

# Texture classification using Local Binary Patterns

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# Problem statement

- **Goal:** Classify textures (13 Brodatz textures) invariant to rotation using local image descriptors.
- **Approach:** Use Local Binary Patterns (LBP) and rotation-invariant / multi-resolution variants, optionally combined with local variance (VAR) and probabilistic histogram-based classification.

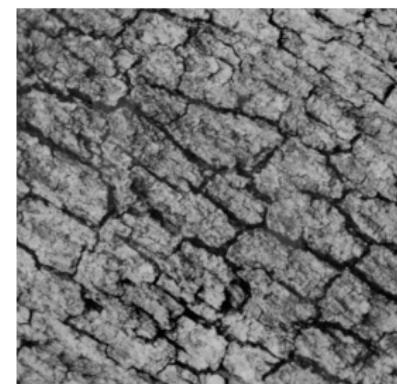
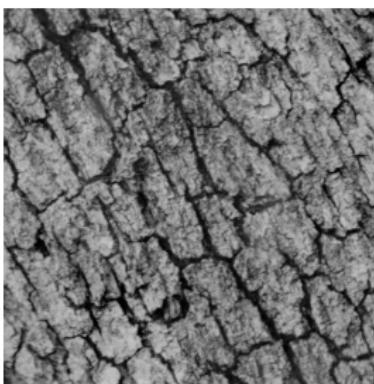


Figure 1: Rotation variants of the Bark texture from Brodatz dataset [2]

# Local Binary Patterns (intuition)

- At each pixel, compare its intensity  $g_c$  with  $P$  circular neighbors  $g_p$  at radius  $R$ .
- Create a binary code using thresholding:

$$s(x) = \begin{cases} 1 & x \geq 0 \\ 0 & x < 0 \end{cases}$$

$$\text{LBP}_{P,R}(x_c) = \sum_{p=0}^{P-1} s(g_p - g_c) 2^p$$

- This encodes local texture structure like edges, corners, and spots.

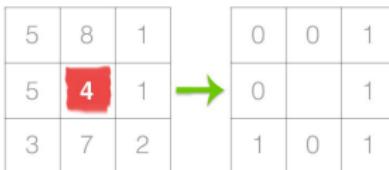


Figure 2: Thresholding neighbor pixels around the center pixel [3].

## LBP Encoding: Bit Ordering

- After thresholding, the binary values are arranged in a fixed circular order.
- Each neighbor contributes a weighted bit:  $2^0, 2^1, \dots, 2^{P-1}$ .
- The final LBP value is a binary-to-decimal conversion of these bits.

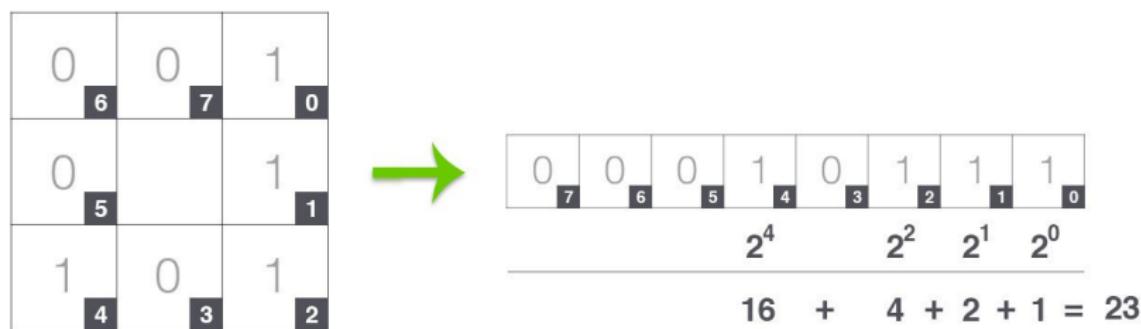


Figure 3: LBP bit indexing and weighted binary encoding [3].

# LBP on Full Image

- The process is repeated for every pixel in the image.
- Each pixel is replaced by its LBP code, generating the LBP image.
- This image captures local texture patterns invariant to monotonic gray-scale changes.

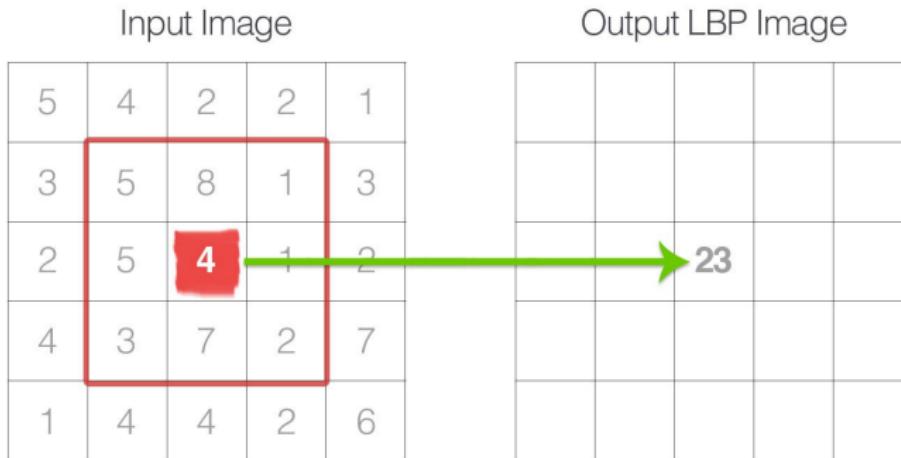


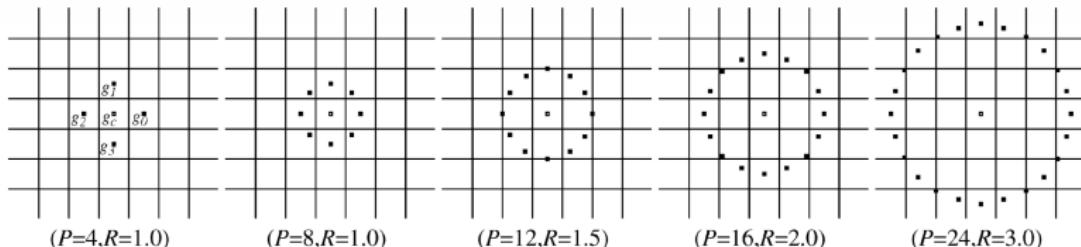
Figure 4: LBP applied to the full image, producing the LBP map [3].

# Rotation Invariant LBP: Circular Neighborhood

- For generalized LBP, neighbors lie on a **circle** of radius  $R$  around the center pixel.
- Number of neighbors:  $P$ , evenly spaced with angle:

$$\theta_p = \frac{2\pi p}{P}, \quad p = 0, \dots, P - 1$$

- Non-integer pixel locations are handled using bilinear interpolation.
- Increasing  $P$  and  $R$  gives **multi-resolution texture description**.



**Figure 5:** Circularly symmetric sampling patterns for different  $(P, R)$  configurations [1].

# Rotation-Invariant LBP

- Standard LBP depends on neighbor ordering.
- Rotation invariance is achieved by finding the **minimum decimal value** over all circular bitwise rotations:

$$\text{LBP}_{P,R}^{ri} = \min_{i=0,\dots,P-1} \{\text{ROR}(\text{LBP}_{P,R}, i)\}$$

where ROR = circular right shift.

- This ensures that rotated microstructures produce identical LBP codes.

## Example:

A pattern like:

10000111 → 00001111 → 00011110 → ...

Choose the smallest decimal value among all rotations.

# Uniform LBP and RIU2 Mapping

- **Uniform patterns:** binary patterns with at most two bitwise transitions ( $0 \rightarrow 1$  or  $1 \rightarrow 0$ ) when traversed circularly.

$$U(\text{LBP}) = |b_{P-1} - b_0| + \sum_{p=1}^{P-1} |b_p - b_{p-1}|$$

- Patterns with  $U(\text{LBP}) \leq 2$  are called **uniform**.
- More than 90% of local patterns in natural images are uniform patterns.

## RIU2 Mapping:

$$\text{LBP}_{P,R}^{riu2} = \begin{cases} \sum b_p, & U(\text{LBP}) \leq 2 \\ P + 1, & \text{otherwise} \end{cases}$$

- Output histogram size reduces from  $2^P$  to  $P + 2$  bins.
- This greatly reduces dimensionality while preserving discriminative power.

# Local Variance (VAR) and Nonparametric Classification

- LBP captures **structure**, but ignores **local contrast**.
- Ojala et al.[1] propose the variance (VAR) as a complementary descriptor. For each pixel, VAR is computed over the same circular neighborhood:

$$VAR_{P,R}(x_c) = \frac{1}{P} \sum_{p=0}^{P-1} (g_p - \mu)^2, \quad \mu = \frac{1}{P} \sum_{p=0}^{P-1} g_p$$

## Nonparametric Classification Principle

- Each texture class is represented by a **model histogram** built from training samples.
- A test image produces a histogram  $S$ , which is compared to each class histogram  $M$ .
- Classification is done by maximizing the log-likelihood similarity:

$$\text{Score}(S, M) = \sum_i S(i) \log(M(i))$$

# LBP: Pseudo-code (per pixel)

```

1: for each pixel  $c$  do
2:    $g_c \leftarrow$  intensity at pixel  $c$ 
3:   for  $p = 0$  to  $P - 1$  do
4:     compute  $(y_p, x_p)$  on circle of radius  $R$ 
5:      $g_p \leftarrow$  bilinear_interpolate(image,  $y_p, x_p$ )
6:      $bit_p \leftarrow \begin{cases} 1 & \text{if } g_p \geq g_c \\ 0 & \text{otherwise} \end{cases}$ 
7:   end for
8:    $LBP \leftarrow \sum_{p=0}^{P-1} bit_p \cdot 2^p$ 
9:   if rotation invariant then
10:     $LBP \leftarrow \text{min\_rotate}(LBP)$ 
11:   end if
12:   if RIU2 mapping enabled then
13:      $u \leftarrow \text{uniformity}(LBP)$ 
14:     if  $u \leq 2$  then
15:       output  $\leftarrow \text{popcount}(LBP)$ 
16:     else
17:       output  $\leftarrow P + 1$ 
18:     end if
19:   end if
20: end for

```

# Dataset: Brodatz Rotated Textures (USC-SIPI)

- We use only the **rotated texture subset** from `rotate.zip` of the USC-SIPI texture database.
- This subset contains **13 Brodatz textures**, each digitized at  $0^\circ, 30^\circ, 60^\circ, 90^\circ, 120^\circ, 150^\circ, 200^\circ$ , resulting in a total of **91 images**.
- The 13 textures used are: bark, brick, bubbles, grass, leather, pigskin, raffia, sand, straw, water, weave, wood, wool (example shown in Fig. 1).
- **Experimental protocol:** For each texture class, the model is trained using *one* rotation angle and tested on the remaining six rotated versions.
- All images are **grayscale,  $512 \times 512$ , 8-bit**. They were digitized using a video camera, so the quality is slightly lower than the original unrotated Brodatz images.

# Implementation Details

- **Patch extraction ( $16 \times 16$  subimages):** Each  $512 \times 512$  texture is divided into fixed  $16 \times 16$  patches to increase training samples and capture local texture statistics.
- **Lookup tables (LUTs):** Precomputed LUTs map raw LBP codes to RIU2 labels, uniformity values, rotation-min codes, and popcount, avoiding expensive per-pixel recomputation.
- **Bilinear interpolation:** Neighbor pixel values on the circular sampling ring are estimated using custom bilinear interpolation for non-integer coordinates.
- **VAR quantization:** Local variance values are discretized into bins using cut-points computed from training statistics.
- **Numerical stability:** Histogram models use Laplace smoothing and log-probabilities during classification to prevent zero-probability errors and floating-point underflow.

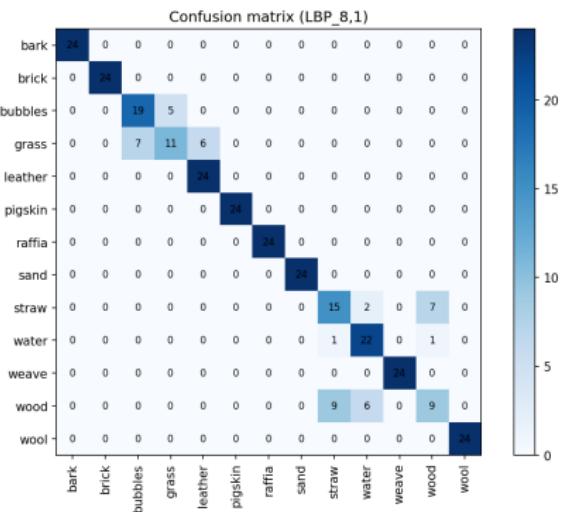
## Accuracy results (summary)

Operator	Train 0	Train 30	Train 60	Train 90	Avg
LBP_8,1	88.46%	89.74%	84.62%	83.33%	86.54%
LBP_16,2	93.59%	96.15%	94.87%	94.87%	94.87%
LBP_24,3	100.00%	98.72%	100.00%	100.00%	99.68%
LBP_16,2/VAR	100.00%	100.00%	100.00%	100.00%	100.00%
LBP_24,3/VAR	98.72%	100.00%	100.00%	100.00%	99.68%
LBP_8,1+16,2	92.31%	93.59%	87.18%	92.31%	91.35%

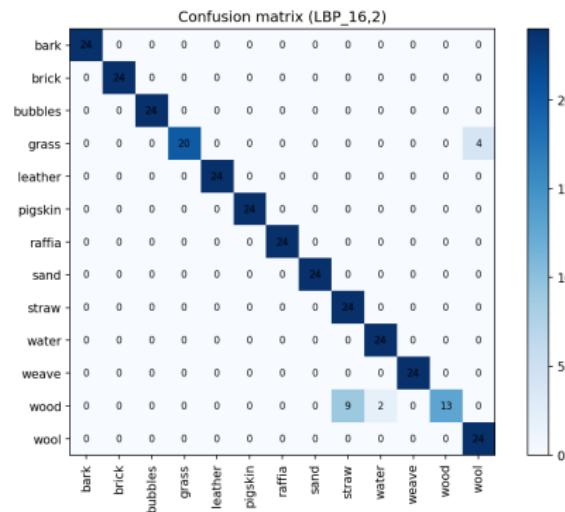
Table 1: Performance of operators at four different training angles

- Best results achieved by combined multi-resolution (16,2 or 24,3) operators and when using VAR combined with LBP.
- RIU2 reduces descriptor dimensionality and preserves rotation invariance.

# Confusion Matrices

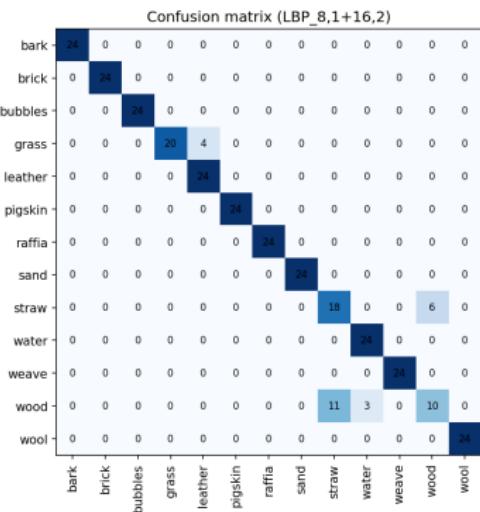


LBP<sub>8,1</sub>

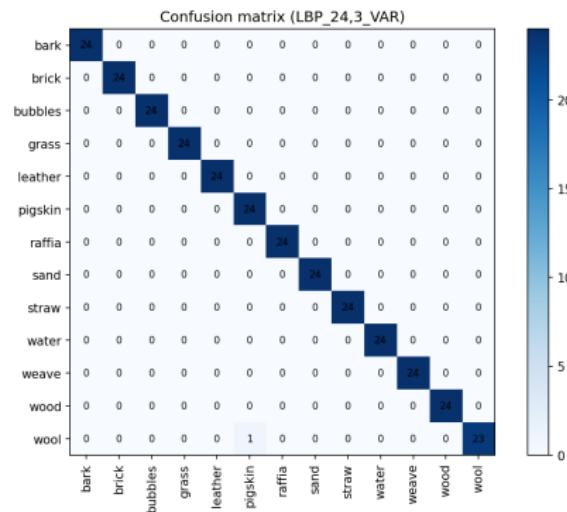


LBP<sub>16,2</sub>

# Confusion Matrices



$LBP_{8,1} + LBP_{16,2}$

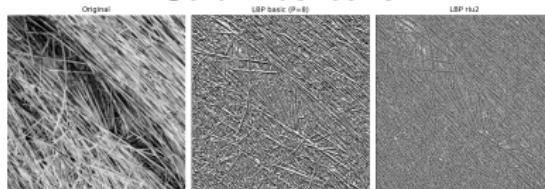


$LBP_{24,3} + VAR$

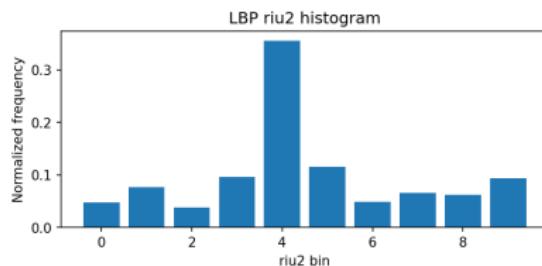
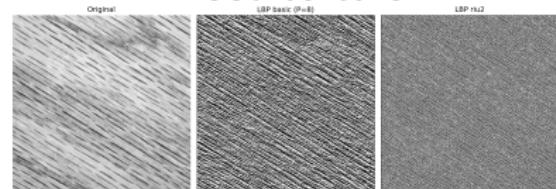
# Why Wood and Straw are Confused (LBP\_8,1)

Both **wood** and **straw** exhibit strong directional, line-like textures. With small-radius LBP ( $P = 8, R = 1$ ), many local neighborhoods become similar: parallel edges produce nearly identical LBP riu2 histograms, leading to confusion.

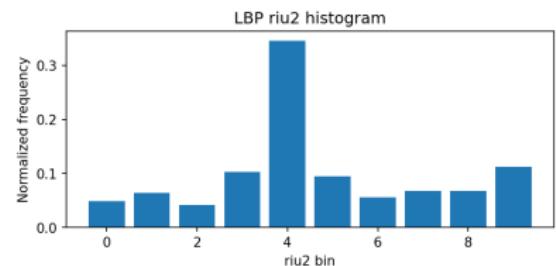
**Straw texture**



**Wood texture**



LBP map and riu2 histogram (Straw)



LBP map and riu2 histogram (Wood)

**Observation:** Both textures produce very similar dominant riu2 bins due to repeated linear micro-patterns.

# Conclusions

- Multi-resolution LBP (especially  $P = 16, R = 2$  and  $P = 24, R = 3$ ) provides strong rotation-invariant discrimination on the Brodatz rotated texture set.
- Increasing  $P$  and  $R$  improves accuracy because larger neighborhoods capture texture structures at coarser spatial scales, making the descriptor more sensitive to dominant orientation patterns and long-range correlations rather than just fine local noise.
- Adding local variance (VAR) complements LBP by encoding contrast information that pure binary patterns discard, leading to substantially better class separation.
- The combined use of multi-scale neighborhood structure and local contrast yields a robust and compact representation for rotated texture classification.

# References

-  T. Ojala, M. Pietikäinen and T. Mäenpää,  
*Multiresolution Gray-scale and Rotation Invariant Texture Classification with Local Binary Patterns*,  
IEEE Transactions on Pattern Analysis and Machine Intelligence, 2002. Available at: [IEEE Xplore](#)
-  Brodatz Rotated Texture Dataset.  
Available at: [Brodatz Database](#)
-  Adrian Rosebrock, *Local Binary Patterns with Python & OpenCV*, PyImageSearch, 2015.  
Available at: [Local Binary Patterns with Python & OpenCV](#)