

Aim: To implement gradient descent and backpropagation for training a simple feedforward neural network on the XOR problem.

Description:

- \* Gradient descent is an optimization algorithm used to minimize the loss function by updating weights in the opposite direction of the gradient.
- \* Backpropagation is the process of calculating the gradient of the loss function with respect to each weight using the chain rule, so we can apply gradient descent efficiently.

The steps are:

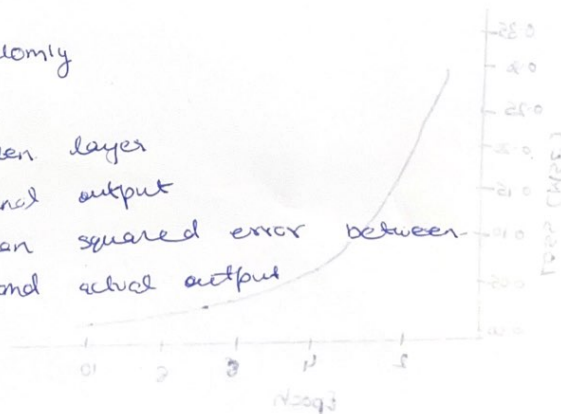
1. Forward pass - Compute output from inputs
2. Compute loss - difference between predicted and actual values.
3. Backpropagation pass - Compute gradients of loss w.r.t weights
4. Update weights - use gradient descent rule.

$$w = w - \eta \cdot \frac{dL}{dw}$$

where  $\eta$  is the learning rate.

Procedure:

1. Initialize weights randomly
2. Forward pass
  - compute the hidden layer
  - compute the final output
3. Compute loss: mean squared error between predicted output and actual output



OUTPUT:

Epoch 0, loss : 0.2558  
Epoch 1000, loss : 0.2494  
Epoch 2000, loss : 0.2454  
Epoch 3000, loss : 0.2047  
Epoch 4000, loss : 0.1532  
Epoch 5000, loss : 0.1387  
Epoch 6000, loss : 0.1336  
Epoch 7000, loss : 0.1312  
Epoch 8000, loss : 0.1297  
Epoch 9000, loss : 0.1288

Final predictions:

[1 0.005 300 868]

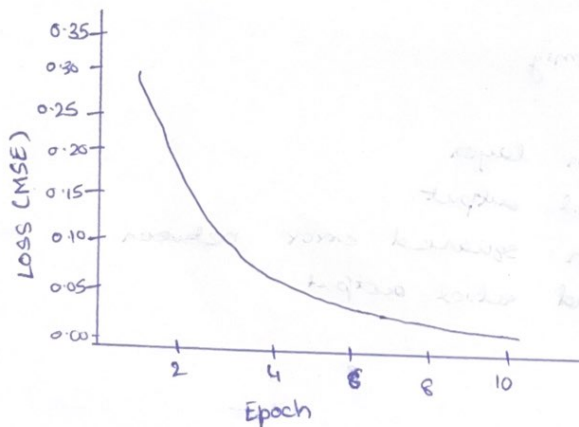
[0.49554 213]

[0.95091 319]

[0.50319 888]

Loss curve

Loss Curve



4. Backpropagation
5. weight update  
update weights and biases using gradient descent
$$w = w - \eta \cdot \frac{dL}{dw}$$
6. Repeat steps 2-5 for several epochs until the loss converges.
7. Print final predictions after training

#### Result:

The code has been successfully executed and shows the network learned the XOR logic  
output near 0 for [0,0] and [1,1] and near 1 for [0,1] and [1,0]

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## EXPERIMENT-7

23-9-25

Aim: To build a convolutional neural network model that can classify images of cats and dogs using a labelled dataset.

### Description:

A CNN is a deep learning algorithm designed to recognize patterns in visual data. ~~CNN are inspired~~ The core idea is to use a series of convolutions over input in to capture features such as edges, textures, and structures.

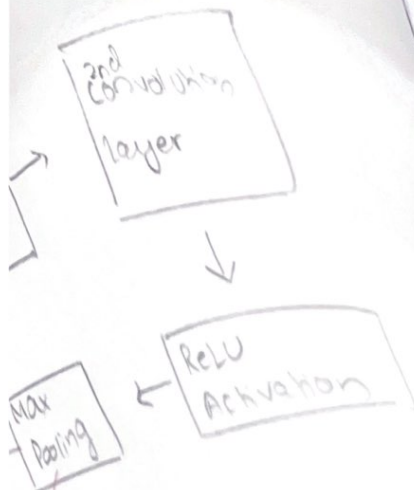
architecture -

- Convolution layer - apply filters to images to extract features.
- Activation (ReLU layer) - Adds non-linearity to the each convolution.

- Pooling layer - Reduces the spatial dimension helping reduce computational and overfitting.

- F.C layer - After feature extraction, flat through FC layer to produce

- Softmax func. - Used in output layer final layer values in classification.



Pseudocode:

Epoch

Epoch	Accuracy	Loss	val-accuracy
1/10	0.4413	0.9051	0.6909
2/10	0.6437	0.6159	0.7636
3/10	0.8026	0.3842	0.7729
4/10	0.7967	0.4149	0.7445
5/10	0.8501	0.3423	0.7455
6/10	0.8345	0.3607	0.8364
7/10	0.7897	0.4351	0.8091
8/10	0.8389	0.3291	0.7727
9/10	0.8384	0.3134	0.8182
10/10	0.8546	0.3006	0.7909

Workflow of CNN



```

import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
from sklearn.datasets import load_iris
from sklearn.model_selection import train_test_split
from sklearn.preprocessing import OneHotEncoder, StandardScaler

```

```

iris = load_iris()
X = pd.DataFrame(iris.data, columns=iris.feature_names)
y = pd.DataFrame(iris.target, columns=["species"])

print("First 5 rows of dataset:")
print(X.head())

print("\nTarget distribution:")
print(y.value_counts())

# Visualize features
pd.plotting.scatter_matrix(X, figsize=(10, 8), diagonal='kde')
plt.suptitle("Iris Dataset Feature Distributions", fontsize=14)
plt.show()

```

First 5 rows of dataset:

	sepal length (cm)	sepal width (cm)	petal length (cm)	petal width (cm)
0	5.1	3.5	1.4	0.2
1	4.9	3.0	1.4	0.2
2	4.7	3.2	1.3	0.2
3	4.6	3.1	1.5	0.2
4	5.0	3.6	1.4	0.2

Target distribution:

species	
0	50
1	50
2	50

Name: count, dtype: int64

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[ ]

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↔ First 5 rows of dataset:

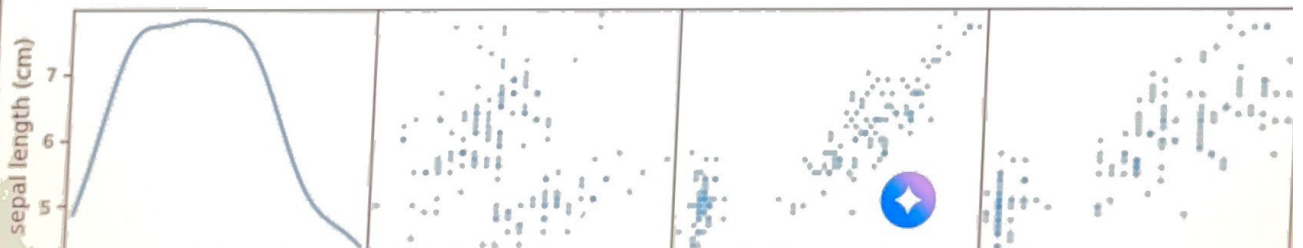
	sepal length (cm)	sepal width (cm)	petal length (cm)	petal width (cm)
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1	4.9	3.0	1.4	0.2
2	4.7	3.2	1.3	0.2
3	4.6	3.1	1.5	0.2
4	5.0	3.6	1.4	0.2

Target distribution:  
species

0	50
1	50
2	50

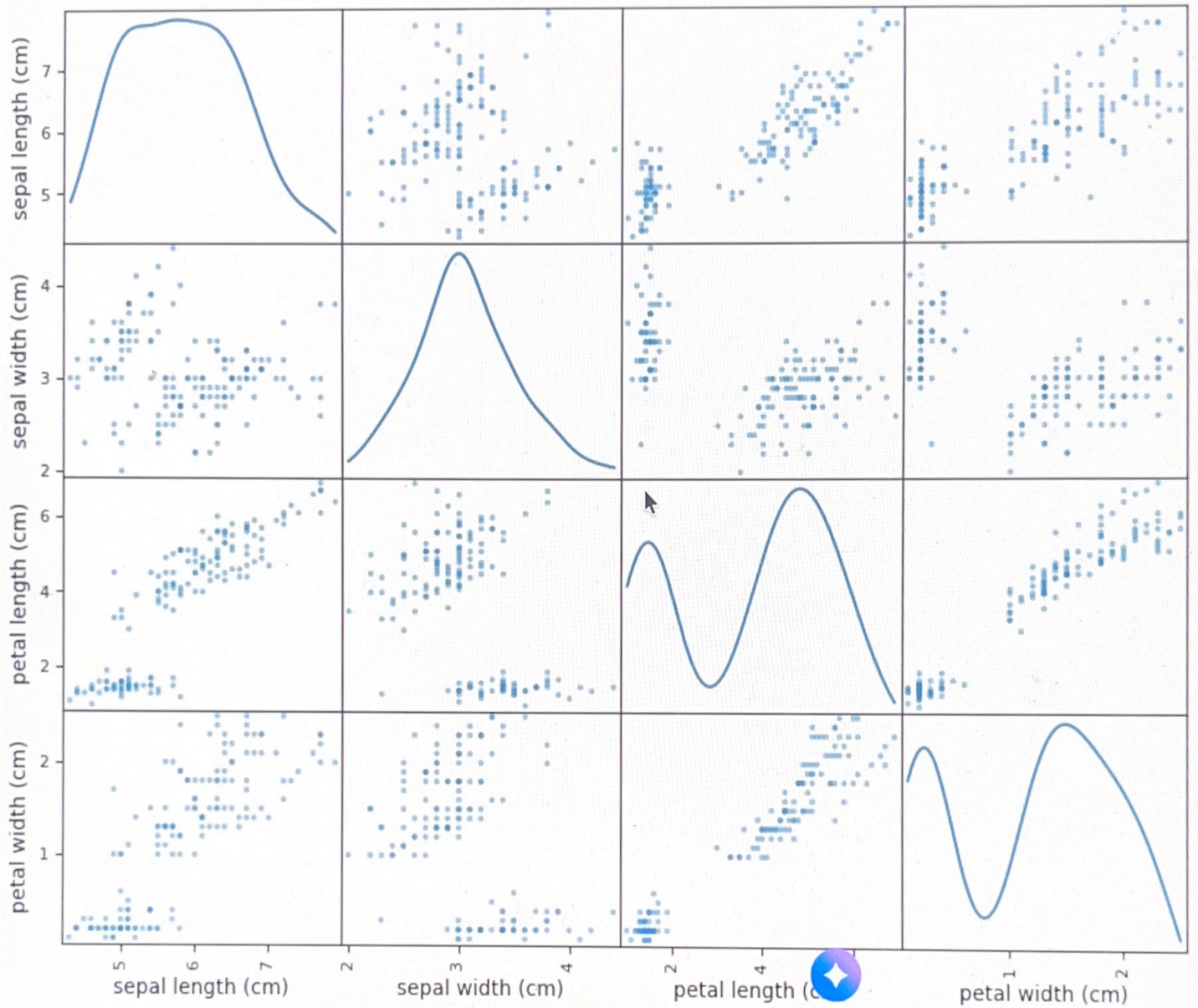
Name: count, dtype: int64

Iris Dataset Feature Distributions





Iris Dataset Feature Distributions





```
[ ] scaler = StandardScaler()
X_scaled = scaler.fit_transform(X)

# One-hot encode labels
encoder = OneHotEncoder(sparse_output=False)
y_encoded = encoder.fit_transform(y)

# Train-test split
X_train, X_test, y_train, y_test = train_test_split(
    X_scaled, y_encoded, test_size=0.2, random_state=42, stratify=y
)
```

```
[ ] def sigmoid(z):
    return 1 / (1 + np.exp(-z))

def sigmoid_derivative(a):
    return a * (1 - a)

def softmax(z):
    exp_z = np.exp(z - np.max(z, axis=1, keepdims=True)) # stability
    return exp_z / np.sum(exp_z, axis=1, keepdims=True)

def cross_entropy(y_true, y_pred):
    m = y_true.shape[0]
    eps = 1e-9
    return -np.sum(y_true * np.log(y_pred + eps)) / m

def accuracy(y_true, y_pred):
    return np.mean(np.argmax(y_true, axis=1) == np.argmax(y_pred, axis=1))
```

```
[ ] class SimpleDNN:
    def __init__(self, input_size, hidden_size, output_size, lr=0.01):
        np.random.seed(42)
        self.W1 = np.random.randn(input_size, hidden_size) * 0.01
        self.b1 = np.zeros((1, hidden_size))
        self.W2 = np.random.randn(hidden_size, output_size) * 0.01
        self.b2 = np.zeros((1, output_size))
```



```

class SimpleDNN:
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        self.b1 = np.zeros((1, hidden_size))
        self.W2 = np.random.randn(hidden_size, output_size) * 0.01
        self.b2 = np.zeros((1, output_size))
        self.lr = lr

    def forward(self, X):
        self.Z1 = np.dot(X, self.W1) + self.b1
        self.A1 = sigmoid(self.Z1)
        self.Z2 = np.dot(self.A1, self.W2) + self.b2
        self.A2 = softmax(self.Z2)
        return self.A2

    def backward(self, X, y, output):
        m = X.shape[0]

        # Output layer gradients
        dZ2 = output - y
        dW2 = np.dot(self.A1.T, dZ2) / m
        db2 = np.sum(dZ2, axis=0, keepdims=True) / m

        # Hidden layer gradients
        dA1 = np.dot(dZ2, self.W2.T)
        dZ1 = dA1 * sigmoid_derivative(self.A1)
        dW1 = np.dot(X.T, dZ1) / m
        db1 = np.sum(dZ1, axis=0, keepdims=True) / m

        # Gradient descent update
        self.W1 -= self.lr * dW1
        self.b1 -= self.lr * db1
        self.W2 -= self.lr * dW2
        self.b2 -= self.lr * db2

    def train(self, X, y, epochs=1000):
        history = {"loss": [], "accuracy": []}
        for i in range(epochs):

```





Week-6.ipynb ☆ ☁

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```
self.W1 = self.lr * db1
self.b1 -= self.lr * db1
self.W2 = self.lr * dw2
self.b2 -= self.lr * db2

def train(self, X, y, epochs=1000):
    history = {"loss": [], "accuracy": []}
    for i in range(epochs):
        output = self.forward(X)
        loss = cross_entropy(y, output)
        acc = accuracy(y, output)
        self.backward(X, y, output)

        history["loss"].append(loss)
        history["accuracy"].append(acc)

        if i % 100 == 0:
            print(f"Epoch {i}: Loss={loss:.4f}, Accuracy={acc:.4f}")

    return history

def predict(self, X):
    probs = self.forward(X)
    return np.argmax(probs, axis=1)
```

[ ]

```
dnn = SimpleDNN(input_size=4, hidden_size=8, output_size=3, lr=0.1)
history = dnn.train(X_train, y_train, epochs=1000)
```



```
Epoch 0: Loss=1.0987, Accuracy=0.3333
Epoch 100: Loss=1.0948, Accuracy=0.8000
Epoch 200: Loss=0.8991, Accuracy=0.7250
Epoch 300: Loss=0.5464, Accuracy=0.8833
Epoch 400: Loss=0.4240, Accuracy=0.9167
Epoch 500: Loss=0.3531, Accuracy=0.9167
Epoch 600: Loss=0.3018, Accuracy=0.9250
Epoch 700: Loss=0.2621, Accuracy=0.9417
Epoch 800: Loss=0.2300, Accuracy=0.9500
Epoch 900: Loss=0.2032, Accuracy=0.9583
```

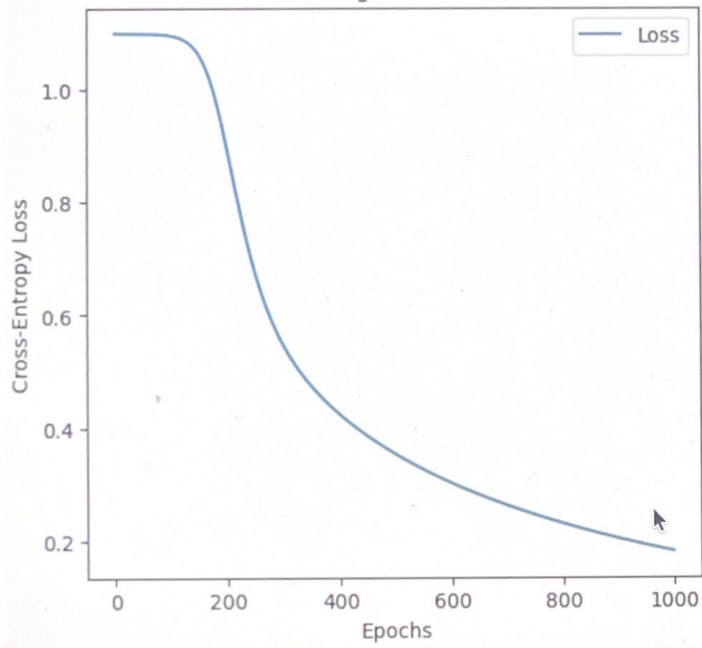
[ ]

```
v pred = dnn.forward(X_test)
```

{ } Variables

Terminal

Training Loss Curve



Training Accuracy Curve

