Rubiks-cube robot

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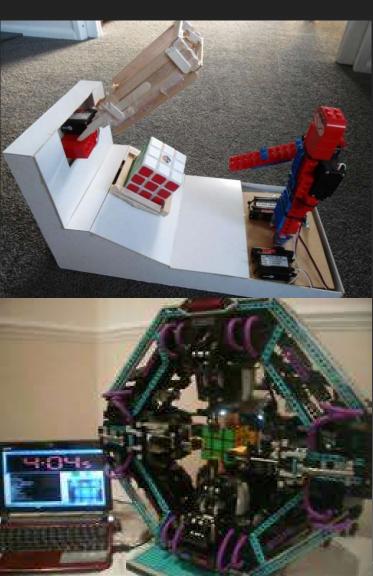


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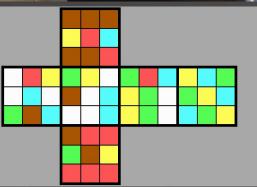
Idea

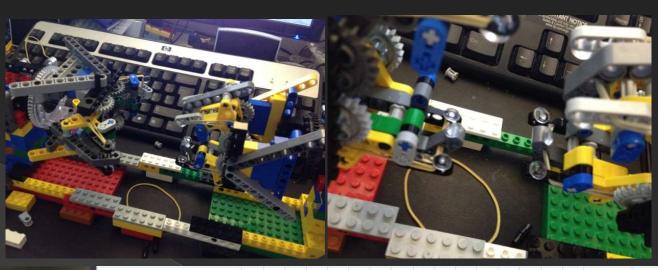




Proceed







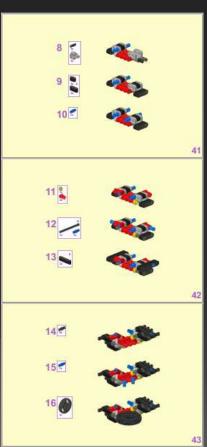


	_																	
		Projektplan																
Aufgaben	04.03.2016	11.03.2016	18.03.2016	25.03.2016	01.04.2016	08.04.2016	15.04.2016	22.04.2016	29.04.2016	06.05.2016	13.05.2016	20.05.2016	27.05.2016	03.06.2016	10.06.2016	17.06.2016		
Requirement schreiben	x	x																
Projektplan					x													
Einkauf der Bauteie			x	x														
Erster Roboterprototyp						х	x											
Code für ansteuerung der Motoren								x										
evt Prototyp verbessern								x										
Code für Farbensensor/tests									x									
Roboter komplett zusammenbauen									x	x								
Code fürx and o's algorithmus						х	x				x	x	x	x				
Vortrag																		
Projektdoku					x			х		x		x		x		x		
Produktdoku					x			х		x		x		x		x		
Optimierung Code(vgeschwindigkeit))													х	x	x		
Gliederung Texte überarbeiten															x	x		
Soll Stunden(ohne Schulzeit):	0.25	0.25	2	0.5	5	20	20	20	20	25	20	30	20	20	25	20	248	Total
Ist Stunden(ohne Schulzeit):	0.5	0	3	1	4.5	25	20	23	21	30	25	24	25	30	35	40	307	Erledigt
Differenz:	0.25	-0.3	1	0.5	-0.5	5	0	3	1	5	5	-6	5	10	10	20	59	Zu tun

Proceed

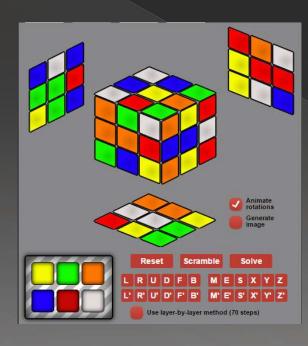
- 2nd robot
- Color sensor





Good / bad

- expiration of the code
- Prototype
- Time
- Guide
- Internet

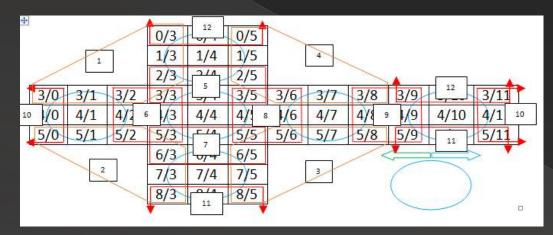


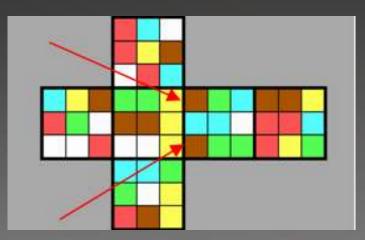
- Connection
- Color sensor
- Debugging
- Trial account

Problems

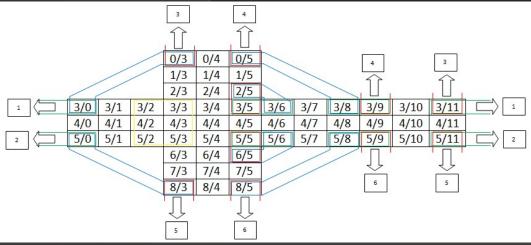
- Can't connect two bricks
- Color sensor are inaccurate
- 2nd robot
- Time
- Wlan-module
- debugging

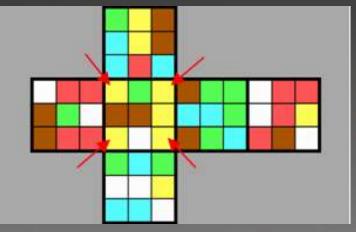
```
#define T() R_fehler(0,"Test","#makro");
#define E(a) int32_disable_gm();printformat("%d",a);W(1);
#define M() R_Show_Muster();W(1);
```





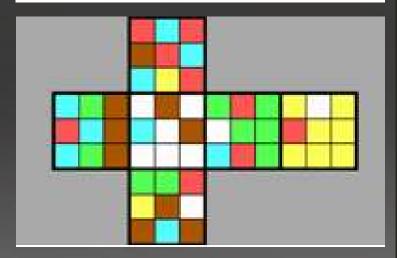
```
R_Berechnungen = R_Berechnungen + 2;
if((RubiksFeld[3][9] == RubiksFeld[3][11]) && (RubiksFeld[0][3] == RubiksFeld[0][5]))
       R Stage 0 Status = 1;
       R_Stage_0_2erPos[11] = 1;
       R_Stage_0_2erStatus = R_Stage_0_2erStatus + R_Stage_0_2erPos[var_i];
if(R_Stage_0_2erStatus > 0)
        //wenn eine andere seitenicht geht wieder in uhrstellung gehen und 90 grad daneben drhehen
        switch(R_Stage_0_ausrichtung)
               case(0)://F
                       R_Stage_0_ausrichtung = 1;
                       R MoveCube_F();
                       R_LWeg[R_LWeg_pointer] = C_F;
                       R_LWeg_pointer++;
               case(1)://Fi
                       R_Stage_0_ausrichtung = 0;
                       R_MoveCube_Fi();
                       R_LWeg[R_LWeg_pointer] = 0; //0 ist kein zug, daher nix
                       R_LWeg_pointer--;
                       R Zuege--;
```





```
R_Berechnungen = R_Berechnungen + 2;
if((RubiksFeld[2][3] == RubiksFeld[3][0]) && (RubiksFeld[3][3] == RubiksFeld[0][3]))
       flag_stein_1 = 1;
        R_MoveCube_D();
        R_LWeg[R_LWeg_pointer] = C_D;
       R_LWeg_pointer++;
        R_MoveCube_Bi();
        R_LWeg[R_LWeg_pointer] = C_Bi;
        R_LWeg_pointer++;
        R_MoveCube_D();
       R_LWeg[R_LWeg_pointer] = C_D;
        R_LWeg_pointer++;
        R_MoveCube_D();
        R_LWeg[R_LWeg_pointer] = C_D;
        R_LWeg_pointer++;
       R_MoveCube_B();
       R_LWeg[R_LWeg_pointer] = C_B;
        R_LWeg_pointer++;
R_Berechnungen = R_Berechnungen + 2;
if((RubiksFeld[2][3] == RubiksFeld[0][3]) && (RubiksFeld[3][3] == RubiksFeld[3][0]))
       flag_stein_1 = 1;
       R_fehler(2,"W[flag_stein_1]","6. blaue möglichkeit B [0/3 3/0]");
```

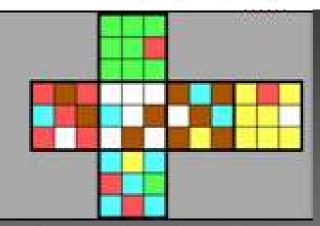
			0/3	0/4	0/5	ľ					
			1/3	1/4	1/5	i.					
			2/3	2/4	2/5						
3/0	3/1	3/2	3/3	3/4	3/5	3/6	3/7	3/8	3/9	3/10	3/11
4/0	4/1	4/2	4/6	4/4	4)5	4/6	4/7	4/8	4/9	4/10	4/11
5/0	5/1	5/2	5/3	5/4	3/5	5/6	5/7	5/8	5/9	5/10	5/11
			6/3	6/4	6/5						
			7/3	7/4	7/5						
			8/3	8/4	8/5						



```
F(var_j,4)
        R_Berechnungen = R_Berechnungen + 4;
if((RubiksFeld[4][4] == RubiksFeld[3][2]) && (RubiksFeld[4][4] == RubiksFeld[3][4]
                 R_MoveCube_R();
                 R_LWeg[R_LWeg_pointer] = C_R;
                 R_LWeg_pointer++;
                 R_MoveCube_U();
                 R_LWeg[R_LWeg_pointer] = C_U;
                 R_LWeg_pointer++;
                 R_MoveCube_Ri();
                 R_LWeg[R_LWeg_pointer] = C_Ri;
                 R_LWeg_pointer++;
                 R_MoveCube_Ui();
                 R_LWeg[R_LWeg_pointer] = C_Ui;
                 R_LWeg_pointer++;
                 R_MoveCube_Fi();
                 R_LWeg[R_LWeg_pointer] = C_Fi;
                 R_LWeg_pointer++;
                 R_MoveCube_Ui();
                R_LWeg[R_LWeg_pointer] = C_Ui;
R_LWeg_pointer++;
                 R_MoveCube_F();
                 R_LWeg[R_LWeg_pointer] = C_F;
                 R_LWeg_pointer++;
                 switch(var_j)
                         case (3):
                                  R_Turn_Cubeandway(VC_nC);
                         case (2):
                                 R_Turn_Cubeandway(VC_nC);
                         case (1):
                                 R_Turn_Cubeandway(VC_nC);
                          default:{R_Stage_2_Status = 1; break;}
                 var_j = 4;
                 R_Turn_Cubeandway(VC_C);
```

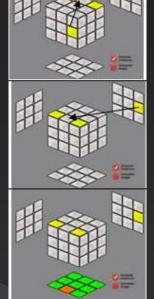
Möglicher Zustand:	Massnahme (Algorithmus):
	RURIWIFIWIF
T-Zustand	50:50:00
L-Zustand	FRI FI WI RI U R
L-Zustand	DILD: UP OUD:
	RU Ri UR 2U Ri
M-Zustand	
Mi-Zustand	Ri UI R UI Ri 2U R
Pi-Zustand	B U 2 B 2 U i B 2 U i B 2 U 2 B
U-Zustand	RIFIUIFUR
H-Zustand	2R 2U <u>Ri</u> 2U 2R

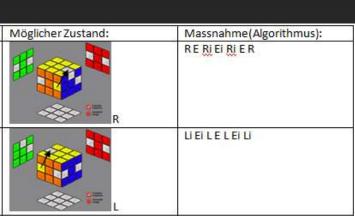
			0/3	0/4	0/5						
			1/3	1/4	1/5						
			2/3	2/4	2/5		-				
3/0	3/1	3/2	3/3	1	3/5/	3/6	3/7	3/8	3/9	3/10	3/11
4/0	4/1	4/2	4/6	4/4	4)5	4/6	4/7	4/8	4/9	4/10	4/11
5/0	5/1	5/2	5/3	5/4	5/5	5/6	5/7	5/8	5/9	5/10	5/11
	Ċ.	W	6/3	6/4	6/5			5	55		
			7/3	7/4	7/5						
			8/3	8/4	8/5	8					



30			0/3	0/4	0/5	ii					
			1/3	1/4	1/5	3					
			2/3	2/4	2/5	3-4					
3/0	3/1	3/2	3/3	3/4	3/5	3/6	3/7	3/8	3/9	3/10	3/11
4/0	4/1	4/2	4/3	4/4	4/5	4/6	4/7	4/8	4/9	4/10	4/11
5/0	5/1	5/2	5/3	5/4	5/5	5/6	5/7	5/8	5/9	5/10	5/11
900			6/3	6/4	6/5						- 10
			7/3	7/4	7/5	8					
			8/3	8/4	8/5						







```
if((RubiksFeld[3][3] == RubiksFeld[4][6]) && (RubiksFeld[2][3] == RubiksFeld[4][5]))// 4/6 4/5
       R_MoveCube_Ri();
       R_LWeg[R_LWeg_pointer] = C_Ri;
       R_LWeg_pointer++;
       R_MoveCube_Ei();
       R_LWeg[R_LWeg_pointer] = C_Ei;
       R_LWeg_pointer++;
       R_MoveCube_R();
       R_LWeg[R_LWeg_pointer] = C_R;
       R_LWeg_pointer++;
       R_MoveCube_B();
       R_LWeg[R_LWeg_pointer] = C_B;
       R_LWeg_pointer++;
       R_MoveCube_Ei();
       R_LWeg[R_LWeg_pointer] = C_Ei;
       R_LWeg_pointer++;
       R_MoveCube_Bi();
       R_LWeg[R_LWeg_pointer] = C_Bi;
       R_LWeg_pointer++;
```

```
var_k = 0;
R_Berechnungen = R_Berechnungen + 4;
if((RubiksFeld[7][4] == RubiksFeld[7][5]) && (RubiksFeld[4][7] == RubiksFeld[5][7]) && (var_k == 0)){var_k++;}
if((RubiksFeld[7][4] == RubiksFeld[5][7]) && (RubiksFeld[4][7] == RubiksFeld[7][5]) && (var_k == 0)){var_k++;}
R_Berechnungen = R_Berechnungen + 4;
if((RubiksFeld[4][1] == RubiksFeld[5][1]) && (RubiksFeld[7][4] == RubiksFeld[7][3]) && (var_k == 0)){var_k++;}
if((RubiksFeld[4][1] == RubiksFeld[7][3]) && (RubiksFeld[7][4] == RubiksFeld[5][1]) && (var_k == 0)){var_k++;}
R_Berechnungen = R_Berechnungen + 4;
if((RubiksFeld[4][1] == RubiksFeld[3][1]) && (RubiksFeld[1][4] == RubiksFeld[1][3]) && (var_k == 0)){var_k++;}
if((RubiksFeld[4][1] == RubiksFeld[1][3]) && (RubiksFeld[1][4] == RubiksFeld[3][1]) && (var_k == 0)){var_k++;}
R_Berechnungen = R_Berechnungen + 4;
if((RubiksFeld[1][4] == RubiksFeld[1][5]) && (RubiksFeld[4][7] == RubiksFeld[3][7]) && (var_k == 0)){var_k++;}
if((RubiksFeld[1][4] == RubiksFeld[3][7]) && (RubiksFeld[4][7] == RubiksFeld[1][5]) && (var_k == 0)){var_k++;}
if(var_k == 0)
       R MoveCube Ei();
       R_LWeg[R_LWeg_pointer] = C_Ei;
       R_LWeg_pointer++;
       R_MoveCube_B();
       R_LWeg[R_LWeg_pointer] = C_B;
       R_LWeg_pointer++;
       R_MoveCube_B();
       R_LWeg[R_LWeg_pointer] = C_B;
       R_LWeg_pointer++;
       R MoveCube E();
       R_LWeg[R_LWeg_pointer] = C_E;
       R LWeg pointer++;
       R_MoveCube_B();
       R_LWeg[R_LWeg_pointer] = C_B;
       R_LWeg_pointer++;
       R_MoveCube_B();
       R_LWeg[R_LWeg_pointer] = C_B;
       R_LWeg_pointer++;
var_k = 0;
```

Möglicher Zustand:	Massnahme (Algorithmus):
3 Falsch	Ei 2B E 2B
2 Falsch	Mi <u>Ui</u> Mi <u>Ui</u> Mi 2Ui M <u>Ui</u> M <u>Ui</u> M 2Ui

	0/3	0/4	0/5						
	1/3	1/4	1/5						
24 4 32 32	2/3	2/4	2/5	ed G	22 22 1		47	300 000	cy <u>se</u>
3/0 3/1 3/2	3/3	3/4	3/5	3/6	3/7	3/8	3/9	3/10	3/11
4/0 4/1 4/2	4/3	4/4	4/5	4/6	4/7	4/8	4/9	4/10	4/11
5/0 5/1 5/2	5/3	5/4	5/5	5/6	5/7	5/8	5/9	5/10	5/11
	6/3	6/4	6/5						
	7/3	7/4	7/5						
8	8/3	8/4	8/5	5					

How i test it

```
float solvecounter = 0;
int as = 3,
    bs = 13,
    cs = 14,
    ds = 16,
    es = 18,
    fs = 23,
    gs = 9,
    hs = 38,
    is = 34;
    //zufallsgenerator
```

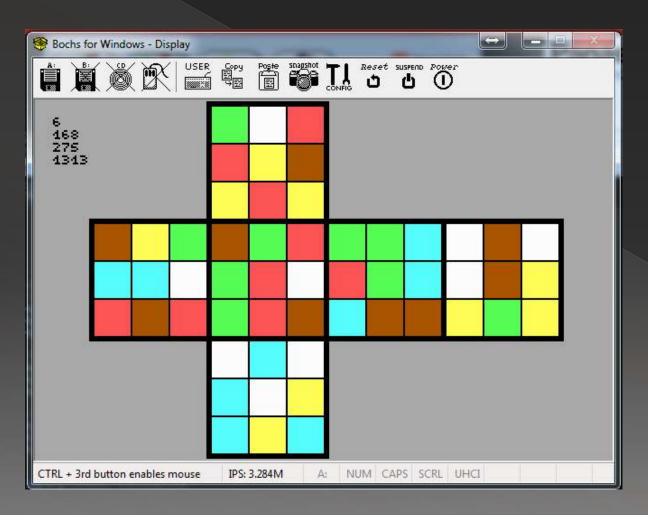
```
//Arrayfeld sit rubiks farben
char Rubiksfeld[s][12] = {//Default stellung/Ziel
char Rubiksfeld[s][12] = {//Default stellung/Ziel
char Rubiksfeld[s][12] = {//Default stellung/Ziel
char Control Contr
```

```
void R_Scan(void)
       char wahl = 0;
       char R_Scan_counter = 0;
       while(R_Scan_counter != 40)
               R_Scan_counter++;
               wahl = ((as + bs + cs + ds + es + fs) * (gs + hs + is))% 16 + 1;
               cs = (as + bs) % 13;
               fs = (ds + es) \% 17;
               is = (gs + hs) % 19;
               as = as % 20;
               bs = bs % 20;
               ds = ds % 20;
               es = es % 20;
               gs = gs % 20;
hs = hs % 20;
               switch(wahl)
                       case(0):
                               bs = bs + 2;
                               ds = ds + 3;
                               es = es + 5;
                               gs = gs + 2;
                               hs = hs + 4;
                               R_MoveCube_R();
                       case(1):
                               as = as + 2;
                               bs = bs + 6;
                               ds = ds + 5;
                               es = es + 1;
                               gs = gs + 3;
                                hs = hs + 4;
                               R_MoveCube_Ri();
```

```
//was muss gedreht werdne
switch(R_LWegReal[pointer])
{
    case(C_R):
        {
             cube_setmotor(hinten);
             cube_setmotor(kralle);
             cube_setmotor(kralle);
             cube_setmotor(kralle);
             cube_setmotor(kralle);
             cube_setmotor(clockk);
             cube_setmotor(hinten);
             cube_setmotor(kralle);
             cube_setmotor(kralle);
             pointer++;
             break;
        }
}
```

```
case(hinten):
        switch(pos)
                case(kralle):
                        moveMotorTarget(motorA, 160, -50);sleep(1500);
                        cube_oldpos = kralle;
                        break;
                case(halte):
                        moveMotorTarget(motorA, 140, -50);sleep(1500);
                        cube_oldpos = halte;
                        break;
               case(C_Mi):
                       R_LWegReal[pointer] = C_Ri;
                       pointer++;
                       R_LWegReal[pointer] = C_L;
                       pointer++;
                       break;
               case(C_S):
                       R_LWegReal[pointer] = C_B;
                       pointer++;
                       R_LWegReal[pointer] = C_Fi;
                       pointer++;
                       break;
```

Demonstration



```
void R_MoveCube_Ui(void)
       Temp 1 = RubiksFeld[6][3];
       Temp_2 = RubiksFeld[6][4];
       Temp 3 = RubiksFeld[6][5];
       RubiksFeld[6][3] = RubiksFeld[3][2];
       RubiksFeld[6][4] = RubiksFeld[4][2];
       RubiksFeld[6][5] = RubiksFeld[5][2];
       RubiksFeld[3][2] = RubiksFeld[2][5];
       RubiksFeld[4][2] = RubiksFeld[2][4];
       RubiksFeld[5][2] = RubiksFeld[2][3];
       RubiksFeld[2][5] = RubiksFeld[5][6];
       RubiksFeld[2][4] = RubiksFeld[4][6];
       RubiksFeld[2][3] = RubiksFeld[3][6];
       RubiksFeld[5][6] = Temp_1;
       RubiksFeld[4][6] = Temp_2;
       RubiksFeld[3][6] = Temp_3;
       Temp_1 = RubiksFeld[5][5];
       Temp_2 = RubiksFeld[5][4];
       RubiksFeld[5][5] = RubiksFeld[5][3];
       RubiksFeld[5][4] = RubiksFeld[4][3];
       RubiksFeld[5][3] = RubiksFeld[3][3];
       RubiksFeld[4][3] = RubiksFeld[3][4];
       RubiksFeld[3][3] = RubiksFeld[3][5];
       RubiksFeld[3][4] = RubiksFeld[4][5];
       RubiksFeld[3][5] = Temp_1;
       RubiksFeld[4][5] = Temp_2;
       R_Wechsel = R_Wechsel + 25; R_Zuege++;
```

Question