Lecture 09

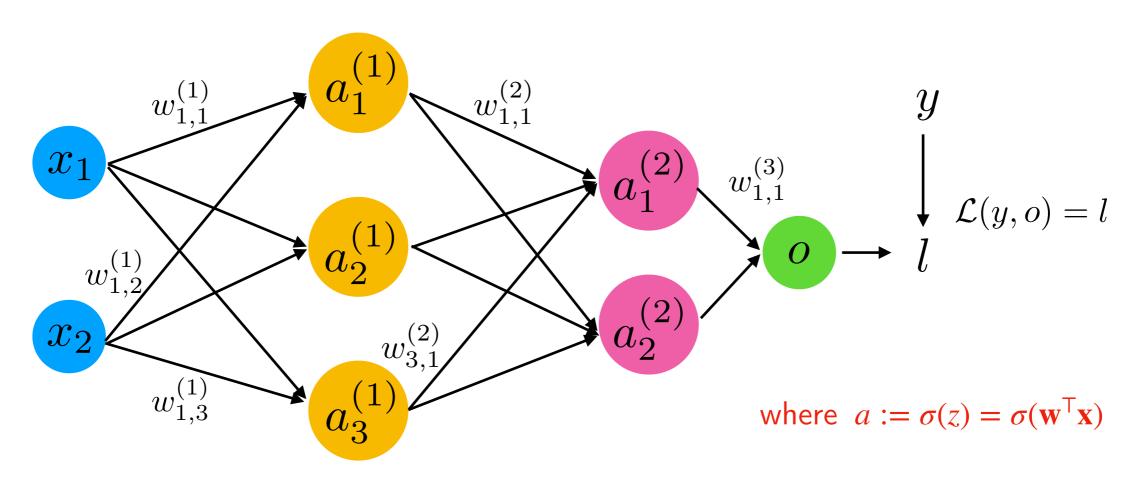
Multilayer Perceptrons

STAT 479: Deep Learning, Spring 2019

Sebastian Raschka

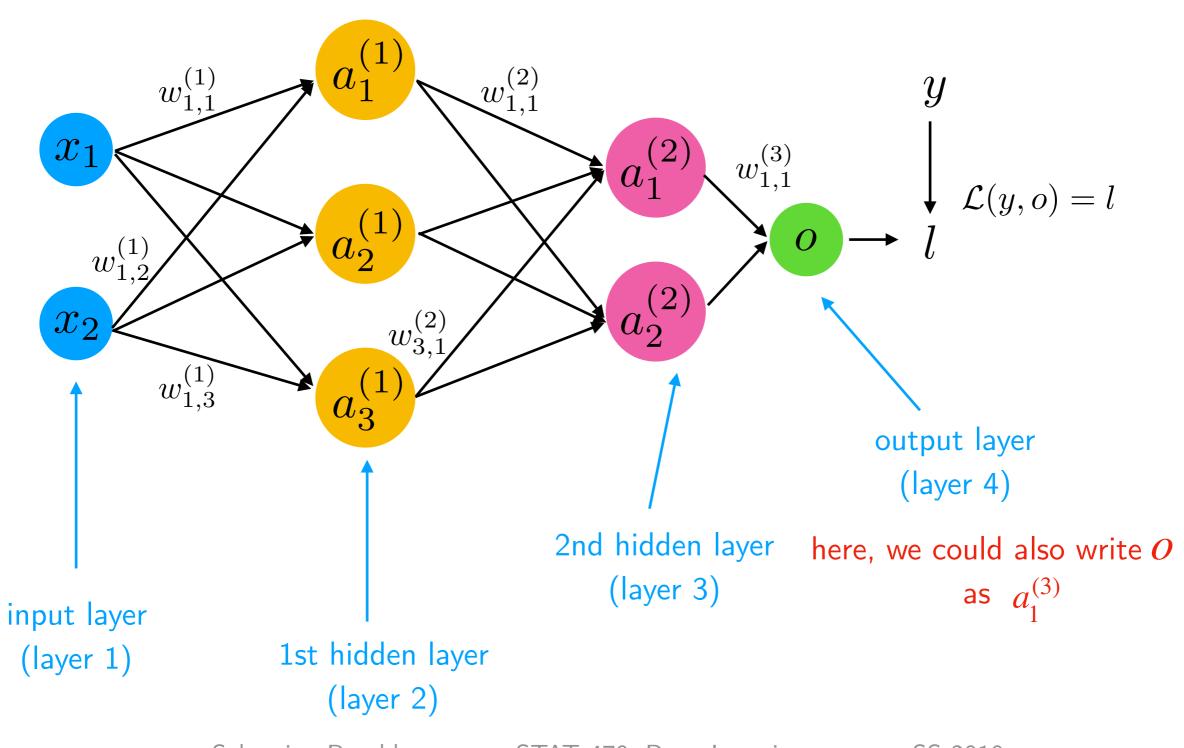
http://stat.wisc.edu/~sraschka/teaching/stat479-ss2019/

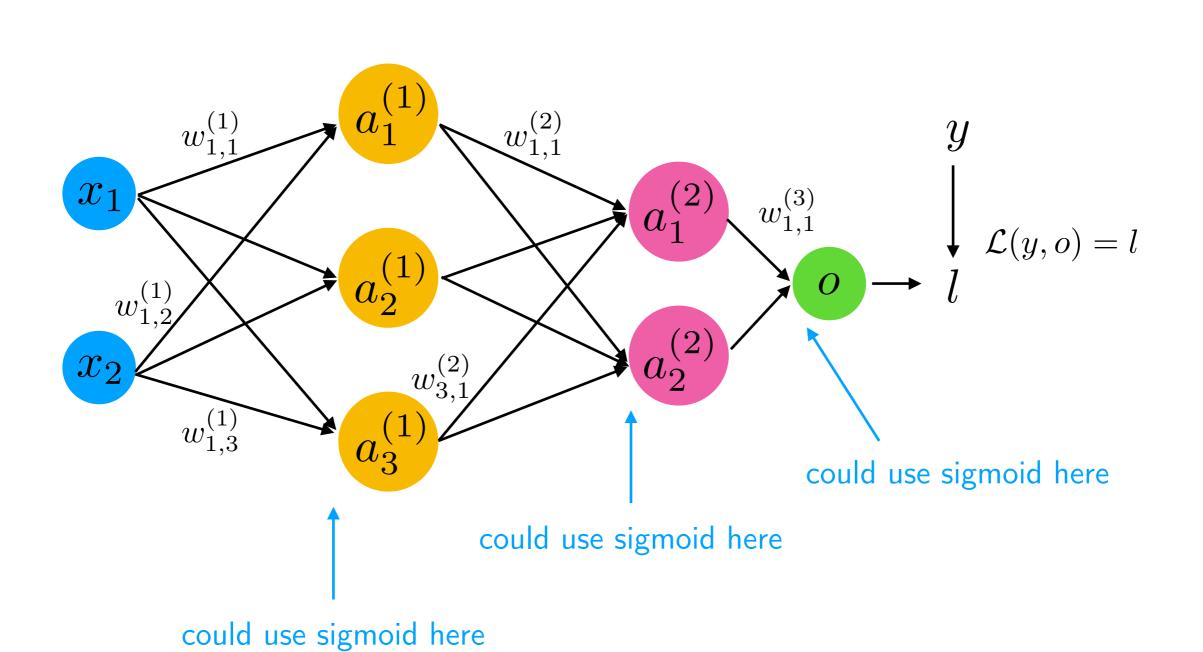
Nothing new, really



$$\frac{\partial l}{\partial w_{1,1}^{(1)}} = \frac{\partial l}{\partial o} \cdot \frac{\partial o}{\partial a_1^{(2)}} \cdot \frac{\partial a_1^{(2)}}{\partial a_1^{(1)}} \cdot \frac{\partial a_1^{(1)}}{\partial w_{1,1}^{(1)}} + \frac{\partial l}{\partial o} \cdot \frac{\partial o}{\partial a_2^{(2)}} \cdot \frac{\partial a_2^{(2)}}{\partial a_1^{(2)}} \cdot \frac{\partial a_2^{(1)}}{\partial a_1^{(1)}} \cdot \frac{\partial a_1^{(1)}}{\partial w_{1,1}^{(1)}} + \frac{\partial a_1^{(1)}}{\partial w_{1,1}^{(1)}}$$

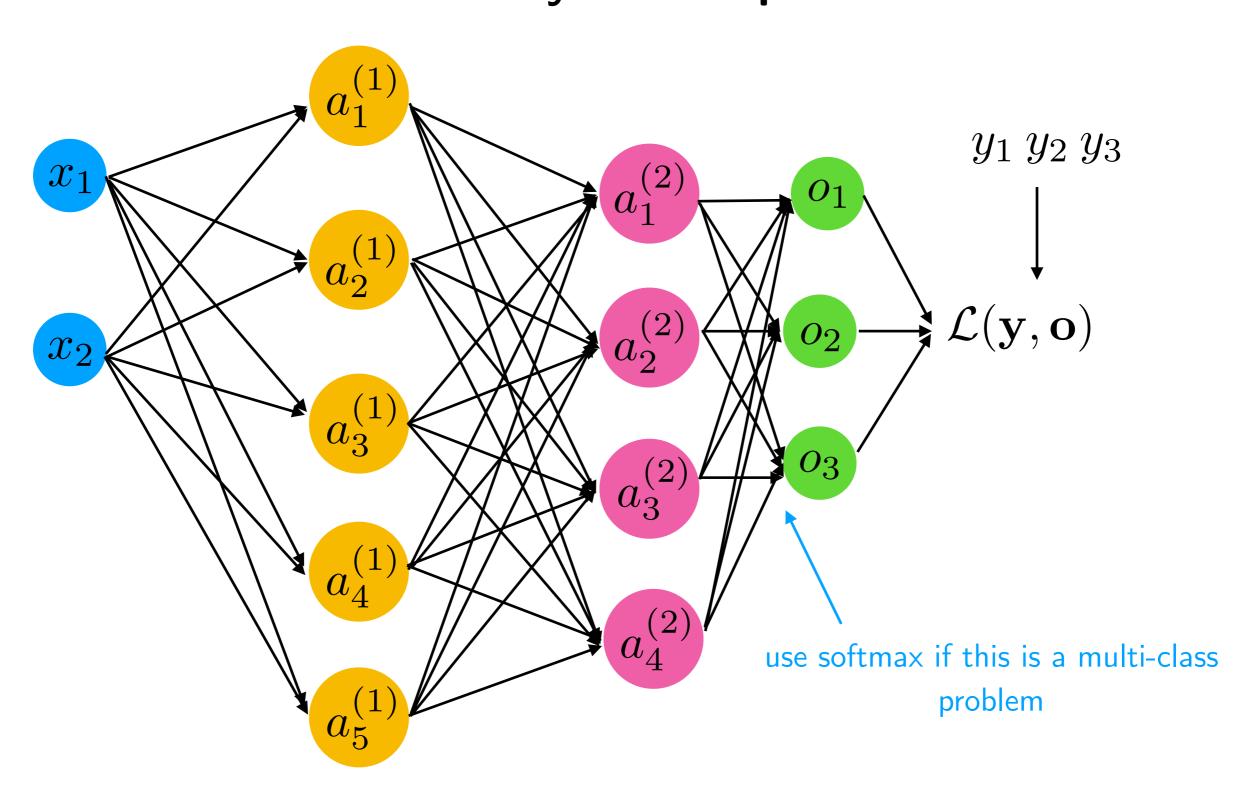
(Assume network for binary classification)





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Note That the Loss is Not Convex Anymore

- Linear regression, Adaline, Logistic Regression, and Softmax Regression had convex loss functions with respect to the weights
- This is not the case anymore; in practice, we usually end up at different local minima if we repeat the training (e.g., by changing the random seed for weight initialization or shuffling the dataset while leaving all setting the same)
- In practice though, we WANT to explore different starting weights, however, because some lead to better solutions than others

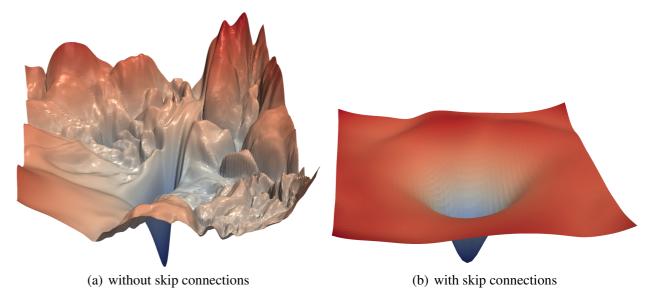


Figure 1: The loss surfaces of ResNet-56 with/without skip connections. The proposed filter normalization scheme is used to enable comparisons of sharpness/flatness between the two figures. 32nd Conference on Neural Information Processing Systems (NIPS 2018), Montréal, Canada.

Image Source: Li, H., Xu, Z., Taylor, G., Studer, C. and Goldstein, T., 2018. Visualizing the loss landscape of neural nets. In Advances in Neural Information Processing Systems (pp. 6391-6401).

Multilayer Perceptron with Sigmoid Activation and MSE Loss (from scratch)

https://github.com/rasbt/stat479-deep-learning-ss19/blob/master/L09_mlp/code/mlpfromscratch sigmoid-mse.ipynb

Multilayer Perceptron with Sigmoid Activation and MSE Loss **VS**

Multilayer Perceptron with Softmax Activation and Cross Entropy Loss (in PyTorch)

https://github.com/rasbt/stat479-deep-learning-ss19/blob/master/L09_mlp/code/mlppytorch.ipynb

About Softmax & Sigmoid in the Output Layer and Issues with MSE

ullet Sigmoid activation + MSE has the problem of very flat gradients when the output is very wrong i.e., 10^{-5} probability and class label 1

$$\frac{\partial \mathcal{L}}{\partial w_i} = -\frac{2}{n} (\mathbf{y} - \mathbf{a}) \odot \sigma(\mathbf{z}) \odot (1 - \sigma(\mathbf{z})) \mathbf{x}_j^{\mathsf{T}} \quad \text{(from HW2: sigmoid + MSE neuron)}$$

 Softmax (forces network to learn probability distribution over labels) in output layer is better than sigmoid because of the mutually exclusive labels as discussed in the Softmax lecture; hence, in output layer, better than sigmoid

About the DataLoader Class

• Example showing how you can create your own data loader to efficiently iterate through your own collection of images (pretend the MNIST images there are some custom image collection)

https://github.com/rasbt/stat479-deep-learning-ss19/tree/master/L09_mlp/ code/custom-dataloader

Your 3rd Homework

 Experiment with a multi-layer perceptron on a subset of the QuickDraw dataset (due next Friday, March 8th 11:59 pm)

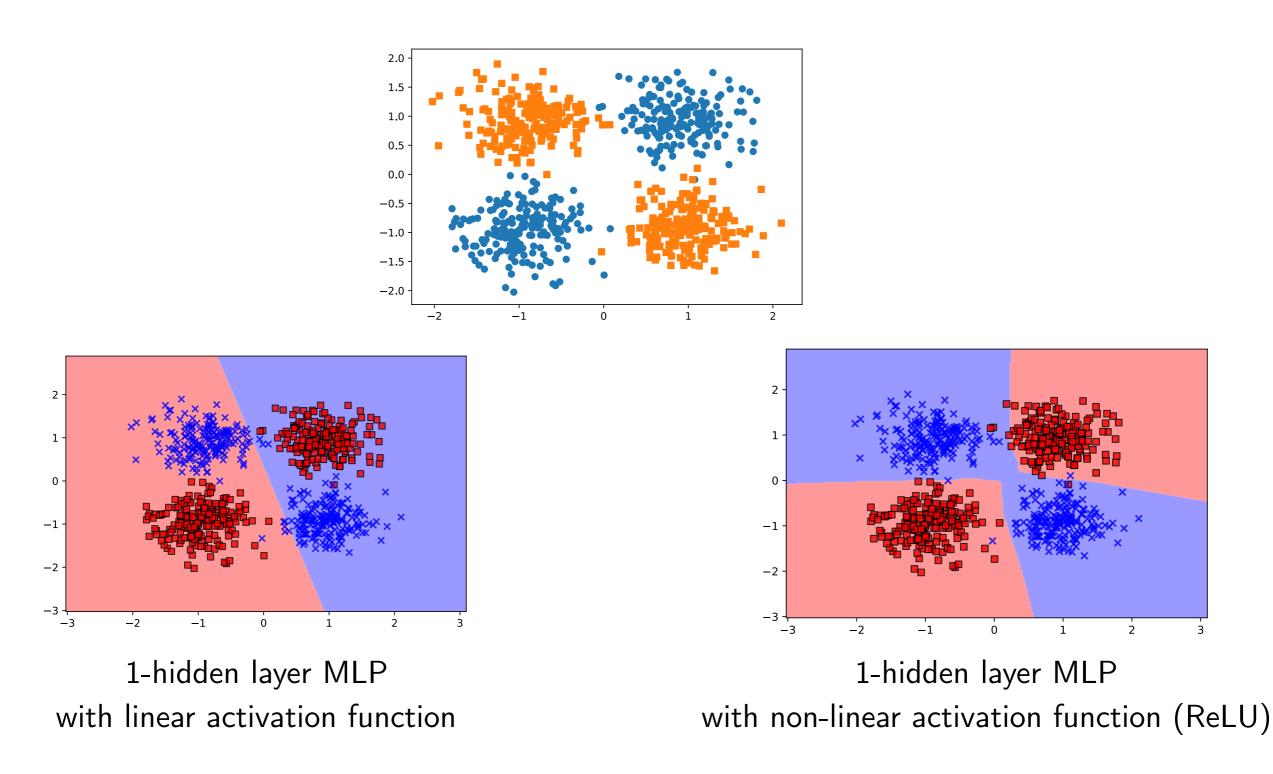
https://github.com/rasbt/stat479-deep-learning-ss19/tree/master/L09_mlp/ code/custom-dataloader

What happens if we initialize the multi-layer perceptron to all-zero weights?

Activation Functions

Question: What happens if we don't use non-linear activation functions?

Solving the XOR Problem with Non-Linear Activations

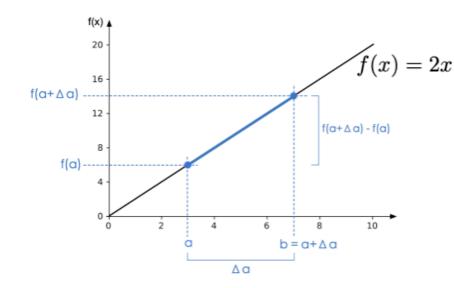


https://github.com/rasbt/stat479-deep-learning-ss19/blob/master/L09_mlp/code/xor-problem.ipynb

Gradient Checking

• Back in the day, we usually checked our gradients manually during debugging (note that this is super slow!)

Derivative of a function = "rate of change" = "slope"



Slope =
$$\frac{f(a + \Delta a) - f(a)}{a + \Delta a - a} = \frac{f(a + \Delta a) - f(a)}{\Delta a}$$

(remember this from the calculus refresher section?)

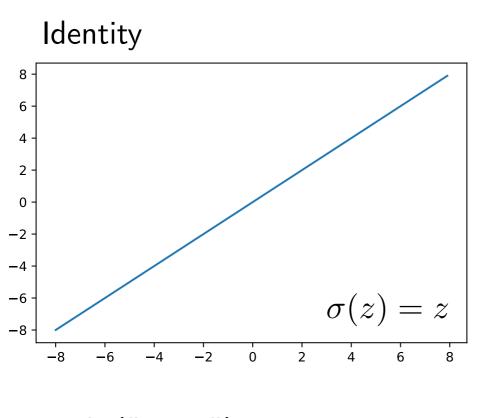
Usually, a centered version works better, where epsilon is a very small value:

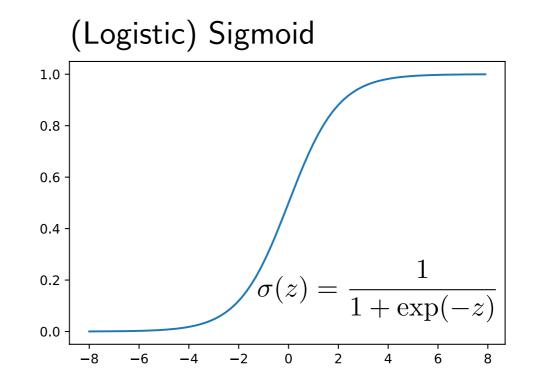
$$\frac{\mathcal{L}\left(w_{i,j}^{(l)} + \varepsilon\right) - \mathcal{L}\left(w_{i,j}^{(l)} - \varepsilon\right)}{2\varepsilon}$$

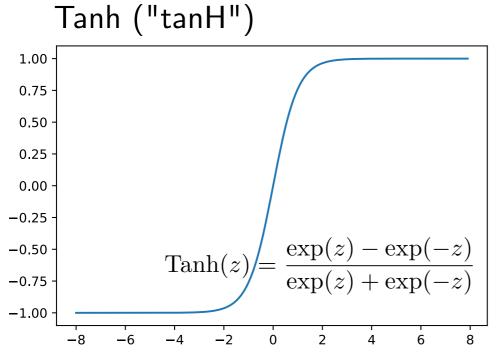
(then compare this with the symbolic gradient and compute the difference, e.g., via L2 norm)

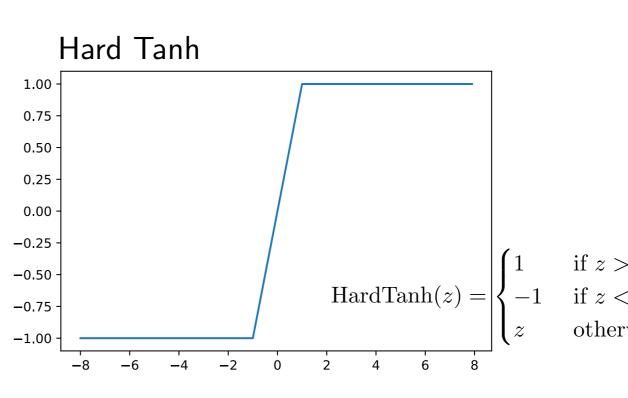
 Rarely done in practice anymore because we usually nowadays use autograd anyway, due to the complexity of deep neural networks

A Selection of Common Activation Functions (1)





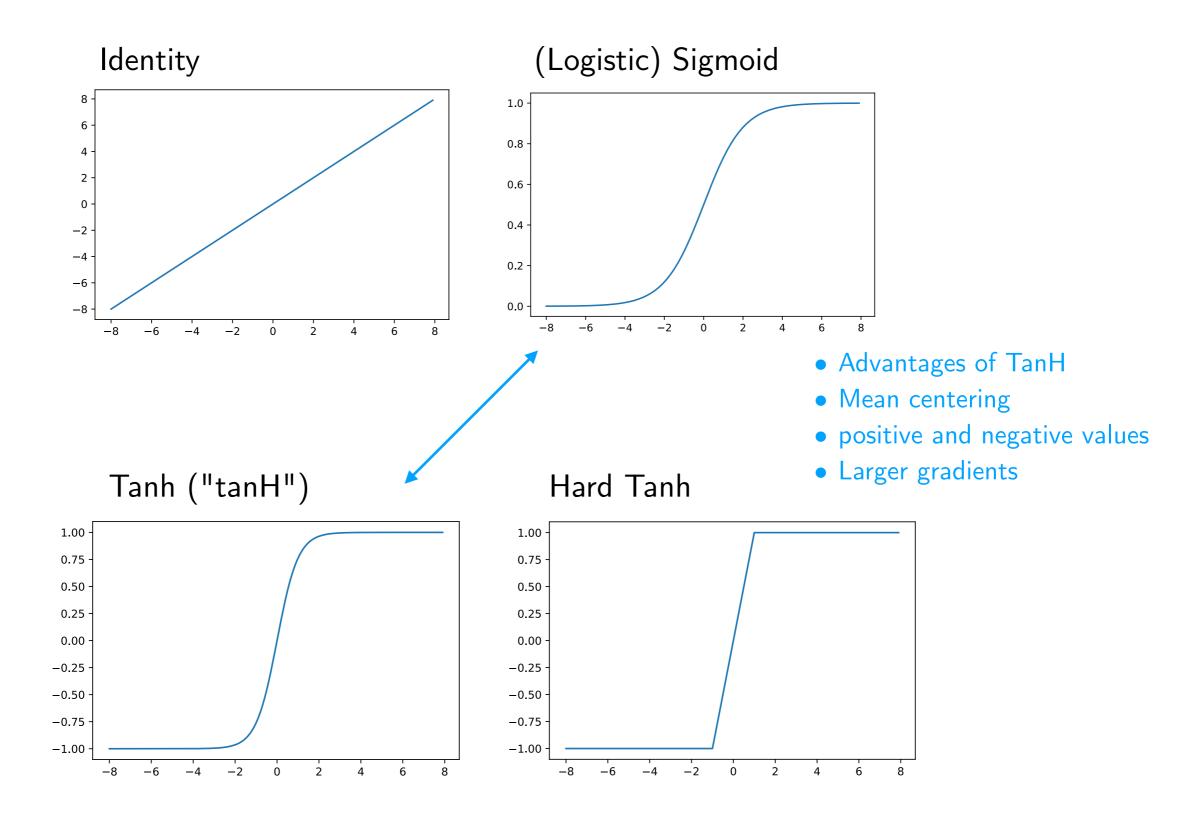




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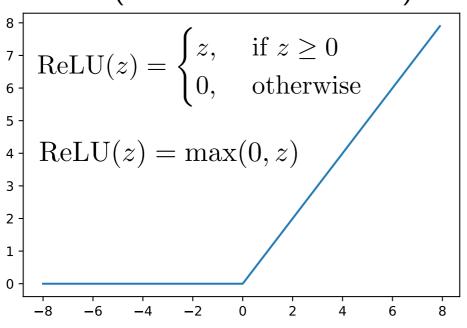
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A Selection of Common Activation Functions (1)

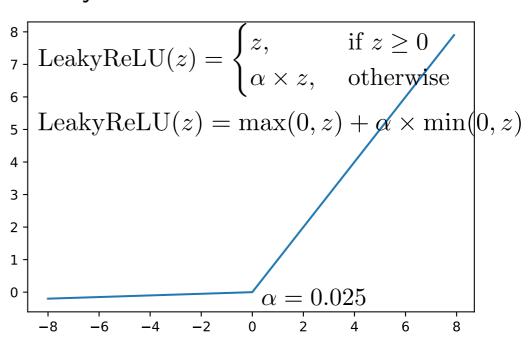


A Selection of Common Activation Functions (2)

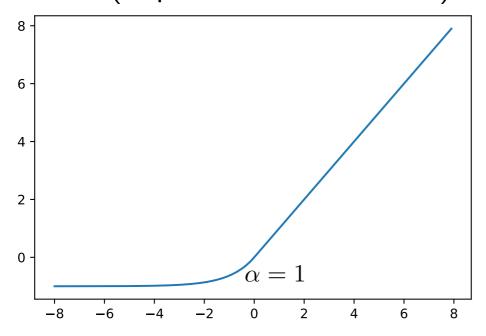
ReLU (Rectified Linear Unit)



Leaky ReLU



ELU (Exponential Linear Unit)



$$ELU(z) = \max(0, z) + \min(0, \alpha \times (\exp(z) - 1))$$

PReLU (Parameterized Rectified Linear Unit)

here, alpha is a trainable parameter

$$PReLU(z) = \begin{cases} z, & \text{if } z \ge 0\\ \alpha z, & \text{otherwise} \end{cases}$$

$$ELU(z) = \max(0, z) + \min(0, \alpha \times (\exp(z) - 1)) \qquad PReLU(z) = \max(0, z) + \alpha \times \min(0, z)$$

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Pros and Cons of Different Activations

to be continued on Monday ...