

# Priority Queues

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## Introduction

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In this lab, we are going to write Python code that simulates events in an operating system. To this end you will write different implementations for the priority queue ADT. In particular, you will implement priority queue using list, BST, and balanced BST.

## Objectives

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The purpose of this lab is to help you:

1. Gain further familiarity with class inheritance
2. Understand the priority queue ADT
3. Learn about different implementations of priority queue
4. Understand Balanced BST

## Events in an operating system

Event is an action or occurrence recognized by software. Events often are generated asynchronously and may be handled by the system. They are added to a queue of unprocessed events and handled in order of their priority. These events will be handled by pulling them from this queue of events.

The purpose of this lab is to simulate events in an operating system. Every event is an entity that has a timestamp, rank, and maybe some other data. A timestamp is a number generated by a global clock ( `Simulator.clock` ) that will be incremented by 1 for every add/delete operation of the queue.

Events will be handled not according to their insertion time but rather according to their priority. Priority is defined as follows:

- Events with lower rank have higher priority.
- If two events have the same rank, then the event with smaller (earlier) timestamp will have higher priority.

We have provided you with a simulator for simulating the events, creation and their handling. It is an object that continuously either creates an event and adds an event to a queue or removes an event from a queue. This simulator will run in a loop and randomly decide what to

do. The user can either interrupt it or pre-specify the number of loop iterations before the simulator stops.

## Accompanied code

This lab includes the following classes:

`PQ` represents the abstract methods of priority queue. These methods are needed in every implementation that you choose. We have provided you with the code for this.

`ListPQ` is class that represents a `PQ` implemented using Python list. This class inherits from `PQ` all abstract methods. We have provided you with the code for this, too.

`BST` is a class that represents a different implementation for priority queue. It also inherits from `PQ`, and all of the `PQ NotImplemented` methods MUST be implemented for it.

`BalancedBST` is a subclass of `BST` that overwrites `BST`'s `add` method to keep the tree balanced. You are required to implement it.

`TreeNode` represents a node in a `BST` or `BalancedBST`.

`Simulator` is a class that simulates the creation and handling of the events in the system. It is initialized with a priority queue (either `ListPQ`, `BST`, or `BalancedBST`) so as to add/remove event to/from it. It also has methods to make it QUIET or keep it LOUD (where it prints out for you what's going on). It also outputs a log of events, which can be used as an alternate way of running the simulator. By using the same log for two different simulator runs (with different `PQ` implementations), you can make sure that they work the same way.

## Part 1 (in-lab) The event simulator

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We have provided you with the `ListPQ` implementation and the `Simulator`. You should be able to do the following with them:

```
x = List() # we can also do BST or BalancedBST here
x.add(5)
x.add(9)
x.add(11)
x.add(10)
x.add(3)
x.add(4)
x.draw()
# len(x) should be 6, highest priority is 3
print("This ListPQ has", len(x), "items, highest priority is", x.peekMin())
y = x.getMin()
```

```

print("Removed", y, "here is what's left")
x.draw()

s = Simulator(ListPQ()) # interactive simulator with ListPQ impl
s1.setLimit(17) # will stop after processing 17 events
log1 = s1.run()

s2 = Simulator(List(), False) # the second argument makes it quiet
s2.useLog(log1) # this will run from log
log2 = s2.run() # log1 and log2 should be identical
print("Total add time:", s2.addTime, "; Total get time:", s2.getTime)

```

Please try this code, and variations that you think of yourself. Also, study the implementations to understand what's going on.

Note that we've included timing in our simulator. It's printed on the last line above. It will come in useful later.

In the given implementations, event is represented by a tuple of two elements: (rank, timestamp). To find the event with the highest priority we need find the one with the lowest rank. If there are two or more events with the same lowest rank we need to find the one with the lowest timestamp.

In the accompanied code we call the `priority` function for every event and compare priorities. In this part you are required to implement the `priority` function.

## Part 2 - Implementing BST add method

Another implementation for priority queue ADT is `BST`. You are given the following `BST` partial definition where a `BST` class inherits from `PQ` base class. This definition includes the magic method `__init__` that initializes new `BST` objects where `self.root` points to the tree root and `self.size` represents the number of events that have been added to the tree so far. Notice that every node in the `BST` is an object of type `TreeNode` class which is also given to you.

In this part you are required to write the `add` method of the `BST` class. In particular you have to implement/override all inherited methods from the `PQ` class that raise the `NotImplemented` exception.

Afterwards, the following code should work:

```

x = BST()
x.add(5)

```

```

x.add(9)
x.add(11)
x.add(10)
x.add(3)
x.add(4)
x.draw()
# len(x) should be 6, highest priority is 3
print("This ListPQ has", len(x), "items, highest priority is", x.peekMin())

```

Note that if the same elements are added to the list in a different order, the tree will look differently. Try it! Depending on the order in which the elements were added, the height of the `BST` can either be  $O(\log n)$  or  $O(n)$ . This is an important point, because it means that we cannot count on the `BST` to give us  $O(\log n)$  performance for `add` or `peekMin` or `getMin`. Balancing is needed to fix this problem, which we will do in part 4 of the lab.

## Debugging tips

To help you debug here and in later parts, we suggest that you use the Simulator's capability to run from a log. It allows you to compare the behavior of your `BST` with that of `ListPQ`, over the same run of events. Also, we have provided `draw` methods for both of `BST` and `PQ` you can call for debugging purposes. Feel free to change them if it helps you.

## Part 3: - Implementing `BST` `getMin` method

Now implement `getMin` to complete the `BST` implementation. This method should remove the node that we find with `peekMin`, obtaining a `BST` with one less item.

After this, all the code that you see at the end of part 1 should work for `BST`s - meaning, if you replace `ListPQ()` by `BST()` - including the use of the Simulator. For example, this will work:

```

s1 = Simulator(BST()) # interactive simulator with BalancedBST impl
s1.setLimit(17) # will stop after processing 17 events
s1.run()

s = Simulator(List(), False) # this will be a long run, don't want it loud
s.setLimit(10000) # will stop after processing 10000 events
log = s.run()

s2 = Simulator(List(), False)
s2.useLog(log) # this will run from log
log1 = s2.run() # log and log1 should be identical
print("Total add time:", s2.addTime, "; Total get time:", s2.getTime)

s3 = Simulator(BST(), False)
s3.useLog(log) # this will run from log

```

```
log1 = s3.run() # log and log1 should be identical  
print("Total add time:", s3.addTime, "; Total get time:", s3.getTime)
```