

1D Toda Lattices

What are crystals?

A solid material whose constituents (such as atoms, molecules, or ions) are arranged in a highly ordered microscopic structure, forming a crystal lattice that extends in all directions.

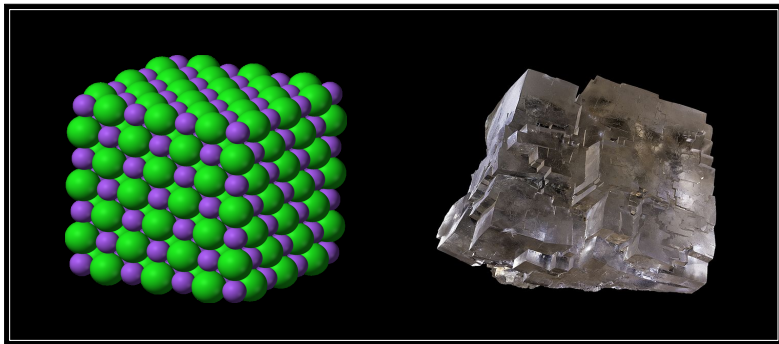
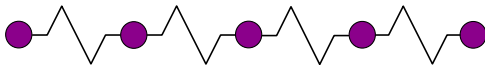


Figure: Halite (table salt, NaCl)

1 dimensional crystals

In a crystal, electrons move in a potential, produced by regularly spaced ion cores.



Assumptions:

Particles have unit mass

Finitely many particles

Terminology:

Open : no boundary conditions

Closed : periodic boundary condition or particles on a ring

Method:

Hamilton's formalism

What is a Hamiltonian?

A Hamiltonian system is a dynamical system governed by Hamilton's equations. Examples include planetary system and electron in an electromagnetic field.

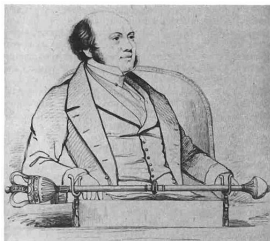


Figure: Sir William Rowan Hamilton (1805-1865)

It is a mathematical formalism developed by Hamilton to describe the evolution equations of a physical system.

Let the phase space be \mathbb{R}^k and consider a system of n particles. The Hamiltonian $H = H(\mathbf{p}, \mathbf{q}, t)$ is a scalar function, where \mathbf{p} and \mathbf{q} denote the momentum and position of n particles. Thus, $\mathbf{p} = (p_1, \dots, p_n)$ and $\mathbf{q} = (q_1, \dots, q_n)$, vectors in \mathbb{R}^{kn} , are functions of time t .

Hamilton's evolution equations:

$$\begin{aligned}\frac{d\mathbf{p}}{dt} &= -\frac{\partial H}{\partial \mathbf{q}} \\ \frac{d\mathbf{q}}{dt} &= \frac{\partial H}{\partial \mathbf{p}}\end{aligned}$$

If the Hamiltonian is not time dependent, then it becomes conserved throughout the motion. Springs, pendulum are examples where H , a constant of motion, equals the energy E of the system.

Harmonic Oscillator

Consider $\mathbf{p} = p$ and $\mathbf{q} = x$ with $H = \frac{p^2}{2m} + \frac{1}{2}kx^2$. Evolution equations are

$$\frac{dp}{dt} = -kx, \quad \frac{dx}{dt} = \frac{p}{m}.$$

In matrix form, we have

$$\begin{pmatrix} p'(t) \\ x'(t) \end{pmatrix} = \underbrace{\begin{pmatrix} 0 & -k \\ \frac{1}{m} & 0 \end{pmatrix}}_A \begin{pmatrix} p(t) \\ x(t) \end{pmatrix}$$

From ordinary differential equations, we know that ($c = k/m$)

$$\begin{pmatrix} p(t) \\ x(t) \end{pmatrix} = e^A \begin{pmatrix} p(0) \\ x(0) \end{pmatrix} = \begin{pmatrix} \cos(\sqrt{ct}) & -\sqrt{km} \sin(\sqrt{ct}) \\ \frac{1}{\sqrt{km}} \sin(\sqrt{ct}) & \cos(\sqrt{ct}) \end{pmatrix} \begin{pmatrix} p(0) \\ x(0) \end{pmatrix}$$

History of the Problem

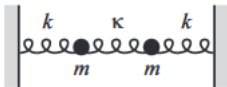
Consider Hamiltonians of the form (for a closed 1D lattice)

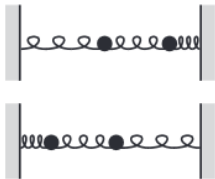
$$H = \sum_{j=1}^n \frac{p_j^2}{2} + \sum_{j=1}^n V(q_{j+1} - q_j)$$

with *harmonic interaction*, i.e., $V(r) = r^2/2$. Evolution equations are

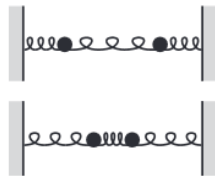
$$\dot{q}_j = p_j, \quad \dot{p}_j = -(2q_j - q_{j-1} - q_{j+1}).$$

This is a system of linear differential equations with constant coefficients. Solution is given by the superposition of **normal modes**.





Both springs move the same way.
 The middle spring is never stretched.
 Same amplitude and frequency is $\sqrt{k/m}$.



Both springs move oppositely.
 The middle spring exerts a restoring force.
 Amplitudes are equal but opposite.
 Frequency is $\sqrt{(k + 2\kappa)/m}$.

Any arbitrary motion of the system is a linear combination of these two normal modes.

Pictures courtesy David Morin's book (draft) *Waves*.

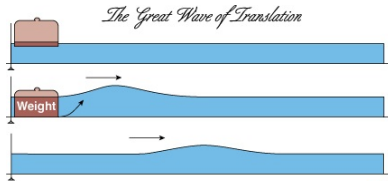
In 1950's it was believed that a generic non-linear perturbation would lead to **thermalization**.

1955 **Fermi, Pasta, Ulam, Tsingou**: Observed a quasi-periodic motion instead of thermalization

1965 **Kruskal, Zabusky**: Connections to solitons and KdV equation

Solitons arise in a wide variety of disciplines - *non-linear differential equations, hydrodynamics, non-linear optics (stability), low frequency oscillations in DNA, communication engineering.*

A **soliton** is a solitary wave that maintains its shape while it propagates at constant velocity.



It was first observed in 1834 by naval engineer J. S. Russell.

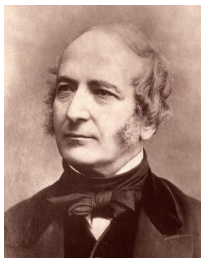


Figure: John Scott Russell (1808-1882)

It was only in 1960's, with the advent of modern computers, that the significance of Scott Russell's observation became apparent. Solitons, by definition, are unaltered in shape and speed by a collision with other solitons. Thus, solitary waves on a water surface are not actually solitons.

1D (Open) Toda Lattice

The search for soliton solutions led Morikazu Toda (in 1967) to consider $V(r) = e^{-r} - 1$. It is a simple model for a one dimensional crystal in solid state physics. It is famous because it is one of the earliest examples of a non-linear, completely integrable system.

Popular Interpretation: System of unit masses, connected by non-linear springs subject to exponential restoring force.

$$H(\mathbf{p}, \mathbf{q}, t) = \sum_{i=1}^n \frac{p_i^2}{2} + \sum_{j=1}^{n-1} e^{2(q_j - q_{j+1})}$$

Assumptions:

$$p_1 + \cdots + p_n = 0 \quad (\text{conservation of momentum})$$

$$q_1 + \cdots + q_n = 0 \quad (\text{conservation of centre of mass})$$

Evolution equations are

$$\begin{aligned}
 \dot{q}_j &= p_j & j &= 1, \dots, n \\
 \dot{p}_1 &= -2e^{2(q_1 - q_2)} \\
 \dot{p}_j &= -2e^{2(q_j - q_{j+1})} + 2e^{2(q_{j-1} - q_j)} & j &= 2, \dots, n-1 \\
 \dot{p}_n &= 2e^{2(q_{n-1} - q_n)}
 \end{aligned}$$

Consider the two matrices (with $Q_{i,j} = e^{q_i - q_j}$)

$$L = \begin{pmatrix} p_1 & Q_{1,2} & 0 & \cdots & 0 \\ Q_{1,2} & p_2 & Q_{2,3} & \cdots & 0 \\ 0 & Q_{2,3} & p_3 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & p_n \end{pmatrix}$$

$$M = \begin{pmatrix} 0 & Q_{1,2} & 0 & \cdots & 0 \\ -Q_{1,2} & 0 & Q_{2,3} & \cdots & 0 \\ 0 & -Q_{2,3} & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 0 \end{pmatrix}$$

We compute $[L, M] := LM - ML$ for $n = 2$. Note that $p_1 + p_2 = 0 = q_1 + q_2$ implies that

$$Q_{1,2} = e^{2q_1} \Rightarrow \dot{Q}_{1,2} = 2e^{2q_1}\dot{q}_1 = (p_1 - p_2)Q_{1,2}.$$

$$\dot{p}_1 = -2e^{2(q_1 - q_2)} = -2e^{4q_1} = -2Q_{1,2}^2$$

$$[L, M] = \begin{pmatrix} -2Q_{1,2}^2 & (p_1 - p_2)Q_{1,2} \\ (p_1 - p_2)Q_{1,2} & 2Q_{1,2}^2 \end{pmatrix} = \begin{pmatrix} \dot{p}_1 & \dot{Q}_{1,2} \\ \dot{Q}_{1,2} & \dot{p}_2 \end{pmatrix} = \dot{L}$$

Theorem

The Lax equation holds, i.e., $\dot{L} = [L, M]$.

Remark Both L and M have trace zero, i.e., elements of the Lie algebra \mathfrak{sl}_n . As M is skew-symmetric, it is in the Lie algebra \mathfrak{so}_n .

For $n = 2$, set $p = p_1 = -p_2$, $q = q_2 = -q_1$ and $Q = e^{-2q}$ such that

$$L = \begin{pmatrix} p & Q \\ Q & -p \end{pmatrix}, \quad M = \begin{pmatrix} 0 & Q \\ -Q & 0 \end{pmatrix}, \quad L(0) = \begin{pmatrix} 0 & v \\ v & 0 \end{pmatrix}$$

Consider the solution given by

$$L(t) = \text{Ad}[\exp(tL(0))]^{-1}_1(L(0))$$

This is motivated by the theory of Lie groups and Lie algebras.

- What is \exp ?

It is the exponential of a matrix, i.e.,

$$\exp(A) = e^A = I + A + \frac{A^2}{2!} + \dots$$

- What is Ad ?

It is the map given by

$$\text{Ad}(A) : M_n(\mathbb{R}) \rightarrow M_n(\mathbb{R}), \quad \text{Ad}(A)(V) = AVA^{-1}.$$

It is an invertible linear map.

- What is the subscript 1?

Any $A \in M_n(\mathbb{R})$ with $\det A = 1$ can be written uniquely as

$$A = BC, \quad BB^t = I_n, \quad \det B = 1$$

and C is lower triangular with positive entries on the diagonal.

We set $A_1 = B$.

In our case, we have the following:

- What is \exp ?

$$\begin{aligned}\exp(tL(0)) &= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + t \begin{pmatrix} 0 & v \\ v & 0 \end{pmatrix} + \frac{t^2}{2!} \begin{pmatrix} 0 & v \\ v & 0 \end{pmatrix}^2 + \dots \\ &= \begin{pmatrix} \cosh(tv) & \sinh(tv) \\ \sinh(tv) & \cosh(tv) \end{pmatrix}\end{aligned}$$

- What is the subscript 1?

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} = \left[\frac{1}{\sqrt{b^2 + d^2}} \begin{pmatrix} d & b \\ -b & d \end{pmatrix} \right] \left[\frac{1}{\sqrt{b^2 + d^2}} \begin{pmatrix} 1 & 0 \\ ab + cd & b^2 + d^2 \end{pmatrix} \right]$$

$$\exp(tL(0))_1 = \frac{1}{\sqrt{\cosh^2(tv) + \sinh^2(tv)}} \begin{pmatrix} \cosh(tv) & \sinh(tv) \\ -\sinh(tv) & \cosh(tv) \end{pmatrix}$$

- What is $\text{Ad}(A)^{-1}$?

Note that

$$(\text{Ad}(A^{-1}) \circ \text{Ad}(A))(V) = \text{Ad}(A^{-1})(AVA^{-1}) = V.$$

Thus, $\text{Ad}(A)^{-1} = \text{Ad}(A^{-1})$.

Putting it all together, we obtain

$$\begin{aligned} L(t) &= \exp(tL(0))_1^{-1} L(0) \exp(tL(0))_1 \\ &= \frac{v}{\cosh(2tv)} \begin{pmatrix} -\sinh(2tv) & 1 \\ 1 & \sinh(2tv) \end{pmatrix} \end{aligned}$$

Therefore, $e^{-2q(t)} = Q(t) = v / \cosh(2tv)$ and

$$q(t) = -\frac{1}{2} \ln v + \frac{1}{2} \ln(\cosh(2tv))$$

Theorem

There is an explicit solution for the Lax equation for any n given by

$$L(t) = \text{Ad}(\exp(tL(0))_1)^{-1}(L(0)).$$

This involves τ -functions and more Lie theory.

Lax pairs and Lax equation were introduced by Peter Lax (1968) to analyze solitons in continuous media.



Further Remarks

- What about an infinite 1D lattice?
1974 **Flaschka**: Solved the infinite 1D lattice (Hilbert spaces, unitary operators)
- What about closed 1D lattices?
1973 **Ford et. al.**: 3 particles in a ring with equal masses
- What about integrability?
1974 **Moser**: Yes, for the Toda 1D lattice
1974 **Flaschka**: Yes, for the infinite 1D lattice
1974 **Hénon**: Yes, for the closed 1D lattice
- Do 1D crystals exist?
2014 **Senga, Komsa et. al.**: Created a “one dimensional” crystal by packing Cesium Iodide (CsI) inside a carbon nanotube.