

windshape.drone.control.
PIDController.PIDController.reset



```
graph LR; A["windshape.drone.control.  
PIDController.PIDController.  
__call__"] --> B["windshape.drone.control.  
PIDController.PIDController.reset"]
```

A diagram showing a call from the `__call__` method of the `PIDController` class to its `reset` method. The `__call__` method is in a white box on the right, and the `reset` method is in a gray box on the left. A blue arrow points from the `__call__` box to the `reset` box.

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PIDController.PIDController.
__call__