

rough.

PAGE NO.:

DATE

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$$F = m \ddot{x}$$

$$\frac{dF}{dt} = m v_0 \dot{x}$$

$$L = \frac{1}{2} m \dot{x}^2 + m v_0 \dot{x}$$

$$\frac{\partial L}{\partial \dot{x}} = m \dot{x} + m v_0 = p_x$$

$$\Rightarrow H = p_x \cdot \frac{(p_x - m v_0)}{m} -$$

$$L = \frac{1}{2} m \left(\frac{p_x - m v_0}{m} \right)^2 + m v_0 \left(\frac{p_x - m v_0}{m} \right)$$

$$= \left(\frac{p_x - m v_0}{m} \right) \left(\frac{1}{2} (p_x + m v_0) - m v_0 \right)$$

$$= \frac{(p_x - m v_0)(p_x + m v_0)}{2m}$$

$$= \frac{p_x^2 - m^2 v_0^2}{2m}$$

$$\Rightarrow \frac{p_x^2}{2m} - m v_0$$

$$\frac{p_x^2}{2m} - p_x v_0 + \frac{p_x^2}{2m} + \frac{m v_0^2}{2}$$

$$\Rightarrow H = \frac{p_x^2}{2m} - p v_0 + \frac{m v_0^2}{2}$$

Q5

$$L = \frac{m}{2} (\dot{x}^2 + \dot{y}^2) - mgy$$

$$H = \frac{m}{2} (\dot{x}^2 + \dot{y}^2) + mgy$$

$$= \frac{p^2}{2m} + \frac{m}{2} (at)^2 + mg \cdot \frac{a}{2} t^2$$

$$= \frac{p^2}{2m} + \frac{ma}{2} (a+g) t^2$$

Q1

$$F(\vec{r}) = -\left(\alpha + \frac{\beta}{r}\right) \vec{r} = -(\alpha r + \beta) \hat{r}$$

$$F = -\nabla V$$

$$= V = \int \alpha r + \beta \, dr = \frac{\alpha r^2}{2} + \beta r$$

No vel
dependence

$$\Rightarrow H = T + V$$

$$= \frac{p_r^2}{2m} + \frac{p_\theta^2}{2mr^2} + \left(\frac{\alpha r^2}{2} + \beta r \right)$$

Q6 $L = \frac{m}{2} \dot{x}^2 + m(\dot{y}^2 + \dot{z}^2) - \frac{k}{2} x^2 - \frac{k}{2} (y+z)^2$

$$\frac{\partial L}{\partial \dot{x}} = m \dot{x}, \quad \frac{\partial L}{\partial \dot{y}} = 2m \dot{y}, \quad \frac{\partial L}{\partial \dot{z}} = 2m \dot{z}$$

$$H = \cancel{m \dot{x}^2 + 2m \dot{y}^2} \left(p_x \frac{p_x}{m} + p_y \frac{p_y}{2m} + p_z \frac{p_z}{2m} \right)$$

$$= \sum_i p_i \dot{q}_i - L = \frac{p_x^2}{2m} + \frac{p_y^2}{4m} + \frac{p_z^2}{4m}$$

$$+ \frac{k}{2} x^2 + \frac{k}{2} (y+z)^2$$

$$\Rightarrow \frac{p_x^2}{2m} + \frac{p_y^2}{4m} + \frac{p_z^2}{4m} + \frac{k}{2} x^2 + \frac{k}{2} (y+z)^2$$

Q4 $f(x,y) = (x+y)^2$

$\frac{\partial f}{\partial y} = 2(x+y) = V$

$$\frac{\partial g}{\partial V} = \frac{\partial g}{\partial x} \cdot \frac{\partial x}{\partial V} + \frac{\partial g}{\partial y} \cdot \frac{\partial y}{\partial V}$$

$$= \frac{\partial g}{\partial x} \cdot \frac{1}{2} + \frac{\partial g}{\partial y} \cdot \frac{1}{2} = y$$

$$f = (x+y)^2 \Rightarrow V = \frac{\partial f}{\partial y}$$

$$g(x,y) \Rightarrow y = \frac{\partial g}{\partial V}$$

$$f = x^2 + y^2 + 2xy, \quad \frac{\partial f}{\partial y} = 2x + 2y$$

$$y = \frac{V - 2x}{2}$$

$$\frac{V - 2x}{2} \Rightarrow \frac{\partial g}{\partial V} \Rightarrow dg = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy$$

$$= \frac{V^2}{4} - xV$$

$$g = \left(\frac{V}{4} - x \right) V$$

$$Q2 \quad \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{r}} \right) = m \ddot{r} - m r \dot{\theta}^2 = m r a^2$$

$$\Rightarrow m \ddot{r} (r - m) = 0$$

$$J = \frac{1}{2} m \dot{r}^2 - \frac{1}{2} m a^2 \dot{\theta}^2$$

$$\Rightarrow \frac{1}{2} m \left(\frac{d}{dt} \left(\frac{a^2}{r} \right) (e^{i\omega t} - e^{-i\omega t})^2 - \frac{a^2}{4} (e^{i\omega t} + e^{-i\omega t})^2 \right)$$

$$\frac{1}{2} m \omega^2 a^2 (-4) = -\frac{m \omega^2 a^2}{2}$$

$$\text{Now } Z = \frac{1}{2} m (\dot{r}^2 + r^2 a^2)$$

$$\frac{d}{dt} \left(\frac{\partial Z}{\partial \dot{r}} \right) = m \ddot{r} = \frac{\partial Z}{\partial r} = m r a^2$$

$$\Rightarrow r = A e^{i\omega t} + B e^{-i\omega t}$$

$$\dot{r} = 0 \Rightarrow r = a$$

$$A + B = a, \quad A = B = \frac{a}{2}$$

$$\Rightarrow r = \frac{a}{2} (e^{i\omega t} + e^{-i\omega t})$$

$$J = m \ddot{r} r - \frac{1}{2} m \dot{r}^2 - \frac{1}{2} m r^2 a^2 = \frac{1}{2} m \ddot{r}^2 - \frac{1}{2} m \dot{\theta}^2 a^2$$