# Lab 7

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# 11:59PM March 31, 2019

Generate  $\mathbb{D}$  with n=100 and p=1 where x is created from iid realizations from a standard uniform, y comes from f(x)=3-4x and  $\delta$  are iid realizations from a T distribution with 10 degrees of freedom.

```
set.seed(1997)
n = 100
p = 1
X = matrix((runif(n)), ncol = 1)
f_x = 3 - 4 * X
delta = rt(n, df = 10)
y = f_x + delta
b = solve(t(X) %*% X) %*% t(X) %*% y
```

Run the linear model using 1m and compute b, RMSE and  $R^2$ .

#### ## [1] 0.4044066

Progressively add columns of x (as draws from a standard uniform), run the linear model, and show  $R^2$  goes to 1 and  $s_e$  goes to zero. Save the  $s_e$  in a vector called in\_sample\_s\_e.

```
in_sample_s_e = array(NA, n - 2)
linear_mods = list()

for (j in 1 : (n - 2)){
    X = cbind(X, runif(n))
    linear_mods[[j]] = lm(y ~ ., data.frame(X))
    in_sample_s_e[j] = sd(linear_mods[[j]]$residuals)
}

summary(linear_mods[[j]])$r.squared
```

```
## [1] 1
tail(in_sample_s_e)
## [1] 0.19626704 0.18477877 0.17373682 0.14093467 0.03613263 0.00000000
d = diff(in_sample_s_e)
all(d < 0)</pre>
```

```
## [1] TRUE
```

Compute a corresponding vector <code>oos\_s\_e</code> and show that it is increasing (for the most part) in degrees of freedom.

```
n_star = 1e5
p = 1
X_star = matrix(runif(n_star) , ncol = 1)
f_x_star = 3 - 4 * X_star
y_star = f_x_star + rt(n_star, df = 10)

oos_s_e = array(NA, n - 2)

for (j in 1 : (n - 2)){
    X_star = cbind(X_star, runif(n_star))
    y_hat_star = predict(linear_mods[[j]], data.frame(X_star))
    oos_s_e[j] = sd(y_star - y_hat_star)
}

d = diff(oos_s_e)
all(d > 0)
```

#### ## [1] FALSE

Validate the linear model for the Boston housing data.

```
Xy = MASS::Boston
K = 10
test_indices = sample(1 : nrow(Xy), 1 / K * nrow(Xy))
train_indices = setdiff(1 : nrow(Xy), test_indices)
Xy_train = Xy[train_indices, ]
Xy_test = Xy[test_indices, ]
lin_mod = lm(medv ~ ., Xy_train)
lin_mod
##
## Call:
## lm(formula = medv ~ ., data = Xy_train)
##
## Coefficients:
## (Intercept)
                       crim
                                                 indus
                                                                chas
##
     35.679799
                  -0.105926
                                0.044428
                                              0.036199
                                                            1.785549
##
           nox
                                      age
                                                   dis
                                                                 rad
##
    -18.514293
                   4.075433
                                -0.000166
                                             -1.454425
                                                           0.310478
##
                   ptratio
                                    black
                                                 lstat
           tax
     -0.012749
                  -0.989053
                                0.009001
                                             -0.492947
##
sd(lin_mod$residuals)
```

```
## [1] 4.725718
```

```
y_hat_test = predict(lin_mod, Xy_test)
sd(Xy_test$medv - y_hat_test)
```

# ## [1] 4.344533

Let x be iid realizations from a U(0,5), y comes from  $f(x) = 3 - 4x + 2x^2$  and  $\epsilon$  are iid realizations from a standard normal distribution. With no limit on the number of samples you cant take, use regular OLS

without a quadratic term, find the true " $h^*(x)$  (there will be no sampling variability at  $n \to \infty$  and find the oos variance of the residuals.

```
n = 1e6
X = cbind(rep(1,n), (runif(n,0,5)))
X1 = X[,2]
f_x = 3 - 4*X1 + 2*(X1^2)
epsilon = rnorm(n)
y = f_x + epsilon
b = solve(t(X) %*% X) %*% t(X) %*% y
h_{star_x} = b[1,1] + b[2,1]*X1
yhat = b %*% X1
n_star = 1e6
p = 1
X_star = matrix(runif(n_star, 0, 5) , ncol = 1)
f_x_{star} = 3 - 4 * X_{star} + 2*(X_{star}^2)
y_star = f_x_star + rnorm(n_star)
y_hat_star = predict(lm(y_star ~ ., data.frame(X1)), data.frame(X_star))
oos_s_e = sd(y - y_hat_star)
oos_s_e
```

#### ## [1] 9.485065

Was there any overfitting in the previous exercise?

Yes, it is overfitting since the RMSE approaches 0 which means no error in the data set. With the out of sample RMSE, happens the opposite instead of going to 0, it gets larger and larger.

Find the error due to misspecification and due to ignorance expressed as variance of components of the residuals.

```
e_misspecify_ignorance = sd(y - f_x)
e_misspecify_ignorance
```

### ## [1] 1.000092

At n = 100, find the error due to estimation, due to misspecification and due to ignorance expressed as variance of components of the residuals.

```
n = 100
X = cbind(rep(1,n), (runif(n,0,5)))
X1 = X[,2]
f_x = 3 - 4*X1 + 2*(X1^2)
epsilon = rnorm(n)
y = f_x + epsilon
b = solve(t(X) %*% X) %*% t(X) %*% y
b
```

```
## [,1]
## [1,] -5.086237
## [2,] 5.821471
h_star_x = b[1,1] + b[2,1]*X1
e_estim = sd(y - h_star_x)
e_estim
```

```
## [1] 3.865573
```

Do the variances add up to the total variance of the residual?

```
tot_e = sd(y - yhat)
tot_e
```

#### ## [1] 18.82731

Validate the linear model for the Boston housing data where each feature is also modeled with a squared feature.

```
X = MASS::Boston
y = X\$medv
X$medv = NULL
X = cbind(X, X^2)
colnames(X)[14 : 26] = paste(colnames(X)[1 : 13], "_sq", sep = "")
X$chas sq = NULL
K = 10
test_indices = sample(1 : nrow(X), 1 / K * nrow(X))
train_indices = setdiff(1 : nrow(X), test_indices)
X_train = X[train_indices, ]
y_train = y[train_indices]
X_test = X[test_indices, ]
y_test = y[test_indices]
lin_mod = lm(y_train ~ ., X_train)
\#lin\_mod
paste("Residuals from squared model:", round(sd(lin_mod$residuals), 5))
```

## ## [1] "Residuals from squared model: 3.882"

```
y_hat_test = predict(lin_mod, X_test)
paste("Deviation after running squared model on data", round(sd(y_test - y_hat_test), 5))
```

#### ## [1] "Deviation after running squared model on data 2.98426"

Validate the linear model for the Boston housing data where each feature is also modeled with a squared feature and a cubed feature.

```
X = MASS::Boston
y = X\$medv
X$medv = NULL
X = cbind(X, X^2, X^3)
colnames(X)[14 : 26] = paste(colnames(X)[1 : 13], "_sq", sep = "")
colnames(X)[27 : 39] = paste(colnames(X)[1 : 13], "_cube", sep = "")
X$chas = NULL
X$chas_sq = NULL
X$chas_cube = NULL
K = 10
test_indices = sample(1 : nrow(X), 1 / K * nrow(X))
train_indices = setdiff(1 : nrow(X), test_indices)
X_train = X[train_indices, ]
y_train = y[train_indices]
X_test = X[test_indices, ]
y_test = y[test_indices]
```

```
lin_mod = lm(y_train ~ ., X_train)
paste("Residuals of cubed model from training data:", round(sd(lin_mod$residuals)), 5)

## [1] "Residuals of cubed model from training data: 4 5"
y_hat_test = predict(lin_mod, X_test)
paste("Deviation after running cubed model on new data:", round(sd(y_test - y_hat_test)), 5)
```

## [1] "Deviation after running cubed model on new data: 4 5"

Validate the linear model for the Boston housing data where each feature is also modeled with a squared feature and a cubed feature and a log(x + 1) feature and an exponential feature.

```
#T0-D0
X = MASS::Boston
y = X\$medv
X$medv = NULL
X$chas = NULL
X = cbind(X, X^2, X^3, log1p(X))
colnames(X)[13 : 24] = paste(colnames(X)[1 : 12], "_sq", sep = "")
colnames(X)[25 : 36] = paste(colnames(X)[1 : 12], "_cube", sep = "")
colnames(X)[37: 48] = paste(colnames(X)[1:12], "_log", sep = "")
K = 10
test_indices = sample(1 : nrow(X), 1 / K * nrow(X))
train_indices = setdiff(1 : nrow(X), test_indices)
X_train = X[train_indices, ]
y train = y[train indices]
X_test = X[test_indices, ]
y_test = y[test_indices]
lin_mod = lm(y_train ~ ., X_train)
paste("Residuals of log model from training data:", round(sd(lin_mod$residuals), 5))
```

## [1] "Residuals of log model from training data: 3.39027"

```
y_hat_test = predict(lin_mod, X_test)
paste("Deviation after running log model on new data:", round(sd(y_test - y_hat_test), 5))
```

## [1] "Deviation after running log model on new data: 3.76739"

Why do we need to  $\log x + 1$ ? Why not use  $\log(x)$ ?

If one of the data points is zero log(x) will diverge to negative infinity. All of the feature data points are positive so x+1 poses no issues.