# Multiple MLP Architectures on MNIST

December 8, 2018

## 1 Multiple MLP Architectures using Keras on MNIST

## 1.1 Purpose

The purpose of the study is to try out 3 different MLP architectures on MNIST dataset to compare the performance. The implementation is done in Keras.

## 1.2 Steps at a Glance:

- 1. Take the famous MNIST dataset as input. http://yann.lecun.com/exdb/mnist/
- 2. Feed it into 2-layered MLP Architecture: Input(784)-ReLu(512)-ReLu(128)-Sigmoid(output)
- 3. Find the accuracy and draw the Loss vs Epoch Plot
- 4. Introduce Batch Normalization and Dropouts.
- 5. Evaluate the model again by estimating accuracy and drawing loss diagram.
- 6. Feed same input to 3 layered MLP Architecture: Input(784)-ReLu(512)-ReLu(256)-ReLu(64)-Sigmoid(output)
- 7. Introduce Batch Normalization and Dropouts & evaluate the model again.
- 8. Feed same input to 5 layered MLP Architecture: Input(784)-ReLu(512)-ReLu(256)-ReLu(144)-ReLu(96)-ReLu(36)-Sigmoid(output)
- 9. Introduce Batch Normalization and Dropouts & evaluate the model again.
- 10. Analyze the output from the above 3 architectures and draw conclusions.

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In [53]: # if you keras is not using tensorflow as backend
     # set "KERAS_BACKEND=tensorflow" use this command
     from keras.utils import np_utils
     from keras.datasets import mnist
     import seaborn as sns
     from keras.initializers import RandomNormal
```

## 1.3 Loading and Pre-processing Data

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Number of training examples: 60000 and each image is of shape (28, 28)
Number of testing examples: 10000 and each image is of shape (28, 28)
In [56]: # if you observe the input shape its 3 dimensional vector
          # for each image we have a (28*28) vector
          # we will convert the (28*28) vector into single dimensional vector of 1\,*\,784
         X_train = X_train.reshape(X_train.shape[0], X_train.shape[1]*X_train.shape[2])
         X test = X_test.reshape(X_test.shape[0], X_test.shape[1]*X_test.shape[2])
In [57]: # after converting the input images from 3d to 2d vectors
         print("Number of training examples :", X_train.shape[0],
                     "and each image is of shape (%d)"%(X_train.shape[1]))
         print("Number of testing examples :", X_test.shape[0],
                     "and each image is of shape (%d)"%(X_test.shape[1]))
Number of training examples: 60000 and each image is of shape (784)
Number of testing examples: 10000 and each image is of shape (784)
In [58]: # An example data point
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In [59]: # if we observe the above matrix each cell is having a value between 0-255 # before we move to apply machine learning algorithms lets try to normalize the data #  $X \Rightarrow (X - Xmin)/(Xmax - Xmin) = X/255$ 

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X\_test = X\_test/255

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In [61]: # here we are having a class number for each image
         print("Class label of first image :", y_train[0])
         # lets convert this into a 10 dimensional vector
         # ex: consider an image is 5 convert it into 5 => [0, 0, 0, 0, 0, 1, 0, 0, 0]
         # this conversion needed for MLPs
         Y_train = np_utils.to_categorical(y_train, 10)
         Y_test = np_utils.to_categorical(y_test, 10)
         print("After converting the output into a vector : ",Y_train[0])
Class label of first image: 5
After converting the output into a vector : [0. 0. 0. 0. 0. 1. 0. 0. 0.]
In [62]: # https://keras.io/getting-started/sequential-model-guide/
         # The Sequential model is a linear stack of layers.
         # you can create a Sequential model by passing
         # a list of layer instances to the constructor:
         # model = Sequential([
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               Dense(32, input_shape=(784,)),
               Activation('relu'),
         #
         #
               Dense(10),
               Activation('softmax'),
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# ])
# You can also simply add layers via the .add() method:
# model = Sequential()
# model.add(Dense(32, input_dim=784))
# model.add(Activation('relu'))
###
# https://keras.io/layers/core/
# keras.layers.Dense(units, activation=None, use_bias=True,
# kernel_initializer='qlorot_uniform', bias_initializer='zeros',
# kernel_regularizer=None, bias_regularizer=None, activity_regularizer=None,
# kernel_constraint=None, bias_constraint=None)
# Dense implements the operation: output = activation(dot(input, kernel) + bias)
# where activation is the element-wise activation function passed as the activation
# argument, kernel is a weights matrix created by the layer, and
# bias is a bias vector created by the layer (only applicable if use_bias is True).
\# output = activation(dot(input, kernel) + bias) => y = activation(WT. X + b)
####
# https://keras.io/activations/
# Activations can either be used through an Activation layer, or through
# the activation argument supported by all forward layers:
# from keras.layers import Activation, Dense
# model.add(Dense(64))
# model.add(Activation('tanh'))
# This is equivalent to:
# model.add(Dense(64, activation='tanh'))
# there are many activation functions available ex: tanh, relu, softmax
from keras.models import Sequential
from keras.layers import Dense, Activation
```

## 2 Initializations

```
In [63]: # initialization of some model parameters
    output_dim = 10
    input_dim = X_train.shape[1]

batch_size = 128
    nb_epoch = 20
```

## 3 Custom-Defined Functions

```
In [64]: %matplotlib inline
         import matplotlib.pyplot as plt
         import numpy as np
         import time
         # https://gist.github.com/greydanus/f6eee59eaf1d90fcb3b534a25362cea4
         # https://stackoverflow.com/a/14434334
         # this function is used to update the plots for each epoch and error
         def plt_dynamic(fig, x, vy, ty, ax, colors=['b']):
             ax.plot(x, vy, 'b', label="Validation Loss")
             ax.plot(x, ty, 'r', label="Train Loss")
             plt.legend()
             plt.grid()
             fig.canvas.draw()
In [65]: # To train the model using Adam
         # This function is common to all models.
         def trainModel(model):
             model.compile(optimizer='adam',
                               loss='categorical_crossentropy', metrics=['accuracy'])
             history = model.fit(X_train, Y_train, batch_size=batch_size,
                         epochs=nb_epoch, verbose=1, validation_data=(X_test, Y_test))
             return history
In [66]: # To plot the Train & Test loss graph.
         # This function is common to all models.
         def plotGraph(model, history):
             score = model.evaluate(X_test, Y_test, verbose=0)
             print('Test score:', score[0])
             print('Test accuracy:', score[1])
             fig,ax = plt.subplots(1,1)
             ax.set_xlabel('epoch') ; ax.set_ylabel('Categorical Crossentropy Loss')
             # list of epoch numbers
```

```
x = list(range(1,nb_epoch+1))
# print(history.history.keys())
# dict_keys(['val_loss', 'val_acc', 'loss', 'acc'])
# history = model drop.fit(X train, Y train, batch size=batch size,
        #epochs=nb_epoch, verbose=1, validation_data=(X_test, Y_test))
# we will get val_loss and val_acc only
# when you pass the paramter validation_data
# val_loss : validation loss
# val_acc : validation accuracy
# loss : training loss
# acc : train accuracy
# for each key in histrory.histrory we will have
# a list of length equal to number of epochs
vy = history.history['val_loss']
ty = history.history['loss']
plt_dynamic(fig, x, vy, ty, ax)
```

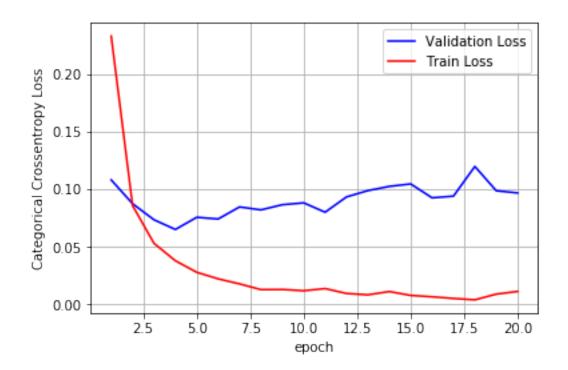
## 3.1 Model 1: (2-layered MLP Architecture)

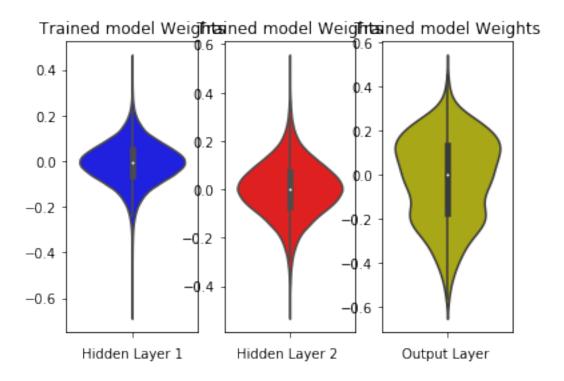
```
In [67]: def plotWeightM1(model):
             w_after = model.get_weights()
             h1_w = w_after[0].flatten().reshape(-1,1)
             h2_w = w_after[2].flatten().reshape(-1,1)
             out_w = w_after[4].flatten().reshape(-1,1)
             fig = plt.figure()
             plt.title("Weight matrices after model trained")
             plt.subplot(1, 3, 1)
             plt.title("Trained Weights")
             ax = sns.violinplot(y=h1_w,color='b')
             plt.xlabel('Hidden Layer 1')
             plt.subplot(1, 3, 2)
             plt.title("Trained Weights")
             ax = sns.violinplot(y=h2_w, color='r')
             plt.xlabel('Hidden Layer 2 ')
             plt.subplot(1, 3, 3)
             plt.title("Trained Weights")
             ax = sns.violinplot(y=out_w,color='y')
             plt.xlabel('Output Layer ')
             plt.show()
```

#### 3.1.1 Input(784)-ReLu(512)-ReLu(128)-Softmax(output)

```
In [68]: model_relu = Sequential()
    model_relu.add(Dense(512, activation='relu',
              input_shape=(input_dim,), kernel_initializer='he_normal'))
    model_relu.add(Dense(128, activation='relu', kernel_initializer='he_normal'))
    model_relu.add(Dense(output_dim, activation='softmax'))
    print(model_relu.summary())
    history = trainModel(model=model_relu)
    plotGraph(model=model_relu, history=history)
    plotWeightM1(model=model_relu)
     -----
Layer (type)
             Output Shape
                          Param #
______
dense_79 (Dense)
             (None, 512)
                          401920
______
dense_80 (Dense)
             (None, 128)
                          65664
dense 81 (Dense)
          (None, 10)
______
Total params: 468,874
Trainable params: 468,874
Non-trainable params: 0
None
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
Epoch 2/20
Epoch 3/20
60000/60000 [=============== ] - 3s 57us/step - loss: 0.0531 - acc: 0.9836 - val
Epoch 4/20
Epoch 5/20
Epoch 6/20
Epoch 7/20
60000/60000 [============== ] - 3s 58us/step - loss: 0.0179 - acc: 0.9942 - val
Epoch 8/20
Epoch 9/20
Epoch 10/20
```

```
Epoch 11/20
Epoch 12/20
60000/60000 [=====
             ========= ] - 3s 56us/step - loss: 0.0096 - acc: 0.9966 - val
Epoch 13/20
60000/60000 [===
              =========] - 3s 56us/step - loss: 0.0085 - acc: 0.9972 - val
Epoch 14/20
Epoch 15/20
60000/60000 [===
                ========] - 3s 56us/step - loss: 0.0079 - acc: 0.9973 - val
Epoch 16/20
Epoch 17/20
60000/60000 [============== ] - 3s 57us/step - loss: 0.0053 - acc: 0.9986 - val
Epoch 18/20
Epoch 19/20
Epoch 20/20
60000/60000 [====
                ========] - 3s 56us/step - loss: 0.0114 - acc: 0.9964 - val
Test score: 0.096843903848933
```





#### 3.1.2 Model 1: M1 + Batch-Normalization on hidden Layers

```
In [69]: # Multilayer perceptron

# https://intoli.com/blog/neural-network-initialization/
# If we sample weights from a normal distribution N(0,)
# we satisfy this condition with = (2/(ni+ni+1).
# h1 => = (2/(ni+ni+1) = 0.039 => N(0,) = N(0,0.039)
# h2 => = (2/(ni+ni+1) = 0.055 => N(0,) = N(0,0.055)
# h1 => = (2/(ni+ni+1) = 0.120 => N(0,) = N(0,0.120)

from keras.layers.normalization import BatchNormalization

model_batch = Sequential()

model_batch.add(Dense(512, activation='relu', input_shape=(input_dim,), kernel_initializer='he_normal'))
model_batch.add(BatchNormalization())

model_batch.add(Dense(128, activation='relu', kernel_initializer='he_normal'))
model_batch.add(BatchNormalization())

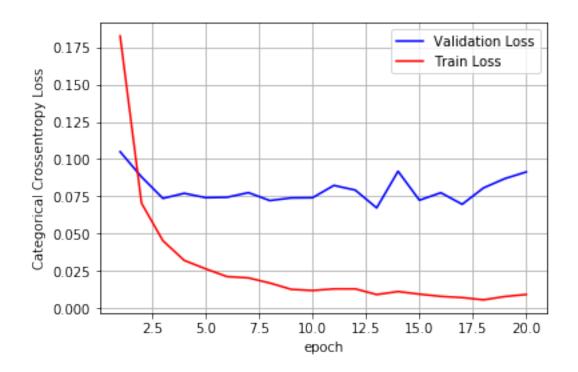
model_batch.add(Dense(output_dim, activation='softmax'))
```

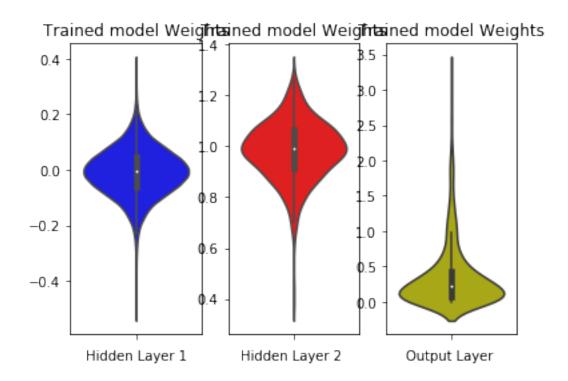
## model\_batch.summary()

history = trainModel(model=model\_batch)
plotGraph(model=model\_batch, history=history)
plotWeightM1(model=model\_batch)

Layer (type)	_	_						
dense_82 (Dense)								
batch_normalization_41 (Batch_normalization_41)				048				
dense_83 (Dense)			65					
batch_normalization_42 (Batch_								
dense_84 (Dense)	(None,	10)	12	290				
Total params: 471,434 Trainable params: 470,154 Non-trainable params: 1,280								
Train on 60000 samples, vali Epoch 1/20 60000/60000 [=================================	date on	10000 sam	nples - 17s 276us,	/step - los				
60000/60000 [======= Epoch 3/20 60000/60000 [=======				_				
Epoch 4/20 60000/60000 [======= Epoch 5/20				_				
60000/60000 [======= Epoch 6/20 60000/60000 [=======				_				
Epoch 7/20 60000/60000 [======= Epoch 8/20		=====]	- 4s 68us/s1	tep - loss:	0.0204 -	acc:	0.9933	- val
60000/60000 [====== Epoch 9/20				•				
60000/60000 [=================================				_				
Epoch 11/20 60000/60000 [======= Epoch 12/20	:=====	=====]	- 4s 66us/st	tep - loss:	0.0131 -	acc:	0.9958	- val

```
Epoch 13/20
60000/60000 [=============== ] - 4s 66us/step - loss: 0.0093 - acc: 0.9970 - val
Epoch 14/20
Epoch 15/20
           ========] - 4s 69us/step - loss: 0.0095 - acc: 0.9966 - val
60000/60000 [=====
Epoch 16/20
60000/60000 [====
            =======] - 4s 68us/step - loss: 0.0080 - acc: 0.9974 - val
Epoch 17/20
Epoch 18/20
Epoch 19/20
Epoch 20/20
Test score: 0.09142072524498654
```



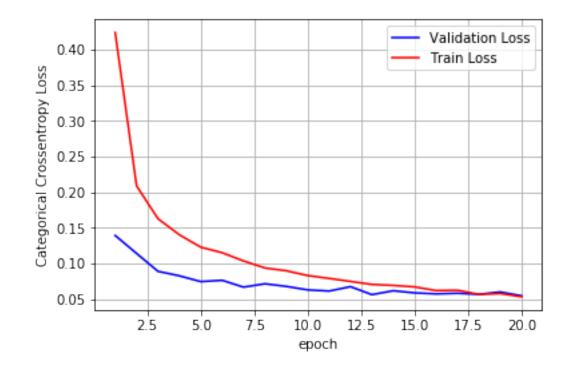


## 3.1.3 Model 1: M1 + Batch-Normalization + Dropout

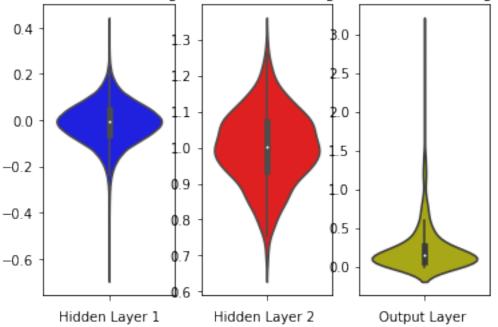
In [70]: # https://stackoverflow.com/questions/34716454/where-do-i-call-the-batchnormalization

```
Layer (type)
          Output Shape
                       Param #
______
            (None, 512)
dense 85 (Dense)
                        401920
batch_normalization_43 (Batc (None, 512)
_____
dropout_21 (Dropout) (None, 512)
-----
dense_86 (Dense)
           (None, 128)
                       65664
      .....
batch_normalization_44 (Batc (None, 128)
                       512
-----
dropout_22 (Dropout) (None, 128)
-----
dense_87 (Dense) (None, 10)
                       1290
______
Total params: 471,434
Trainable params: 470,154
Non-trainable params: 1,280
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
60000/60000 [============== ] - 17s 281us/step - loss: 0.4242 - acc: 0.8725 - variables
Epoch 2/20
60000/60000 [============== ] - 4s 72us/step - loss: 0.2088 - acc: 0.9374 - val
Epoch 3/20
Epoch 4/20
Epoch 5/20
Epoch 6/20
Epoch 7/20
Epoch 8/20
Epoch 9/20
Epoch 10/20
60000/60000 [============== ] - 5s 76us/step - loss: 0.0828 - acc: 0.9738 - val
Epoch 11/20
60000/60000 [============== ] - 5s 77us/step - loss: 0.0788 - acc: 0.9746 - val
Epoch 12/20
Epoch 13/20
60000/60000 [============== ] - 4s 74us/step - loss: 0.0704 - acc: 0.9782 - val
```

```
Epoch 14/20
Epoch 15/20
60000/60000 [=====
            =========] - 4s 73us/step - loss: 0.0669 - acc: 0.9793 - val
Epoch 16/20
60000/60000 [====
             ========] - 4s 73us/step - loss: 0.0617 - acc: 0.9808 - val
Epoch 17/20
Epoch 18/20
60000/60000 [===
             ========] - 4s 73us/step - loss: 0.0564 - acc: 0.9817 - val
Epoch 19/20
Epoch 20/20
Test score: 0.054348885305505246
```







## 3.2 Model 2 (3-layered MLP Architecture):

### 3.2.1 Plot Weights: Common Function

```
In [71]: def plotWeightM2(model):
             w_after = model.get_weights()
             h1_w = w_after[0].flatten().reshape(-1,1)
             h2_w = w_after[2].flatten().reshape(-1,1)
             h3_w = w_after[4].flatten().reshape(-1,1)
             out_w = w_after[6].flatten().reshape(-1,1)
             fig = plt.figure()
             plt.title("Weight matrices after model trained")
             plt.subplot(1, 4, 1)
             plt.title("Trained Wt")
             ax = sns.violinplot(y=h1_w,color='b')
             plt.xlabel('Hidden Layer 1')
             plt.subplot(1, 4, 2)
             plt.title("Trained Wt")
             ax = sns.violinplot(y=h2_w, color='r')
             plt.xlabel('Hidden Layer 2 ')
```

```
ax = sns.violinplot(y=h3_w, color='g')
          plt.xlabel('Hidden Layer 3 ')
          plt.subplot(1, 4, 4)
          plt.title("Trained Wt")
          ax = sns.violinplot(y=out_w,color='m')
          plt.xlabel('Output Layer ')
          plt.show()
3.2.2 Input(784)-ReLu(512)-ReLu(256)-ReLu(64)-Softmax(output)
In [72]: model_relu = Sequential()
       model_relu.add(Dense(512, activation='relu',
                       input_shape=(input_dim,), kernel_initializer='he_normal'))
       model_relu.add(Dense(256, activation='relu', kernel_initializer='he_normal'))
       model_relu.add(Dense(64, activation='relu', kernel_initializer='he_normal'))
       model_relu.add(Dense(output_dim, activation='softmax'))
       print(model_relu.summary())
       history = trainModel(model=model_relu)
       plotGraph(model=model_relu, history=history)
       plotWeightM2(model=model_relu)
Layer (type)
            Output Shape
                                          Param #
______
                      (None, 512)
dense_88 (Dense)
._____
                     (None, 256)
dense_89 (Dense)
                                          131328
-----
dense_90 (Dense)
               (None, 64)
                                           16448
-----
dense_91 (Dense) (None, 10)
                                          650
Total params: 550,346
Trainable params: 550,346
Non-trainable params: 0
```

plt.subplot(1, 4, 3)
plt.title("Trained Wt")

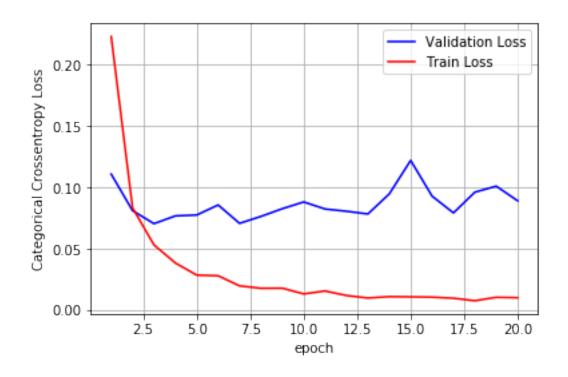
Train on 60000 samples, validate on 10000 samples

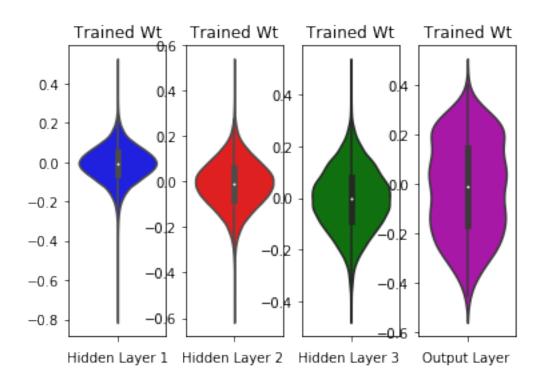
Epoch 1/20

Epoch 2/20

Epoch 3/20

```
60000/60000 [=============== ] - 4s 67us/step - loss: 0.0533 - acc: 0.9836 - val
Epoch 4/20
Epoch 5/20
60000/60000 [============== ] - 4s 67us/step - loss: 0.0287 - acc: 0.9906 - val
Epoch 6/20
Epoch 7/20
Epoch 8/20
60000/60000 [============== ] - 4s 68us/step - loss: 0.0180 - acc: 0.9942 - val
Epoch 9/20
Epoch 10/20
Epoch 11/20
Epoch 12/20
Epoch 13/20
Epoch 14/20
Epoch 15/20
Epoch 16/20
Epoch 17/20
Epoch 18/20
Epoch 19/20
Epoch 20/20
Test score: 0.08919506263012462
```



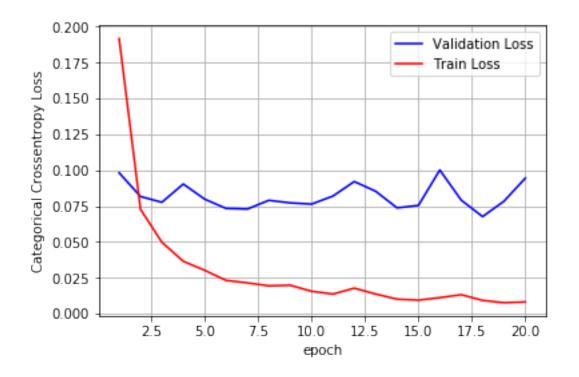


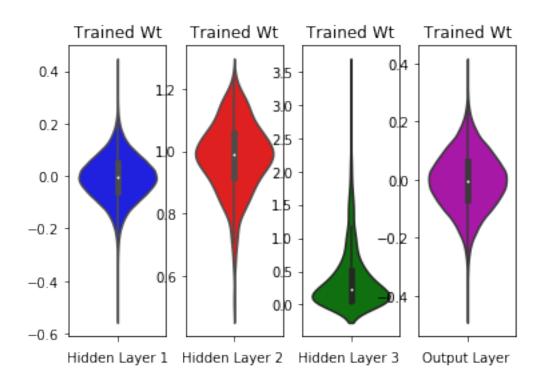
#### 3.2.3 Model 2: M2 + Batch-Normalization on 3 hidden Layers

```
In [73]: # Multilayer perceptron
        # https://intoli.com/blog/neural-network-initialization/
        # If we sample weights from a normal distribution N(0,) we satisfy this condition wit
        \# h1 \Rightarrow =(2/(ni+ni+1) = 0.039 \Rightarrow N(0,) = N(0,0.039)
        \# h2 \Rightarrow =(2/(ni+ni+1) = 0.055 \Rightarrow N(0,) = N(0,0.055)
        # h1 \Rightarrow =(2/(ni+ni+1) = 0.120 \Rightarrow N(0,) = N(0,0.120)
        from keras.layers.normalization import BatchNormalization
        model_batch = Sequential()
        model_batch.add(Dense(512, activation='relu',
                          input_shape=(input_dim,), kernel_initializer='he_normal'))
        model_batch.add(BatchNormalization())
        model_batch.add(Dense(256, activation='relu', kernel_initializer='he_normal'))
        model_batch.add(BatchNormalization())
        model_batch.add(Dense(64, activation='relu', kernel_initializer='he_normal'))
        model_batch.add(BatchNormalization())
        model_batch.add(Dense(output_dim, activation='softmax'))
        model_batch.summary()
        history = trainModel(model=model_batch)
        plotGraph(model=model_batch, history=history)
        plotWeightM2(model=model_batch)
              Output Shape
Layer (type)
                                                 Param #
______
dense 92 (Dense)
                         (None, 512)
   _____
batch_normalization_45 (Batc (None, 512)
                                                 2048
dense_93 (Dense)
                  (None, 256)
                                                 131328
batch_normalization_46 (Batc (None, 256)
                                                  1024
dense_94 (Dense)
                 (None, 64)
                                                  16448
batch_normalization_47 (Batc (None, 64)
                                                  256
dense_95 (Dense) (None, 10)
                                                 650
```

Total params: 553,674
Trainable params: 552,010
Non-trainable params: 1,664

Train on 60000 samples, validate on 10000 samples Epoch 1/20 60000/60000 [============== ] - 19s 313us/step - loss: 0.1918 - acc: 0.9438 - v Epoch 2/20 60000/60000 [=============== ] - 5s 90us/step - loss: 0.0727 - acc: 0.9782 - val Epoch 3/20 60000/60000 [============== ] - 5s 87us/step - loss: 0.0498 - acc: 0.9850 - val Epoch 4/20 Epoch 5/20 Epoch 6/20 Epoch 7/20 Epoch 8/20 Epoch 9/20 Epoch 10/20 Epoch 11/20 Epoch 12/20 Epoch 13/20 Epoch 14/20 60000/60000 [============== ] - 5s 87us/step - loss: 0.0101 - acc: 0.9969 - val Epoch 15/20 60000/60000 [=============== ] - 5s 87us/step - loss: 0.0094 - acc: 0.9970 - val Epoch 16/20 60000/60000 [=============== ] - 5s 82us/step - loss: 0.0111 - acc: 0.9964 - val Epoch 17/20 Epoch 18/20 Epoch 19/20 Epoch 20/20 Test score: 0.0944686686351095 Test accuracy: 0.9776





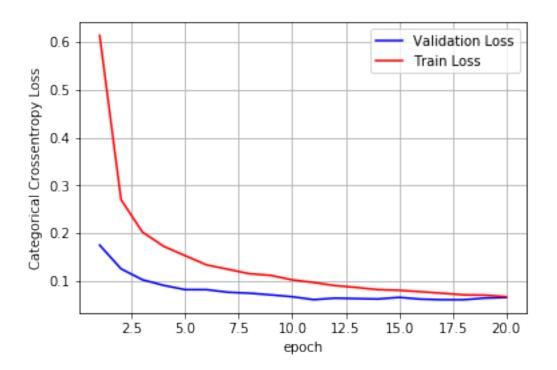
### 3.2.4 Model 2: M2 + Batch-Normalization + Dropout

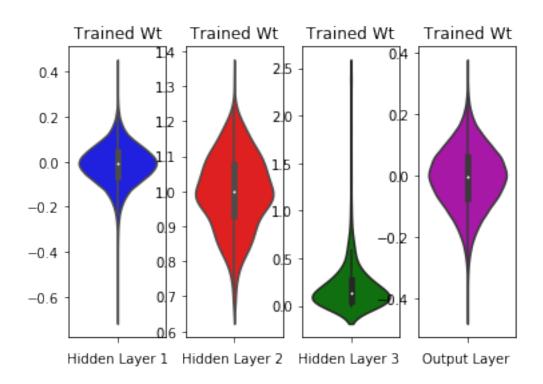
```
In [74]: # https://stackoverflow.com/questions/34716454/where-do-i-call-the-batchnormalization
       from keras.layers import Dropout
       model_drop = Sequential()
       model_drop.add(Dense(512, activation='relu',
                     input_shape=(input_dim,), kernel_initializer='he_normal'))
       model_drop.add(BatchNormalization())
       model_drop.add(Dropout(0.5))
       model_drop.add(Dense(256, activation='relu', kernel_initializer='he_normal'))
       model_drop.add(BatchNormalization())
       model_drop.add(Dropout(0.5))
       model_drop.add(Dense(64, activation='relu', kernel_initializer='he_normal'))
       model_drop.add(BatchNormalization())
       model_drop.add(Dropout(0.5))
       model_drop.add(Dense(output_dim, activation='softmax'))
       model_drop.summary()
       history = trainModel(model=model_drop)
       plotGraph(model=model_drop, history=history)
       plotWeightM2(model=model_drop)
 ______
                      Output Shape
Layer (type)
                                             Param #
______
dense_96 (Dense)
                        (None, 512)
                                              401920
batch_normalization_48 (Batc (None, 512)
                                             2048
dropout_23 (Dropout) (None, 512)
                   (None, 256)
dense_97 (Dense)
                                             131328
        _____
batch_normalization_49 (Batc (None, 256)
                                             1024
dropout_24 (Dropout) (None, 256)
dense_98 (Dense) (None, 64)
                                             16448
batch_normalization_50 (Batc (None, 64)
                                              256
```

dropout\_25 (Dropout) (None, 64)

```
dense_99 (Dense)
           (None, 10)
                      650
______
Total params: 553,674
Trainable params: 552,010
Non-trainable params: 1,664
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
60000/60000 [=============== ] - 19s 310us/step - loss: 0.6132 - acc: 0.8129 - va
Epoch 2/20
Epoch 3/20
Epoch 4/20
60000/60000 [=============== ] - 5s 88us/step - loss: 0.1724 - acc: 0.9514 - val
Epoch 5/20
60000/60000 [============== ] - 5s 87us/step - loss: 0.1530 - acc: 0.9574 - val
Epoch 6/20
Epoch 7/20
Epoch 8/20
60000/60000 [=============== ] - 5s 87us/step - loss: 0.1153 - acc: 0.9673 - val
Epoch 9/20
60000/60000 [============== ] - 5s 87us/step - loss: 0.1118 - acc: 0.9674 - val
Epoch 10/20
Epoch 11/20
Epoch 12/20
Epoch 13/20
Epoch 14/20
Epoch 15/20
Epoch 16/20
Epoch 17/20
60000/60000 [=============== ] - 5s 87us/step - loss: 0.0745 - acc: 0.9775 - val
Epoch 18/20
Epoch 19/20
Epoch 20/20
60000/60000 [============== ] - 5s 90us/step - loss: 0.0672 - acc: 0.9801 - val
```

Test score: 0.06557027021200047





## 3.3 Model 3 (5-layered MLP Architecture):

### 3.3.1 Plot Weights: Common Function

```
In [75]: def plotWeightM3(model):
             w_after = model.get_weights()
             h1_w = w_after[0].flatten().reshape(-1,1)
             h2_w = w_after[2].flatten().reshape(-1,1)
             h3_w = w_after[4].flatten().reshape(-1,1)
             h4_w = w_after[6].flatten().reshape(-1,1)
             h5_w = w_after[8].flatten().reshape(-1,1)
             out_w = w_after[10].flatten().reshape(-1,1)
             fig = plt.figure()
             plt.title("Weight matrices after model trained")
             plt.subplot(1, 6, 1)
             plt.title("Weights")
             ax = sns.violinplot(y=h1_w,color='b')
             plt.xlabel('Hidden 1')
             plt.subplot(1, 6, 2)
             plt.title("Weights")
             ax = sns.violinplot(y=h2_w, color='r')
             plt.xlabel('Hidden 2 ')
             plt.subplot(1, 6, 3)
             plt.title("Weights")
             ax = sns.violinplot(y=h3_w, color='g')
             plt.xlabel('Hidden 3 ')
             plt.subplot(1, 6, 4)
             plt.title("Weights")
             ax = sns.violinplot(y=h4_w, color='c')
             plt.xlabel('Hidden 4 ')
             plt.subplot(1, 6, 5)
             plt.title("Weights")
             ax = sns.violinplot(y=h5_w, color='m')
             plt.xlabel('Hidden 5 ')
             plt.subplot(1, 6, 6)
             plt.title("Weights")
             ax = sns.violinplot(y=out_w,color='y')
```

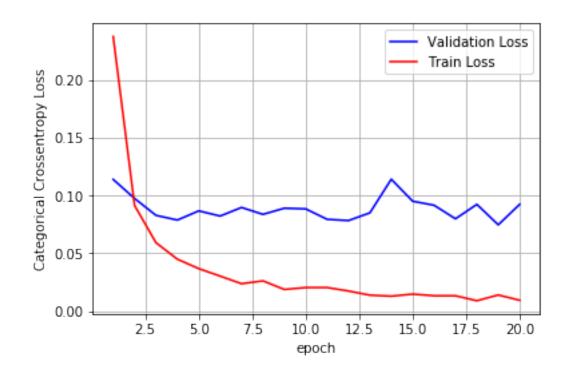
```
plt.xlabel('Out Layer')
plt.show()
```

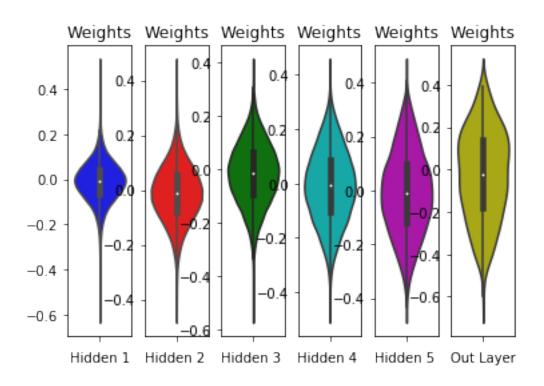
#### 3.3.2 Input(784)-ReLu(512)-ReLu(256)-ReLu(144)-ReLu(96)-ReLu(36)-Softmax(output)

```
In [76]: model_relu = Sequential()
     model_relu.add(Dense(512, activation='relu',
                input_shape=(input_dim,), kernel_initializer='he_normal'))
     model_relu.add(Dense(256, activation='relu', kernel_initializer='he_normal'))
     model_relu.add(Dense(144, activation='relu', kernel_initializer='he_normal'))
     model_relu.add(Dense(96, activation='relu', kernel_initializer='he_normal'))
     model_relu.add(Dense(36, activation='relu', kernel_initializer='he_normal'))
     model_relu.add(Dense(output_dim, activation='softmax'))
     print(model_relu.summary())
     history = trainModel(model=model_relu)
     plotGraph(model=model_relu, history=history)
     plotWeightM3(model=model_relu)
Layer (type)
               Output Shape
                                   Param #
dense_100 (Dense)
                   (None, 512)
                                    401920
dense_101 (Dense) (None, 256)
                                    131328
dense_102 (Dense) (None, 144)
                                    37008
dense_103 (Dense)
              (None, 96)
                                    13920
dense_104 (Dense)
                  (None, 36)
                                    3492
-----
dense_105 (Dense) (None, 10)
______
Total params: 588,038
Trainable params: 588,038
Non-trainable params: 0
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
Epoch 2/20
Epoch 3/20
```

Epoch 4/20

```
Epoch 5/20
60000/60000 [============== ] - 5s 86us/step - loss: 0.0368 - acc: 0.9880 - val
Epoch 6/20
60000/60000 [============== ] - 5s 76us/step - loss: 0.0303 - acc: 0.9900 - val
Epoch 7/20
Epoch 8/20
60000/60000 [=============== ] - 5s 78us/step - loss: 0.0262 - acc: 0.9919 - val
Epoch 9/20
Epoch 10/20
Epoch 11/20
Epoch 12/20
Epoch 13/20
Epoch 14/20
Epoch 15/20
Epoch 16/20
Epoch 17/20
Epoch 18/20
Epoch 19/20
Epoch 20/20
60000/60000 [============== ] - 5s 78us/step - loss: 0.0094 - acc: 0.9972 - val
Test score: 0.09236639852523267
```



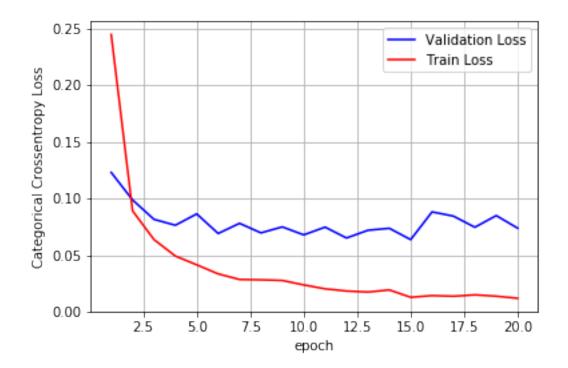


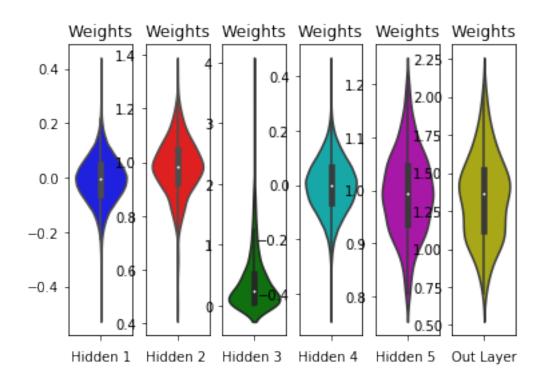
#### 3.3.3 Model 3: M3 + Batch-Normalization on 5 hidden Layers

```
In [77]: # Multilayer perceptron
         # https://intoli.com/blog/neural-network-initialization/
         # If we sample weights from a normal distribution N(0,) we satisfy this condition wit
         \# h1 \Rightarrow =(2/(ni+ni+1) = 0.039 \Rightarrow N(0,) = N(0,0.039)
         \# h2 \Rightarrow =(2/(ni+ni+1) = 0.055 \Rightarrow N(0,) = N(0,0.055)
         # h1 \Rightarrow =(2/(ni+ni+1) = 0.120 \Rightarrow N(0,) = N(0,0.120)
        from keras.layers.normalization import BatchNormalization
        model_batch = Sequential()
        model_batch.add(Dense(512, activation='relu',
                             input_shape=(input_dim,), kernel_initializer='he_normal'))
        model_batch.add(BatchNormalization())
        model_batch.add(Dense(256, activation='relu', kernel_initializer='he_normal'))
        model_batch.add(BatchNormalization())
        model_batch.add(Dense(144, activation='relu', kernel_initializer='he_normal'))
        model_batch.add(BatchNormalization())
        model_batch.add(Dense(96, activation='relu', kernel_initializer='he_normal'))
        model_batch.add(BatchNormalization())
        model_batch.add(Dense(36, activation='relu', kernel_initializer='he_normal'))
        model_batch.add(BatchNormalization())
        model_batch.add(Dense(output_dim, activation='softmax'))
        model_batch.summary()
        history = trainModel(model=model_batch)
        plotGraph(model=model_batch, history=history)
        plotWeightM3(model=model batch)
Layer (type)
                            Output Shape
                                                      Param #
______
dense_106 (Dense)
                           (None, 512)
                                                      401920
batch_normalization_51 (Batc (None, 512)
                                                      2048
dense 107 (Dense)
                           (None, 256)
                                                     131328
batch_normalization_52 (Batc (None, 256)
                                                     1024
```

```
(None, 144)
dense_108 (Dense)
                     37008
batch_normalization_53 (Batc (None, 144)
                     576
          (None, 96)
dense 109 (Dense)
                     13920
batch_normalization_54 (Batc (None, 96)
                     384
-----
dense_110 (Dense)
        (None, 36)
                     3492
batch_normalization_55 (Batc (None, 36)
                     144
dense 111 (Dense)
       (None, 10)
                     370
______
Total params: 592,214
Trainable params: 590,126
Non-trainable params: 2,088
Train on 60000 samples, validate on 10000 samples
Epoch 1/20
Epoch 2/20
60000/60000 [=============== ] - 6s 98us/step - loss: 0.0890 - acc: 0.9734 - val
Epoch 3/20
60000/60000 [============== ] - 6s 97us/step - loss: 0.0637 - acc: 0.9801 - val
Epoch 4/20
Epoch 5/20
Epoch 6/20
Epoch 7/20
Epoch 8/20
Epoch 9/20
Epoch 10/20
Epoch 11/20
60000/60000 [============== ] - 6s 98us/step - loss: 0.0202 - acc: 0.9936 - val
Epoch 12/20
Epoch 13/20
Epoch 14/20
```

Test score: 0.07374950621149037





#### 3.3.4 Model 3: M3 + Batch-Normalization + Dropout

 $\label{eq:com_questions} \textbf{In [78]: } \# \ https://stackoverflow.com/questions/34716454/where-do-i-call-the-batchnormalization and the statement of the state$ 

```
model_drop.add(Dense(36, activation='relu', kernel_initializer='he_normal'))
model_drop.add(BatchNormalization())
model_drop.add(Dropout(0.5))

model_drop.add(Dense(output_dim, activation='softmax'))

model_drop.summary()

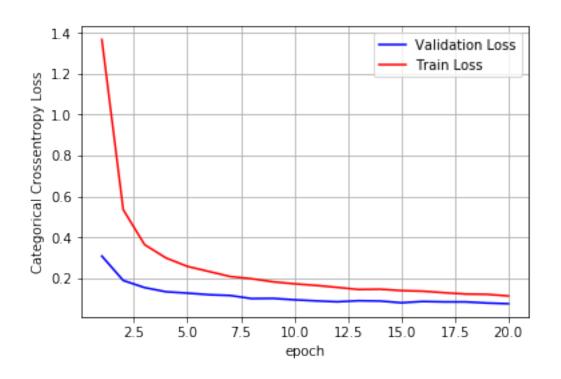
history = trainModel(model=model_drop)
plotGraph(model=model_drop, history=history)
plotWeightM3(model=model_drop)
```

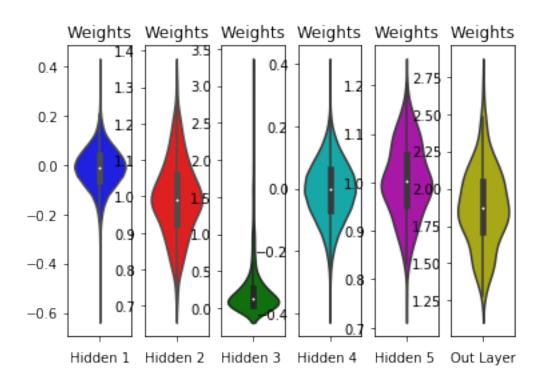
Layer (type)	Output	Shape	Param #
dense_112 (Dense)	(None,	512)	401920
batch_normalization_56 (I	Batc (None,	512)	2048
dropout_26 (Dropout)	(None,	512)	0
dense_113 (Dense)	(None,	256)	131328
batch_normalization_57 (F	Batc (None,	256)	1024
dropout_27 (Dropout)	(None,	256)	0
dense_114 (Dense)	(None,	144)	37008
batch_normalization_58 (F	Batc (None,	144)	576
dropout_28 (Dropout)	(None,	144)	0
dense_115 (Dense)	(None,	96)	13920
batch_normalization_59 (F	Batc (None,	96)	384
dropout_29 (Dropout)	(None,	96)	0
dense_116 (Dense)	(None,	36)	3492
batch_normalization_60 (F	Batc (None,	36)	144
dropout_30 (Dropout)	(None,	36)	0
dense_117 (Dense)	(None,	10)	370

Total params: 592,214 Trainable params: 590,126 Non-trainable params: 2,088

Test accuracy: 0.9814

Train on 60000 samples, validate on 10000 samples Epoch 1/20 Epoch 2/20 Epoch 3/20 Epoch 4/20 Epoch 5/20 60000/60000 [============== ] - 7s 109us/step - loss: 0.2589 - acc: 0.9363 - va Epoch 6/20 Epoch 7/20 Epoch 8/20 Epoch 9/20 Epoch 10/20 Epoch 11/20 Epoch 12/20 Epoch 13/20 Epoch 14/20 60000/60000 [============== ] - 6s 107us/step - loss: 0.1475 - acc: 0.9655 - va Epoch 15/20 Epoch 16/20 Epoch 17/20 Epoch 18/20 Epoch 19/20 Epoch 20/20 Test score: 0.0764596716644708





## 4 Summary Statistics

Model	Total Parameters	Accuracy	Loss vs Epoch Plot
Model 1 (784x512x128x10)	468,874	98.18	Diverging
M1 + Batch-Normalization	471,434	98.06	Diverging
M1 + Batch-Normalization+Dropout	471,434	98.32	Converging
Model 2 (784x512x256x64x10)	550,346	97.85	Diverging
M2 + Batch-Normalization	553,674	98.06	Diverging
M2 + Batch-Normalization+Dropout	553,674	98.24	Converging
Model 3 (784x512x256x144x96x10)	588,038	97.96	Diverging
M3 + Batch-Normalization	592,214	97.88	Diverging
M3+Batch-Normalization+Dropout	592,214	98.26	Converging

## 5 Conclusions

- 1. The **difference in accuracy between 2, 3 & 5 layered networks is very small**. This could be due to the simplicity and small size of input data.
- 2. The 'cross entropy loss vs epoch' plot for train and test data is found diverging, when the dropout layer is not added. This means reduction in training loss but increase in test loss at the same time, indicative of overfitting.
- 3. Thus, addition of dropout layer is found as a good regularization in practice.
- 4. The accuracy is also more when Batch Normalization and dropout layers are added.
- 5. All distributions of trained weights along all the layers are expectedly found as Gaussian curves.
- 6. For MNIST problem, model M1 coupled with Batch Normalizaton and Dropout seems to be the best bet.