

Solutions for Exercise Round 7

Exercise 1. (Optimal importance distributions)

Recall that in order to compute $\int f(x)q(x)dx = \int f(x)\frac{q(x)}{\pi(x)}\pi(x)dx$ you can use the empirical approximation $\int f(x)dx \approx \frac{1}{N}\sum_{i=1}^N f(x^{(i)})\frac{q(x^{(i)})}{\pi(x^{(i)})}$, where the $x^{(i)}$'s are i.i.d. sampled from π .

(a) Suppose that f(x) > 0 for all x. Find the distribution π that minimises the variance of $\frac{1}{N} \sum_{i=1}^{N} f(x^{(i)}) \frac{q(x^{(i)})}{\pi(x^{(i)})}$.

Proof. We have

$$\mathbb{V}\left[\frac{1}{N}\sum_{i=1}^{N}f(x^{(i)})\frac{q(x^{(i)})}{\pi(x^{(i)})}\right] = \frac{1}{N^2}\sum_{i=1}^{N}\mathbb{V}\left[f(x^{(i)})\frac{q(x^{(i)})}{\pi(x^{(i)})}\right]$$
$$= \frac{N}{N^2}\mathbb{V}_{\pi}\left[f(x)\frac{q(x)}{\pi(x)}\right]$$

The first equality being by independence and the second one by the fact that they are all samples from π . So that the variance of the estimate is minimised when the variance of the single term $\mathbb{E}\left[f(x)\frac{q(x)}{\pi(x)}\right]$ is. Now, the variance is a non-negative quantity, so that if we find something so that it's 0, we have found the optimal π . Taking $\pi(x) \propto f(x)q(x)$, that is $\pi(x) = \frac{f(x)q(x)}{\int f(x)q(x)\mathrm{d}x}$ will make the term inside the variance constant, so of null variance.

(b) Derive the optimal π in the general case when f can be positive or negative.

Proof. We now need to take $\pi(x) \propto |f(x)|q(x)$. This can be seen by splitting f into its positive and negative parts $f^+ = \frac{f+|f|}{2}$ and negative part $f^- = \frac{|f|-f}{2}$, with $f = f^+ - f^-$ and repeating the analysis above. The critical argument is that changin the value of π on the domain where f is negative does not affect the variance of the positive part and vice versa.

(c) Is the goal of designing such an importance density realistic? What would you do in practice?



Proof. Computing $\int |f(x)|q(x)dx$ appearing in the expression of π is generally as complicated as computing the original problem $\int f(x)q(x)dx$ for which we resorted to importance sampling in the first place... Instead this gives us a rule of thumb for designing π : we need to take it to be as close as possible to the target that we want to integrate. There are many solutions that you will see in the next lectures: in particular using the Gaussian approximations given by extended and unscented Kalman filtering methods is a typical go-to solution (also think Laplace estimates, or neural nets, etc).

Exercise 2. (Rejection Sampling for Beta distribution)

See the notebook.

Exercise 3. (Rejection Sampling Failure)

Consider the model

$$p(x) = N(x \mid 0, 1), p(y \mid x) = N(y \mid x, 1).$$
(1)

(a) Compute the posterior distribution $p(x \mid y)$.

Proof. The posterior distribution can be computed using, for example, the Kalman filter update and it is $p(x \mid y) = N(x \mid y/2, 1/2)$.

(b) Let us now assume that we use a distribution $\pi(x) = N(x \mid 0, v)$ with some variance v as the proposal distribution for rejection sampling. Show that there exists no bound M such that $p(x \mid y)/\pi(x) \leq M$. Hint: What is the maximum of $-(x-y/2)^2 + \frac{1}{2v}x^2$ over x and y?

Proof. The required bound (which should be less than a constant M) now has the form

$$\frac{p(x \mid y)}{\pi(x)} = \frac{N(x \mid y/2, 1/2)}{N(x \mid 0, v)} = \frac{\sqrt{2\pi v}}{\sqrt{\pi}} \exp\left(-(x - y/2)^2 + \frac{1}{2v}x^2\right). \quad (2)$$

The maximum of this w.r.t. y is obtained when y/2 = x which gives

$$\frac{\sqrt{2\pi v}}{\sqrt{\pi}} \exp\left(\frac{1}{2v}x^2\right),\tag{3}$$

which is unbounded in x.



(c) What does this result imply on the weights of importance sampling if we use $\pi(x)$ as the importance distribution?

Proof. The result implies that the importance weights will also be unbounded which further implies that the variance of the weights can become large. \Box