Aeden Gasser-Brennan

www.aedengasserbrennan.com

EDUCATION

• University of California, Berkeley

Berkeley, CA

BS, Mechanical Engineering, GPA 3.9, Regents Scholar

Graduation Date: Spring 2023

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- o ME C85 (Mechanics), ME40 (Thermo), ME102B (Mechatronics), ME132 (Controls & Dynamics), E26 (Solidworks), E25 (Drafting), E7 (MATLAB), PHYS7B (Thermodynamics + E&M), CHEM1A (General Chem), MATH 53 (Multivariable Calculus), MATH 54 (Lin. Alg, Differential Equations)
- Harvard-Westlake High School High School Diploma: GPA: 4.45

'19 Los Angeles, CA

EXPERIENCE

• UC Berkeley Formula SAE Subteam Lead

Aug 2019 - Current

- Responsible for managing vehicle dynamics subteam, as well as running all testing on the car, designing suspension geometry and improvement of team lap-simulation software. Vehicle assembly, and composite manufacturing.
- Mehcanical Engineering Intern: Wavemaker Labs

Oct 2020 - Dec 2020

- o Designed drive system kinematics and navigation code for automated lawnmower. Wrote static stability model for mower. Designed automated food expo system for quick service restaurants.
- Wave Power Generation; UC Berkeley Mechanical Engineering

- o Undergraduate research assistant in laboratory of Dr. Reza Alam. Working on DoE Waves to Water design competition. Wrote time domain simulator for wave power-take-off system to optimize system parameters for energy absorption. Currently working on adjustable displacement pump to match hydrodynamic damping with pump impedance for max energy absorption.
- High Performance 3D-Printed Harmonic Drive Creation; Personal Project May 2020 - Current o Working on fully custom 3D printed harmonic drive. Matlab point-cloud generation for tooth profile generation optimized for maximum tooth contact while obeying fundamental law of gearing. Includes custom designed flexible ball bearings. Custom MSLA light bleed compensation software written to achieve 0.0005" tolerances on parts from commercial MSLA printer. Max torque is best published for a plastic harmonic drive (using glass filled material).
- Freelance CAD Designer; Upwork & Fiverr

Jun 2019 - Current

- o Product design, DFM, and working with manufacturers for small businesses and individuals. 10+ satisfied clients in accessories, plumbing, outdoors, and healthcare industries.
- Battlebots®Robotics Team Shellshock

May 2019 - Jul 2019

- Helped design solid parts for chassis, weapon, shell, and drivetrain for Battlebots team Shellshock. Manufactured 3-axis milled parts and worked with machine shops to produce complex 5-axis mill and CNC lathe parts.
- Quadruped Prosthetics; CSU Fullerton Mechanical Engineering

Jun 2018 - Aug 2018

- o Summer intern in the laboratory of Dr. Nina Robson, Dept. of Mechanical Engineering, CSU Fullerton. Worked on CAD modeling, 3D printing, and testing of a customized prosthetic for paraplegic dogs.
- Co-author on 2 posters at CSU Fullerton Science and Engineering Summer Research Symposium:
 - * Lopez, Gasser-Brennan, Chen, Robson, "Supporting Orthotic Wheelchair for Disabled Quadrupeds"
 - * Nguyen, Gasser-Brennan, Robson, "Performance Evaluation of a Human Upper-Extremity Prosthetic Device" Jun 2017 - Aug 2017
- Anechoic Wind Tunnel; CSU Fullerton Mechanical Engineering

- Designed and manufactured movable sensor arrays to test the acoustic damping properties of supersonic wing vortices in lab of Dr. Salvador Mayoral; Motorized gantry system to move sensors in wind tunnel during operation.
- Wind Tunnel Control Systems; CSU Fullerton Mechanical Engineering Jun 2016 - Aug 2016 • Made circuit diagrams and built custom control system for laboratory wind tunnel in lab of Salvador Mayoral. Control system incorporated pressure transducers to monitor wind tunnel, motor controllers to control sensor array. and relays to control main compressor.
- FRC Robotics Team 3328

Sep 2017 - Jun 2019

- o Lead designer and programmer, First Robotics Team 3328. Designed team's first ever custom gearboxes, and over one thousand machined parts overall. Worked with local machine shops and material suppliers for sponsorship.
- VEX Robotics Team 6007X

Jan 2013 - Apr 2018

o Founder, and 6 years as captain of Vex Robotics Team 6007; was main designer, builder, and programmer. Pioneered use of CNC manufactured parts in competition that is traditionally mostly off-the-shelf. Top 1% of competitors internationally (see below), 6007x.us

SKILLS

- CAD Software: Solidworks (CSWA Certified), Autodesk Inventor, Fusion 360
- Machining Experience: 3, 5-axis CNC Mill, Laser Cutter, Waterjet, 3D Printer, CNC Lathe, CNC Brake Press
- Markup/Program. Languages: MATLAB/Octave, Python, Java, C. JS, HTML/CSS, IATEX, github/AedenGB Awards
- UC Berkeley Regents Scholar: Top 2% of admitted class.

Mar 2019 - Current

Caroline D. Bradley Scholar: Four years private high school tuition paid.

2015 - 2019 2013 - 2018

- **Vex Robotics**
 - o 2017 High School Division Champion, World Championships. o 2014-2018 World Championship Competitor
 - o 2017, 2016, 2014 State Champion, CA State Championships.