# CS380L: Advanced Operating Systems Lab #1

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### 1 Environment

We use a Linux server for all the experiments. The server has 4 Intel(R) Xeon(R) CPU E3-1220 v5 @ 3.00GHz processors and 16GB of memory, and runs Ubuntu 16.04.2 LTS (kernel version 4.11.0). The CPU has 32KB of L1 data cache per core (8-way set associative) (found through getconf - a | grep CACHE). In addition, it has two-level TLBs. The first level (data TLB) has 64 entries (4-way set associative), and the second level has 1536 entries for both instructions and data (6-way set associative) (found through cpuid | grep -i tlb).

# 2 Memory map

/proc/[pid]/maps file contains process [pid]'s mapped memory regions and their access permissions [1]. We use the following code to read content of /proc/self/maps file <sup>2</sup>:

```
sprintf(filepath, "/proc/%u/maps", (unsigned)getpid());
FILE *f = fopen(filepath, "r");

printf("%-32s %-8s %-10s %-8s %-10s %s\n", "address", "perms", "offset", "dev", "inode", "pathname");

while (fgets(line, sizeof(line), f) != NULL) {
    sscanf(line, "%s%s%s%s%s", address, perms, offset, dev, inode, pathname);
    printf("%-32s %-8s %-10s %-8s %-10s %s\n", address, perms, offset, dev, inode, pathname);

pathname);

fclose(f);
```

In the file, each line corresponds to a mapped memory region. There are six columns of each line, which represent six properties of the mapped memory region: address, perms, offset, dev, inode, and pathname. The result of running memory map.c is below:

The address field gives range of virtual memory address of the mapped memory region. Access permission of each memory region is indicated by perms field. There are four bits in the field: rwx

<sup>&</sup>lt;sup>1</sup>30 hours spent on this lab.

<sup>&</sup>lt;sup>2</sup>see memory\_map.c for complete code

address	perms	offset	dev	inode	pathname
00400000-00401000	r-xp	00000000	fd:01	12374202	/home/zeyuanhu/380L-Spring19/lab1/src/a.out
00600000-00601000	rp	00000000	fd:01	12374202	/home/zeyuanhu/380L-Spring19/lab1/src/a.out
00601000-00602000	rw-p	00001000	fd:01	12374202	/home/zeyuanhu/380L-Spring19/lab1/src/a.out
022c1000-022e2000	rw-p	00000000	00:00	0	[heap]
7fea45315000-7fea454d5000	r-xp	00000000	fd:01	24903836	/lib/x86_64-linux-gnu/libc-2.23.so
7fea454d5000-7fea456d5000	р	001c0000	fd:01	24903836	/lib/x86_64-linux-gnu/libc-2.23.so
7fea456d5000-7fea456d9000	rp	001c0000	fd:01	24903836	/lib/x86_64-linux-gnu/libc-2.23.so
7fea456d9000-7fea456db000	rw-p	001c4000	fd:01	24903836	/lib/x86_64-linux-gnu/libc-2.23.so
7fea456db000-7fea456df000	rw-p	00000000	00:00	0	/lib/x86_64-linux-gnu/libc-2.23.so
7fea456df000-7fea45705000	r-xp	00000000	fd:01	24903834	/lib/x86_64-linux-gnu/ld-2.23.so
7fea458e0000-7fea458e3000	rw-p	00000000	00:00	0	/lib/x86_64-linux-gnu/ld-2.23.so
7fea45904000-7fea45905000	rp	00025000	fd:01	24903834	/lib/x86_64-linux-gnu/ld-2.23.so
7fea45905000-7fea45906000	rw-p	00026000	fd:01	24903834	/lib/x86_64-linux-gnu/ld-2.23.so
7fea45906000-7fea45907000	rw-p	00000000	00:00	0	/lib/x86_64-linux-gnu/ld-2.23.so
7ffe67d7e000-7ffe67d9f000	rw-p	00000000	00:00	0	[stack]
7ffe67da3000-7ffe67da5000	rp	00000000	00:00	0	[vvar]
7ffe67da5000-7ffe67da7000	r-xp	00000000	00:00	0	[vdso]
ffffffff600000-fffffffff60100	0 r-xp	00000000	00:00	0	[vsyscall]

Figure 1: Output of memory\_map.c

represents read, write, and executable respectively; the last bit (p or s) represents whether the region is private or shared. offset field represents the offset in the mapped file. dev field indicates the device (represented with format of major:minor) that the mapped file resides. There are two kinds of value in this column for our case: fd:01 and 00:00. The former one is the device id (in hex) of / (checked with mountpoint -d /) and the latter one represents no device associated with the file. inode field represents the inode number of the file on the device. 0 means no file is associated with the mapped memory region. pathname field gives the absolute path to the file associated with the mapped memory region. It can be some special values like [heap], [stack], [vdso], etc.

To locate the start of the text section of the executable, we invoke objdump -h on the binary and get 000000000400600. Output of /proc/self/maps shows that the start address of libc is 7fea45315000. The reason for these two addresses are different is libc is dynamic loaded library, which is loaded during the runtime of executable, which is not compiled and linked as part of executable. The code segment contains the executable instruction, not the dynamic loaded library.

One interesting thing happens between runs of the executable: the content of /proc/self/maps is different. Addresses of all mapped memory regions are different except for the regions mapped to the executable and [vsyscall]. The root cause behind this phenomenon is Address Space Layout Randomization (ASLR) [2] for programs in user space. This feature is enabled by default and can be seen via the content of /proc/sys/kernel/randomize\_va\_space file. In our case, the value is 2, which means the positions of stack itself, virtual dynamic shared object (VDSO) page, shared memory regions, and data segments are randomized [3].

### 3 Obtaining and building the kernel

We first obtain the Linux Kernel source via wget https://cdn.kernel.org/pub/linux/kernel/v4.x/linux-4.20.4.tar.xz. Then, we extract the files using tar -xJf linux-4.20.4.tar.xz. We make a new directory kbuild as the build directory for kernel and cd kbuild, we generate .config file using yes "" | make -C ../linux-4.20.4/ O=\$(pwd)x86\_64\_defconfig. Note that generating the .config file like this automatically set CONFIG\_SATA\_AHCI=y. We run make -j4 3to build the kernel.

## 4 Installing and Copying Kernel Modules

We install the newly-built kernel by first making a new directory called kinstall as a sibling of kbuild. kinstall will contain the built kernel modules. Inside kbuild, we run make INSTALL\_MOD\_PATH =../kinstall modules\_install.

We can see lib directory inside kinstall, which has to be copied to the root file system of the VM. We notice there are two symbolic links build and source inside kinstall/lib/modules/4.20.4, which links to the built kernel image and the source of the kernel. They are useless and may cause problems when copying files to the VM. Thus we just delete them. Next, we copy the entire 4.20.4 directory to /lib/modules in the guest system by doing scp -P 4444 -r 4.20.4/ ubuntu@localhost:/home/ubuntu and inside the guest system, do sudo mv 4.20.4/ /lib/modules /.

# 5 Booting KVM with your new Kernel

We can now start VM with our own Linux kernel. The shell command we run now:

```
qemu-system-x86_64 \
-enable-kvm -curses \
-m 512 -smp 4 -redir tcp:4444::22 \
-hda my-disk.img -hdb my-seed.img \
-kernel ~/3801-lab0/kbuild/arch/x86_64/boot/bzImage \
-append "root=/dev/sda1" \
-cpu host
```

Note that we append two new options -kernel and -append to QEMU. -kernel option tells the location of the kernel to use, and -append option suggests the parameters to start the kernel. The

<sup>&</sup>lt;sup>3</sup>-j4 means 4 threads are used, which can speed up the build process

```
ubuntu@ubuntu:~$ uname -a
Linux ubuntu 4.20.4 #1 SMP Fri Jan 25 17:02:21 CST 2019 x86_64 x86_64 x86_64 GNU
/Linux
ubuntu@ubuntu:~$ ■
```

Figure 2: VM with our newly-built kernel

root parameter suggests the disk partition used as root file system. After login, use uname -a to check the kernel version string, which is shown in Figure 2.

### 6 Booting, kernel modules, and discovering devices

The wall clock time (tracked using a stopwatch) for our boot takes 34.08 seconds while the time reported by the Kernel takes 28.81 seconds. This difference may be due to the human delay on stopping the stopwatch and also due to a disagreement between human and OS on how to define boot finish status. Here, we stop our stopwatch when we see the login prompt but the last line of dmesg <sup>4</sup> shows:

```
[ 28.811823] new mount options do not match the existing superblock, will be ignored
```

To eliminate the potential human error, we use real-time clock in Linux system to time the difference between the wall clock time and the time reported by Kernel.

```
$ dmesg -T | grep "RTC time"
[Fri Jan 25 23:54:33 2019] RTC time: 23:54:32, date: 01/25/19
```

RTC stands for "real-time clocks" <sup>5</sup>. We find that the time reported by Kernel is 1 second slower than the real-time clock at that moment. "RTC vs system clock" section in man rtc explains possible root cause for this 1 second difference: when the system is in a low power state, only RTC work not the system clock. The system clock is mantained by kernel implemented as counting of timer interrupts and the system clock will set to the wall clock time once the system boots and out of low power state. Thus, one possible explanation of the 1 second difference is due to the slower

<sup>&</sup>lt;sup>4</sup>dmesg is used to inspect the kernel ring buffer, which contains the system log during kernel boot.

<sup>&</sup>lt;sup>5</sup>definition of RTC can be found via man rtc

frequency of timer interrupts and another possible explanation is because the system clock has not aligned well with the wall clock time yet.

We also inspect the discovery of PCI devices at boot time from the boot log. We use the command lspci and there are 6 PCI devices in the VM:

# \$ lspci 00:00.0 Host bridge: Intel Corporation 440FX - 82441FX PMC [Natoma] (rev 02) 00:01.0 ISA bridge: Intel Corporation 82371SB PIIX3 ISA [Natoma/Triton II] 00:01.1 IDE interface: Intel Corporation 82371SB PIIX3 IDE [Natoma/Triton II] 00:01.3 Bridge: Intel Corporation 82371AB/EB/MB PIIX4 ACPI (rev 03) 00:02.0 VGA compatible controller: Device 1234:1111 (rev 02) 00:03.0 Ethernet controller: Intel Corporation 82540EM Gigabit Ethernet Controller (rev 03)

We can search the boot log with the pattern of 0000:ID (e.g., 0000:00:00.0) from lspci to learn how the kernel discovers and identifies these devices during the boot process and the log message helps us to decide what kind of the device is.

```
$ dmesg | grep "0000:00:00.0"
[ 0.244811] pci 0000:00:00.0: [8086:1237] type 00 class 0x060000
[ 0.579080] pci 0000:00:00.0: Limiting direct PCI/PCI transfers
$ dmesg | grep "0000:00:01.0"
[ 0.245549] pci 0000:00:01.0: [8086:7000] type 00 class 0x060100
[ 0.578484] pci 0000:00:01.0: PIIX3: Enabling Passive Release
[ 0.586375] pci 0000:00:01.0: Activating ISA DMA hang workarounds
$ dmesg | grep "0000:00:01.1"
[ 0.246566] pci 0000:00:01.1: [8086:7010] type 00 class 0x010180
[ 0.250524] pci 0000:00:01.1: reg 0x20: [io 0xc040-0xc04f]
[ 0.252018] pci 0000:00:01.1: legacy IDE quirk: reg 0x10: [io 0x01f0-0x01f7]
<-- snip -->
$ dmesg | grep "0000:00:01.3"
[ 0.256256] pci 0000:00:01.3: [8086:7113] type 00 class 0x068000
[ 0.257044] pci 0000:00:01.3: quirk: [io 0x0600-0x063f] claimed by PIIX4 ACPI
[ 0.257208] pci 0000:00:01.3: quirk: [io 0x0700-0x070f] claimed by PIIX4 SMB
```

```
$ dmesg | grep "0000:00:02.0"
[ 0.258317] pci 0000:00:02.0: [1234:1111] type 00 class 0x030000
[ 0.259810] pci 0000:00:02.0: reg 0x10: [mem 0xfd000000-0xfdffffff pref]
[ 0.262214] pci 0000:00:02.0: reg 0x18: [mem 0xfebb0000-0xfebb0fff]
<-- snip -->

$ dmesg | grep "0000:00:03.0"
[ 0.267327] pci 0000:00:03.0: [8086:100e] type 00 class 0x020000
[ 0.268194] pci 0000:00:03.0: reg 0x10: [mem 0xfeb80000-0xfeb9ffff]
[ 0.268973] pci 0000:00:03.0: reg 0x14: [io 0xc000-0xc03f]
<-- snip -->
```

# 7 Tracing the kernel

### 7.1 Make a debug build

To trace the kernel, we need to make a debug build of the kernel by modifying several debug options. Make a new directory debug\_bld2 for holding the debug build. In the created directory, run

```
make -C ../linux-4.20.4 0=$(pwd) x86_64_defconfig
make -C ../linux-4.20.4 0=$(pwd) kvmconfig
make -C ../linux-4.20.4 0=$(pwd) menuconfig
```

The last command will bring up a configuration menu and we change the options as follow [4]:

- Kernel hacking
  - Compile-time checks and compiler options
    - \* Compile the kernel with debug info (check this)
      - · Generate dwarf4 debuginfo (check this)
      - · Provide GDB scripts for kernel debugging (check this)
  - KGDB: kernel debugger (check this)
- General setup
  - Configure standard kernel features (expert users) (check this)
- Processor type and features
  - Build a relocatable kernel (uncheck this)

```
zeyuanhu @ HotDog(ubuntu) ~/3801-lab0/debug_bld2
Thu Jan 31 17:39:17 $ gdb vmlinux

GNU gdb (Ubuntu 8.1-@ubuntu3) 8.1.0.20180409-git
Copyright (C) 2018 Free Software Foundation, Inc.
License GPLv3+: GNU GPL version 3 or later <a href="http://gnu.org/licenses/gpl.html">http://gnu.org/licenses/gpl.html</a>
This is free software: you are free to change and redistribute it.
There is NO WARRANTY, to the extent permitted by law. Type "show copying"
and "show warranty" for details.
This GDB was configured as "x86_64-linux-gnu".
Type "show configuration" for configuration details.
For bug reporting instructions, please see:
<a href="http://www.gnu.org/software/gdb/bugs/">http://www.gnu.org/software/gdb/bugs/</a>.
Find the GDB manual and other documentation resources online at:
<a href="http://www.gnu.org/software/gdb/documentation/">http://www.gnu.org/software/gdb/documentation/</a>.
For help, type "help".
Type "apropos word" to search for commands related to "word"...
Reading symbols from vmlinux...done.
(gdb) target remote :1234
Remote debugging using :1234
default_idle () at /home/zeyuanhu/3801-lab0/linux-4.20.4/arch/x86/kernel/process.c:562
trace_cpu_idle_rcuidle(PWR_EVENT_EXIT, smp_processor_id());
```

Figure 3: Fire up GDB and be ready to debug kernel

We also want to explict set CONFIG\_DEBUG\_INFO\_REDUCED=n explicitly in .config of debug\_bld2. Then we compile the kernel make -j16 and start the VM as

```
sudo qemu-system-x86_64 -enable-kvm -nographic -m 512 -smp 4 -redir tcp:4444::22 -
s -hda my-disk.img -hdb my-seed.img -kernel ~/3801-lab0/debug_bld2/arch/x86_64
/boot/bzImage -append "root=/dev/sda1" -cpu hos
```

Note that we add an option -s, which tells QEMU to start a GDB server on port 1234 for debugging [?] <sup>6</sup>. we can start GDB in debug\_bld2 directory via gdb vmlinux, and type target remote :1234 to connect gdb to the kgdb server in the guest system. Figure 3 shows a screenshot of the GDB that is ready to debug the kernel.

### 7.2 Tracing the kernel

Next, we create a program testprog.c on the guest system like the following 7:

```
#include<unistd.h>
#include<fcntl.h>
int main()

{
    int fd = open("/dev/urandom", O_RDONLY);
    char data[4096];
    read(fd, &data, 4096);
```

<sup>&</sup>lt;sup>6</sup>We also use -nographic instead of -curses because we find out that typing ./testprog can be quite sluggish on the guest system (due to the constant checking of the breakpoint) and using -nographic instead of -curses to boot up the VM and login the VM via SSH helps to alleviate this effect.

<sup>&</sup>lt;sup>7</sup>We modify the program by appending extra line while (1){}. Doing so make sure that the breakpoint will be hit evetually when the program is being executed (since the program is non-terminal). Since the program is fairly short and the execution is very quick. If we do not add this line, sometimes the program will finish execution without the breakpoint getting hit and that hurts reproducibility

```
s close(fd);
fd = open("/dev/null", O_WRONLY);
write(fd, &data, 4096);
close(fd);
while (1) {}
}
```

Compile it with gcc: gcc -o testprog -g testprog.c. Now, we want to trace into the kernel when the process contains testprog is running <sup>8</sup>. To do so, we set a conditional breakpoint in spin\_lock in kernel code that will only stop execution if the above process is running. spin\_lock is an inline Macro and the actual symbol name is \_\_raw\_spin\_lock, which is defined in include /linux/spinlock\_api\_smp.h. To ensure the breakpoint only be triggered during the execution of testprog, we have to add a condition to the breakpoint. We use the helper script provided by kernel to figure out the PID of testprog. We achieve so via \$lx\_current(), which reads task\_struct of current task in GDB and task\_struct contains all the information we need to identify the current proces. Specifically, \$lx\_current().pid gives the PID of the current running process and \$lx\_current().comm gives the command line content, which we will use it to identify the process.

The command we run is the following, where 2297 is the pid of the program. <sup>9</sup>

```
b __raw_spin_lock if $lx_current().pid == 2297
```

The kernel backtrace of the first instance we find looks like below:

- #0 \_raw\_spin\_lock (lock=0xffff88801f2a0a80) at /home/zeyuanhu/3801-lab0/linux
  -4.20.4/kernel/locking/spinlock.c:144
- #1 Oxfffffff8108cbf7 in rq\_lock (rf=<optimized out>, rq=<optimized out>) at /home
  /zeyuanhu/3801-lab0/linux-4.20.4/kernel/sched/sched.h:1124
- #2 scheduler\_tick () at /home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/sched/core.c :3045
- #3 0xfffffff810ceb0b in update\_process\_times (user\_tick=0) at /home/zeyuanhu/3801 -lab0/linux-4.20.4/kernel/time/timer.c:1641

<sup>&</sup>lt;sup>8</sup>We first run target remote :1234 and then we setup the breakpoint. Afterward, we issue continue in the GDB so that we can run testprog on the guest system.

<sup>&</sup>lt;sup>9</sup>Alternatively, we can b \_\_raw\_spin\_lock if \$\_streq(\$lx\_current().comm, "testprog"). This command directly compares the process name with the target program, which has more overhead than comparing process id. This is quite noticeable for a frequently-used function like spin lock in this case and for a machine with less powerful CPU. The detailed steps of using the comparing-process-id approach can be found in Appendix.

Figure 4: testprog hits breakpoint

- #4 0xfffffff810dea7f in tick\_sched\_handle (ts=<optimized out>, regs=<optimized
   out>) at /home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/time/tick-sched.c:164
- #5 0xffffffff810debc2 in tick\_sched\_timer (timer=0xffff88801f29bfc0) at /home/ zeyuanhu/380l-lab0/linux-4.20.4/kernel/time/tick-sched.c:1274
- #6 Oxffffffff810cf6d3 in \_\_run\_hrtimer (flags=<optimized out>, now=<optimized out
  >, timer=<optimized out>, base=<optimized out>, cpu\_base=<optimized out>) at /
  home/zeyuanhu/380l-lab0/linux-4.20.4/kernel/time/hrtimer.c:1398
- #7 \_\_hrtimer\_run\_queues (cpu\_base=0xfffff88801f29ba80, now=<optimized out>, flags=<
   optimized out>, active\_mask=<optimized out>) at /home/zeyuanhu/3801-lab0/linux
   -4.20.4/kernel/time/hrtimer.c:1460
- #8 Oxffffffff810cfe10 in hrtimer\_interrupt (dev=<optimized out>) at /home/zeyuanhu /3801-lab0/linux-4.20.4/kernel/time/hrtimer.c:1518
- #9 0xffffffff81c01e1d in local\_apic\_timer\_interrupt () at /home/zeyuanhu/3801-lab0
  /linux-4.20.4/arch/x86/kernel/apic/apic.c:1034
- #10 smp\_apic\_timer\_interrupt (regs=<optimized out>) at /home/zeyuanhu/3801-lab0/ linux-4.20.4/arch/x86/kernel/apic/apic.c:1059
- #11 0xffffffff81c0152f in apic\_timer\_interrupt () at /home/zeyuanhu/3801-lab0/ linux-4.20.4/arch/x86/entry/entry\_64.S:807

<-- snip -->

Here, the kernel acquires a lock on the run queue and charge one tick to the current process (update\_process\_time). Then, the kernel runs handler for the timer interrupt. If we take a look at

function hrtimer\_interrupt in kernel/time/hrtimer.c, we know the hrtimer\_bases, a per-CPU variable [?], acquired a lock <sup>10</sup>.

The second instance that we take a look at is the following:

- #0 \_raw\_spin\_lock (lock=0xffff88801f2a0a80) at /home/zeyuanhu/3801-lab0/linux
  -4.20.4/kernel/locking/spinlock.c:144
- #1 0xfffffff8108bb81 in rq\_lock (rf=<optimized out>, rq=<optimized out>) at /home
  /zeyuanhu/3801-lab0/linux-4.20.4/kernel/sched/sched.h:1124
- #2 ttwu\_queue (wake\_flags=<optimized out>, cpu=<optimized out>, p=<optimized out>)
   at /home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/sched/core.c:1845
- #3 try\_to\_wake\_up (p=0xffff88801eddd780, state=<optimized out>, wake\_flags=0) at /
  home/zeyuanhu/3801-lab0/linux-4.20.4/kernel/sched/core.c:2057
- #4 Oxfffffff8108bcbc in wake\_up\_process (p=<optimized out>) at /home/zeyuanhu/380 l-lab0/linux-4.20.4/kernel/sched/core.c:2129

Here, kernel tries to awaken a sleeping process through calling try\_to\_wake\_up(). try\_to\_wake\_up
() function wakes a sleeping or stopped process by setting its state to TASK\_RUNNING and inserting
it into the runqueue of the local CPU [5].

The third instance is the following:

- #0 \_raw\_spin\_lock (lock=0xffff88001cc1ec6c) at /home/zeyuanhu/linux-4.20.4/kernel/ locking/spinlock.c:144
- <-- snip -->
- #4 \_\_handle\_mm\_fault (vma=<optimized out>, address=6295640, flags=<optimized out>)
   at /home/zeyuanhu/linux-4.20.4/mm/memory.c:4008
- #5 Oxffffffff811678ad in handle\_mm\_fault (vma=<optimized out>, address=<optimized
   out>, flags=<optimized out>) at /home/zeyuanhu/linux-4.20.4/mm/memory.c:4104
- #6 Oxffffffff8104bede in \_\_do\_page\_fault (regs=0xffffc90000317ce8, error\_code=2, address=6295640) at /home/zeyuanhu/linux-4.20.4/arch/x86/mm/fault.c:1426

At this place, kernel tries to handle the page fault. In /arch/x86/entry/entry\_64.S, we can see async\_page\_fault() is invoked when we're in the KVM guest environment (i.e., QEMU this case). do\_page\_fault() function, which is the Page Fault interrupt service routine for the x86 architecture, compares the linear address that caused the Page Fault against the memory regions of the current

<sup>10</sup> In GDB, the helper script also provides a function \$lx\_per\_cpu to obtain per-CPU variables (actually \$lx\_current () is a shorthand to \$lx\_per\_cpu("current task"))

process and determines the proper way to handle the exception. In this case, handle\_mm\_fault() is invoked to allocate a new page frame [5].

### 8 Differences between /dev/random and /dev/urandom

Both /dev/random and /dev/urandom are interfaces to the kernel's random number generator [?] and both of them are fed by the same cryptographically secure pseudorandom number generator [6]. However, they are different on how they handle their repective entropy pool when the pool is empty. /dev/random will block the reads if its entropy pool is empty and the reads will be blocked until additional environmental noise is gathered. However, /dev/urandom will not block waiting for more entropy and as a result, the returned values may have theoretical vulunerability. There is an argument on when to use which and some suggests that use /dev/urandom is strictly better as the thoeretical vulunerability may not lead to computational vulunerability [6] and thus should be used all the time. But, man page seems to suggest that it is a case-by-case situation [?].

### References

- [1] "proc(5) linux man page." http://man7.org/linux/man-pages/man5/proc.5.html.
- [2] "Address space layout randomization (aslr)." https://en.wikipedia.org/wiki/Address\_space\_layout\_randomization, 2018.
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- [5] D. P. Bovet and M. Cassetti, Understanding the Linux Kernel. Sebastopol, CA, USA: O'Reilly & Associates, Inc., 2000.
- [6] "Myths about /dev/urandom." https://www.2uo.de/myths-about-urandom/.

# Appendices

# A Detailed steps to let program hit breakpoint

Let T1 denotes the tab with gdb vmlinux, let T1 and T2 denote the tabs that we ssh into the guest system. Then we proceed as the following:

```
    gdb vmlinux (T1)
    target remote :1234 (T1)
    c (T1)
    gdb testprog (T2)
    b main (T2)
    r (T2)
    ps aux | grep test (T3) to obtain pid of testprog
    b __raw_spin_lock if $lx_current().pid == 2297 (2297 is the pid we find out in the earlier step) (T1)
    c (T1)
```

Now, at some point, T1 will show that the breakpoint is hit.

 $10.\ \mathsf{c}\ (T2)$