

Gradient

Let us consider a scalar function of three variables $T(x,y,z)$.

A theorem on partial derivative states that –

$$dT = \left(\frac{\partial T}{\partial x}\right) dx + \left(\frac{\partial T}{\partial y}\right) dy + \left(\frac{\partial T}{\partial z}\right) dz$$

This gives how T changes when we alter all three variables by infinitesimal amounts dx , dy and dz .

Above equation is reminiscent of a dot product –

$$dT = \left(\frac{\partial T}{\partial x} \hat{x} + \frac{\partial T}{\partial y} \hat{y} + \frac{\partial T}{\partial z} \hat{z}\right) \cdot (dx \hat{x} + dy \hat{y} + dz \hat{z}) = \overrightarrow{\nabla T} \cdot \overrightarrow{dl}$$

Where $\overrightarrow{\nabla T} = \frac{\partial T}{\partial x} \hat{x} + \frac{\partial T}{\partial y} \hat{y} + \frac{\partial T}{\partial z} \hat{z}$ is a **gradient of T** .

$\overrightarrow{\nabla T}$ is a vector quantity with three components.

Significance of Gradient

- Like any vector, gradient has a magnitude and direction.

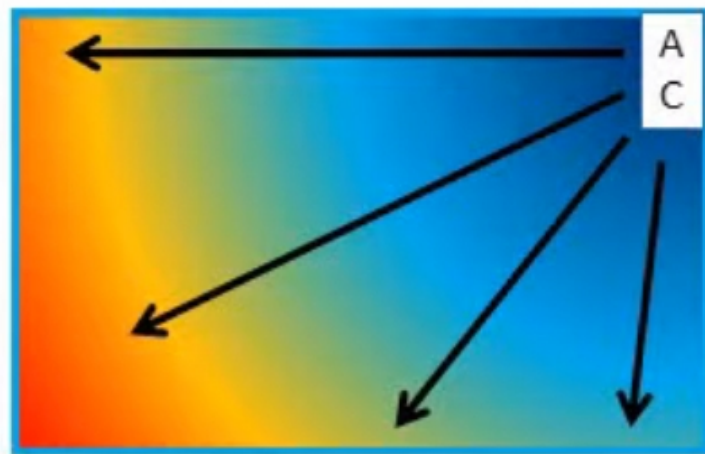
$$dT = \vec{\nabla T} \cdot d\vec{l} = |\vec{\nabla T}| |d\vec{l}| \cos\theta$$

Where θ is angle between $\vec{\nabla T}$ and $d\vec{l}$

- If we fix the magnitude $|d\vec{l}|$ and search in various directions for different values of θ , maximum change in T will occur for $\cos\theta = 1$ i.e. for $\theta = 0$.
- It means that for a fixed distance $|d\vec{l}|$, change in T i.e. dT is maximum in the same direction of $\vec{\nabla T}$.

Thus, the gradient $\vec{\nabla T}$ points in the direction of maximum increase of the function T.

Also, the magnitude $|\vec{\nabla T}|$ gives us the slope (i.e. rate of increase) along this direction.



Find the gradient of $r = \sqrt{x^2 + y^2 + z^2}$ (magnitude of a position vector)

$$\begin{aligned}\vec{\nabla} r &= \frac{\partial r}{\partial x} \hat{x} + \frac{\partial r}{\partial y} \hat{y} + \frac{\partial r}{\partial z} \hat{z} \\&= \frac{\partial(\sqrt{x^2 + y^2 + z^2})}{\partial x} \hat{x} + \frac{\partial(\sqrt{x^2 + y^2 + z^2})}{\partial y} \hat{y} + \frac{\partial(\sqrt{x^2 + y^2 + z^2})}{\partial z} \hat{z} \\&= \frac{1}{2} \frac{2x}{\sqrt{x^2 + y^2 + z^2}} \hat{x} + \frac{1}{2} \frac{2y}{\sqrt{x^2 + y^2 + z^2}} \hat{y} + \frac{1}{2} \frac{2z}{\sqrt{x^2 + y^2 + z^2}} \hat{z} \\&= \frac{x \hat{x} + y \hat{y} + z \hat{z}}{\sqrt{x^2 + y^2 + z^2}} = \frac{\vec{r}}{r} = \hat{r}\end{aligned}$$

Significance : The distance from origin increases most rapidly along the direction of \vec{r} .

Find the gradient of $\phi(x, y, z) = 3x^2y - y^3z^2$ at point $(1, -2, -1)$.

$$\frac{\partial \phi}{\partial x} = \frac{\partial(3x^2y - y^3z^2)}{\partial x} = 6xy$$

$$\frac{\partial \phi}{\partial y} = \frac{\partial(3x^2y - y^3z^2)}{\partial y} = 3x^2 - 3y^2z^2$$

$$\frac{\partial \phi}{\partial z} = \frac{\partial(3x^2y - y^3z^2)}{\partial z} = -2y^3z$$

$$\overrightarrow{\nabla \phi} = \frac{\partial \phi}{\partial x} \hat{x} + \frac{\partial \phi}{\partial y} \hat{y} + \frac{\partial \phi}{\partial z} \hat{z}$$

$$= (6xy) \hat{x} + (3x^2 - 3y^2z^2) \hat{y} - (2y^3z) \hat{z}$$

$$\begin{aligned} \therefore \overrightarrow{\nabla \phi} \Big|_{(1, -2, -1)} &= 6(1)(-2) \hat{x} + (3(1)^2 - 3(-2)^2(-1)^2) \hat{y} - 2(-2)^3(-1) \hat{z} \\ &= -12 \hat{x} - 9 \hat{y} - 16 \hat{z} \end{aligned}$$

The operator $\vec{\nabla}$ (del operator)

The gradient has a formal appearance of a operator $\vec{\nabla}$ acting on a scalar T .

$$\vec{\nabla}T = \frac{\partial T}{\partial x}\hat{x} + \frac{\partial T}{\partial y}\hat{y} + \frac{\partial T}{\partial z}\hat{z} \quad \text{i.e.} \quad \vec{\nabla}T = \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) T$$

Here, $\vec{\nabla} = \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right)$ is called as 'del'.

- This 'del' is not a vector.
- It does not multiply a function; rather it is an instruction to differentiate what follows.
- It does not have any meaning until we provide it with a function to act upon.
- To be precise, $\vec{\nabla}$ is not a vector that multiplies T . $\vec{\nabla}$ is a vector operator that acts on T .

The operator $\vec{\nabla}$ can act in three ways –

- On a scalar function T –

i.e. $\vec{\nabla}T$ (the gradient)

- On a vector function \vec{v} via dot product –

$\vec{\nabla} \cdot \vec{v}$ (the divergence)

- On a vector function \vec{v} via cross product –

$\vec{\nabla} \times \vec{v}$ (the curl)

The Divergence

- When the operator $\vec{\nabla}$ act on a vector function \vec{v} , via dot product, we get divergence of a vector function \vec{v} .

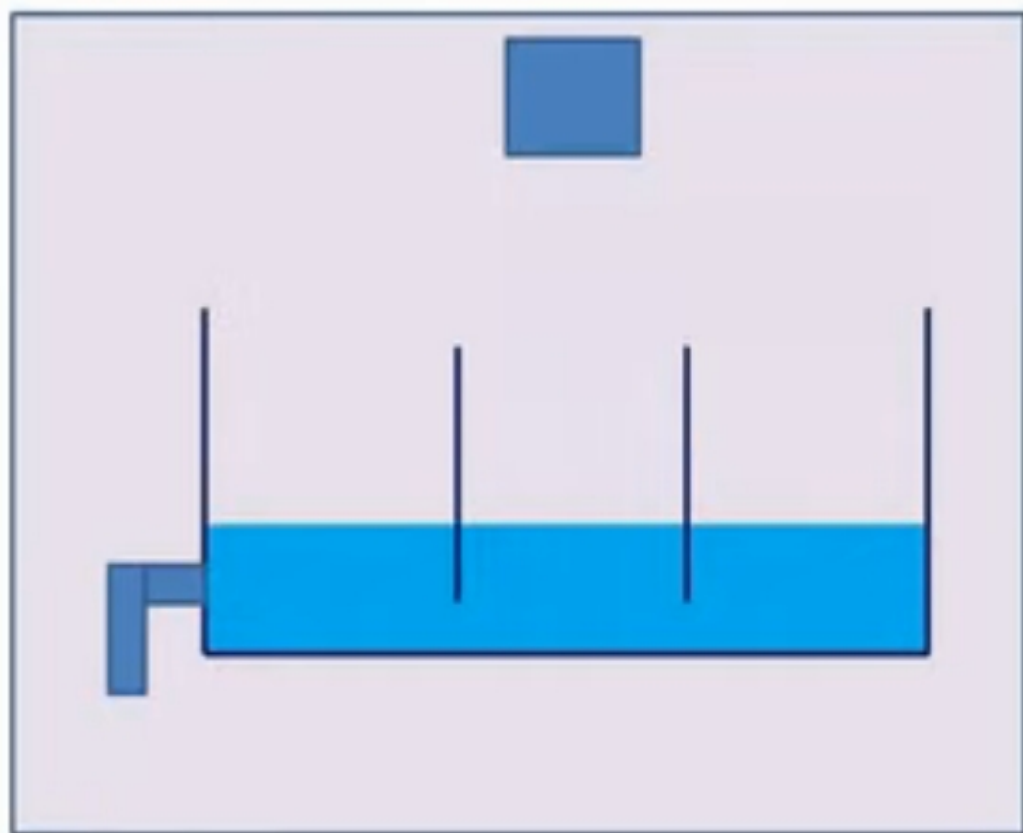
$$\vec{\nabla} \cdot \vec{v} = \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \cdot (v_x \hat{x} + v_y \hat{y} + v_z \hat{z})$$
$$\vec{\nabla} \cdot \vec{v} = \left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \right)$$

- The divergence of a vector function is a scalar. The divergence of a scalar function can not be written and it is meaningless.

Significance of divergence :

Divergence $\vec{\nabla} \cdot \vec{v}$ is a measure of how much the vector \vec{v} spreads out (diverges) from the given point.

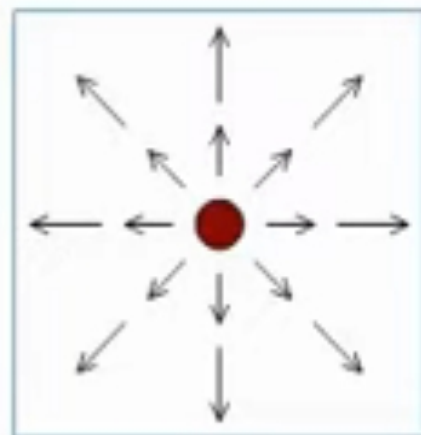
The Divergence



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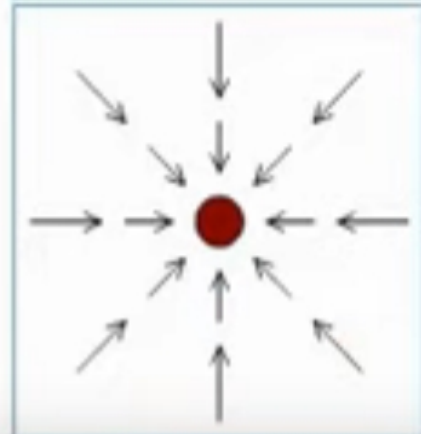


$$\vec{v} = x \hat{x} + y \hat{y} + z \hat{z}$$

This vector function has a large positive divergence.

$$\vec{\nabla} \cdot \vec{v} = \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \cdot (x \hat{x} + y \hat{y} + z \hat{z})$$

$$\vec{\nabla} \cdot \vec{v} = \left(\frac{\partial x}{\partial x} + \frac{\partial y}{\partial y} + \frac{\partial z}{\partial z} \right) = 1 + 1 + 1 = 3$$



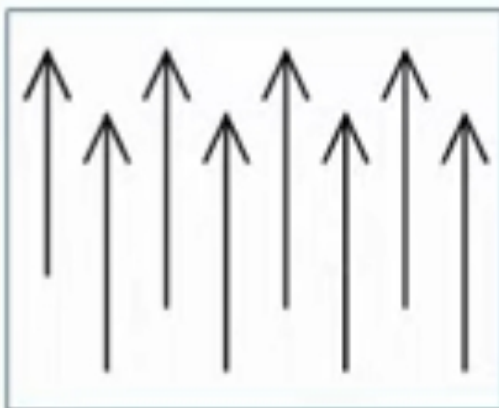
$$\vec{v} = -x \hat{x} - y \hat{y} - z \hat{z}$$

This vector function has large negative divergence

$$\vec{\nabla} \cdot \vec{v} = \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \cdot (-x \hat{x} - y \hat{y} - z \hat{z})$$

$$\vec{\nabla} \cdot \vec{v} = \left(\frac{\partial(-x)}{\partial x} + \frac{\partial(-y)}{\partial y} + \frac{\partial(-z)}{\partial z} \right) = -1 - 1 - 1 = -3$$

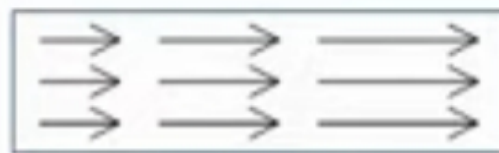
The Divergence



$\vec{v} = K \hat{z}$
K is constant.
This vector has
zero divergence

$$\vec{\nabla} \cdot \vec{v} = \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \cdot (0\hat{x} + 0\hat{y} + K\hat{z})$$

$$\vec{\nabla} \cdot \vec{v} = \left(\frac{\partial 0}{\partial x} + \frac{\partial 0}{\partial y} + \frac{\partial K}{\partial z} \right) \\ = 0 + 0 + 0 = 0$$



$\vec{v} = y \hat{y}$
This vector has
positive
divergence.

$$\vec{\nabla} \cdot \vec{v} = \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \cdot (0\hat{x} + y\hat{y} + 0\hat{z})$$

$$\vec{\nabla} \cdot \vec{v} = \left(\frac{\partial 0}{\partial x} + \frac{\partial y}{\partial y} + \frac{\partial 0}{\partial z} \right) \\ = 0 + 1 + 0 = 1$$

If $\vec{v}_A = x \hat{x} + y \hat{y} + z \hat{z}$ and $\vec{v}_B = y \hat{y}$, calculate their divergence.

$$\vec{\nabla} \cdot \vec{v}_A = \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \cdot (x \hat{x} + y \hat{y} + z \hat{z})$$

$$\vec{\nabla} \cdot \vec{v}_A = \left(\frac{\partial x}{\partial x} + \frac{\partial y}{\partial y} + \frac{\partial z}{\partial z} \right) = 1 + 1 + 1 = 3$$

$$\vec{\nabla} \cdot \vec{v}_B = \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \cdot (y \hat{y})$$

$$\vec{\nabla} \cdot \vec{v}_B = \left(\frac{\partial 0}{\partial x} + \frac{\partial y}{\partial y} + \frac{\partial 0}{\partial z} \right) = 0 + 1 + 0 = 1$$

If $\vec{v} = 1 \hat{x} + 2 \hat{y} + 3 \hat{z}$, find divergence of \vec{v} .

$$\vec{\nabla} \cdot \vec{v} = \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \cdot (1\hat{x} + 2\hat{y} + 3\hat{z})$$

$$\vec{\nabla} \cdot \vec{v} = \left(\frac{\partial(1)}{\partial x} + \frac{\partial(2)}{\partial y} + \frac{\partial(3)}{\partial z} \right)$$

$$= 0 + 0 + 0 = 0$$

If $\vec{A} = x^2z \hat{x} - 2y^2z^2 \hat{y} + xy^2z \hat{z}$, Find $\vec{\nabla} \cdot \vec{A}$ at point (1,-1,1)

$$\vec{\nabla} \cdot \vec{A} = \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \cdot (x^2z \hat{x} - 2y^2z^2 \hat{y} + xy^2z \hat{z})$$

$$\begin{aligned} \vec{\nabla} \cdot \vec{A} &= \left(\frac{\partial(x^2z)}{\partial x} + \frac{\partial(-2y^2z^2)}{\partial y} + \frac{\partial(xy^2z)}{\partial z} \right) \\ &= 2xz - 4yz^2 + xy^2 \end{aligned}$$

$$\begin{aligned} \vec{\nabla} \cdot \vec{A} \Big|_{(1,-1,1)} &= 2(1)(1) - 4(-1)(1)^2 + (1)(-1)^2 \\ &= 2 + 4 + 1 = 7 \end{aligned}$$

The Curl

When the operator $\vec{\nabla}$ act on a vector function \vec{v} via cross product, we get curl of a vector function \vec{v} .

$$\vec{\nabla} \times \vec{v} = \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \times (v_x \hat{x} + v_y \hat{y} + v_z \hat{z})$$

$$\vec{\nabla} \times \vec{v} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix}$$

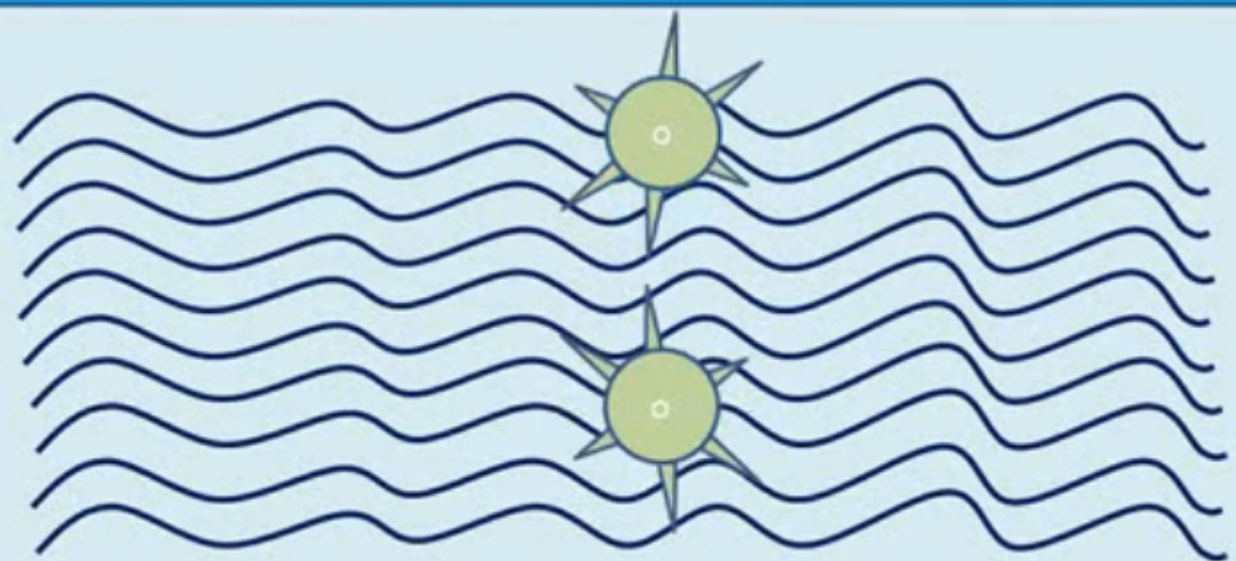
$$\vec{\nabla} \times \vec{v} = \hat{x} \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) + \hat{y} \left(\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) + \hat{z} \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right)$$

Significance of the curl

$\vec{\nabla} \times \vec{v}$ is a measure of how much the vector \vec{v} curls around the given point. Zero curl means there is no rotation.

The curl of a vector function is a vector.

The Curl



Significance of the curl

$\vec{\nabla} \times \vec{v}$ is a measure of how much the vector \vec{v} curls around the given point. Zero curl means there is no rotation.

If $\vec{v} = x \hat{x} + y \hat{y} + z \hat{z}$, calculate its curl.

$$\vec{\nabla} \times \vec{v} = \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \times (x \hat{x} + y \hat{y} + z \hat{z})$$

$$\vec{\nabla} \times \vec{v} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & y & z \end{vmatrix}$$

$$\vec{\nabla} \times \vec{v} = \hat{x} \left(\frac{\partial z}{\partial y} - \frac{\partial y}{\partial z} \right) + \hat{y} \left(\frac{\partial x}{\partial z} - \frac{\partial z}{\partial x} \right) + \hat{z} \left(\frac{\partial y}{\partial x} - \frac{\partial x}{\partial y} \right)$$

$$= 0 + 0 + 0 = 0$$

Calculate curl of \vec{v} if $\vec{v} = -y\hat{x} + x\hat{y}$.

$$\vec{\nabla} \times \vec{v} = \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \times (-y \hat{x} + x \hat{y} + 0 \hat{z})$$

$$\vec{\nabla} \times \vec{v} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -y & x & 0 \end{vmatrix}$$

$$\vec{\nabla} \times \vec{v} = \hat{x} \left(\frac{\partial(0)}{\partial y} - \frac{\partial(x)}{\partial z} \right) + \hat{y} \left(\frac{\partial(-y)}{\partial z} - \frac{\partial(0)}{\partial x} \right) + \hat{z} \left(\frac{\partial(x)}{\partial x} - \frac{\partial(-y)}{\partial y} \right)$$

$$\vec{\nabla} \times \vec{v} = \hat{x}(0) + \hat{y}(0) + \hat{z}(1 - (-1)) = 2\hat{z}$$

Show that divergence of a curl is zero.

Let us consider $\vec{v} = v_x \hat{x} + v_y \hat{y} + v_z \hat{z}$.

Curl of \vec{v} is given by -
$$\vec{\nabla} \times \vec{v} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix}$$

$$\vec{\nabla} \times \vec{v} = \hat{x} \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) + \hat{y} \left(\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) + \hat{z} \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right)$$

Divergence of Curl of \vec{v} is given by -

$$\begin{aligned} \vec{\nabla} \cdot (\vec{\nabla} \times \vec{v}) &= \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \cdot \left(\hat{x} \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) + \hat{y} \left(\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) + \hat{z} \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right) \right) \\ &= \frac{\partial}{\partial x} \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) + \frac{\partial}{\partial y} \left(\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) + \frac{\partial}{\partial z} \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right) \\ &= \left(\frac{\partial^2 v_z}{\partial x \partial y} - \frac{\partial^2 v_y}{\partial x \partial z} \right) + \left(\frac{\partial^2 v_x}{\partial y \partial z} - \frac{\partial^2 v_z}{\partial y \partial x} \right) + \left(\frac{\partial^2 v_y}{\partial z \partial x} - \frac{\partial^2 v_x}{\partial z \partial y} \right) = 0 \end{aligned}$$

Thus divergence of a curl is zero.

Gauss Theorem (Divergence theorem)

Gauss Theorem States that – If V is the volume bound by the surface S , volume integral of divergence of a function $\vec{\nabla}$ over volume V is equal to surface integral of the function \vec{v} over the surface S that surrounds the given volume.

$$\int_V \vec{\nabla} \cdot \vec{v} \, dv = \oint_S \vec{v} \cdot \vec{ds}$$

Stoke's Theorem (Fundamental Theorem for Curl)

Stokes Theorem States that – If S is the surface area bound by the boundary P , surface integral of curl of a vector function \vec{v} over surface area S is equal to line integral of the vector function \vec{v} over the closed curve P bounding that surface.

$$\int_S (\vec{\nabla} \times \vec{v}) \cdot d\vec{s} = \oint_P \vec{v} \cdot d\vec{l}$$