

Problem set 1
DUE: Tue. September 8, 2015

Problem 1 In general case no, because summation of two polynomials can give us another denominator. In case if fixed denominator it is obviously a linear space. Its dimension is n and the basis is $\left(\frac{1}{q(x)}, \frac{x}{q(x)}, \dots, \frac{x^n}{q(x)}\right)$.

Problem 2

1. $v_4 + v_1 = v_1 + v_2 - (v_2 + v_3) + (v_3 + v_4)$, that means, that we can represent the last vector in terms of other. Thus this combination is not linearly independent.
2. $(v_1 - v_2) + (v_2 - v_3) + (v_3 - v_4) = -1 \cdot (v_4 - v_1)$ Thus this combination is not linearly independent.
3. This combination is linearly independent because I cannot represent the last vector in terms of others.
4. $-(v_1 + v_2) + (v_2 + v_3) = (v_3 - v_4) + (v_4 - v_1)$ Thus this combination is not linearly independent.

Problem 3

According to the fundamental theorem of algebra, we can represent such polynomials in the following form: $p(x) = (x - x_{-1})(x - x_0)(x - x_1) \cdot (x - x_2) \cdot \dots \cdot (x - x_{n-1})$.

It means, that all vectors in this vector space will include first three guys of $p(x)$. It means, that everything left is polynomial with degree not exceeding $n - 1$. Thus the dimension is n . The basis is $((x - x_{-1})(x - x_0)(x - x_1), x \cdot (x - x_{-1})(x - x_0)(x - x_1), \dots, x^{n-1} \cdot (x - x_{-1})(x - x_0)(x - x_1))$

Problem 4

$$A_I^1 = \begin{pmatrix} 1 & 1 \\ 1 & -\frac{1}{2} \end{pmatrix}$$

$$A_1^{II} = \begin{pmatrix} 1 & 2 \\ 2 & -1 \end{pmatrix}$$

$$A_I^{II} = A_I^1 \cdot A_1^{II} = \begin{pmatrix} 3 & 1 \\ 0 & 2.5 \end{pmatrix}$$

Problem 5

For some particular B there are several possible variants: if coordinates of B are not equal there are no solutions (example $(1, -1)$). Otherwise there are infinite number of solutions (example $(1, 1)$).

$$\begin{pmatrix} 1 & 2 \\ 1 & 2 \end{pmatrix} \cdot (x_1, x_2)^T = (x_1 + x_2, x_1 + x_2)^T$$

$$\text{Thus, } \ker(A) = (0, 0)^T$$

Problem 6

Yes, these matrices form a vector space. The basis is set of matrices of size $(n \times m)$ with one on A_{ii} place. This space has dimension $\min(n, m)$ because there are $\min(n, m)$ linearly independent rows.

Coordinates of this space have the following form.

$$\begin{pmatrix} 1 \\ 0 \\ \dots \\ 0 \end{pmatrix}_{\min(m,n)}.$$

Given matrices are obviously linear independent. Yes, they form a basis over matrices two by two.

$$A = \begin{pmatrix} \frac{1}{a} & 0 & 0 & \frac{1}{d} \\ 0 & \frac{1}{b} & \frac{1}{c} & 0 \\ 0 & \frac{1}{b} & -\frac{1}{c} & 0 \\ \frac{1}{a} & 0 & 0 & -\frac{1}{d} \end{pmatrix}$$

Problem 7

Blue whale brought me on his tale the following scalar product $\langle C, D \rangle = \text{Tr}(D^T C)$. Occasionally it is well defined and according to this scalar product given basis is orthonormal. For the parametrized case we can introduce $\langle C, D \rangle = A^{-1} \text{Tr}((AD)^T AC)$.

Problem 8

$$a_0 = \int_0^1 x - x^2 dx = \frac{1}{6}$$

$$b_n = 2 \int_0^1 (x - x^2) \sin(2\pi n x) dx = 0$$

$$a_n = 2 \int_0^1 (x - x^2) \cos(2\pi n x) dx = \frac{-1}{(\pi n)^2}$$

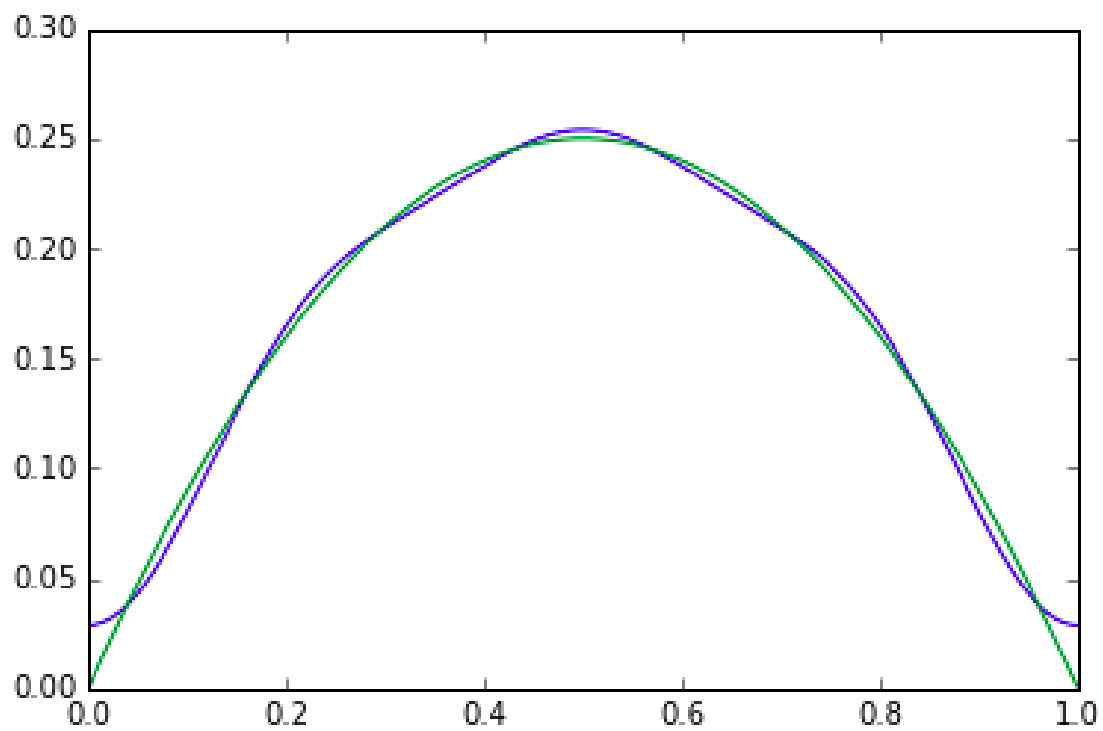


Рис. 1: "Fourier approximation"

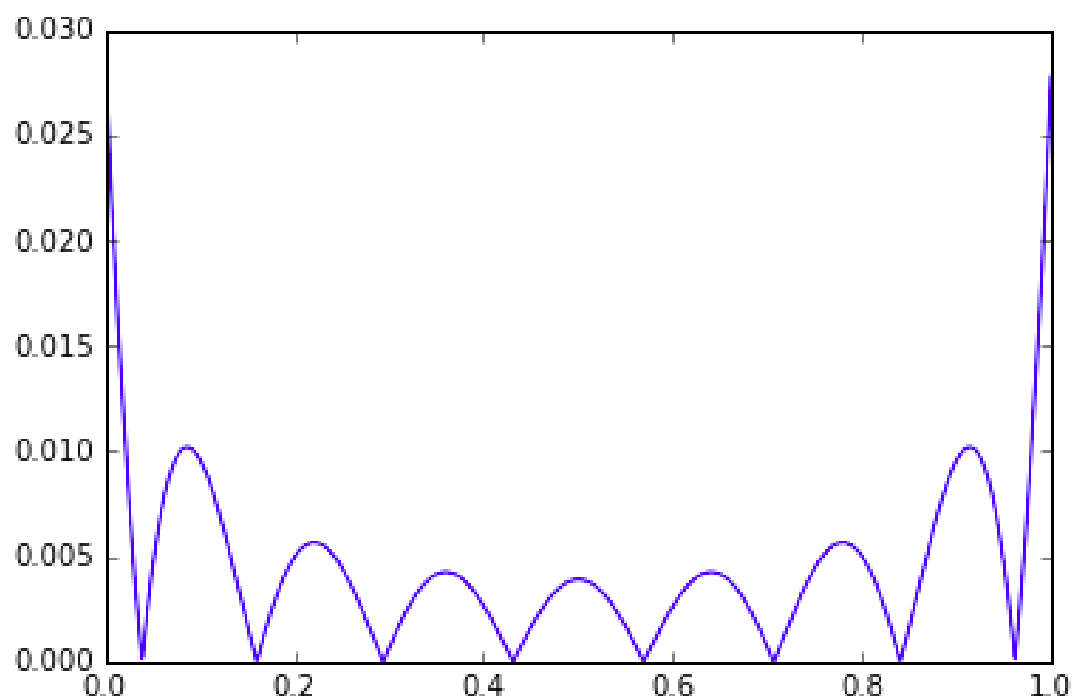


Рис. 2: "Deviation"

Problem 9

$$a_0 = \int_0^1 x dx = \frac{1}{2}$$

$$a_n = 2 \int_0^1 x \cos(2\pi n x) dx = 0$$

$$b_n = 2 \int_0^1 x \sin(2\pi n x) dx = \frac{-\cos(2\pi n)}{n\pi}$$

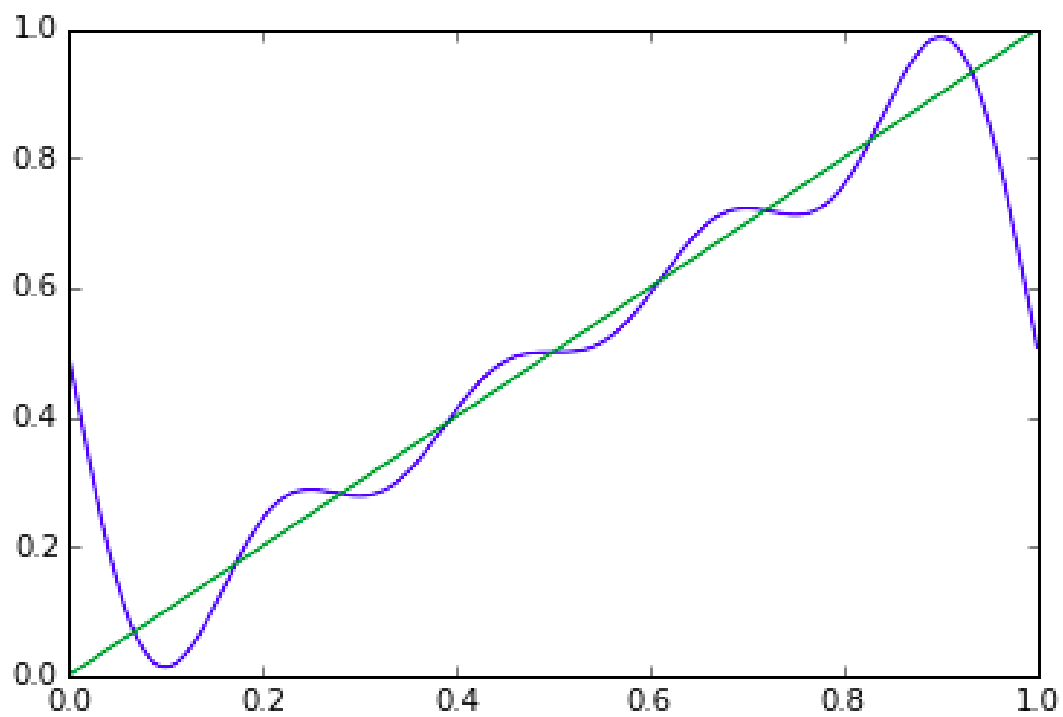


Рис. 3: "Fourier approximation"

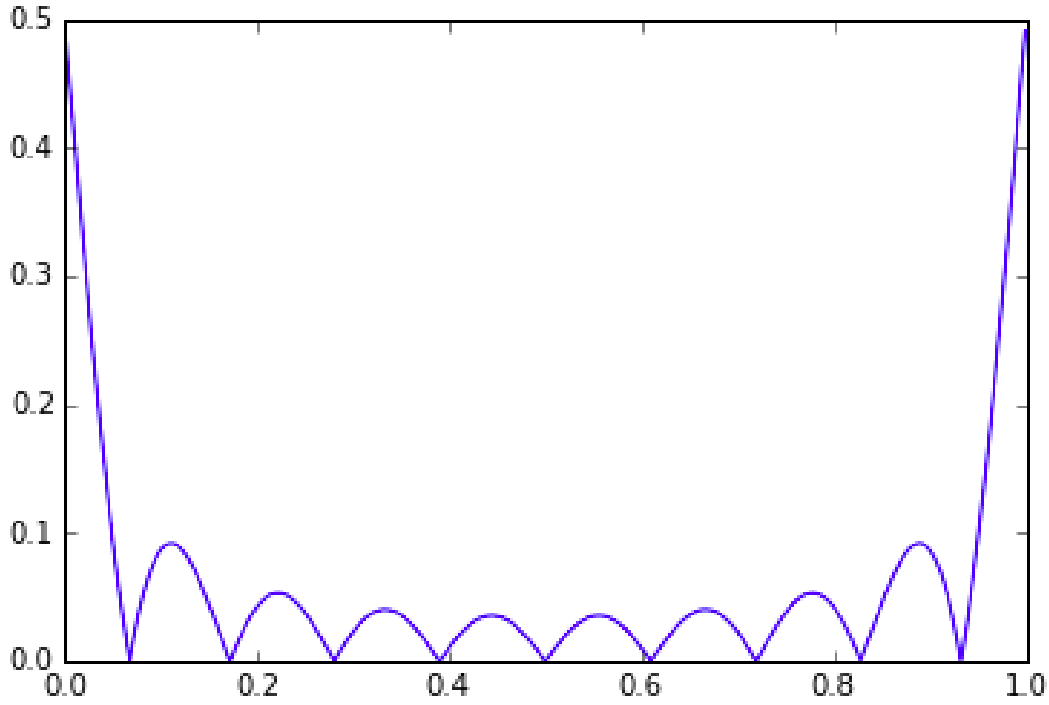


Рис. 4: "Deviation"

Problem 10

(a b) $(a \ b)^T = a^2 + b^2 + 2\lambda ab$ Thus only if $\lambda = 0$ there are no such a and b that can make A not positive definite. Eigenvector of A with $\lambda = 0$ is $(a, b)^T$ for any real a and b.

Problem 11

Finding the characteristic polynomial gives us: $\lambda^3 - 9\lambda^2 - 6\lambda = 0$

Thus $\lambda_1 = 0, \lambda_{2,3} = \frac{9 \pm \sqrt{105}}{2}$

For $\lambda = 0$ eigenvector is $(1 \ -2 \ 1)^T$

For $\lambda = \frac{9 + \sqrt{105}}{2}$ eigenvector is $(\frac{\sqrt{105} - 5}{10} \ \frac{\sqrt{105} + 5}{20} \ 1)^T$

For $\lambda = \frac{9 - \sqrt{105}}{2}$ eigenvector is $(\frac{-\sqrt{105} - 5}{10} \ \frac{-\sqrt{105} + 5}{20} \ 1)^T$

$$\text{Thus } A = \begin{pmatrix} 1 & \frac{\sqrt{105} - 5}{10} & \frac{-\sqrt{105} - 5}{20} \\ -2 & \frac{\sqrt{105} + 5}{20} & \frac{-\sqrt{105} + 5}{20} \\ 1 & \frac{1}{1} & \frac{1}{1} \end{pmatrix}.$$

Now we can represent initial matrix as $A D A^{-1}$. Where D is $\text{diag}(0 \frac{9 + \sqrt{5}}{2} \frac{9 - \sqrt{5}}{2})$

Given matrix cannot be a scalar product because it is not commutative for multiplication.

Problem 12 For M_1 :

$$M = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

$$A = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}.$$

For M_2 :

Its eigenvectors are zero and so it is impossible to diagonalize it.