Lecture 09—Race Conditions; More Synchronization

January 23, 2015

Roadmap

Last Time: Race Conditions, Locking (mutexes)

Now: More Synchronization Mechanisms

Part I

More Synchronization

Mutexes Recap

Our focus is on how to use mutexes correctly:

- Call lock on mutex m1. Upon return from lock, you have exclusive access to m1 until you unlock it.
- Other calls to lock m1 will not return until m1 is available.

For background on selection algorithms, look at Lamport's bakery algorithm.

(Not in scope for this course.)

More on Mutexes

Can also "try-lock": grab lock if available, else return to caller (and do something else).

Excessive use of locks can serialize programs.

- Linux kernel used to rely on a Big Kernel Lock protecting lots of resources in the 2.0 era.
- Linux 2.2 improved performance on SMPs by cutting down on the use of the BKL.

Note: in Windows, "mutex" is an inter-process communication mechanism. Windows "critical sections" are our mutexes.

Spinlocks

Functionally equivalent to mutex.

 pthread_spinlock_t, pthread_spin_lock, pthread_spin_trylock and friends

Implementation difference: spinlocks will repeatedly try the lock and will not put the thread to sleep.

Good if your protected code is short.

Mutexes may be implemented as a combination between spinning and sleeping (spin for a short time, then sleep).

Read-Write Locks

Two observations:

- If there are only reads, there's no datarace.
- Often, writes are relatively rare.

With mutexes/spinlocks, you have to lock the data, even for a read, since a write could happen.

But, most of the time, reads can happen in parallel, as long as there's no write.

Solution: Multiple threads can hold a read lock (pthread_rwlock_rdlock)

grabbing the write waits until current readers are done.

Semaphores

Semaphores have a value. You specify initial value.

Semaphores allow sharing of a # of instances of a resource.

Two fundamental operations: wait and post.

- wait is like lock; reserves the resource and decrements the value.
 - ▶ If value is 0, sleep until value is greater than 0.
- post is like unlock; releases the resource and increments the value.

Barriers

Allows you to ensure that (some subset of) a collection of threads all reach the barrier before finishing.

Pthreads: A barrier is a pthread_barrier_t.

Functions: _init() (parameter: how many threads the barrier should wait for) and _destroy().

Also _wait(): similar to pthread_join(), but waits for the specified number of threads to arrive at the barrier

Lock-Free Algorithms

We'll talk more about this in a few weeks.

Modern CPUs support atomic operations, such as compare-and-swap, which enable experts to write lock-free code.

Lock-free implementations are extremely complicated and must still contain certain synchronization constructs.

Semaphores Usage

```
#include <semaphore.h>
int sem_init(sem_t *sem, int pshared, unsigned int value);
int sem_destroy(sem_t *sem);
int sem_post(sem_t *sem);
int sem_wait(sem_t *sem);
int sem_trywait(sem_t *sem);
```

- Also must link with -pthread (or -lrt on Solaris).
- All functions return 0 on success.
- Same usage as mutexes in terms of passing pointers.

How could you use as semaphore as a mutex?

Semaphores Usage

```
#include <semaphore.h>
int sem_init(sem_t *sem, int pshared, unsigned int value);
int sem_destroy(sem_t *sem);
int sem_post(sem_t *sem);
int sem_wait(sem_t *sem);
int sem_trywait(sem_t *sem);
```

- Also must link with -pthread (or -lrt on Solaris).
- All functions return 0 on success.
- Same usage as mutexes in terms of passing pointers.

How could you use as semaphore as a mutex?

 If the initial value is 1 and you use wait to lock and post to unlock, it's equivalent to a mutex.

Here's an example from the book. How would you make this always print "Thread 1" then "Thread 2" using semaphores?

```
#include <pthread.h>
#include <stdio.h>
#include <semaphore.h>
#include <stdlib.h>
void* p1 (void* arg) { printf("Thread 1\n"); }
void* p2 (void* arg) { printf("Thread 2\n"); }
int main(int argc, char *argv[])
{
    pthread_t thread[2];
    pthread_create(&thread[0], NULL, p1, NULL);
    pthread_create(&thread[1], NULL, p2, NULL);
    pthread_join(thread[0], NULL);
    pthread_join(thread[1], NULL);
    return EXIT_SUCCESS;
```

Here's their solution. Is it actually correct?

```
sem_t sem:
void* p1 (void* arg) {
  printf("Thread 1\n");
  sem_post(&sem);
void* p2 (void* arg) {
  sem_wait(&sem);
  printf("Thread 2\n");
int main(int argc, char *argv[])
{
    pthread_t thread[2];
    sem_init(\&sem, 0, /* value: */ 1);
    pthread_create(&thread[0], NULL, p1, NULL);
    pthread_create(&thread[1], NULL, p2, NULL);
    pthread_join(thread[0], NULL);
    pthread_join(thread[1], NULL);
    sem_destroy(&sem);
```

- value is initially 1.
- Say p2 hits its sem_wait first and succeeds.
- value is now 0 and p2 prints "Thread 2" first.
 - If p1 happens first, it would just increase value to 2.

- value is initially 1.
- Say p2 hits its sem_wait first and succeeds.
- value is now 0 and p2 prints "Thread 2" first.
 - If p1 happens first, it would just increase value to 2.
 - Fix: set the initial value to 0.

Then, if p2 hits its sem_wait first, it will not print until p1 posts (and prints "Thread 1") first.

volatile Keyword

 Used to notify the compiler that the variable may be changed by "external forces". For instance,

```
int i = 0;
while (i != 255) {
...
```

volatile prevents this from being optimized to:

```
int i = 0;
while (true) {
    ...
```

- Variable will not actually be volatile in the critical section and only prevents useful optimizations.
- Usually wrong unless there is a **very** good reason for it.

C++ atomics

Coming soon. Short version: wrap the type in atomic, e.g. atomic<int> x;