MICT-5101: Probability and Stochastic Process¹

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Lecture Outline I

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 - 1.2 Distribution of Renewal Process
 - 1.3 Finding the Renewal Function
 - 1.4 Branching Processes
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 - **1.6** Mathematical Model of a Branching Process
 - 1.7 Mean of Branching Process
 - 1.8 Variance of Branching Process



Chapter 7. Renewal Process and Branching Process



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 - 1.5 Key Features of Branching Process
 - **1.6** Mathematical Model of a Branching Process
 - 1.7 Mean of Branching Process
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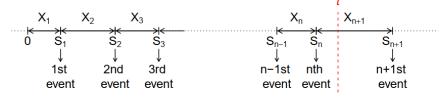
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Renewal Process

We have seen that a Poisson process is a counting process for which the times between successive events are independent and identically distributed exponential random variables. One possible generalization is to consider a counting process for which the times between successive events are independent and identically distributed with an arbitrary distribution. Such a counting process is called a *renewal process*.

Definition 1.1

Let $\{N(t), t \geq 0\}$ be a counting process and let X_n denote the time between the (n-1)st and the nth event of this process, $n \geq 1$. If the sequence of nonnegative random variables $\{X_1, X_2, X_3 \ldots\}$ is independent and identically distributed, then the counting process $\{N(t), t \geq 0\}$ is said to be a renewal process. It was introduced as a generalization of Poisson process. It was considered as a process in continuous time.



Let X_1, X_2, \ldots be i.i.d random variables with $\mathbb{E}[X_i] < \infty$, and $\mathrm{P}(X_i > 0) = 1$. Let

$$S_0 = 0, \quad S_n = X_1 + \ldots + X_n, \ n \ge 1.$$

Define

$$N(t) = \max\{n : S_n \leq t\}.$$

Then $\{N(t), t \geq 0\}$ is called a *renewal process*.

- ▶ Events are called "renewals". The interarrival times between events X_1, X_2, \ldots are also called "renewals"
- ightharpoonup A more general definition allows the first renewal X_1 to be of a different distribution, called a **delayed renewal process**.

Renewal Process

Example:

Suppose, we have an infinite number of electric light bulbs whose life times are iid random variables. Suppose we use a single light bulb at a time and we immediately replace it by a new one if it fail. Let N(t) represents the number of light bulbs that have failed by time t, then $\{N(t); t \geq 0\}$ is a Renewal Process.



Renewal process used inn a variety of situations such as

- demography
- manpower studies
- reliability
- replacement and maintenance
- inventory control
- queuing process
- simulation and so on.



Classification of Renewal Process

- ① Delayed/General/Modified renewal process A renewal process $\{N(t); t \ge 0\}$ is said to be delayed/general/modified renewal process if the first arrival time X_1 has a different distribution than the other $X_2, X_3, ...$
- 2 Equilibrium renewal process A renewal process $\{N(t); t \ge 0\}$ is said to be equilibrium renewal process if the distribution of the 1st interarrival tie is specified which is

$$F_e(t) = \int_0^t \frac{1 - F(x)}{\mu} dx$$

where μ = mean of F. and it different from the iid distributed other.



Difference between Renewal Process and Poisson Process

- (i) Interarrival times of the renewal process $\{N(t); g \ge 0\}$ are iid with arbitrary distribution.
- (ii) The mean function is

$$m(t) = \sum_{n=1}^{\infty} F_n(t)$$

- (iii) Renewal process is the generalization of Poisson process.
- (iv) mean function may be linear.

- (i) Interarriavals time have independently identical exponentially distributed.
- (ii) The mean function is

$$m(t) = \lambda t$$

- (iii) Renewal process is a particular case of renewal process.
- (iv) Mean function always linear.



General Renewal Process: Distribution of N(t)

Let X_1, X_2, X_3, \ldots be i.i.d. random variables representing the inter-arrival times in a renewal process. Define the total time of the n-th renewal by:

$$S_n = X_1 + X_2 + \cdots + X_n$$

The number of renewals N(t) by time t is:

$$N(t) = \max\{n: S_n \le t\}$$

The probability that exactly n renewals occur by time t is:

$$P(N(t) = n) = P(S_n \le t \text{ and } S_{n+1} > t)$$

This can be written as the difference of cumulative distribution functions (CDFs) of S_n :

$$P(N(t) = n) = P(S_n \le t) - P(S_{n+1} \le t) = F_n(t) - F_{n+1}(t)$$



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Example 7.1 Suppose that $P\{X_n = i\} = p(1-p)^{i-1}$, $i \ge 1$. That is, suppose that the interarrival distribution is geometric. Now $S_1 = X_1$ may be interpreted as the number of trials necessary to get a single success when each trial is independent and has a probability p of being a success. Similarly, S_n may be interpreted as the number of trials necessary to attain n successes, and hence has the negative binomial distribution

$$P\{S_n = k\} = \begin{cases} \binom{k-1}{n-1} p^n (1-p)^{k-n}, & k \ge n \\ 0, & k < n \end{cases}$$

Thus, from Equation (7.3) we have that

$$P\{N(t) = n\} = \sum_{k=n}^{\lfloor t \rfloor} {k-1 \choose n-1} p^n (1-p)^{k-n}$$
$$-\sum_{k=n+1}^{\lfloor t \rfloor} {k-1 \choose n} p^{n+1} (1-p)^{k-n-1}$$



Equivalently, since an event independently occurs with probability p at each of the times 1, 2, ...

$$P\{N(t) = n\} = \binom{[t]}{n} p^n (1-p)^{[t]-n}$$

Another expression for P(N(t) = n) can be obtained by conditioning on S_n . This yields

$$P(N(t) = n) = \int_0^\infty P(N(t) = n | S_n = y) f_{S_n}(y) dy$$

Now, if the *n*th event occurred at time y > t, then there would have been less than *n* events by time *t*. On the other hand, if it occurred at a time $y \le t$, then there would be exactly *n* events by time *t* if the next interarrival exceeds t - y. Consequently,

$$P(N(t) = n) = \int_0^t P(X_{n+1} > t - y | S_n = y) f_{S_n}(y) dy$$
$$= \int_0^t \overline{F}(t - y) f_{S_n}(y) dy$$

where $\bar{F} = 1 - F$.



Example 7.2 If $F(x) = 1 - e^{\lambda x}$ then S_n , being the sum of *n* independent exponentials with rate λ , will have a gamma (n, λ) distribution. Consequently, the preceding identity gives

$$P(N(t) = n) = \int_0^t e^{-\lambda(t-y)} \frac{\lambda e^{-\lambda y} (\lambda y)^{n-1}}{(n-1)!} dy$$
$$= \frac{\lambda^n e^{-\lambda t}}{(n-1)!} \int_0^t y^{n-1} dy$$
$$= e^{-\lambda t} \frac{(\lambda t)^n}{n!}$$



Finding the Renewal Function

The mean value of a renewal process $\{N(t); t \ge 0\}$ is known as the renewal function. Let $P_n(t) = P(N(t) = n)$ is a probability mass function of $\{N(t); t \ge 0\}$. Then the expression of the renewal function is

$$m(t) = E[N(t)]$$

$$= \sum_{n=1}^{\infty} nP_n(t)$$

$$= P_1(t) + 2P_2(t) + 3P_3(t) + 4P_4(t) + \cdots$$

$$= P_1(t) + P_2(t) + P_3(t) + P_4(t) + \cdots$$

$$+ P_2(t) + P_3(t) + P_4(t) + \cdots$$

$$+ P_3(t) + P_4(t) + \cdots$$

$$= \Pr(N(t) \ge 1) + \Pr(N(t) \ge 2) + \Pr(N(t) \ge 3) + \cdots$$

$$= \sum_{n=1}^{\infty} \Pr(N(t) \ge n) = \sum_{n=1}^{\infty} \Pr(S_n \le n) = \sum_{n=1}^{\infty} F_n(t)$$



As $t \to \infty$, if the inter-arrival times have mean μ , the renewal process exhibits the following asymptotic behavior:

$$\lim_{t\to\infty}\frac{m(t)}{t}=\frac{1}{\mu}$$



Introduction to Branching Processes

- A branching process is a stochastic model that describes the evolution of populations where each individual in the population can produce offspring.
- Individuals reproduce and generate offspring, and the population size evolves over time.
- The key feature of a branching process is its probabilistic nature.
- The Galton-Watson branching process is a common model for such processes.



Key Features

- **Generations**: The population is divided into generations.
- Offspring Distribution: The number of offspring each individual has
 is determined by a random variable with a specific distribution.
- **Extinction**: The process may eventually result in the extinction of the population (i.e., no individuals are left).



Mathematical Model of a Branching Process

Consider a **Galton-Watson branching process**:

- Let Z_n be the population size at generation n.
- lacktriangle The population starts with Z_0 individuals.
- Each individual produces offspring independently according to some probability distribution p_k , where p_k is the probability that an individual produces k offspring.

The size of the population in the next generation is given by:

$$Z_n = \sum_{i=1}^{Z_{n-1}} X_i$$

where X_i is the number of offspring produced by the i-th individual, and X_i are i.i.d. random variables.

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Mean of Branching Process

Consider a Galton-Watson process where Z_n represents the population size at generation n.

The population at generation n is the sum of offspring from generation n-1:

$$Z_n = \sum_{i=1}^{Z_{n-1}} X_i$$

where X_i is the number of offspring of the *i*-th individual, and X_i are i.i.d. random variables with mean $\mathbb{E}[X_i] = \mu$.

Using the linearity of expectation:

$$\mathbb{E}[Z_n] = \mathbb{E}\left[\sum_{i=1}^{Z_{n-1}} X_i\right] = \mathbb{E}[Z_{n-1}] \cdot \mathbb{E}[X_1] = \mu \cdot \mathbb{E}[Z_{n-1}]$$

Thus, iterating this recurrence:

$$\mathbb{E}[Z_n] = \mu^n \cdot Z_0$$

where Z_0 is the initial population size.



Variance of Branching Process

To calculate the variance $Var(Z_n)$, we apply the law of total variance:

$$Var(Z_n) = \mathbb{E}[Var(Z_n \mid Z_{n-1})] + Var(\mathbb{E}[Z_n \mid Z_{n-1}])$$

First, the conditional variance $Var(Z_n \mid Z_{n-1})$ is:

$$Var(Z_n \mid Z_{n-1}) = Z_{n-1} \cdot Var(X_1)$$

where $Var(X_1) = \sigma^2$, the variance in the number of offspring per individual. The conditional expectation $\mathbb{E}[Z_n \mid Z_{n-1}]$ is:

$$\mathbb{E}[Z_n \mid Z_{n-1}] = Z_{n-1} \cdot \mu$$

Therefore, the total variance is:

$$Var(Z_n) = \sigma^2 \cdot \mathbb{E}[Z_{n-1}] + \mu^2 \cdot Var(Z_{n-1})$$

Iterating this recurrence:

$$Var(Z_n) = Z_0 \cdot \sigma^2 \cdot \frac{\mu^n - 1}{\mu - 1}$$



Types of Branching Processes

- Supercritical Branching Process ($\mu > 1$): The expected number of offspring per individual is greater than 1, and the population has a chance of growing indefinitely.
- Critical Branching Process ($\mu = 1$): The expected number of offspring per individual is equal to 1, and the population is expected to stay roughly constant.
- **Subcritical Branching Process** (μ < 1): The expected number of offspring per individual is less than 1, and the population is expected to die out.



Applications of Branching Processes

- Epidemiology: Used to model the spread of infectious diseases in populations.
- Population Biology: Modeling the growth or extinction of species over time.
- Physics: Describing reactions and particle interactions in nuclear and particle physics.
- Computer Science: Studying recursive algorithms and data structures like search trees.

