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% An analysis of nodal reaction forces, nodal deformations, element
% internal forces, and element internal stresses for a truss of a
    certain
% configuration is required. This analysis must use the direct
    stiffness
% method. A plot of maximum stress vs loaded mass is also desired, as
    is a
% deformed shape plot for Case 5.

% For this particular truss (UBID 50084114), height and width are both
% 4 meters. It is composed of magnesium alloy, and the masses loaded
% are 150 kg. Material properties are assumed to be those of Magnesium
% AM60B Cast Alloy (the properties of this alloy can be found at the
% following link: http://www.azom.com/article.aspx?ArticleID=9237#4).
    Case
% 1 has a mass at joint 2. Case 2 has a mass at joint 2 and 3. Case 3
    has a
% mass at joint 2, 3, and 4. Case 4 has a mass at joint 2, 3, 4, and
    5.
% Case 5 has a mass at joint 2, 3, 4, 5, and 6.

% The effects of member weight and member buckling are ignored in this
% analysis, and all joints are assumed to be pin joints.

% The truss was analyzed using a script and function. The script
    stores
% user inputs (load vector, E, A, nodes, etc) for the parameters of
    the
% truss, and passes them along to the function TrussDirectStiffness.
    It is
% also responsible for plotting maximum stress vs mass loaded, and
% creating a fit function along with calculating the goodness of fit
    for
% that function.

% The TrussDirectStiffness function takes user inputs for the b
    vector,
% along with the node coordinates, members, E, A, and other
    information,
% and uses this to create localized stiffness matrices and concatenate
% them. Finally, it solves the resulting system of equations (using
% boundary conditions to eliminate rows and columns of the K matrix
    and b
% and u vectors that would otherwise render the system unsolvable) and
% returns a variety of outputs.

% For each case, the reactions, nodal deformations, internal forces,
    and
% internal stresses are outputted to the user. The highest magnitude
    axial
% stresses and nodal displacements are also shown. A yielding check is
% performed (if the user so desires) as a preliminary check for member
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% failure. The MATLAB function TrussDirectStiffness also outputs a
    shape
% plot if prompted to do so, which shows a representation of the truss
    in its
% deformed state.

% For the analysis results of each case, along with a test case
    showing the
% deformed shape plot in greater detail, see the code output. Design
% details are included in the extensive comments in the code itself.

clear all; close all; clc; % Clear everything, close everything.
% TRUSS PARAMETERS ENTERED HERE
nodes = [0 0;4 0;8 0;12 0;16 0;20 0;24 0;4 4;20 4;8 8;12 8;16 8]; %
    Enter the coordinates of our joints (meters) [x y].
elements = [1 2;1 8;2 3;2 8;3 4;3 10;4 5;4 12;4 11;5 6;5 9;5 12;6 7;6
    9;8 3;8 10;9 7;10 4;10 11;11 12;12 9]; % Enter the joints that our
    members connect [startjoint endjoint].
E = 45000000000; % Enter the Modulus of Elasticity here (Pa). For
    magnesium alloy, this is 45 GPa.
A = 0.00755; % Enter our area here (m^2).
sigmay = 130000000; % Enter our yield strength here (for magnesium
    alloy, this is 130 MPa for both compressive and tensile stresses).
unconstrained = [3 4 5 6 7 8 9 10 11 12 15 16 17 18 19 20 21 22 23
    24]; % Enter boundary conditions: the unconstrained joint directions
    (3 4 means joint 2 is free in x and y).
constrained = [1 2 13 14]; % Enter boundary conditions: the
    constrained joint directions (1 2 means joint 1 cannot move in x and
    y).
% END OF TRUSS PARAMETERS
% C1
load1 = [0;0;0;150;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0]; % Enter
    the load vector (kg).
b1=-9.81*load1; % The load vector is converted into N, and comprises
    the initial b vector fed into the function.
[maxstress(1,1)] =
    TrussDirectStiffness(nodes,elements,b1,E,A,unconstrained,constrained,1,sigmay); %
    Call TrussDirectStiffness function with defined parameters, and
    obtain the max stress (which is stored in a column vector).
% C2
load2 = [0;0;0;150;0;150;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0];
b2=-9.81*load2;
[maxstress(2,1)] =
    TrussDirectStiffness(nodes,elements,b2,E,A,unconstrained,constrained,1,sigmay);
% C3
load3 = [0;0;0;150;0;150;0;150;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0];
b3=-9.81*load3;
[maxstress(3,1)] =
    TrussDirectStiffness(nodes,elements,b3,E,A,unconstrained,constrained,1,sigmay);
% C4
load4 = [0;0;0;150;0;150;0;150;0;150;0;0;0;0;0;0;0;0;0;0;0;0;0;0];
b4=-9.81*load4;
[maxstress(4,1)] =
    TrussDirectStiffness(nodes,elements,b4,E,A,unconstrained,constrained,1,sigmay);

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% C5
load5 = [0;0;0;150;0;150;0;150;0;150;0;150;0;0;0;0;0;0;0;0;0;0;0];
b5=-9.81*load5;

figure1=figure('Position', [100, 100, 800, 600]); % Plot options
    including vertical/horizontal size.
[maxstress(5,1)] =
    TrussDirectStiffness(nodes,elements,b5,E,A,unconstrained,constrained,1,sigmay,1);
    Note that the deformed shape plot has been enabled.

mass(1,1) = sum(load1); % Calculate the total weight loaded on the
    truss for each loading scenario.
mass(2,1) = sum(load2);
mass(3,1) = sum(load3);
mass(4,1) = sum(load4);
mass(5,1) = sum(load5);

figure2=figure('Position', [100, 100, 800, 600]); % Plot options
    including vertical/horizontal size.
scatter(mass,abs(maxstress),'filled') % A scatter plot is most
    appropriate for these discrete points, this one plots the max stress
    vs total mass loaded.
xlabel('Total Mass (kg)','fontsize',16);
ylabel('Maximum Stress Magnitude (Pa)','fontsize',16);
title('Maximum Stress Magnitude vs Total Mass','fontsize',16); %
    Title, x label, y label, x interval settings, etc.
set(gca,'XTick',0:150:mass(end,1));
hold on

p = polyfit(mass(:,1),abs(maxstress(:,1)),3); % Fit the max stress vs
    mass scatterplot with a polynomial, order 3.
yfit = @(x) p(1)*x.^3 + p(2)*x.^2 + p(3)*x +p(4); % Using the four
    coefficients outputted by the built in polyfit function, we define
    fit function.
fplot(yfit,[mass(1,1) mass(end,1)]); % Plot our fit function.

resid = abs(maxstress(:,1)) - feval(yfit,mass(:,1)); % This series of
    calculations evaluates goodness of fit.
SSresid = sum(resid.^2);
SStotal = (length(maxstress(:,1))-1)*var(maxstress(:,1));
r2 = 1-SSresid/SStotal; % r2, the coefficient of determination, is
    calculated.

disp(['The coefficient of determination r^2 is ' num2str(r2) ' for
    this fitting function.']); % Text output for user.

Nodal Reactions (N) ----- [Node      X      Y]

reaction =

      1      613.12      1226.2
      2           0     -1471.5
      3           0           0
      4           0           0

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5	0	0
6	0	0
7	-613.12	245.25
8	0	0
9	0	0
10	0	0
11	0	0
12	0	0

Nodal Displacements (m) ----- [Node      X      Y]

displacement =

1	0	0
2	7.2185e-06	-9.4672e-05
3	1.4437e-05	-7.4924e-05
4	1.2993e-05	-4.3248e-05
5	8.6623e-06	-2.4565e-05
6	4.3311e-06	-1.2035e-05
7	0	0
8	3.6514e-05	-7.7348e-05
9	-3.8678e-06	-1.2035e-05
10	4.3122e-07	-5.7599e-05
11	-3.8999e-06	-4.3248e-05
12	-8.231e-06	-2.4565e-05

Element Internal Forces (N) ----- [Element      Internal Force]

force =

1	613.12
2	-1734.2
3	613.12
4	1471.5
5	-122.62
6	735.75
7	-367.88
8	274.2
9	2.8778e-13
10	-367.87
11	-2.0349e-13
12	-1.4389e-13
13	-367.87
14	0
15	-1040.5
16	-693.67
17	-346.84
18	-274.2
19	-367.87
20	-367.87
21	-346.84

Element Axial Stresses (Pa) ----- [Element      Axial Stress]

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stress =

1	81209
2	-2.2969e+05
3	81209
4	1.949e+05
5	-16242
6	97450
7	-48725
8	36318
9	3.8116e-11
10	-48725
11	-2.6952e-11
12	-1.9058e-11
13	-48725
14	0
15	-1.3782e+05
16	-91877
17	-45939
18	-36318
19	-48725
20	-48725
21	-45939

The largest magnitude axial stress is -229692.6332 (Pa).

The largest magnitude displacement is -9.4672e-05 (m).

Yielding due to axial stress does not occur.

Nodal Reactions (N) ----- [Node      X      Y]

reaction =

1	1348.9	2207.3
2	0	-1471.5
3	0	-1471.5
4	0	0
5	0	0
6	0	0
7	-1348.9	735.75
8	0	0
9	0	0
10	0	0
11	0	0
12	0	0

Nodal Displacements (m) ----- [Node      X      Y]

displacement =

1	0	0
2	1.0106e-05	-0.0001696
3	2.0212e-05	-0.00018633
4	2.1656e-05	-0.00010524
5	1.4437e-05	-6.3135e-05
6	7.2185e-06	-3.6599e-05

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7	0	0
8	7.877e-05	-0.00015227
9	-1.2099e-05	-3.6599e-05
10	1.1853e-05	-0.00013436
11	-1.1409e-06	-0.00010524
12	-1.4134e-05	-6.3135e-05

Element Internal Forces (N) ----- [Element      Internal Force]

force =

1	858.37
2	-3121.5
3	858.37
4	1471.5
5	122.63
6	2207.3
7	-613.13
8	822.59
9	1.1511e-12
10	-613.13
11	-6.1047e-13
12	5.7556e-13
13	-613.12
14	0
15	-1040.5
16	-2081
17	-1040.5
18	-822.59
19	-1103.6
20	-1103.6
21	-1040.5

Element Axial Stresses (Pa) ----- [Element      Axial Stress]

stress =

1	1.1369e+05
2	-4.1345e+05
3	1.1369e+05
4	1.949e+05
5	16242
6	2.9235e+05
7	-81209
8	1.0895e+05
9	1.5247e-10
10	-81209
11	-8.0857e-11
12	7.6233e-11
13	-81209
14	0
15	-1.3782e+05
16	-2.7563e+05
17	-1.3782e+05

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18	-1.0895e+05
19	-1.4618e+05
20	-1.4618e+05
21	-1.3782e+05

The largest magnitude axial stress is -413446.7398 (Pa).  
The largest magnitude displacement is -0.00018633 (m).  
Yielding due to axial stress does not occur.  
Nodal Reactions (N) ----- [Node      X      Y]

reaction =

1	2084.6	2943
2	0	-1471.5
3	0	-1471.5
4	0	-1471.5
5	0	0
6	0	0
7	-2084.6	1471.5
8	0	0
9	0	0
10	0	0
11	0	0
12	0	0

Nodal Displacements (m) ----- [Node      X      Y]

displacement =

1	0	0
2	1.0106e-05	-0.00021284
3	2.0212e-05	-0.00024832
4	2.1656e-05	-0.00019794
5	1.4437e-05	-0.00012513
6	7.2185e-06	-7.9847e-05
7	0	0
8	9.7517e-05	-0.00019552
9	-3.0846e-05	-7.9847e-05
10	2.4846e-05	-0.00019635
11	-1.1409e-06	-0.00019794
12	-2.7128e-05	-0.00012513

Element Internal Forces (N) ----- [Element      Internal Force]

force =

1	858.37
2	-4162
3	858.37
4	1471.5
5	122.63
6	2207.3
7	-613.13
8	1645.2

---

9	1.1511e-12
10	-613.12
11	-1.2209e-12
12	1.1511e-12
13	-613.12
14	0
15	-1040.5
16	-3121.5
17	-2081
18	1.3835e-12
19	-2207.3
20	-2207.3
21	-2081

Element Axial Stresses (Pa) ----- [Element      Axial Stress]

stress =

1	1.1369e+05
2	-5.5126e+05
3	1.1369e+05
4	1.949e+05
5	16242
6	2.9235e+05
7	-81209
8	2.1791e+05
9	1.5247e-10
10	-81209
11	-1.6171e-10
12	1.5247e-10
13	-81209
14	0
15	-1.3782e+05
16	-4.1345e+05
17	-2.7563e+05
18	1.8325e-10
19	-2.9235e+05
20	-2.9235e+05
21	-2.7563e+05

The largest magnitude axial stress is -551262.3197 (Pa).

The largest magnitude displacement is -0.00024832 (m).

Yielding due to axial stress does not occur.

Nodal Reactions (N) ----- [Node      X      Y]

reaction =

1	2820.4	3433.5
2	0	-1471.5
3	0	-1471.5
4	0	-1471.5
5	0	-1471.5
6	0	0
7	-2820.4	2452.5



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8	0	0
9	0	0
10	0	0
11	0	0
12	0	0

Nodal Displacements (m) ----- [Node			X	Y]
displacement =				
1	0	0		
2	7.2185e-06	-0.00023741		
3	1.4437e-05	-0.00028689		
4	1.2993e-05	-0.00025994		
5	8.6623e-06	-0.00023653		
6	4.3311e-06	-0.00015477		
7	0	0		
8	0.00010575	-0.00022008		
9	-7.3102e-05	-0.00015477		
10	3.0749e-05	-0.00023492		
11	-3.8999e-06	-0.00025994		
12	-3.8549e-05	-0.00020189		

Element Internal Forces (N) ----- [Element		Internal Force]
force =		
1	613.12	
2	-4855.7	
3	613.12	
4	1471.5	
5	-122.63	
6	2207.2	
7	-367.88	
8	1096.8	
9	2.3022e-12	
10	-367.87	
11	-2.8489e-12	
12	1471.5	
13	-367.87	
14	0	
15	-1040.5	
16	-3815.2	
17	-3468.4	
18	548.4	
19	-2943	
20	-2943	
21	-3468.4	

Element Axial Stresses (Pa) ----- [Element		Axial Stress]
stress =		
1	81209	

---

---

2	-6.4314e+05
3	81209
4	1.949e+05
5	-16242
6	2.9235e+05
7	-48725
8	1.4527e+05
9	3.0493e-10
10	-48725
11	-3.7733e-10
12	1.949e+05
13	-48725
14	0
15	-1.3782e+05
16	-5.0532e+05
17	-4.5939e+05
18	72635
19	-3.898e+05
20	-3.898e+05
21	-4.5939e+05

The largest magnitude axial stress is -643139.373 (Pa).  
The largest magnitude displacement is -0.00028689 (m).  
Yielding due to axial stress does not occur.  
Nodal Reactions (N) ----- [Node      X      Y]

reaction =

1	3433.5	3678.7
2	0	-1471.5
3	0	-1471.5
4	0	-1471.5
5	0	-1471.5
6	0	-1471.5
7	-3433.5	3678.8
8	0	0
9	0	0
10	0	0
11	0	0
12	0	0

Nodal Displacements (m) ----- [Node      X      Y]

displacement =

1	0	0
2	2.8874e-06	-0.00024944
3	5.7748e-06	-0.00031146
4	-7.5757e-20	-0.00030319
5	-5.7748e-06	-0.00031146
6	-2.8874e-06	-0.00024944
7	0	0
8	0.00010962	-0.00023212
9	-0.00010962	-0.00023212

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10	3.898e-05	-0.00025949
11	-2.2522e-20	-0.00030319
12	-3.898e-05	-0.00025949

Element Internal Forces (N) ----- [Element      Internal Force]

force =

1	245.25
2	-5202.5
3	245.25
4	1471.5
5	-490.5
6	2207.3
7	-490.5
8	822.59
9	2.3022e-12
10	245.25
11	-1040.5
12	2207.3
13	245.25
14	1471.5
15	-1040.5
16	-4162
17	-5202.5
18	822.59
19	-3310.9
20	-3310.9
21	-4162

Element Axial Stresses (Pa) ----- [Element      Axial Stress]

stress =

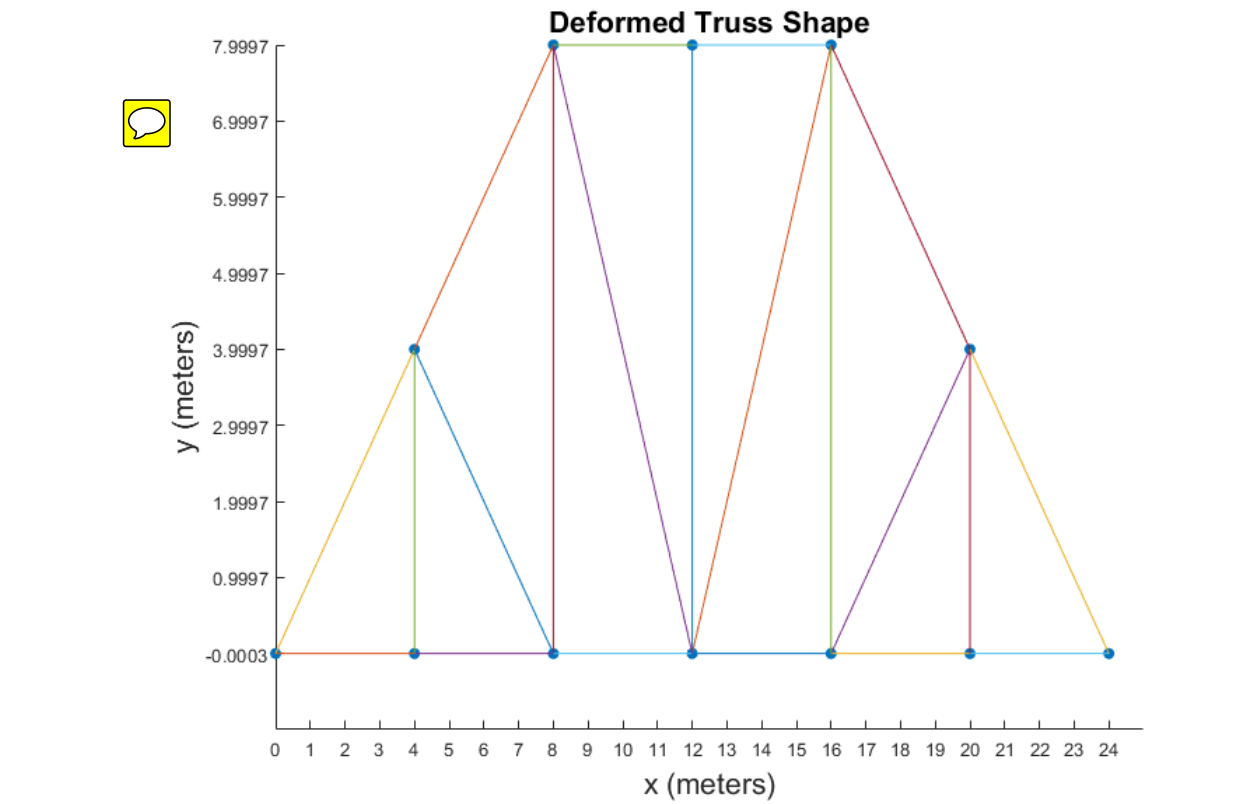
1	32483
2	-6.8908e+05
3	32483
4	1.949e+05
5	-64967
6	2.9235e+05
7	-64967
8	1.0895e+05
9	3.0493e-10
10	32483
11	-1.3782e+05
12	2.9235e+05
13	32483
14	1.949e+05
15	-1.3782e+05
16	-5.5126e+05
17	-6.8908e+05
18	1.0895e+05
19	-4.3853e+05
20	-4.3853e+05

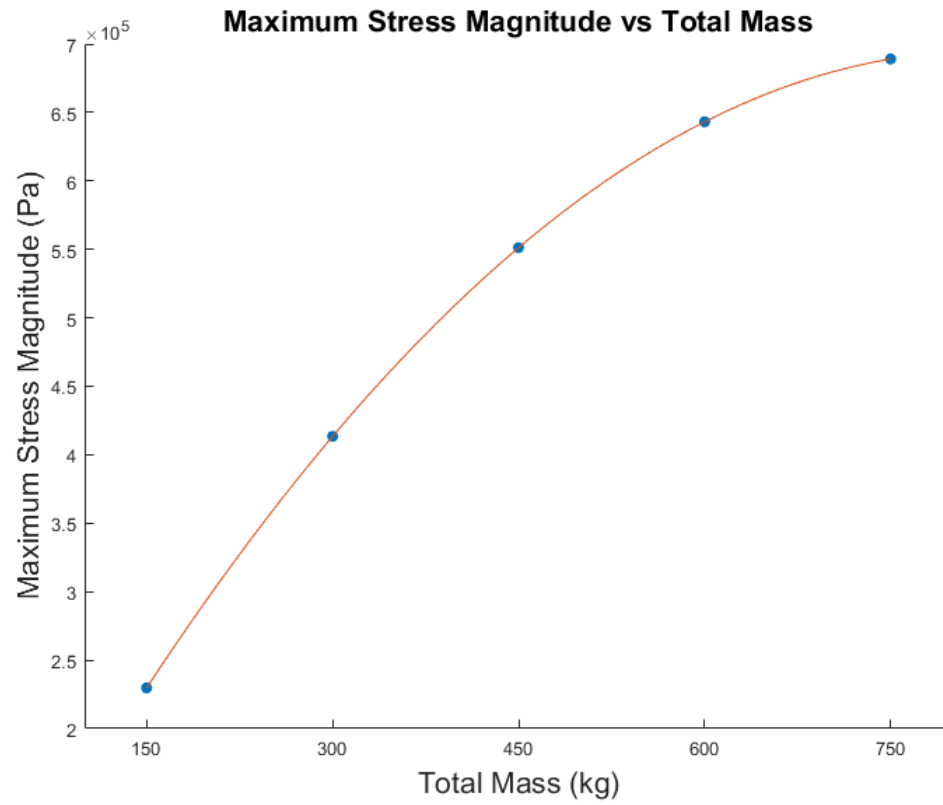
The largest magnitude axial stress is -689077.8997 (Pa).

The largest magnitude displacement is  $-0.00031146$  (m).

*Yielding due to axial stress does not occur.*

The coefficient of determination  $r^2$  is 1 for this fitting function.





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```
% This is a test case that I used to troubleshoot this code. It also
% shows what a large deformation would look like (hard to tell if the
% deformed shape plot is working with the small deformations that
% occur
% in the 5 provided cases).
```

```
clear all; close all; clc; % Clear everything, close everything.
% TRUSS PARAMETERS ENTERED HERE
nodes = [0 0;4 0;8 0;12 0;16 0;20 0;24 0;4 4;20 4;8 8;12 8;16 8]; %
    Enter the coordinates of our joints (meters) [x y].
elements = [1 2;1 8;2 3;2 8;3 4;3 10;4 5;4 12;4 11;5 6;5 9;5 12;6 7;6
    9;8 3;8 10;9 7;10 4;10 11;11 12;12 9]; % Enter the joints that our
    members connect [startjoint endjoint].
E = 45000000000; % Enter the Modulus of Elasticity here (Pa). For
    magnesium alloy, this is 45 GPa.
A = 0.00755; % Enter our area here (m^2).
sigmay = 130000000; % Enter our yield strength here (for magnesium
    alloy, this is 130 MPa for both compressive and tensile stresses).
unconstrained = [3 4 5 6 7 8 9 10 11 12 15 16 17 18 19 20 21 22 23
    24]; % Enter boundary conditions: the unconstrained joint directions
    (3 4 means joint 2 is free in x and y).
constrained = [1 2 13 14]; % Enter boundary conditions: the
    constrained joint directions (1 2 means joint 1 cannot move in x and
    y).
% CTest
load1 = [0;0;0;5000000;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0;0]; %
    That's a nice truss you've got there, shame if someone put 5 million
    kg on joint 2.
b1=-9.81*load1;
```

```
figure1=figure('Position', [100, 100, 800, 600]); % Plot options
    including vertical/horizontal size.
```

```
[maxstress(1,1)] =
    TrussDirectStiffness(nodes,elements,b1,E,A,unconstrained,constrained,1,sigmay,1);
```

Nodal Reactions (N) ----- [Node        X        Y]

reaction =

1	2.0437e+07	4.0875e+07
2	0	-4.905e+07
3	0	0
4	0	0
5	0	0
6	0	0
7	-2.0437e+07	8.175e+06
8	0	0
9	0	0
10	0	0
11	0	0
12	0	0

---

Nodal Displacements (m) ----- [Node        X        Y]

displacement =

1	0	0
2	0.24062	-3.1557
3	0.48124	-2.4975
4	0.43311	-1.4416
5	0.28874	-0.81882
6	0.14437	-0.40116
7	0	0
8	1.2171	-2.5783
9	-0.12893	-0.40116
10	0.014374	-1.92
11	-0.13	-1.4416
12	-0.27437	-0.81882

Element Internal Forces (N) ----- [Element        Internal Force]

force =

1	2.0438e+07
2	-5.7806e+07
3	2.0438e+07
4	4.905e+07
5	-4.0875e+06
6	2.4525e+07
7	-1.2263e+07
8	9.1399e+06
9	9.43e-09
10	-1.2262e+07
11	-1.3336e-08
12	0
13	-1.2262e+07
14	0
15	-3.4684e+07
16	-2.3122e+07
17	-1.1561e+07
18	-9.1399e+06
19	-1.2263e+07
20	-1.2262e+07
21	-1.1561e+07

Element Axial Stresses (Pa) ----- [Element        Axial Stress]

stress =

1	2.707e+09
2	-7.6564e+09
3	2.707e+09
4	6.4967e+09
5	-5.4139e+08
6	3.2483e+09
7	-1.6242e+09

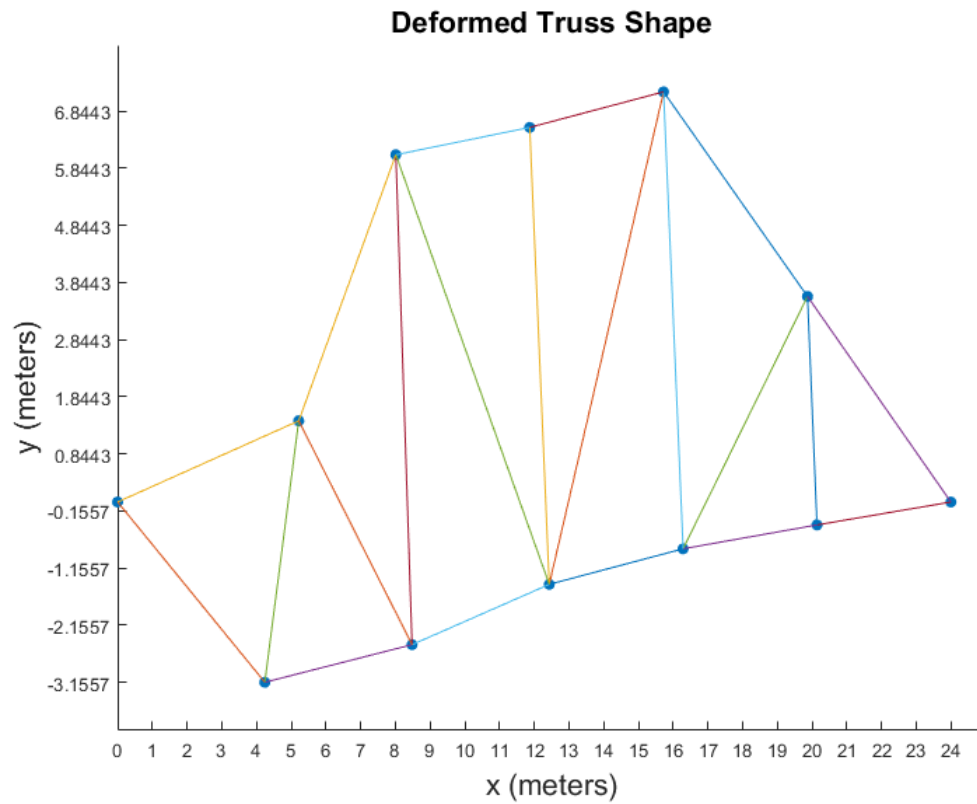
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```

      8    1.2106e+09
      9    1.249e-06
     10   -1.6242e+09
     11   -1.7664e-06
     12           0
     13   -1.6242e+09
     14           0
     15   -4.5939e+09
     16   -3.0626e+09
     17   -1.5313e+09
     18   -1.2106e+09
     19   -1.6242e+09
     20   -1.6242e+09
     21   -1.5313e+09

```

The largest magnitude axial stress is -7656421107.5497 (Pa).  
 The largest magnitude displacement is -3.1557 (m).  
 Yielding due to axial stress occurs in at least one member.




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```

function [maxstress maxdisplacement reaction
displacement force stress b u f st K] = 
TrussDirectStiffness(nodes,elements,b,E,A,unconstrained,constrained,yieldcheck,si
Define our inputs, outputs.

% Function outputs max stress, max displacement, reaction matrix,
% displacement matrix, internal force matrix, axial stress matrix, as
% well as raw form force vector, nodal displacement vector, internal
% force vector, and axial stress vector. The global stiffness matrix K
is
% also outputted for troubleshooting purposes. The function also
performs a
% preliminary yield check for all members using inputted yield
strength
% value (if one is inputted), and outputs a deformed shape plot if
prompted
% to do so.

% Function requires nodes matrix, elements matrix, b vector, E, A,
% unconstrained and constrained matrix (boundary conditions for the
direct
% stiffness method.

if nargin<7,error('The following input arguments are required:
nodes,elements,b,E,A,unconstrained,constrained'),end % Check for
sufficient input arguments.
if nargin==8 && yieldcheck ~= 0,error('To enable yield check, enter
the yield strength of the material sigmay. Otherwise, yieldcheck =
0 or simply leaving the yieldcheck input blank will disable yield
check.'),end % Enabling yield check without inputting sigma y causes
an error.
if nargin<8,yieldcheck = 0; end % If there is no yieldcheck input
provided, that loop is disabled.
if nargin<10,shape = 0; end % If the user does not request a deformed
shape plot, disable loop.
if yieldcheck ~= 0 && yieldcheck ~= 1, error('Input for yieldcheck
must be 0 (off) or 1 (on)'),end
if sigmay <= 0, error('Yield strength must be positive.'),end
if shape ~= 0 && shape ~= 1, error('Input for shape must be 0 (off) or
1 (on)'),end
if size(nodes,2) ~= 2, error('Node coordinate matrix must be of size n
by 2.'),end % Next lines check for dimensional mismatches.
if size(elements,2) ~= 2, error('Element matrix must be of size n by
2.'),end
if size(b,2)~= 1, error('b must be a column vector.'),end
if size(b,1)~= 2*size(nodes,1), error('b must be a column vector of
size 2n'),end
if size(unconstrained,1)~= 1, error('unconstrained must be a row
vector.'),end
if size(constrained,1)~= 1, error('constrained must be a row
vector.'),end

```

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```

if size(unconstrained,2)+size(constrained,2) ~= 2*size(nodes,1),
    error('Not enough boundary conditions specified. '),end
if size(E,1)~= 1, error('E must be a scalar value. '),end
if size(E,2)~= 1, error('E must be a scalar value. '),end
if size(A,1)~= 1, error('A must be a scalar value. '),end
if size(A,2)~= 1, error('A must be a scalar value. '),end

Nelements = size(elements,1); % The number of "elements" for the
    direct stiffness method (an element is a truss member linking two
    joints).
Nnodes = size(nodes,1); % The number of "nodes" for the direct
    stiffness method (a node is a truss joint).

K = zeros(2*Nnodes); % Initializing K matrix, the assembled global
    stiffness matrix (must be square matrix of size = 2*number of nodes,
    because each node has vertical and horizontal degree of freedom).
    Values are unknown, therefore initialize as zeros.
u = zeros(2*Nnodes,1); % Initializing u displacement matrix (column
    vector of size = 2*number of nodes, 1). Values are unknown, therefore
    initialize as zeros.

for i=1:Nelements % Iterate from 1 to the number of elements.
    elementnodes = elements(i,1:2); % This selects the start and end
    nodes (start and end joints) of each member.
    nodecoordinates = nodes(elementnodes,:); % This selects the
    corresponding node coordinates from the joints matrix.

    x1 = nodecoordinates(1,1); % Retrieves the x1, x2, y1, y2 values
    from the supplied nodecoordinates matrix.
    x2 = nodecoordinates(2,1);
    y1 = nodecoordinates(1,2);
    y2 = nodecoordinates(2,2);

    L = sqrt((x2-x1)^2+(y2-y1)^2); % Length is calculated in terms of
    node coordinates.
    cos = (x2-x1)/L; % Calculation of cos and sin for usage in Klocal
    matrix.
    sin = (y2-y1)/L;

    Klocal = (E*A/L)*[cos^2 cos*sin -cos^2 -cos*sin;cos*sin sin^2 -
    cos*sin -sin^2;-cos^2 -cos*sin cos^2 cos*sin;-cos*sin -sin^2 cos*sin
    sin^2]; % The Klocal matrix is the stiffness matrix for one bar type
    element in global coordinates.

    idBeg = 2*(elementnodes(1)-1)+1:2*(elementnodes(1)-1)+2; % The
    displacement corresponding to the beginning of the element (what
    position it occupies in the u column vector).
    idEnd = 2*(elementnodes(2)-1)+1:2*(elementnodes(2)-1)+2; % The
    displacement corresponding to the end of the element.
    id = [idBeg idEnd]; % This identifies which values of the
    displacement vector u this local stiffness matrix corresponds to, and
    will be used in assembling the matrix below.

```

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```

        K(id,id) = K(id,id) + Klocal; % The elementdisplacement vector
        is used to assemble the local stiffness matrices into one global
        stiffness matrix.
    end

    u(unconstrained) = K(unconstrained,unconstrained)\(b(unconstrained)-
    K(unconstrained,constrained)*u(constrained)); % The unconstrained
        node elements of the u vector are found (these are our unknown
        deformations).
    b(constrained) = K(constrained,:)*u; % The elements of the force
        vector corresponding to constrained nodes are found (these are our
        unknown reaction forces).

    for i=1:Nelements
        elementnodes = elements(i,1:2); % This selects the start and end
        nodes (start and end joints) of each member.
        nodecoordinates = nodes(elementnodes,:); % This selects the
        corresponding node coordinates from the joints matrix.

        x1 = nodecoordinates(1,1); % Retrieves the x1, x2, y1, y2 values
        from the supplied nodecoordinates matrix
        x2 = nodecoordinates(2,1);
        y1 = nodecoordinates(1,2);
        y2 = nodecoordinates(2,2);

        L = sqrt((x2-x1)^2+(y2-y1)^2); % Length is calculated in terms of
        node coordinates.
        cos = (x2-x1)/L; % Calculation of cos and sin for usage in Klocal
        matrix.
        sin = (y2-y1)/L;

        idBeg = 2*(elementnodes(1)-1)+1:2*(elementnodes(1)-1)+2; % The
        displacement corresponding to the beginning of the element (what
        position it occupies in the u column vector).
        idEnd = 2*(elementnodes(2)-1)+1:2*(elementnodes(2)-1)+2; % The
        displacement corresponding to the end of the element.

        f(i,1)=(E*A/L)*(cos*(u(idEnd(1),1)-
    u(idBeg(1),1))+sin*(u(idEnd(2),1)-u(idBeg(2),1))); % The internal
        force in each member is calculated based on the displacements of the
        beginning and end nodes, and arranged in a column vector.
        st(i,1) = (1/A)*f(i,1); % The stress is easily calculated,
        simply multiply the force vector by the scalar 1/A (equivalent to
        elementwise division by area, sigma = F/A).
    end

    [~,maxstresselement] = max(abs(st));
    maxstress = st(sub2ind(size(st),maxstresselement,1:size(st,2))); % The
        greatest magnitude value in the matrix is returned, with +/- symbol

    [~,maxdisplacementnode] = max(abs(u));
    maxdisplacement =
        u(sub2ind(size(u),maxdisplacementnode,1:size(u,2))); % This process
        is repeated for maximum displacement.

```

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---

```

reaction = zeros(Nnodes,3); % The u and b column vectors are broken
    down into matrix of size = (Nnodes,2) for readability, so that [x1
    y1;x2 y2;...] corresponds to the x and y reactions/displacements of
    node 1, node 2, etc.
reaction(:,1) = 1:Nnodes;
reaction(:,2) = b(1:2:end);
reaction(:,3) = b(2:2:end);
displacement = zeros(Nnodes,3);
displacement(:,1) = 1:Nnodes;
displacement(:,2) = u(1:2:end);
displacement(:,3) = u(2:2:end);
force = zeros(Nelements,2); % The internal force and stress vectors
    are also placed into a more readable, indexed format.
force(:,1) = 1:Nelements;
force(:,2) = f(:,1);
stress = zeros(Nelements,2);
stress(:,1) = 1:Nelements;
stress(:,2) = st(:,1);

format short g % The reformatted reaction, displacement, force, and
    stress matrices are presented to the user.
disp(['Nodal Reactions (N) ----- [Node      X      Y]']); reaction
disp(['Nodal Displacements (m) ----- [Node      X      Y]']);
    displacement
disp(['Element Internal Forces (N) ----- [Element      Internal
    Force]']); force
disp(['Element Axial Stresses (Pa) ----- [Element      Axial
    Stress]']); stress
disp(['The largest magnitude axial stress is '
    num2str(maxstress) ' (Pa).']); % Maximum stress (greatest magnitude)
    is displayed. Note that this may be compressive or tensile, and
    includes +/- symbol.
disp(['The largest magnitude displacement is '
    num2str(maxdisplacement) ' (m).']); % Maximum displacement (greatest
    magnitude) is displayed.

if yieldcheck == 1 % If the user has decided to enable yieldchecking,
    this loop proceeds.
if abs(maxstress) > sigmay % This if loop checks maximum internal
    stress against the yield strength inputted into our function.
    disp(['Yielding due to axial stress occurs in at least one
    member.']); % If yield strength is exceeded, the user is warned.
else
    disp(['Yielding due to axial stress does not occur.']); % If yield
    strength is not exceeded, no warning.
end
elseif yieldcheck == 0 % If the user has disabled yieldchecking or
    left yieldcheck input blank, the loop is disabled.
    return
end

if shape == 1 % If the "shape" input is 1, this triggers the loop that
    draws the deformed truss shape.

```

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---

```

    deformedshape(:,1:2) = nodes(:,1:2)+ displacement(:,2:3); % The
    new positions of the nodes are calculated by adding the initial node
    positions and displacements.

    scatter(deformedshape(:,1),deformedshape(:,2),'filled') %
    A scatter plot is made of the nodes in their post deformation
    positions.
    xlabel('x (meters)','fontsize',16);
    ylabel('y (meters)','fontsize',16);
    title('Deformed Truss Shape','fontsize',16); % Plot settings and
    labels.
    hold on

for i=1:Nelements % Iterate from 1 to number of elements.
    elementnodes = elements(i,1:2); % Obtain the start and end
    nodes of each element (similar to the step that creates the global
    stiffness matrix).
    nodecoordinates = deformedshape(elementnodes,:); % This selects
    the corresponding node coordinates from the joints matrix.

    x1 = nodecoordinates(1,1); % Retrieves the x1, x2, y1, y2 values
    from the supplied nodecoordinates matrix
    x2 = nodecoordinates(2,1);
    y1 = nodecoordinates(1,2);
    y2 = nodecoordinates(2,2);

    m = (y2-y1)/(x2-x1); % This calculates the slope of the line
    formed by these nodes.
    y = @(x) m*x-m*x1+y1; % The equation of the line passing through
    both nodes is defined.
    if x2 > x1
        fplot(y,[x1 x2]); % If x2>x1, the function is plotted on this
        range. Alternatively, the x2 and x1 positions are switched.
    elseif x2 < x1
        fplot(y,[x2 x1]);
    elseif x2 == x1
        if y2 > y1
            line([x1 x2],[y1 y2]); % If x1 and x2 are equal, a vertical
            line must be drawn. Note the y1 and y2 positions switch much like the
            x1 and x2 positions above.
        else
            line([x1 x2],[y2 y1]);
        end
    end
end

set(gca,'XTick',min(deformedshape(:,1)):max(deformedshape(:,1))); % X
and Y intervals are set.
set(gca,'YTick',min(deformedshape(:,2)):max(deformedshape(:,2)));
hold on
end
elseif shape == 0 % If the shape input is 0, the loop above is not
triggered and a graph is not produced.
    return
end
end

```

---

---

end

*Error using TrussDirectStiffness (line 16)  
The following input arguments are required:  
nodes,elements,b,E,A,unconstrained,constrained*

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