

# Statistics for Data Science

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# References

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# Introduction

Def.  $(\Omega, \mathcal{K}, P)$  is called a probability space, where

1)  $\Omega$  - sample space = the set of all possible outcomes

2)  $\mathcal{K} \subset \mathcal{P}(\Omega)$  the power set of  $\Omega$  (the set of all subsets of  $\Omega$ )

$\mathcal{K}$  is a  $\sigma$ -algebra  $\left[ \begin{array}{l} \emptyset \in \mathcal{K} \\ A \in \mathcal{K} \Rightarrow \bar{A} \in \mathcal{K} \\ A_n \in \mathcal{K} \Rightarrow \bigcup_{n=1}^{\infty} A_n \in \mathcal{K} \end{array} \right.$

3)  $P: \mathcal{K} \rightarrow [0, 1]$  is a probability measure function

$$P(\Omega) = 1$$

- a measure function:  $\left[ \begin{array}{l} P: \mathcal{K} \rightarrow [0, \infty) \\ P(\emptyset) = 0 \\ P\left(\bigcup_{n=1}^{\infty} A_n\right) = \sum_{n=1}^{\infty} P(A_n) \text{ if } A_n \in \mathcal{K}, \\ A_i \cap A_j = \emptyset, \forall i \neq j. \end{array} \right.$

The elements of  $\mathcal{K}$  are called random events.

# Introduction

Def. If  $S$  is a set, the  $\sigma$ -algebra generated by  $S$ , written  $\mathcal{B}(S)$ , is:

$$\mathcal{B}(S) \stackrel{\text{def}}{=} \bigcap_{\substack{\mathcal{F} \supset S \\ \mathcal{F} \text{ is } \sigma\text{-algebra}}} \mathcal{F}$$

If  $S = \mathbb{R}$  then  $\mathcal{B}(S) = \mathcal{B}((a, b) \mid a, b \in \mathbb{R})$

If  $S$  is finite or countable then  $\mathcal{B}(S) = \mathcal{P}(S)$ .

$(S, \mathcal{B}(S))$  is a measurable space.

Def.  $X: (\Omega, \mathcal{X}) \rightarrow (S, \mathcal{B}(S))$  is a random variable if  
 $\forall B \in \mathcal{B}(S) \Rightarrow X^{-1}(B) \in \mathcal{X}$ .

$$P \circ X^{-1}: \mathcal{B}(S) \rightarrow [0, 1], \quad (P \circ X^{-1})(B) = P(X^{-1}(B))$$



# Introduction

The cumulative distribution function (CDF) of  $X$  is

$$F(x) \stackrel{\text{def}}{=} (P \circ X^{-1})(-\infty, x) = P(X < x)$$

$$F: \mathbb{R} \rightarrow [0, 1]$$

$$F(-\infty) = 0; \quad F(\infty) = 1; \quad F \text{ is monotonically increasing}$$

- for  $X$  a continuous random variable,  $P \circ X^{-1}$  is specified by the density function  $f(x)$ ,

$$f(x) \geq 0 \quad \forall x$$

$$\int_{-\infty}^{\infty} f(x) dx = 1$$

$$f(x) = F'(x)$$

$$F(x) = \int_{-\infty}^x f(t) dt$$

# Introduction

- for  $X$  a discrete random variable,  $P \circ X^{-1}$  is specified by  $\{p(x), x \in S\}$ ,  $p(x) \geq 0, \forall x$

$$\sum_{x \in S} p(x) = 1$$

$$X = \begin{pmatrix} x_1 & \dots & x_n \\ p_1 & \dots & p_n \end{pmatrix}$$

$$F(x) = \sum_{x_i < x} P(x = x_i)$$

$$E(X) = \int_{-\infty}^{\infty} x f(x) dx \quad \left( \text{or } \sum_{i=1}^n x_i p_i \text{ for the discrete case} \right)$$

$$\text{Var}(X) = E((X - E(X))^2) = E(X^2) - E(X)^2$$

$$\sigma = \sqrt{\text{Var}(X)} \quad - \text{ standard deviation}$$

# Stochastic models of different phenomena of interest

- Categorical random variables/vectors.
- Quantitative discrete/continuous random variables/vectors.

Def. A stochastic process is a family of random variables  $\{X_t, t \in T\}$  defined on a probability space  $(\Omega, \mathcal{K}, P)$ .

time  $T$ , states  $S$

< time  $\mathbb{N} / \mathbb{Z} / \mathbb{R} / [0, \infty)$   
state discrete /  $\mathbb{R} / \mathbb{R}^d$



# Stochastic models of different phenomena of interest

- Observations in "transversal" studies (at a fixed moment of time)  
 $\{X_1, \dots, X_n\}$  random variables, independent and identically distributed (iid) like the stochastic model  $X: \Omega \rightarrow S$ .  
Statistical data are the observed values  $(x_1, \dots, x_n) \in S^n$ .
- Observations in "longitudinal" studies (on a fixed time interval)  
 $\{X_t, t \leq t_n\} \subset \{X_t, t \in T\}$   
statistical data are the observed part of the process trajectory  $(x_t, t \leq t_n)$



# Stochastic models of different phenomena of interest

## Parametric statistics

Hypothesis: statistical data come from a stochastic model whose distribution has a known functional form, but it depends on an unknown parameter  $\theta \in \mathbb{R}^k$ ,  $k \geq 1$ .

- Statistical data are available;
- Looking for estimators of  $\theta$  or tests on hypotheses over  $\theta$ .

# Example of stochastic models

1. categorical 1-dim random variable

$X$  = satisfaction degree

$S = \{vun, un, se, vse\}$

$$P_{0X^{-1}} = \begin{pmatrix} vun & un & se & vse \\ p_1 & p_2 & p_3 & p_4 \end{pmatrix} \quad \begin{matrix} p_i \geq 0 \\ \sum_{i=1}^4 p_i = 1 \end{matrix}$$

2. categorical 2-dim random vector

$X = (X_1, X_2)' = (\text{intention to vote, satisfaction degree about the current situation})$

$S = \{(\text{yes}, vun), (\text{yes}, un), (\text{yes}, se), (\text{yes}, vse),$   
 $(\text{no}, vun), (\text{no}, un), (\text{no}, se), (\text{no}, vse)\}$

# Example of stochastic models

Quantitative discrete random variables

3. discrete uniform distribution - e.g. rolling a dice

$$X \sim U\{1, \dots, n\}, \quad n \in \mathbb{N}, \quad n \geq 2$$

$$S = \{1, 2, \dots, n\}$$

$$P(X=x) = \frac{1}{n}, \quad x = 1, 2, \dots, n$$

$$E(X) = \frac{n+1}{2}$$

$$\text{Var}(X) = \frac{n^2-1}{12}$$



# Example of stochastic models

4. Bernoulli distribution – e.g. having “success” in a trial with two possible outcomes: success/failure.

$$X \sim B(1, \theta), \quad \theta \in (0, 1) \quad S = \{0, 1\}$$

$$P_{\theta}(X=x) = \theta^x (1-\theta)^{1-x}, \quad x=0, 1$$

$$X: \begin{pmatrix} 0 & 1 \\ 1-\theta & \theta \end{pmatrix}$$

$$E(X) = \theta$$

$$\text{Var}(X) = \theta(1-\theta)$$



# Example of stochastic models

5. Binomial distribution – e.g. number of "successes" in  $n$  independent trials with two possible outcomes: success/failure.

$$X \sim \text{Bi}(n, \theta), \quad \theta \in (0, 1), \quad S = \{0, 1, \dots, n\}$$

$$P_{\theta}(X=x) = C_n^x \cdot \theta^x (1-\theta)^{n-x}, \quad x = 0, 1, \dots, n$$

$$E(X) = n \cdot \theta$$

$$\text{Var}(X) = n \cdot \theta (1-\theta)$$

# Example of stochastic models

6. Poisson distribution - e.g. number of defective devices in a very large volume lot.

$$X \sim \text{Po}(\theta), \quad \theta \in (0, \infty), \quad S = \mathbb{N}$$

$$P_{\theta}(X=x) = \frac{\theta^x}{x!} e^{-\theta}, \quad x=0,1,\dots$$

$$E(X) = \theta$$

$$\text{Var}(X) = \theta$$

# Example of stochastic models

7. Geometric distribution - e.g. the moment of the first "success" in a sequence of independent trials with two possible outcomes: success/failure.

$$X \sim \text{Ge}(\theta), \quad \theta \in (0,1), \quad S = \mathbb{N}^*$$

$$P_{\theta}(X=x) = (1-\theta)^{x-1} \cdot \theta \quad x=1,2,\dots$$

$$E(X) = \frac{1}{\theta}$$

$$\text{Var}(X) = \frac{1-\theta}{\theta^2}$$



# Example of stochastic models

Quantitative discrete random vectors

8. Multinomial distribution - e.g. sampling with replacement  
 $n$  trials - extractions from a ballot box containing balls  
of  $d$  colors

$$X = (x_1, \dots, x_d)' \sim M(n; p_1, \dots, p_d)$$

$$P_{\theta}(X = (x_1, \dots, x_d)') = \frac{n!}{x_1! \dots x_d!} p_1^{x_1} \dots p_d^{x_d}, \text{ where}$$

$$S = \left\{ (x_1, \dots, x_d)' \mid x_i \in \{0, 1, \dots, n\} \forall i = \overline{1, d}, \sum_{i=1}^d x_i = n \right\}$$

$$\theta = (p_1, \dots, p_d), \quad p_i \in [0, 1] \forall i = \overline{1, d}, \sum_{i=1}^d p_i = 1$$

$$E(x_i) = np_i \quad i = \overline{1, d}$$

$$\text{Var}(x_i) = np_i(1-p_i)$$

$$\text{Cov}(x_i, x_j) = -np_i p_j, \quad i \neq j$$



# Example of stochastic models

Quantitative continuous random variables

9. Continuous uniform distribution - e.g. throw a dart at random at the interval  $[0, \theta]$  - all the points are equally likely to be hit.

$$X \sim U(0, \theta), \theta \in (0, \infty)$$

$$f(x; \theta) = \begin{cases} \frac{1}{\theta} & , x \in [0, \theta] \\ 0 & , x \notin [0, \theta] \end{cases}$$

$$E(X) = \frac{\theta}{2}$$

$$\text{Var}(X) = \frac{\theta^2}{12}$$

# Example of stochastic models

10. Exponential distribution - e.g. the simplest model for lifetime

$$X \sim \text{Exp}(\theta), \quad \theta \in (0, \infty)$$

$$f(x; \theta) = \begin{cases} \frac{1}{\theta} \exp\left(-\frac{x}{\theta}\right), & x \in [0, \infty) \\ 0, & x \in (-\infty, 0) \end{cases}$$

$$E(X) = \theta$$

$$\text{Var}(X) = \theta^2$$

# Example of stochastic models

11. Gamma distribution - e.g. general model for lifetime

$$X \sim \text{Gamma}(\alpha, \theta), \quad \alpha \in (0, \infty), \quad \theta \in (0, \infty)$$

$$f(x; \alpha, \theta) = \begin{cases} \frac{1}{\Gamma(\alpha) \cdot \theta^\alpha} \cdot x^{\alpha-1} \cdot \exp\left(-\frac{x}{\theta}\right), & x \in [0, \infty) \\ 0, & x \in (-\infty, 0) \end{cases}, \text{ where}$$

$$\Gamma(\alpha) = \int_0^\infty x^{\alpha-1} e^{-x} dx$$

$$E(X) = \alpha \cdot \theta$$

$$\text{Var}(X) = \alpha \cdot \theta^2$$

# Example of stochastic models

12. Normal (Gaussian) distribution

$$X \sim N(\mu, \sigma^2), \quad \theta = (\mu, \sigma^2) \in \mathbb{R} \times (0, \infty)$$

$$f(x; \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \cdot \exp\left(-\frac{1}{2\sigma^2}(x-\mu)^2\right), \quad x \in \mathbb{R}$$

$$E(X) = \mu$$

$$\text{Var}(X) = \sigma^2$$



# Example of stochastic models

Quantitative continuous random vectors

13. Normal distribution  $N(d; 0, I)$

- is the product of  $d$  normal distributions  $N(0, 1)$

$$X = (x_1, \dots, x_d)' \sim N(d; 0, I)$$

$$f(x) = \frac{1}{(2\pi)^{d/2}} \cdot \exp\left\{-\frac{1}{2} x' x\right\}, \quad x = (x_1, \dots, x_d)' \in \mathbb{R}^d$$

# Example of stochastic models

Quantitative continuous random vectors

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14. Normal distribution  $N(d; \mu, \Sigma)$

$$X = (x_1, \dots, x_d)' \sim N(d; \mu, \Sigma)$$

$$f(x; \mu, \Sigma) = \frac{1}{(2\pi)^{d/2} (\det \Sigma)^{1/2}} \cdot \exp\left\{-\frac{1}{2} (x - \mu)' \Sigma^{-1} (x - \mu)\right\},$$

$$x = (x_1, \dots, x_d)' \in \mathbb{R}^d$$

$$E(X) = \mu$$

$$\text{Cov}(X, X') = E\left((X - E(X))(X - E(X))'\right) = \Sigma$$

$\Sigma$  is symmetric and positive definite matrix

# To do:

Write algorithms to generate the following random variables/vectors:

$$1) \quad X = \begin{pmatrix} a_1 & a_m \\ p_1 & p_m \end{pmatrix} \quad \sum_{i=1}^m p_i = 1, \quad p_i \geq 0$$

$$2) \quad X \sim \text{Ge}(\theta) \quad \theta \in (0, 1)$$

$$3) \quad X = (X_1, \dots, X_d)' \sim M(n; p_1, \dots, p_d) \quad \sum_{i=1}^d p_i = 1, \quad p_i \geq 0$$