

# CS380L: Advanced Operating Systems Lab #0

Zeyuan Hu <sup>1</sup>, iamzeyuanhu@utexas.edu

EID:zh4378 Spring 2019

## 1 Introduction

In this writeup, we demonstrate the steps to compile and boot the Linux kernel on the KVM-qemu virtual machine. We time the OS bootup time using both timer and RTC, real-time clock in Linux and explain the value difference using the difference between system time and RTC. We also trace the kernel during the execution of a test program `testprog` and we explain the difference between `/dev/random` and `/dev/urandom`.

## 2 Environment

We use a machine that has 2 Intel(R) Core(TM)2 Duo CPU @ 3.00GHz processors and 8GB of memory. The machine runs Ubuntu 18.04.1 LTS (kernel version 4.15.0-43-generic).

KVM is enabled on the machine, and we use QEMU (version 2.11.1) <sup>2</sup> to create and run a VM for the lab. The VM runs a Ubuntu 18.04 LTS with the kernel we built (version 4.20.4).

## 3 Getting a VM running in KVM

We use the Ubuntu cloud image to setup the VM. The image for QEMU can be downloaded from <https://cloud-images.ubuntu.com/releases/18.04/release/ubuntu-18.04-server-cloudimg-amd64.img>. We use the cloud image instead of the regular desktop image to save space (e.g., We do not need to have GUI installed).

Ubuntu cloud image needs additional metadata to boot (mainly containing the login password). The metadata can be provided via a seed image [1]. To create a seed image, we first create a file `my-user-data` with contents:

```
#cloud-config
```

---

<sup>1</sup>20 hours spent on this lab.

<sup>2</sup>`qemu-system-x86_64 --version`

```
password: passw0rd
chpasswd: { expire: False }
ssh_pwauth: True
```

Then we create the seed image by running:

```
sudo apt-get install cloud-utils
cloud-localds my-seed.img my-user-data
```

We then use the downloaded Ubuntu cloud image to create root disk image for the VM<sup>3</sup>.

```
qemu-img create -f qcow2 \
-b ubuntu-18.04-server-cloudimg-amd64-disk1.img \
my-disk.img 15G
```

Now, we are ready to boot up our VM:

```
qemu-system-x86_64 \
-enable-kvm -curses \
-m 512 -smp 4 -redir tcp:4444::22 \
-hda my-disk.img -hdb my-seed.img \
-cpu host
```

This will start a VM with 4 CPU cores and 512MB of memory. We redirect port 4444 of local machine to port 22 of the VM in order to login the VM via SSH. The VM will run in the terminal, and login with user name `ubuntu` and `passw0rd` set in `my-user-data`. The login screen of VM is shown in Figure 1. Once we have our VM boot up, we can remote access it via SSH from host `ssh -p 4444 ubuntu@localhost`.

## 4 Obtaining and building the kernel

We first obtain the Linux Kernel source via `wget https://cdn.kernel.org/pub/linux/kernel/v4.x/linux-4.20.4.tar.xz`. Then, we extract the files using `tar -xJf linux-4.20.4.tar.xz`. We make a new directory `kbuild` as the build directory for kernel and

---

<sup>3</sup>The default virtual size is 2G, we can resize the image via `qemu-img resize my-disk.img +10G`. We add additional 10G in this case.

```
ubuntu login: ubuntu
Password:
Last login: Fri Jan 25 22:13:51 UTC 2019 from 10.0.2.2 on pts/0
Welcome to Ubuntu 18.04.1 LTS (GNU/Linux 4.15.0-43-generic x86_64)

 * Documentation:  https://help.ubuntu.com
 * Management:    https://landscape.canonical.com
 * Support:       https://ubuntu.com/advantage

System information as of Fri Jan 25 22:15:57 UTC 2019

System load: 0.17          Processes:            116
Usage of /:  6.7% of 14.37GB Users logged in:      1
Memory usage: 30%          IP address for ens3: 10.0.2.15
Swap usage:  0%

Get cloud support with Ubuntu Advantage Cloud Guest:
http://www.ubuntu.com/business/services/cloud

0 packages can be updated.
0 updates are security updates.

ubuntu@ubuntu:~$ █
```

Figure 1: Login screen of our VM

`cd kbuild`, we generate `.config` file using `yes "" | make -C ../linux-4.20.4/ O=$(pwd)x86_64_defconfig`. Note that generating the `.config` file like this automatically set `CONFIG_SATA_AHCI=y`<sup>4</sup>. We run `make -j4`<sup>5</sup> to build the kernel.

## 5 Installing and Copying Kernel Modules

We install the newly-built kernel by first making a new directory called `kinstall` as a sibling of `kbuild`. `kinstall` will contain the built kernel modules. Inside `kbuild`, we run `make INSTALL_MOD_PATH=../kinstall modules_install`.

We can see `lib` directory inside `kinstall`, which has to be copied to the root file system of the VM. We notice there are two symbolic links `build` and `source` inside `kinstall/lib/modules/4.20.4`, which links to the built kernel image and the source of the kernel. They are useless and may cause problems when copying files to the VM. Thus we just delete them. Next, we copy the entire `4.20.4` directory to `/lib/modules` in the guest system by doing `scp -P 4444 -r 4.20.4/ ubuntu@localhost:/home/ubuntu` and inside the guest system, do `sudo mv 4.20.4/ /lib/modules/`.

---

<sup>4</sup>We also disable `CONFIG_RETPOLINE` in `.config` since our compiler is not retpoline-capable.

<sup>5</sup>`-j4` means 4 threads are used, which can speed up the build process

```
ubuntu@ubuntu:~$ uname -a
Linux ubuntu 4.20.4 #1 SMP Fri Jan 25 17:02:21 CST 2019 x86_64 x86_64 x86_64 GNU
/Linux
ubuntu@ubuntu:~$ █
```

Figure 2: VM with our newly-built kernel

## 6 Booting KVM with your new Kernel

We can now start VM with our own Linux kernel. The shell command we run now:

```
qemu-system-x86_64 \
-enable-kvm -curses \
-m 512 -smp 4 -redir tcp:4444::22 \
-hda my-disk.img -hdb my-seed.img \
-kernel ~/3801-lab0/kbuild/arch/x86_64/boot/bzImage \
-append "root=/dev/sda1" \
-cpu host
```

Note that we append two new options `-kernel` and `-append` to QEMU. `-kernel` option tells the location of the kernel to use, and `-append` option suggests the parameters to start the kernel. The `root` parameter suggests the disk partition used as root file system. After login, use `uname -a` to check the kernel version string, which is shown in Figure 2.

## 7 Booting, kernel modules, and discovering devices

The wall clock time (tracked using a stopwatch) for our boot takes 34.08 seconds while the time reported by the Kernel takes 28.81 seconds. This difference may be due to the human delay on stopping the stopwatch and also due to a disagreement between human and OS on how to define boot finish status. Here, we stop our stopwatch when we see the login prompt but the last line of `dmesg`<sup>6</sup> shows:

---

<sup>6</sup>`dmesg` is used to inspect the kernel ring buffer, which contains the system log during kernel boot.

```
[ 28.811823] new mount options do not match the existing superblock, will  
be ignored
```

To eliminate the potential human error, we use real-time clock in Linux system to time the difference between the wall clock time and the time reported by Kernel.

```
$ dmesg -T | grep "RTC time"
```

```
[Fri Jan 25 23:54:33 2019] RTC time: 23:54:32, date: 01/25/19
```

RTC stands for “real-time clocks”<sup>7</sup>. We find that the time reported by Kernel is 1 second slower than the real-time clock at that moment. “RTC vs system clock” section in `man rtc` explains possible root cause for this 1 second difference: when the system is in a low power state, only RTC work not the system clock. The system clock is maintained by kernel implemented as counting of timer interrupts and the system clock will set to the wall clock time once the system boots and out of low power state. Thus, one possible explanation of the 1 second difference is due to the slower frequency of timer interrupts and another possible explanation is because the system clock has not aligned well with the wall clock time yet.

We also inspect the discovery of PCI devices at boot time from the boot log. We use the command `lspci` and there are 6 PCI devices in the VM:

```
$ lspci  
00:00.0 Host bridge: Intel Corporation 440FX - 82441FX PMC [Natomia] (rev  
02)  
00:01.0 ISA bridge: Intel Corporation 82371SB PIIX3 ISA [Natomia/Triton II]  
00:01.1 IDE interface: Intel Corporation 82371SB PIIX3 IDE [Natomia/Triton  
II]  
00:01.3 Bridge: Intel Corporation 82371AB/EB/MB PIIX4 ACPI (rev 03)  
00:02.0 VGA compatible controller: Device 1234:1111 (rev 02)  
00:03.0 Ethernet controller: Intel Corporation 82540EM Gigabit Ethernet  
Controller (rev 03)
```

We can search the boot log with the pattern of `0000:ID` (e.g., `0000:00:00.0`) from `lspci` to learn how the kernel discovers and identifies these devices during the boot process and the log message helps us to decide what kind of the device is.

---

<sup>7</sup>definition of RTC can be found via `man rtc`

```

$ dmesg | grep "0000:00:00.0"
[ 0.244811] pci 0000:00:00.0: [8086:1237] type 00 class 0x060000
[ 0.579080] pci 0000:00:00.0: Limiting direct PCI/PCI transfers

$ dmesg | grep "0000:00:01.0"
[ 0.245549] pci 0000:00:01.0: [8086:7000] type 00 class 0x060100
[ 0.578484] pci 0000:00:01.0: PIIX3: Enabling Passive Release
[ 0.586375] pci 0000:00:01.0: Activating ISA DMA hang workarounds

$ dmesg | grep "0000:00:01.1"
[ 0.246566] pci 0000:00:01.1: [8086:7010] type 00 class 0x010180
[ 0.250524] pci 0000:00:01.1: reg 0x20: [io 0xc040-0xc04f]
[ 0.252018] pci 0000:00:01.1: legacy IDE quirk: reg 0x10: [io 0x01f0-0x01f7
    ]
<-- snip -->

$ dmesg | grep "0000:00:01.3"
[ 0.256256] pci 0000:00:01.3: [8086:7113] type 00 class 0x068000
[ 0.257044] pci 0000:00:01.3: quirk: [io 0x0600-0x063f] claimed by PIIX4
    ACPI
[ 0.257208] pci 0000:00:01.3: quirk: [io 0x0700-0x070f] claimed by PIIX4
    SMB

$ dmesg | grep "0000:00:02.0"
[ 0.258317] pci 0000:00:02.0: [1234:1111] type 00 class 0x030000
[ 0.259810] pci 0000:00:02.0: reg 0x10: [mem 0xfd000000-0xfdffffff pref]
[ 0.262214] pci 0000:00:02.0: reg 0x18: [mem 0xfebb0000-0xfebb0fff]
<-- snip -->

$ dmesg | grep "0000:00:03.0"
[ 0.267327] pci 0000:00:03.0: [8086:100e] type 00 class 0x020000
[ 0.268194] pci 0000:00:03.0: reg 0x10: [mem 0xfeb80000-0xfeb9ffff]

```

```
[ 0.268973] pci 0000:00:03.0: reg 0x14: [io 0xc000-0xc03f]
<-- snip -->
```

## 8 Tracing the kernel

### 8.1 Make a debug build

To trace the kernel, we need to make a debug build of the kernel by modifying several debug options. Make a new directory `debug_bld2` for holding the debug build. In the created directory, run

```
make -C ../linux-4.20.4 O=$(pwd) x86_64_defconfig
make -C ../linux-4.20.4 O=$(pwd) kvmconfig
make -C ../linux-4.20.4 O=$(pwd) menuconfig
```

The last command will bring up a configuration menu and we change the options as follow [2]:

- Kernel hacking
  - Compile-time checks and compiler options
    - \* Compile the kernel with debug info (check this)
      - Generate dwarf4 debuginfo (check this)
      - Provide GDB scripts for kernel debugging (check this)
  - KGDB: kernel debugger (check this)
- General setup
  - Configure standard kernel features (expert users) (check this)
- Processor type and features
  - Build a relocatable kernel (uncheck this)

We also want to explicit set `CONFIG_DEBUG_INFO_REDUCED=n` explicitly in `.config` of `debug_bld2`. Then we compile the kernel `make -j16` and start the VM as

```

zeyuanhu @ HotDog(ubuntu) ~/3801-lab0/debug_bld2
Thu Jan 31 17:39:17 $ gdb vmlinux
GNU gdb (Ubuntu 8.1-0ubuntu3) 8.1.0.20180409-git
Copyright (C) 2018 Free Software Foundation, Inc.
License GPLv3+: GNU GPL version 3 or later <http://gnu.org/licenses/gpl.html>
This is free software: you are free to change and redistribute it.
There is NO WARRANTY, to the extent permitted by law. Type "show copying"
and "show warranty" for details.
This GDB was configured as "x86_64-linux-gnu".
Type "show configuration" for configuration details.
For bug reporting instructions, please see:
<http://www.gnu.org/software/gdb/bugs/>.
Find the GDB manual and other documentation resources online at:
<http://www.gnu.org/software/gdb/documentation/>.
For help, type "help".
Type "apropos word" to search for commands related to "word"...
Reading symbols from vmlinux...done.
(gdb) target remote :1234
Remote debugging using :1234
default_idle 0 at /home/zeyuanhu/3801-lab0/linux-4.20.4/arch/x86/kernel/process.c:562
562         trace_cpu_idle_rcuidle(PWR_EVENT_EXIT, smp_processor_id());

```

Figure 3: Fire up GDB and be ready to debug kernel

```

sudo qemu-system-x86_64 -enable-kvm -nographic -m 512 -smp 4 -redir tcp
:4444::22 -s -hda my-disk.img -hdb my-seed.img -kernel ~/3801-lab0/
debug_bld2/arch/x86_64/boot/bzImage -append "root=/dev/sda1" -cpu hos

```

Note that we add an option `-s`, which tells QEMU to start a GDB server on port 1234 for debugging [3]<sup>8</sup>. We can start GDB in `debug_bld2` directory via `gdb vmlinux`, and type `target remote :1234` to connect gdb to the kgdb server in the guest system. Figure 3 shows a screenshot of the GDB that is ready to debug the kernel.

## 8.2 Tracing the kernel

Next, we create a program `testprog.c` on the guest system like the following<sup>9</sup>:

```

1 #include<unistd.h>
2 #include<fcntl.h>
3 int main()
4 {
5     int fd = open("/dev/urandom", O_RDONLY);
6     char data[4096];
7     read(fd, &data, 4096);
8     close(fd);

```

<sup>8</sup>We also use `-nographic` instead of `-curses` because we find out that typing `./testprog` can be quite sluggish on the guest system (due to the constant checking of the breakpoint) and using `-nographic` instead of `-curses` to boot up the VM and login the VM via SSH helps to alleviate this effect.

<sup>9</sup>We modify the program by appending extra line `while (1){}`. Doing so make sure that the breakpoint will be hit eventually when the program is being executed (since the program is non-terminal). Since the program is fairly short and the execution is very quick. If we do not add this line, sometimes the program will finish execution without the breakpoint getting hit and that hurts reproducibility



```

9  fd = open("/dev/null", O_WRONLY);
10 write(fd, &data, 4096);
11 close(fd);
12 while (1) {}
13 }

```

Compile it with gcc: `gcc -o testprog -g testprog.c`. Now, we want to trace into the kernel when the process contains `testprog` is running<sup>10</sup>. To do so, we set a conditional breakpoint in `spin_lock` in kernel code that will only stop execution if the above process is running. `spin_lock` is an inline Macro and the actual symbol name is `__raw_spin_lock`, which is defined in `include/linux/spinlock_api_smp.h`. To ensure the breakpoint only be triggered during the execution of `testprog`, we have to add a condition to the breakpoint. We use the helper script provided by kernel to figure out the PID of `testprog`. We achieve so via `$!x_current()`, which reads `task_struct` of current task in GDB and `task_struct` contains all the information we need to identify the current proces. Specifically, `$!x_current().pid` gives the PID of the current running process and `$!x_current().comm` gives the command line content, which we will use it to identify the process.

The command we run is the following, where 2297 is the pid of the program.<sup>11</sup>

```
b __raw_spin_lock if $!x_current().pid == 2297
```

Figure 4 shows the result of `testprog` hits the breakpoint. From the figure we can see that `$!x_current().pid` gives 2297 and `$!x_current().comm` gives "`testprog\000\000\000\000\000\000\000\000`", which confirm that we are in `testprog` process when we hit `spin_lock` breakpoint. Then, we use `bt` to examine the call stack.

The kernel backtrace of the first instance we find looks like below:

```

#0 __raw_spin_lock (lock=0xffff88801f2a0a80) at /home/zeyuanhu/3801-lab0/
    linux-4.20.4/kernel/locking/spinlock.c:144
#1 0xffffffff8108cbf7 in rq_lock (rf=<optimized out>, rq=<optimized out>)
    at /home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/sched/sched.h:1124

```

<sup>10</sup>We first run `target remote :1234` and then we setup the breakpoint. Afterward, we issue `continue` in the GDB so that we can run `testprog` on the guest system.

<sup>11</sup>Alternatively, we can `b __raw_spin_lock if $!streq($!x_current().comm, "testprog")`. This command directly compares the process name with the target program, which has more overhead than comparing process id. This is quite noticeable for a frequently-used function like spin lock in this case and for a machine with less powerful CPU. The detailed steps of using the comparing-process-id approach can be found in Appendix.

```

Thread 2 hit Breakpoint 1, __raw_spin_lock (lock=0xffff88801f2a0a80) at /home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/locking/spinlock.c:144
144      __raw_spin_lock(lock);
(gdb) bt
#0 __raw_spin_lock (lock=0xffff88801f2a0a80) at /home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/locking/spinlock.c:144
#1 0xffffffff8108cbf7 in rq_lock (rf=<optimized out>, rq=<optimized out>) at /home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/sched/sched.h:1124
#2 scheduler_tick () at /home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/sched/core.c:3045
#3 0xffffffff810ceb0b in update_process_times (user_tick=0) at /home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/time/timer.c:1641
#4 0xffffffff810dea7f in tick_sched_handle (ts=<optimized out>, regs=<optimized out>) at /home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/time/tick-sched.c:164
#5 0xffffffff810debc2 in tick_sched_timer (timer=0xffff88801f29bfc0) at /home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/time/tick-sched.c:1274
#6 0xffffffff810cf6d3 in __run_hrtimer (flags=<optimized out>, now=<optimized out>, timer=<optimized out>, base=<optimized out>, cpu_base=<optimized out>) at
/home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/time/hrtimer.c:1398
#7 __hrtimer_run_queues (cpu_base=0xffff88801f29ba80, now=<optimized out>, flags=<optimized out>, active_mask=<optimized out>) at /home/zeyuanhu/3801-lab0/li
nux-4.20.4/kernel/time/hrtimer.c:1460
#8 0xffffffff810cfe10 in hrtimer_interrupt (dev=<optimized out>) at /home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/time/hrtimer.c:1518
#9 0xffffffff810e1d in local_apic_timer_interrupt () at /home/zeyuanhu/3801-lab0/linux-4.20.4/arch/x86/kernel/apic/apic.c:1034
#10 smp_apic_timer_interrupt (regs=<optimized out>) at /home/zeyuanhu/3801-lab0/linux-4.20.4/arch/x86/kernel/apic/apic.c:1059
#11 0xffffffff81c0152f in apic_timer_interrupt () at /home/zeyuanhu/3801-lab0/linux-4.20.4/arch/x86/entry/entry_64.S:807
#12 0xffffc900004bb0c9 in ?? ()
#13 0x0000000000000000 in ?? ()
(gdb) i b
Num      Type          Disp Enb Address              What
1        breakpoint    keep y   0xffffffff81a34b30 in __raw_spin_lock at /home/zeyuanhu/3801-lab0/linux-4.20.4/arch/x86/include/asm/atomic.h:200
stop only if $lx_current().pid == 2297
breakpoint already hit 2 times
(gdb) p $lx_current().pid
$1 = 2297
(gdb) p $lx_current().comm
$2 = "testprog\000\000\000\000\000\000\000\000"
(gdb)

```

Figure 4: testprog hits breakpoint

```

#2 scheduler_tick () at /home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/sched/
    core.c:3045
#3 0xffffffff810ceb0b in update_process_times (user_tick=0) at /home/
    zeyuanhu/3801-lab0/linux-4.20.4/kernel/time/timer.c:1641
#4 0xffffffff810dea7f in tick_sched_handle (ts=<optimized out>, regs=<
    optimized out>) at /home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/time/
    tick-sched.c:164
#5 0xffffffff810debc2 in tick_sched_timer (timer=0xffff88801f29bfc0) at /
    home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/time/tick-sched.c:1274
#6 0xffffffff810cf6d3 in __run_hrtimer (flags=<optimized out>, now=<
    optimized out>, timer=<optimized out>, base=<optimized out>, cpu_base=<
    optimized out>) at /home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/time/
    hrtimer.c:1398
#7 __hrtimer_run_queues (cpu_base=0xffff88801f29ba80, now=<optimized out>,
    flags=<optimized out>, active_mask=<optimized out>) at /home/zeyuanhu
    /3801-lab0/linux-4.20.4/kernel/time/hrtimer.c:1460
#8 0xffffffff810cfe10 in hrtimer_interrupt (dev=<optimized out>) at /home/
    zeyuanhu/3801-lab0/linux-4.20.4/kernel/time/hrtimer.c:1518

```

```

#9 0xffffffff81c01e1d in local_apic_timer_interrupt () at /home/zeyuanhu
    /3801-lab0/linux-4.20.4/arch/x86/kernel/apic/apic.c:1034
#10 smp_apic_timer_interrupt (regs=<optimized out>) at /home/zeyuanhu/3801-
    lab0/linux-4.20.4/arch/x86/kernel/apic/apic.c:1059
#11 0xffffffff81c0152f in apic_timer_interrupt () at /home/zeyuanhu/3801-
    lab0/linux-4.20.4/arch/x86/entry/entry_64.S:807
<-- snip -->

```

Here, the kernel acquires a lock on the run queue and charge one tick to the current process (`update_process_time`). Then, the kernel runs handler for the timer interrupt. If we take a look at function `hrtimer_interrupt` in `kernel/time/hrtimer.c`, we know the `hrtimer_bases`, a per-CPU variable [4], acquired a lock <sup>12</sup>.

The second instance that we take a look at is the following:

```

#0 _raw_spin_lock (lock=0xffff88801f2a0a80) at /home/zeyuanhu/3801-lab0/
    linux-4.20.4/kernel/locking/spinlock.c:144
#1 0xffffffff8108bb81 in rq_lock (rf=<optimized out>, rq=<optimized out>)
    at /home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/sched/sched.h:1124
#2 ttwu_queue (wake_flags=<optimized out>, cpu=<optimized out>, p=<
    optimized out>) at /home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/sched/
    core.c:1845
#3 try_to_wake_up (p=0xffff88801eddd780, state=<optimized out>, wake_flags
    =0) at /home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/sched/core.c:2057
#4 0xffffffff8108bcbc in wake_up_process (p=<optimized out>) at /home/
    zeyuanhu/3801-lab0/linux-4.20.4/kernel/sched/core.c:2129

```

Here, kernel tries to awaken a sleeping process through calling `try_to_wake_up()`. `try_to_wake_up()` function wakes a sleeping or stopped process by setting its state to `TASK_RUNNING` and inserting it into the runqueue of the local CPU [5].

The third instance is the following:

```

#0 _raw_spin_lock (lock=0xffff88001cc1ec6c) at /home/zeyuanhu/linux-4.20.4/
    kernel/locking/spinlock.c:144

```

---

<sup>12</sup>In GDB, the helper script also provides a function `$!x_per_cpu` to obtain per-CPU variables (actually `$!x_current()` is a shorthand to `$!x_per_cpu("current task")`)

```

<-- snip -->
#3 0xffffffff81167316 in pud_alloc (address=<optimized out>, p4d=<optimized
    out>, mm=<optimized out>) at /home/zeyuanhu/linux-4.20.4/include/linux
    /mm.h:1733
#4 __handle_mm_fault (vma=<optimized out>, address=6295640, flags=<
    optimized out>) at /home/zeyuanhu/linux-4.20.4/mm/memory.c:4008
#5 0xffffffff811678ad in handle_mm_fault (vma=<optimized out>, address=<
    optimized out>, flags=<optimized out>) at /home/zeyuanhu/linux-4.20.4/
    mm/memory.c:4104
#6 0xffffffff8104bede in __do_page_fault (regs=0xffffc90000317ce8,
    error_code=2, address=6295640) at /home/zeyuanhu/linux-4.20.4/arch/x86/
    mm/fault.c:1426
#7 0xffffffff81a0168b in async_page_fault () at /home/zeyuanhu/linux
    -4.20.4/arch/x86/entry/entry_64.S:1118

```

At this place, kernel tries to handle the page fault. In `/arch/x86/entry/entry_64.S`, we can see `async_page_fault()` is invoked when we're in the KVM guest environment (i.e., QEMU this case). `do_page_fault()` function, which is the Page Fault interrupt service routine for the x86 architecture, compares the linear address that caused the Page Fault against the memory regions of the current process and determines the proper way to handle the exception. In this case, `handle_mm_fault()` is invoked to allocate a new page frame [5].

## 9 Differences between `/dev/random` and `/dev/urandom`

Both `/dev/random` and `/dev/urandom` are interfaces to the kernel's random number generator [6] and both of them are fed by the same cryptographically secure pseudorandom number generator [7]. However, they are different on how they handle their respective entropy pool when the pool is empty. `/dev/random` will block the reads if its entropy pool is empty and the reads will be blocked until additional environmental noise is gathered. However, `/dev/urandom` will not block waiting for more entropy and as a result, the returned values may have theoretical vulnerability. There is an argument on when to use which and some suggests that use `/dev/urandom` is strictly better as the theoretical vulnerability may not

lead to computational vulnerability [7] and thus should be used all the time. But, `man` page seems to suggest that it is a case-by-case situation [6].

## References

- [1] S. Moser, “Using ubuntu cloud-images without a cloud.” <http://ubuntu-smoser.blogspot.com/2013/02/using-ubuntu-cloud-images-without-cloud.html>, 2011.
- [2] “Cs380l: Advanced operating systems lab 0.” <https://www.cs.utexas.edu/~rossbach/380L/lab/lab0.html#debug-config>, 2018.
- [3] “Debugging kernel and modules via gdb.” <https://01.org/linuxgraphics/gfx-docs/drm/dev-tools/gdb-kernel-debugging.html>, 2018.
- [4] “A brief introduction to per-cpu variables.” <http://thinkiii.blogspot.com/2014/05/a-brief-introduction-to-per-cpu.html>, 2014.
- [5] D. P. Bovet and M. Casetti, *Understanding the Linux Kernel*. Sebastopol, CA, USA: O’Reilly & Associates, Inc., 2000.
- [6] “urandom(4) - linux man page.” <https://linux.die.net/man/4/urandom>.
- [7] “Myths about /dev/urandom.” <https://www.2uo.de/myths-about-urandom/>.

## Appendices

### A Detailed steps to let program hit breakpoint

Let  $T1$  denotes the tab with `gdb vmlinux`, let  $T1$  and  $T2$  denote the tabs that we ssh into the guest system. Then we proceed as the following:

1. `gdb vmlinux (T1)`
2. `target remote :1234 (T1)`
3. `c (T1)`
4. `gdb testprog (T2)`
5. `b main (T2)`

6. `r` ( $T2$ )
7. `ps aux | grep test` ( $T3$ ) to obtain pid of *testprog*
8. `b __raw_spin_lock if $lx_current().pid == 2297` (2297 is the pid we find out in the earlier step) ( $T1$ )
9. `c` ( $T1$ )
10. `c` ( $T2$ )

Now, at some point,  $T1$  will show that the breakpoint is hit.