## Fall 2019 - ECON 634 - Advance Macroeconomics - Problem Set 2

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- 1. Since the Resource constraint (Social Planner Problem) is  $c_t = A_t k_t^{\alpha} + (1-\delta)k_t k_{t+1}$  we can write the budget constraint in recursive form as  $c = Ak^{\alpha} + (1-\delta)k k'$ 
  - State variable: k, A
  - Control variable: k'

Therefore, the Bellman equation:

$$V(k,A) = \max_{k'} \left\{ \frac{(Ak^{\alpha} + (1-\delta)k - k')^{1-\sigma}}{1-\sigma} + \beta \sum_{A' \in A} \Pi(A'|A)V(k',A') \right\}$$

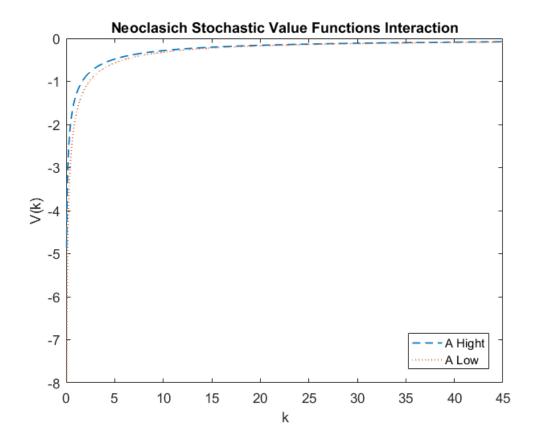
subject to

$$c \in [0, f(k)] \tag{1}$$

$$k' \in [0, f(k)] \tag{2}$$

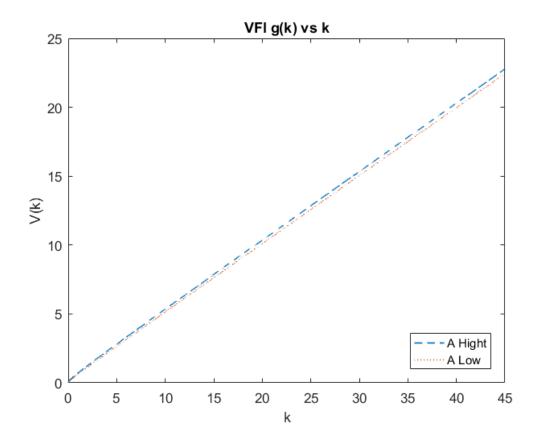
2. Using the VFI, the Graphs are like follows:

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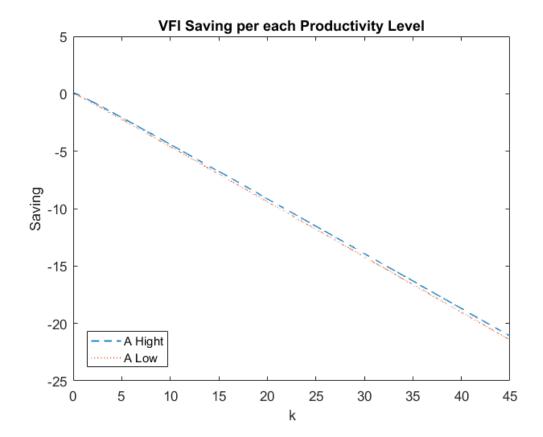
As we can see, both are increasing and concave functions.

3. The Policy function over k looks as follows:



This relationship is decreasing in k but increasing in A.

Assuming that by saving, it means what is left from production after consumption:  $s = k' - (1 - \delta)k$ , the Saving over k looks as follows:



where this relationship is decreasing in k and increasing in A. This make sense because

4. For this, I will use the code for the part (5), since it seems more reasonable results. Using the results, I get a sd(y) = 0.1755, which does not match the results from the data.

Ideally, I should do a while loop and try for a low tolerance between my simulated standard deviation and the actual standard deviation. Because the code **VFIP5** is so slow, I decide against it and just try randomly picking numbers for the High value different to  $A_h = 1.1$  and backing out the  $A_l$  values.

Doing the markov change process to find stationary probabilities:

$$\begin{pmatrix} \bar{\pi}_h & \bar{\pi}_l \end{pmatrix} = \begin{pmatrix} \bar{\pi}_h & \bar{\pi}_l \end{pmatrix} P$$

This means

Therefore,

$$\bar{\pi}_h = 3.22\bar{\pi}_l \tag{3}$$

$$\bar{\pi}_l = 0.31\bar{\pi}_h \tag{4}$$

Since  $\bar{\pi}_h + \bar{\pi}_l = 1$ 

$$4.22\bar{\pi}_l = 1\tag{5}$$

$$\bar{\pi}_l = 0.24 \tag{6}$$

$$\bar{\pi}_h = 0.76 \tag{7}$$

Therefore, I will try first,  $A_h = 1.05$ , which implies sung the Long-run probabilities  $A_l = \frac{1 - \bar{\pi}_h A_h}{\bar{\pi}_l} = 0.839$ . With this results, the standard deviation is sd(y) = 0.1445, which means I need to keep trying for a smaller value of  $A_h$ .

- Using  $A_h = 1.0003$ ,  $A_l = 0.99903$ , then sd(y) = 0.1310
- Using  $A_h = 1.00001$ ,  $A_l = 0.9999678$ , then sd(y) = 0.1310
- Using  $A_h = 1.0000001$ ,  $A_l = 0.9999997$ , then sd(y) = 0.0.1310
- Using  $A_h = 1.000000000001$ ,  $A_l = 0.999999999999967820$ , then sd(y) = 0.1143

Obviously, this compare with the information we saw in class, the numbers are different and quite high and very difficult to find the standard deviation that I want. So, I further do the changed with the previous way. However, my results are definitely very small standard deviation, actually very close to the optimal one.

5. See Code **VFIP5**. Using two loops over all K is quite slow and does spend a long time to find a solution.

The time on the previous program Elapsed time is 0.326278 seconds. For the second one, limiting to the Elapsed time is 1049.453223 seconds. Therefore, time is significantly higher for this one.

Since, to me, this second version is correct, but I get differents results, I will add the graphs for this. The results for the VFI is:

