


CA_Map::CreateRoom



```
graph LR; A[CA_Map::CreateRoom] --> B[Map::isInBounds]
```

A diagram showing a call from the function `CA_Map::CreateRoom` to the function `Map::isInBounds`. The first box is shaded gray and the second is white. A blue arrow points from the right side of the first box to the left side of the second box.

Map::isInBounds