

Software Testing, Quality Assurance & Maintenance—Lecture 14

Patrick Lam

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Last Time

MAY-beliefs versus MUST-beliefs

Cross-checking beliefs

Today

Inferring beliefs via statistics
Linters

Part I

Inferring beliefs

Redundancy Checking

Assumption: code ought to do something

Look for identity operations, e.g.

$x = x, 1 * y, x \& x, x | x.$

```
/* 2.4.5-ac8/net/appletalk/aarp.c */  
da.s_node = sa.s_node;  
da.s_net = da.s_net;
```

Also look for unread writes:

```
for (entry=priv->lec_arp_tables[i];  
      entry != NULL; entry=next) {  
    next = entry->next; // never read!  
    ...  
}
```

Redundancy suggests conceptual confusion.

(examples courtesy Dawson Engler)

From MUST to MAY

Preceding examples were about MUST beliefs:
violations were clearly wrong.

Let's examine MAY beliefs next:

- need more evidence of wrongdoing.

Verifying MAY beliefs

- 1 Record every successful MAY-belief check as “check”.
- 2 Record every unsuccessful belief check as “error”.
- 3 Rank errors based on “check” : “error” ratio.

Most likely errors: “check” is large, “error” small.

Let's find some MAY beliefs

use-after-free:

```
free(p) ;  
print(*p) ;
```

That is a MUST-belief.

However, other resources are freed by custom (undocumented) free functions.

Let's derive them behaviourally.

Finding custom free functions

Key idea:

If pointer p not used after calling $f_{\text{oo}}(p)$,
then derive a MAY belief that $f_{\text{oo}}(p)$ frees p .

Just assume all functions free all arguments.

- emit “check” at every call site;
- emit “error” at every use.

(in reality, filter functions with suggestive names).

Example: finding free functions

Putting that into practice,
we might observe:

foo(p)	foo(p)	foo(p)	bar(p)	bar(p)	bar(p)
*p = x;	*p = x;	*p = x;	p = 0;	p=0;	*p = x;

Rank `bar`'s error first.

Sample results: 23 free errors, 11 false positives.

More statistical techniques: nullness checks

Situation:

Want to know which routines may return `NULL`.

Possible solution: static analysis to find out.

Problems:

- difficult to know statically (“`return p->next;`”?)
- get false positives:
functions return `NULL` under special cases only.

Applying a statistical technique to nullness checks

Instead: let's observe what the programmer does.
Again, rank errors based on checks vs non-checks.

Just assume **all** functions can return `NULL`.

- pointer checked before use: emit “check”;
- pointer used before check: emit “error”.

Example: finding NULL-returning functions

This time, we might observe:

<code>p = bar(...);</code> <code>*p = x;</code>		<code>p = bar(...);</code> <code>if (!p) return;</code> <code>*p = x;</code>		<code>p = bar(...);</code> <code>if (!p) return;</code> <code>*p = x;</code>		<code>p = bar(...);</code> <code>if (!p) return;</code> <code>*p = x;</code>
--	--	--	--	--	--	--

Sort errors based on “check”：“error” ratio.

Sample results: 152 free errors, 16 false positives.

General statistical technique

“a(); ... b();” implies MAY-belief that a() followed by b().
(is it real or fantasy? we don't know!)

Algorithm:

- assume every $a-b$ is a valid pair;
- emit “check” for each path with “a()” and then “b()”;
- emit “error” for each path with “a()” and no “b()”.

(actually, prefilter functions that look paired).

Example: general technique

Consider:

```
foo(p, ...);  
bar(p, ...); // check
```

```
foo(p, ...);  
bar(p, ...); // check
```

```
foo(p, ...);  
// error: foo, no bar!
```

Application: course project

```
void scope1() {  
    A(); B(); C(); D();  
}
```

“A() and B() must be paired”:
either A() then B() or B() then A().

```
void scope2() {  
    A(); C(); D();  
}
```

```
void scope3() {  
    A(); B();  
}
```

Support = # times a pair of functions
appears together.

```
void scope4() {  
    B(); D(); scope1();  
}
```

$\text{support}(\{A,B\})=3$

```
void scope5() {  
    B(); D(); A();  
}
```

Confidence($\{A,B\},\{A\}$) =
 $\text{support}(\{A,B\})/\text{support}(\{A\}) = 3/4$

```
void scope6() {  
    B(); D();  
}
```


Application: course project

```
void scope1() {  
    A(); B(); C(); D();  
}
```

```
void scope2() {  
    A(); C(); D();  
}
```

```
void scope3() {  
    A(); B();  
}
```

```
void scope4() {  
    B(); D(); scope1();  
}
```

```
void scope5() {  
    B(); D(); A();  
}
```

```
void scope6() {  
    B(); D();  
}
```

Sample output for support threshold 3, confidence threshold 65% (intra-procedural analysis):

- bug:A in scope2, pair: (A B), support: 3, confidence: 75.00%
- bug:A in scope3, pair: (A D), support: 3, confidence: 75.00%
- bug:B in scope3, pair: (B D), support: 4, confidence: 80.00%
- bug:D in scope2, pair: (B D), support: 4, confidence: 80.00%

Why are we doing this again?

```
/* 2.4.0: drivers/sound/cmpci.c:cm_midi_release: */
lock_kernel(); // [PL: GRAB THE LOCK]
if (file->f_mode & FMODE_WRITE) {
    add_wait_queue(&s->midi.owait, &wait);
    ...
    if (file->f_flags & O_NONBLOCK) {
        remove_wait_queue(&s->midi.owait, &wait);
        set_current_state(TASK_RUNNING);
        return -EBUSY; // [PL: OH NOES!!1]
    }
    ...
}
unlock_kernel();
```

Problem: lock() and unlock() must be paired!

Summary: Belief Analysis

We don't know what the right spec is.
Instead, look for contradictions.

MUST-beliefs: contradictions = errors!

MAY-beliefs: pretend they're MUST, rank by confidence.

(Key assumption: most of the code is correct.)

Further references

Dawson R. Engler, David Yu Chen, Seth Hallem, Andy Chou and Benjamin Chelf.

“Bugs as Deviant Behaviors: A general approach to inferring errors in systems code”.

In SOSP '01.

Dawson R. Engler, Benjamin Chelf, Andy Chou, and Seth Hallem.

“Checking system rules using system-specific, programmer-written compiler extensions”.

In OSDI '00 (best paper).

www.stanford.edu/~engler/mc-osdi.pdf

Junfeng Yang, Can Sar and Dawson Engler.

“eXplode: a Lightweight, General system for Finding Serious Storage System Errors”.

In OSDI'06.

www.stanford.edu/~engler/explode-osdi06.pdf

Part II

Using Linters

source: `jamie-wong.com/2015/02/02/linters-as-invariants/`

First there was C

Statically-typed languages like C:

```
#include <stdio.h>
```

```
int main() {  
    printf("%d\n", num);  
    return 0;  
}
```

Compiler saves you from yourself.

Guaranteed invariant:

“if code compiles, all symbols resolve”.

Less-nice languages

OK, so you try to run that in JavaScript and it crashes right away.

Invariant:

“if code runs, all symbols resolve”?

Counterexample

But what about this:

```
function main(x) {  
  if (x) {  
    console.log("Yay");  
  } else {  
    console.log(num);  
  }  
}
```

```
main(true);
```

Nope!

Still no invariants

Invariant:

“if code runs without crashing, all symbols referenced in the code path executed resolve”?

Nope

```
function main() {  
  try {  
    console.log(num);  
  } catch (err) {  
    console.log("nothing to see here");  
  }  
}  
  
main();
```

JavaScriptWorld Problems

When maintaining old code:

- is this variable defined?
- is this variable always defined?
- do I need to load a script to define that variable?

Why is this the developer's problem?

Solution: Linters

```
plam@banach ~> cat foo.js
```

```
function main(x) {  
  if (x) {  
    console.log("Yay");  
  } else {  
    console.log(num);  
  }  
}
```

```
main(true);
```

```
plam@banach ~> nodejs /usr/local/lib/node_modules/  
  jshint/bin/jshint --config jshintrc foo.js  
foo.js: line 5, col 17, 'num' is not defined.
```

```
1 error
```

Invariant

“If code passes JSHint, all top-level symbols resolve.”

Strengthening the Invariant

Add a pre-commit hook.

“If code is checked-in and commit hook ran,
all top-level symbols resolve.”

Better yet...

Block deploys on test failures.

“If code is deployed,
all top-level symbols resolve.”

Even better yet...

Hard to tell if code is deployed or not.

Use git feature branches, merge when deployed.

“If code is in master,
all top-level symbols resolve.”