

11/21/2024





# We shall start from the beginning

Cos`the beginning`s a good place to start

- Propositional Logic
- Atomic entities, the *propositions*
- Forming phrases or formulas through *connectives*
- Are they false? Are they true?
- Are they always true? Are they always false?





# Why Prop?

Because it works?

- Well, often!
- Benefit from well-developed algorithm
- Used in many, many applications
- From Theophrastus' *modus ponens*
- To Boole's calculus
- To SAT, WSAT, Model Counting, BDDs, Circuits,...



# Finite Domains

- WE have N variables  $X_i$
- Where each takes a value in a domain  $X_i \in D_j$
- And a function  $F(X_1 \dots X_n)$
- We want to satisfy the constraints:  $F(X_1 \dots X_n) = \mathbf{T}$
- Or find the best solution:  $\text{maxarg} F(X_1 \dots X_n)$



# Constraint Programming

- Initially used constraint solvers: SICStusProlog, ECLIPSe;
- Others work as libraries: Gecode, and OR-Tools in C++, Choco and JaCoP in Java
- MiniZinc is a huge effort to construct a constraint programming language
- Both MiniZinc and OR-Tools use SAT solvers
- Translations from Zhou and from BEE

# An Example

%		S	E	N	D	
%	+	M	O	R	E	
%	-----					
%		M	O	N	E	Y

# Define the Problem

```
main(Letters) :-  
    Letters = [S,E,N,D,M,0,R,Y] ,  
    foldl(domain(0,9), Letters),  
    plus(D,E,Y),  
    carry(D,E,C0),  
    plus(C0,N,R,E),  
    carry(C0,N,R,C1),  
    plus(C1,E,0,N),  
    carry(C1,E,0,C2),  
    plus(C2,S,M,0),  
    carry(C1,E,0,C2),  
    eq(C3,M).
```

# Spec: Notes

- We have to specify:
  - Entities
  - Relationships
- Notice we describe the computation of the addition



# The booleans

- Translate each variable into 10 boolean variables:
- $E_0 \vee E_1 \vee E_2 \vee E_3 \vee E_4 \vee E_5 \vee E_6 \vee E_7 \vee E_8 \vee E_9$
- Besides we know

$$\forall E_i, E_j : E_i \rightarrow \neg E_j$$

- Or
- $\forall E_i, E_j : \neg E_i \vee \neg E_j$

# The Equations

- The letters S E N D M O R Y must be different, eg:
- $E_i \rightarrow \neg M_i$
- Arithmetic
- We cannot write all possible sums directly,
- We just write down the arithmetic

$$(D_0 \wedge E_0 \rightarrow Y_0) \wedge (D_0 \wedge E_1 \rightarrow Y_1) \wedge \dots$$

# Arithmetic

- We should also consider carry-in e carry-out
- $(c^0 \wedge D_0 \wedge E_0 \rightarrow Y_0 \wedge c_1) \wedge (c^0 \wedge D_0 \wedge E_1 \rightarrow Y_1 \wedge c^1) \wedge \dots$
- Notice the carry is a single bool per column
- $(c^0 \wedge D_0 \wedge Y_0 \rightarrow E_0 \wedge c_1) \wedge (c^0 \wedge D_0 \wedge Y_1 \rightarrow E_1 \wedge c^1) \wedge \dots$



# Implementation

```
main :-  
    Letters = [S,E,N,D,M,O,R,Y],  
    foldl(domain(0,9), Letters),  
    plus(C0,D,E,Y,C1),  
    plus(C1,N,R,E,C2),  
    C2=1,  
    C0=0.
```

```
domain(I,J,Input,TVs*DVs) :-  
    NVs is J+1-i,  
    length(Vs,NVs),  
    at_least_one_true(Vs,TVs),  
    all_different(Vs, DVs).
```

```
at_least_one_true([V],V)  
at_least_one_true([V,V2|Vs],(V+Vs)) :-  
    at_least_one_true([V2|Vs],Vs).
```

```
all_different([V|Vs],F*Fs) :-  
    differs(V,Vs,F),  
    all_different(Vs,Fs).
```

```
differs(V,[V1],xor(V,V1)).  
differs(V,[V1|Vs],xor(V,V1)*F1):-  
    differs(V,Vs,F1),
```

# Implementation

```
enumerate(C1, IX, IY, IZ, C2, (IZ+ -IX + -IY + -C0)*  
                                C1+ -IX + -IY + -C0) :-
```

```
member(Ci, [0,1]),
```

```
member(IX, [0,1,2,3,4,5,6,7,8,9] ),
```

```
member(IY, [0,1,2,3,4,5,6,7,8,9] ),
```

```
IZ is (Ci+IX+IY) mod 10,
```

```
C2 is (Ci+IX+IY)//10,
```

```
IX\=IY, IZ \= IX, IY\=Z.
```

# An Example

PySAT

- Interface to glucose solver: `G = Glucose3()`
- $A \rightarrow B$ : `G.add_clause([-1,2])`
- $B \rightarrow C$  `G.add_clause([-2,3])`
- `G.solve()`
- `G.get_model()`



# How does it work ?

Davis-Putnam-Logemann-Loveland (DPLL) Algorithm (1962)x

- Explores the search space of potential models, and backtracks
- We will define the algorithm as building up a partial model •
- A partial model assigns truth values to only some variables; a partial function •
- We will represent partial models by finite sets of literals (e.g. ) •
- The algorithm returns either (sat,M) or unsat •
- in the former case, M will be a model for the input formula T

# Propagation in DPLL

- If  $\Lambda$  is  $\top$  then return (sat,  $M$ )
- If  $\Lambda$  contains an empty clause then return unsat
- Pure literal rule: If  $p$  occurs only positively (negatively) in  $\Lambda$ , delete clauses of  $\Lambda$  in which  $p$  occurs, update  $M$  to  $M \cup \{p\}$  (to  $M \cup \{\neg p\}$ )
- Unit propagation:
  - If  $I$  is a unit clause  $M \rightarrow \{I\} \cup M$
  - remove all clauses from  $\Lambda$  which have  $\neg I$  as a disjunct, and
  - update all clauses in  $\Lambda$  containing  $I$  as a disjunct by removing that disjunct

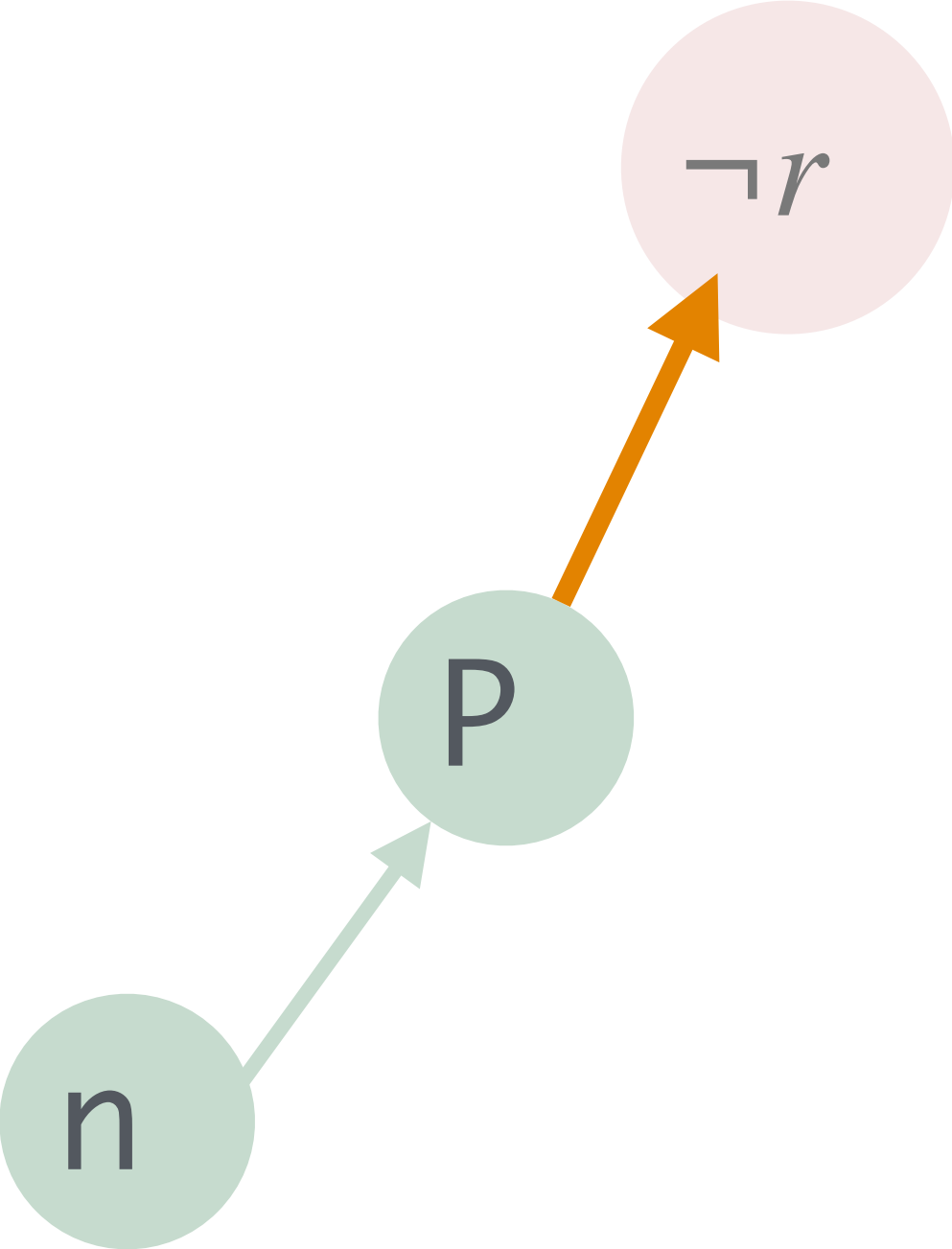
# Propagation

n

$n+p$
$-n+p+s$
$-p+-r$
$-u+t$
$q+r+t$
$-q+s$
$-p+t+u$
$-p+-t+-u$
$r+-t+u$

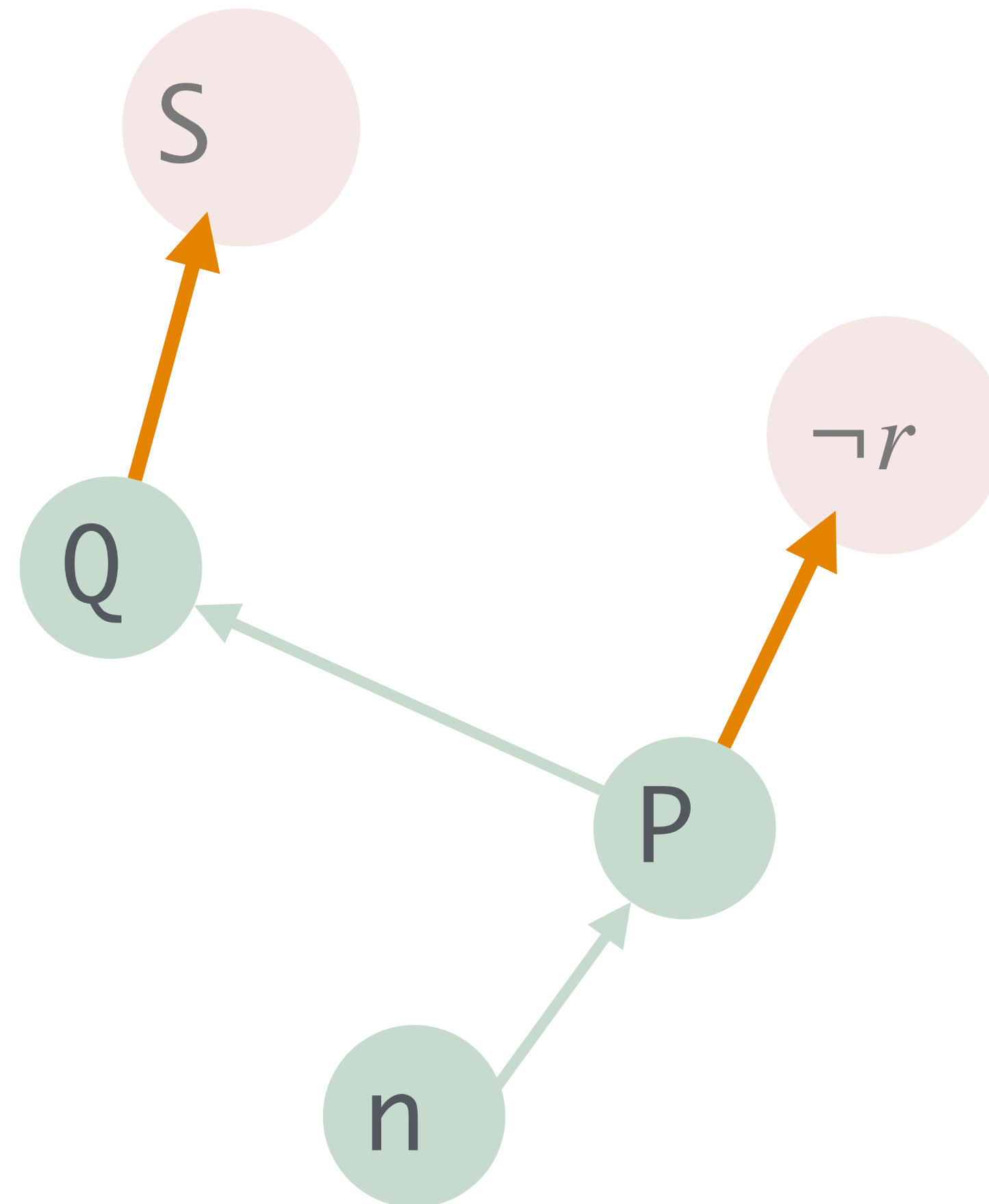


# Propagation



$p+s$
$-p+-r$
$-u+t$
$q+r+t$
$-q+s$
$-p+t+u$
$-p+-t+-u$
$r+-t+u$

# Propagation



$-u+t$

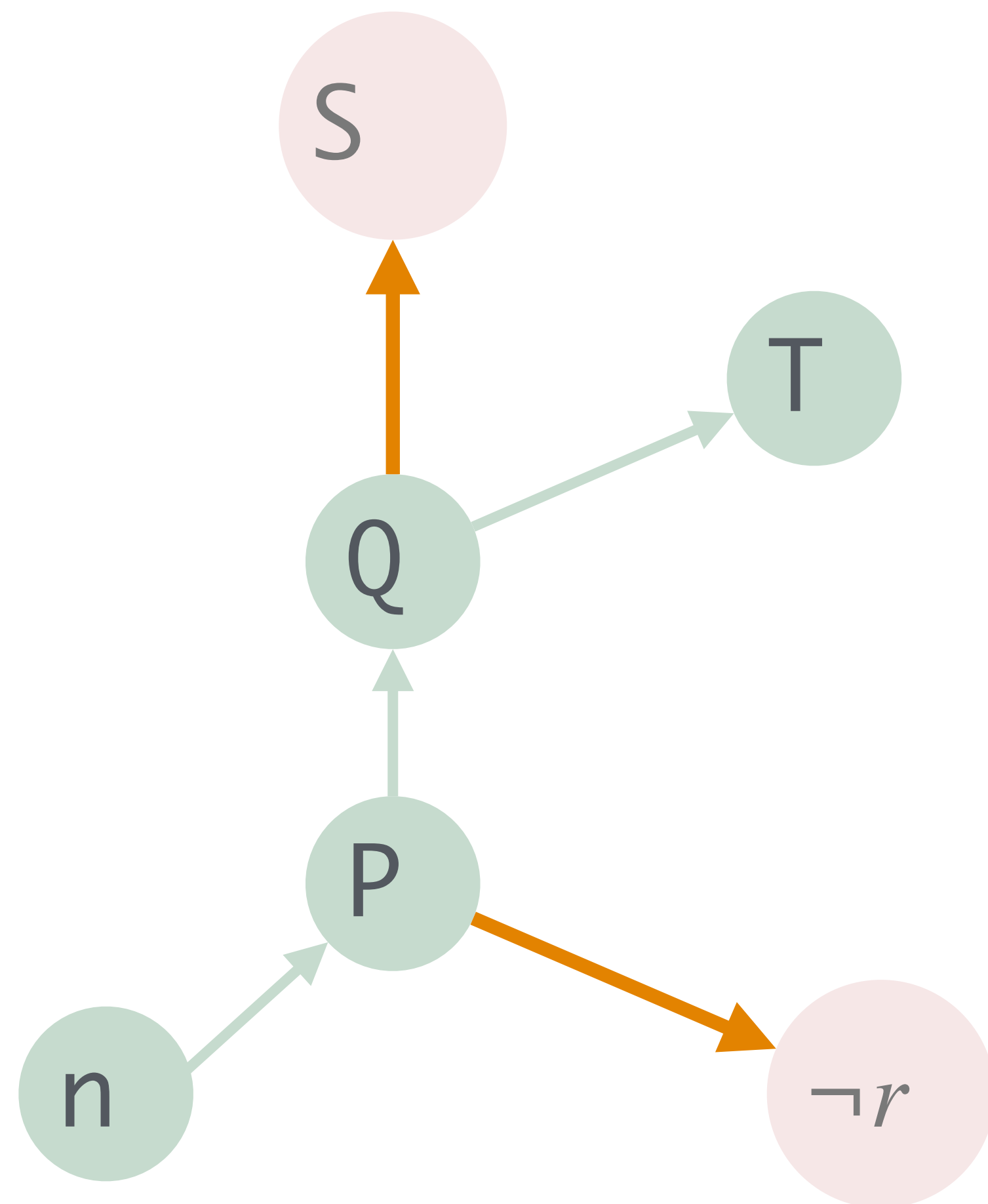
$-q+s$

$t+u$

$-t+-u$

$-t+u$

# Propagation



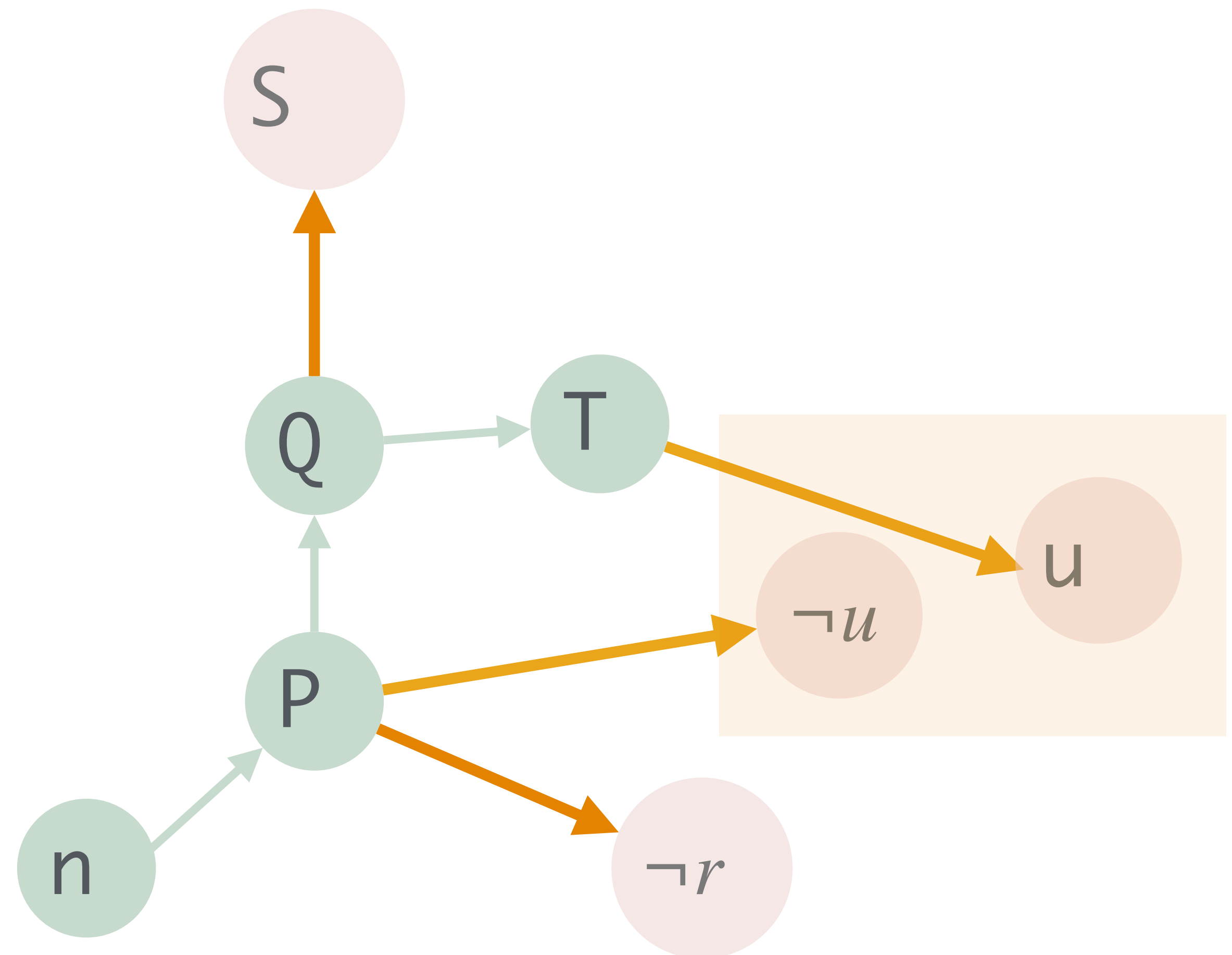
**CONFLICT!!**

$-u+t$
$t+u$
$-t+-u$
$-t+u$



# Conflict Resolution

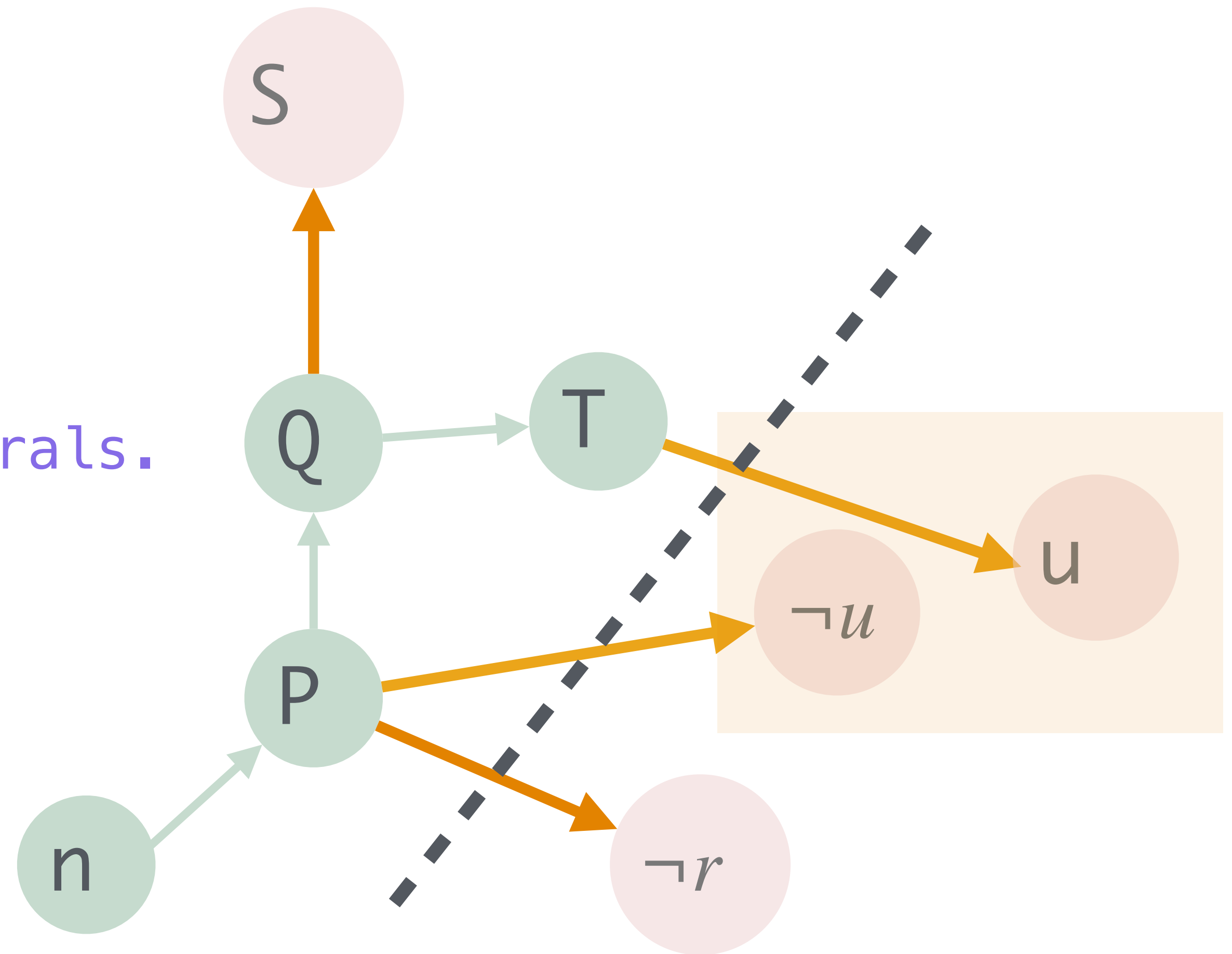
- Conflict between  $\neg t \vee \neg p \vee \neg u$  and  $r \vee \neg t \vee u$
- Involves three variables:  $t, p, r$
- $\neg r$  follows from  $p$
- DPLL must retry  $t$  or  $p$
- Non-chronological backtracking
- Pop  $t$  and  $q$
- Try  $\neg t$
- If it fails,  $\neg p$



# Conflict Resolution

# Learning

- To avoid the conflict
- Cut the conflict
- Add disj of negated border literals.
- Eg:  $\neg P + \neg T$



# CDCL

## Conflict-Driven Clause Learning

- DPLL plus heuristics for conflict handling
- Different ways to do clause learning:
  - “1-UIP strategy”: working backwards from conflicting literals, find the first (“latest”) node which is on all paths from the decision literal to be changed.
  - Learned rules may lead to earlier propagation
  - They may grow too quickly

# SAT Research

SAT 2024 and CAV2024

- Symmetry
- Satzilla: using ML in SAT solving
- Compilation to OBDD, decision-DNNF
- Scalability and Parallelism
- Quantum Computing
- NeuralNetworks

# ML of Boolean Networks

- Learning Local Search Heuristics for Boolean Satisfiability
- Boolean Decision Rules via Column Generation
- A boolean task algebra for reinforcement learning
- Boolformer: Symbolic Regression of Logic Functions with Transformers
- On Quantifying Literals in Boolean Logic and its Applications to Explainable AI (Extended Abstract)
-



# Other representations

- And-Or Trees
  - Popular in Bayes Networks
  - Exploit independence
  - Exploit exclusiveness
  - See work by Darwiche
  - We'll focus on Binary Decision Diagrams

# OBDD

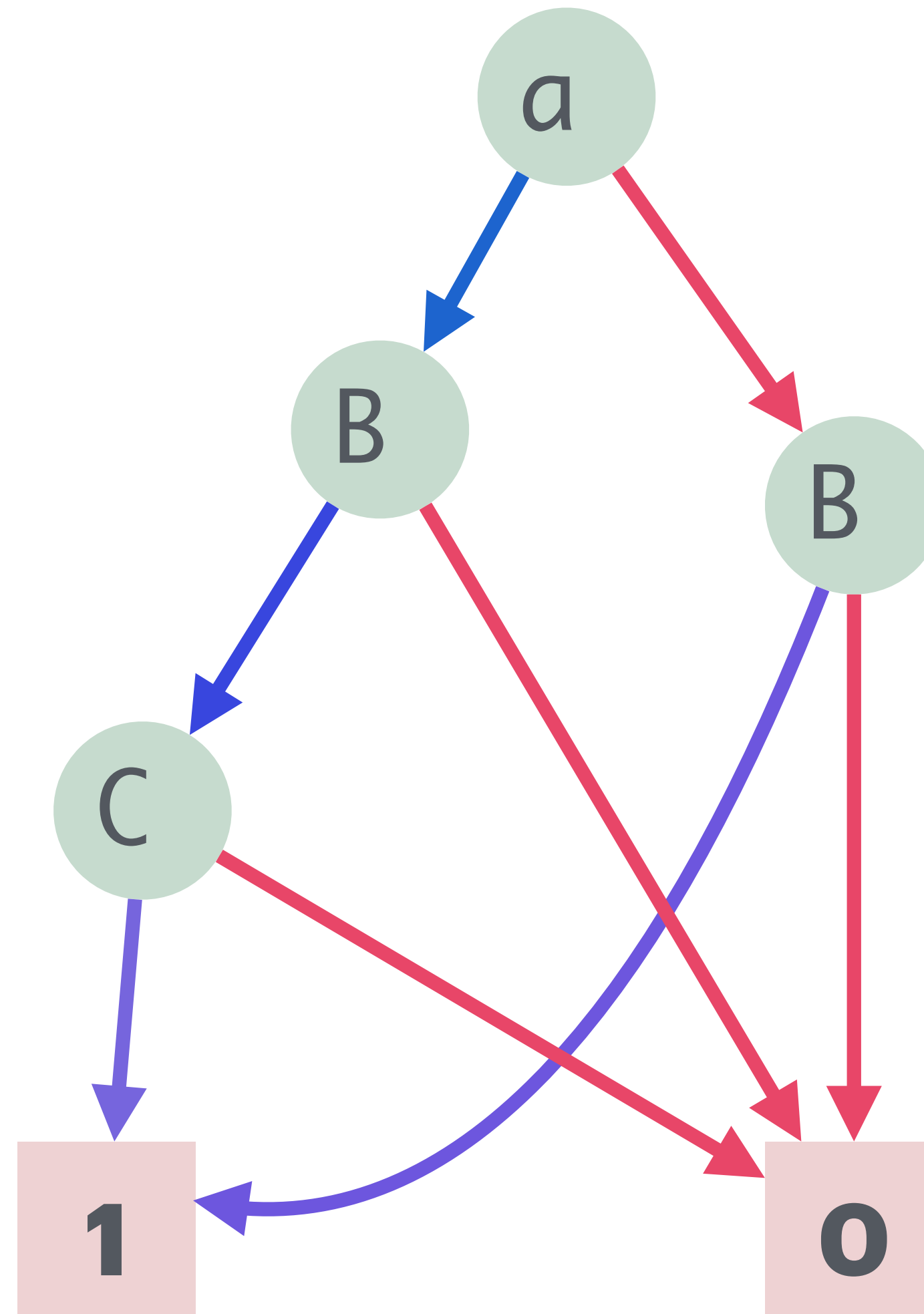
Work by Bryant

- Consider  $a \wedge (\neg b \vee c) \vee b \wedge c \vee \neg a \wedge \neg c \wedge b$
- Same as  $a \wedge (\neg b \vee c) \vee (a \vee \neg a) \wedge b \wedge c \vee \neg a \wedge \neg c \wedge b$
- Or  $a \wedge (\neg b \vee c \vee b \wedge c) \vee \neg a \wedge (\neg c \wedge b \vee b \wedge c)$
- We can take c:  $a \wedge (b \wedge c \vee \neg b) \vee \neg a \wedge (b)$

# OBDD

$$a \wedge (\neg b \vee c) \vee b \wedge c \vee \neg a \wedge \neg c \wedge b$$

$$a \wedge (b \wedge c \vee \neg b) \vee \neg a \wedge (b)$$



# OBDD

How?

- Split on variables until reaching true or false
- For each node  $T$  with left-subtree  $VT$  and right-subtree  $FT$ :
- $V = T \wedge VT \vee \neg T \wedge FT$
- Also, also choose the same order for selecting variables, independent of branch
- Plus, merge equal bottom subtrees

# OBDD

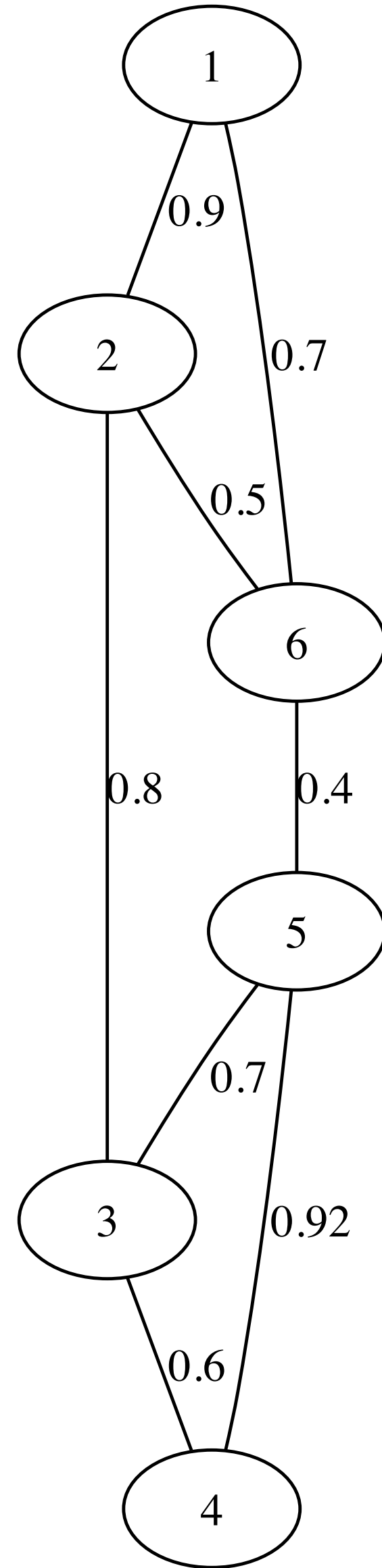
## Why

- Compiled Representation of theory
- $a \neg bc$  is true?
- $\neg a \neg b \neg c$  is true?
- Just follow the path in the graph
- Is the theory satisfiable?
- Just look for a path from top to 1, or 1 to top
- Is the theory a tautology?
-



# A Prolog program for path finding

```
% An example graph:  
0.9::edge(1,2).  
0.8::edge(2,3).  
0.6::edge(3,4).  
0.7::edge(1,6).  
0.5::edge(2,6).  
0.4::edge(6,5).  
0.7::edge(5,3).  
0.2::edge(5,4).
```



←  
**Probabilities**

→  
**Prolog**

%%%

% definition of acyclic path

% using list of visited nodes

path(X,Y) :- path(X,Y,[X],\_).

path(X,X,A,A).

path(X,Y,A,R) :-

X \== Y,

edge(X,Z),

absent(Z,A),

path(Z,Y,[Z|A],R).

% using directed edges in both

% directions

edge(X,Y) :- dir\_edge(Y,X).

edge(X,Y) :- dir\_edge(X,Y).

% checking whether node hasn't

% been visited before

absent(\_,[]).

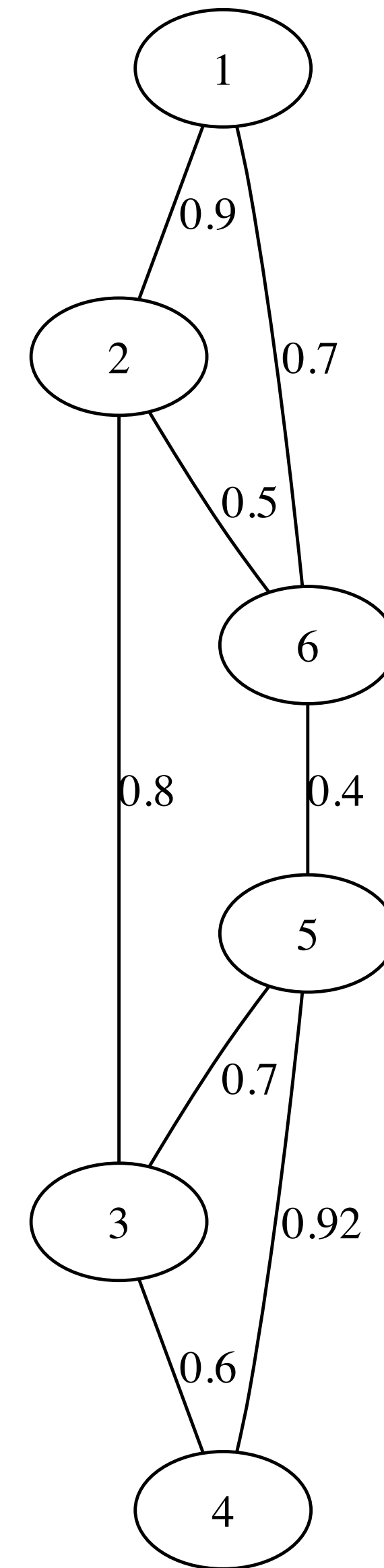
absent(X,[Y|Z]):-X \= Y, absent(X,Z).

# Computing Probabilities

Prob of reaching node 4 from node 1

- $\text{Pr}(1 \dots 4)$  is the union of
  - $\text{Pr}(1,2,3,4) = \text{Pr}(1 \rightarrow 2) \text{Pr}(2 \rightarrow 3) \text{Pr}(3 \rightarrow 4)$
  - $\text{Pr}(1,2,3,5,4) = \text{Pr}(1 \rightarrow 2) \text{Pr}(2 \rightarrow 3) \text{Pr}(3 \rightarrow 5) \text{Pr}(5 \rightarrow 4)$
  - $\text{Pr}(1,2,6,5,3,4) = \text{Pr}(1 \rightarrow 2) \text{Pr}(2 \rightarrow 6) \text{Pr}(6 \rightarrow 5) \text{Pr}(5 \rightarrow 3) \text{Pr}(3 \rightarrow 4)$
  - $\text{Pr}(1,2,6,5,4) = \text{Pr}(1 \rightarrow 2) \text{Pr}(2 \rightarrow 6) \text{Pr}(6 \rightarrow 5) \text{Pr}(5 \rightarrow 4)$
  - $\text{Pr}(1,6,5,3,4) = \text{Pr}(1 \rightarrow 6) \text{Pr}(6 \rightarrow 5) \text{Pr}(5 \rightarrow 3) \text{Pr}(3 \rightarrow 4)$
  - $\text{Pr}(1,6,5,4) = \text{Pr}(1 \rightarrow 6) \text{Pr}(6 \rightarrow 5) \text{Pr}(5 \rightarrow 4)$

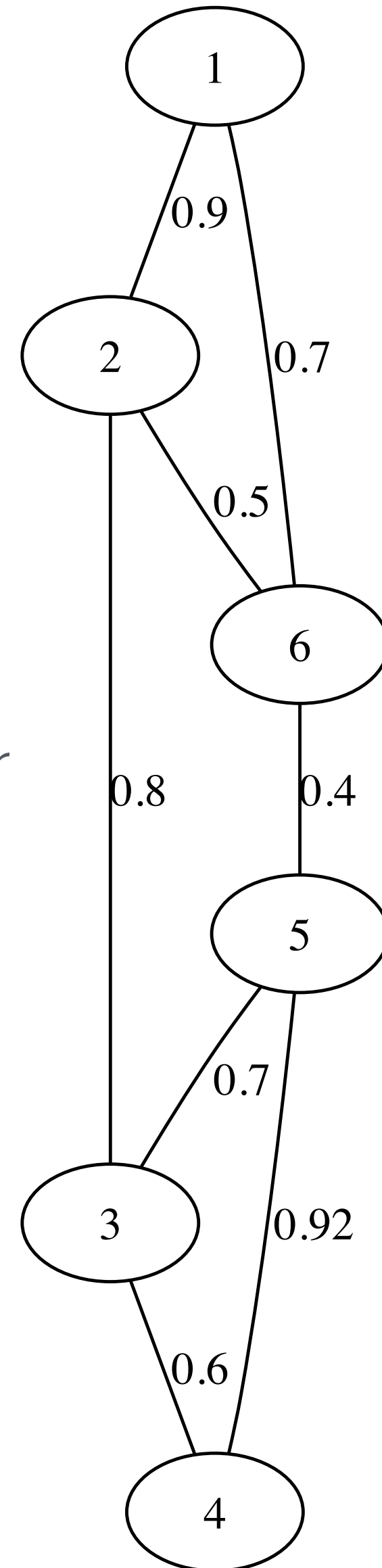
• **Union is a Sum-Product**



# BDD to the rescue

Pr(1—4)?

- BDDs split on a variable
- $:V \wedge T \vee \neg V \wedge F$
- The splits in the same order
- Generate layers



1--2

2--3

3--4

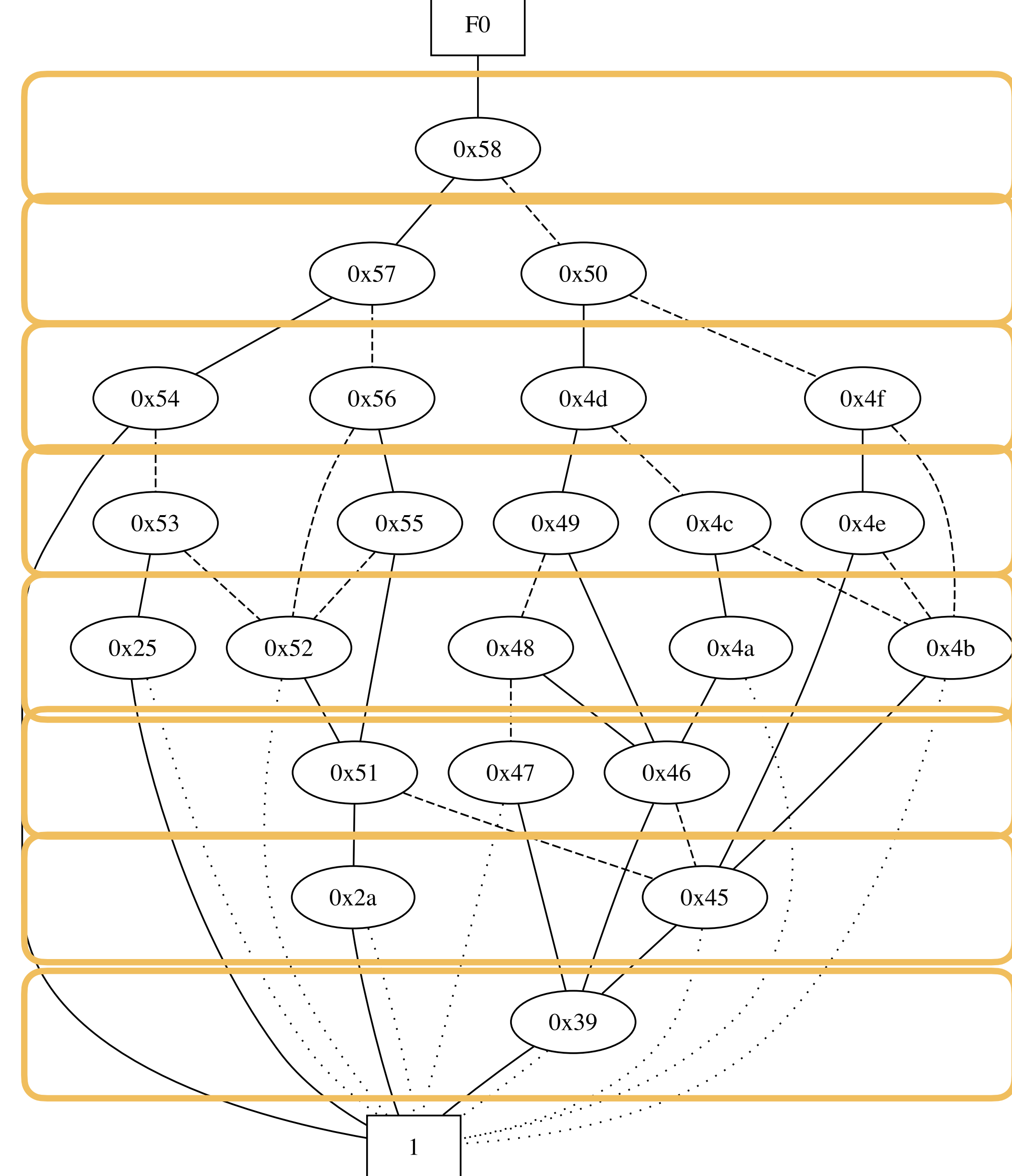
5--3

5--4

2--6

6--5

1--6



# BDD to the rescue

Pr(1—4)?

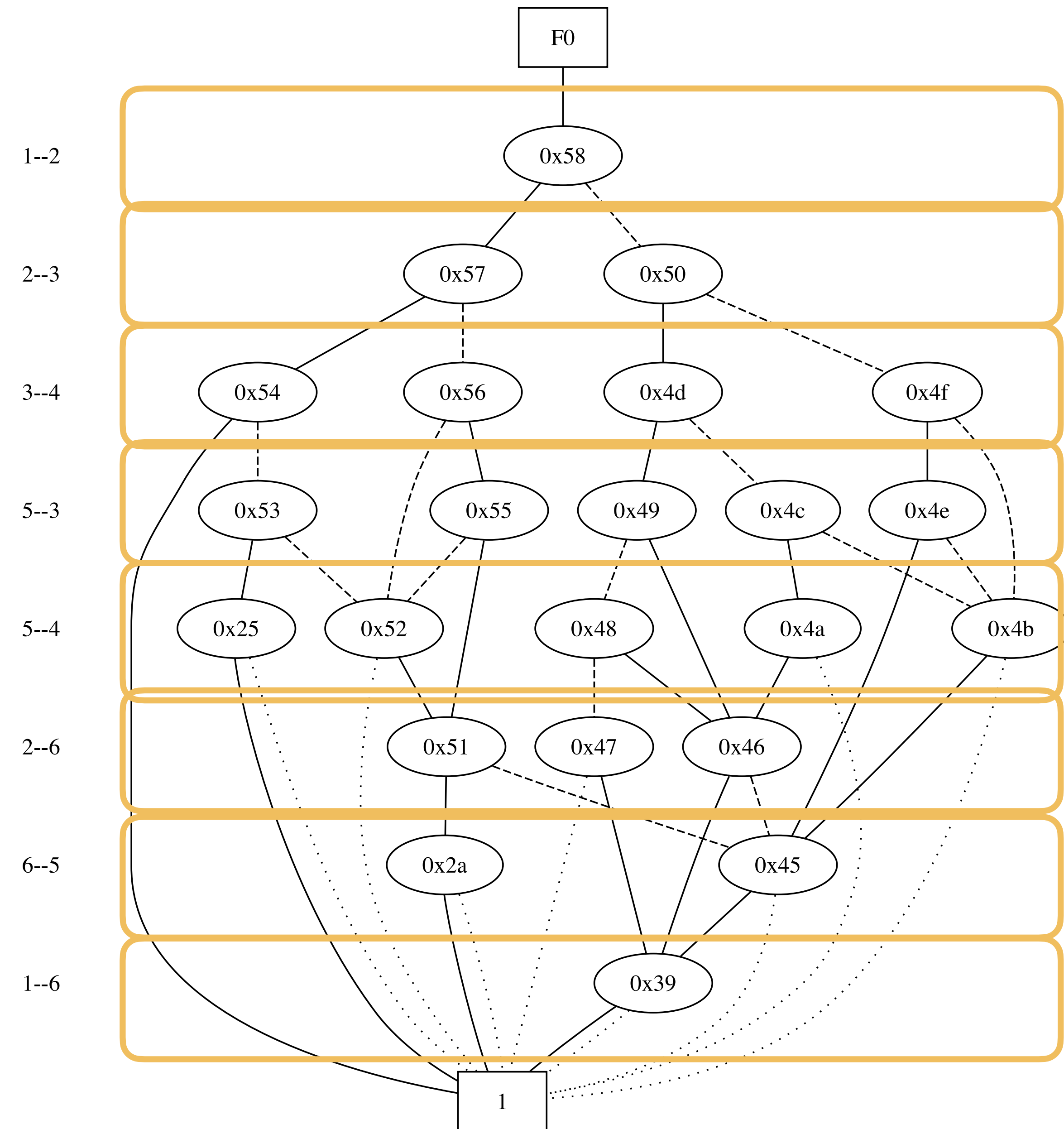
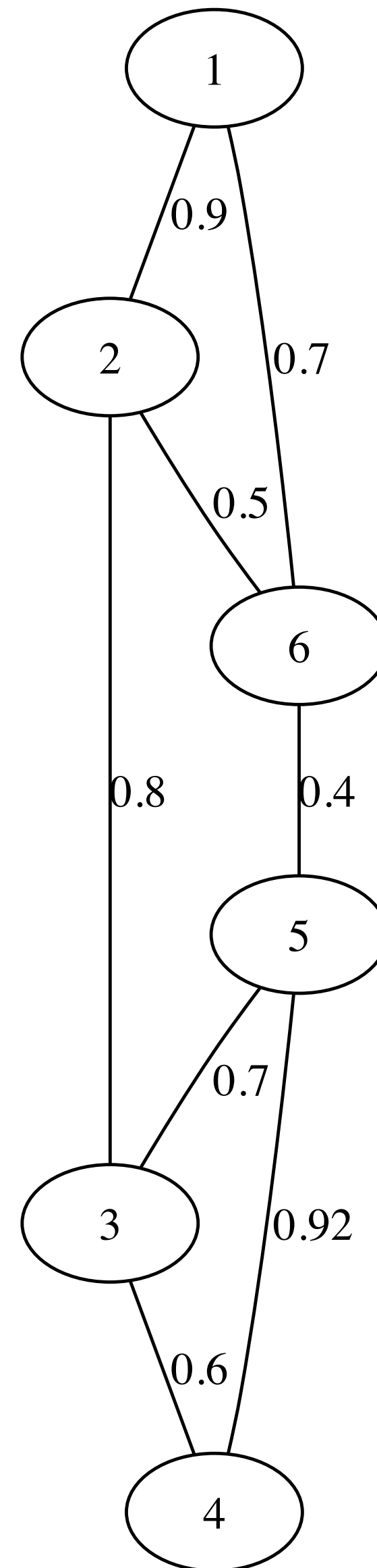
- BDDs split on a variable

- $:V \wedge T \vee \neg V \wedge F$

- Problog softens split

- $Pr(T)\theta_v + Pr(F)(1 - \theta_v)$

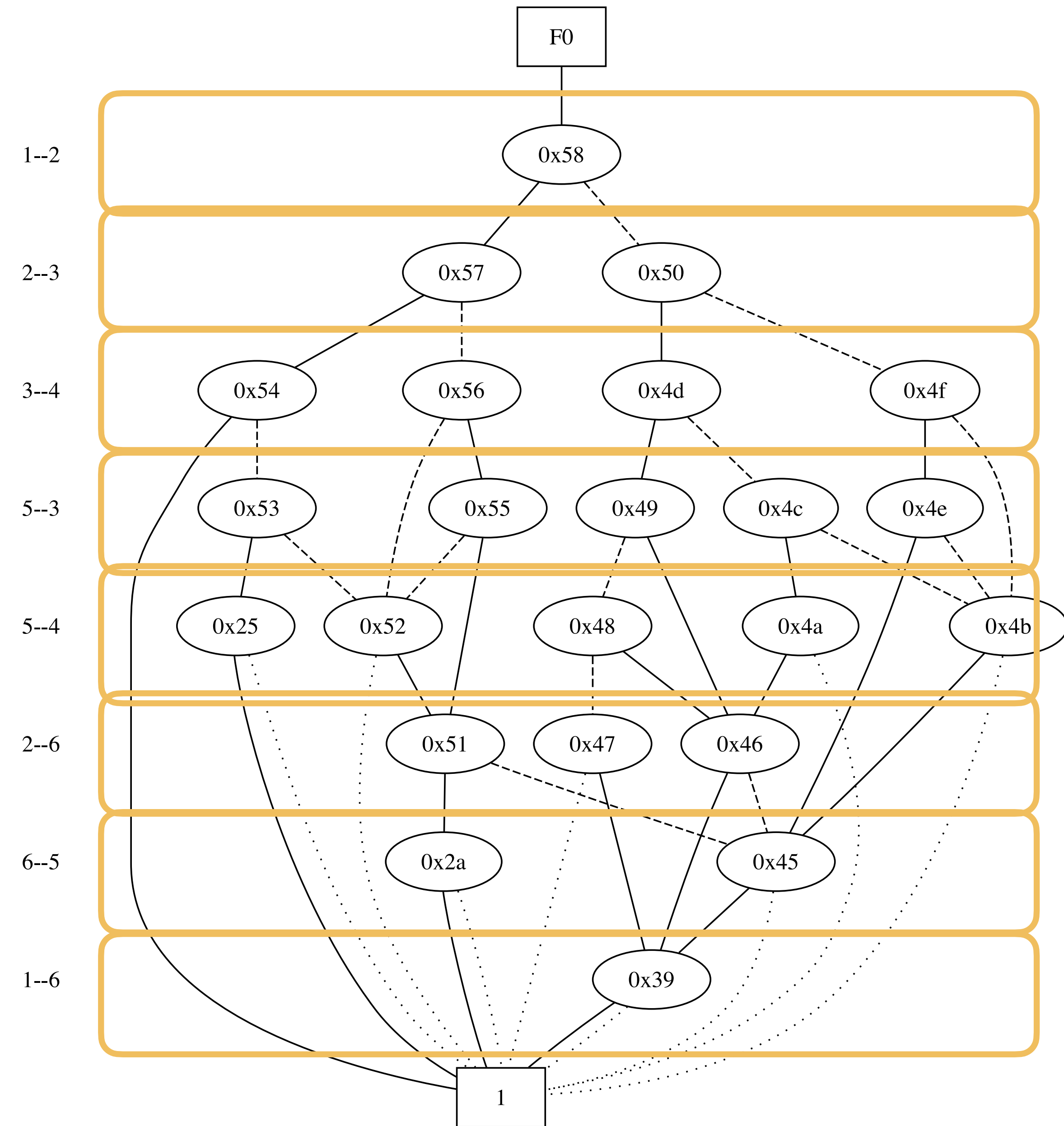
- Compute bottom up



# BDD to the rescue

## Pr(1—4)?

- Problog softens split
- $Pr(Node) = \theta_v Pr(T) + (1 - \theta_v) Pr(F)$
- $Pr(0x2a) = \theta_{56} + (1 - \theta_{56})(1 - 1) = \theta_{56}$
- $Pr(0x39) = \theta_{16} + (1 - \theta_{16})(1 - 1) = \theta_{16}$
- $Pr(0x45) = \theta_{16}\theta_{56} + (1 - \theta_{56})(1 - 1) = \theta_{16}\theta_{56}$
- Pr(0x51)...
- Until we reach F





# Parameter Learning

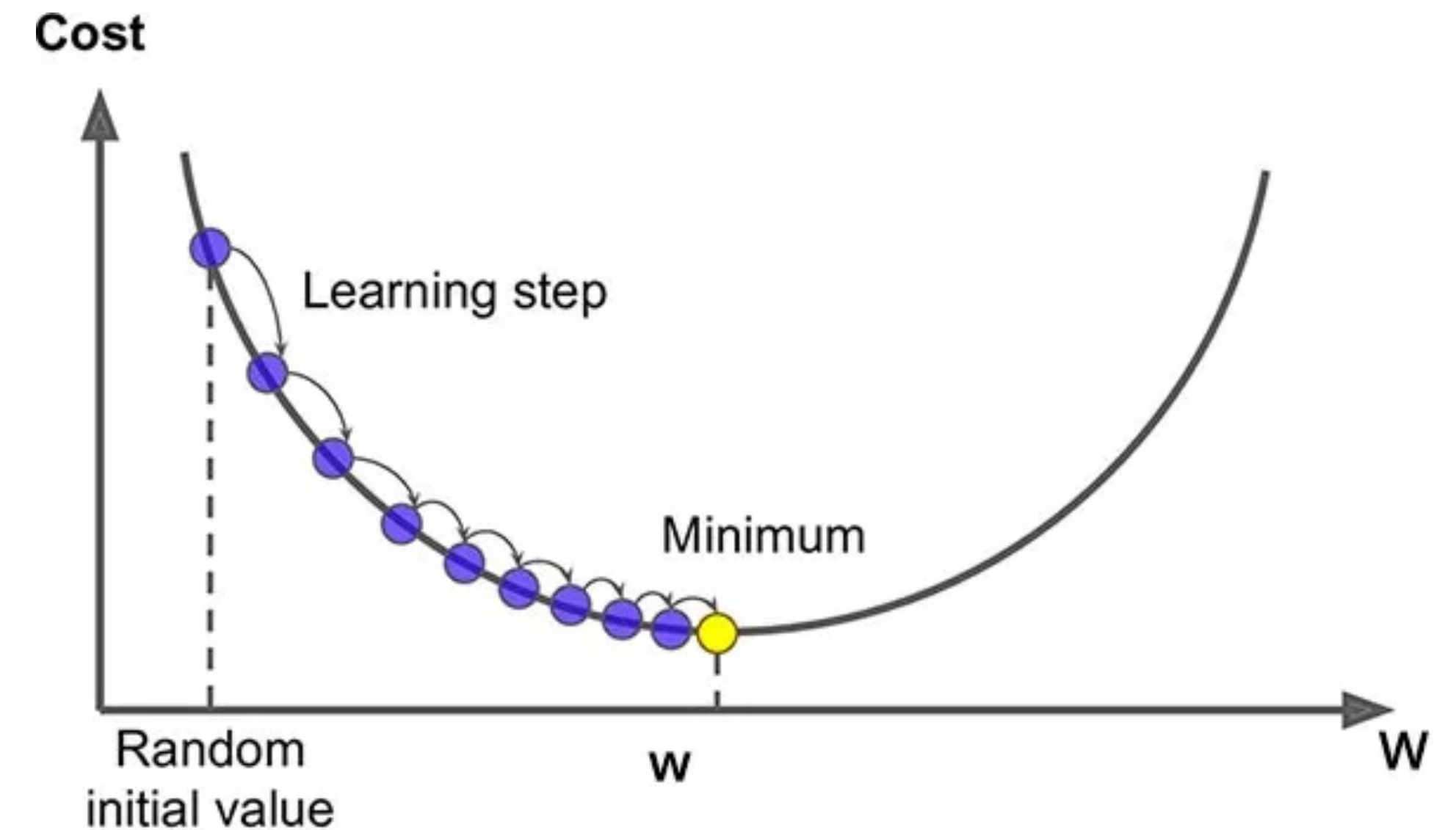
Probabilities from ex

- We want to minimise  $\sum_i |\hat{F}(\mathbf{x}_i) - y_i|$

- To use gradient descent

- solve  $\sum_i \frac{\delta \hat{F}(\mathbf{x}_i)}{\delta \theta_{ij}} = 0$

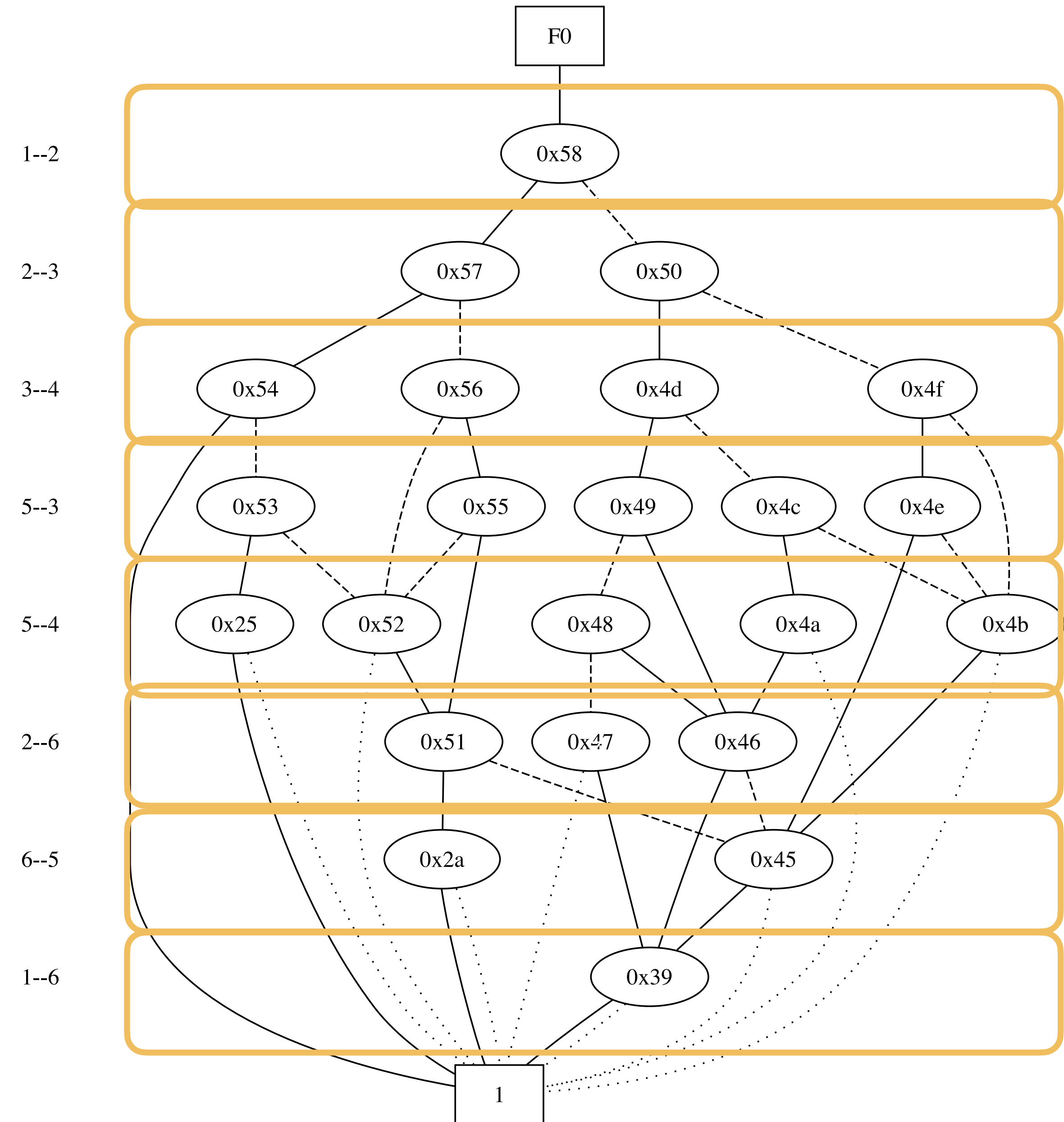
- How to compute a derivative for a tree?



# The Gradient

Let us obtain  $\delta F / \delta \theta_{34}$

Using  $Pr(T)\theta_v + Pr(F)(1 - \theta_v)$

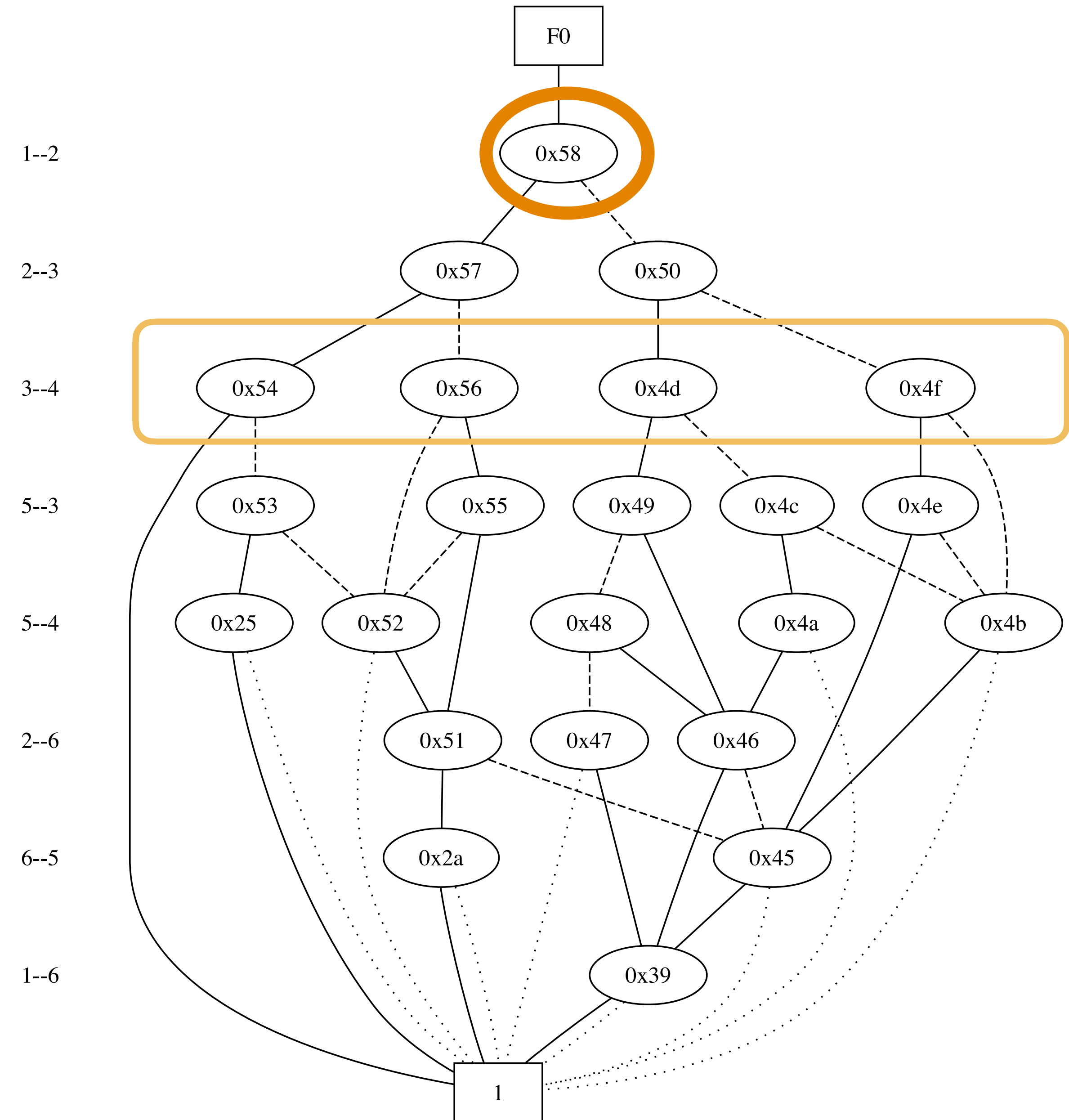


# The Gradient

Let us obtain  $\delta F / \delta \theta_{34}$

Using  $Pr(T)\theta_v + Pr(F)(1 - \theta_v)$

$$F = \theta_{12}F(0x57) + (1 - \theta_{12})F(0x59)$$

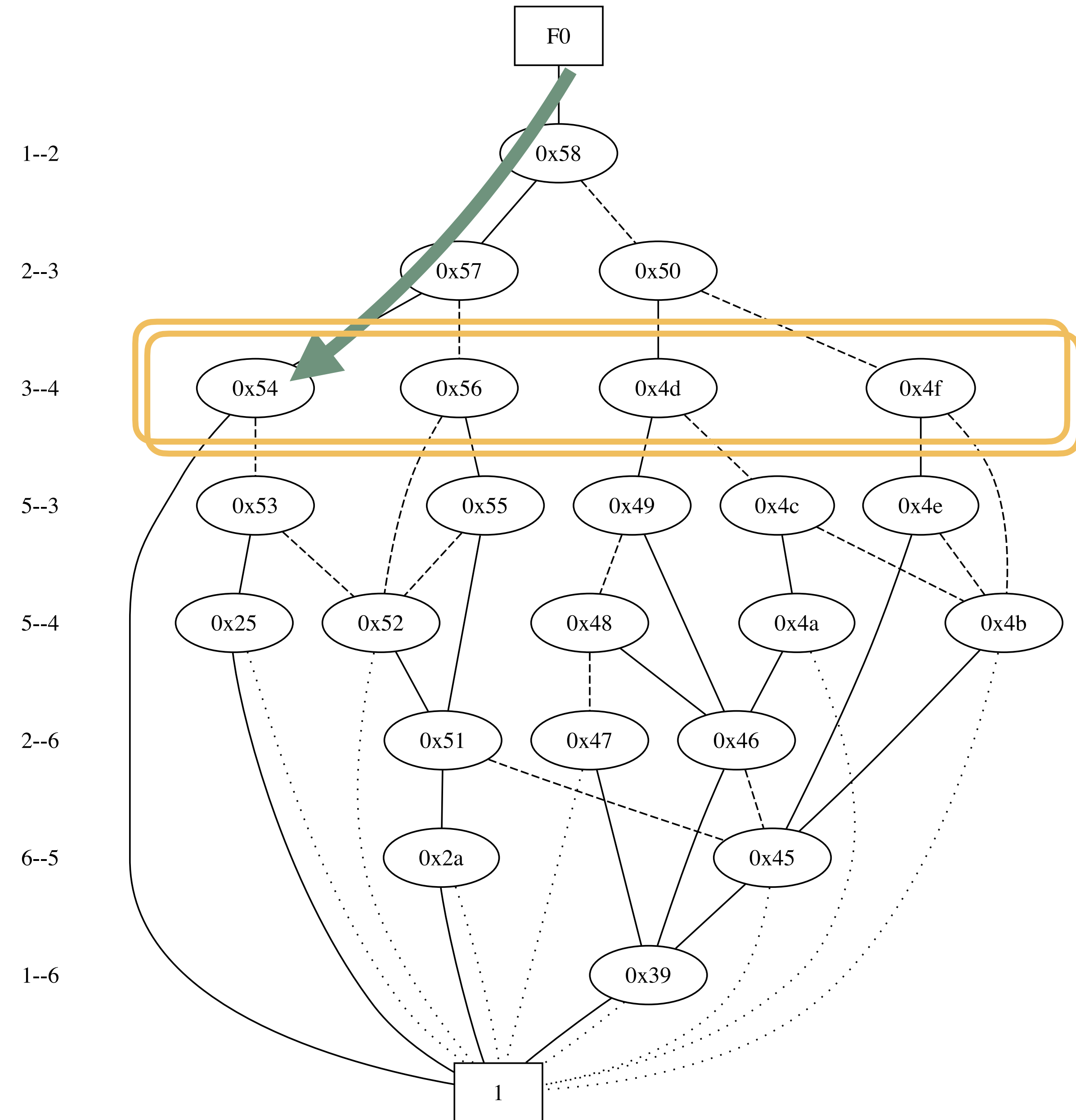


# The Gradient

Let us obtain  $\delta F / \delta \theta_{34}$

Using  $Pr(T)\theta_v + Pr(F)(1 - \theta_v)$

$$F = \theta_{12}\theta_{23}F(0x54) + \dots$$

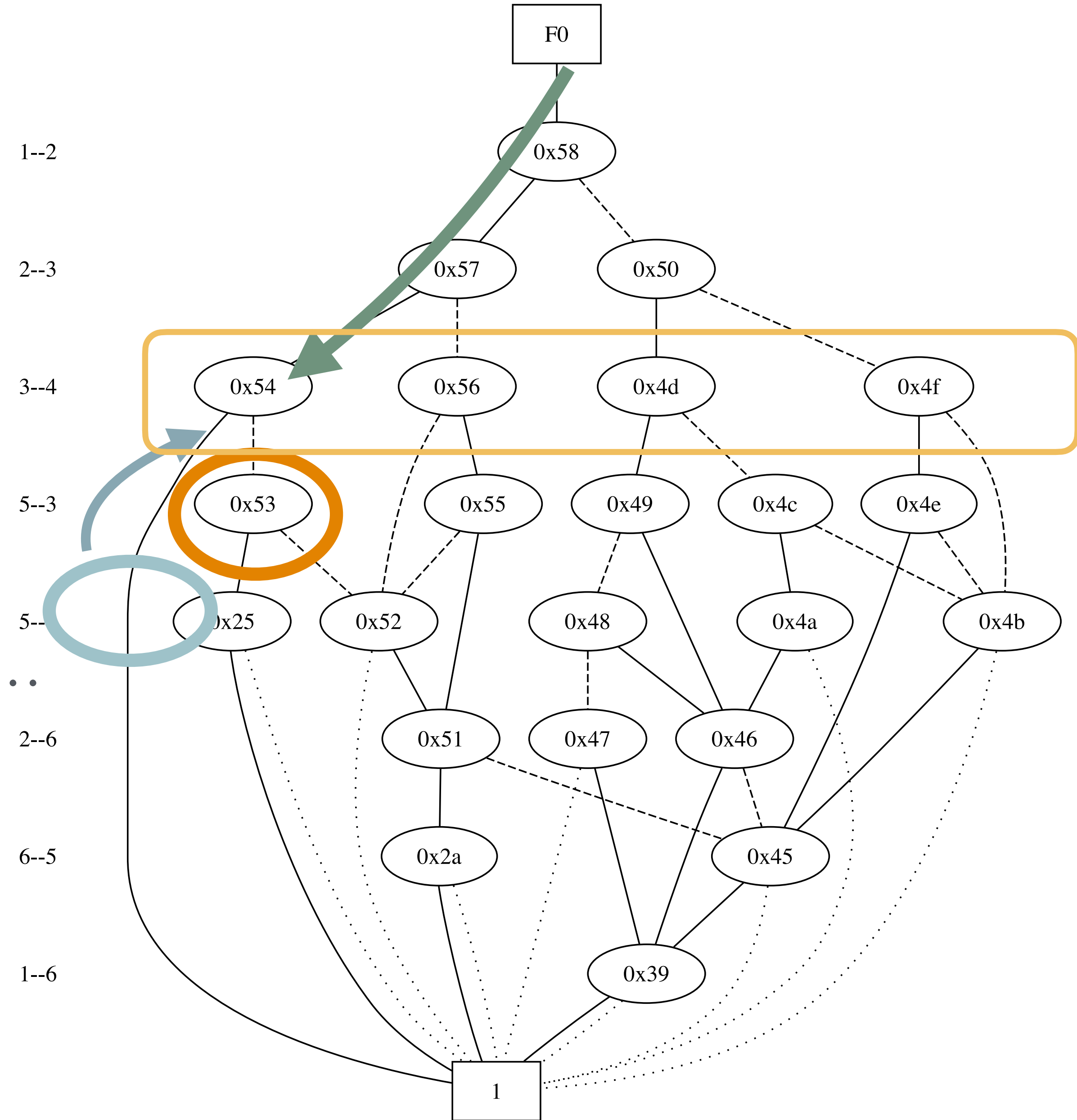


# The Gradient

Let us obtain  $\delta F / \delta \theta_{34}$

$$F = \theta_{12}\theta_{23}F(0x54) + \dots$$

$$F = \theta_{12}\theta_{23}(\theta_{34} \times F(1) + (1 - \theta_{34})F(0x53)) + \dots$$



# BackPropagation

- First compute probabilities from bottom-up:  $\text{Pr}(\text{0x39})$ ,  $\text{Pr}(\text{0x2a})$ ...
- Then compute the paths from top down
- Multiply and sum
- This BDD acts as a **Neural Network**
- We can see a node as a neuron
- Do we want to?



# ProbLog-2

- Designed to learn from interpretations
- First grounds the program
- Uses sentential decision diagrams
- Idea should still work?
- But, can we interpret a BDD?