

'Parameters" A tuning Knob

For Bernoulli, p is the "probability of success"

pe(0,1) (if I is 1 the definition of success).

X n Bern (0) = Deg (0) = { 0 wp. 1 "degenerate" are deterministic

X ~ Bern (1) = Deg (1) = ? 1 wp. 1

p=0 or p=1 are degenerate cases. Is a convention, we exclude them
from the param space

Parameter Space the set of all parameter values which are not degenerate.

For Binomial pc (0,1)

n ∈ {1,2,...} = N

 $X \sim \mathcal{N}(\mathcal{M}, \sigma^{2}) = \frac{1}{\sqrt{2\pi} \sigma^{2}} \cdot e^{-\frac{1}{2\sigma^{2}}(X - \mathcal{M})^{2}}$   $Supp[X] = \mathbb{R}$   $\mathcal{M} \in \mathbb{R}$   $\sigma^{2} = Var[X] := \mathbb{E}[(X - \mathcal{M})^{2}]$   $\sigma^{2} \in (0, \infty)$ 

Let 0 be the unknown parameter.

And 0 = [ this] parameters.

And (A) be the parameter opace

 $\times \sim \text{Bern}(\Theta) := \Theta^{\times}(1-\Theta)^{1-\times}$  $\times \sim \mathcal{N}(\Theta_1, \Theta_2)$ 

Parametric Model

F:= { P(X; 0): 0 € (H)}

space of PMF/

perameter model PDF PMF 'needs'

the perameter value

If  $X_1, X_2, ..., X_n$  are random variable  $p(x_1, X_2, ..., x_n; \vec{\theta})$  is the joint mass function / joint density function.  $p(x_1, X_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_2; \vec{\theta}) \cdot ... \cdot p(x_n; \vec{\theta}) = \prod_{i=1}^n p_i(x_i; \vec{\theta})$   $p(x_1, X_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_2; \vec{\theta}) \cdot ... \cdot p(x_n; \vec{\theta}) = \prod_{i=1}^n p_i(x_i; \vec{\theta})$   $p(x_1, X_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_2; \vec{\theta}) \cdot ... \cdot p(x_n; \vec{\theta}) = \prod_{i=1}^n p_i(x_i; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_2; \vec{\theta}) \cdot ... \cdot p(x_n; \vec{\theta}) = \prod_{i=1}^n p_i(x_i; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_2; \vec{\theta}) \cdot ... \cdot p(x_n; \vec{\theta}) = \prod_{i=1}^n p_i(x_i; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_2; \vec{\theta}) \cdot ... \cdot p(x_n; \vec{\theta}) = \prod_{i=1}^n p_i(x_i; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_2; \vec{\theta}) \cdot ... \cdot p(x_n; \vec{\theta}) = \prod_{i=1}^n p_i(x_i; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_2; \vec{\theta}) \cdot ... \cdot p(x_n; \vec{\theta}) = \prod_{i=1}^n p_i(x_i; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_2; \vec{\theta}) \cdot ... \cdot p(x_n; \vec{\theta}) = \prod_{i=1}^n p_i(x_i; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_2; \vec{\theta}) \cdot ... \cdot p(x_n; \vec{\theta}) = \prod_{i=1}^n p_i(x_i; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_2; \vec{\theta}) \cdot ... \cdot p(x_n; \vec{\theta}) = \prod_{i=1}^n p_i(x_i; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_2; \vec{\theta}) \cdot ... \cdot p(x_n; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_1; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_1; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_1; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_1; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_1; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_1; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_1; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_1; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_1; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_1; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_1; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta}) = p(x_1; \vec{\theta}) \cdot p(x_1; \vec{\theta})$   $p(x_1, x_2...x_n; \vec{\theta})$ 

Three Goals of Inference

@ Paint Estimation. Provide # best single gress of O (denoted ô).

(Step II) Inference (i.e figure out the value of 0)

(I) Confidence set. Provide range of likely O

Theory Test. Test plaussibility these O is some value or belongs to some sets.