



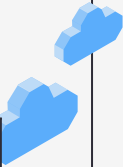
# Self-Driving Simulations: Develop Autonomous Car with Python

by Chris Raharja



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# Whom This Course is Intended for?



## **Automotive Enthusiast**

People who are interested in the latest trend in automotive industry which is self driving technology and curious to understand how it works from the technical perspective



## **Aspiring Software Engineer**

People who are planning to be a software engineer and particularly interested in improving Python programming skills through building projects with real use cases



# Tools, IDE, and Libraries



## Tools

Programming Language:  
Python 3.0



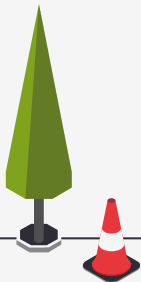
## IDE

- Visual Studio Code
- Sublime Text
- Pycharm



## Libraries

- Pygame
- Neat



# Introduction to Autonomous Cars



## What?

A car with self driving capability where it can operate on the road without human supervision



## Technologies

- ❖ Neural network
- ❖ Reinforcement learning
- ❖ Machine learning



## Capabilities

- Real time decision making
- Accurate sensor system

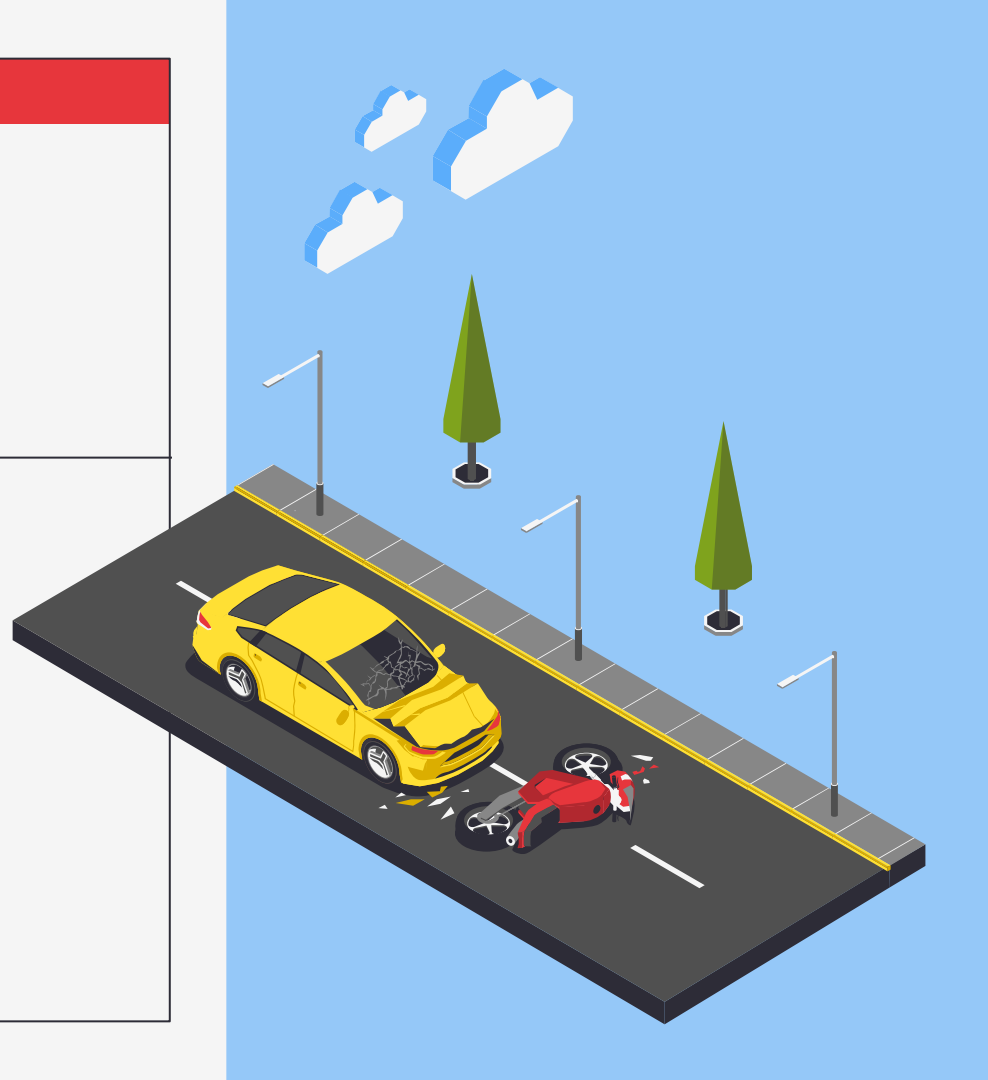


## Limitations

- ❑ Limited human like intuition
- ❑ Complex & unpredictable situation



# How Autonomous Car Works?



# Setting Up All Required Tools



01

## Visual Studio Code

<https://code.visualstudio.com/>



02

## Python

<https://www.python.org/downloads/>



03

## Neat

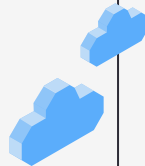
<https://neat-python.readthedocs.io/en/latest/>



04

## Pygame

<https://pypi.org/project/pygame/>



# Basic Python Training Session

## Data Types

Learning different data types/variables in Python

## Class

Learning how to create class in python and understanding how it works

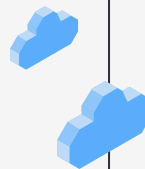


## Function & Parameter

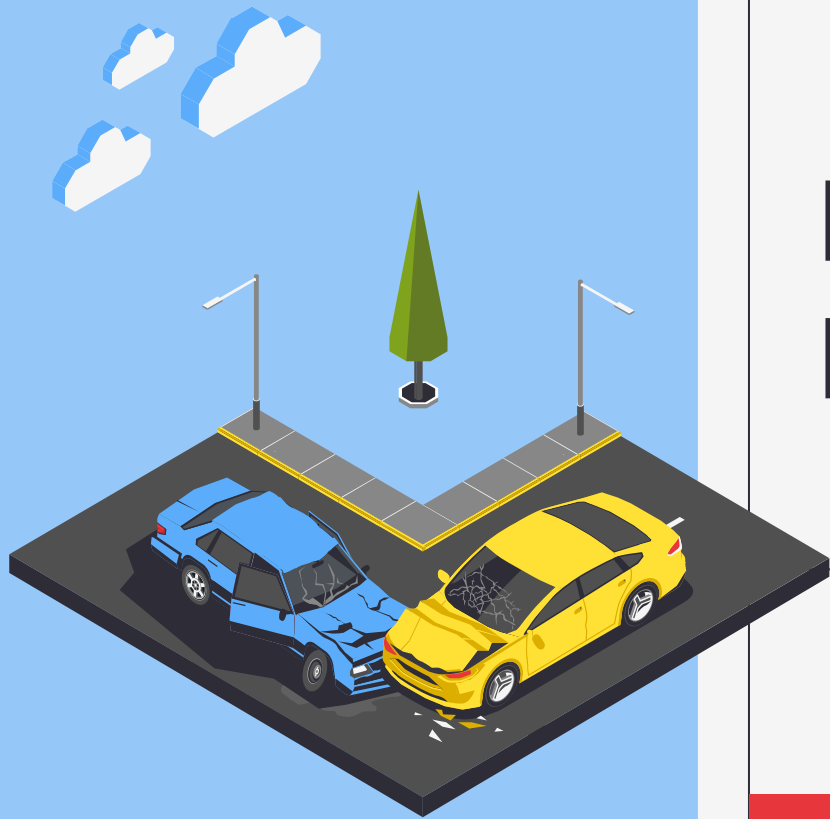
Learning how to create function and pass down parameter to the function

## Basics of Pygame

Learning the basic concepts of Pygame







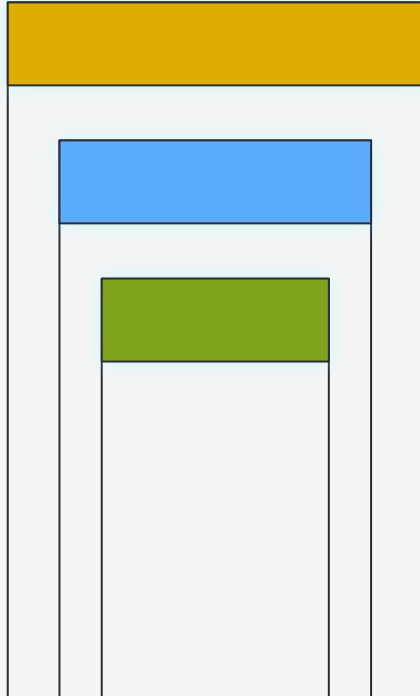
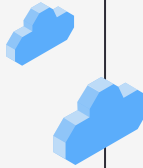
# Building the Project

## Self Driving Autonomous Car Simulation

- [https://www.gimp.org/tutorials/Draw\\_A\\_Paint\\_Brush/](https://www.gimp.org/tutorials/Draw_A_Paint_Brush/)
- <https://neat-python.readthedocs.io/en/stable/pdf/>



# Testing Self Driving Features



## Decision Making Ability

Car can navigate lanes, handle intersections, change lanes, and react to dynamic scenarios in a reliable and robust manner



## Sensor Integration

Test the perception system of the autonomous car simulation by examining its ability to accurately detect and interpret objects, road markings, traffic signs



## Collision Prevention

Test the collision avoidance capabilities of the self-driving car simulation



# Conclusion & Summary



## Testing is Essential

Always make sure to test your project to ensure it works the way you expected



## Game Projects

Creating your own real self driving car might sound a bit unrealistic but what about creating your own self driving car game?



## Be Creative & Innovative

There are limitless opportunities you can potentially do with this expertise and always think outside the box



## Code Quality & Documentation

When it comes to writing code, always make sure that your code is readable and easy to understand



# Thank You

