i,j} = [z_i, z_j]$$

if ($j == i$)

$$\operatorname{Loss}(Z_{i,j}) = \frac{P - p_j + n_j}{m}$$

else

$$\operatorname{Loss}(Z_{i,j}) = \operatorname{Loss}(Z_{i,j-1}) + \frac{n_j - p_j}{m}$$

if $\operatorname{Loss}(Z_{i,j}) < \min_error$

$$\min_error = \operatorname{Loss}(Z_{i,j})$$

$$i^* = i$$

$$j^* = j$$

5. Return i^*, j^*

Complexity:

1. sorting $\mathcal{O}(m \cdot \log m)$
2. computing $P - \mathcal{O}(m)$
3. computing $p_j, n_j - \mathcal{O}(m)$
4. Loss($Z_{i,j}$) = constant time

Total: $\mathcal{O}(m^2)$

□

Exercise 2 Let $\mathcal{X} = \mathbf{R}$ and consider \mathcal{H} the class of 3-piece classifiers (signed intervals):

$$\mathcal{H} = \{h_{a,b,s}: \mathbf{R} \rightarrow \{-1, 1\}, a \leq b, s \in \{-1, +1\}\}$$

$$\text{where } h_{a,b,s}(x) = \begin{cases} s & \text{if } x \in [a, b] \\ -s & \text{if } x \notin [a, b] \end{cases}$$

Give an efficient ERM algorithm for class \mathcal{H} and compute its complexity for each of the following cases:

- a. realizable case.
- b. agnostic case.

Solution. **a.** realizable case

There exists a function $h_{a^*, b^*, s^*} \in \mathcal{H}$ that labels the training points

$$S = \{(x_1, y_1), (x_2, y_2), \dots, (x_m, y_m)\} \quad y_i = h_{a^*, b^*, s^*}(x_i)$$

We can have the following possibilities for examples appearing in S :

$$\begin{aligned} &+++++ \quad (\text{only positive examples}) \\ &- - - - - \quad (\text{only negative examples}) \\ &+++--++ \\ &---++-- \\ &++++-- \\ &-----++ \end{aligned}$$

Consider the following algorithm

$$\begin{aligned} \text{Initialization:} \quad & a_+ = -\infty \quad a_- = -\infty \\ & b_+ = +\infty \quad b_- = +\infty \\ \text{Compute } a_+ &= \min_{\substack{i=1, m \\ y_i=+1}} x_i \quad \text{if there is no } x_i \text{ with } y_i = +1, \text{ then } a_+ = -\infty \\ b_+ &= \max_{\substack{i=1, m \\ y_i=+1}} x_i \quad \text{if there is no } x_i \text{ with } y_i = +1, \text{ then } b_+ = +\infty \\ a_- &= \min_{\substack{i=1, m \\ y_i=-1}} x_i \quad \text{if there is no } x_i \text{ with } y_i = -1, \text{ then } a_- = -\infty \\ b_- &= \max_{\substack{i=1, m \\ y_i=-1}} x_i \quad \text{if there is no } x_i \text{ with } y_i = -1, \text{ then } b_- = +\infty \end{aligned}$$

If $a_+ < a_-$ return $h_{a_+, b_+, -1}$
 else return $h_{a_+, b_+, +1}$

b. agnostic case

Can think of $\mathcal{H}_{\text{signed intervals}} = \mathcal{H}_{\text{intervals}}^+ \cup \mathcal{H}_{\text{intervals}}^-$

$$\mathcal{H}_{\text{intervals}}^+ = \left\{ h_{a,b}^+ : \mathbb{R} \rightarrow \{-1, 1\}, a \leq b, h_{a,b}^+(x) = \begin{cases} 1 & x \in [a, b] \\ -1 & x \notin [a, b] \end{cases} \right\}$$

$$\mathcal{H}_{\text{intervals}}^- = \left\{ h_{a,b}^- : \mathbb{R} \rightarrow \{-1, 1\}, a \leq b, h_{a,b}^-(x) = \begin{cases} -1 & x \in [a, b] \\ 1 & x \notin [a, b] \end{cases} \right\}$$

Use the algorithm in exercise 1 (efficient implementation of the $\text{ERM}_{\mathcal{H}}$ rule) and run it for $\mathcal{H}_{\text{intervals}}^+$ and $\mathcal{H}_{\text{intervals}}^-$.

Obtain the hypotheses h_{a^*, b^*}^+ and h_{c^*, d^*}^- .

Choose the one with the minimum empirical risk. \square

Exercise 3 (exercise 10.1 in the book)

Boosting the Confidence: Let A be an algorithm that guarantees the following: There exist some constant $\delta_0 \in (0, 1)$ and a function $m_{\mathcal{H}} : (0, 1) \rightarrow \mathbb{N}$ such that, for every $\epsilon \in (0, 1)$, if $m \geq m_{\mathcal{H}}(\epsilon)$, then, for every distribution \mathcal{D} , it holds that, with probability of at least $1 - \delta_0$, $L_{\mathcal{D}}(A(S)) \leq \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h) + \epsilon$.

Suggest a procedure that relies on A and learns \mathcal{H} in the usual agnostic PAC learning model and has a sample complexity of

$$m_{\mathcal{H}}(\epsilon, \delta) \leq k m_{\mathcal{H}}(\epsilon/2) + \left\lceil \frac{2 \log(4k/\delta)}{\epsilon^2} \right\rceil$$

where

$$k = \lceil \log(\delta/2) / \log(\delta_0) \rceil$$

Hint: Divide the data into $k + 1$ chunks, where each of the first k chunks is of size $m_{\mathcal{H}}(\epsilon/2)$ examples. Train the first k chunks using A . Argue that the probability that for all these chunks we have $L_{\mathcal{D}}(A(S)) > \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h) + \epsilon$ is at most $\delta_0^k \leq \delta/2$. Finally, use the last chunk to choose from the k hypotheses that A generated from the k chunks (by relying on Corollary 4.6).

Corollary 4.6. Let \mathcal{H} be a finite hypothesis class, let Z be a domain, and let $\ell : \mathcal{H} \times Z \rightarrow [0, 1]$ be a loss function. Then, \mathcal{H} enjoys the uniform convergence property with sample complexity

$$m_{\mathcal{H}}^{UC}(\epsilon, \delta) \leq \left\lceil \frac{\log(2|\mathcal{H}|/\delta)}{2\epsilon^2} \right\rceil$$

Furthermore, the class is agnostically PAC learnable using the ERM algorithm with sample complexity

$$m_{\mathcal{H}}(\epsilon, \delta) \leq m_{\mathcal{H}}^{UC}(\epsilon/2, \delta) \leq \left\lceil \frac{2 \log(2|\mathcal{H}|/\delta)}{\epsilon^2} \right\rceil$$

Solution. A algorithm with the following property: $\exists \delta_0 \in (0, 1)$ and $m_{\mathcal{H}} : (0, 1) \rightarrow \mathbb{N}$ such that for every $\epsilon \in (0, 1)$ if $m \geq m_{\mathcal{H}}(\epsilon)$ then for every distribution \mathcal{D} it holds

$$\mathbb{P}_{S \sim \mathcal{D}^m} \left(L_{\mathcal{D}}(A(S)) \leq \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h) + \epsilon \right) \geq 1 - \delta_0$$

Suggest a procedure based on algorithm A that learns \mathcal{H} in the agnostic PAC setting and has a sample complexity of

$$m_{\mathcal{H}}(\epsilon, \delta) \leq k * m_{\mathcal{H}}(\epsilon/2) + \left\lceil \frac{2 \log(4k/\delta)}{\epsilon^2} \right\rceil \quad \text{where } k = \left\lceil \frac{\log \delta/2}{\log \delta_0} \right\rceil$$

Definition of agnostic PAC: \mathcal{H} is agnostic PAC if there exists a function $m_{\mathcal{H}} : (0, 1)^2 \rightarrow \mathbb{N}$ and a learning algorithm A' with the following property: $\forall \epsilon > 0, \forall \delta > 0, \forall \mathcal{D}$ distribution function over $Z = \mathcal{X} \times \{0, 1\}$ when we run the algorithm A' on a training set S of $m \geq m_{\mathcal{H}}(\epsilon, \delta)$ examples sampled i.i.d. from \mathcal{D} , A' returns $h_S = A'(S)$ such that

$$\mathbb{P}_{S \sim \mathcal{D}^m} \left(L_{\mathcal{D}}(h_S) \leq \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h) + \epsilon \right) \geq 1 - \delta$$

This is equivalent to:

$$P_{S \sim \mathcal{D}^m} \left(L_{\mathcal{D}}(h_S) > \underbrace{\min_{h \in \mathcal{H}} L_{\mathcal{D}}(h) + \epsilon}_{\min_{h \in \mathcal{H}} L_{\mathcal{D}}(h) + \frac{\epsilon}{2} + \frac{\epsilon}{2}} \right) < \delta$$

Follow the indications.

Let $\epsilon, \delta \in (0, 1)$. Pick k “chunks” S_1, S_2, \dots, S_k of size $m_{\mathcal{H}}(\frac{\epsilon}{2})$. Use the property of the algorithm A given.

$$\begin{aligned} \forall i = \overline{1, k} \quad & A(S_i) = h_i \\ P_{S_i \sim \mathcal{D}^{m_{\mathcal{H}}(\frac{\epsilon}{2})}} \left(L_{\mathcal{D}}(h_i) \leq \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h) + \frac{\epsilon}{2} \right) & \geq 1 - \delta_0 \\ \Leftrightarrow P_{S_i \sim \mathcal{D}^{m_{\mathcal{H}}(\frac{\epsilon}{2})}} \left(L_{\mathcal{D}}(h_i) > \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h) + \frac{\epsilon}{2} \right) & < \delta_0 \quad (\text{the probability of having a bad } h_i) \end{aligned}$$

The probability that all $h_i, i = \overline{1, k}$ are bad is given by:

$$\begin{aligned} P \left(L_{\mathcal{D}}(h_1) > \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h) + \frac{\epsilon}{2} \text{ and } L_{\mathcal{D}}(h_2) > \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h) + \frac{\epsilon}{2} \text{ and } \dots \right) & < (\delta_0)^k \\ \text{Find } k \text{ such that } \delta_0^k & < \delta/2 \\ \Leftrightarrow k \cdot \ln \delta_0 < \ln \frac{\delta}{2} \quad \Big| : \ln \delta_0 \\ k & \geq \left\lceil \frac{\ln \delta - \ln 2}{\ln \delta_0} \right\rceil \end{aligned}$$

Consider $\mathcal{H}' = \{h_1, h_2, \dots, h_k\}$. \mathcal{H}' finite, apply Corrolary (4.6).

If $m \geq m_{\mathcal{H}}^{UC}(\epsilon/2, \delta/2) \leq \left\lceil \frac{2 \log(4k/\delta)}{\epsilon^2} \right\rceil$ we have that

$$P_{S_{k+1} \sim \mathcal{D}^{m_{\mathcal{H}}^{UC}(\epsilon/2, \delta/2)}} \left(L_{\mathcal{D}}(h_{k+1}) > \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h) + \frac{\epsilon}{2} \right) < \frac{\delta}{2}$$

S_{k+1} has $\left\lceil \frac{2 \log(4k/\delta)}{\epsilon^2} \right\rceil$ examples.

So: $L_{\mathcal{D}}(h_{k+1}) > \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h) + \epsilon$ if either we have

$$\begin{aligned} \text{A: all } h_i \text{ are bad: } & L_{\mathcal{D}}(h_i) > \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h) + \frac{\epsilon}{2} \\ \text{B: } h_{k+1} \text{ is bad: } & L_{\mathcal{D}}(h_{k+1}) > \min_{h \in \mathcal{H}'} L_{\mathcal{D}}(h) + \frac{\epsilon}{2} \end{aligned}$$

$$P(A \cup B) \leq P(A) \cup P(B) = \frac{\delta}{2} + \frac{\delta}{2} = \delta.$$

$$\text{So, take } m = k \cdot m_{\mathcal{H}}(\frac{\epsilon}{2}) + \left\lceil \frac{2 \log(4k/\delta)}{\epsilon^2} \right\rceil, k = \left\lceil \frac{\ln \delta - \ln 2}{\ln \delta_0} \right\rceil$$

$$\underbrace{(S_1, S_2, \dots, S_k)_{h_1, h_2, \dots, h_k}}_{\downarrow h_{k+1}} (L_{\mathcal{D}}(h_{k+1}) > \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h) + \epsilon) < \delta \quad \checkmark$$

□