

3.1. perception cost function: $J(w) = \sum_{x \in Y} \delta_x w^T x$

where Y is the set of all misclassified input vectors. We know that $J(w)$ is piecewise linear because for values of w where the set Y is not affected we have:

$$J(w) = \sum_{x \in Y} \delta_x w^T x = w^T \left(\sum_{x \in Y} \delta_x x \right) = w^T a = a^T w$$

$\xrightarrow{\text{linear}}$
 both a and w are vectors

But if we change the value of w smoothly at a certain threshold (w_t), the set Y of misclassified examples changes. New examples may enter the set while old examples may be exited. Let's call this new set Y' and $Y \cap Y' = A$ and $Y' - Y = B$ and $Y - Y' = C$. We have:

$$J_Y(w) = \sum_{x \in A} \delta_x w^T x + \sum_{x \in C} \delta_x w^T x$$

$$J_{Y'}(w) = \sum_{x \in A} \delta_x w^T x + \sum_{x \in B} \delta_x w^T x$$

Here's what we need to note here: when we approach w_t the original set Y is about to be altered into Y' . However, for every example that enters or leaves Y (i.e. sets B and C), the value of $w^T x$ must pass through zero because the sign of $w^T x$ for those examples must be flipped in order for them to enter or leave set Y . This change in sign occurs exactly at w_t therefore we have: (assuming we're increasing the value of w)

$$\lim_{w \rightarrow w_t^+} J(w) = \lim_{w \rightarrow w_t^+} J_Y(w) = \lim_{w \rightarrow w_t^+} \left[\sum_{x \in A} \delta_x w^T x + \sum_{x \in C} \delta_x w^T x \right]$$

$$= \sum_{x \in A} \delta_x w_t^T x + \lim_{w \rightarrow w_t^+} \sum_{x \in C} \delta_x w^T x = \lim_{w \rightarrow w_t^+} J(w)$$

with the same exact reasoning

$\Rightarrow J(w)$ is continuous

3.4. Reward and Punishment Perceptron Algorithm:

$$\begin{cases} w_{t+1} = w_t + \rho x_t, & \text{if } x_t \in \omega_1 \text{ and } w_t^T x_t \leq 0 \\ w_{t+1} = w_t - \rho x_t, & \text{if } x_t \in \omega_2 \text{ and } w_t^T x_t > 0 \\ w_{t+1} = w_t, & \text{o.w.} \end{cases}$$

The problem is not linearly separable without a bias so we will augment the input and weight vectors:

$$w_1 = \left\{ \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\}, w_2 = \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}, w_0 = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Running the algorithm:

1. $w_0^T x_0 = 0, x_0 \in \omega_1 \rightarrow w_1 = w_0 + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

2. $w_1^T x_1 = 1, x_1 \in \omega_1 \rightarrow w_2 = w_1$

3. $w_2^T x_2 = 1, x_2 \in \omega_2 \rightarrow w_3 = w_2 - \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix}$

4. $w_3^T x_3 = -1, x_3 \in \omega_2 \rightarrow w_4 = w_3$

5. $w_4^T x_4 = 0, x_4 \in \omega_1 \rightarrow w_5 = w_4 + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$

6. $w_5^T x_5 = 1, x_5 \in \omega_1 \rightarrow w_6 = w_5$

7. $w_6^T x_6 = 0, x_6 \in \omega_2 \rightarrow w_7 = w_6$

8. $w_7^T x_7 = 0, x_7 \in \omega_2 \rightarrow w_8 = w_7$

9. $w_8^T x_8 = 1, x_8 \in \omega_1 \rightarrow w_9 = w_8$

→ all patterns classified correctly

$$\Rightarrow \underline{w_{\text{final}}} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

3.5. Refer to the MATLAB script.

$$3.8. J_{SSE} = \sum_{(x,y) \in S} (y - w^T x)^2, \quad J_{MSE} = \frac{1}{|S|} \sum_{(x,y) \in S} (y - w^T x)^2$$

$$\frac{\partial J_{SSE}(w)}{\partial w} = -2 \sum_{(x,y) \in S} x(y - x^T \hat{w}) = 0 \Rightarrow \sum_{(x,y) \in S} x(y - x^T \hat{w}) = 0 \quad (I)$$

$$\frac{\partial J_{MSE}(w)}{\partial w} = \frac{-2}{|S|} \sum_{(x,y) \in S} x(y - x^T \hat{w}) = 0 \Rightarrow \sum_{(x,y) \in S} x(y - x^T \hat{w}) = 0 \quad (II)$$

Equations (I) and (II) are the same, which means that the optimal \hat{w} obtained from either J_{SSE} or J_{MSE} will be similar.

3.10. If N is the number of samples and M is the number of classes we can form matrices:

$$Y = [y_1, y_2, \dots, y_M]^T \text{ and } W = [w_1, w_2, \dots, w_M]^T$$

The minimal J_{SSE} yields the optimal \hat{w} :

$$\hat{w} = \underset{w}{\operatorname{argmin}} \sum_{i=1}^N \|y - w^T x\|^2 = \underset{w}{\operatorname{argmin}} \sum_{i=1}^N \sum_{j=1}^M (y_j^{(i)} - w_j^T x_j^{(i)})^2$$

However the summations in the last term are interchangeable because their indices are independent. Therefore we have:

$$\hat{w} = \underset{w}{\operatorname{argmin}} \sum_{j=1}^M \sum_{i=1}^N (y_j^{(i)} - w_j^T x_j^{(i)})^2$$

This means that instead of minimizing $\sum_{j=1}^M (y_j^{(i)} - w_j^T x_j^{(i)})^2$ for every sample $(x^{(i)}, y^{(i)})$ we can instead fix a class w_j and

Persian minimize the cost w.r.t. class over all input samples.

\Rightarrow Instead of solving for w over N we can solve for w_j for every $j=1, \dots, M$ over N

3.11. If x and y are jointly Gaussian the probability distribution is given by:

$$P(x, y) = \frac{1}{2\pi\sigma_x\sigma_y\sqrt{1-\alpha^2}} \exp \left\{ -\frac{1}{2(1-\alpha^2)} \left[\frac{(x-\mu_x)^2}{\sigma_x^2} + \frac{(y-\mu_y)^2}{\sigma_y^2} - 2\alpha \frac{(x-\mu_x)(y-\mu_y)}{\sigma_x\sigma_y} \right] \right\}$$

Additionally if x and y are jointly Gaussian they are also independently Gaussian by definition because:

$$x, y \text{ jointly gaussian} \rightarrow ax + by \sim N(\mu, \sigma^2)$$

$$\text{Setting } a=1 \text{ and } b=0 \rightarrow x \sim N(\mu_x, \sigma_x^2)$$

$$\text{Setting } b=1 \text{ and } a=0 \rightarrow y \sim N(\mu_y, \sigma_y^2)$$

Also, using the probability chain rule we know:

$$P(x, y) = P(x) \cdot P(y|x)$$

$$\Rightarrow P(y|x) = \frac{P(x, y)}{P(x)} \text{ where } P(x) = \frac{1}{\sqrt{2\pi}\sigma_x} \exp \left\{ -\frac{(x-\mu_x)^2}{2\sigma_x^2} \right\}$$

$$\Rightarrow P(y|x) = \frac{\frac{1}{2\pi\sigma_x\sigma_y\sqrt{1-\alpha^2}} \exp \left\{ -\frac{(x-\mu_x)^2}{2\sigma_x^2(1-\alpha^2)} + \frac{(x-\mu_x)^2}{2\sigma_x^2} - \frac{1}{2(1-\alpha^2)} \left[\frac{(y-\mu_y)^2}{\sigma_y^2} - 2\alpha \frac{(x-\mu_x)(y-\mu_y)}{\sigma_x\sigma_y} \right] \right\}}{\frac{1}{\sqrt{2\pi}\sigma_x} \exp \left\{ -\frac{(x-\mu_x)^2}{2\sigma_x^2} \right\}}$$

$$\Rightarrow P(y|x) = \frac{1}{\sigma_y\sqrt{2\pi(1-\alpha^2)}} \exp \left\{ -\frac{1}{2(1-\alpha^2)} \left[\frac{\alpha^2(x-\mu_x)^2}{\sigma_x^2} + \frac{(y-\mu_y)^2}{\sigma_y^2} - 2\alpha \frac{(x-\mu_x)(y-\mu_y)}{\sigma_x\sigma_y} \right] \right\}$$

$$\left(\frac{\alpha(x-\mu_x)}{\sigma_x} - \frac{(y-\mu_y)}{\sigma_y} \right)^2$$

$$E[y|x] = \int y P(y|x) dy = \frac{1}{\sigma_y \sqrt{2\pi(1-\alpha^2)}} \int y \exp \left\{ -\frac{\left(\frac{\alpha(x-\mu_x)}{\sigma_x} - \frac{y-\mu_y}{\sigma_y} \right)^2}{2\sigma_y^2(1-\alpha^2)} \right\} dy$$

...

3.13. MSE attempts to minimize a cost function $J(w)$.

$J(w) = E[(f(x;w) - y)^2]$ → the expectation of squared errors of the trained function w.r.t. targets y .

$$E[(f(x;w) - y)^2] = P(x, w_1)(f(x;w_1) - y_1)^2 + P(x, w_2)(f(x;w_2) - y_2)^2 \quad (1)$$

$$P(x, w_i) = P(w_i|x) \cdot P(x) \Rightarrow (2) = (f(x;w) - 1)^2 P(w_1|x) + (f(x;w) + 1)^2 P(w_2|x)$$

$y_1 = +1(w_1), y_2 = -1(w_2)$

$$= f(x;w)^2 - 2f(x;w)[P(w_1|x) - P(w_2|x)] + \underbrace{P(w_1|x) + P(w_2|x)}_1$$

Adding and subtracting $[P(w_1|x) - P(w_2|x)]^2$ we have:

$$f(x;w)^2 - 2f(x;w)[P(w_1|x) - P(w_2|x)] + [P(w_1|x) - P(w_2|x)]^2 - [P(w_1|x) - P(w_2|x)]^2 + 1$$

$\rightarrow g(x)$, the optimal Bayes decision surface.

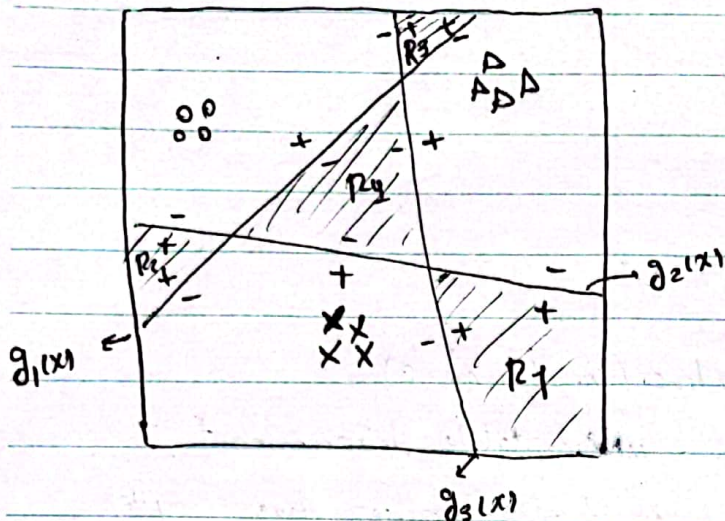
$$= (f(x;w) - [P(w_1|x) - P(w_2|x)])^2 - [P(w_1|x) - P(w_2|x)]^2 + 1$$

this part is not affected by the parameters of f , namely w therefore we ignore it in the minimization task.

$$\Rightarrow \tilde{w}_{MSE} = \arg \min_w E[(f(x;w) - y)^2] = \arg \min_w [f(x;w) - g(x)]^2$$

minimizing $J(w)$ is equivalent to approximating $g(x)$ in MSE optimal sense.

3.15. Take the example below in a bivariate space:



Legend: $\circ \rightarrow w_1$
 $\Delta \rightarrow w_2$
 $\times \rightarrow w_2$

as we can see with this configuration regions R_1, R_2, R_3 result in positive $g(x)$ for more than one class and do not contain any training data. While R_4 results in negative $g(x)$ for all classes.

3.16. If we write the KKT conditions for the problem stated in example 3.5 we have:

$$\lambda_1 (w_1 + w_2 + w_0 - 1) = 0$$

$$\lambda_2 (w_1 - w_2 + w_0 - 1) = 0$$

$$\lambda_3 (w_1 - w_2 + w_0 - 1) = 0$$

$$\lambda_4 (w_1 + w_2 - w_0 - 1) = 0$$

restricting to
 lines passing
 through the origin
 $w_0 = 0$

$$\lambda_1 (w_1 + w_2 - 1) = 0$$

$$\lambda_2 (w_1 - w_2 - 1) = 0$$

$$\lambda_3 (w_1 - w_2 - 1) = 0$$

$$\lambda_4 (w_1 + w_2 - 1) = 0$$

By removing w_0 we have effectively reduced the number of constraints to two as λ_1, λ_4 and λ_2, λ_3 can be squashed together.

Therefore the new KKT conditions are:

$$\begin{cases} \lambda_1' (w_1 + w_2 - 1) = 0 \\ \lambda_2' (w_1 - w_2 - 1) = 0 \end{cases} \quad \begin{cases} \frac{\partial L}{\partial w_1} = 0 \Rightarrow w_1 = \lambda_1' + \lambda_2' \\ \frac{\partial L}{\partial w_2} = 0 \Rightarrow w_2 = \lambda_1' - \lambda_2' \end{cases}$$

Substitution of (1) in (2) results in:

$$\begin{cases} \lambda_1'(2\lambda_1'-1)=0 \\ \lambda_2'(2\lambda_2'-1)=0 \end{cases}$$

Now we will consider 4 cases:

Case #1: both λ_1' and λ_2' are inactive ($\lambda_1'=0$; $\lambda_2'=0$)

$\Rightarrow w_1=0, w_2=0 \rightarrow g(x)=0 \rightarrow$ unacceptable discriminant
as it misclassifies two samples
while we're using hard-sum.

Case #2 and #3: either one of λ_1' or λ_2' is active ($\lambda_1'=0, \lambda_2' \neq 0$ or $\lambda_1' \neq 0, \lambda_2'=0$)

Both cases are similar so w.l.o.g let's assume $\lambda_1'=0, \lambda_2' \neq 0$

$$\rightarrow (2\lambda_2'-1)=0 \Rightarrow \lambda_2'=\frac{1}{2} \rightarrow w_1=\frac{1}{2}, w_2=-\frac{1}{2}$$

$\Rightarrow g(x)=\frac{1}{2}x_1 - \frac{1}{2}x_2 \rightarrow$ unacceptable discriminant since it
misclassifies one sample

(for the other case we get $g(x)=-\frac{1}{2}x_1 + \frac{1}{2}x_2$ which is unacceptable for the same reason)

Case #4: Both λ_1' and λ_2' are active ($\lambda_1' \neq 0$ and $\lambda_2' \neq 0$)

$$\rightarrow \begin{cases} 2\lambda_1'-1=0 \\ 2\lambda_2'-1=0 \end{cases} \rightarrow \begin{cases} \lambda_1'=\frac{1}{2} \\ \lambda_2'=\frac{1}{2} \end{cases} \rightarrow \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} + \frac{1}{2} \\ \frac{1}{2} - \frac{1}{2} \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$\rightarrow g(x)=x_1 \rightarrow$ which is also the boundary achieved in example 3.5 and classifies perfectly.