

# MA2102: LINEAR ALGEBRA

## Lecture 13: Linear Isomorphism

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Indian Institute of Science Education & Research Kolkata



We study the space of all linear maps together. Given vector spaces  $V$  and  $W$  (over a field  $F$ ), consider

$$\mathcal{L}(V, W) := \{T : V \rightarrow W \mid T \text{ is linear}\}.$$

When  $W = V$ , we simplify  $\mathcal{L}(V, V)$  to  $\mathcal{L}(V)$ , the set of linear self-maps of  $V$ . Given  $S, T : V \rightarrow W$ , set

$$(S + T)(v) := S(v) + T(v)$$

**Claim:**  $S + T$  is a linear map

Check that

$$(S + T)(cv) = S(cv) + T(cv) = cS(v) + cT(v) = c(S + T)(v)$$

Given two vectors  $v_1, v_2 \in V$

$$\begin{aligned}(S + T)(v_1 + v_2) &= S(v_1 + v_2) + T(v_1 + v_2) \\ &= S(v_1) + S(v_2) + T(v_1) + T(v_2) \\ &= (S + T)(v_1) + (S + T)(v_2)\end{aligned}$$

This defines a map

$$+ : \mathcal{L}(V, W) \times \mathcal{L}(V, W) \rightarrow \mathcal{L}(V, W), \quad (S, T) \mapsto S + T$$

This is commutative and associative (as addition of functions behave likewise). The zero map  $\mathbb{O} : V \rightarrow W$  is the additive identity in  $\mathcal{L}(V, W)$ .

To define the scaling, consider for any scalar  $c$  and  $T \in \mathcal{L}(V, W)$  the map

$$(cT)(v) := cT(v)$$

Show that  $cT$  is a linear map. This defines a map

$$\cdot : F \times \mathcal{L}(V, W) \rightarrow \mathcal{L}(V, W), \quad (c, T) \mapsto cT$$

Thus,  $1T = T$  and it can be seen that  $(-1)T$  is the inverse of  $T$ . All other axioms can now be verified easily.

**Observation**    *The set  $\mathcal{L}(V, W)$  is a vector space.*

**Examples** (1) Consider  $\mathcal{L}(\mathbb{R}, \mathbb{R}^n)$  and let  $T : \mathbb{R} \rightarrow \mathbb{R}^n$  be a linear map. Since  $\{1\}$  is a basis of  $\mathbb{R}$ ,  $T$  is determined by  $T(1)$  ( $T(c) = cT(1)$ ). It seems intuitively clear that the map

$$\text{ev} : \mathcal{L}(\mathbb{R}, \mathbb{R}^n) \rightarrow \mathbb{R}^n, \quad T \mapsto T(1)$$

is a bijection. It is onto (given  $\mathbf{v} \in \mathbb{R}^n$  set  $T(c) = c\mathbf{v}$ ).

It is one-to-one (if  $T(1) = S(1)$ , then  $T(c) = cT(1) = cS(1) = S(c)$ ).  
Moreover,

$$\text{ev}(S + T) = (S + T)(1) = S(1) + T(1) = \text{ev}(S) + \text{ev}(T)$$

$$\text{ev}(cT) = (cT)(1) = cT(1) = c \text{ev}(T)$$

implies that  $\text{ev}$  is actually a linear bijection. It follows from lecture 12 that  $\text{ev}^{-1}$  is a linear map (**exercise**).

(2) We shall see later that  $\mathcal{L}(\mathbb{R}^n, \mathbb{R}^m)$  can be identified (by a linear bijection) to  $M_{m \times n}(\mathbb{R})$ .

**Definition** [Linear Isomorphism] A linear map  $T : V \rightarrow W$  is called a linear isomorphism if  $T$  is one-to-one and onto.

We say  $V$  and  $W$  are **isomorphic** (as vector spaces) if there exists a linear isomorphism  $T : V \rightarrow W$ .

Note that  $T$  being one-to-one and onto guarantees that  $T^{-1} : W \rightarrow V$  is a well-defined linear map (cf. lecture 12). Thus, an alternative definition of isomorphism can be the existence of a linear map  $S : W \rightarrow V$  such that  $T \circ S = \text{id}_W$  and  $S \circ T = \text{id}_V$ . This implies that  $T$  is a bijection and  $S = T^{-1}$ .

**Remark** The notion of isomorphism is an equivalence relation.

- The identity map  $\text{id} : V \rightarrow V$  is a linear isomorphism.
- If  $S : V \rightarrow W$  is a linear isomorphism, then  $S^{-1} : W \rightarrow V$  is also an isomorphism.
- If  $S : V \rightarrow W$  and  $T : U \rightarrow V$  are linear isomorphisms, then  $S \circ T : U \rightarrow W$  is also an isomorphism.

We may now make precise what we had meant by “looks like”. It means “is isomorphic to”.

**Proposition**    *Let  $T : V \rightarrow W$  be a linear map.*

(i) *Let  $\{w_1, \dots, w_n\} \subset W$  be a linearly independent set and let  $T$  be surjective. If  $v_i \in V$  such that  $T(v_i) = w_i$ , then  $\{v_1, \dots, v_n\}$  is linearly independent.*

(ii) *Let  $\{v_1, \dots, v_n\} \subset V$  be a linearly independent set. If  $T$  is injective, then  $\{T(v_1), \dots, T(v_n)\}$  is linearly independent.*

(iii) *Let  $T$  be a linear isomorphism. If  $\beta = \{v_1, \dots, v_n\}$  is a basis for  $V$ , then  $\{T(v_1), \dots, T(v_n)\}$  is a basis for  $W$ .*

**Proof.**

(ii) If  $c_1 T(v_1) + \dots + c_n T(v_n) = \mathbf{0}_W$ , then by linearity of  $T$ ,  $T(c_1 v_1 + \dots + c_n v_n) = \mathbf{0}_W$ . Thus,  $c_1 v_1 + \dots + c_n v_n = \mathbf{0}_V$  due to injectivity of  $T$ . As  $v_j$ 's are linearly independent,  $c_j$ 's are all zero.

(i) If  $c_1v_1 + \cdots + c_nv_n = \mathbf{0}_V$ , then by linearity of  $T$ ,

$$\mathbf{0}_W = T(c_1v_1 + \cdots + c_nv_n) = c_1T(v_1) + \cdots + c_nT(v_n) = c_1w_1 + \cdots + c_nw_n.$$

As  $w_j$ 's are linear independent,  $c_j$ 's are zero.

(iii) Since  $\beta$  spans  $V$  and  $T$  is onto,  $T(\beta) = \{T(v_1), \dots, T(v_n)\}$  spans  $W$ . As  $\beta$  is linearly independent, by (ii)  $T(\beta)$  is linearly independent. This proves that  $T(\beta)$  is a basis.  $\square$

**Remark** The proposition works for infinite linearly independent sets as well as for infinite dimensional vector spaces. For instance, in (i) we may choose any linearly independent set  $S$  in  $V$  to prove that  $T(S)$  is linearly independent. Similarly, in (iii), the image of a basis is a basis, even if  $V$  is not finite dimensional.