

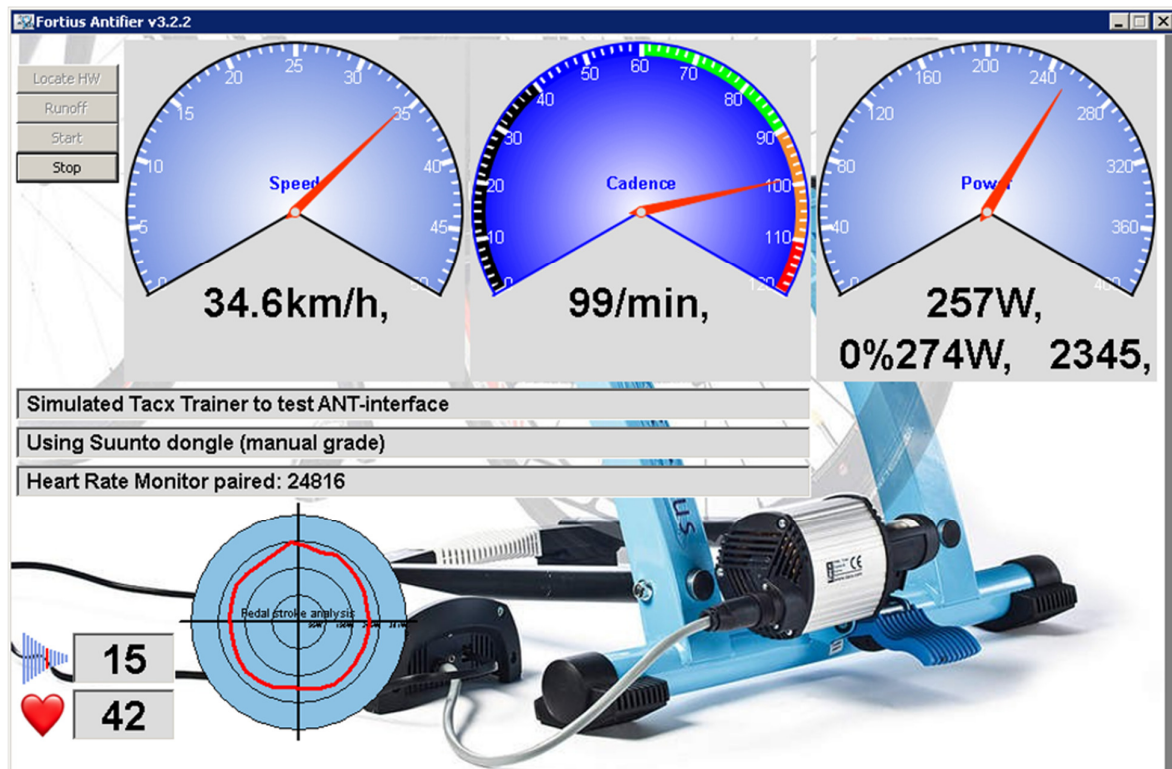


Fortius ANT

User Manual

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1. Introduction

1.1 Summary

Tacx created trainers and provided software (Tacx Training Software, TTS) to enable users to do structured training or ride in virtual world. Trainer and TTS were sold in a package and the interface was not available for other manufacturers.

Based upon these initial products, open standards were defined. ANT+ defines the way how CTP's (Cycling Training Programs) and FE-C's (Controllable Fitness Equipment) communicate with each other. This open standard enables that software (CTP) and hardware (FE-C) can be created by different manufacturers.

Known CTP's are Zwift, Trainer Road and Rouvy. Programs have their own specialty domain: Zwift provides the possibility to train together in a virtual world, Trainer Road has structured training programs and Rouvy allows to ride in augmented reality – and of course each product also provides functionality in the competitive area.

Trainers are provided by hardware manufacturers, like Tacx, Wahoo, Elite and others.

The open ANT+ standard allows the CTP's to communicate with FE-C's.

BUT: old Tacx trainers are left behind – the proprietary Tacx-interface is not supported by the modern CTP's.

This is where FortiusAnt has its place: **FortiusAnt enables users of old Tacx Trainers (like Fortius, Magic, Flow, Vortex and others) to use modern Cycling Training Programs (like Zwift, Trainer Road, Rouvy and others).**

1.2 Thanks

FortiusAnt is based upon the methods and architecture from **[Antifier]** and uses the interface description from **[TotalReverse]** and without their work, FortiusAnt would not have existed. Same is valid for Golden Cheetah for i-Magic's resistance formulas.

Thanks to **@darkpotpot** and **@iepuzaur** for testing the i-Vortex, **@yegorvin** for testing the i-Magic power curve and **@EIDonad** for cracking the CYCPLUS dongle issue and **@mattee** for enthusiasm on programming, correctness and testing as well as valuable github- and vsc-lessons. Of course, thanks to all who have reacted and added to FortiusAnt improvements.

If you use FortiusAnt, let me know and add yourself to the map!



FortiusAnt has matured in 2020's corona era, locked-down@home - sporting@home - programming@home. It shows where github code-sharing and joint effort can bring us; a new and inspiring experience for myself.

If you use FortiusANT, let me know and you add stars on the map!



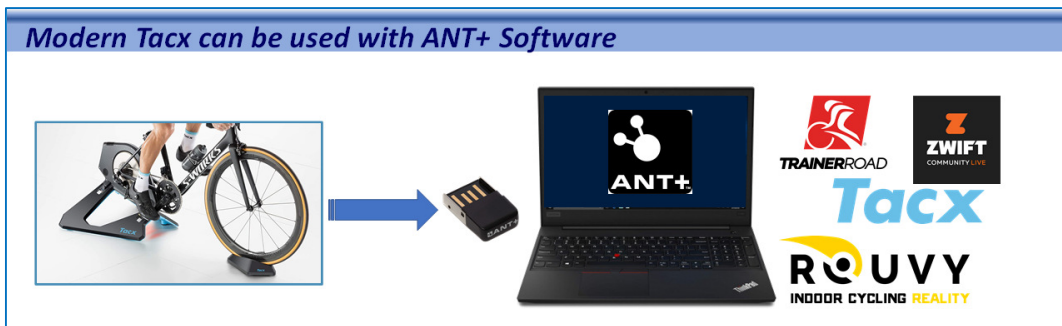
1.3 The structure of this manual

After the introduction you are now reading; the manual has the following chapters

- Background information; explaining concepts
- Installation instructions; how to install FortiusAnt
- Operating instructions; how to run FortiusAnt
- Questions and special situations; to describe anything else

I hope the manual helps in operating FortiusAnt and I'm always happy to hear from you @github!

1.4 The story in a picture:





1.5 References, abbreviations and terminology

Term	Explanation	See also
[Antifier]	The predecessor of FortiusAnt, created by “John”.	https://github.com/john-38787364/antifier
[ANT+]	ANT+ is a wireless technology that allows devices to talk to each other. The following documents are most interesting to study when digging into the python code: <ul style="list-style-type: none">D00000652_ANT_Message_Protocol_and_Usage_Rev_5.1.pdfD00001198_-_ANT+_Common_Data_Pages_Rev_3.1.pdfD000001231_-_ANT+Device_Profile-Fitness_Equipment-Rev_5.0(6).pdfD00000693 - ANT+Device_Profile- Heart Rate Rev 2.1.pdf	www.thisisant.com
[CTP]	Cycling Training Program, such as Zwift, Trainer Road or Rouvy	
[FE]	Fitness Equipment, like legacy Tacx trainers	
[FE-C]	Controllable Fitness Equipment, the ANT+ name for an indoor trainer. A [FE] + [FortiusAnt] becomes an FE-C.	
[FortiusAnt]	FortiusAnt enables a usb-connected Tacx trainer to communicate with TrainerRoad, Rouvy or Zwift through ANT.	https://github.com/WouterJD/FortiusAnt
[Python]	Python is a high-level programming language	www.python.com
[TotalReverse]	Invaluable source of information regarding Tacx USB interfaces.	https://github.com/totalreverse/tty1941
[TTS]	Tacx Training Software; proprietary [CTP] connecting to Tacx trainers only.	

1.6 Revision History

Date of this revision: October, 1st 2020	Version: v3 Published
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Version	Revision Date	Summary of Changes	Changes marked
3.a	June, 17 th 2020	First version	
3.b	October 1 st , 2020	First version published	No



2. Background information

2.1 FortiusAnt Sensor- and Monitor devices

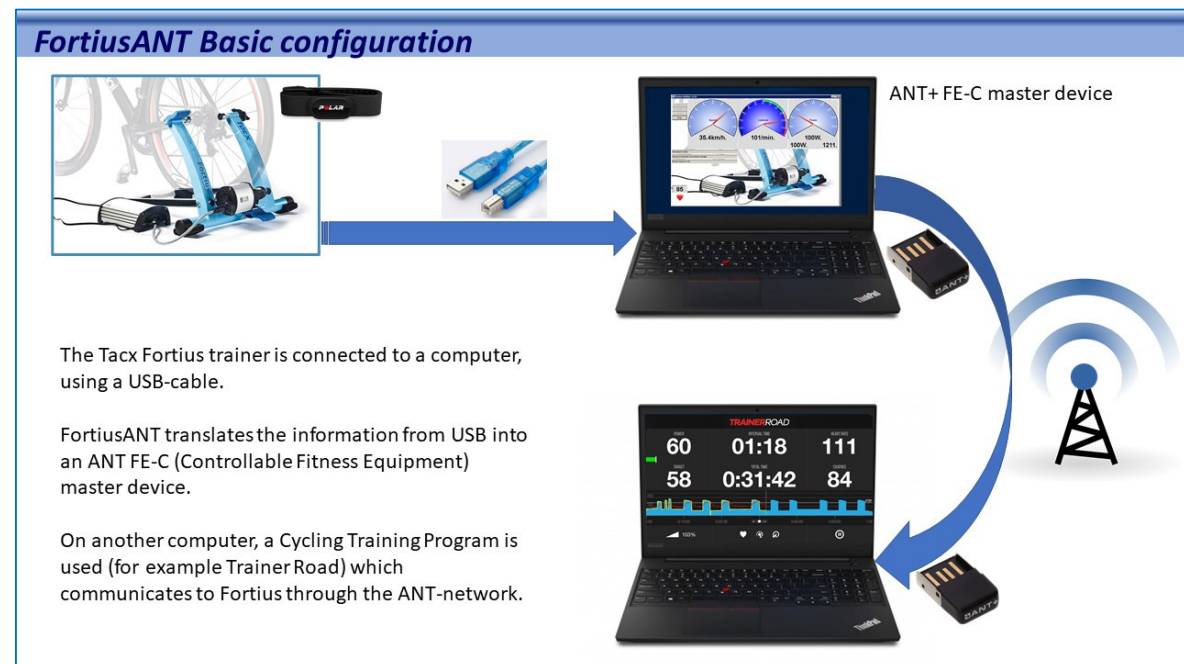
ANT+ terminology is Master and Slave which may be replaced with other names in near future.

ANT+ Master devices are Heartrate monitor, Powermeter, Speed- and Cadence sensor and **[FE-C]**'s. "Master" could be replaced by "Sensor": they measure and transmit the results through ANT+.

ANT+ Slave devices receive the transmitted signals and display the results, like a speed/cadence/power display on a bicycle; they may also send commands to the sensor – for example a **[CTP]** sends commands to a **[FE-C]**. "Slave" could be replaced by "Monitor": the display/monitor/control what the sensor does.

FortiusANT follows ANT+ terminology also when the terms Master and Slave are replaced in future.

To understand "what we are doing"; the following pictures explain at a high level what happens "under the hood".





ANT master and slave devices



ANT+ FE-C master device

ANT recognizes master- and slave-devices.
The Tacx Fortius is a master-device (broadcasting its information),
The Cycling Training Program (listening to the master and displaying its information) is a slave-device.

The Tacx Fortius sends four types of data on its cable: Speed, Cadence, Power and Heart rate. All this data is broadcasted on the ANT FE-C channel.



ANT+ FE-C slave device



FortiusANT creates two ANT+ master devices (FE-C and HRM)



ANT+ FE-C master device
ANT+ HRM master device

Tacx Fortius is from before the ANT-period and integrates the heart rate monitor. This is supported by the ANT FE-C definition, but Cycling Training Programs like Trainer Road and Zwift expect independent HRM's.

For that reason, FortiusANT creates two ANT+ master-devices: FE-C and HRM.



ANT+ FE-C and HRM slave device





FortiusANT can also listen to an independent ANT+ HRM strap



ANT+ FE-C master device
ANT+ HRM slave device



Although the basic purpose of FortiusANT is to translate Fortius to ANT+ FE-C, the following option is implemented. A little gadget in fact.

Imagine, you use an ANT+ coded Heartrate monitor; the Tacx Fortius does not recognize the HRM and no data can be displayed or broadcasted.

Therefore the -H flag tells FortiusANT to listen to a master HRM-device and display the heartrate. In that case, no master ANT+ HRM device is created.



ANT+ FE-C
and HRM
slave device



Zwift works slightly different



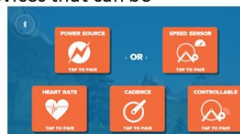
ANT+ FE-C master device
ANT+ HRM master device



As explained, FortiusANT creates two master devices

ZWIFT shows the following devices that can be paired individually:

- ANT+ Heartrate monitor
- ANT+ Controller
- ANT+ Cadence sensor
- ANT+ Power meter



The latter three can all be paired to the FortiusANT FE-C device, but if your bicycle has an own power-meter, you could choose to connect to that device instead.





2.2 Description

A [CTP] (Cycling Training Program) send commands to the [FE-C] (Controllable Fitness Equipment) through ANT+. There are two modes: Power- or Ergo-mode and Resistance- or Slope-mode.

2.2.1 Resistance

It is important to understand that an [FE-C] only knows 'resistance' which is the torque to turn the braking axle. From physics we know that power (Watt) = torque (Nm) * speed (km/hr). For a given resistance, the power required is linear with the speed (=cadence), provided you do not change gears. Also, for a given resistance and cadence, the power required is linear with the gear-ratio.

PS. This is especially valid for the older trainers; Tacx i-Vortex can be set natively to a defined Power.

2.2.2 Power- or Ergo-mode

In Powermode the [CTP] sends the required power to the [FE-C] and regardless gear or cadence, the requested power is constant. FortiusAnt calculates the resistance = power/speed (with some constants applied). Note that, if you change gears and/or cadence, the required power will remain equal because the resistance is adjusted.

2.2.3 Resistance mode

In resistance mode, FortiusAnt receives the required grade from [CTP]. Grade may vary from -20% (downhill) to +20% (uphill). FortiusAnt calculates the resistance to be sent to the [FE].

The power required to ride up a hill is based upon the given grade with a weight of 90 kg (rider + bike) at a given speed'. Input parameters are grade and weight (from [CTP]) and speed (as measured by [FE]). Result is Power and conversion to resistance is described above.

2.3 Tacx trainers

FortiusAnt supports the following USB-trainers:

- Head unit 0x1904 # New "white, green" iMagic headunit (firmware inside)
- Head unit 0x1932 # New "white, blue" Fortius headunit (firmware inside)
- Head unit 0x1942 # Old "solid blue" Fortius (firmware inside)
- Head unit 0xe6be # Old "solid blue" Fortius (without firmware)
This head unit requires software to be loaded when FortiusANT is started.
- Head unit 0x1902 # Old "solid green" iMagic head unit (with or without firmware)
This head unit uses a so-called legacy-USB protocol, the others the New-USB-protocol.
- The i-Vortex is a special case since it does not use a USB-cable and hence cannot be detected automatically. Therefore the -t command-line parameter is used.

Note that, FortiusAnt only "knows" the head unit, not what brake is behind it, that is completely invisible.



2.4 Calculations

2.4.1 Power mode

When the [CTP] is in power-mode, a required number of Watts is sent to [FE-C], in our case FortiusAnt. "The head-unit of the Tacx-trainer" in short: "The [FE] requires a resistance to be set and hence a function TargetPower2Resistance(Power, Speed) is used to convert. The function is different for legacy- and new-USB trainers.

So, if you want to ride with a power of 100Watt and the bicycle wheel runs at 10kmh, the [FE] needs to receive another required resistance than when the wheel is rotation at 40kmh.

Similarly, the [FE] returns the currently realized resistance and a function is used to calculate the realized Actual Power.

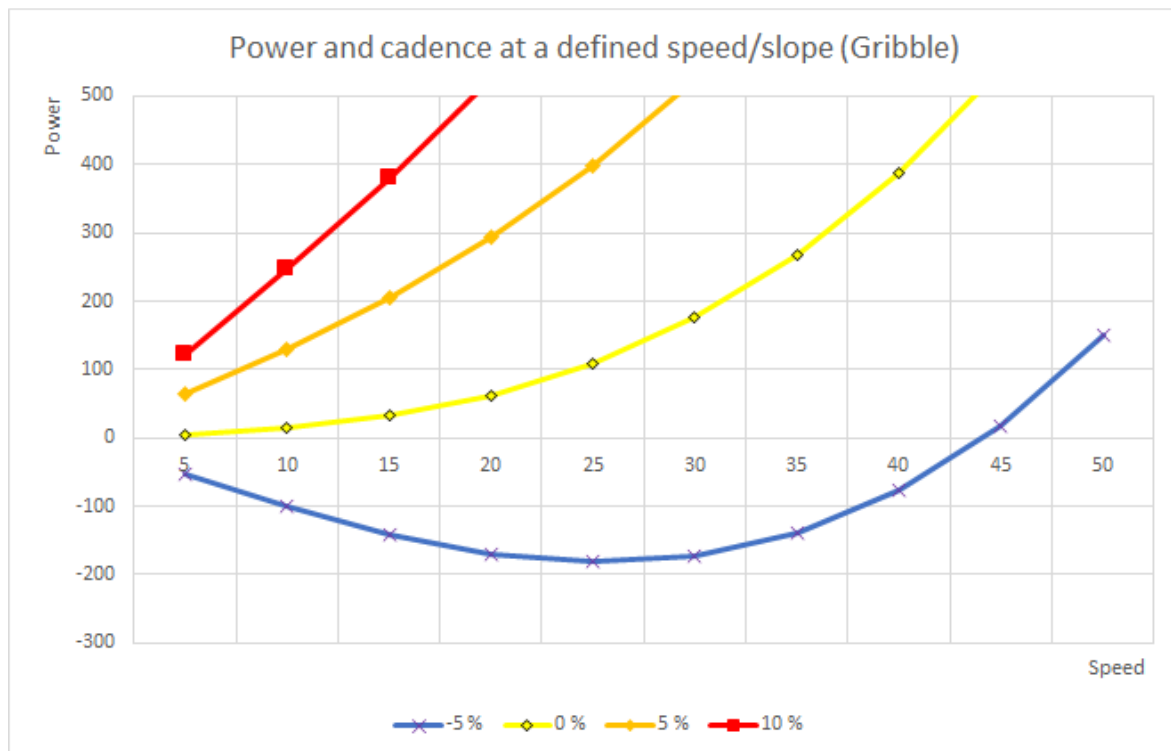
2.4.2 Grade mode

In Grade mode, the [CTP] communicates the slope where you are riding: flat = 0%, up hill (e.g. 10%) or downhill (e.g. -10%).

An additional step is required, using function Grade2Power(Grade, Speed, UserAndBikeWeight). First the Grade is converted to power and then the same applies as described in the previous paragraph.

The function also depends on RollingResistance, WindResistance, WindSpeed and DraftingFactor. Constants are used if [CTP] does not explicitly specify these parameters. The default value for UserAndBikeWeight is 85kg.

The formula results in the power curve as shown below. Note that, on a flat surface (yellow curve) you need 100Watt to ride 25km/hr. On a hill of 5% (orange curve) you need 300Watts at 20km/hr. And if you ride downhill -5% (blue curve) you would ride around 44 km/hr without adding additional power.





3. Installation instructions

3.1 Introduction

FortiusAnt is written in **[Python]** and can be run on any computer for which a python runtime environment is created. For Windows, FortiusAnt is also available as an executable, containing the python runtime environment. Windows users can therefore decide which version to use.

FortiusAnt communicates with the Tacx Trainer through a USB-interface, which needs some special care. And at the other side, FortiusAnt communicates with a CTP using an ANTdongle.

3.2 Download FortiusAnt from github

Goto <https://github.com/WouterJD/FortiusAnt/>

In section <code> click on [↓Code] and download the code as a zipfile.

Create a folder on your computer called C:\Github\FortiusAnt (windows) or ../Github/FortiusAnt (unix). From now on, this folder will be referred to **<the FortiusAnt folder>**.

The downloaded file contains a folder called **FortiusAnt-master** copy the contents into **<the FortiusAnt folder>**.

3.3 Install python

Note: Python is NOT required when you use the Windows executable.

- Goto <https://www.python.org/downloads/>
- Follow the installation instructions for your system. It's impossible to handle all operating systems specific instructions. For Windows it's easiest NOT to install for "All users".

Note that, Python version 3 is required. If you have multiple instances of python installed, mind the PATH settings!

After installation, the python version can be checked with the following commands:

```
python --version  
pip --version
```

You can check whether the most recent pip is installed with the command:

```
pip install --upgrade pip
```

As soon as python is installed correctly, the modules that are required for FortiusAnt can be installed as follows:

```
pip install -r requirements.txt
```

the requirements file is available in code/pythoncode in **<the FortiusAnt folder>**.



3.4 Install USB-driver

3.4.1 Windows

On the system where FortiusAnt is running, the easiest is that TTS is not installed, since the two programs require different USB-drivers which may be conflicting. There are studies to have both programs installed, for sake of simplicity of this installation instruction will describe a FortiusAnt-only installation. **Refer to** 5.4 "Can TTS4 and FortiusAnt coexist?" for more information!

You have to (re)install your trainer as a libusb-win32 device.

Download the libusb driver

- Download software from <https://sourceforge.net/projects/libusb-win32/>
- Read the wiki, sections download and Device Driver Installation
- Download libusb-win32-bin-1.2.6.0.zip from files/libusb-win32-releases/1.2.6.0/
- Unzip the file

Uninstall TTS-driver (refer to **section** 5.4 "Can TTS4 and FortiusAnt coexist?" first)

- Open device manager.
- Right click on the device and click "Uninstall". It may be listed as a "Jungo" device (see <http://www.tacxdata.com/files/support/Windows10driverissues.pdf> - DO NOT RUN TacxDriversSetup.exe!)
- Unplug the trainer, wait 5 seconds, and plug it back in again

Install option 1

- Find it again (usually under other devices>VR-interface)
- Right click and select "update driver software"
- Select "Browse my computer for driver software"
- Select "Let me select from a list of device drivers on my computer"
- Select libusb-win32 devices
- Select ANT USB Stick 2, then OK in the warning, then close Your USB-trainer is now installed as "ANT USB Stick 2" which works, but perhaps is not a very clear name.

Install option 2

- Go to the ..\libusb-win32-bin-1.2.6.0\bin folder
- Start inf-wizard.exe, click next
- Select "VR-Interface" (which is the USB-device you plugged in again), click next
- Specify the name for Manufacturer (Tacx) and Device (VR-Interface), click next
- Store the results in the same folder; this creates a file like VR-Interface.inf
- Complete the installation

Now the USB-trainer is installed as "VR-Interface" (you could have chosen for "Fortius Virtual Trainer").

Technically, it is the same as option 1, but especially if you have two ANT sticks and one Tacx Trainer a named device is nicer. The names will only show up in device manager and ExplorANT and have little significance for the end-user.

3.4.2 MacOS

** to be supplied, since I have no MacOS environment to test

Hints: libusb can be installed using brew install libusb; Get brew if you don't have it already:
<https://brew.sh/>.



3.4.3 Linux – General

Hints:

- Root required
- Refer to AntBridge installation instructions for hints (<https://github.com/pepelkod/AntBridge>).
- Instructions supplied by FortiusAnt users, since I have no linux environment to test.

3.4.4 Linux Ubuntu 20.04

As provided by [@msinaessens](#); thanks.

Fresh install of Ubuntu 20.04; installed in Oracle VM VirtualBox 6.1; 2048 MB ram; 4 cpu cores (i7 8750H); 16 MB video memory; installed on MSI GV62 8RC laptop.

```
sudo apt install git
git clone https://github.com/WouterJD/FortiusAnt
sudo apt upgrade python3
sudo apt install python3-pip
pip3 install --upgrade pip
sudo apt-get install python3-pygame
```

```
sudo apt install make gcc libgtk-3-dev libgstreamer-gl1.0-0 freeglut3 freeglut3-dev python3-
gst-1.0 libglib2.0-dev ubuntu-restricted-extras libgstreamer-plugins-base1.0-dev ubuntu-dev-
tools
```

```
sudo apt install python3-wxgtk4.0
pip3 install -r ./FortiusAnt/pythoncode/requirements.txt
pip3 install --upgrade wxpython
```

```
git clone https://github.com/pepelkod/AntBridge
LOC=/lib/modules/uname -r/kernel/drivers/usb/serial/
sudo mv $LOC/usb-serial-simple.ko ~/Documents
sudo mv $LOC/usbserial.ko ~/Documents
sudo rmmod usb_serial_simple usbserial
sudo apt install libusb-dev
sudo apt install libgoogle-glog-dev
sudo apt install libusb-1.0-0-dev
sudo apt install pkg-config
```

Open terminal in AntBridge folder

make; make;

```
sudo make install
```




```
git clone https://github.com/Tigge/openant
git clone https://github.com/Tigge/antfs-cli
```

```
open terminal in openant folder:
sudo python3 setup.py install
open terminal in antfs-cli folder
sudo python3 setup.py install
```

Now run FortiusAnt:

```
sudo python3 ./FortiusAnt/pythoncode/FortiusAnt.py
```

Done!

3.5 Install ANTdongle

ANTdongles are a lot easier to use than a USB-interface, since they are plug&play; insert the dongle in your computer and the required drivers will be installed automatically.

Dongles from manufacturer=CYCPLUS are reported not working well with FortiusAnt, refer to github FortiusAnt issues (#61, #45 and #65).

3.6 Start FortiusAnt

Now FortiusAnt should be able to operate now. Since we start FortiusAnt without additional command-line variables, FortiusAnt will use the default (best-practice) settings. To start FortiusAnt, you have to make a shortcut, a menu-entry or a command-file, containing the command which is then executed.

<**The FortiusAnt folder**> contains a folder "StartUp" where you find some command-files, which can be used as an example. When the debug-option is used, logfiles are created in this folder, this will be described later.

"FortiusAnt.bat" contains the following two lines:

```
..\WindowsExecutable\FortiusAnt.exe
pause
```

and "FortiusAnt (exe).bat" contains:

```
..\WindowsExecutable\FortiusAnt.exe
pause
```

Start FortiusAnt by double-clicking the file from Windows-explorer. A "console" is opened and then the FortiusAnt user-interface is started. After completion of FortiusAnt you will get a prompt to press enter (the pause command) so you can see messages in the "console".

Note that starting FortiusAnt on other operating systems is done in a similar way.

See section 4.2 "Command line" for information on parameters that can be passed on the command-line.



3.7 Check FortiusAnt

When FortiusAnt is started without additional command-line parameters, the following text is displayed in the console:

```
-----
Hello!
You have started FortiusAnt without command-line parameters.

Therefore, we start with a best practice setting:
FortiusAnt.exe -a -g -H0 -A

If you want to start without the graphical user interface:
FortiusAnt.exe -a

For more info, please refer to the wiki on github.
Succes!
-----

FortiusAnt is open source and can freely be used.

A free gift would be appreciated:
Put yourself on the FortiusAnt map by making yourself known
by leaving a message with name/location/trainer on
https://github.com/WouterJD/FortiusAnt/issues/14

Just for the fun of knowing where we are training.
-----
```

And then the graphical user interface appears:

FortiusANT Graphical User Interface



When the GUI is shown, you know that FortiusAnt is installed correctly.



The user interface contains the following elements:

1. The window title displays name and version of the software you run
2. <Locate HW> is a button and when pressed, FortiusAnt will search for a Tacx USB-device and an ANT-dongle. When found, the result is displays in (5) and (6), the button is disabled and <Runoff> and <Start> are enabled.
3. <Runoff> activates the user-driven calibration
4. <Start> activates FortiusAnt to bridges USB data to ANT+ and vice-versa; then <Start> is disabled and <Stop> enabled.
5. <Stop> stops the FortiusAnt bridge.
6. Shows what USB-trainer is found
7. Shows what ANT-dongle is found
8. Shows what heartrate is used
9. Displays the speed of the bicycle wheel (returned by the Tacx trainer)
10. Displays the cadence of the pedals (returned by the Tacx trainer)
11. Displays the power as returned by the Tacx trainer.
Also, the target is displayed as requested by the CTP.
12. Displays the Pedal Stroke Analysis, as calculated by FortiusAnt.
13. The heartrate.
14. The virtual gearbox; displayed only in Grade-mode.



4. Operating instructions

4.1 The main functions of FortiusAnt and the head unit.

After that FortiusAnt is started (see 3.6 Start FortiusAnt) you see the user interface with the buttons

- Locate HW
- Runoff
- Start
- Stop

4.1.1 *Locate HW*

Checks for the presence of USB-trainer and ANT-dongle. If successful, results are displayed and the button is disabled. For more info read section 4.3 "Locate HW".

4.1.2 *Runoff test*

To ensure comparable training sessions, the trainer should provide the same relative resistance each time

1. Aim for about 7 bar (100psi) in tire when cold
2. Warm up for 2-3 minutes to warm tire
3. Increase speed and pass the 40 km/hr speed, then stop pedalling and let wheel slow down
4. Ideally, the wheel should stop after 7 seconds from 40kph

If the rundown is too short, the role may be too tight and if the rundown is too long, the role may be too loose. In that case, adjust the role and retry the rundown test.

4.1.3 *Start*

Pressing this button starts FortiusANT to listen to the FE (Tacx USB-trainer) and CTP (ANT-dongle, Zwift, Trainer Road, Rouvy, ...) and exchange info between them.

FortiusANT starts to calibrate the trainer (if supported and -n is not specified). Calibration means that the brake rotates the wheel at 20 km/hr and returns the resistance found. As soon as the resistance is constant, the calibration stops. The calibration time is at least 30 seconds (warming up the tire) and stops when the resistance value is constant.

Note that the calibration starts when you turn the pedal as if starting to cycle, which is the only physical action to take. Note that, starting the motor automatically would be a risk for physical injury, therefore the confirmation with a pedal-kick is required.

After calibration, the Fortius is ready for training.

4.1.4 *Stop*

Pressing this button stops the currently running process (runoff, calibration or operational mode).



4.1.5 Buttons on the Tacx head unit

There are four buttons: Cancel, Enter, Up, Down.

- **Cancel** is active in all modes.
- If not in an active mode, **Up/Down** navigate through the menu, **Enter** activates the selected button and **Cancel** exits FortiusANT.
- In runoff or manual mode, **Up/Down** modify the required power with ± 50 Watt. **OK** *) resets the power to the initial value of 100Watt.
- In manual grade mode, **Up/Down** modify the slope with ± 1 degree. **OK** *) resets the slope to the initial value of 0 degrees.
- In normal resistance mode, **Up/Down** modify the resistance of the Fortius by $\pm 10\%$. **OK** *) resets the resistance is reset to the initial value of 100%.

*) Tacx has a variety of trainers with different head units, not all head-units have an OKbutton.



4.2 Command line

FortiusANT is started with a command (see 3.6 Start FortiusAnt). In addition to the examples shown there, parameters can be passed on the command-line:

```
FortiusAnt.py [-h] [-a] [-A] [-d DEBUG] [-g] [-H HRM] [-m] [-M] [-n] [-p FACTOR] [-P] [-s] [-t TACXTYPE]
```

Basic arguments:

- h Show a help message and exit.
- a Automatically start; "Locate HW" and "Start" if the required devices were found.
- g Run with graphical user interface.

Advanced arguments:

- A Pedal Stroke Analysis.
- H HRM Pair this Heart Rate Monitor (0: any, -1: none).
- m Run manual power (ignore target from ANT+ Dongle).
- M Run manual grade (ignore target from ANT+ Dongle).
- n Do not calibrate before start.
- p FACTOR Adjust target Power by multiplying by this factor for static calibration.
- P Power mode has preference over Resistance mode (for 30 seconds).
- t TACXTYPE Specify Tacx Type; e.g. i-Vortex, default=autodetect.

Developer arguments:

- d DEBUG Show debugging data.
- s Simulated trainer to test ANT+ connectivity.



Examples:

FortiusAnt.py	FortiusANT is started without user-interface, -g -a -A -H0 are assumed.
FortiusAnt.py -g -a	FortiusANT is started with user-interface and starts automatically.
FortiusAnt.py -g -m	FortiusANT is started with user-interface. No [CTP] is required, power can be set using the console. Although intended for interface testing, you could do a manual ride this way.
FortiusAnt.py -g -M	Same as -m but now the slope-grade can be adjusted.
FortiusAnt.py -g -s	FortiusANT is started with user-interface. No [FE] is required, automatic response to [CTP] is generated. This is intended for interface testing.

Values for parameters:

DEBUG	Is a binary flag list what to write to the logfile, 0=nothing, 127=everything. The values below can be added together. No = 0 Application = 1 Function = 2 antDongle = 4 usbTrainer = 8
FACTOR	Correction factor 0.9 ... 1.10
HRM	The device ID of the Heart Rate Monitor to be used. 0: pair with first found, -1 do not pair at all.

4.3 Locate HW

When the "Locate HW" button is pressed, the following happens:

Find ANT+ dongle

A check is done whether an ANT+ device with DeviceID 4100, 4104 or 4105 is found. If found, an attempt is made to use the dongle, if in use another dongle will be searched for.

FortiusANT always needs an ANT-dongle, unless -m or -M is specified in that case you can set power or slope with the trainer's head unit buttons.

The following messages can be displayed:"

```
No (free) ANT-dongle found
Using <manufacturer> dongle
```

or messages indicating what interface-error occurred.



Find Tacx Trainer

Then a check is done whether a Tacx device is used with one of the DeviceID's as listed in section 2.3 "Tacx trainers".

The following messages can be displayed:"

```
No Tacx trainer found
Connected to Tacx Trainer T<DeviceID>
```

or messages indicating what interface-error occurred.

Note that, when the -s command-line parameter is specified, the following message is displayed:

```
Simulated Tacx Trainer to test ANT-interface
```

Note that, when the -t i-Vortex command-line parameter is specified, the following messages are displayed:

```
Pair with Tacx i-Vortex and Head unit (pairing can take a minute)
Tacx i-Vortex paired: %s, Head unit: %s
```

Heartrate monitor

Old Tacx trainers paired with a heartrate monitor (HRM) and passed the heartrate through the USB-interface to **[TTS]**. Even though this option is supported on the **[FE-C]** ANT+ interface, it is not used by **[CTP]** since this software pairs with a HRM itself.

The FortiusANT display shows the heartrate and therefore the following options exist:

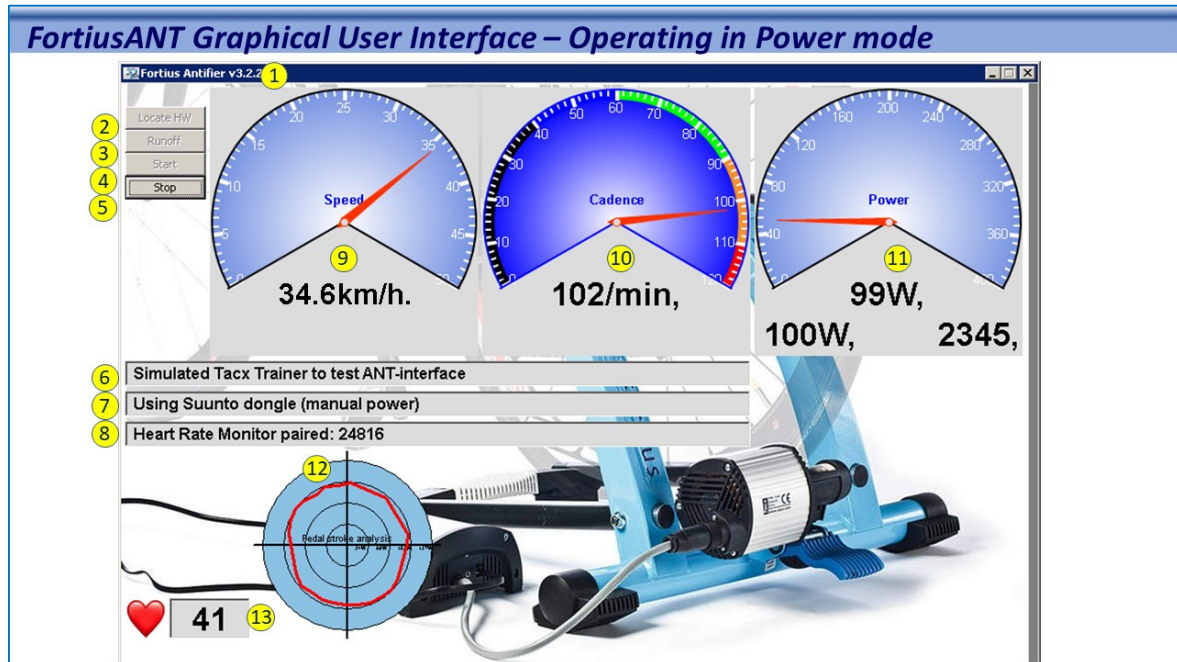
- No command-line option: use the heartrate from the Tacx trainer
- -H0: pair with an ANT+ HRM", use the first HRM that is found
- -Hnnnnn: pair with the ANT+ HRM with DeviceID=nnnnn
- -H-1: no HRM.

The following messages can be displayed:"

```
Heartrate expected from Tacx Trainer
Heartrate expected from ANT+ HRM
Heart Rate Monitor paired: <DeviceID>
```



4.4 The FortiusAnt display in power mode

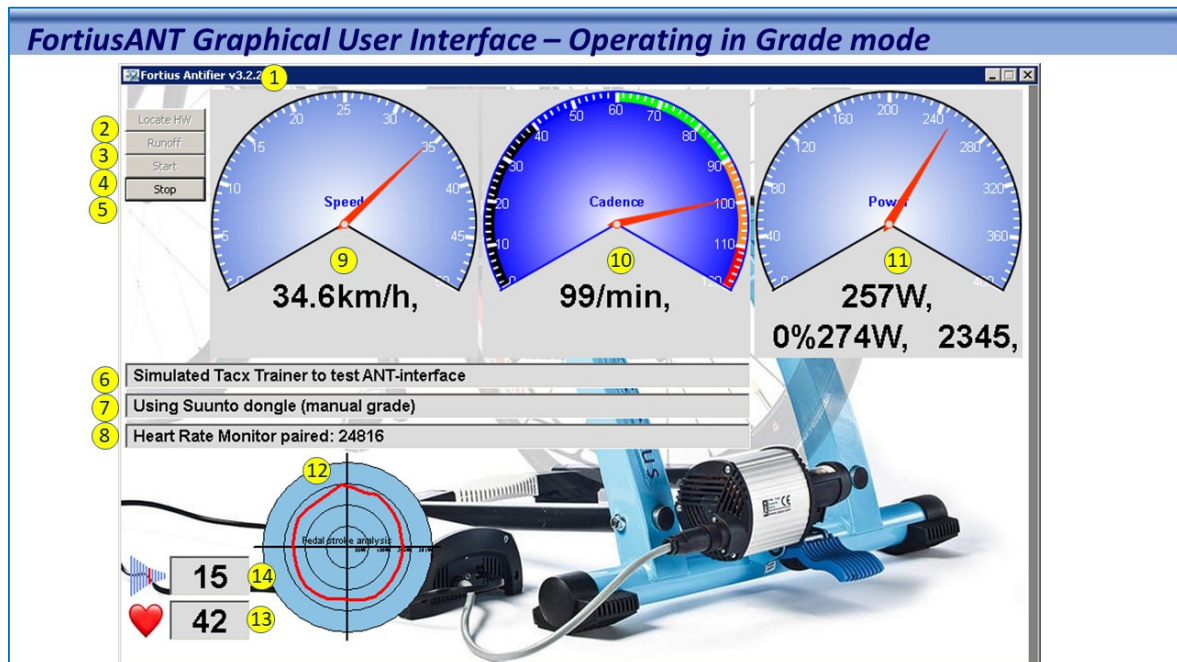


The elements on the screen are explained in section 3.7 "Check FortiusAnt".

In addition to the standard display, under the power gauge (11) the actual power (99W), the requested power (100W) and the resistance set in the trainer (2345) are displayed.



4.5 The FortiusAnt display in grade mode



The elements on the screen are explained in section 3.7 “Check FortiusAnt”.

In addition to the standard display, under the power gauge (11) the actual power (257W), the requested grade (0%) and resulting required power (274W) and the resistance set in the trainer (2345) are displayed.

Here you also see the “digital gearbox”. In addition to the gears on your bicycle imagine you have a second drive train with a 15x15 ratio. So, the displayed situation is neutral. When you press Up/down the ratio is changed with $\pm 10\%$, increasing and decreasing the required resistance on the bike. The digital gearbox shows the number of teeth on your digital cassette.

If your [CTP] requires to ride uphill with a slope of +10% and you have a high wheel-speed (because that is how the Fortius works well, see section 5.1 “Low cadence on Fortius”) you would need a high power. If that required power is higher than you can produce, you can reduce the required power using the down-button without reducing speed. If you are using Zwift you will see that the difference in Speed in Zwift (based upon power) and the speed displayed by FortiusAnt will increase).

The digital gearbox is not active in power-mode, because if 100W is required, 100W you must give. At a high wheelspeed, the resistance is already calculated accordingly.

Thanks to Erik OT for the magnificent suggestion!



5. Questions and special situations

5.1 Low cadence on Fortius

One of the limitations of the Fortius is the resistance at low wheel-speed, which implies a low rotational speed of the brake.

If you have a high wheel-speed, the Fortius can realise a resistance of 1000Watt. This works fine and is good to train your power.

At a low wheel-speed however, the brake does not work very fine and therefore it needs some thinking to train "Uphill training at 20%", requiring high power and low speed. You would be inclined to reduce gears as you would do in real world.

What I do is always use a high gear, causing a high wheel-speed, and drop the cadence without shifting. For example, if you want to simulate a steep uphill, requiring 500Watt you still go in the highest gear and use a cadence of 50 rpm.

FortiusAnt will reduce resistance for the trainer and the result is that you ride at 30km/hr with 500Watt and 50 rpm. Just ignore the wheel-speed!

Note that modern trainers have a direct drive and no wheel; there the wheel is ignored completely.

5.2 Zwift speed does not match Garmin

If you ride your bicycle on your trainer; the speed that Zwift displays does not match Garmin's speed.

Your Garmin receives the speed from the bicycle and displays the real speed of the wheel on the trainer. (Probably you realize, with the same effort, you would not achieve that speed in the real world)

Zwift receives the realized power from the trainer and uses its own algorithms to conclude what speed you are riding: If riding on a flat surface, without headwind, the simple formula would be: $\text{speed} = \text{power} / \text{resistance}$. But when you ride uphill and you take air-resistance into account, the formula is far more complicated.

Interested in the power you need to ride?

- <https://www.fiets.nl/2016/05/02/de-natuurkunde-van-het-fietsen/>
- https://www.gribble.org/cycling/power_v_speed.html

The gribble formulas are used by FortiusAnt to convert grade to power, see also section 2.4.2 "Grade mode".

5.3 Average speed in Trainer Road

Jerome uses TrainerRoad and notices that during a ride his average speed is 20km/hr and his friend is going at 40 km/hr. How is that possible?

Imagine that TrainerRoad requires to ride with a Power of 200Watt, the two riders have the same bike and the same trainer and have selected the same gear-ratio.

If Jerome choses to ride with 50 rpm, his speed will be low, and the trainer will increase the resistance so that the required power of 200Watt is realized.

If his friend rides at 100 rpm, his speed will be higher than yours and the trainer will decrease the resistance so that the required power of 200Watt is realized.



Note that power = resistance * speed! Jerome rides at half speed of his friend, but with a higher resistance and hence both athletes produce the same power at a different speed and different distance. Note therefore that, on a [FE] speed and distance are irrelevant, time, power and cadence are the deciding factors.

For you it's a pity that your Strava statistics for the end-of-year applause run behind; but having read the explanation - that would be a lesser issue.

The situation in real world is different; if you go for a ride together time, speed and distance will be the same and therefore you will come home with the same average power. Difference choice in gears will change the resistance and cadence which is less observed in the Strava results.

Why would you ride at 50rpm or 100rpm?

When TrainerRoad demands 200Watt it may instruct you (through the displayed texts) to ride at a high or a low cadence, depending what purpose is intended. It is not correct to say that the speed is not relevant: it may be that either you or your friend did not do the intended training (high power or high force).

5.4 Can TTS4 and FortiusAnt coexist?

[TTS] is Tacx' own training software which uses it's own USB-driver and/or ANT+ interface. The installation instruction suggests to de-install (for simplicity), see 3.4 "Install USB-driver".

The following information is of interest for everybody who would like to work with [TTS] and other [CTP]'s.

iepuzaur: I am running on Windows10 TTS4 and FortiusANT, at first I also thought I have to uninstall the Jungo driver TTS uses, but then I noticed you can have both drivers installed and there is no issue on my system.

Of course, you cannot use them concurrently, if you start TTS4 it will use the Jungo driver, while when you start FortiusANT the libusb drive will be selected.

So as long as you do not intent to use them at the same moment, the drivers shall not conflict (at least this is my case). (Thanks to @iepuzaur, june 2020).

Note however: If your TTS4 software is already installed and registered then that should work. If it isn't, it won't as the registration servers have been switched off. The only software that works without registration is Fortius v2.02.

Never uninstall TTS4 if you have a working registered copy as there is no way to reinstall it and re-register it. (Thanks to Shaun Murray, @aegisdesign, sept 2020).

frense8: I have been using FortiusAnt for 2 months now in combination with the Tacx Desktop App (Windows 10). It works fine! The Tacx Desktop App connects via ANT with ANT-ID 57591 (identified as Tacx Neo2T!).

Incidentally, I also own the 4iii Viiiva HRM with ANT to BT bridge, but I expect the bridge to work in one direction only, so not from BT to ANT. So, using BT via the 4iii HRM is unlikely to provide a solution, I failed. However, this is not necessary, because FortiusAnt can work directly via ANT with the Tacx Desktop App.

By the way: I'm using FortiusAnt and Tacx App on two different laptops, because I sometimes want to use Tacx TTS4 (installed on the same laptop as Tacx Desktop App). I failed to get FortiusAnt and TTS4 to work on the same laptop.

Note that, TTS4 and Tacx Desktop App are 2 different applications. TTS 4 is outdated software, but like the Tacx Desktop App. A few years ago, Tacx replaced TTS4 with the Desktop App and they changed the revenue model: with the Desktop App they introduced the subscription model (monthly / annual fee). TTS4 uses real life videos that had to be purchased separately.

FortiusAnt also works with TTS4 (with 2 laptops), but that is not necessary, because TTS 4 also works via the USB connection of the Fortius trainer (with the Jungo USB driver that is installed by TTS4). It is **tricky to uninstall the jungo driver** (to try to run TTS4 and FortiusAnt on 1 laptop), because Tacx has ended the support of TTS4 and reinstallation of TTS4 is therefore no longer easily possible (because Tacx servers for authentication are out of operation). (Thanks to @frense8, August 2020)